CS 3320 – Numerical Software Module 8 – Program "LU Factorization"

Write a program, named lud.py, that solves linear systems using the LU factorization with partial pivoting. Separate the factorization and the solution into two functions:

- 1. factor(A, n, pivot)
 - a. A is the square matrix of coefficients
 - b. n is the rank (number of rows/columns) of A
 - c. pivot is an output vector that records the partial pivoting swaps
- 2. solve (A, n, pivot, b, x)
 - a. A, n and pivot are from factor() (A is overwritten with its own LU factorization)
 - b. b is a right-hand side to solve for
 - c. x is an output vector with the solution of Ax = b

Write your main() function to process an arbitrary number of input files. Each file contains information for one linear system, with possibly multiple right-hand sides to solve for. For example, if the files lu1.dat and lu2.dat are as follows:

then the expected output to 2 decimals is as follows:

File lu2.dat:

```
L\U =5.00 3.00 -1.00 0.00

0.00 6.00 -2.00 3.00

0.40 -0.20 4.00 1.60

-0.60 0.80 -0.50 3.40

b = 11.00 1.00 -2.00 9.00

x = 1.00 2.00 -0.00 -1.00

b = 7.00 7.00 2.00 7.00

x = 1.00 1.00 1.00 1.00
```

The layout of the input files is:

```
<rank of system (number of rows)>
<the rows of the matrix, a>
<number of right-hand sides>
<the right hand sides>
```

Note that you are printing out the LU factorization that overwrites A. Be sure to check for invalid input, such as missing data (if you run out of numbers, print a message and continue to the next file). If you cannot find a non-zero pivot element during partial pivoting in factor(), then the system either has no solution or infinite number of solutions, return an error status (-1). Your program will then print a message indicating that the A matrix is singular then continue to the next file.