

# How do you use evidence to make a decision?

# Readings for today

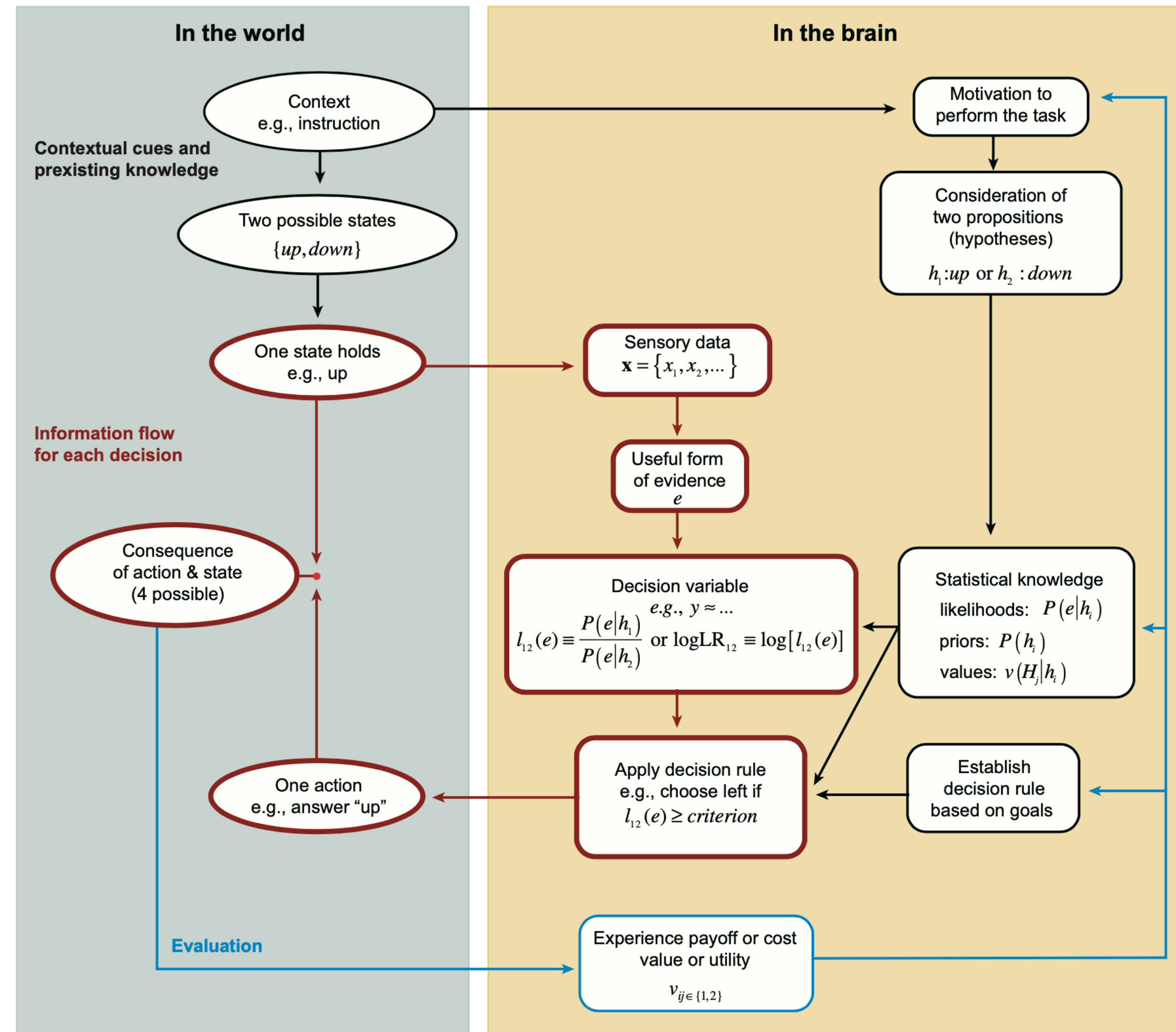
- Gold, J. I., & Shadlen, M. N. (2007). The neural basis of decision making. *Annu. Rev. Neurosci.*, 30, 535-574.

