

Supplementary material: Exploiting inter-agent coupling information for efficient model-free reinforcement learning of cooperative LQR

Appendix A. Proof of Lemma 3.1

Proof *needs to be written in $u(t), x(t)$.* We prove a stronger version of the lemma that holds irrespective of the linear dynamics and quadratic cost assumption. For some $i, j \in \mathcal{V}$, let $j \in \mathcal{I}_Q^i$. For the sake of contradiction, assume that $\exists a k \in \mathcal{R}_{SO}^j$ such that $k \notin \mathcal{I}_Q^i$. By the definition of \mathcal{I}_Q^i , $j \in \mathcal{I}_Q^i$ implies that for some some $t' \geq t$, \exists a function (or composition of functions) $f : \mathcal{S} \times \mathcal{U} \rightarrow \mathbb{R}$ such that

$$c_i(x_{\mathcal{I}_C^i}(t'), u_{\mathcal{I}_C^i}(t')) = f(x_j(t), u_j(t), \bigcup_{g \in \mathcal{I}_Q^i \setminus j} \{x_g(\cdot), u_g(\cdot)\}). \quad (15)$$

Recall that the control $u_j(t) \in \mathcal{U}$ depends only on its partial observation $o_j(t)$, current state $x_j(t)$, and local policy $\pi_j(\cdot)$. Therefore, \exists a function $g_j : \mathcal{Z}_j \rightarrow P(\mathcal{U}_j)$ such that

$$u_j(t) \sim g_j(o_j(t)) = g_j(\{x_m(t)\}_{m \in \mathcal{I}_O^j}) \quad (16)$$

Similarly, due to the Markovian assumption for each $x_j(t)$, \exists a mapping $h_j : \prod_{n \in \mathcal{I}_S^j} \mathcal{S}_n \times \prod_{n \in \mathcal{I}_S^j} \mathcal{U}_n \rightarrow P(\mathcal{S}_j)$ such that

$$x_j(t) \sim h_j(\{x_n(t-1)\}_{n \in \mathcal{I}_S^j}, \{u_n(t-1)\}_{n \in \mathcal{I}_S^j}) \quad (17)$$

Using (16) and (17), (15) can be rewritten as

$$c_i(x_{\mathcal{I}_C^i}(t'), u_{\mathcal{I}_C^i}(t')) = f(x_j(t), u_j(t), \bigcup_{g \in \mathcal{I}_Q^i \setminus j} x_g, u_g) \quad (18)$$

$$= f(h_j(\{x_n(t-1)\}_{n \in \mathcal{I}_S^j}, \{u_n(t-1)\}_{n \in \mathcal{I}_S^j}), g_j(\{x_m(t)\}_{m \in \mathcal{I}_O^j}), \bigcup_{g \in \mathcal{I}_Q^i \setminus j} \{x_g(\cdot), u_g(\cdot)\}) \quad (19)$$

$$= f(h_j(\{x_n(t-1), u_n(t-1)\}_{n \in \mathcal{I}_S^j}), g_j(\{x_l(t-1), u_l(t-1)\}_{l \in \mathcal{I}_S^m} \}_{m \in \mathcal{I}_O^j}), \bigcup_{g \in \mathcal{I}_Q^i \setminus j} \{x_g(\cdot), u_g(\cdot)\}) \quad (20)$$

On recursive expansion of (20), it is straightforward to verify that $c_i(x_{\mathcal{I}_C^i}(t'), u_{\mathcal{I}_C^i}(t'))$ depends on $\{x_s(t''), u_s(t'')\}_{s \in \mathcal{R}_{SO}^j}$, for some $t'' \leq t \leq t'$. Thus, $i \in \mathcal{I}_{GD}^s \forall s \in \mathcal{R}_{SO}^j$ which implies that $s \in \mathcal{I}_Q^i \forall s \in \mathcal{R}_{SO}^j$. But as $k \in \mathcal{R}_{SO}^j$, $k \in \mathcal{I}_Q^i$ which is a contradiction. Therefore, our assumption is false and hence if $j \in \mathcal{I}_Q^i$, then $\forall k \in \mathcal{R}_{SO}^j$, $k \in \mathcal{I}_Q^i$ as required. \blacksquare

Appendix B. Proof of Theorem 3.1

Proof For the networked system, observe that the individual cost-to-go for each agent Q_i is dependent on the global state and control due to the long-term inter-agent dependencies between the agents. Recall that

$$Q_i(x, u) = c_i(x_{\mathcal{I}_C^i}, u_{\mathcal{I}_C^i}) + \mathbb{E} \left[\sum_{t=1}^T c_i(x_{\mathcal{I}_C^i}(t), u_{\mathcal{I}_C^i}(t)) \right]. \quad (21)$$

For LTI dynamics (1) and quadratic cost (2), (21) can be rewritten as

$$\begin{aligned} Q_i(x, u) &= \begin{bmatrix} x_{\mathcal{I}_C^i}(t) \\ u_{\mathcal{I}_C^i}(t) \end{bmatrix}^\top \begin{bmatrix} S_i & 0 \\ 0 & R_i \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_C^i}(t) \\ u_{\mathcal{I}_C^i}(t) \end{bmatrix} + \mathbb{E}_{w(t), \eta(t)} \left[\begin{bmatrix} x_{\mathcal{I}_C^i}(t+1) \\ u_{\mathcal{I}_C^i}(t+1) \end{bmatrix}^\top \begin{bmatrix} S_i & 0 \\ 0 & R_i \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_C^i}(t+1) \\ u_{\mathcal{I}_C^i}(t+1) \end{bmatrix} \right. \\ &\quad \left. + \mathbb{E}_{w(t+1), \eta(t+1)} \left[\begin{bmatrix} x_{\mathcal{I}_C^i}(t+2) \\ u_{\mathcal{I}_C^i}(t+2) \end{bmatrix}^\top \begin{bmatrix} S_i & 0 \\ 0 & R_i \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_C^i}(t+2) \\ u_{\mathcal{I}_C^i}(t+2) \end{bmatrix} + \mathbb{E}[\dots] \right] = \\ &\quad \sum_{j, k \in \mathcal{I}_C^i} \left[(x_j(t))^\top S_{jk} (x_k(t)) + (u_j(t))^\top R_{jk} (u_k(t)) + [\sigma_w^2 \text{Tr}(S_i) + \sigma_\eta^2 \text{Tr}(R_i)]_{j \in \mathcal{I}_C^i} + \right. \\ &\quad \left[x_{\mathcal{I}_S^j}^\top(t) A_j^\top S_i A_j x_{\mathcal{I}_S^j}(t) + u_{\mathcal{I}_S^j}^\top(t) B_j^\top S_i B_j u_{\mathcal{I}_S^j}(t) + 2x_{\mathcal{I}_S^j}^\top(t) A_j^\top S_i B_j u_{\mathcal{I}_S^j}(t) + x_{\mathcal{I}_O^j}^\top(t) K_j^\top R_i K_j x_{\mathcal{I}_O^j}(t) \right]_{j \in \mathcal{I}_C^i} \\ &\quad \left. + \sigma_\eta^2 \text{Tr} \left(B_j^\top S_i B_j \mathbb{I}_{n_u |\mathcal{I}_S^j|} \right) + 2\text{Tr} \left(A_j^\top S_i B_j w_k(t) \eta_l^\top(t) \right)_{\substack{k \in \mathcal{I}_S^j \\ l \in \mathcal{I}_O^j}} + \sigma_w^2 \text{Tr} \left(A_j^\top S_i A_j \mathbb{I}_{n_x |\mathcal{I}_S^j|} \right) + \dots \right] \end{aligned} \quad (22)$$

