

# POINT KINETICS\*

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**Abstract.** This is an example SIAM L<sup>A</sup>T<sub>E</sub>X article. This can be used as a template for new articles. Abstracts must be able to stand alone and so cannot contain citations to the paper’s references, equations, etc. An abstract must consist of a single paragraph and be concise. Because of online formatting, abstracts must appear as plain as possible. Any equations should be inline.

**Key words.** example, L<sup>A</sup>T<sub>E</sub>X

**AMS subject classifications.** 68Q25, 68R10, 68U05

## 1. Point Kinetics and Reactor Dynamics.

**1.1. The Motivation for a Simpler Model.** Reactor dynamics are governed by the transport of energetic neutrons throughout the active core. In particular, we define the diffusion of these neutrons in Eq. (1.1).

$$(1.1) \quad \frac{\partial N(\vec{r}, t)}{\partial t} = Dv\nabla^2 N - \Sigma_a v N + S$$

where  $N(\vec{r}, t)$  and  $S(\vec{r}, t)$  are the neutron density and produced additional neutron density in some volume  $dV$  at location  $\vec{r}$  at time  $t$ .  $D$  is the diffusion constant;  $v$  is the neutron speed; and  $\Sigma_a$  is the macroscopic neutron absorption cross-section. (CITE)

Note that this partial differential equation effectively encodes the conservation of neutrons throughout the core. Neutrons in a given volume of fuel can: (1) move to an adjacent volume, (2) be absorbed in the given volume, or (3) be generated as a result of a fission within the volume.

This branching structure lends itself wonderfully to the use of Monte Carlo codes to simulate neutron transport in very high fidelity (CITE SERPENT). Unfortunately, modeling macroscopic reactor behavior with these high fidelity tools is infeasible. Coupling the thermalhydraulic behavior of the plant’s power conversion system to the dynamics of subatomic neutrons is computationally intractable. Consequently, we must create an abstraction from the neutronics to core-wide dynamics that effectively model important plant behavior without knowledge of individual neutrons. To do this, we use the Point Reactor model.

**1.2. The Point Reactor.** The point reactor model operates under a few critical assumptions. First, it is assumed that the neutrons included in  $N(\vec{r}, t)$  are all of a single energy (for our purposes, this is “fast”, rather than “thermal” energies). Additionally, our treatment of the neutron production term  $S(\vec{r}, t)$  in Eq. (1.1) must be formally defined for the point reactor. As shown in Eq. (1.2), produced neutrons can be of two types: *prompt* and *delayed*. Prompt neutrons are produced through direct fission of fuel nuclei, while delayed neutrons are the byproduct of fission-product decay significantly later than the prompt generation.

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$$(1.2) \quad S(\vec{r}, t) = \underbrace{(1 - \beta)k_{\infty}\Sigma_a v N}_{\text{prompt generation}} + \underbrace{\Sigma_i \lambda_i C_i}_{\text{delay generation}}$$

The proportionality constants shown in Eq. (1.2) are outside the scope of this analysis. However,  $C_i$  refers to the current concentration of “delayed neutron group”  $i$ . It has been shown that the inclusion of six delayed neutron groups constitutes a reasonably accurate approximation of reactor dynamics. (CITE FOR NEUTRON GROUPS - Keepin 1965)

The final, and most critical assumption the Point Reactor model makes can be defined as follows: (1) the densities of prompt and delay neutrons are separable in time and space, and (2) the spatial dependence of prompt neutron density matches that of delayed neutron density.

While the derivation of these final differential equations is outside the scope of this analysis, they are reproduced in Eqs. (1.3) and (1.4).

$$(1.3) \quad \frac{dn}{dt} = \frac{\rho - \beta}{\Lambda} n + \Sigma_i \lambda_i c_i$$

$$(1.4) \quad \frac{dc_i}{dt} = \frac{\beta_i}{\Lambda} n - \lambda_i c_i$$

Here, formal definition of the parameters is critical to understanding of the following analysis. Parameters are defined in Eqs. Equations (1.5)–(1.10).

