

### 3. Multivariate Normal Distribution

The MVN distribution is a generalization of the univariate normal distribution which has the density function (p.d.f.)

$$f(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left\{-\frac{(x-\mu)^2}{2\sigma^2}\right\} \quad -\infty < x < \infty$$

where  $\mu$  = mean of distribution,  $\sigma^2$  = variance. In  $p$ -dimensions the density becomes

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2}(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu})\right\} \quad (3.1)$$

Within the mean vector  $\boldsymbol{\mu}$  there are  $p$  (independent) parameters and within the symmetric covariance matrix  $\Sigma$  there are  $\frac{1}{2}p(p+1)$  independent parameters [ $\frac{1}{2}p(p+3)$  independent parameters in total]. We use the notation

$$\mathbf{x} \sim N_p(\boldsymbol{\mu}, \Sigma) \quad (3.2)$$

to denote a RV  $\mathbf{x}$  having the  $p$ -variate MVN distribution with

$$\begin{aligned} \mathbb{E}(\mathbf{x}) &= \boldsymbol{\mu} \\ \text{Cov}(\mathbf{x}) &= \Sigma \end{aligned}$$

Note that MVN distributions are entirely characterized by the first and second moments of the distribution.

#### 3.1 Basic properties

If  $\mathbf{x}$  ( $p \times 1$ ) is MVN with mean  $\boldsymbol{\mu}$  and covariance matrix  $\Sigma$

- Any linear combination of  $\mathbf{x}$  is MVN

Let  $\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{c}$  with  $\mathbf{A}$  ( $q \times p$ ) and  $\mathbf{c}$  ( $q \times 1$ ) then

$$\mathbf{y} \sim N_q(\boldsymbol{\mu}_y, \Sigma_y)$$

where  $\boldsymbol{\mu}_y = \mathbf{A}\boldsymbol{\mu} + \mathbf{c}$  and  $\Sigma_y = \mathbf{A}\Sigma\mathbf{A}^T$

- Any subset of variables in  $\mathbf{x}$  has a MVN distribution.
- If a set of variables is uncorrelated, then they are independently distributed. In particular
  - i) if  $\sigma_{ij} = 0$  then  $x_i, x_j$  are independent.

ii) if  $\mathbf{x}$  is MVN with covariance matrix  $\Sigma$ , then  $\mathbf{Ax}$  and  $\mathbf{Bx}$  are independent if and only if

$$\begin{aligned} \text{Cov}(\mathbf{Ax}, \mathbf{Bx}) &= \mathbf{A}\Sigma\mathbf{B}^T \\ &= \mathbf{0} \end{aligned} \quad (3.3)$$

- Conditional distributions are MVN.

### Result

For the MVN distribution, variable are uncorrelated  $\Leftrightarrow$  variable are independent.

### Proof

Let  $\mathbf{x}$  ( $p \times 1$ ) be partitioned as

$$\mathbf{x} = \begin{bmatrix} \mathbf{x}_1 \\ \mathbf{x}_2 \end{bmatrix} \begin{matrix} q \\ p - q \end{matrix}$$

with mean vector

$$\boldsymbol{\mu} = \begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix} \begin{matrix} q \\ p - q \end{matrix}$$

and covariance matrix

$$\Sigma = \begin{bmatrix} q & p - q \\ \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} \begin{matrix} q \\ p - q \end{matrix}$$

- i) Independent  $\Rightarrow$  uncorrelated (always holds).

Suppose  $\mathbf{x}_1, \mathbf{x}_2$  are independent. Then  $f(\mathbf{x}_1, \mathbf{x}_2) = h(\mathbf{x}_1)g(\mathbf{x}_2)$  is a factorization of the multivariate p.d.f. and  $\Sigma_{12} = \text{Cov}(\mathbf{x}_1, \mathbf{x}_2) = \mathbb{E}[(\mathbf{x}_1 - \boldsymbol{\mu}_1)(\mathbf{x}_2 - \boldsymbol{\mu}_2)^T]$  factorizes into the product of  $\mathbb{E}[(\mathbf{x}_1 - \boldsymbol{\mu}_1)]$  and  $\mathbb{E}[(\mathbf{x}_2 - \boldsymbol{\mu}_2)^T]$  which are both zero since  $\mathbb{E}(\mathbf{x}_1) = \boldsymbol{\mu}_1$  and  $\mathbb{E}(\mathbf{x}_2) = \boldsymbol{\mu}_2$ . Hence  $\Sigma_{12} = 0$ .

- ii) Uncorrelated  $\Rightarrow$  independent (for MVN)

This result depends on factorizing the p.d.f. (3.1) when  $\Sigma_{12} = 0$ .