Therefore, from (22), it is clear that for time-invariant inter-agent couplings, the $Q_i(\cdot)$ for each $i \in \mathcal{V}$ depends on its neighbors in the cost graph which in turn depend on their neighbors in the state, and observation graphs and so on. In other words, $\forall i \in \mathcal{V}$, $Q_i(\cdot)$ depends on a subset of agents $\mathcal{I}_Q^i := \{\mathcal{I}_C^i \cup \{\mathcal{R}_{SO}^k\}_{k \in \mathcal{I}_C^i}\} = \{\mathcal{R}_{SO}^k\}_{k \in \mathcal{I}_C^i}$. By Lemma 3.1, we have that \mathcal{I}_Q^i is closed under \mathcal{R}_{SO} which implies that the information of agents in \mathcal{I}_Q^i is sufficient to exactly compute the future costs of agent i . Therefore, it follows that $Q_i(x(t), u(t)) = Q_i(x_{\mathcal{I}_Q^i}(t), u_{\mathcal{I}_Q^i}(t))$ as required. ■

Appendix C. Proof of Theorem 3.2

Proof Recall that

$$\begin{aligned}
Q^\pi(x, u) &= \mathbb{E}_\pi \left[\sum_{i=1}^N \sum_{t=0}^{\infty} c_i(x_{\mathcal{I}_C^i}(t), u_{\mathcal{I}_C^i}(t)) | x(0)=x, u(0)=u \right] \\
&= \mathbb{E}_\pi \left[\sum_{j \in \mathcal{I}_{\text{GD}}^i} \sum_{t=0}^{\infty} c_j(x_{\mathcal{I}_C^j}(t), u_{\mathcal{I}_C^j}(t)) | x(0)=x, u(0)=u \right] \\
&\quad + \mathbb{E}_\pi \left[\sum_{j \notin \mathcal{I}_{\text{GD}}^i} \sum_{t=0}^{\infty} c_j(x_{\mathcal{I}_C^j}(t), u_{\mathcal{I}_C^j}(t)) | x(0)=x, u(0)=u \right] \\
&= \sum_{j \in \mathcal{I}_{\text{GD}}^i} Q_j^\pi(x_{\mathcal{I}_Q^j}, u_{\mathcal{I}_Q^j}) + \sum_{k \notin \mathcal{I}_{\text{GD}}^i} Q_k^\pi(x_{\mathcal{I}_Q^k}, u_{\mathcal{I}_Q^k}) = \hat{Q}_i^\pi(x_{\mathcal{I}_Q^i}, u_{\mathcal{I}_Q^i}) + \bar{Q}_i^\pi(x_{\mathcal{I}_Q^i}, u_{\mathcal{I}_Q^i}), \tag{23}
\end{aligned}$$

where $\bar{Q}_i^\pi(x_{\mathcal{I}_Q^i}, u_{\mathcal{I}_Q^i}) = Q^\pi(x, u) - \hat{Q}_i^\pi(x_{\mathcal{I}_Q^i}, u_{\mathcal{I}_Q^i}) = \sum_{k \notin \mathcal{I}_{\text{GD}}^i} Q_k^\pi(x_{\mathcal{I}_Q^k}, u_{\mathcal{I}_Q^k})$. From Theorem 3.1, the reward of each agent $i \in \mathcal{V}$ depends on $x_j(t)$, $u_j(t) \forall j \in \mathcal{I}_Q^i$ and $\mathcal{E}_{\text{GD}} = \mathcal{E}_{\text{VD}}^\top$ by definition of \mathcal{G}_{GD} . Therefore, if $j \notin \mathcal{I}_{\text{GD}}^i$, then $i \notin \mathcal{I}_Q^j$. Hence, $\sum_{j \notin \mathcal{I}_{\text{GD}}^i} c_j(x_{\mathcal{I}_C^j}(t), u_{\mathcal{I}_C^j}(t))$ is independent of $u_i(t)$ and thus K_i . It then follows that $Q_j^\pi(\cdot)$, is independent of $K_i, \forall j \notin \mathcal{I}_{\text{GD}}^i$, which implies

$$\begin{aligned}
\nabla_{K_i} \bar{Q}_i^\pi &= \nabla_{K_i} \mathbb{E}_\pi \left[\sum_{j \notin \mathcal{I}_{\text{GD}}^i} \sum_{t=0}^{\infty} c_j(x_{\mathcal{I}_C^j}(t), u_{\mathcal{I}_C^j}(t)) | x(0)=x, u(0)=u \right] \\
&\stackrel{(a)}{=} \mathbb{E}_\pi \left[\nabla_{K_i} \sum_{j \notin \mathcal{I}_{\text{GD}}^i} \sum_{t=0}^{\infty} c_j(x_{\mathcal{I}_C^j}(t), u_{\mathcal{I}_C^j}(t)) | x(0)=x, u(0)=u \right] = 0, \tag{24}
\end{aligned}$$

where (a) in (24) is obtained by interchanging the derivative and integral assuming that each $Q_j^\pi(\cdot)$ is sufficiently smooth in state and control. Hence, the gradient of the global action value function with respect to K_i is given by $\nabla_{K_i} Q^\pi(s, a) = \nabla_{K_i} [\hat{Q}_i^\pi + \bar{Q}_i^\pi] = \nabla_{K_i} \hat{Q}_i^\pi$, as required. \blacksquare

Appendix D. Proof of Proposition 4.1

Proof From (9), we have

$$\hat{Q}_i^\pi(x_{\mathcal{I}_Q^i}, u_{\mathcal{I}_Q^i}) = \begin{bmatrix} x_{\mathcal{I}_Q^i}(t) \\ u_{\mathcal{I}_Q^i}(t) \end{bmatrix} \begin{bmatrix} S_{\mathcal{I}_Q^i} & 0 \\ 0 & R_{\mathcal{I}_Q^i} \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_Q^i}(t) \\ u_{\mathcal{I}_Q^i}(t) \end{bmatrix} + \mathbb{E} \left[\hat{Q}_i(x_{\mathcal{I}_Q^i}(t+1), u_{\mathcal{I}_Q^i}(t+1)) \right]. \tag{25}$$

