

Modern Geometry PSET 1

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Proposition 1. *Every topological manifold is path-connected if and only if it is connected.*

The following lemma is useful.

Lemma 1. *Let M^n be a topological manifold. Then M^n is locally path-connected.*

Proof. Given a point $x \in M$, it suffices to show that there exists an open path-connected neighborhood $U \ni x$. Let x lie in the chart (V, ψ) ; then $\psi(V)$ is an open set in \mathbb{R}^n . By the topology of \mathbb{R}^n , we can find an open ball $B \ni \psi(x)$ such that $B \subset \psi(V)$. Since B is clearly path-connected and open, so is $\psi^{-1}(B)$. Then $\psi^{-1}(B)$ is an open path-connected neighborhood of x , and we are done. \square

We now prove the proposition.

Proof. Let C be a path-component of M . Given some point $p \in C$, path-connectedness implies that there exists a path-connected neighborhood U of p . It's clear that U must be contained in C , and hence C must be open. It is true in general that path-connectedness implies connectedness; it suffices to show that connectedness implies path-connectedness. Suppose M is connected, i.e. M consists of one (open) component. For some $p \in M$ consider the path component P containing p . Suppose P is not the only path-component in M . Then the set $\{P, M \setminus P\}$ would be separation of M , contradicting that M is connected. Hence P must be the only path-component of M , and since M is connected it follows that $P = M$, i.e. that M is path-connected. \square

Proposition 2. *Consider the diagram*

$$\begin{array}{ccc} \mathbb{R}^{n+1} \setminus \{0\} & \xrightarrow{\quad f \quad} & S^n \times \mathbb{R} \\ \pi \downarrow & & \downarrow p \\ \mathbb{RP}^n & \xleftarrow{\quad \pi|_{S^n} \quad} & S^n \end{array}$$

where π is the quotient map and p is projection onto the first factor. Then the following are true:

- (a) *there exists a homeomorphism $f : \mathbb{R}^{n+1} \setminus \{0\} \rightarrow S^n \times \mathbb{R}$ such that the diagram commutes;*
- (b) *the inverse image of an open set in \mathbb{RP}^n in $S^n \times \mathbb{R}$ is*
- (c) *\mathbb{RP}^n is Hausdorff, second-countable, and compact.*

Proof. (a) Define the map f by $\vec{v} \mapsto (\vec{v}/|\vec{v}|, \ln |\vec{v}|)$. It's clear that the map is bijective with inverse $f^{-1} : (\vec{w}, x) \mapsto e^x \vec{w}$ and that both f and f^{-1} are continuous. Hence f is a homeomorphism. To check that the diagram commutes, note that $p(f(\vec{v})) = \vec{v}/|\vec{v}|$, which when projected to \mathbb{RP}^n simply yields $[\vec{v}]$, as needed.

- (b) Geometrically, the map $\pi|_{S^n}$ simply identifies antipodal points on the sphere, and hence the inverse image of an open set in \mathbb{RP}^n is two open sets on S^n (antipodally symmetric). The inverse image of this in $S^n \times \mathbb{R}$ gives us back these open sets but with fibers isomorphic to \mathbb{R} attached to each point. Geometrically we can imagine a double-napped hypercone (with center at the center of the sphere) that intersects S^n in the shape of the open set of \mathbb{RP}^n .
- (c) We showed in class that \mathbb{RP}^n is locally Euclidean and constructed charts (U_i, ϕ_i) . Let us first show that \mathbb{RP}^n is second-countable. Take the collection of open sets $\{\pi^{-1}(U_i)\}$, which is an open cover of $\mathbb{R}^{n+1} \setminus \{0\}$. Pick a countable sub-cover of this collection and call \mathcal{U}' the collection of open sets of \mathbb{RP}^n whose preimage by π is this countable sub-cover. Then \mathcal{U}' is a countable cover of \mathbb{RP}^n by Euclidean balls of dimension n . Since each ball has a countable basis, the union of such bases gives us a countable cover for \mathbb{RP}^n .

