

```

> with(plots)
[animate, animate3d, animatecurve, arrow, changecoords, complexplot,
complexplot3d, conformal, conformal3d, contourplot, contourplot3d,
coordplot, coordplot3d, densityplot, display, dualaxisplot, fieldplot,
fieldplot3d, gradplot, gradplot3d, implicitplot, implicitplot3d, inequal,
interactive, interactiveparams, intersectplot, listcontplot, listcontplot3d,
listdensityplot, listplot, listplot3d, loglogplot, logplot, matrixplot, multiple,
odeplot, pareto, plotcompare, pointplot, pointplot3d, polarplot,
polygonplot, polygonplot3d, polyhedra_supported, polyhedraplot,
rootlocus, semilogplot, setcolors, setoptions, setoptions3d, shadebetween,
spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]

```

```

> ec:=(D@@2)(x)(t)+w0^2*x(t)=0
ec := D(2)(x)(t) + w02 x(t) = 0

```

```

> sol_a:=dsolve(ec,x(t))
sol_a := x(t) = c1 sin(w0 t) + c2 cos(w0 t)

```

```

> sol_b:=subs({c__1=R*cos(delta), c__2=R*sin(delta)}, sol_a)
sol_b := x(t) = R cos(δ) sin(w0 t) + R sin(δ) cos(w0 t)

```

```

> sol_b:=combine(sol_b)
sol_b := x(t) = R sin(w0 t + δ)

```

```

> cond:=x(0)=x0,D(x)(0)=v0
cond := x(0) = x0, D(x)(0) = v0

```

```

> sol:=dsolve({ec,cond}, x(t))
sol := x(t) =  $\frac{v0 \sin(w0 t)}{w0} + x0 \cos(w0 t)$ 

```

```

> ec1:=R*cos(delta)=v0/w0
ec1 := R cos(δ) =  $\frac{v0}{w0}$ 

```

```

> ec2:=R*sin(delta)=x0
ec2 := R sin(δ) = x0

```

```

> sol_c:=solve({ec1,ec2},{R,delta})
sol_c :=  $\left\{ R = \frac{\text{RootOf}(-x0^2 w0^2 + Z^2 - v0^2)}{w0}, \delta \right.$ 
 $= \arctan\left( \frac{x0 w0}{\text{RootOf}(-x0^2 w0^2 + Z^2 - v0^2)} \right),$ 
 $\left. \frac{v0}{\text{RootOf}(-x0^2 w0^2 + Z^2 - v0^2)} \right\}$ 