Then, the expected future Q-value can be rewritten as

$$\begin{aligned}
 & \mathbb{E} \left[\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i(t+1), u_{\mathcal{I}_{\widehat{Q}}}^i(t+1)) \right] \\
 &= \mathbb{E} \left[\begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t+1) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t+1) \end{bmatrix} \begin{bmatrix} S_{\mathcal{I}_{\widehat{Q}}}^i & 0 \\ 0 & R_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t+1) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t+1) \end{bmatrix} \right] + \mathbb{E} \left[\mathbb{E} \left[\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i(t+2), u_{\mathcal{I}_{\widehat{Q}}}^i(t+2)) \right] \right] \\
 &= \mathbb{E} \left[(A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t) + w_{\mathcal{I}_{\widehat{Q}}}^i(t))^{\top} S_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t) + w_{\mathcal{I}_{\widehat{Q}}}^i(t)) \right] + \\
 & \mathbb{E} \left[(K_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t) + w_{\mathcal{I}_{\widehat{Q}}}^i(t)))^{\top} R_{\mathcal{I}_{\widehat{Q}}}^i (K_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t) + w_{\mathcal{I}_{\widehat{Q}}}^i(t))) \right] \\
 &+ \mathbb{E} \left[\mathbb{E} \left[\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i(t+2), u_{\mathcal{I}_{\widehat{Q}}}^i(t+2)) \right] \right] \\
 &= (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t))^{\top} S_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t)) + \sigma_w^2 \text{Tr} \left(S_{\mathcal{I}_{\widehat{Q}}}^i + K_{\mathcal{I}_{\widehat{Q}}}^{\top} R_{\mathcal{I}_{\widehat{Q}}}^i K_{\mathcal{I}_{\widehat{Q}}}^i \right) \\
 &+ (K_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t)))^{\top} R_{\mathcal{I}_{\widehat{Q}}}^i (K_{\mathcal{I}_{\widehat{Q}}}^i (A_{\mathcal{I}_{\widehat{Q}}}^i x_{\mathcal{I}_{\widehat{Q}}}^i(t) + B_{\mathcal{I}_{\widehat{Q}}}^i u_{\mathcal{I}_{\widehat{Q}}}^i(t))) \\
 &+ \mathbb{E} \left[\mathbb{E} \left[\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i(t+2), u_{\mathcal{I}_{\widehat{Q}}}^i(t+2)) \right] \right]
 \end{aligned} \tag{26}$$

$$\begin{aligned}
 &= \begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t) \end{bmatrix} \begin{bmatrix} A_{\mathcal{I}_{\widehat{Q}}}^{\top} \\ B_{\mathcal{I}_{\widehat{Q}}}^{\top} \end{bmatrix} (S_{\mathcal{I}_{\widehat{Q}}}^i + K_{\mathcal{I}_{\widehat{Q}}}^{\top} R_{\mathcal{I}_{\widehat{Q}}}^i K_{\mathcal{I}_{\widehat{Q}}}^i) \begin{bmatrix} A_{\mathcal{I}_{\widehat{Q}}}^i & B_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t) \end{bmatrix} + \sigma_w^2 \begin{bmatrix} \mathbb{I} \\ K_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix}^{\top} \begin{bmatrix} S_{\mathcal{I}_{\widehat{Q}}}^i & 0 \\ 0 & R_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix} \begin{bmatrix} \mathbb{I} \\ K_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix} \\
 &+ \mathbb{E} \left[\mathbb{E} \left[\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i(t+2), u_{\mathcal{I}_{\widehat{Q}}}^i(t+2)) \right] \right].
 \end{aligned} \tag{27}$$

Recursive expansion of (27) yields

$$\widehat{Q}_i(x_{\mathcal{I}_{\widehat{Q}}}^i, u_{\mathcal{I}_{\widehat{Q}}}^i) = \begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t) \end{bmatrix} \widehat{Q}_i \begin{bmatrix} x_{\mathcal{I}_{\widehat{Q}}}^i(t) \\ u_{\mathcal{I}_{\widehat{Q}}}^i(t) \end{bmatrix} + \sigma_w^2 \begin{bmatrix} \mathbb{I} \\ K_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix}^{\top} \widehat{Q}_i \begin{bmatrix} \mathbb{I} \\ K_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix}, \tag{28}$$

where with a slight abuse of notation [how is the 2nd term obtained?](#)

$$\widehat{Q}_i = \begin{bmatrix} S_{\mathcal{I}_{\widehat{Q}}}^i & 0 \\ 0 & R_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix} + \begin{bmatrix} A_{\mathcal{I}_{\widehat{Q}}}^{\top} \\ B_{\mathcal{I}_{\widehat{Q}}}^{\top} \end{bmatrix} \mathcal{L} \left(A_{\mathcal{I}_{\widehat{Q}}}^i + B_{\mathcal{I}_{\widehat{Q}}}^i K_{\mathcal{I}_{\widehat{Q}}}^i, S_{\mathcal{I}_{\widehat{Q}}}^i + K_{\mathcal{I}_{\widehat{Q}}}^{\top} R_{\mathcal{I}_{\widehat{Q}}}^i K_{\mathcal{I}_{\widehat{Q}}}^i \right) \begin{bmatrix} A_{\mathcal{I}_{\widehat{Q}}}^i & B_{\mathcal{I}_{\widehat{Q}}}^i \end{bmatrix},$$

$\mathcal{L}(X, Y)$ is the analytical solution of the discrete time Lyapunov equation $\mathcal{P} = X\mathcal{P}X^{\top} + Y$. ■

Appendix E. Proof of Lemma 5.1

Proof

- (a) **Necessary condition.** Assume that $\mathcal{I}_Q^i \subset \mathcal{V}$. This implies that $\exists k \in \mathcal{V}$ such that $k \notin \bigcup_{j \in \mathcal{I}_{\text{GD}}^i} \mathcal{I}_Q^j$ i.e., $k \notin \mathcal{I}_{\text{GD}}^i$, and $k \notin \mathcal{I}_Q^j, \forall j \in \mathcal{I}_{\text{GD}}^i$. By definition, $k \notin \mathcal{I}_{\text{GD}}^i$ if $i \notin \mathcal{I}_C^k$ which implies $i \notin \mathcal{I}_C^k$, and $i \notin \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^k}$. Similarly, $k \notin \mathcal{I}_Q^j, \forall j \in \mathcal{I}_{\text{GD}}^i$ if $k \notin \mathcal{I}_C^j$, and $k \notin \{\mathcal{R}_{SO}^m\}_{m \in \mathcal{I}_C^j}, \forall j \in \mathcal{I}_{\text{GD}}^i$. However, if $j \in \mathcal{I}_{\text{GD}}^i$, implies $i \in \mathcal{I}_Q^j$ i.e., either $i \in \mathcal{I}_C^j$ or $i \in \{\mathcal{R}_{SO}^m\}_{m \in \mathcal{I}_C^j}$. Since, $\forall j \in \mathcal{I}_{\text{GD}}^i, i \in \mathcal{I}_C^j$, and $k \notin \mathcal{I}_C^j$ implies that $\mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^k = \emptyset$. Also, as $i \notin \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^k}$, and $k \notin \{\mathcal{R}_{SO}^m\}_{m \in \mathcal{I}_C^j}$ implies that $\mathcal{R}_{(SO)\tau}^i \cap \mathcal{R}_{(SO)\tau}^k = \emptyset$ as required.

