Modern Geometry I: PSET 1

Nilay Kumar

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Problem 1

(a) We first show that $(S^n - \{N\}, \pi_1)$ and $(S^n - \{S\}, \pi_2)$ are charts for S^n . To do this, we write π_1 and π_2 in coordinates. Suppose a point p on S^n is given by coordinates in \mathbb{R}^{n+1} as (p_1, \ldots, p_{n+1}) . The line from the north pole to p can be written parametrically as $(p_1, \ldots, p_{n+1} - 1)t + (0, \ldots, 1)$, and hence intersects the hyperplane $x_{n+1} = 0$ when $t = 1/(1 - p_{n+1})$. Then

$$\pi_1(p_1,\ldots,p_{n+1}) = \frac{1}{1-p_{n+1}}(p_1,\ldots,p_n),$$

which is of course continuous on the open $S^n - \{N\}$ (this set is open in the subspace topology as it is the complement of a point). Conversely, given $(x_1, \ldots, x_n) \in \mathbb{R}^n$, the corresponding point on the sphere can be found by solving for the t for which $|(x_1 - x_1t, \ldots, x_n - x_nt, t)| = 1$. The quadratic formula reveals that this occurs when $t = (\sum_i x_i^2 - 1)/(\sum_i x_i^2 + 1)$. Denote this value of t by $\tau(x)$. Then the inverse is given

$$\pi_1^{-1}(x_1,\ldots,x_n)=(x_1-\tau(x)x_1,\ldots,x_n-\tau(x)x_n,\tau(x)),$$

which is continuous. Hence π_1 is a homeomorphism and $(S^n - \{N\}, \pi_1)$ provides a chart for S^n . Similarly, we find that

$$\pi_2(p_1,\ldots,p_{n+1}) = \frac{1}{1+p_{n+1}}(p_1,\ldots,p_n),$$

which is continuous on the open $S^n - \{S\}$. We can compute the inverse just as above, and π_2 becomes a homeomorphism, and $(S^n - \{S\}, \pi_2)$ provides a chart.

It remains to show that these two stereographic charts are compatible. Consider the composition $\pi_2 \circ \pi_1^{-1} : \pi_1(S^n - \{N, S\}) \to \pi_2(S^n - \{N, S\}).$

We write

$$\pi_2(\pi_1^{-1}(x_1, \dots, x_n)) = \pi_2(x_1 - \tau(x)x_1, \dots, x_n - \tau(x)x_n, \tau(x))$$

$$= \frac{1}{\tau(x)}(x_1 - \tau(x)x_1, \dots, x_n - \tau(x)x_n)$$

$$= \left(\frac{x_1}{\tau(x)} - x_1, \dots, \frac{x_n}{\tau(x)} - x_n\right).$$

This composition is clearly smooth, as $\tau(x)$ is non-zero on the domain of definition of $\pi_2 \circ \pi_1^{-1}$, to wit, x is not zero. For the sake of brevity, we do not describe the computation of the transition function $\pi_1 \circ \pi_2^{-1}$, but an identical argument shows that it is differentiable. Hence the two transition functions are diffeomorphisms, and the above two charts form a smooth atlas for S^n .

(b) Consider now the inclusion map $\iota: S^n \to \mathbb{R}^{n+1}$. The inclusion is a homeomorphism onto its image as it is a bijective continuous map (onto its image) from a compact topological space to a (subset of a) Hausdorff space. Moreover, ι is a smooth map, as $\pi_i^{-1} \circ \iota \circ \operatorname{Id}_{\mathbb{R}^{n+1}}$ is smooth, as given in the previous part. It remains to show that ι is an immersion. In coordinates, this amounts to showing that the Jacobian of $i \circ \pi^{-1}$ has rank n. We can compute, for example, that

$$\frac{\partial}{\partial x_j}(x_i - \tau(x)x_i) = \delta_{ij} - \delta_{ij}\tau(x) - \frac{4x_ix_j}{(\sum_k x_k^2 + 1)^2},$$

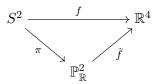
and hence

$$d\iota = \frac{1}{(\sum_{k} x_{k}^{2} + 1)^{2}} \begin{pmatrix} 2(\sum_{k} x_{k}^{2} + 1) - 4x_{1}^{2} & \cdots & -4x_{1}x_{n} \\ \vdots & \ddots & \vdots \\ -4x_{1}x_{n} & \cdots & 2(\sum_{k} x_{k}^{2} + 1) - 4x_{n}^{2} \\ 4x_{1} & \cdots & 4x_{n} \end{pmatrix}$$

Suppose, now, that the columns of this matrix are linearly dependent, i.e. there exist c_k (for 1 < k < n+1) such that $c_1(d\iota)_{k1} + \ldots + c_n(d\iota)_{kn} = 0$. Imposing this condition forces $\sum_k c_k x_k = 0$ due to the last row, and hence the first row yields $2c_1(\sum_k x_k^2 + 1) = 0$, forcing $c_1 = 0$, and similarly for the following n-1 rows. Hence the columns are independent, and $d\iota$ has rank n.