```

```

> L:=39.24/100
L := 0.3924000000

```

```
> g:=9.81
```

$$g := 9.81 \quad (12)$$

```
> w0:=sqrt(g/L)
```

$$w0 := 5.000000000 \quad (13)$$

```
> x0:=15/100
```

$$x0 := \frac{3}{20} \quad (14)$$

```
> v0:=0
```

$$v0 := 0 \quad (15)$$

```
> evalf(sol_c)
```

$$\{R = 0.1500000000, \delta = 1.570796327\} \quad (16)$$

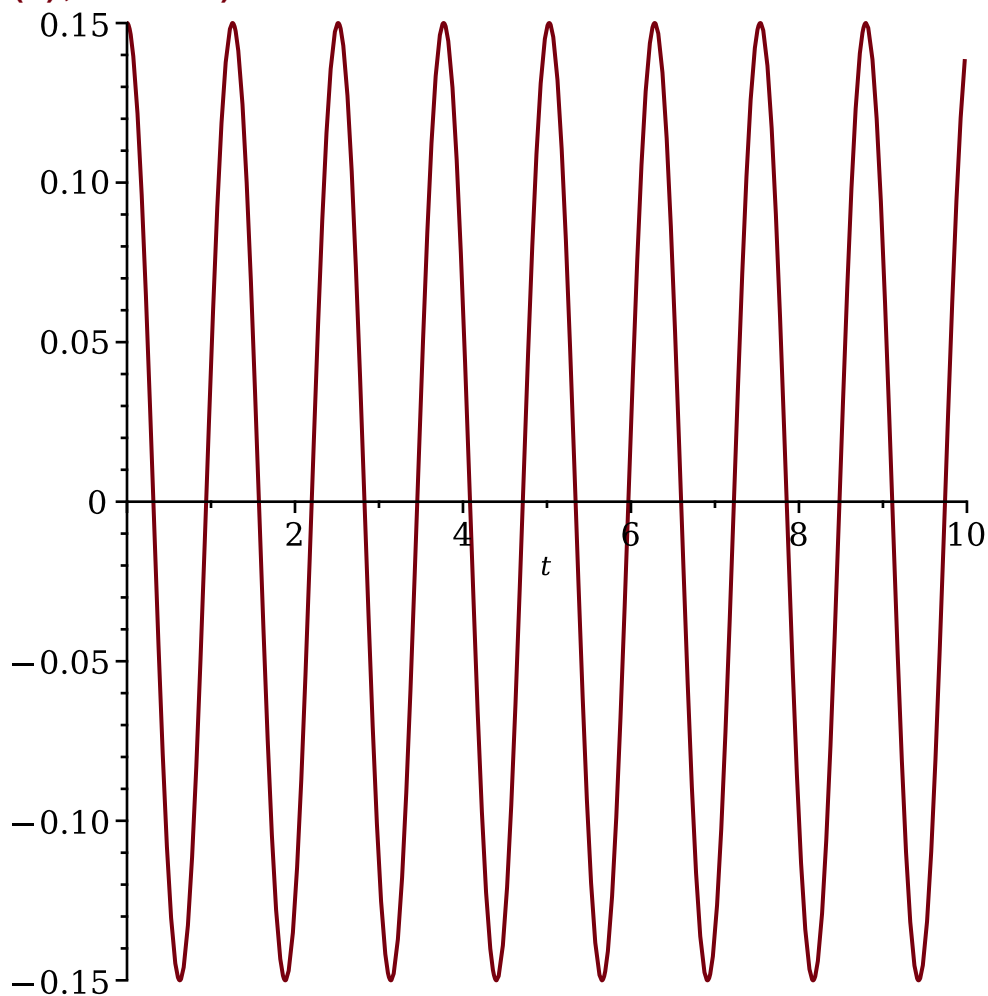
```
> sol_d:=evalf(sol)
```

$$sol_d := x(t) = 0.1500000000 \cos(5.000000000 t) \quad (17)$$

```
> y1:=unapply(rhs(sol_d),t)
```

$$y1 := t \mapsto 0.1500000000 \cdot \cos(5.000000000 \cdot t) \quad (18)$$

```
> plot(y1(t),t=0..10)
```



```
> restart
```

```
> with(plots)
```

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$$\begin{aligned} &> \text{ec} := (\text{D} @ \text{@} 2)(\text{x})(\text{t}) + \text{lambd}a * \text{D}(\text{x})(\text{t}) + \text{w0}^2 * \text{x}(\text{t}) = 0 \\ &\quad \text{ec} := \text{D}^{(2)}(\text{x})(\text{t}) + \lambda \text{D}(\text{x})(\text{t}) + \text{w0}^2 \text{x}(\text{t}) = 0 \end{aligned} \quad (20)$$

$$\begin{aligned} &> \text{sol_a} := \text{dsolve}(\{\text{ec}\}, \text{x}(\text{t})) \\ &\quad \text{sol_a} := \left\{ \text{x}(\text{t}) = c_1 e^{\left(-\frac{\lambda}{2} + \frac{\sqrt{\lambda^2 - 4 \text{w0}^2}}{2}\right) t} + c_2 e^{\left(-\frac{\lambda}{2} - \frac{\sqrt{\lambda^2 - 4 \text{w0}^2}}{2}\right) t} \right\} \end{aligned} \quad (21)$$

$$\begin{aligned} &> \text{lambd}a := 25 \\ &\quad \lambda := 25 \end{aligned} \quad (22)$$

