

# An Introduction to Automorphisms of $\mathbb{P}^n$

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Recall the definition of projective space  $\mathbb{P}^n$  from last week.

**Definition 1.** We denote by  $\mathbb{P}^n$  the space of lines passing through the origin of  $\mathbb{A}^{n+1}$ . More precisely, let  $\mathbb{A}^*$  act on  $\mathbb{A}^{n+1} - \{0\}$  by scaling as  $\lambda \cdot (x_0, \dots, x_n) = (\lambda x_0, \dots, \lambda x_n)$  and define **projective  $n$ -space** to be the quotient  $\mathbb{P}^n = \mathbb{A}^{n+1} - \{0\} / \mathbb{A}^*$  by this action.

Thinking of projective space as parametrizing a set of lines can be confusing at times, as it somewhat obscures the fact that  $\mathbb{P}^n$  is simply  $\mathbb{A}^n$  with extra “stuff” added at infinity. Let us thus think of projective space in terms of its coordinates.

**Definition 2.** Consider a point  $p \in \mathbb{P}^n$ . Treating  $\mathbb{P}^n$  as a quotient space, we can think of  $p$  as the equivalence class of points on a line through  $\mathbb{A}^{n+1}$ . Suppose that this line passes through the point  $\vec{x} = (x_0, \dots, x_n) \in \mathbb{A}^{n+1}$ . We write **homogeneous coordinates** for  $p$  as

$$p = [x_0 : \dots : x_n] = [\lambda x_0 : \dots : \lambda x_n],$$

for any  $\lambda \in \mathbb{A}^*$ . Note that these coordinates respect the action of  $\mathbb{A}^*$  defining  $\mathbb{P}^n$  and hence are well-defined. Moreover, not all  $x_i$  can be zero.

With this coordinate system in hand, let us try to build an intuitive picture of projective space in the next few examples.

**Example 1** (Real projective line). Let  $\mathbb{A} = \mathbb{R}$  and consider  $\mathbb{P}_{\mathbb{R}}^1$ , the space of lines through the origin of  $\mathbb{R}^2$ . It is clear that we can parametrize this space by the slopes of the lines everywhere except for the vertical line. This yields an  $\mathbb{R}$ ’s worth of points, giving us the real line. If we now take the slope of the vertical line to be “infinity,” we obtain the whole projective space  $\mathbb{P}_{\mathbb{R}}^1$ . This is formalized by the homogeneous coordinates defined on  $\mathbb{P}_{\mathbb{R}}^1$ .

Consider a point  $[x : y] \in \mathbb{P}_{\mathbb{R}}^1$ . Suppose  $y \neq 0$ . Then, letting  $\lambda = y^{-1}$ ,

$$[x : y] = y^{-1} \cdot [x, y] = [x/y : 1].$$

If we now note that  $x$  is free to range over all values in  $\mathbb{R}$ , we recover a copy of  $\mathbb{R}$  embedding in  $\mathbb{P}_{\mathbb{R}}^1$ . We can think of this as the set of lines with finite slopes. If  $y = 0$ , on the other hand, we can write

$$[x : 0] = x^{-1} \cdot [x : 0] = [1 : 0].$$

This implies that there is only one point in  $\mathbb{P}_{\mathbb{R}}^1$  with  $y = 0$ , which can be thought of as the “point at infinity.” It is important to note that the point at infinity is fundamentally no “different” than the other points in  $\mathbb{P}_{\mathbb{R}}^1$  – a concept that will become clear when we show that automorphisms of projective space can swap points at infinity with, say, the origin (in this case  $[0 : 1]$ ). In this sense, we can think of the projective line as a disjoint union or a “compactification”  $\mathbb{P}_{\mathbb{R}}^1 = \mathbb{R} \cup \{\infty\}$  (with the topology extended to the quotient topology of  $\mathbb{R}^2 / \mathbb{R}^*$ ).

**Example 2** (Real projective plane). Let  $\mathbb{A} = \mathbb{R}$  and consider  $\mathbb{P}_{\mathbb{R}}^2$ , the space of lines through the origin of  $\mathbb{R}^3$ . Using homogeneous coordinates, take a point  $[x : y : z] \in \mathbb{P}_{\mathbb{R}}^2$ .