In this case  $(\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu})$  has the partitioned form

$$\begin{aligned} & \begin{bmatrix} \mathbf{x}_1^T - \boldsymbol{\mu}_1^T & \mathbf{x}_2^T - \boldsymbol{\mu}_2^T \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \mathbf{0} \\ \mathbf{0} & \Sigma_{22} \end{bmatrix}^{-1} \begin{bmatrix} \mathbf{x}_1 - \boldsymbol{\mu}_1 \\ \mathbf{x}_2 - \boldsymbol{\mu}_2 \end{bmatrix} \\ &= \begin{bmatrix} \mathbf{x}_1^T - \boldsymbol{\mu}_1^T & \mathbf{x}_2^T - \boldsymbol{\mu}_2^T \end{bmatrix} \begin{bmatrix} \Sigma_{11}^{-1} & \mathbf{0} \\ \mathbf{0} & \Sigma_{22}^{-1} \end{bmatrix} \begin{bmatrix} \mathbf{x}_1 - \boldsymbol{\mu}_1 \\ \mathbf{x}_2 - \boldsymbol{\mu}_2 \end{bmatrix} \\ &= (\mathbf{x}_1 - \boldsymbol{\mu}_1)^T \Sigma_{11}^{-1} (\mathbf{x}_1 - \boldsymbol{\mu}_1) + (\mathbf{x}_2 - \boldsymbol{\mu}_2)^T \Sigma_{22}^{-1} (\mathbf{x}_2 - \boldsymbol{\mu}_2) \end{aligned}$$

so that  $\exp\{(\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x} - \boldsymbol{\mu})\}$  factorizes into the product of  $\exp\{(\mathbf{x}_1 - \boldsymbol{\mu}_1)^T \boldsymbol{\Sigma}_{11}^{-1} (\mathbf{x}_1 - \boldsymbol{\mu}_1)\}$  and  $\exp\{(\mathbf{x}_2 - \boldsymbol{\mu}_2)^T \boldsymbol{\Sigma}_{22}^{-1} (\mathbf{x}_2 - \boldsymbol{\mu}_2)\}$ . Therefore the p.d.f. can be written as

$$f(\mathbf{x}) = g(\mathbf{x}_1) h(\mathbf{x}_2)$$

proving that  $\mathbf{x}_1$  and  $\mathbf{x}_2$  are independent. ■

### 3.2 Conditional distribution

Let  $\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \begin{matrix} q \\ p-q \end{matrix}$  be a partitioned MVN random  $p$ -vector, with mean  $\boldsymbol{\mu} = \begin{bmatrix} \boldsymbol{\mu}_1 \\ \boldsymbol{\mu}_2 \end{bmatrix}$  and covariance matrix

$$\boldsymbol{\Sigma} = \begin{bmatrix} \boldsymbol{\Sigma}_{11} & \boldsymbol{\Sigma}_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{bmatrix}$$

The conditional distribution of  $\mathbf{X}_2$  given  $\mathbf{X}_1 = \mathbf{x}_1$  is MVN with

$$\mathbb{E}(\mathbf{X}_2 | \mathbf{X}_1 = \mathbf{x}_1) = \boldsymbol{\mu}_2 + \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} (\mathbf{x}_1 - \boldsymbol{\mu}_1) \quad (3.4a)$$

$$\text{Cov}(\mathbf{X}_2 | \mathbf{X}_1 = \mathbf{x}_1) = \boldsymbol{\Sigma}_{22} - \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{12} \quad (3.4b)$$

**Note:** the notation  $\mathbf{X}_1$  to denote the *r.v.* and  $\mathbf{x}_1$  to denote a specific constant value (realization of  $\mathbf{X}_1$ ) will be very useful here.

#### Proof of 3.4a

Define a transformation from  $(\mathbf{X}_1, \mathbf{X}_2)$  to new variables  $\mathbf{X}_1$  and  $\mathbf{X}'_2 = \mathbf{X}_2 - \boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} \mathbf{X}_1$ . This is achieved by the linear transformation

$$\begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}'_2 \end{bmatrix} = \begin{bmatrix} \mathbf{I} & \mathbf{0} \\ -\boldsymbol{\Sigma}_{21} \boldsymbol{\Sigma}_{11}^{-1} & \mathbf{I} \end{bmatrix} \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix} \quad (3.5a)$$

$$= \mathbf{A} \mathbf{X} \quad \text{say.} \quad (3.5b)$$

This linear relationship shows that  $\mathbf{X}_1, \mathbf{X}'_2$  are jointly MVN (by first property of MVN stated above.)

We now show that  $\mathbf{X}'_2$  and  $\mathbf{X}_1$  are *independent* by proving that  $\mathbf{X}_1$  and  $\mathbf{X}'_2$  are uncorrelated.