Problem 2

Let $F: \mathbb{R}^3 \to \mathbb{R}^4$ be given by $F(x,y,z) = (x^2 - y^2, xy, zx, yz)$ and denote by f the restriction of F to $S^2 \subset \mathbb{R}^3$. Note that F(x,y,z) = F(-x,-y,-z) and thus f descends to a map $\tilde{f}: \mathbb{P}^2_{\mathbb{R}} = S^2/\{\pm 1\} \to \mathbb{R}^4$. In other words, the diagram



commutes, where π is the natural quotient map. The map \tilde{f} is smooth, as it takes, in coordinates (say where $x \neq 0$)

$$(\alpha, \beta) \mapsto \frac{1}{1 + \alpha^2 + \beta^2} (1 - \alpha^2, \alpha, \beta, \alpha\beta).$$

Moreover, to show that \tilde{f} is injective, it suffices to show that f is two-to-one (compatible with the quotient map). This is done as follows. Suppose $f(x, y, z) = f(\alpha, \beta, \gamma)$, i.e.

$$x^{2} - y^{2} = \alpha^{2} - \beta^{2}$$
$$xy = \alpha\beta$$
$$xz = \alpha\gamma$$
$$yz = \beta\gamma.$$

Dividing, we find that $r \equiv x/\alpha = \beta/y = \gamma/z$ (the cases where α, y , or z are zero fall out easily). The first equation yields

$$r^{2}\alpha^{2} - \frac{\beta^{2}}{r^{2}} = \alpha^{2} - \beta^{2}$$
$$(r^{2} - 1)(r^{2}\alpha^{2} + \beta^{2}) = 0,$$

which forces $r=\pm 1$. In other words $f(x,y,z)=f(\alpha,\beta,\gamma)$ if and only if $\vec{x}=\pm \vec{\alpha}$. As these points are identified in projective space, we find that \tilde{f} is indeed injective. Thus, as a bijective continuous map from a compact topological space to a Hausdorff topological space is a homeomorphism, we find that \tilde{f} is a homeomorphism onto its image. It remains now to show that \tilde{f} is an immersion. This is done using the coordinate representation of \tilde{f} as

$$\tilde{f}_{x\neq 0}(\alpha,\beta) = \frac{1}{1+\alpha^2+\beta^2}(1-\alpha^2,\alpha,\beta,\alpha\beta).$$

$$d\tilde{f}_{x\neq 0}(\alpha,\beta) = \frac{1}{(1+\alpha^2+\beta^2)^2} \begin{pmatrix} -2\alpha(2+\beta^2) & 2\beta(\alpha^2-1) \\ 1-\alpha^2+\beta^2 & -2\alpha\beta \\ -2\alpha\beta & 1-\beta^2+\alpha^2 \\ \beta(1-\alpha^2+\beta^2) & \alpha(1-\beta^2+\alpha^2) \end{pmatrix}.$$

Computing the determinant of the minor consisting of the second and third rows yields

$$(1 - \alpha^2 + \beta^2)(1 - \beta^2 + \alpha^2) + 4\alpha^2\beta^2 = 0$$
$$1 - 2\alpha^2\beta^2 - \alpha^4 - \beta^4 = 0$$
$$\alpha^2 + \beta^2 = 1.$$

This minor thus has rank 2 away from the unit circle. On the unit circle, we compute the determinant of the minor consisting of the second and fourth rows

$$\alpha(1 - \beta^2 + \alpha^2)(1 - \alpha^2 + \beta^2) + 2\alpha\beta^2(1 - \alpha^2 + \beta^2) = 0$$
$$\alpha(1 - \alpha^2 + \beta^2)(1 + \alpha^2 + \beta^2) = 0$$
$$4\alpha\beta^2 = 0.$$

Hence the differential is of rank 2 away from the four points $(\pm 1,0)$ and $(0,\pm 1)$. Finally, we compute the determinant of the minor consisting of the first and the fourth rows

$$-2\alpha^{2}(2+\beta^{2})(1-\beta^{2}+\alpha^{2}) - 2\beta^{2}(\alpha^{2}-1)(1-\alpha^{2}+\beta^{2}) = 0$$
$$-2(1-\beta^{2})(2+\beta^{2})(2-2\beta^{2}) + 4\beta^{6} = 0$$
$$-4(1-\beta^{2})^{2}(2+\beta^{2}) + 4\beta^{6} = 0.$$

It is clear that $\beta=0,\pm 1$ are not solutions, and hence $d\tilde{f}$ is rank 2 everywhere. A similar computation in other charts reveals that $d\tilde{f}$ is injective everywhere. Consequently, \tilde{f} is an injective immersion homeomorphic to its image, and thus a smooth embedding of $\mathbb{P}^2_{\mathbb{R}}$ into \mathbb{R}^4 .