Sufficient condition. We prove this using proof by contraposition. Assume that $\forall k \in \mathcal{V}, \mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^k \neq \emptyset$, or $\mathcal{R}_{(SO)\tau}^i \cap \mathcal{R}_{(SO)\tau}^k \neq \emptyset$.

Case 1: If $\mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^k \neq \emptyset$, then $\exists j \in \mathcal{V}$ such that $\{i, k\} \in \mathcal{I}_C^j$ which implies $j \in \mathcal{I}_{\text{GD}}^i$ and $k \in \mathcal{I}_Q^j$. Therefore, $k \in \mathcal{I}_Q^i$ which implies $\mathcal{I}_Q^i = \mathcal{V}$.

Case 2: If $\mathcal{R}_{(SO)\tau}^i \cap \mathcal{R}_{(SO)\tau}^k \neq \emptyset$, then $\exists j \in \mathcal{V}$ such that $\{i, k\} \in \mathcal{R}_{SO}^j$. Since, by definition, $j \in \mathcal{I}_C^j$ implies that $\{i, k\} \in \mathcal{I}_Q^j$ and $j \in \mathcal{I}_{\text{GD}}^i \cap \mathcal{I}_{\text{GD}}^k$. Hence, as $j \in \mathcal{I}_{\text{GD}}^i$, and $k \in \mathcal{I}_Q^j$, we have that $k \in \mathcal{I}_Q^i$ which implies that $\mathcal{I}_Q^i = \mathcal{V}$.

In either case, $\mathcal{I}_Q^i = \mathcal{V}$. Therefore, $\forall k \in \mathcal{V}$, if $\mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^k \neq \emptyset$, or $\mathcal{R}_{(SO)\tau}^i \cap \mathcal{R}_{(SO)\tau}^k \neq \emptyset$, then $\mathcal{I}_Q^i = \mathcal{V}$. The sufficient condition follows by contraposition as required.

- (b) **Necessary condition.** Consider an $i \in \mathcal{V}$ and assume that \exists an $j \in \mathcal{I}_{\text{GD}}^i$, such that $\mathcal{I}_Q^j \subset \mathcal{I}_Q^i$. This implies that $\exists k \in \mathcal{I}_Q^j$ such that $k \notin \mathcal{I}_Q^i$, and $k \in \bigcup_{h \in \mathcal{I}_{\text{GD}}^i \setminus \{j\}} \mathcal{I}_Q^h$. If $k \notin \mathcal{I}_Q^j$, then by definition, $k \notin \mathcal{I}_C^j$, and $k \notin \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^j}$. But, as $k \in \bigcup_{h \in \mathcal{I}_{\text{GD}}^i \setminus \{j\}} \mathcal{I}_Q^h$, implies that $\exists h \in \mathcal{I}_{\text{GD}}^i \setminus \{j\}$ such that either $k \in \mathcal{I}_C^h$ or $k \in \{\mathcal{R}_{SO}^m\}_{m \in \mathcal{I}_C^h}$.

Case 1 Let $k \in \mathcal{I}_C^h$. Then, as $h \in \mathcal{I}_{\text{GD}}^i$, either $i \in \mathcal{I}_C^h$, or $i \in \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^h}$.

- If $i \in \mathcal{I}_C^h$, then $\mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^k = \{h\} \neq \emptyset$. or,
- If $i \in \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^h}$, then \exists an $m \in \mathcal{I}_C^h \cap \mathcal{R}_{(SO)\tau}^i$. Hence, $\mathcal{I}_{C\tau}^m \cap \mathcal{I}_{C\tau}^k = \{h\} \neq \emptyset$.

Case 2 Let $k \in \{\mathcal{R}_{SO}^m\}_{m \in \mathcal{I}_C^h}$. Then, \exists an $p \in \mathcal{I}_C^h \cap \mathcal{R}_{(SO)\tau}^k$, and as $h \in \mathcal{I}_{\text{GD}}^i$, either $i \in \mathcal{I}_C^h$, or $i \in \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^h}$.

- If $i \in \mathcal{I}_C^h$, then $\mathcal{I}_{C\tau}^i \cap \mathcal{I}_{C\tau}^p = \{h\} \neq \emptyset$. or,
- If $i \in \{\mathcal{R}_{SO}^l\}_{l \in \mathcal{I}_C^h}$, then \exists an $m \in \mathcal{I}_C^h \cap \mathcal{R}_{(SO)\tau}^i$. Hence, $\mathcal{I}_{C\tau}^m \cap \mathcal{I}_{C\tau}^p = \{h\} \neq \emptyset$.

Therefore, in either case we conclude that if $\mathcal{I}_Q^j \subset \mathcal{I}_Q^i$, then $p \in \mathcal{R}_{(SO)\tau}^k, m \in \mathcal{R}_{(SO)\tau}^i$, such that $\mathcal{I}_{C\tau}^m \cap \mathcal{I}_{C\tau}^p \subset \mathcal{I}_{\text{GD}}^i$.

Sufficient condition. Consider an $i \in \mathcal{V}$ and assume that \exists an $j \in \mathcal{I}_{\text{GD}}^i$ for which \exists a $k \in \mathcal{V} \setminus \mathcal{I}_Q^j$. Let $\exists h \in \mathcal{I}_{\text{GD}}^i, m \in \mathcal{R}_{(SO)\tau}^i$, and $p \in \mathcal{R}_{(SO)\tau}^k$, such that $h \in \mathcal{I}_{C\tau}^m \cap \mathcal{I}_{C\tau}^p$. Hence, as $p \in \mathcal{I}_C^h$, by definition $k \in \mathcal{I}_Q^h$. But, as $h \in \mathcal{I}_{\text{GD}}^i$, we have that $k \in \mathcal{I}_Q^i$. However, $k \notin \mathcal{I}_Q^j$ which implies that $k \in \mathcal{I}_Q^i \setminus \mathcal{I}_Q^j$ or $\mathcal{I}_Q^j \subset \mathcal{I}_Q^i$ as required.

