Analysing Spatial Data in R: Representing Spatial Data

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Object framework

- To begin with, all contributed packages for handling spatial data in R had different representations of the data.
- This made it difficult to exchange data both within R between packages, and between R and external file formats and applications.
- The result has been an attempt to develop shared classes to represent spatial data in R, allowing some shared methods and many-to-one, one-to-many conversions.
- We chose to use new-style classes to represent spatial data, and are confident that this choice was justified.

Spatial objects

- ► The foundation object is the Spatial class, with just two slots (new-style class objects have pre-defined components called slots)
- The first is a bounding box, and is mostly used for setting up plots
- ➤ The second is a CRS class object defining the coordinate reference system, and may be set to CRS(as.character(NA)), its default value.
- ▶ Operations on Spatial* objects should update or copy these values to the new Spatial* objects being created

Spatial points

- The most basic spatial data object is a point, which may have 2 or 3 dimensions
- A single coordinate, or a set of such coordinates, may be used to define a SpatialPoints object; coordinates should be of mode double and will be promoted if not
- The points in a SpatialPoints object may be associated with a row of attributes to create a SpatialPointsDataFrame object
- The coordinates and attributes may, but do not have to be keyed to each other using ID values

Spatial points

Using the Meuse bank data set of soil samples and measurements of heavy metal pollution provided with ${\bf sp},$ we'll make a

- SpatialPoints object.
- > library(sp) > data(meuse)
- > coords <- SpatialPoints(meuse[, c("x", "y")]) > summary(coords)
- Object of class SpatialPoints
- Coordinates: min max x 178605 181390
- y 329714 333611 Is projected: NA
- projected: MA projecting: [NA] Number of points: 155

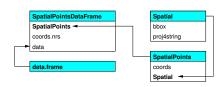
Spatial points

Now we'll add the original data frame to make a SpatialPointsDataFrame object. Many methods for standard data frames just work with SpatialPointsDataFrame objects.

```
> names(meuse1)
                        "cadmium" "copper" "lead"
[7] "elev" "dist"
                                 "ffreq" "soil"
[13] "landuse" "dist.m"
> summary(meusei$zinc)
  Min. 1st Qu. Median Mean 3rd Qu.
  113.0 198.0 326.0 469.7 674.5 1839.0
> stem(meuse1$zinc, scale = 1/2)
  The decimal point is 2 digit(s) to the right of the |
  0 | 122233333444445566667777888889999999
  2 | 000000011111112222233444555666678880022334455788
  4 | 00012235677001455556789
  6 | 01144678890012455678889
  8 | 0133113
  10 | 235604469
  12 I 8
  14 | 5357
  16 | 7
  18 | 4
```

> meusei <- SpatialPointsDataFrame(coords, meuse)

Spatial points classes and their slots



Spatial lines and polygons

- A Line object is just a spaghetti collection of 2D coordinates;
 a Polygon object is a Line object with equal first and last coordinates
- A Lines object is a list of Line objects, such as all the contours at a single elevation; the same relationship holds between a Polygons object and a list of Polygon objects, such as islands belonging to the same county
- SpatialLines and SpatialPolygons objects are made using lists of Lines or Polygons objects respectively
- SpatialLinesDataFrame and SpatialPolygonsDataFrame objects are defined using SpatialLines and SpatialPolygons objects and standard data frames, and the ID fields are here required to match the data frame row names

Spatial polygons

The Meuse bank data set also includes the coordinates of the edge of the river, linked together at the edge of the study area to form a polygon. We can make these coordinates into a SpatialPolygons object:

Spatial lines

> library(mantools)