(1.5)  $n$  = normalized number of neutrons in the core (effective reactor power)

(1.6)  $c_i$  = normalized number of delayed neutrons of group  $i$

(1.7)  $\rho$  = external reactivity (pcm)

(1.8)  $\beta$  = delayed neutron fraction ( $\Sigma_i \beta_i$ )

(1.9)  $\Lambda$  = mean neutron generation time (s)

(1.10)  $\lambda_i$  = precursor time constants (1/s)

This ordinary differential equation (ODE) constitutes the primary focus of this analysis.

**1.3. Important Concepts for this Analysis.** In order to fully understand the process by which we examine this dynamical system, one must be acquainted with the following terms that are used to describe particular features of a reactor transient.

**DEFINITION 1.1. *External Reactivity:*** External reactivity is defined as an artificial addition (or subtraction) of some fraction of the total reactor neutron population. We call any external reactivity, an “insertion”, whether or not it has positive or negative value. It is measured in pcm, or per cent mille (0.001%)

**DEFINITION 1.2. *Dollar (reactivity):*** One dollar of reactivity (\$) is defined as the reactivity required to cross the threshold from delayed criticality to prompt criticality. It is numerically equal to the  $\beta$  constant defined in Eq. (1.8).

**DEFINITION 1.3. *Prompt Criticality:*** *Prompt criticality refers to a reactor state in which a positive feedback nuclear chain reaction is sustained entirely by the generation of prompt neutrons. This differs from delayed criticality in that it does not require the presense of delayed neutron groups to maintain its fission chain reaction. Prompt criticality is characterised by fast spikes in power due to the short generation times for prompt neutrons.*

**1.4. Analytical Jacobian Analysis.** The form of the ODE defined in Eqs. (1.3) and (1.4), lead to an analytical definition of this system's Jacobian. (CITE GANOPOL) Particularly, our system is as defined in Eq. (1.11), so there exists a true form of the Jacobian, shown in Eq. (1.12).

$$(1.11) \quad \frac{du}{dt} = A(t)u$$

$$(1.12) \quad A(t) = \begin{pmatrix} \frac{\rho(t)-\beta}{\Lambda} & \lambda_1 & \lambda_2 & \cdots & \lambda_6 \\ \frac{\beta_1}{\Lambda} & -\lambda_1 & 0 & \cdots & 0 \\ \frac{\beta_2}{\Lambda} & 0 & -\lambda_2 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \frac{\beta_6}{\Lambda} & 0 & 0 & \cdots & -\lambda_6 \end{pmatrix}$$

Here,  $A(t)$  is the time dependent Jacobian for our dynamical system. Note the time independence for all but the prompt neutron term. This is a critical feature of the system. We can see that, at operating conditions where  $0 \leq \rho(t) < \beta = 1\$, all of the diagonal terms of our Jacobian are negative. This property ensures that the reactor is in a delayed critical state, and the unbounded growth in power is relatively slow. Transients in which  $\rho(t) \geq \beta = 1\$ have Jacobians with a positive diagonal element. This corresponds to the reactor going prompt critical, and the reactor power grows without bound millions of times faster than when it is delayed critical.$$

There are a few things to note: (1) the unbounded growth of reactor power seen in transients with positive  $\rho(t)$  parameters is a numerical result. In reality, nuclear material undergoes a “fizzle” (CITE) that limits this rapid overpower (except in the cases of nuclear weapons). This effect is not captured in the Point Reactor model, but does not affect solutions around the time of reactivity insertion. (2) For sections of a reactor transient timeseries over which  $\rho(t)$  is constant, there is an analytical solution to the dynamical system involving a series of exponential functions defined by the eigenvalues of  $A$ .

For the purposes of building a modeling tool that can aid in iterating reactor design, we focus our analysis on the efficacy of solver methods on the order of 100pcm reactivity insertions. These insertions correspond to moderate transients seen during normal operations.

**1.5. The Analytical Solution to the Step Insertion.** As previously stated, in cases where  $\rho(t)$  is constant, there exists an analytical solution to the point kinetics ODE. This solution is reproduced in Eq. ??.

## Appendix A. An example appendix.

LEMMA A.1. *Test Lemma.*

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120

REFERENCES