# Topics

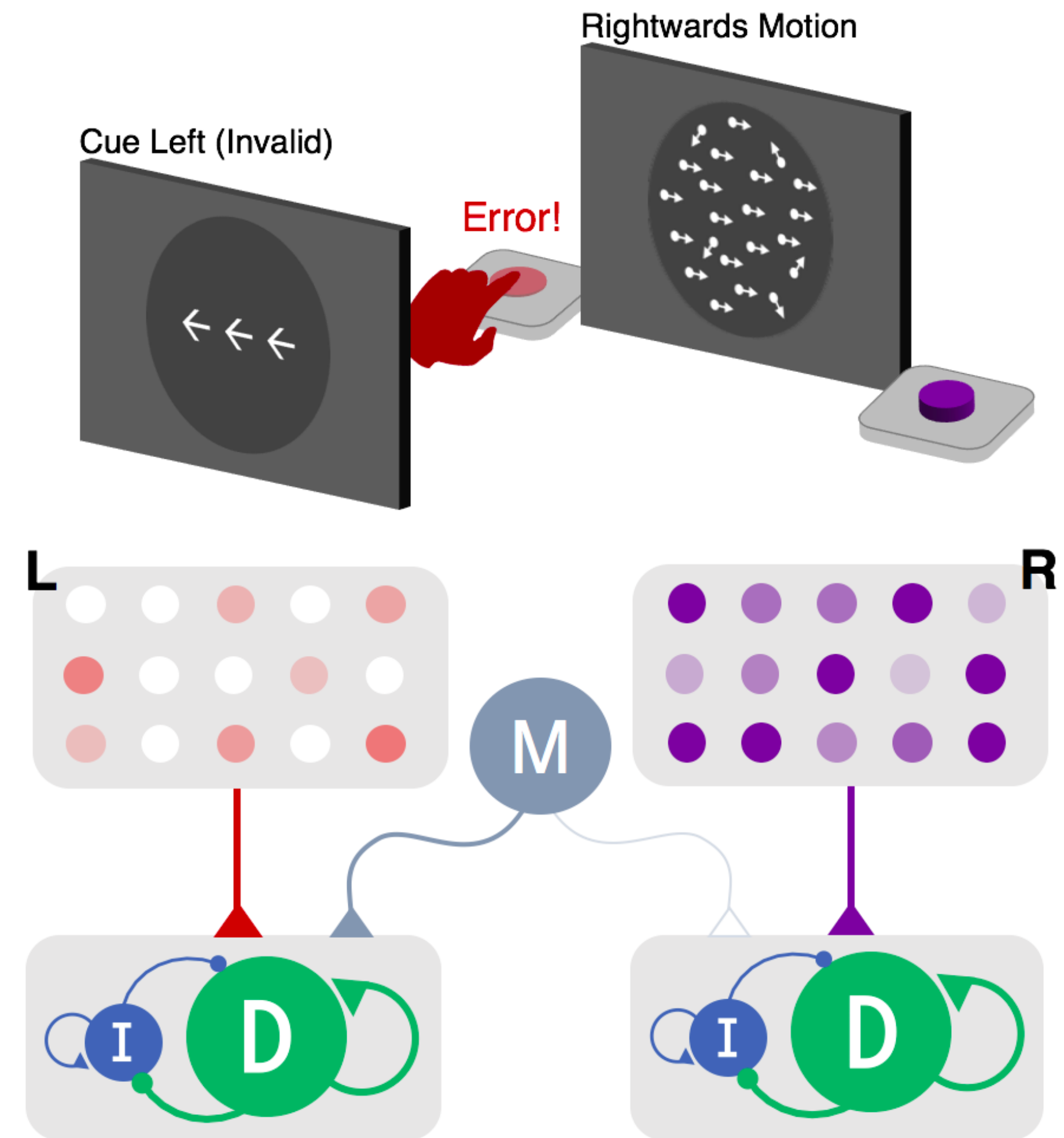
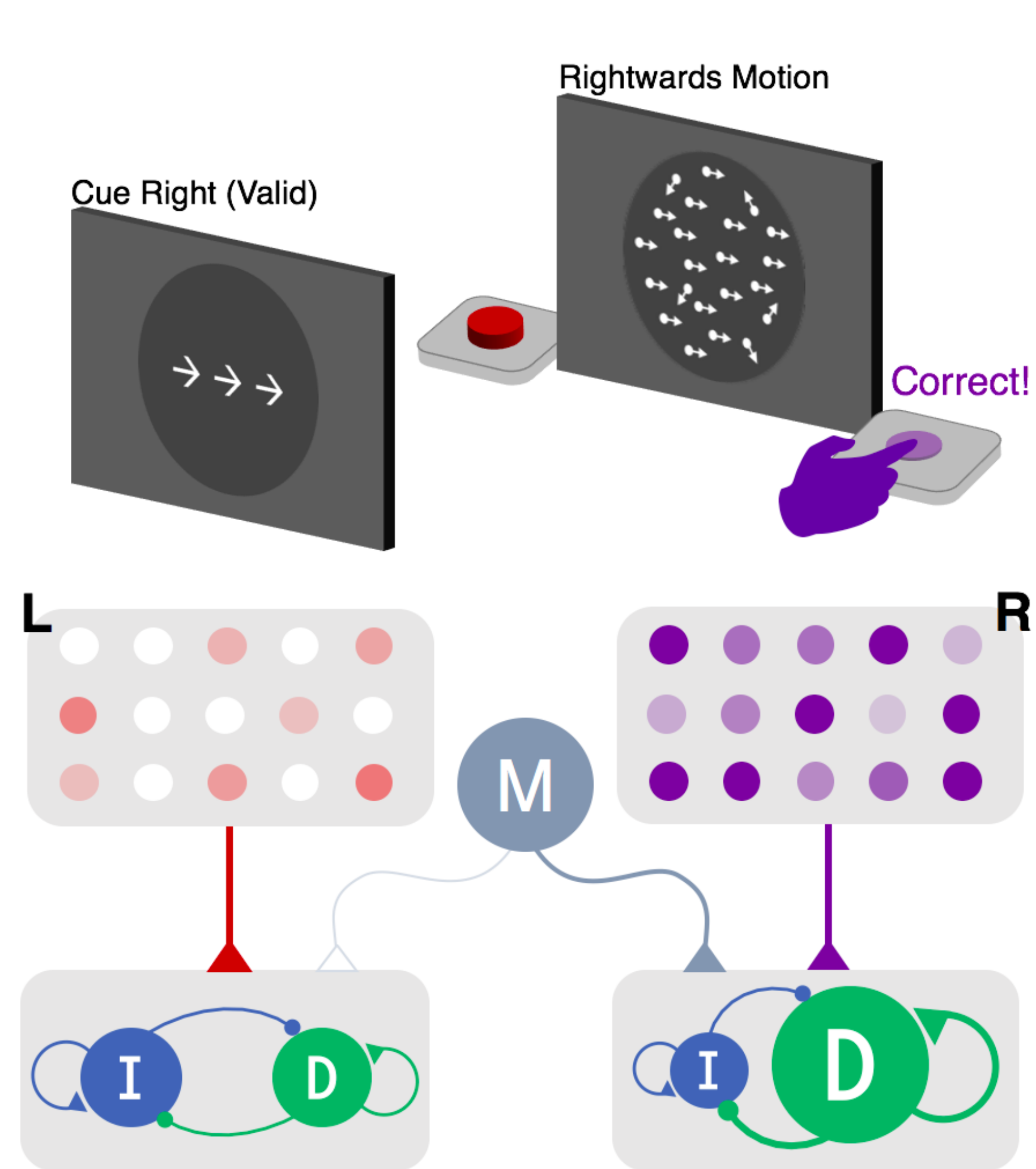
- Information accumulation
- The drift diffusion model

