## **YOPO:** Hardware Design and Equipment List of Our Drone

In this document, we provide a detailed description of the hardware and modules for drone in our method YOPO[1] (You Only Plan Once). The drone is designed to be very compact, with a diagonal wheelbase of 155 mm (Fig. 1). It has a takeoff weight of 850 g and a thrust-to-weight ratio of 4.7, enabling high-speed (Fig. 2) and agile (Fig. 3) flights in cluttered environments. We select the NVIDIA Orin 16G as the onboard computer, which offers ample computational capacity for handling various complex tasks (Fig. 4). The drone is designed modularly, with user-friendly interface connections and convenient



Fig.1 The drone is designed to be compact and modular.

flight controller debugging. Furthermore, the structure is stable, and as shown in our early experiment (Fig. 5), the drone successfully reaches its destination after experiencing consecutive lateral collisions at a speed of 6 m/s.



high-speed flight in dense forest.

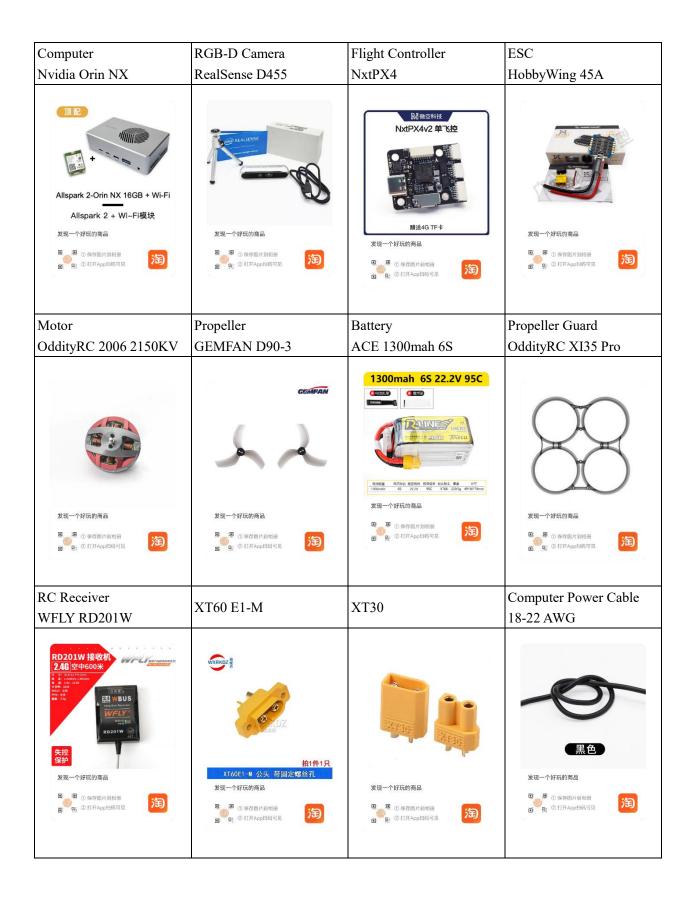
Fig. 2 High-Speed: Achieving 8 m/s Fig. 3 Agile: Achieving 6 m/s target Fig. 4 Ample Computing: Remaining tracking in dense forest.

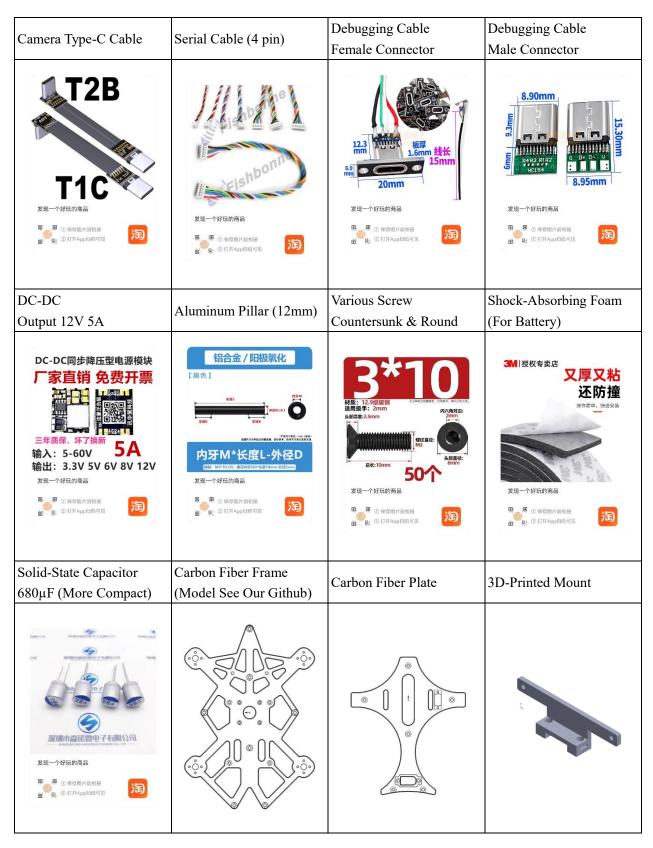
85% CPU and 75% GPU while running VINS, YOPO, and others.



Fig. 5 Sturdy: The drone successfully reaches the destination after suffering lateral collisions with trees at speeds of over 6 m/s.

The frame of the drone is custom-made from carbon fiber, and the camera mount is 3D printed (The SolidWorks file and frame model can be found in https://github.com/TJU-Aerial-Robotics/YOPO). The important modules are listed as follows and some other essentials (e.g., electrical tape, heat shrink tubing, 3M double-sided tape, Velcro strap, M2-M3 screws and nuts, etc.) are omitted for brevity.





Finally, if our work benefits your research, we would greatly appreciate it if you could cite our related papers.

[1] J. Lu, X. Zhang, H. Shen, L. Xu and B. Tian, "You Only Plan Once: A Learning-Based One-Stage Planner With Guidance Learning," in *IEEE Robotics and Automation Letters*, vol. 9, no. 7, pp. 6083-6090, July 2024, doi: 10.1109/LRA.2024.3399589.