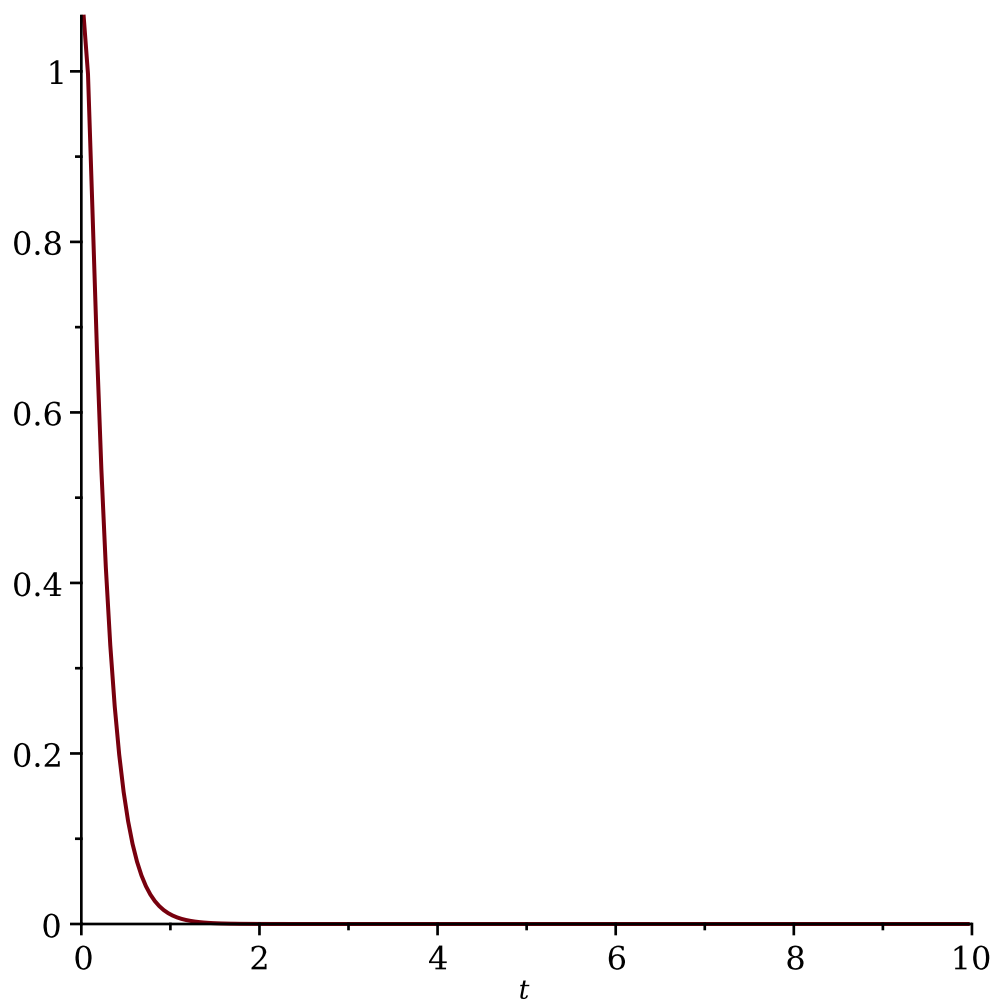
$$\begin{aligned} &> \text{w0} := 10 \\ &\quad \text{w0} := 10 \end{aligned} \quad (23)$$

$$\begin{aligned} &> \text{cond} := \text{x}(0) = 1, \text{D}(\text{x})(0) = 5 \\ &\quad \text{cond} := \text{x}(0) = 1, \text{D}(\text{x})(0) = 5 \end{aligned} \quad (24)$$

$$\begin{aligned} &> \text{sol_b} := \text{dsolve}(\{\text{ec}, \text{cond}\}, \text{x}(\text{t})) \\ &\quad \text{sol_b} := \text{x}(\text{t}) = \frac{5 e^{-5 t}}{3} - \frac{2 e^{-20 t}}{3} \end{aligned} \quad (25)$$

$$\begin{aligned} &> \text{y1} := \text{unapply}(\text{rhs}(\text{sol_b}), \text{t}) \\ &\quad \text{y1} := t \mapsto \frac{5 \cdot e^{-5 \cdot t}}{3} - \frac{2 \cdot e^{-20 \cdot t}}{3} \end{aligned} \quad (26)$$

