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4. Referencing

4.1 Licensee agrees to reference the following publications:

Ghosh, Suman and Cavinato, Valentina, and Gallego, Guillermo; ES-PTAM: Event-based Stereo Parallel Tracking and Mapping; European Conference on Computer Vision (ECCV) Workshops; 29.09.2024; https://arxiv.org/pdf/2408.15605

- 4.2. Licensee shall include the following copyright notices in the source code in a customary manner with respect to the Software:
 - * \file
 - * \brief
 - * \author (1) Suman Ghosh
 - *\date 2024-09-29
 - * \author (2) Valentina Cavinato
 - * \date 2024-09-29
 - * \author (3) Guillermo Gallego
 - * \date 2024-09-29
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 - * Prof. Guillermo Gallego
 - * Robotic Interactive Perception
 - * Marchstrasse 23, Sekr. MAR 5-5
 - * 10587 Berlin, Germany

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https://github.com/tub-

rip/dvs mcemvs/blob/main/Software License Agreement TUB dvs mcemvs.pdf and

https://github.com/ghoshsuman/rpg_dvs_evo_open/blob/noetic/SOURCE%20CODE%20LICEN_SE%20AGREEMENT_evo.doc

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```
author = {Suman Ghosh and Guillermo Gallego},
title = {Multi-Event-Camera Depth Estimation and Outlier Rejection by Refocused Events},
journal = {Journal of Advanced Intelligent Systems},
year = {2022},
volume = {4},
issue = {12},
month = dec,
doi = {10.1002/aisy.202200221}
```

and

```
= {Rebecq, Henri and Horstschaefer, Timo and Gallego, Guillermo and Scaramuzza,
author
           Davide \}.
         = {IEEE Robotics and Automation Letters},
iournal
         = {EVO: A Geometric Approach to Event-Based 6-DOF Parallel Tracking and Mapping
title
            in Real Time},
         = \{2017\},
year
volume = \{2\},
number = \{2\}.
         = \{593-600\},\
pages
doi
         = {10.1109/LRA.2016.2645143}
```

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- 9.6 The terms stipulated in this Agreement may not be modified in any way without the mutual consent of the parties in writing.

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