# Information accumulation

# Elements of making a decision

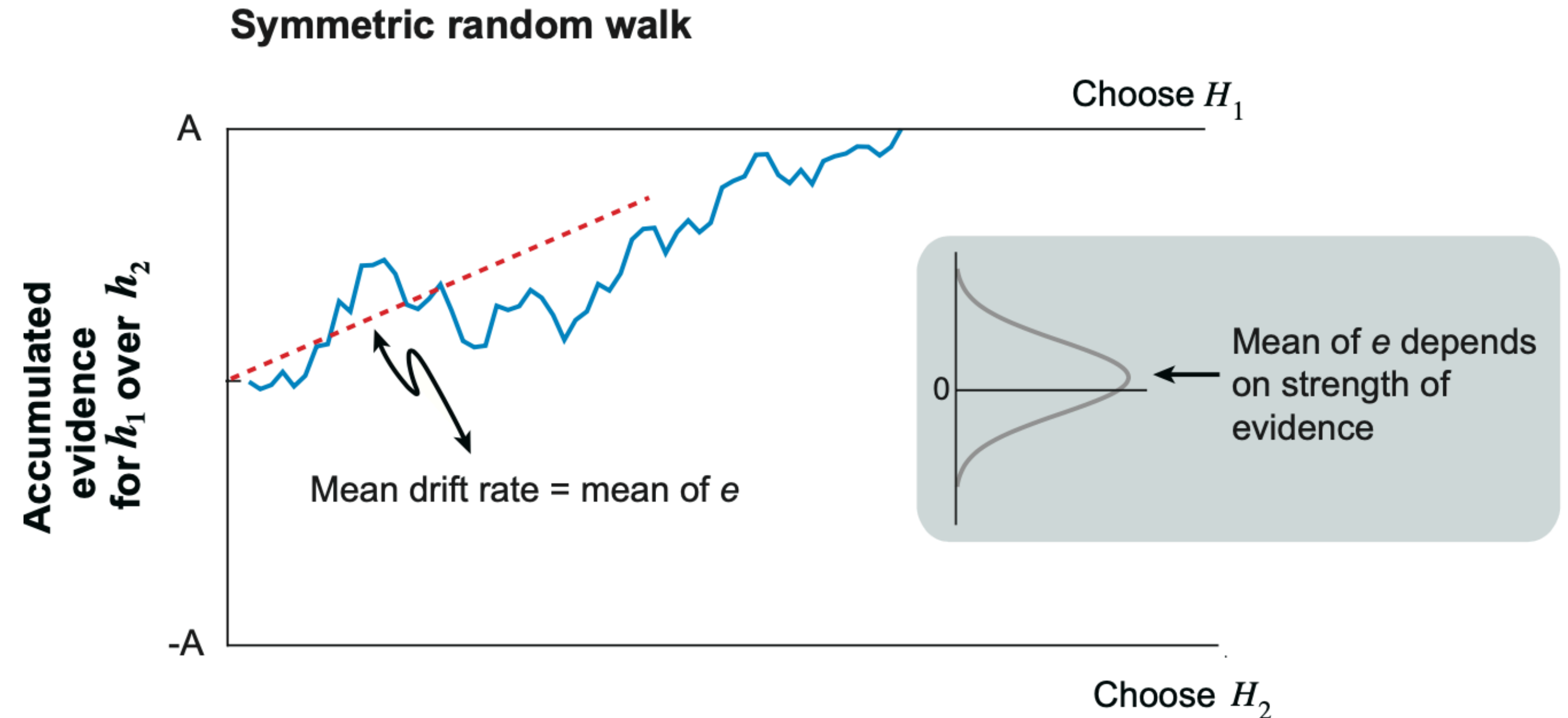
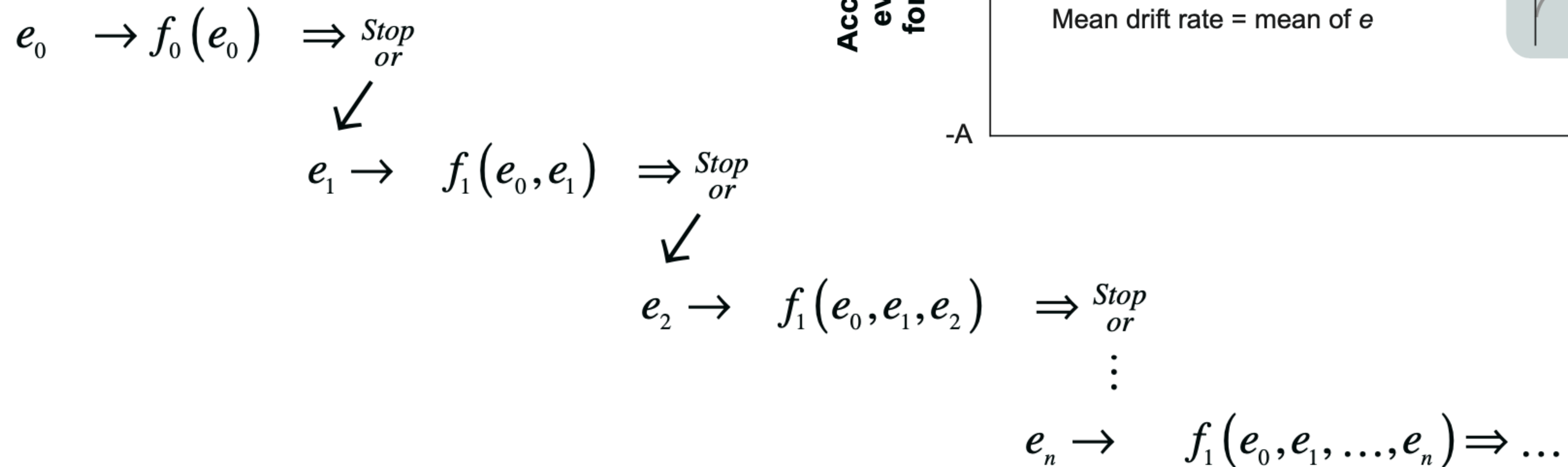