*Approach 1:*

$$\begin{aligned}
Cov(\mathbf{X}_1, \mathbf{X}_2') &= Cov(\mathbf{X}_1, \mathbf{X}_2 - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{X}_1) \\
&= Cov(\mathbf{X}_1, \mathbf{X}_2) - Cov(\mathbf{X}_1, \mathbf{X}_1)\Sigma_{11}^{-1}\Sigma_{12} \\
&= \Sigma_{12} - \Sigma_{11}\Sigma_{11}^{-1}\Sigma_{12} \\
&= \mathbf{0}
\end{aligned}$$

Approach 2:

In (3.3), write  $\mathbf{A} = \begin{bmatrix} \mathbf{B} \\ \mathbf{C} \end{bmatrix}$  where  $\mathbf{B} = \begin{bmatrix} \mathbf{I} & \mathbf{0} \end{bmatrix}$  and  $\mathbf{C} = \begin{bmatrix} -\Sigma_{21}\Sigma_{11}^{-1} & \mathbf{I} \end{bmatrix}$

$$\begin{aligned}
Cov(\mathbf{X}_1, \mathbf{X}_2') &= Cov(\mathbf{B}\mathbf{X}, \mathbf{C}\mathbf{X}) \\
&= \mathbf{B}\Sigma\mathbf{C}^T \\
&= \begin{bmatrix} \mathbf{I} & \mathbf{0} \end{bmatrix} \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix} \begin{bmatrix} -\Sigma_{11}^{-1}\Sigma_{12} \\ \mathbf{I} \end{bmatrix} \\
&= \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \end{bmatrix} \begin{bmatrix} -\Sigma_{11}^{-1}\Sigma_{12} \\ \mathbf{I} \end{bmatrix} \\
&= \mathbf{0}
\end{aligned}$$

Since  $\mathbf{X}_2'$  and  $\mathbf{X}_1$  are MVN and uncorrelated they are independent. Thus

$$\begin{aligned}
\mathbb{E}(\mathbf{X}_2' | \mathbf{X}_1 = \mathbf{x}_1) &= \mathbb{E}(\mathbf{X}_2') \\
&= \mathbb{E}(\mathbf{X}_2 - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{X}_1) \\
&= \boldsymbol{\mu}_2 - \Sigma_{21}\Sigma_{11}^{-1}\boldsymbol{\mu}_1
\end{aligned}$$

Now, as  $\mathbf{X}_2' = \mathbf{X}_2 - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{X}_1$  and  $\mathbf{X}_1 = \mathbf{x}_1$  is given, we have

$$\begin{aligned}
\mathbb{E}(\mathbf{X}_2 | \mathbf{X}_1 = \mathbf{x}_1) &= \mathbb{E}(\mathbf{X}_2' | \mathbf{X}_1 = \mathbf{x}_1) + \Sigma_{21}\Sigma_{11}^{-1}\mathbf{x}_1 \\
&= \boldsymbol{\mu}_2 - \Sigma_{21}\Sigma_{11}^{-1}\boldsymbol{\mu}_1 + \Sigma_{21}\Sigma_{11}^{-1}\mathbf{x}_1 \\
&= \boldsymbol{\mu}_2 + \Sigma_{21}\Sigma_{11}^{-1}(\mathbf{x}_1 - \boldsymbol{\mu}_1)
\end{aligned}$$

as required.

#### Proof of 3.4b

Because  $\mathbf{X}_2'$  is independent of  $\mathbf{X}_1$

$$Cov(\mathbf{X}_2' | \mathbf{X}_1 = \mathbf{x}_1) = Cov(\mathbf{X}_2')$$

The left hand side is

$$\begin{aligned}
LHS &= Cov(\mathbf{X}'_2 | \mathbf{X}_1 = \mathbf{x}_1) \\
&= Cov(\mathbf{X}_2 - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{x}_1 | \mathbf{X}_1 = \mathbf{x}_1) \\
&= Cov(\mathbf{X}_2 | \mathbf{X}_1 = \mathbf{x}_1)
\end{aligned}$$

The right hand side is

$$\begin{aligned}
RHS &= Cov(\mathbf{X}'_2) \\
&= Cov(\mathbf{X}_2 - \Sigma_{21}\Sigma_{11}^{-1}\mathbf{X}_1) \\
&= \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12}
\end{aligned}$$

following from the general expansion

$$\begin{aligned}
Cov(\mathbf{X}_2 - \mathbf{D}\mathbf{X}_1) &= Cov(\mathbf{X}_2, \mathbf{X}_2) - \mathbf{D}Cov(\mathbf{X}_1, \mathbf{X}_2) \\
&\quad - Cov(\mathbf{X}_2, \mathbf{X}_1)\mathbf{D}^T + \mathbf{D}Cov(\mathbf{X}_1, \mathbf{X}_1)\mathbf{D}^T
\end{aligned}$$

with  $\mathbf{D} = \Sigma_{21}\Sigma_{11}^{-1}$ . Therefore

$$Cov(\mathbf{X}_2 | \mathbf{X}_1 = \mathbf{x}_1) = \Sigma_{22} - \Sigma_{21}\Sigma_{11}^{-1}\Sigma_{12}$$

as required.