> plot(y1(t), t=0..10)



```
> lambda:='lambda'
```

$$\lambda := \lambda \quad (27)$$

```
> w0:='wo'
```

$$w0 := wo \quad (28)$$

```
> ec_c:=(D@@2)(x)(t)+lambda*D(x)(t)+lambda^2/4*x(t)=0
```

$$ec_c := D^{(2)}(x)(t) + \lambda D(x)(t) + \frac{\lambda^2 x(t)}{4} = 0 \quad (29)$$

```
> sol_c:=dsolve(ec_c,x(t))
```

$$sol_c := x(t) = c_1 e^{-\frac{\lambda t}{2}} + c_2 e^{-\frac{\lambda t}{2}} t \quad (30)$$

```
> lambda:=20
```

$$\lambda := 20 \quad (31)$$

```
> w0:=10
```

$$w0 := 10 \quad (32)$$

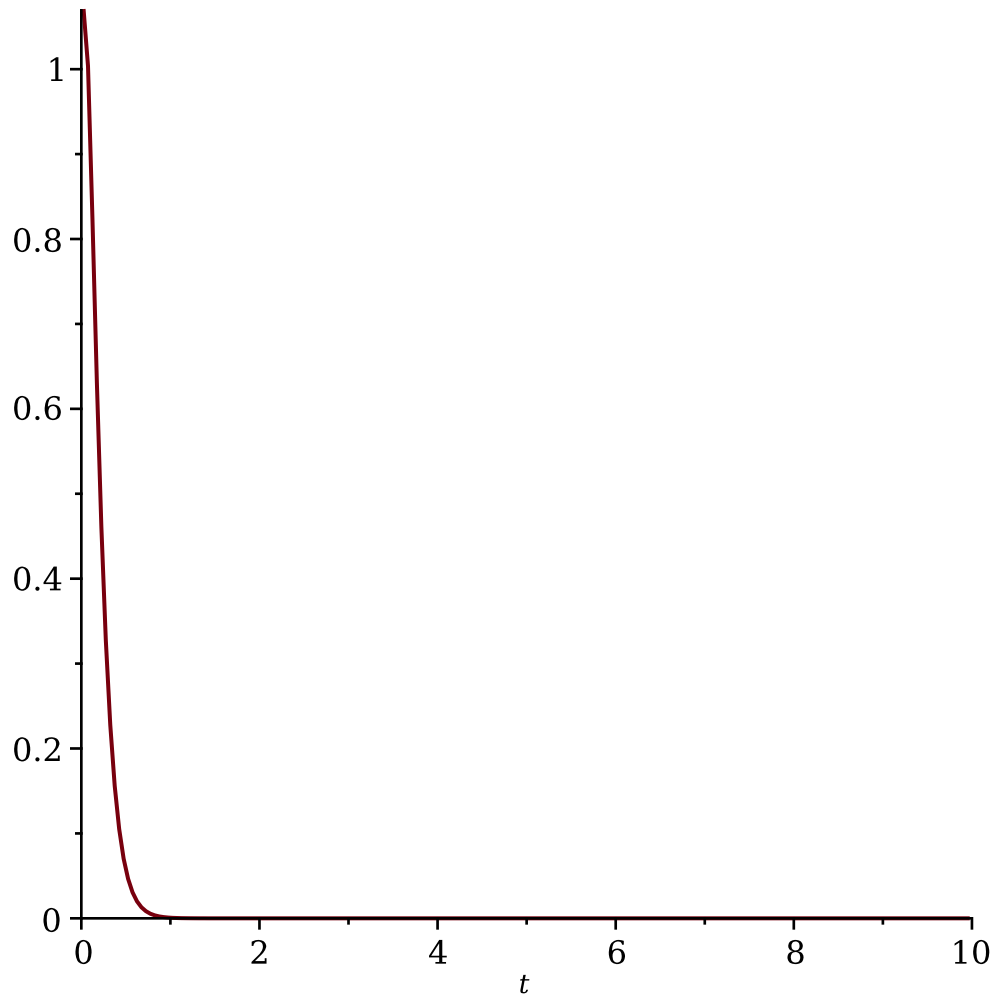
```
> sol_d:=dsolve({ec_c,cond},x(t))
```

