

# Concurrent Model Repair: Eshmun

## Models, Repairs, and Formal Verification

Ali Cherri<sup>1</sup>, Kinan Dak Al Bab<sup>1</sup>

<sup>1</sup>American University of Beirut  
Department of Computer Science

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# Getting Started

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# Why Formal Verification ?

## Computing Catastrophes<sup>1</sup>

- **Ariane 5** : Blew up due to code re-use without verification.
- **Therac-25** : Radiation Therapy Machine. Killed 6 due to a software error.
- **Mars Climate Crasher** : Crashed on Mars after 286-days trip. Due to unit conversions.
- **AT&T** : AT&T assumed it was being hacked. In fact, the company's long distance switches kept rebooting in sequence.

## Dijkstra's Thoughts<sup>2</sup>

The formal provability of a program is a major criterion for correctness : the central challenges of computing hadn't been met, due to an insufficient emphasis on program correctness.

# Modeling Sequential Programs

## Kripke Structure :

- State-transition Diagram : A Directed Graph where nodes are states of the program, and edges are transitions.
- Used to model sequential programs.
- The full diagram represents all the possible executions of the program.
- Each state satisfies certain properties (Boolean Formulae).

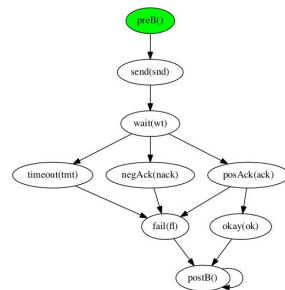


FIGURE: Kripke Structure for a Phone call

# Modeling Asynchronous Concurrent Programs

## Multi-Kripke Structure :

- Several Kripke Structure.
- Each Kripke Structure relates to two processes.
- Doing things in **pairwise representation** is more efficient !

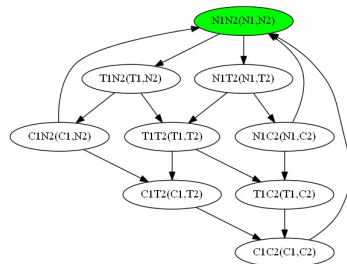


FIGURE: Pair Kripke Structure

# Temporal Logic

## Definition

Temporal Logic is a system of rules and boolean propositions that are quantified in terms of time. e.g. I am always Hungry.

## Computation Tree Logic (CTL)<sup>4</sup>

- Subset of Temporal Logic.
- Useful in tree-like structures where the future is not determined.
- Path Operators : quantify over a branch, path, or combination of both.
- CTL is useful for expressing properties like liveness and safety.

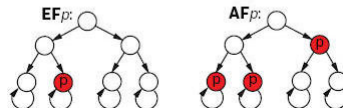
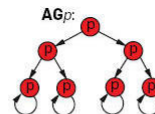


FIGURE: Notable Temporal Operators

# Model Checking<sup>4</sup>

- Used to verify Model Correctness.
- Given a Model and its Specification (In CTL), determines if the Model satisfies the specs.
- Great impact on industry :
  - Used extensively to verify correctness of Hardware.
  - Increasing use in verifying correctness of Software (**Windows Device Drivers**).

Emerson, Clarke, and Sifakis were given the **Turing Award** in 2007 for inventing model checking.

# Model Repair

- We are given a Model and its specifications, the model doesn't satisfy the specifications.
- We want to apply a **Subtractive Model Repair Algorithm** in order to get a new model that satisfies the specifications.
- This requires us to find the un-wanted transitions/states that are causing the model to be incorrect.
- These transitions/states should be **deleted** in a way that doesn't affect the program's flow and totality.
- The decision version of the problem is proved to be NP-Complete<sup>5</sup>.



# Model Repair : The Solution

- We encode the problem as a boolean formula.
- The formula contains different types of variables.
- The value of each variable indicates whether the corresponding state (or transition) is kept or deleted in the new model.
- The formula forces the new model to be total and have some start state, it also relates States to transitions.
- The formula is then passed to a SAT solver, each satisfying assignment would represent a repaired model.
- The Overall length of the repair formula is  $O(|States|^2 \times |Specifications| \times Out\_degree + |States| \times |Transitions| \times |Propositions|)^5$ .

# Model Repair : Getting the New Model

## Boolean Satisfiability Problem (SAT)

Determining If a boolean formula is Satisfiable or not. Is there an assignment that makes the formula true ? Boolean SAT is NP-Complete

## Repairing with SAT Solver

- By construction, if the repair formula is unsatisfiable then the model is un-repairable.
- Furthermore, the satisfying assignment of the formula is the needed repair.
- The satisfying assignment tells us which transitions and states are to be deleted.
- If all the start states are deleted then the model is un-repairable.

# What was already done

- A tool that repairs Single Kripke was done by M. Sakr (master's thesis).
- The tool used a Model Checker written by Emile Chartouni.
- The tool was a proof of concept.
- The tool had techniques that allow you to reduce the model into a smaller one to make repair more efficient.
- Repairing Mutual Exclusion for 4 Processes required more than 12GB of RAM.
- Data structures for models and repair algorithm were impossible to extend.