### Example

Let  $\mathbf{x}$  have a MVN distribution with covariance matrix

$$\Sigma = \begin{bmatrix} 1 & \rho & \rho^2 \\ \rho & 1 & 0 \\ \rho^2 & 0 & 1 \end{bmatrix}$$

Show that the conditional distribution of  $(X_1, X_2)$  given  $X_3 = x_3$  is also MVN with mean

$$\boldsymbol{\mu} = \begin{bmatrix} \mu_1 + \rho^2(x_3 - \mu_3) \\ \mu_2 \end{bmatrix}$$

and covariance matrix

$$\begin{bmatrix} 1 - \rho^4 & \rho \\ \rho & 1 \end{bmatrix}$$

### Solution

Let  $\mathbf{Y}_1 = \begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$  and  $\mathbf{Y}_2 = (X_3)$  then

$$\begin{aligned}\mathbb{E}\mathbf{Y}_1 &= \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} \\ \mathbb{E}\mathbf{Y}_2 &= (\mu_3).\end{aligned}$$

We have  $Cov \begin{bmatrix} \mathbf{Y}_1 \\ \mathbf{Y}_2 \end{bmatrix} = \begin{bmatrix} \Sigma_{11} & \Sigma_{12} \\ \Sigma_{21} & \Sigma_{22} \end{bmatrix}$  where

$$\begin{aligned}\Sigma_{11} &= \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} \\ \Sigma_{12} &= \begin{bmatrix} \rho^2 \\ 0 \end{bmatrix} = \Sigma_{21}^T \\ \Sigma_{22} &= [1]\end{aligned}$$

Hence

$$\begin{aligned}\mathbb{E}[\mathbf{Y}_1 | \mathbf{Y}_2 = x_3] &= \boldsymbol{\mu}_1 + \Sigma_{12}\Sigma_{22}^{-1}(x_3 - \mu_3) \\ &= \begin{bmatrix} \mu_1 \\ \mu_2 \end{bmatrix} + \begin{bmatrix} \rho^2 \\ 0 \end{bmatrix} (x_3 - \mu_3) \\ &= \begin{bmatrix} \mu_1 + \rho^2(x_3 - \mu_3) \\ \mu_2 \end{bmatrix}\end{aligned}$$

and .

$$\begin{aligned}Cov[\mathbf{Y}_1 | \mathbf{Y}_2 = x_3] &= \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21} \\ &= \begin{bmatrix} 1 & \rho \\ \rho & 1 \end{bmatrix} - \begin{bmatrix} \rho^2 \\ 0 \end{bmatrix} \begin{bmatrix} \rho^2 & 0 \end{bmatrix} \\ &= \begin{bmatrix} 1 - \rho^4 & \rho \\ \rho & 1 \end{bmatrix}\end{aligned}$$

### 3.3 Maximum-likelihood estimation

Let  $\mathbf{X}^T = (\mathbf{x}_1, \dots, \mathbf{x}_n)$  contain an independent random sample of size  $n$  from  $N_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$ .

The maximum likelihood estimates (MLE 's) of  $\boldsymbol{\mu}, \boldsymbol{\Sigma}$  are the sample mean and covariance matrix (with divisor  $n$ )

$$\hat{\boldsymbol{\mu}} = \bar{\mathbf{x}} \tag{3.6a}$$

$$\hat{\boldsymbol{\Sigma}} = \mathbf{S} \tag{3.6b}$$

The likelihood function is a function of the parameters  $\boldsymbol{\mu}, \boldsymbol{\Sigma}$  given the data  $\mathbf{X}$

$$L(\boldsymbol{\mu}, \boldsymbol{\Sigma} | \mathbf{X}) = \prod_{r=1}^n f(\mathbf{x}_r | \boldsymbol{\mu}, \boldsymbol{\Sigma}) \quad (3.7)$$

The RHS is evaluated by substituting the individual data vectors  $\{\mathbf{x}_1, \dots, \mathbf{x}_n\}$  in turn into the p.d.f. of  $N_p(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  and taking the product.