$$sol_d := x(t) = e^{-10t} (1 + 15t) \quad (33)$$

```
> y2:=unapply(rhs(sol_d),t)
```

$$y2 := t \mapsto e^{-10t} \cdot (1 + 15 \cdot t) \quad (34)$$

```
> plot(y2(t),t=0..10)
```



```
> lambda:='lambda'
```

$\lambda := \lambda$

(35)

```
> w0:='wo'
```

$w0 := wo$

(36)

```
> assume (lambda^2<4*wo^2)
```

```
> sol_e:=dsolve({ec},x(t))
```

$$sol_e := \left\{ x(t) = c_1 e^{-\frac{\lambda t}{2}} \sin\left(\frac{\sqrt{-\lambda^2 + 4 wo^2} t}{2}\right) + c_2 e^{-\frac{\lambda t}{2}} \cos\left(\frac{\sqrt{-\lambda^2 + 4 wo^2} t}{2}\right) \right\}$$

(37)

```
> lambda:=5
```

$\lambda := 5$

(38)

```
> w0:=10
```

$w0 := 10$

(39)

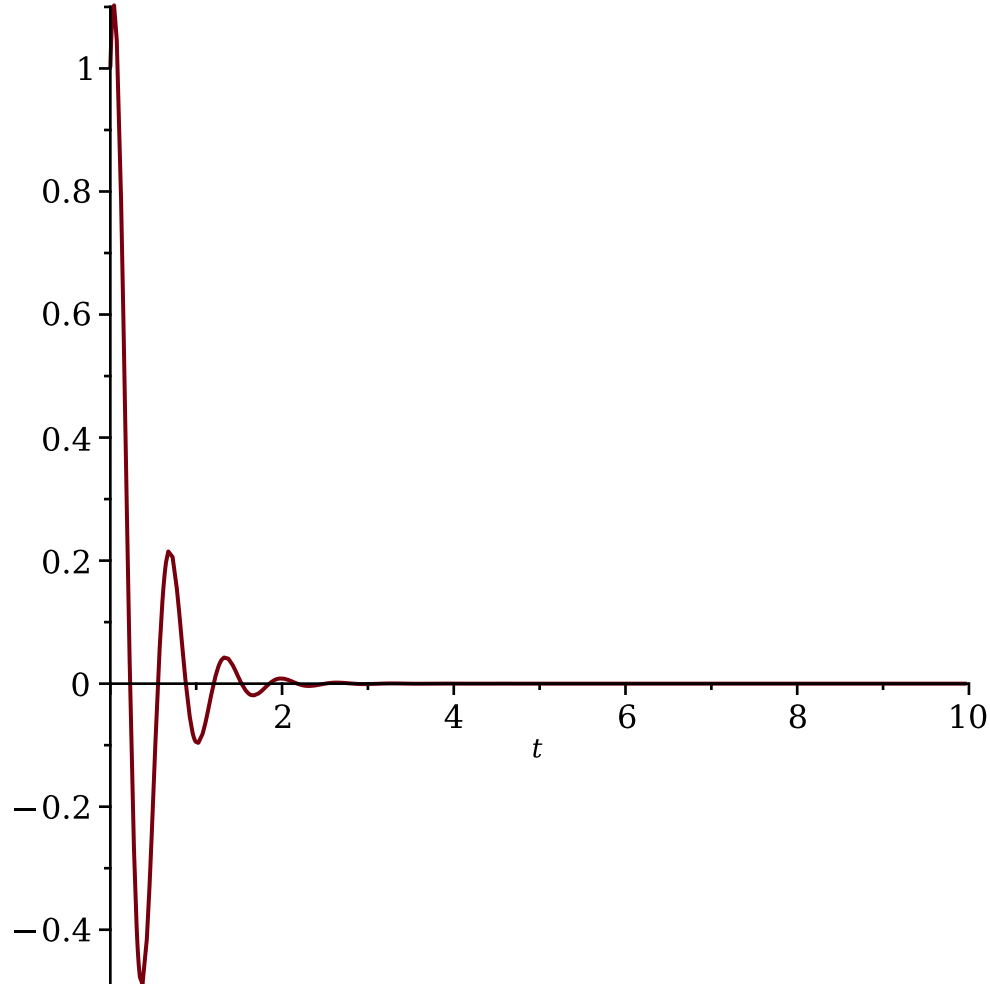
```
> sol_f:=dsolve({ec,cond},x(t))
```

$$\text{sol}_f := x(t) = \frac{e^{-\frac{5t}{2}} \left(\sqrt{15} \sin\left(\frac{5\sqrt{15}t}{2}\right) + 5 \cos\left(\frac{5\sqrt{15}t}{2}\right) \right)}{5} \quad (40)$$

> **y3:=unapply(rhs(sol_f),t)**