■

Appendix F. Proof of Theorem 5.1

Employing a *linear architecture*, (??) can be expressed as

$$\sum_{j \in \mathcal{I}_{\text{GD}}^i} r_j(t) = \lambda + \left[\text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix}^\top \right) - \mathbb{E} \left[\text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t+1) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t+1) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t+1) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t+1) \end{bmatrix}^\top \right) \right] \right]^\top \text{svec}(P_{\mathcal{I}_{\hat{Q}}^i}), \quad (29)$$

where $\lambda \in \mathbb{R}$ is a free parameter to satisfy the fixed point equation. Let $\lambda = \left\langle P_i, \begin{bmatrix} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x & \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x K_{\mathcal{I}_{\hat{Q}}^i}^\top \\ K_{\mathcal{I}_{\hat{Q}}^i} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x & K_{\mathcal{I}_{\hat{Q}}^i} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x K_{\mathcal{I}_{\hat{Q}}^i}^\top \end{bmatrix} \right\rangle$.

For brevity, in the remainder of the proof denote $\phi_t = \text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix}^\top \right)$, $\psi_t = \text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ K_{\mathcal{I}_{\hat{Q}}^i} x_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t) \\ K_{\mathcal{I}_{\hat{Q}}^i} x_{\mathcal{I}_{\hat{Q}}^i}(t) \end{bmatrix}^\top \right)$, $f = \text{svec} \left(\begin{bmatrix} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x & \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x K_{\mathcal{I}_{\hat{Q}}^i}^\top \\ K_{\mathcal{I}_{\hat{Q}}^i} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x & K_{\mathcal{I}_{\hat{Q}}^i} \Sigma_{\mathcal{I}_{\hat{Q}}^i}^x K_{\mathcal{I}_{\hat{Q}}^i}^\top \end{bmatrix} \right)$, and $\xi_t = \mathbb{E} \left[\text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t+1) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t+1) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}^i}(t+1) \\ u_{\mathcal{I}_{\hat{Q}}^i}(t+1) \end{bmatrix}^\top \right) \right]$.

Assuming that we have a single trajectory of $\left\{ x_{\mathcal{I}_{\hat{Q}}^i}(t), u_{\mathcal{I}_{\hat{Q}}^i}(t), x_{\mathcal{I}_{\hat{Q}}^i}(t+1) \right\}_{t=1}^T$, (98) can be expressed in matrix form as

$$\mathbf{r} = (\mathbf{\Phi} - \mathbf{\Xi} + \mathbf{F})\mathbf{p}, \quad (30)$$

where

$$\mathbf{\Phi} = \begin{bmatrix} \phi_1^\top \\ \phi_2^\top \\ \vdots \\ \phi_T^\top \end{bmatrix}, \quad \mathbf{\Xi} = \begin{bmatrix} \xi_1^\top \\ \xi_2^\top \\ \vdots \\ \xi_T^\top \end{bmatrix}, \quad \mathbf{r} = \begin{bmatrix} r(1) \\ r(2) \\ \vdots \\ r(T) \end{bmatrix}, \quad \mathbf{F} = \begin{bmatrix} f^\top \\ f^\top \\ \vdots \\ f^\top \end{bmatrix}$$

Let

$$\psi_+ = \begin{bmatrix} \psi_2^\top \\ \psi_3^\top \\ \vdots \\ \psi_{T+1}^\top \end{bmatrix}.$$

Note that (30) is an instance of the error-in-variables least square problem whose solution is given by

$$\hat{p} = (\mathbf{\Phi}^\top (\mathbf{\Phi} - \mathbf{\Psi}_+ + \mathbf{F}))^{-1} \mathbf{\Phi}^\top \mathbf{r} \quad (31)$$

Rearranging the terms in (31) to obtain

$$\begin{aligned}\Phi^\top(\Phi - \Psi_+ + \mathbf{F})\hat{p} &= \Phi^\top \mathbf{r} \\ \Rightarrow \Phi\hat{p} &= \Phi(\Phi^\top\Phi)^{-1}\Phi^\top(\mathbf{r} + (\Psi_+ - \mathbf{F})\hat{p})\end{aligned}\quad (32)$$

Define $P_\Phi = \Phi(\Phi^\top\Phi)^{-1}\Phi^\top$ as the orthogonal projection onto the columns of Φ . Combining (30), (32), and using the fact that $P_\Phi\Phi = \Phi$ yields

$$P_\Phi(\Phi - \Xi + \mathbf{F})(p - \hat{p}) = P_\Phi(\Xi - \Psi_+)\hat{p} \quad (33)$$

Consider the i^{th} row of $\Phi - \Xi + \mathbf{F}$,

$$\begin{aligned}\text{svec}\left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix}^\top - \mathbb{E}\left[\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t+1) \\ K_{\mathcal{I}_{\hat{Q}}}^i(x_{\mathcal{I}_{\hat{Q}}}^i(t+1)) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t+1) \\ K_{\mathcal{I}_{\hat{Q}}}^i(x_{\mathcal{I}_{\hat{Q}}}^i(t+1)) \end{bmatrix}^\top\right] \right. \\ \left. + \begin{bmatrix} \Sigma_{\mathcal{I}_{\hat{Q}}}^x & \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \\ K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x & K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \end{bmatrix}\right), \\ \text{where } x_{\mathcal{I}_{\hat{Q}}}^i(t+1) = A_{\mathcal{I}_{\hat{Q}}}^i x_{\mathcal{I}_{\hat{Q}}}^i(t) + B_{\mathcal{I}_{\hat{Q}}}^i u_{\mathcal{I}_{\hat{Q}}}^i(t) + \eta_{\mathcal{I}_{\hat{Q}}}^i. \\ = \text{svec}\left(\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix}^\top - L \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t) \end{bmatrix}^\top L^\top - \begin{bmatrix} \Sigma_{\mathcal{I}_{\hat{Q}}}^x & \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \\ K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x & K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \end{bmatrix} \right. \\ \left. + \begin{bmatrix} \Sigma_{\mathcal{I}_{\hat{Q}}}^x & \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \\ K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x & K_{\mathcal{I}_{\hat{Q}}}^i \Sigma_{\mathcal{I}_{\hat{Q}}}^x K_{\mathcal{I}_{\hat{Q}}}^\top \end{bmatrix}\right), \\ \text{where } L = \begin{bmatrix} A_{\mathcal{I}_{\hat{Q}}}^i & B_{\mathcal{I}_{\hat{Q}}}^i \\ K_{\mathcal{I}_{\hat{Q}}}^i A_{\mathcal{I}_{\hat{Q}}}^i & K_{\mathcal{I}_{\hat{Q}}}^i B_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \\ = (\mathbb{I} - L \otimes_s L)\phi_t.\end{aligned}\quad (34)$$

Combining (34) and (33) and assuming that Φ is full column rank, we obtain

$$\begin{aligned}\Phi(\mathbb{I} - L \otimes_s L)^\top(p - \hat{p}) &= P_\Phi(\Xi - \Psi_+)\hat{p} \\ \Rightarrow (\mathbb{I} - L \otimes_s L)^\top(p - \hat{p}) &= (\Phi^\top\Phi)^{-1}\Phi^\top(\Xi - \Psi_+)\hat{p}.\end{aligned}\quad (35)$$