$$\begin{aligned} \prod_{r=1}^n f(\mathbf{x}_r | \boldsymbol{\mu}, \boldsymbol{\Sigma}) &= (2\pi)^{-\frac{np}{2}} |\boldsymbol{\Sigma}|^{-n/2} \\ &\quad \exp \left\{ -\frac{1}{2} \sum_{r=1}^n (\mathbf{x}_r - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_r - \boldsymbol{\mu}) \right\} \end{aligned}$$

Maximizing  $L$  is equivalent to *minimizing* the "log likelihood" function

$$\begin{aligned} l(\boldsymbol{\mu}, \boldsymbol{\Sigma}) &= -2 \log L \\ &= -2 \sum_{r=1}^n \log f(\mathbf{x}_r | \boldsymbol{\mu}, \boldsymbol{\Sigma}) \\ &= K + n \log |\boldsymbol{\Sigma}| + \sum_{r=1}^n (\mathbf{x}_r - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_r - \boldsymbol{\mu}) \end{aligned} \quad (3.8)$$

where  $K$  is a constant independent of  $\boldsymbol{\mu}, \boldsymbol{\Sigma}$ .

### Result 3.3

$$l(\boldsymbol{\mu}, \boldsymbol{\Sigma}) = n \{ \log |\boldsymbol{\Sigma}| + \text{tr} [\boldsymbol{\Sigma}^{-1} (\mathbf{S} + \mathbf{d}\mathbf{d}^T)] \} \quad (3.9)$$

up to an additive constant, where  $\mathbf{d} = \bar{\mathbf{x}} - \boldsymbol{\mu}$ .

### Proof

Noting that  $\mathbf{x}_r - \boldsymbol{\mu} = (\mathbf{x}_r - \bar{\mathbf{x}}) + \mathbf{d}$  the final term in the likelihood expression (3.8) becomes

$$\begin{aligned} &\sum_{r=1}^n (\mathbf{x}_r - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_r - \boldsymbol{\mu}) \\ &= \sum_{r=1}^n (\mathbf{x}_r - \bar{\mathbf{x}})^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_r - \bar{\mathbf{x}}) + n \mathbf{d}^T \boldsymbol{\Sigma}^{-1} \mathbf{d} \\ &= n \text{tr} (\boldsymbol{\Sigma}^{-1} \mathbf{S}) + n \mathbf{d}^T \boldsymbol{\Sigma}^{-1} \mathbf{d} \\ &= n \text{tr} [\boldsymbol{\Sigma}^{-1} (\mathbf{S} + \mathbf{d}\mathbf{d}^T)] \end{aligned}$$

proving the expression (3.9). Note that the cross-product terms have vanished because  $\sum_{r=1}^n \mathbf{x}_r =$

$n\bar{\mathbf{x}}$  and therefore

$$\begin{aligned}\sum_{r=1}^n \mathbf{d}^T \boldsymbol{\Sigma}^{-1} (\mathbf{x}_r - \bar{\mathbf{x}}) &= \mathbf{d}^T \boldsymbol{\Sigma}^{-1} \sum_{r=1}^n (\mathbf{x}_r - \bar{\mathbf{x}}) \\ &= \sum_{r=1}^n (\mathbf{x}_r - \bar{\mathbf{x}})^T \boldsymbol{\Sigma}^{-1} \mathbf{d} \\ &= 0\end{aligned}$$

In (3.9) the dependence on  $\boldsymbol{\mu}$  is entirely through  $\mathbf{d}$ . Now assume that is positive definite (p.d.), then so is  $\boldsymbol{\Sigma}^{-1}$  as

$$\boldsymbol{\Sigma}^{-1} = \mathbf{V} \boldsymbol{\Lambda}^{-1} \mathbf{V}^T$$

where  $\boldsymbol{\Sigma} = \mathbf{V} \boldsymbol{\Lambda} \mathbf{V}^T$  is the eigenanalysis of  $\boldsymbol{\Sigma}$ . Thus  $\forall \mathbf{d} \neq \mathbf{0}$  we have  $\mathbf{d}^T \boldsymbol{\Sigma}^{-1} \mathbf{d} > 0$ . Hence  $l(\boldsymbol{\mu}, \boldsymbol{\Sigma})$  is minimized with respect to  $\boldsymbol{\mu}$  for fixed  $\boldsymbol{\Sigma}$  when  $\mathbf{d} = \mathbf{0}$  i.e.

$$\hat{\boldsymbol{\mu}} = \bar{\mathbf{x}}$$

*Final part of proof:* to minimize the log-likelihood  $l(\hat{\boldsymbol{\mu}}, \boldsymbol{\Sigma})$  w.r.t.  $\boldsymbol{\Sigma}$  let

$$\begin{aligned}l(\hat{\boldsymbol{\mu}}, \boldsymbol{\Sigma}) &= n \{ \log |\boldsymbol{\Sigma}| + \text{tr}(\boldsymbol{\Sigma}^{-1} \mathbf{S}) \} \\ &= \Phi(\boldsymbol{\Sigma})\end{aligned}\tag{3.10}$$

