Notes on Topological and Differentiable Manifolds

Nilay Kumar

1 Elementary Topology

Let us begin with the definition of a topology:

Definition 1. A **topology** on a set X is a collection \mathcal{T} of subsets of X, called **open sets**, satisfying the following properties:

- 1. X and \varnothing are elements of \mathcal{T} .
- 2. \mathcal{T} is closed under finite intersections: If $U_1 \dots U_n \in \mathcal{T}$, then their intersection $U_1 \cap \dots \cap U_n$ is in \mathcal{T} .
- 3. \mathcal{T} is closed under arbitrary unions: If $U_1 \dots U_n \dots$ is any (finite or infinite) collection of elements of \mathcal{T} , then their union $\cup_{\alpha} U_{\alpha}$ is in \mathcal{T} .

A pair (X, \mathcal{T}) consisting of a set X and a topology \mathcal{T} on X is called a **topological space**. The elements of a topological space are usually called its **points**.

Definition 2. If X is a topological space and $q \in X$, a **neighborhood** of q is just an open set containing q. More generally, a neighborhood of a subset $K \subset X$ is an open set containing K.

Definition 3. If X is a topological space and $\{q_i\}$ is any sequence of points in X, we say that the sequence **converges** to $q \in X$, and q is the **limit** of the sequence, if for every neighborhood U of q there exists N such that $q_i \in U$ for all $i \geq N$. We denote this as $q_i \to q$ or $\lim_{i \to \infty} q_i = q$.

Example 1. Let Y be a trivial topological space (i.e. the only open sets are X and \varnothing). Each point has only 1 neighborhood: X itself. Thus, any sequence can be entirely contained in the neighborhood X, and consequently, any sequence converges to any point in X.

Example 2. Let X be a discrete topological space (i.e. all every subset of X is open). Take any sequence of points $\{q_i\}$. If the sequence converges to q, every open set containing q must contain all but a finite elements of the sequence. By virtue of the discrete topology, there exists an open set that contains only q. Obviously, then, there must exist an N such that $q_i = q$ for all $i \geq N$. Consequently, the only convergent sequences in X are the ones that are "eventually constant."

Definition 4. If X and Y are topological spaces, a map $f: X \to Y$ is said to be **continuous** if for every open set $U \subset Y$, $f^{-1}(U)$ is open in X.

Lemma 1. Let X, Y, Z be topological spaces.

- 1. Any constant map $f: X \to Y$ is continuous.
- 2. The identity map $\mathrm{Id}: X \to X$ is continuous.
- 3. If $f: X \to Y$ is continuous, so is the restriction of f to any open subset of X.
- 4. If $f: X \to Y$ and $g: Y \to Z$ are continuous, so is their composition $g \circ f: X \to Z$.

Proof. Let us begin with the constant map. Suppose f maps X to the constant $\lambda \in Y$. We wish to show that the preimage of f of every open set U in Y is open. There are two cases: U either does or does not contain λ . If it does, $f^{-1}(U) = X$; otherwise, $f^{-1}(U) = \emptyset$. As both X and \emptyset are open sets, f is continuous.

The continuity of the identity map follows trivially from the fact that Id maps any open set back to the same open set.

To prove the third statement, take any open set U in Y. U can be written as a union of points in and outside $f(V) \subset Y$: $U = U_i \cup U_o$. We want to show that $g^{-1}(U)$ is open in V. Since $g^{-1}(U_o) = \emptyset$, which is open, and $g^{-1}(U_i) \subset V$ and is open in X by the continuity of f, $g^{-1}(U_o \cup U_i) = g^{-1}(U_o) \cup g^{-1}(U_i)$ is open in V.

To prove the fourth statement, it suffices to show that $(g \circ f)^{-1}(U)$, with $U \subset Z$ open, is open in X. First note that $(g \circ f)^{-1}(U) = f^{-1}(g^{-1}(U))$. Since g is continuous, $g^{-1}(U)$ is an open set in Y. Similarly, f^{-1} of an open set in Y is open in X as f is continuous, and we are done.