$$y3 := t \mapsto \frac{e^{-\frac{5t}{2}} \cdot \left(\sqrt{15} \cdot \sin\left(\frac{5 \cdot \sqrt{15} \cdot t}{2}\right) + 5 \cdot \cos\left(\frac{5 \cdot \sqrt{15} \cdot t}{2}\right) \right)}{5} \quad (41)$$

> **plot(y3(t),t=0..10)**



> **restart**

> **with(plots)**

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(42)

polygonplot, polygonplot3d, polyhedra_supported, polyhedraplot, rootlocus, semilogplot, setcolors, setoptions, setoptions3d, shadebetween, spacecurve, sparsematrixplot, surfdata, textplot, textplot3d, tubeplot]

$$\begin{aligned} > \text{ec} := (D @ @ 2)(x)(t) + w0^2 \cdot x(t) = F0 \cdot \cos(w \cdot t) \\ & \quad ec := D^{(2)}(x)(t) + w0^2 x(t) = F0 \cos(w t) \end{aligned} \quad (43)$$

$$> \text{sol_a} := \text{dsolve}(\text{ec}, x(t))$$

$$\text{sol_a} := x(t) = \sin(w0 t) c_2 + \cos(w0 t) c_1 - \frac{F0 \cos(w t)}{w^2 - w0^2} \quad (44)$$

$$\begin{aligned} > \text{cond} := x(0) = 0, D(x)(0) = 0 \\ & \quad \text{cond} := x(0) = 0, D(x)(0) = 0 \end{aligned} \quad (45)$$