We show that

$$\begin{aligned}\Phi(\boldsymbol{\Sigma}) - \Phi(\mathbf{S}) &= n \{ \log |\boldsymbol{\Sigma}| - \log |\mathbf{S}| + \text{tr}(\boldsymbol{\Sigma}^{-1} \mathbf{S}) - p \} \\ &= n \{ \text{tr}(\boldsymbol{\Sigma}^{-1} \mathbf{S}) - \log |\boldsymbol{\Sigma}^{-1} \mathbf{S}| - p \} \\ &\geq 0\end{aligned}\tag{3.11}$$

### Lemma 1

$\boldsymbol{\Sigma}^{-1} \mathbf{S}$  is positive semi-definite (proved elsewhere). Therefore the eigenvalues of  $\boldsymbol{\Sigma}^{-1} \mathbf{S}$  are positive.

### Lemma 2

For any set of positive numbers

$$A \geq \log G + 1$$

where  $A$  and  $G$  are the arithmetic, geometric means respectively.

### Proof



For all  $x$  we have  $e^x \geq 1 + x$  (simple exercise). Consider a set of  $n$  strictly positive numbers  $\{y_i\}$

$$\begin{aligned} y_i &\geq 1 + \log y_i \\ \sum y_i &\geq n + \sum \log y_i \\ A &\geq 1 + \log \left( \prod y_i \right)^{\frac{1}{n}} \\ &= 1 + \log G \end{aligned}$$

as required.

Recall that for any  $(n \times n)$  matrix  $\mathbf{A}$ , we have  $\text{tr}(\mathbf{A}) = \sum_{i=1}^n \lambda_i$  the sum of the eigenvalues, and  $|\mathbf{A}| = \prod \lambda_i$  the product of the eigenvalues. Let  $\lambda_i$  ( $i = 1, \dots, p$ ) be the positive eigenvalues of  $\Sigma^{-1}\mathbf{S}$  and substitute in (3.11)

$$\begin{aligned} \log |\Sigma^{-1}\mathbf{S}| &= \log \left( \prod \lambda_i \right) \\ &= p \log G \end{aligned}$$

$$\begin{aligned} \text{tr}(\Sigma^{-1}\mathbf{S}) &= \sum \lambda_i \\ &= pA \end{aligned}$$

Hence

$$\begin{aligned} \Phi(\Sigma) - \Phi(\mathbf{S}) &= np \{A - \log G - 1\} \\ &\geq 0 \end{aligned}$$

This proves that the MLE's are as stated in (3.6).

### 3.3 Sampling distribution of $\bar{\mathbf{x}}$ and $\mathbf{S}$

#### The Wishart distribution (Definition)

If  $\mathbf{M}$  ( $p \times p$ ) can be written  $\mathbf{M} = \mathbf{X}^T \mathbf{X}$  where  $\mathbf{X}$  ( $m \times p$ ) is a data matrix from  $N_p(\mathbf{0}, \Sigma)$  then  $\mathbf{M}$  is said to have a Wishart distribution with scale matrix  $\Sigma$  and degrees of freedom  $m$ . We write

$$\mathbf{M} \sim W_p(\Sigma, m) \quad (3.12)$$

When  $\Sigma = \mathbf{I}_p$  the distribution is said to be in standard form.

**Note:**

The Wishart distribution is the multivariate generalization of the chi-square  $\chi^2$  distribution

### Additive property of matrices with a Wishart distribution

Let  $\mathbf{M}_1, \mathbf{M}_2$  be matrices having the Wishart distribution

$$\begin{aligned}\mathbf{M}_1 &\sim W_p(\mathbf{\Sigma}, m_1) \\ \mathbf{M}_2 &\sim W_p(\mathbf{\Sigma}, m_2)\end{aligned}$$

independently, then

$$\mathbf{M}_1 + \mathbf{M}_2 \sim W_p(\mathbf{\Sigma}, m_1 + m_2)$$

This property follows from the definition of the Wishart distribution because data matrices are additive in the sense that if

$$\mathbf{X} = \begin{bmatrix} \mathbf{X}_1 \\ \mathbf{X}_2 \end{bmatrix}$$

is a combined data matrix consisting of  $m_1 + m_2$  rows then

$$\mathbf{X}^T \mathbf{X} = \mathbf{X}_1^T \mathbf{X}_1 + \mathbf{X}_2^T \mathbf{X}_2$$

is matrix (known as the "Gram matrix") formed from the combined data matrix  $\mathbf{X}$ .

