

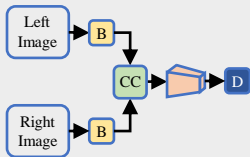
### Input:

Left Image  
Right Image

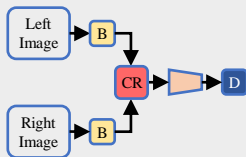
### Data:

Data Loader  
Data Sampler  
Data Transform

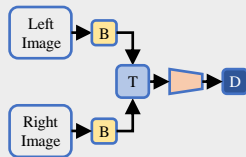
## Various Frameworks



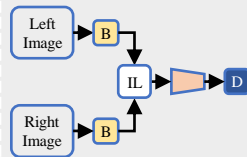
(a) Concatenate-based



(b) Correlation-based



(c) Transformer-based



(d) Interlaced-based

## *OpenStereo*



### Benchmarks:

Scene Flow  
KITTI 2012  
KITTI 2015  
Middlebury 2014  
ETH3D  
DrivingStereo