$$\begin{aligned} > w0 := 5 \\ & \quad w0 := 5 \end{aligned} \quad (46)$$

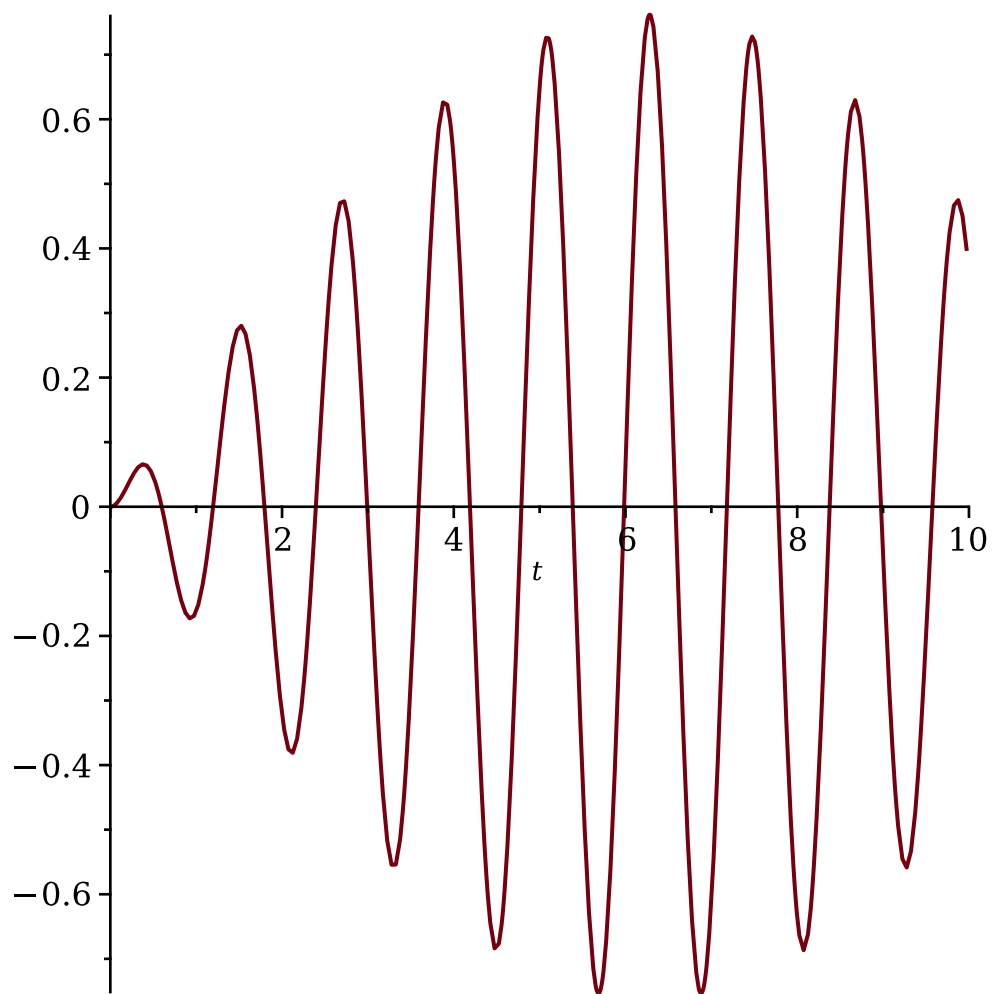
$$\begin{aligned} > w := 5.5 \\ & \quad w := 5.5 \end{aligned} \quad (47)$$

$$\begin{aligned} > F0 := 2 \\ & \quad F0 := 2 \end{aligned} \quad (48)$$

$$\begin{aligned} > \text{sol_b} := \text{dsolve}(\{\text{ec}, \text{cond}\}, x(t)) \\ & \quad \text{sol_b} := x(t) = \frac{8 \cos(5 t)}{21} - \frac{8 \cos\left(\frac{11 t}{2}\right)}{21} \end{aligned} \quad (49)$$

$$\begin{aligned} > y1 := \text{unapply}(\text{rhs}(\text{sol_b}), t) \\ & \quad y1 := t \mapsto \frac{8 \cdot \cos(5 \cdot t)}{21} - \frac{8 \cdot \cos\left(\frac{11 \cdot t}{2}\right)}{21} \end{aligned} \quad (50)$$

$$> \text{plot}(y1(t), t=0..10)$$



```
> w:='w'
```

$$w := w \quad (51)$$

```
> w0:='w0';F0:='F0'
```

$$\begin{aligned} w0 &:= w0 \\ F0 &:= F0 \end{aligned} \quad (52)$$

```
> ec_c:=(D@@2)(x)(t)+w^2*x(t)=F0*cos(w*t)
```

$$ec_c := D^{(2)}(x)(t) + w^2 x(t) = F0 \cos(w t) \quad (53)$$

```
> sol_c:=dsolve(ec_c,x(t))
```

$$sol_c := x(t) = \sin(w t) c_2 + \cos(w t) c_1 + \frac{F0 \sin(w t) t}{2 w} \quad (54)$$

```
> w:=5; F0:=2
```

$$\begin{aligned} w &:= 5 \\ F0 &:= 2 \end{aligned} \quad (55)$$

```
> sol_d:=dsolve({ec_c,cond},x(t))
```