#### Case of $p = 1$

When  $p = 1$  we know from the definition of  $\chi_r^2$  as the distribution of the sum of squares of  $r$  independent  $N(0, 1)$  variates that

$$\mathbf{M} = \sum_{i=1}^m x_i^2 \sim \sigma^2 \chi_m^2$$

so that

$$W_1(\sigma^2, m) \equiv \sigma^2 \chi_m^2$$

### Sampling distributions

Let  $\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_n$  be a random sample of size  $n$  from  $N_p(\boldsymbol{\mu}, \mathbf{\Sigma})$ . Then

1. The sample mean  $\bar{\mathbf{x}}$  has the normal distribution

$$\bar{\mathbf{x}} \sim N_p\left(\boldsymbol{\mu}, \frac{1}{n} \mathbf{\Sigma}\right)$$

2. The (scaled) sample covariance matrix has the Wishart distribution:

$$(n-1) \mathbf{S}_u \sim W_p(\mathbf{\Sigma}, n-1)$$

3. The distributions of  $\bar{\mathbf{x}}$  and  $\mathbf{S}_u$  are independent.

### 3.4 Estimators for special circumstances

#### 3.4.1 $\mu$ proportional to a given vector

Sometimes  $\mu$  is known to be proportional to a given vector, so  $\mu = k\mu_0$  with  $\mu_0$  being a known vector.

For example if  $\mathbf{x}$  represents a sample of repeated measurements then  $\mu = k\mathbf{1}$  where  $\mathbf{1} = (1, 1, \dots, 1)^T$  is the  $p$ -vector of 1's.

We find the MLE of  $k$  for this situation. Suppose  $\Sigma$  is known and  $\mu = k\mu_0$ . Let  $d_0 = \bar{x} - k\mu_0$ . The log likelihood is

$$\begin{aligned} l(k) &= -2 \log L \\ &= n \left[ \log |\Sigma| + \text{tr} \left\{ \Sigma^{-1} (\mathbf{S} + d_0 d_0^T) \right\} \right] \\ &= n \left[ \log |\Sigma| + \text{tr} \left( \Sigma^{-1} \mathbf{S} \right) + (\bar{x} - k\mu_0)^T \Sigma^{-1} (\bar{x} - k\mu_0) \right] \\ &= n \left[ \bar{x}^T \Sigma^{-1} \bar{x} - 2k\mu_0^T \Sigma^{-1} \bar{x} + k^2 \mu_0^T \Sigma^{-1} \mu_0 \right] \\ &\quad + \text{constant terms indept of } k \end{aligned}$$

Set  $\frac{dl}{dk} = 0$  to minimize  $l(k)$  w.r.t.  $k$

$$-2\mu_0^T \Sigma^{-1} \bar{x} + 2(\mu_0^T \Sigma^{-1} \mu_0) k = 0$$

from which

$$\hat{k} = \frac{\mu_0^T \Sigma^{-1} \bar{x}}{\mu_0^T \Sigma^{-1} \mu_0} \quad (3.13)$$

#### Properties

We now show that  $\hat{k}$  is an unbiased estimator of  $k$  and determine the variance of  $\hat{k}$

In (3.13)  $\hat{k}$  takes the form  $\frac{1}{\alpha} \mathbf{c}^T \bar{x}$  with  $\mathbf{c}^T = \mu_0^T \Sigma^{-1}$  and  $\alpha = \mu_0^T \Sigma^{-1} \mu_0$  so

$$\begin{aligned} \mathbb{E} \left[ \hat{k} \right] &= \frac{\mathbf{c}^T \mathbb{E} [\bar{x}]}{\alpha} \\ &= \frac{k \mathbf{c}^T \mu_0}{\alpha} \\ &= \frac{k \mu_0^T \Sigma^{-1} \mu_0}{\alpha} \end{aligned}$$

since  $\mathbb{E} [\bar{x}] = k\mu_0$ . Hence

$$\mathbb{E} \left[ \hat{k} \right] = k \quad (3.14)$$

showing that  $\hat{k}$  is an unbiased estimator.

Note that  $Var[\bar{\mathbf{x}}] = \frac{1}{n}\mathbf{\Sigma}$  and therefore that  $Var[\mathbf{c}^T \bar{\mathbf{x}}] = \frac{1}{n}\mathbf{c}^T \mathbf{\Sigma} \mathbf{c}$  we have

$$\begin{aligned} Var(\hat{k}) &= \frac{1}{n\alpha^2} \mathbf{c}^T \mathbf{\Sigma} \mathbf{c} \\ &= \frac{1}{n} \boldsymbol{\mu}_0^T \mathbf{\Sigma}^{-1} \mathbf{\Sigma} \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_0 (\boldsymbol{\mu}_0^T \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_0)^{-2} \\ &= \frac{1}{n \boldsymbol{\mu}_0^T \mathbf{\Sigma}^{-1} \boldsymbol{\mu}_0} \end{aligned} \quad (3.15)$$

### 3.4.2 Linear restriction on $\boldsymbol{\mu}$

We determine an estimator for  $\boldsymbol{\mu}$  to satisfy a linear restriction

$$\mathbf{A}\boldsymbol{\mu} = \mathbf{b}$$

where  $\mathbf{A}$  ( $m \times p$ ) and  $\mathbf{b}$  ( $m \times 1$ ) are given constants and  $\mathbf{\Sigma}$  is assumed to be known.