# Cued dot motion task



# Serial evaluation of evidence

## Sequential analysis framework



# Log-likelihood ratio (logLR) test

$$\begin{aligned}\log LR_{12} &\equiv \log \frac{P(e_1, e_2, \dots, e_n | h_1)}{P(e_1, e_2, \dots, e_n | h_2)} \\ &= \sum_{i=1}^n \log \frac{P(e_i | h_1)}{P(e_i | h_2)}.\end{aligned}$$

Given  $n$  samples of evidence ( $e$ ), what is the likelihood that the evidence was generated under one of two competing hypotheses ( $h$ )?

**Problem:** When have you accumulated enough evidence to make a decision?



# The sequential probability ratio test (SPRT)

1. On each sample  $i$ , evaluate logLR

$$w_i = \log \left( \frac{P(e_i | h_1)}{P(e_i | h_2)} \right)$$

2. Sum all logLR tests up to current observation

$$y_n = \sum_{i=1}^n w_i$$

3. Determine stopping rule

$$y_n \geq \log \frac{1-\alpha}{\alpha}, \text{ then select } h_1$$

$$y_n \leq \log \frac{\beta}{1-\beta}, \text{ then select } h_2$$

$$\log \frac{\beta}{1-\beta} \leq y_n \leq \log \frac{1-\alpha}{\alpha}, \text{ continue sampling}$$

# The drift diffusion model

# The Drift Diffusion Model (DDM)

$\theta$  : evidence (decision) variable.