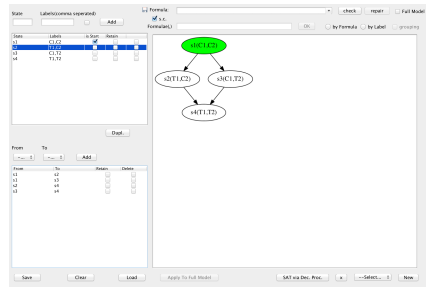


FIGURE: The old tool

## Our Contribution : Optimizing the tool

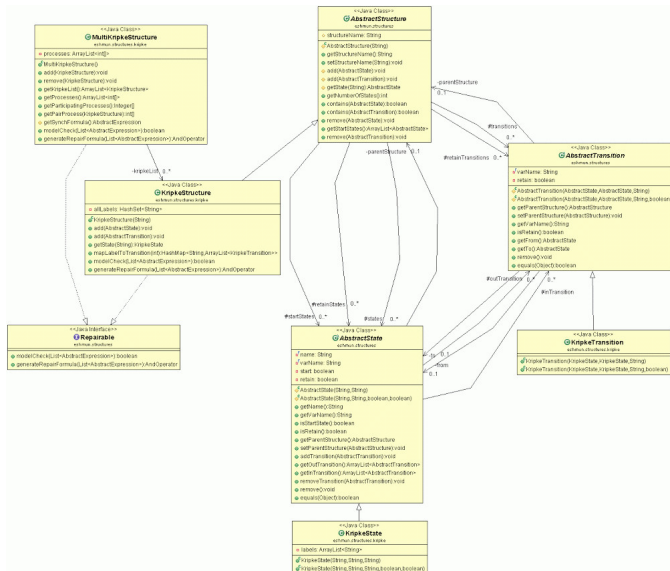
- Portability : The previous tool only ran on windows.
- An easy to use, interactive, and **User Focused** GUI.
- Feeding the SAT Solver from memory using a custom InputStream.
- The ability to iterate through different repairs.
- An IDE like enviroment for inputing Boolean Formulae.
- Memory Optimization, Implemented a different CTL-Logic API.
- New Data structures for models, Respecting OOP Guide lines.
- Complete seperation of modules, each functionality has its own classes in its own packages.
- Porting the Model Checker and Model Repair to use the new Logic API and datastructures.
- We re-implemented Everything !!

## Our Contribution : Multi Kripke Repair

- The ability to repair concurrent programs, modeled as Multi-Kripke Structures **Breakthrough.**
- Each of the sub-kripke structure has its own repair formula.
- All the sub-repair formulae are conjoined.
- A formula for synchronizing the processes across different sub-structures is automatically inferred and added to the complete repair formula.



# Data Structures



# Some Bragging

## Meterics

- Number of classes and interfaces : 88
- Number of methods : 1,027
- Lines of code : 19,103

## Technologies Used

- Java : The tool is written in java, it uses extensively concepts from OOP.
- Java Swing and Graphics2D : used to develop the GUI and the graphics.
- ANTLR : for building a parser for CTL logic expressions.
- SAT4J : a sat solver for java.
- PYTHON : For writting testing scripts, and generating different models.
- JavaDoc : A complete and extensive documentation of the code is provided.
- HTML : Used in the documentation and in the user manuel.



# Benchmarks

## Mutual Exclusion

- 2 Process : 107MS — 93MS
- 3 Process : 104MS — 1,210MS
- 4 Process : 248MS — Out of Memory

## Barrier Synchronization

- 2 Process : 63MS — 67MS
- 3 Process : 107MS — 460MS
- 4 Process : 164MS — 1.1Second

These numbers result from repairing the given problems using a single Kripke Structure.

## Future Work

- Get it published.
- Support more Concurrent Models : I/O Automata, BIP.
- Extend to Infinite State Models.
- Additive Repair Algorithm : add new transitions and states.

# Credits

## Credits

- We would like to thank our advisor Dr. Paul Attie, he offered a lot of help and guiding.
- We would like to thank Mohammad Ali Baydoun and George E. Zakhour for providing us with an algorithm and a working routine to auto space and format a graph, this was done by simulating the graph as a physical system with attraction and repulsion forces.

# Summary

- We can Model behavior of programs using formal tools (Kripke, Multi-Kripke, ...).
- Temporal Logic is an extension of First order logic that is useful to quantify over time (execution paths in case of CTL).
- By using model checking we can know if a program satisfies a given specification (CTL Formula).
- We can also Generate a repair formula for the model based on the definition of temporal operators.
- Using a SAT Solver we can get a satisfying assignment (if it exists) which is by construction the repair formula.
- We have implemented a tool that does all that.

# References

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## Conclusion

Thank You