Let $\sigma_{\min}(\cdot)$ denote the minimum singular value of a matrix. Then, we have that

$$\|(\mathbb{I} - L \otimes_s L)^\top(p - \hat{p})\| \geq \sigma_{\min}(\mathbb{I} - L \otimes_s L)\|p - \hat{p}\|, \quad (36)$$

$$\begin{aligned} \|(\Phi^\top \Phi)^{-1} \Phi^\top (\Xi - \Psi_+) \hat{p}\| &\leq \sigma_{\max}((\Phi^\top \Phi)^{-\frac{1}{2}}) \|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\| \\ &= \lambda_{\max}((\Phi^\top \Phi)^{-\frac{1}{2}}) \|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\| \\ &(\because \Phi^\top \Phi \text{ is symmetric and P.S.D.}, (\Phi^\top \Phi)^{-\frac{1}{2}} \text{ is symmetric and P.S.D.}) \\ &= \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\|}{\lambda_{\min}((\Phi^\top \Phi)^{\frac{1}{2}})} \\ &= \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\|}{\sqrt{\lambda_{\min}(\Phi^\top \Phi)}} \\ &= \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\|}{\sigma_{\min}(\Phi)} \end{aligned} \quad (37)$$

Combining (39), (36), (37) yields

$$\begin{aligned} \sigma_{\min}(\mathbb{I} - L \otimes_s L)\|p - \hat{p}\| &\leq \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\|}{\sigma_{\min}(\Phi)} \\ \Rightarrow \|p - \hat{p}\| &\leq \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \hat{p}\|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} \\ &\leq \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \| \|p - \hat{p}\|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} + \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p\|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} \\ &\quad (\text{By triangle inequality and Cauchy-Schwartz inequality}) \end{aligned} \quad (38)$$

If $\frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} < \frac{1}{2}$, then

$$\|p - \hat{p}\| \leq 2 \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p\|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)}. \quad (39)$$

F.1. Lower bound on $\sigma_{\min}(\Phi)$

Let y be an arbitrary vector on a unit sphere $\mathcal{S}^{n_{\hat{x}}+n_{\hat{u}}-1}$. Define a process $Z_t = \langle \phi_t, y \rangle$, the filtration $\mathcal{F}_t = \sigma(u_{\mathcal{I}_{\hat{Q}}}^i(\tau), w_{\mathcal{I}_{\hat{Q}}}^i(\tau-1))_{\tau=1}^T$.

Then,

$$\begin{bmatrix} x_{\mathcal{I}_{\hat{Q}}}^i(t+1) \\ u_{\mathcal{I}_{\hat{Q}}}^i(t+1) \end{bmatrix} = \begin{bmatrix} A_{\mathcal{I}_{\hat{Q}}}^i x_{\mathcal{I}_{\hat{Q}}}^i(t) + B_{\mathcal{I}_{\hat{Q}}}^i u_{\mathcal{I}_{\hat{Q}}}^i(t) + w_{\mathcal{I}_{\hat{Q}}}^i(t) \\ K_{\mathcal{I}_{\hat{Q}}}^{\prime i} (A_{\mathcal{I}_{\hat{Q}}}^i x_{\mathcal{I}_{\hat{Q}}}^i(t) + B_{\mathcal{I}_{\hat{Q}}}^i u_{\mathcal{I}_{\hat{Q}}}^i(t) + w_{\mathcal{I}_{\hat{Q}}}^i(t)) + \eta_{\mathcal{I}_{\hat{Q}}}^i(t+1). \end{bmatrix} \quad (40)$$

Let $\mu = A_{\mathcal{I}_{\hat{Q}}^i} x_{\mathcal{I}_{\hat{Q}}^i}(t) + B_{\mathcal{I}_{\hat{Q}}^i} u_{\mathcal{I}_{\hat{Q}}^i}(t)$, $C = \begin{bmatrix} \mathbb{I} & 0 \\ K'_{\mathcal{I}_{\hat{Q}}^i} & \mathbb{I} \end{bmatrix} \begin{bmatrix} \Sigma_{\hat{Q}}^{\frac{1}{2}} & 0 \\ 0 & \Sigma_{\hat{Q}}^{\frac{1}{2}} \end{bmatrix}$, $g = \begin{bmatrix} w_{\mathcal{I}_{\hat{Q}}^i}(t) \\ \eta_{\mathcal{I}_{\hat{Q}}^i}(t+1) \end{bmatrix}$, and $Y = \text{smat}(y)$. Therefore, we can express

$$\begin{aligned} \langle \phi_{t+1}, y \rangle &= \begin{bmatrix} x_{t+1} \\ u_{t+1} \end{bmatrix}^\top Y \begin{bmatrix} x_{t+1} \\ u_{t+1} \end{bmatrix} \\ &= (\mu + Cg)^\top Y (\mu + Cg). \end{aligned} \quad (41)$$

is a Gaussian polynomial of degree 2.

Lemma F.1 (Gaussian hyper-contractivity (Proposition 5.48, Aubrun and Szarek (2017))) *For a Gaussian polynomial x of degree atmost k , $\forall q \geq 2$,*

$$\mathbb{E}[\|x\|_{L_q}] \leq (q-1)^{\frac{k}{2}} \mathbb{E}[\|x\|_{L_2}].$$

Therefore, from Lemma F.1 we have

$$\begin{aligned} \mathbb{E}[|Z_{t+1}|_{L_4} | \mathcal{F}_t] &\leq 3\mathbb{E}[|Z_{t+1}|_{L_2} | \mathcal{F}_t] \\ \Rightarrow \mathbb{E}[|Z_{t+1}|^4 | \mathcal{F}_t] &\leq 81\mathbb{E}[|Z_{t+1}|^2 | \mathcal{F}_t]^2. \end{aligned} \quad (42)$$

Employing the Payley-Zygmund inequality, we conclude that for any $\theta \in (0, 1)$,

$$\begin{aligned} P(|Z_{t+1}| \geq \sqrt{\theta \mathbb{E}[|Z_{t+1}|^2 | \mathcal{F}_t]} | \mathcal{F}_t) &= P(|Z_{t+1}|^2 \geq \theta \mathbb{E}[|Z_{t+1}|^2 | \mathcal{F}_t] | \mathcal{F}_t) \\ &\geq (1-\theta)^2 \frac{\mathbb{E}[|Z_{t+1}|^2 | \mathcal{F}_t]^2}{\mathbb{E}[|Z_{t+1}|^4 | \mathcal{F}_t]} \geq \frac{(1-\theta)^2}{81} \text{ (From (42))}. \end{aligned} \quad (43)$$