$\theta(0) = z \rightarrow$  initialized with value  $z$  at  $t = t_{er}$

Continuous time for (Stochastic Diff Eq)

$$d\theta = vdt + \sigma dW$$

$dW$  : Wiener noise process

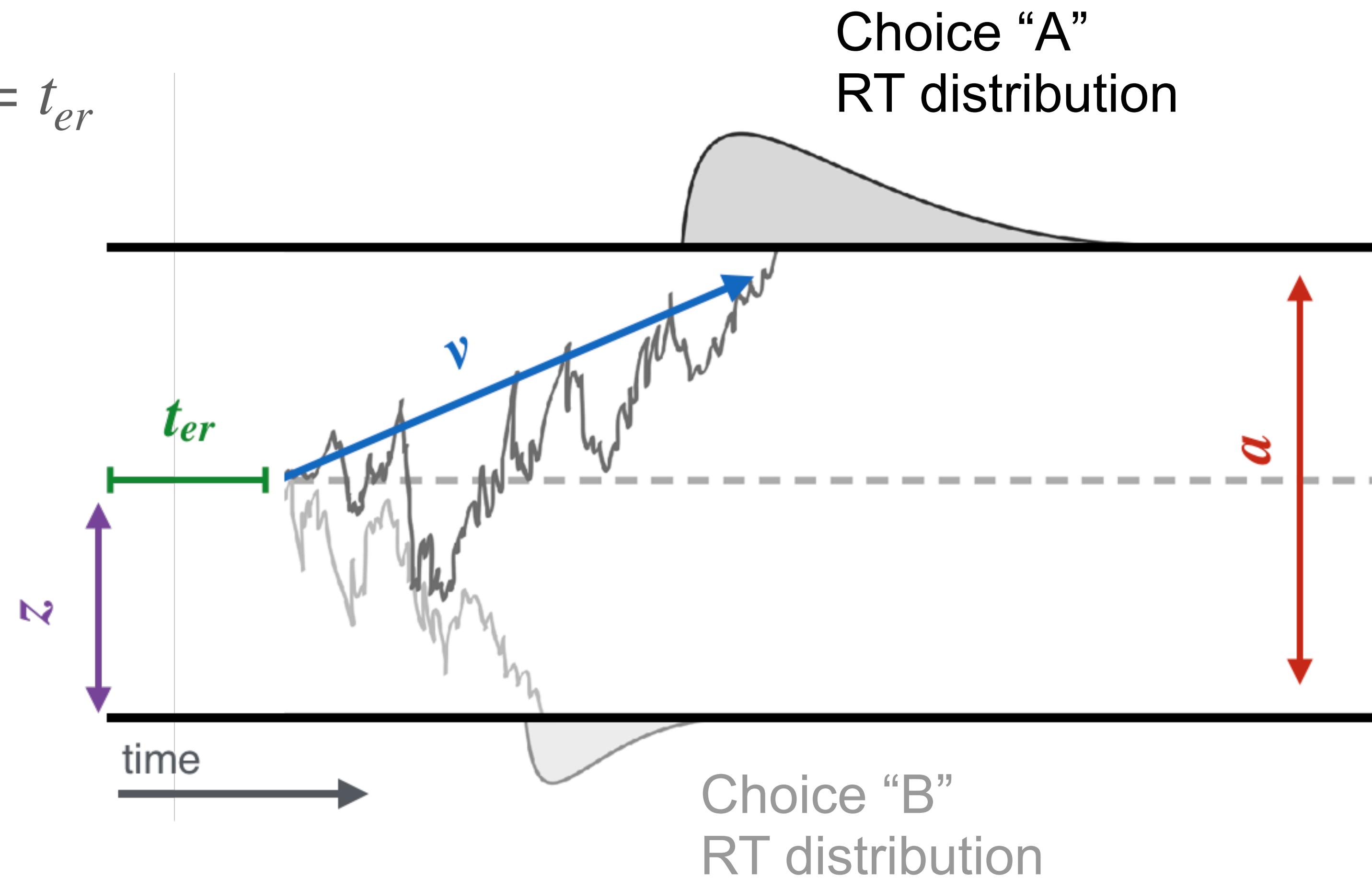
$\sigma$  : diffusion constant (noise scalar)

Discrete time form

$$\theta(t + \Delta t) = \theta(t) + v\Delta t + \sigma\sqrt{\Delta t}\epsilon(t)$$

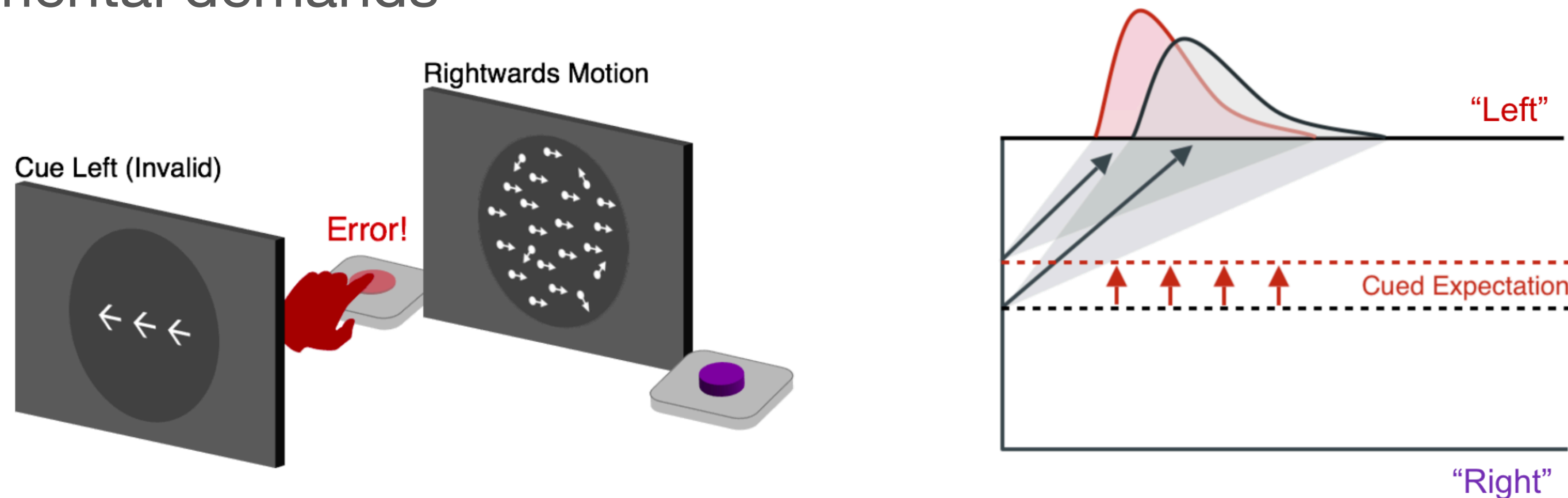
$\epsilon \sim N(0,1)$  : Gaussian noise