Next we show that \mathbb{RP}^n is Hausdorff. Pick two distinct points $x, y \in \mathbb{RP}^n$. The preimage of x in S^n is $\{x, -x\}$ and the preimage of y is $\{y, -y\}$. Consider S^n as embedded in \mathbb{R}^{n+1} and define the following open sets of S^n :

$$U = S^n \cap B_\epsilon(x)$$

$$V = S^n \cap B_\epsilon(y).$$

for $\epsilon = \min(|x - y|, |x + y|)/2$. It's clear then that on the n -sphere, $U, V, -U$, and $-V$ are disjoint neighborhoods of $x, y, -x$ and $-y$. Note now that the preimage of the image of U and V under $\pi|_{S^n}$ are $-U \cup U$ and $-V \cup V$ respectively. By definition of the quotient topology, $\pi|_{S^n}(U)$ and $\pi|_{S^n}(V)$ are open in \mathbb{RP}^n . Additionally, they must be disjoint, because if there were a point common to both, the preimage of the point would fall into both $-U \cup U$ and $-V \cup V$, which is impossible as they are disjoint. Hence \mathbb{RP}^n is Hausdorff.

That \mathbb{RP}^n is compact follows from the fact that compactness is preserved by continuous maps (i.e. if X is compact then $f(X)$ is compact) applied to the quotient map $\pi|_{S^n}$ since the sphere is obviously compact. □

Proposition 3. *If M, N, L are smooth manifolds with $f : M \rightarrow N$ and $g : N \rightarrow L$ smooth maps, then the composition $g \circ f : M \rightarrow L$ is smooth.*

Proof. Since g is smooth, we can find smooth charts (V, ψ) containing $f(p)$ and (W, ξ) containing $g(f(p))$ such that $g(V)$ is contained in W and the composition $\xi \circ g \circ \psi^{-1}$ is smooth. But now, by smoothness of f , we can find a chart (U, ϕ) containing p such that $f(U)$ is contained in V (as we discussed in class, the coordinate representation of a smooth map is smooth with respect to every pair of smooth charts). Hence the composition $\psi \circ f \circ \phi^{-1}$ is smooth as well. Composing these compositions, we find that $\xi \circ g \circ f \circ \phi^{-1}$ is smooth, and we conclude that the composition $g \circ f$ is smooth. □

Proposition 4. *Bump functions, etc.*

Proof. (a) It's clear that f is continuous and smooth on $\mathbb{R} \setminus \{0\}$. Additionally, f is continuous at $x = 0$ because $f(0) = 0$ and $\lim_{x \rightarrow 0} e^{-1/x^2} = 0$. Hence it suffices to compute the derivatives at all orders of f at $x = 0$.

Let us first prove by induction that for $x > 0$,

$$\frac{d^n f}{dx^n} = p_n(x) \frac{e^{-1/x^2}}{x^{3n}},$$

for some polynomial $p_n(x)$. The formula clearly holds for $n = 0$. We assume it holds for $n - 1$. Then

$$\begin{aligned}\frac{d^n f}{dx^n} &= \frac{d}{dx} \left(p_{n-1}(x) \frac{e^{-1/x^2}}{x^{3(n-1)}} \right) \\ &= p'_{n-1}(x) \frac{e^{-1/x^2}}{x^{3(n-1)}} + p_{n-1}(x) \left(2e^{-\frac{1}{x^2}} x^{-3-3(-1+n)} - 3e^{-\frac{1}{x^2}} (-1+n)x^{-1-3(-1+n)} \right) \\ &= p'_{n-1}(x) \frac{e^{-1/x^2}}{x^{3(n-1)}} + p_{n-1}(x) \frac{e^{-1/x^2}}{x^{3n}} (2 - 3(n-1)x^2).\end{aligned}$$

Combining the two terms yields an overall denominator of x^{3n} with a now-different polynomial out front. Hence we are done.