From (41), we have that

$$\begin{aligned} \mathbb{E}[Z] &= \mathbb{E}[(\mu + Cg)^\top Y (\mu + Cg)] = \mathbb{E}[\mu^\top Y \mu + g^\top C^\top Y C g + 2\mu^\top Y C g] \\ &= \mu^\top Y \mu + \text{Tr}(C^\top Y C) \quad (\because g \text{ is zero mean}). \end{aligned} \quad (44)$$

Therefore,

$$Z - \mathbb{E}[Z] = g^\top C^\top Y C g + 2\mu^\top Y C g - \text{Tr}(C^\top Y C) \quad (45)$$

Assuming $\mathbb{E}(Z^2) \geq 2\|C^\top Y C\|_F^2$, we have that

$$\mathbb{E}[Z_{t+1}^2 | \mathcal{F}_t] \geq 2\|C^\top Y C\|_F^2 = 2\|(C^\top \otimes C^\top)y\| \geq 2\sigma_{\min}^2(C^\top \otimes C^\top) = 2\sigma_{\min}^4(C).$$

Substituting $\theta = \frac{1}{2}$ in (43) yields

$$P(|Z_{t+1}| \geq \sigma_{\min}^2(C) | \mathcal{F}_t) \geq \frac{1}{324}, \quad (46)$$

which establishes that $(Z_t)_{t \geq 1}$ satisfies the $(1, \sigma_{\min}^2(C), \frac{1}{324})$ block martingale small ball condition (BMSB) in Simchowitz et al. (2018).

To compute a crude upper bound on $\|\Phi\|$ using Markov's inequality as

$$P(\|\Phi\|^2 \geq t^2) \leq \frac{\mathbb{E}(\|\Phi\|^2)}{t^2} = \frac{\mathbb{E}(\lambda_{\max}(\Phi^\top \Phi))}{t^2} \stackrel{(a)}{\leq} \frac{\mathbb{E}(\text{Tr}(\Phi^\top \Phi))}{t^2} \stackrel{(b)}{\leq} \frac{\text{Tr}(\mathbb{E}(\Phi^\top \Phi))}{t^2}, \quad (47)$$

where (a) follows from the fact that the $\|\cdot\|_2 \leq \|\cdot\|_F$, and (b) is due to Jensen's inequality.

Now we upper bound $\mathbb{E}[\|\phi_t\|^2]$. Letting $z_t = (x_{\mathcal{I}_{\hat{Q}}}^i(t), u_{\mathcal{I}_{\hat{Q}}}^i(t))$, then we have $\mathbb{E}[\|\phi_t\|^2] = \mathbb{E}[\|z_t\|^4]$. By assumption, x_0 is zero mean which implies z_t is zero mean $\forall t$. Hence, $\mathbb{E}[\|\phi_t\|^2] = \mathbb{E}[\|z_t\|^4] \leq 3(\mathbb{E}[\|z_t\|^2])^2$.

Note that

$$\begin{aligned} \mathbb{E}[\|z_t\|^2] &= \mathbb{E}[(x_{\mathcal{I}_{\hat{Q}}}^\top \ x_{\mathcal{I}_{\hat{Q}}}^\top(t) K_{\mathcal{I}_{\hat{Q}}}^{\prime\top} + \eta_{\mathcal{I}_{\hat{Q}}}^\top) (x_{\mathcal{I}_{\hat{Q}}}^\top \ x_{\mathcal{I}_{\hat{Q}}}^\top(t) K_{\mathcal{I}_{\hat{Q}}}^{\prime\top} + \eta_{\mathcal{I}_{\hat{Q}}}^\top)^\top] \\ &= \mathbb{E}[x_{\mathcal{I}_{\hat{Q}}}^\top x_{\mathcal{I}_{\hat{Q}}}^\top] + \mathbb{E}[x_{\mathcal{I}_{\hat{Q}}}^\top(t) K_{\mathcal{I}_{\hat{Q}}}^{\prime\top} K_{\mathcal{I}_{\hat{Q}}}^{\prime} x_{\mathcal{I}_{\hat{Q}}}^\top(t)] + \mathbb{E}[x_{\mathcal{I}_{\hat{Q}}}^\top(t) \eta_{\mathcal{I}_{\hat{Q}}}^\top] + \mathbb{E}[\eta_{\mathcal{I}_{\hat{Q}}}^\top K_{\mathcal{I}_{\hat{Q}}}^{\prime\top} x_{\mathcal{I}_{\hat{Q}}}^\top(t)] + \mathbb{E}[\eta_{\mathcal{I}_{\hat{Q}}}^\top \eta_{\mathcal{I}_{\hat{Q}}}^\top] \\ &= (1 + \|K_{\mathcal{I}_{\hat{Q}}}^{\prime\top}\|^2) \text{Tr}(\mathbb{E}[x_{\mathcal{I}_{\hat{Q}}} x_{\mathcal{I}_{\hat{Q}}}^\top]) + \text{Tr}(\mathbb{E}[\eta_{\mathcal{I}_{\hat{Q}}} \eta_{\mathcal{I}_{\hat{Q}}}^\top]) \quad (\because \mathbb{E}\eta = 0) \\ &= (1 + \|K_{\mathcal{I}_{\hat{Q}}}^{\prime\top}\|^2) \text{Tr}(\Sigma_i^{\hat{x}}) + \text{Tr}(\Sigma_i^{\hat{u}}) \end{aligned} \quad (48)$$

Assume that the initial global state is sampled from a zero-mean Gaussian distribution i.e., $x(0) \sim \mathcal{N}(0, \Sigma_0^x)$, which implies that $\forall t$, $\mathbb{E}(x(t)) = \mathbb{E}(u(t)) = 0$. Consider the propagation of the covariance

$$\begin{aligned} \Sigma_i^{\hat{x}}(t) &= \mathbb{E}(\hat{x}^i(t)(\hat{x}^i(t))^\top) \\ &= \mathbb{E}[(\hat{A}_{t-1}^i \hat{x}_{t-1}^i + \hat{B}_{t-1}^i \hat{u}_{t-1}^i + \hat{w}_{t-1}^i)(\hat{A}_{t-1}^i \hat{x}_{t-1}^i + \hat{B}_{t-1}^i \hat{u}_{t-1}^i + \hat{w}_{t-1}^i)^\top] \\ &= \mathbb{E}[(\hat{A}_{t-1}^i + \hat{B}_{t-1}^i \hat{K}_{t-1}^i) \hat{x}_{t-1}^i + \hat{B}_{t-1}^i \hat{v}_{t-1}^i + \hat{w}_{t-1}^i] \\ &\quad ((\hat{A}_{t-1}^i + \hat{B}_{t-1}^i \hat{K}_{t-1}^i) \hat{x}_{t-1}^i + \hat{B}_{t-1}^i \hat{v}_{t-1}^i + \hat{w}_{t-1}^i)^\top] \\ &= (\hat{A}_{t-1}^i + \hat{B}_{t-1}^i \hat{K}_{t-1}^i) \mathbb{E}[\hat{x}_{t-1}^i \hat{x}_{t-1}^{i\top}] (\hat{A}_{t-1}^i + \hat{B}_{t-1}^i \hat{K}_{t-1}^i)^\top + \hat{B}_{t-1}^i \mathbb{E}[\hat{v}_{t-1}^i \hat{v}_{t-1}^{i\top}] \hat{B}_{t-1}^{i\top} \\ &\quad + \mathbb{E}[\hat{w}_{t-1}^i \hat{w}_{t-1}^{i\top}]. \end{aligned} \quad (49)$$