$\Delta t$  : timestep



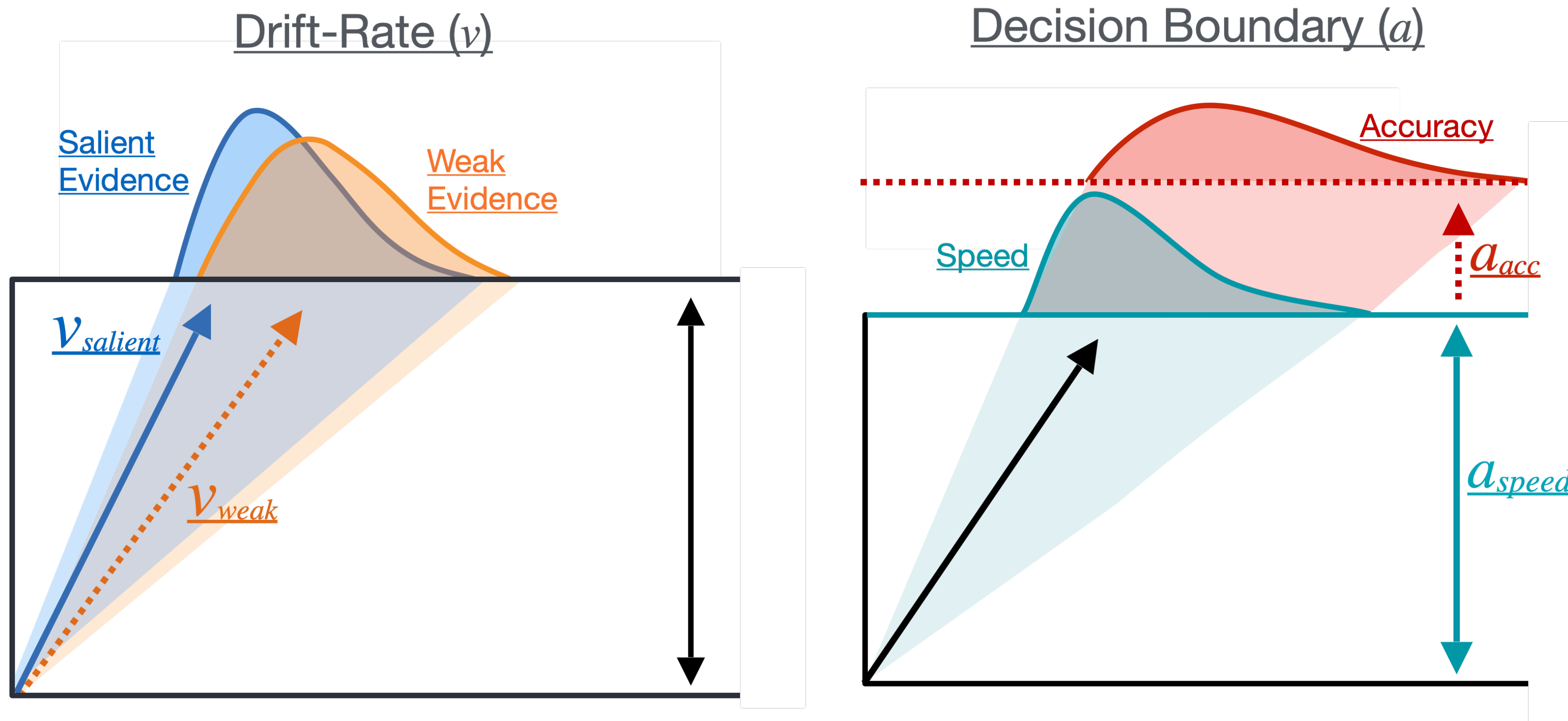
# Two critical properties of the DDM

1. Parameters are *identifiable* (e.g., recoverable) from behavioral data (RT distributions and choice accuracy)
2. Parameters are reliably modulated by specific task variables, capturing sensible links between internal decision mechanisms and external task environmental demands