Now let us compute the n th derivative of f at zero:

$$\left. \frac{d^n f}{dx^n} \right|_{x=0} = \lim_{h \rightarrow 0} \frac{p_n(h) \frac{e^{-1/h^2}}{h^{3n}}}{h} = p_n(0) \lim_{h \rightarrow 0} \frac{e^{-1/h^2}}{h^{3n+1}} = 0.$$

Since the derivatives exist, they must be continuous as well. Hence f is smooth.

(b) Define $g : \mathbb{R} \rightarrow \mathbb{R}$ by

$$g(x) = \frac{f(1 - |x|)}{f(1 - |x|) + f(|x| - 1/2)}.$$

For $|x| > 1$ the numerator vanishes, as desired and for $|x| < 1/2$, note that the second term in the denominator vanishes and hence g is identically 1. It is also easy to see that when $|x| < 1$, g is positive (by the properties of f). This function is smooth by composition on $\mathbb{R} \setminus \{0\}$. It is, in fact, also smooth at 0 as it is identically 1 in an open neighborhood of 0.

(c) Define $h : \mathbb{R} \rightarrow [0, 1]$ by

$$h(x) = 1 - \frac{f(1 - x)}{f(1 - x) + f(x)}.$$

Consider for now just the fraction: for $x < 0$, the second term in the denominator vanishes and hence we get 1. For $x > 1$, the numerator vanishes and we get 0. This is precisely the opposite of what we want. Hence we subtract it from 1. This function is smooth by composition.

(d) Take $\psi : \mathbb{R}^n \rightarrow \mathbb{R}$ given by

$$\psi(\vec{x}) = \frac{f(2\epsilon - |x|)}{f(2\epsilon - |x|) + f(|x| - \epsilon)},$$

for $\epsilon > 0$. The numerator is zero for $|x| \geq 2\epsilon$ by the definition of f , and hence ψ is zero for $|x| \geq 2\epsilon$. For $\epsilon \leq |x| \leq 2\epsilon$ the second term in the denominator vanishes and hence ψ is identically 1, as desired. By composition, ψ is clearly smooth on $\mathbb{R}^n \setminus \{0\}$. At zero, however, it is also smooth, as ψ is identically 1 in an open neighborhood of zero.

(e) Consider $h(U) \subset \mathbb{R}^n$ where (U, h) is a coordinate chart. Pick balls $B(p), B'(p)$ such that $B(p) \subset B'(p) \subset h(U)$. We can construct a function (just as in the previous part of this problem) that is 1 on $B(p)$ and 0 outside $B'(p)$; call this function ψ . Then the function $\phi : M \rightarrow \mathbb{R}$ given by $\psi \circ h$ on U and 0 on $M \setminus U$ satisfies our requirements and is smooth because the coordinate representation is smooth (in U , this follows from the previous part, outside U the function is simply 0).

□

Proposition 5. *The stereographic charts for S^2 are compatible.*

Proof. Let $U_- = S^2 \setminus \{0, 0, 1\}$ and $U_+ = S^2 \setminus \{0, 0, -1\}$.

The line that goes through $(0, 0, 1)$ and $(x, y, z) \in S^2$ is given by $(0, 0, 1) + t(x, y, z - 1)$ for $t \in \mathbb{R}$. This line intersects the plane $z = 0$ when $1 + t(z - 1) = 0$, i.e. when $t = -1/(z - 1)$. Hence we define

$$\phi_-(x, y, z) = \left(-\frac{x}{z-1}, -\frac{y}{z-1} \right)$$

as our chart (U_-, ϕ_-) . Since $z \neq 1$ in U_- , ϕ_- is continuous. If we write $\phi_-(x, y, z) = (u, v)$, we can solve for z (via the quadratic formula, discarding the case $z = 1$) and then x, y in terms of u, v which yields the inverse

$$\phi_-^{-1}(u, v) = \left(\frac{2u}{u^2 + v^2 + 1}, \frac{2v}{u^2 + v^2 + 1}, \frac{u^2 + v^2 - 1}{u^2 + v^2 + 1} \right),$$

which is clearly continuous as well. Hence ϕ_- is a homeomorphism.