$$sol_d := x(t) = \frac{\sin(5 t) t}{5} \quad (56)$$

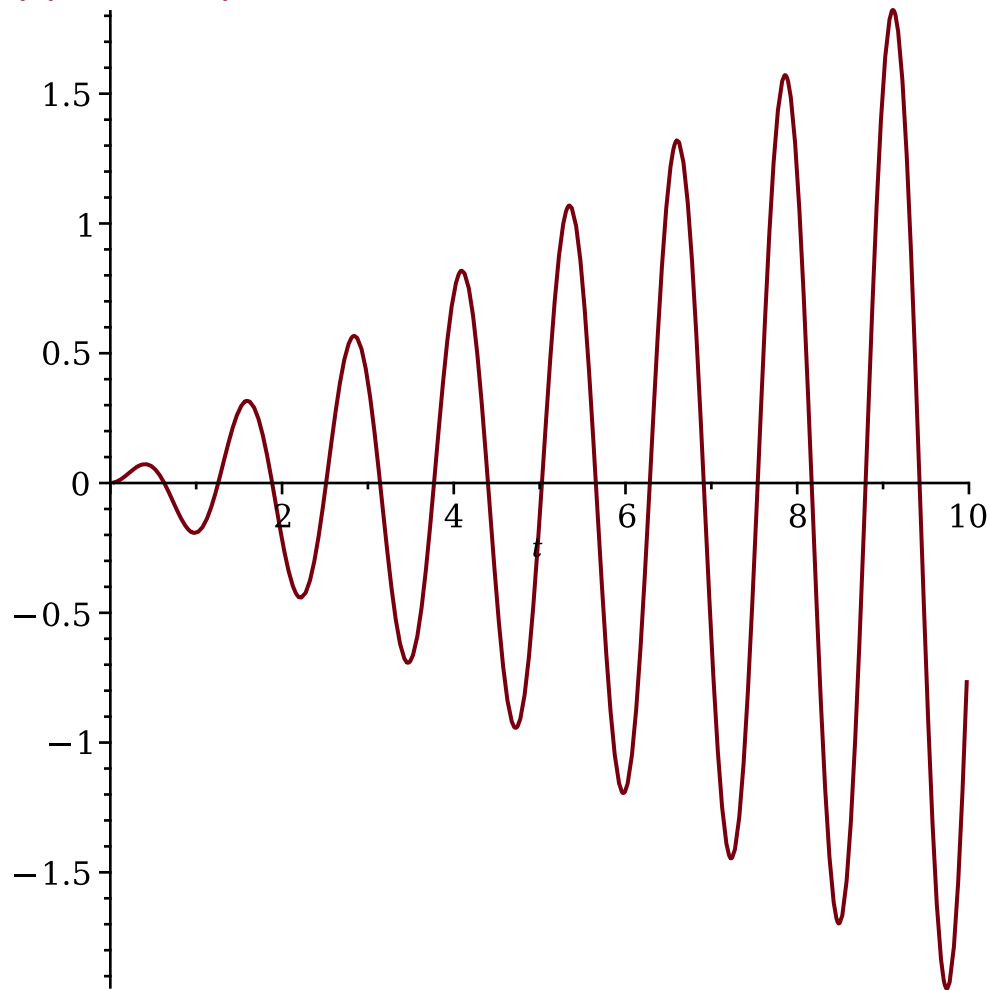
```
> y2:=unapply(rhs(sol_d),t)
```

$$(57)$$

$$y2 := t \mapsto \frac{\sin(5 \cdot t) \cdot t}{5}$$

(57)

> plot(y2(t), t=0..10)



> w:='w'; F0:='F0'

$w := w$

$F0 := F0$

(58)

> sol:=dsolve({ec,cond},x(t))

$$sol := x(t) = \frac{F0 (\cos(w0 t) - \cos(w t))}{w^2 - w0^2}$$

(59)

> y3:=unapply(rhs(sol),t,w)

$$y3 := (t, w) \mapsto \frac{F0 \cdot (\cos(w0 \cdot t) - \cos(w \cdot t))}{w^2 - w0^2}$$

(60)

> limit(y3(t,w),w=w0)

$$\frac{F0 \sin(w0 t) t}{2 w0}$$

(61)

> dsolve({ec_c,cond},x(t))

$$x(t) = \frac{F0 \sin(w t) t}{2 w}$$

(62)