Problem 3

Let Y_r be the set of points in \mathbb{R}^3 at a distance r > 0 from the unit circle in the xy-plane. Let $A = \{r \in (0, \infty) \mid Y_r \text{ is a smooth submanifold of } \mathbb{R}^3\}$.

(a) We consider three cases: r < 1, r = 1, and r > 1. For r = 1, it is clear that Y_1 is not locally Euclidean: let U be an open neighborhood of Y_1 at the origin. Removing the point at the origin yields a disconnected

open neighborhood; if a homeomorphism to an open subset of \mathbb{R}^n were to exist, it would have to be disconnected after removing a point, which is clearly impossible. For r<1, we obviously obtain a smooth submanifold by the preimage theorem stated in class; one can write a level set expression $((1-\sqrt{x^2+y^2})^2+z^2-r^2=0)$ and the differential is easily checked to be surjective. Finally, for r>1, Y_r is clearly homeomorphic to the sphere, and thus forms a topological manifold. However, Y_r cannot be a smooth submanifold or \mathbb{R}^3 , for the following reason. If it were, i.e. we were to have a smooth inclusion $\iota:Y_r\to\mathbb{R}^3$, the rank of $d\iota$ would be three (as we can find three linearly independently vectors $(\sqrt{r^2-1},0,1),(-\sqrt{r^2-1},0,1)$, and $(0,\sqrt{r^2-1},1)$ tangent to Y_r at $(0,0,\sqrt{r^2-1})$, which is absurd. In other words, the dimension of the tangent space of Y_r at the points $(0,0,\pm\sqrt{r^2-1})$ would not be 2. Thus, A=(0,1).

(b) Recall the stereographic charts π_1 and π_2 for the sphere. The smooth structure of $S^1 \times S^1$ is given by four charts, $\pi_i \times \pi_j$, for $1 \leq i, j \leq 2$. Now define $\iota: S^1 \times S^1 \to \mathbb{R}^3$ as

$$\iota(x, y, \alpha, \beta) = (x + rx\alpha, y + ry\alpha, r\beta),$$

where (x,y) are the coordinates on the first circle and (α,β) are the coordinates on the second circle (as embedding in \mathbb{R}^2), and $r \in A = (0,1)$. It is clear that $\iota(S^1 \times S^1) = Y_r$; it suffices to check that ι is an immersion (a smooth embedding is a diffeomorphism onto its image). Working in the chart given by $\pi_1 \times \pi_1$, we find that

$$(\pi_1 \times \pi_1)^{-1}(x,y) = \left(\frac{2x}{x^2+1}, \frac{x^2-1}{x^2+1}, \frac{2y}{y^2+1}, \frac{y^2-1}{y^2+1}\right),$$

and hence

$$\iota \circ (\pi_1 \times \pi_1)^{-1}(x,y) = \left(\frac{2x}{x^2 + 1} + \frac{4rxy}{(x^2 + 1)(y^2 + 1)}, \frac{x^2 - 1}{x^2 + 1} + \frac{2ry(x^2 - 1)}{(x^2 + 1)(y^2 + 1)}, \frac{r(y^2 - 1)}{y^2 + 1}\right).$$

Denote the differential of this map by M. We compute:

$$M = \begin{pmatrix} \frac{1-x^2}{(1+x^2)^2} \left(2 + \frac{4ry}{y^2+1}\right) & \frac{4rx(1-y^2)}{(x^2+1)(y^2+1)^2} \\ \frac{4x}{(x^2+1)^2} \left(1 + \frac{2ry}{y^2+1}\right) & \frac{2r(x^2-1)(1-y^2)}{(x^2+1)(y^2+1)^2} \\ 0 & \frac{4ry}{(y^2+1)^2} \end{pmatrix}$$

The determinant of the bottom 2×2 minor vanishes when either x or y are zero. However, we see by inspection that (x,0),(0,y), and (0,0) for $x\neq 0,y\neq 0$ all yield matrices of rank 2. This proves that $S^1\times S^1\cong Y_r$.