The line that goes through $(0, 0, -1)$ and $(x, y, z) \in S^2$ is given by $(0, 0, -1) + t(x, y, z + 1)$ for $t \in \mathbb{R}$. This line intersects the plane $z = 0$ when $-1 + t(z + 1) = 0$, i.e. when $t = 1/(z + 1)$. Hence we define

$$\phi_+(x, y, z) = \left(\frac{x}{z+1}, \frac{y}{z+1} \right)$$

as our chart (U_+, ϕ_+) . Since $z \neq -1$ in U_+ , ϕ_+ is continuous. If we write $\phi_+(x, y, z) = (u, v)$, we can solve for z (via the quadratic formula, discarding the case $z = -1$) and then x, y in terms of u, v which yields the inverse

$$\phi_+^{-1}(u, v) = \left(\frac{2u}{u^2 + v^2 + 1}, \frac{2v}{u^2 + v^2 + 1}, \frac{-u^2 - v^2 + 1}{u^2 + v^2 + 1} \right),$$

which is clearly continuous as well. Hence ϕ_+ is a homeomorphism.

Let us now check that the charts (U_-, ϕ_-) and (U_+, ϕ_+) are compatible, i.e. $\phi_+ \circ \phi_-^{-1} : \phi_-(U \cap V) \rightarrow \phi_+(U \cap V)$ and $\phi_- \circ \phi_+^{-1} : \phi_+(U \cap V) \rightarrow \phi_-(U \cap V)$ are smooth. We compute

$$\begin{aligned} \phi_+ \circ \phi_-^{-1}(u, v) &= \phi_+ \left(\frac{2u}{u^2 + v^2 + 1}, \frac{2v}{u^2 + v^2 + 1}, \frac{u^2 + v^2 - 1}{u^2 + v^2 + 1} \right) \\ &= \left(\frac{u}{u^2 + v^2}, \frac{v}{u^2 + v^2} \right) \\ \phi_- \circ \phi_+^{-1}(u, v) &= \phi_- \left(\frac{2u}{u^2 + v^2 + 1}, \frac{2v}{u^2 + v^2 + 1}, \frac{-u^2 - v^2 + 1}{u^2 + v^2 + 1} \right) \\ &= \left(\frac{u}{u^2 + v^2}, \frac{v}{u^2 + v^2} \right), \end{aligned}$$

which are clearly smooth since $(u, v) \neq (0, 0)$ in the overlap. □

Proposition 6. *For $M \xrightarrow{\phi} N \xrightarrow{\psi} P$ smooth maps of manifolds, the push-forward is covariant, i.e. $(\psi \circ \phi)_* = \psi_* \circ \phi_*$.*

Proof. Consider two functions $n : N \rightarrow \mathbb{R}, p : P \rightarrow \mathbb{R}$ and vectors $X \in T_q M, Y \in T_{\phi(q)} N$. The push-forward of the composition $(\psi \circ \phi)_* : T_q M \rightarrow T_{\psi(\phi(q))} P$ gives us, by definition,

$$(\psi \circ \phi)_*(X)(p) = X(p \circ \psi \circ \phi).$$

Next consider the composition of pushforwards. Again, by definition, we have

$$\begin{aligned}\phi_*(X)(n) &= X(n \circ \phi) \\ \psi_*(Y)(p) &= Y(p \circ \psi)\end{aligned}$$

Composing these, $\psi_* \circ \phi_* : T_q M \rightarrow T_{\psi(\phi(q))} P$ we find:

$$\psi_*(\phi_*(X))(p) = \phi_*(X)(p \circ \psi) = X(p \circ \psi \circ \phi),$$

precisely as needed. □

Proposition 7. *If a non-empty m -manifold M is diffeomorphic to an n -manifold N , then $m = n$.*

Proof. Pick a point $p \in M$. We have a diffeomorphism $\phi : M \rightarrow N$, and hence a pushforward $\phi_* : T_p M \rightarrow T_{\phi(p)} N$ that is a vector space isomorphism. Note however that $T_p M$ has dimension m and $T_{\phi(p)} N$ has dimension n , and hence m must equal n . □