# Parameter identifiability

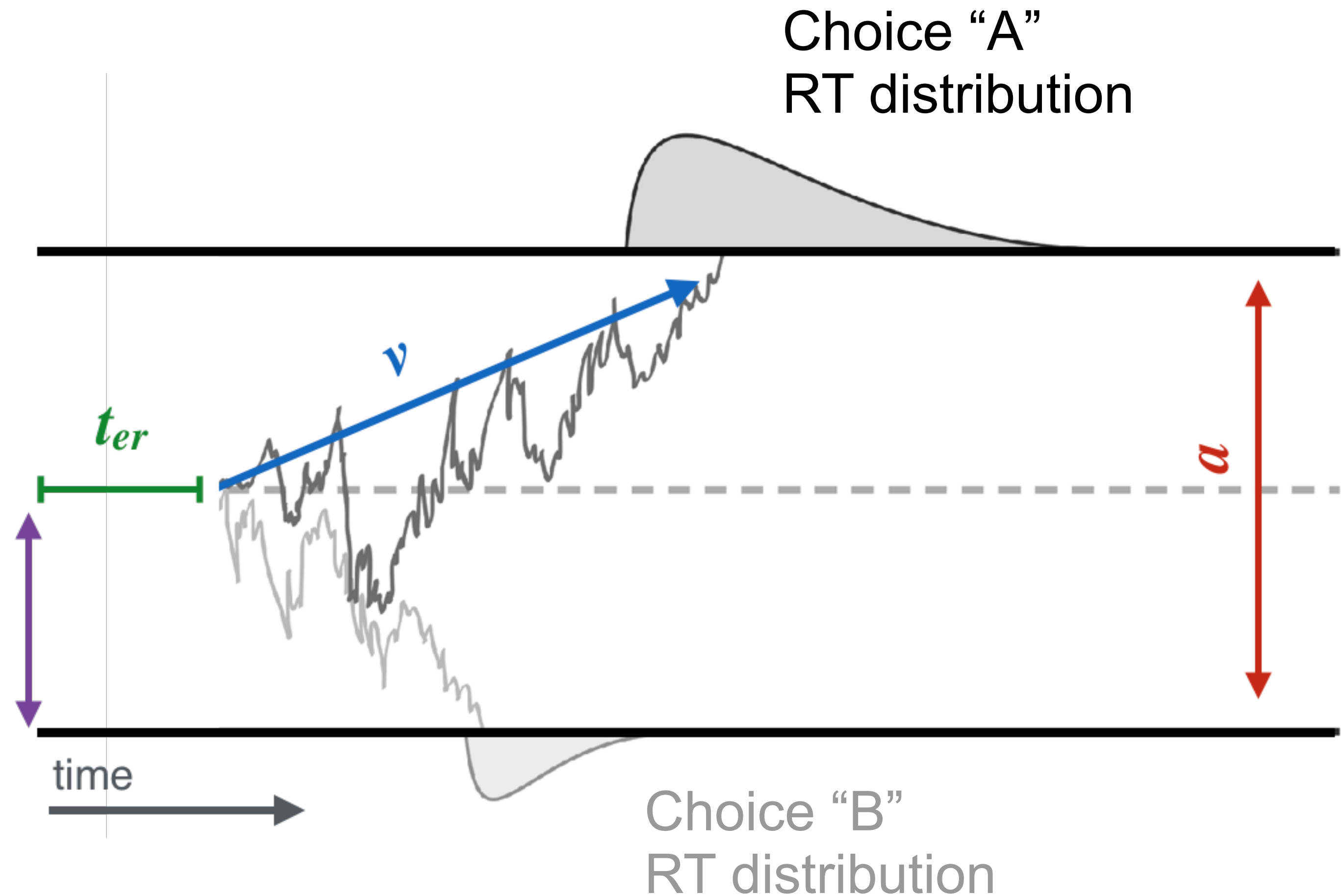
**Example:** How do we distinguish between behavioral effects caused by a change in drift-rate ( $v$ ) and change in boundary height ( $a$ )?





# Links between variables & task parameters

- boundary height ( $a$ ): evidence criterion
  - reflects internal strategy or priorities of agent
    - liberal strategy or prioritize speed (reduce  $a$ )
    - cautious strategy or prioritize accuracy (raise  $a$ )
- drift-rate ( $v$ ): relative strength of evidence for two alt. choices
  - typically depends on environment (externally controlled)
    - higher motion coherence => increase in  $v$
    - greater difference in associated value of alt. actions => increase in  $v$
- starting-point ( $z$ ): initial value of evidence, bias
  - reflects internal biases or expectations of agent
    - anticipate left motion, move  $z$  closer to “left” decision boundary
    - anticipate right motion, move  $z$  closer to “right” decision boundary
- non-decision time ( $tr$ ) sensory and motor delays:
  - traditionally viewed as a “nuisance” parameter (i.e., capturing internal and/or external variables related to sensory or motor but *not* decision computation)