There is a helper function contourLines2SLDF to convert the list of contours returned by contourLines into a SpatialLinesDataFrame object. This example shows how the data slot row names match the ID slot values of the set of Lines objects making up the SpatialLinesDataFrame, note that some Lines objects include multiple Line objects:

```
> volcane_si <- ContentInseqUaterrinseq(volcane))

> volcane_si <- ContentInseqUaterrinseq(volcane))

[3] "C_1" "C_2" "C_3" "C_4" "C_5" "C_5" "C_7" "C_8" "C_9"

> samply(sint(volcane_si, "lines"), function(x) slot(x, "TP")

[1] "C_1" "C_2" "C_3" "C_4" "C_5" "C_6" "C_7" "C_8" "C_9"

[3] "C_1" "C_2" "C_3" "C_4" "C_5" "C_6" "C_7" "C_8" "C_9"

> samply(sint(volcane_si, "lines"), function(x) length(slot(x, "lines")))

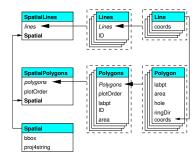
[3] 3 4 1 1 2 3 2 1

> volcane_sifisevs

[4] 100 101 100 100 140 180 180 170 180 190
```

Levels: 100 110 120 130 140 150 160 170 180 190

Spatial Polygons classes and slots



Spatial grids and pixels

- There are two representations for data on regular rectangular grids (oriented N-S, E-W): SpatialPixels and SpatialGrid
- SpatialPixels are like SpatialPoints objects, but the coordinates have to be regularly spaced; the coordinates are stored, as are grid indices
- SpatialPixelsDataFrame objects only store attribute data where it is present, but need to store the coordinates and grid indices of those grid cells
- SpatialGridDataFrame objects do not need to store coordinates, because they fill the entire defined grid, but they need to store NA values where attribute values are missing

Spatial pixels

Let's make a SpatialPixelsDataFrame object for the Meuse bank grid data provided, with regular points at a 40m spacing. The data include soil types, flood frequency classes and distance from the river bank:

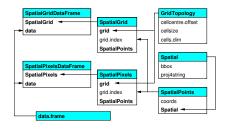
Spatial grids

[1] 3103 7

In this case we convert the SpatialPixelsDataFrame object to a SpatialGridDataFrame by making a change in-place. In other contexts, it is much more usual to create the GridTopology object in the grid slot directly, and populate the grid from there, as we'll see later:

[1] 8112 7

Spatial grid and pixels classes and their slots



Spatial classes provided by sp

This table summarises the classes provided by **sp**, and shows how they build up to the objects of most practical use, the Spatial*DataFrame family objects:

data type	class	attributes	extends
points	SpatialPoints	none	Spatial
points	SpatialPointsDataFrame	data.frame	SpatialPoints
pixels	SpatialPixels	none	SpatialPoints
pixels	SpatialPixelsDataFrame	data.frame	SpatialPixels
	-		SpatialPointsDataFrame
full grid	SpatialGrid	none	SpatialPixels
full grid	SpatialGridDataFrame	data.frame	SpatialGrid
line	Line	none	-
lines	Lines	none	Line list
lines	SpatialLines	none	Spatial, Lines list
lines	SpatialLinesDataFrame	data.frame	SpatialLines
polygon	Polygon	none	Line
polygons	Polygons	none	Polygon list
polygons	SpatialPolygons	none	Spatial, Polygons list
polygons	SpatialPolygonsDataFrame	data.frame	SpatialPolygons

Methods provided by sp

This table summarises the methods provided by sp:

method	what it does
[select spatial items (points, lines, polygons, or
	rows/cols from a grid) and/or attributes variables
\$, \$<-, [[, [[<-	retrieve, set or add attribute table columns
spsample	sample points from a set of polygons, on a set of
	lines or from a gridded area
bbox	get the bounding box
proj4string	get or set the projection (coordinate reference sys-
1	tem)
coordinates	set or retrieve coordinates
coerce	convert from one class to another
overlay	combine two different spatial objects

Using Spatial family objects

- Very often, the user never has to manipulate Spatial family objects directly, as we have been doing here, because methods to create them from external data are also provided
- Because the Spatial*DataFrame family objects behave in most cases like data frames, most of what we are used to doing with standard data frames just works like [or \$ (but no merge, etc., yet)
 These objects are very similar to typical representations of the
- same kinds of objects in geographical information systems, so they do not suit spatial data that is not geographical (like medical imaging) as such

 They provide a standard base for analysis packages on the one
- They provide a standard base for analysis packages on the one hand, and import and export of data on the other, as well as shared methods, like those for visualisation we turn to now