We write the restriction in vector form  $\mathbf{g}(\boldsymbol{\mu}) = \mathbf{0}$  and form the Lagrangean

$$\mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\lambda}) = l(\boldsymbol{\mu}) + 2\boldsymbol{\lambda}^T \mathbf{g}(\boldsymbol{\mu})$$

where  $\boldsymbol{\lambda}^T = (\lambda_1, \dots, \lambda_m)$  is a **vector** of Lagrange multipliers (the factor 2 is inserted just for convenience).

$$\begin{aligned} \mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\lambda}) &= l(\boldsymbol{\mu}) + 2\boldsymbol{\lambda}^T (\mathbf{A}\boldsymbol{\mu} - \mathbf{b}) \\ &= n \left\{ (\bar{\mathbf{x}} - \boldsymbol{\mu})^T \mathbf{\Sigma}^{-1} (\bar{\mathbf{x}} - \boldsymbol{\mu}) + 2\boldsymbol{\lambda}^T (\mathbf{A}\boldsymbol{\mu} - \mathbf{b}) \right\} \\ &\quad \text{ignore constant terms involving } \mathbf{\Sigma} \end{aligned}$$

Set  $\frac{d}{d\boldsymbol{\mu}} \mathcal{L}(\boldsymbol{\mu}, \boldsymbol{\lambda}) = \mathbf{0}$  using results from Example Sheet 2:

$$\begin{aligned} -2\mathbf{\Sigma}^{-1} (\bar{\mathbf{x}} - \boldsymbol{\mu}) + 2\mathbf{A}^T \boldsymbol{\lambda} &= \mathbf{0} \\ \bar{\mathbf{x}} - \boldsymbol{\mu} &= \mathbf{\Sigma} \mathbf{A}^T \boldsymbol{\lambda} \end{aligned} \quad (3.16)$$

We use the constraint  $\mathbf{A}\boldsymbol{\mu} = \mathbf{b}$  to evaluate the Lagrange multipliers  $\boldsymbol{\lambda}$ . Premultiply by  $\mathbf{A}$

$$\begin{aligned} \mathbf{A}\bar{\mathbf{x}} - \mathbf{b} &= \mathbf{A}\mathbf{\Sigma} \mathbf{A}^T \boldsymbol{\lambda} \\ \boldsymbol{\lambda} &= (\mathbf{A}\mathbf{\Sigma} \mathbf{A}^T)^{-1} (\mathbf{A}\bar{\mathbf{x}} - \mathbf{b}) \end{aligned}$$

Substitute into (3.16)

$$\boxed{\hat{\boldsymbol{\mu}} = \bar{\mathbf{x}} - \mathbf{\Sigma} \mathbf{A}^T (\mathbf{A}\mathbf{\Sigma} \mathbf{A}^T)^{-1} (\mathbf{A}\bar{\mathbf{x}} - \mathbf{b})} \quad (3.17)$$

### 3.4.3 Covariance matrix $\Sigma$ proportional to a given matrix

We consider estimating  $k$  when  $\Sigma = k\Sigma_0$ , where  $\Sigma_0$  is a given constant matrix. The likelihood (3.8) takes the form when  $\mathbf{d} = \mathbf{0}$  ( $\hat{\boldsymbol{\mu}} = \bar{\mathbf{x}}$ )

$$l(k) = n \left\{ \log |k\Sigma_0| + \text{tr} \left( \frac{1}{k} \Sigma_0^{-1} \mathbf{S} \right) \right\}$$

plus constant terms (not involving  $k$ ).

$$\begin{aligned} l(k) &= \left\{ p \log k + \frac{1}{k} \text{tr} (\Sigma_0^{-1} \mathbf{S}) \right\} \\ &\quad + \text{constant terms} \\ \frac{dl}{dk} &= 0 \Rightarrow \frac{p}{k} - \frac{1}{k^2} \text{tr} (\Sigma_0^{-1} \mathbf{S}) = 0 \end{aligned}$$

Hence

$$\boxed{\hat{k} = \frac{\text{tr} (\Sigma_0^{-1} \mathbf{S})}{p}} \tag{3.18}$$