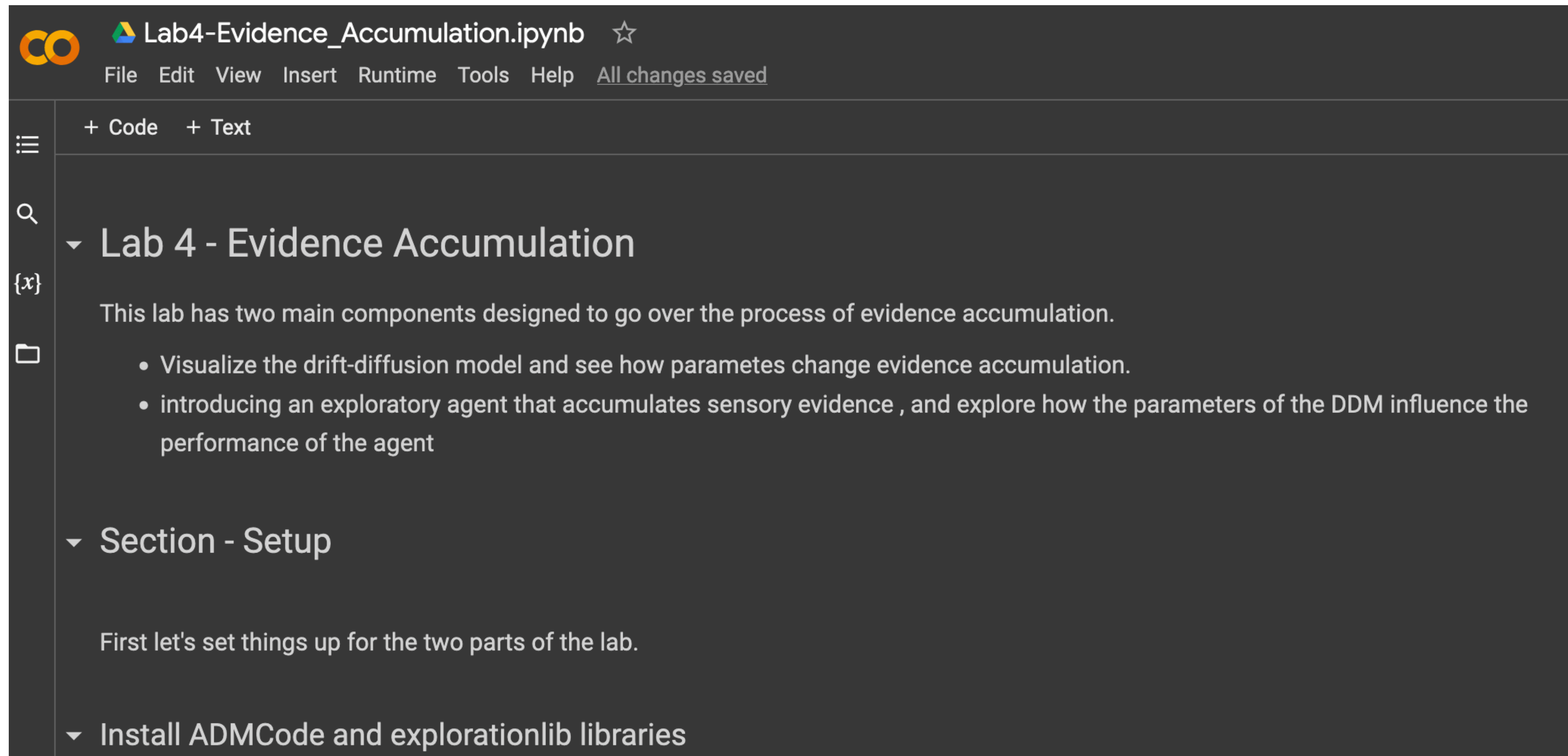


# Take home message

- At any given moment, the ratio of likelihoods is the optimal method for evaluating two hypotheses (when probabilities are known).
- Accumulation of evidence optimally occurs via a sequential probability ratio test (SPRT), which follows an information diffusion process.
- Models like the drift diffusion model reflect operationalizations of the SPRT that can be fit to empirical data.

# Lab 4: Evidence accumulation

URL: <https://github.com/CoAxLab/BiologicallyIntelligentExploration/tree/main/Labs>



The screenshot displays a JupyterLab environment with a dark theme. At the top, the file name 'Lab4-Evidence\_Accumulation.ipynb' is shown with a star icon and a menu bar containing 'File', 'Edit', 'View', 'Insert', 'Runtime', 'Tools', 'Help', and 'All changes saved'. Below the menu bar, there are buttons for '+ Code' and '+ Text'. The main area of the notebook is titled 'Lab 4 - Evidence Accumulation' and contains the following text:

This lab has two main components designed to go over the process of evidence accumulation.

- Visualize the drift-diffusion model and see how parameters change evidence accumulation.
- introducing an exploratory agent that accumulates sensory evidence , and explore how the parameters of the DDM influence the performance of the agent

Below the list, there is a section titled 'Section - Setup' with the text: 'First let's set things up for the two parts of the lab.'

At the bottom, there is a section titled 'Install ADMCode and explorationlib libraries'.