Assuming time-invariant system and control gain matrices, recursive expansion of (49) yields

$$\begin{aligned} \Sigma_i^{\hat{x}}(t) &= (\hat{A}^i + \hat{B}^i \hat{K}^i)^t \Sigma_i^{\hat{x}}(0) ((\hat{A}^i + \hat{B}^i \hat{K}^i)^\top)^t \\ &\quad + \sum_{k=1}^t (\hat{A}^i + \hat{B}^i \hat{K}^i)^{k-1} [\Sigma_w^{\hat{x}} + \hat{B}^i \Sigma_\eta^{\hat{u}} \hat{B}^{i\top}] ((\hat{A}^i + \hat{B}^i \hat{K}^i)^\top)^{k-1}. \end{aligned} \quad (50)$$

Applying the trace operator on both sides yields

$$\begin{aligned} \text{Tr}(\Sigma_i^{\hat{x}}(t)) &= \text{Tr}((\hat{A}^i + \hat{B}^i \hat{K}^i)^t \Sigma_i^{\hat{x}}(0) ((\hat{A}^i + \hat{B}^i \hat{K}^i)^\top)^t) \\ &\quad + \text{Tr}\left(\sum_{k=1}^t (\hat{A}^i + \hat{B}^i \hat{K}^i)^{k-1} [\Sigma_w^{\hat{x}} + \hat{B}^i \Sigma_\eta^{\hat{u}} \hat{B}^{i\top}] ((\hat{A}^i + \hat{B}^i \hat{K}^i)^\top)^{k-1}\right) \\ &\stackrel{(a)}{\leq} (n_{\hat{x}} + n_{\hat{u}}) \|\Sigma_i^{\hat{x}}(0)\| \|(\hat{A}^i + \hat{B}^i \hat{K}^i)^t\|^2 \\ &\quad + \text{Tr}\left(\sum_{k=1}^t (\hat{A}^i + \hat{B}^i \hat{K}^i)^{k-1} [\Sigma_w^{\hat{x}} + \hat{B}^i \Sigma_\eta^{\hat{u}} \hat{B}^{i\top}] ((\hat{A}^i + \hat{B}^i \hat{K}^i)^\top)^{k-1}\right), \end{aligned} \quad (51)$$

where (a) follows from the identity that $\forall M \in \mathbb{R}^n, \|M\|_F \leq \sqrt{n} \|M\|$.

Assume that $(\hat{A}^i + \hat{B}^i \hat{K}^i)$ is (τ, ρ) -stable and \hat{K}^i stabilizes (\hat{A}^i, \hat{B}^i) . Let \mathfrak{P}_∞ denote the unique solution of the Lyapunov equation

$$\mathfrak{P} = (\hat{A}^i + \hat{B}^i \hat{K}^i) \mathfrak{P} (\hat{A}^i + \hat{B}^i \hat{K}^i)^\top + \Sigma_{\hat{w}} + \hat{B}^i \Sigma_{\hat{\eta}}^{\hat{u}} \hat{B}^{i\top}. \quad (52)$$

Then, (51) can be rewritten as

$$\text{Tr}(\Sigma_{\hat{i}}^{\hat{x}}(t)) \leq (n_{\hat{x}} + n_{\hat{u}}) \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| (\tau \rho)^2 + \text{Tr}(\mathfrak{P}_\infty), \quad (53)$$

Therefore, we have that

$$\begin{aligned} \sqrt{\mathbb{E}[\|\phi_t\|^2]} &\leq \sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) \text{Tr}(\Sigma_{\hat{i}}^{\hat{x}}(t)) + \text{Tr}(\Sigma_{\hat{i}}^{\hat{u}}(t))) \\ \text{Assuming } A_{\hat{Q}} + B_{\hat{Q}} K_{\hat{Q}}' &\text{ is } (\tau, \rho)\text{-stable.} \\ &\leq \sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty)) + \text{Tr}(\Sigma_{\hat{i}}^{\hat{u}})) \\ \text{Assuming } \text{Tr}(\Sigma_{\hat{i}}^{\hat{u}}) &\leq \text{Tr}(\Sigma_{\hat{i}}^{\hat{x}}(t)) \leq \text{Tr}(\mathfrak{P}_\infty), \text{ we have} \\ &\leq 2\sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty))) \end{aligned} \quad (54)$$

Therefore, the inequality in (47) can be written as

$$P(\|\Phi\|^2 \geq t^2) \leq \frac{T(2\sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty))))^2}{t^2} \quad (55)$$

Choose $t^2 = \frac{T(2\sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty))))^2}{\delta}$, for some $\delta > 0$, then we have that

$$P\left(\|\Phi\| \geq \frac{2\sqrt{T}}{\sqrt{\delta}} \sqrt{3}((1 + \|K_{\hat{Q}}'^\top\|^2) (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty)))\right) \leq \delta. \quad (56)$$

For some $\epsilon > 0$, let $\mathcal{N}(\epsilon)$ denote the ϵ -net of the unit sphere $\mathcal{S}^{(n_{\hat{x}}+n_{\hat{u}})(n_{\hat{x}}+n_{\hat{u}}+1)/2-1}$. By Proposition 2.5 in Simchowicz et al. (2018), and (46), each $\nu \in \mathcal{N}(\epsilon)$ satisfies

$$P\left(\|\Phi\nu\| \leq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}}\right) \leq e^{\frac{-T}{324^2 \cdot 8}} \quad (57)$$

From Corollary 4.2.13 in Vershynin (2018), we have that $\forall \epsilon > 0$, the covering number of the unit sphere S^{d-1} satisfies

$$N(\epsilon) \leq (1 + \frac{2}{\epsilon})^d.$$

Combining this with a union bound over all possible $\nu \in \mathcal{N}(\epsilon)$ yields

$$\begin{aligned} P\left(\min_{\nu \in \mathcal{N}(\epsilon)} \|\Phi\nu\| \geq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}}\right) &\geq 1 - (1 + 2/\epsilon)^{(n_{\hat{x}}+n_{\hat{u}})(n_{\hat{x}}+n_{\hat{u}}+1)/2} e^{\frac{-T}{324^2 \cdot 8}} \\ &\geq 1 - (1 + 2/\epsilon)^{(n_{\hat{x}}+n_{\hat{u}})^2} e^{\frac{-T}{324^2 \cdot 8}}. \end{aligned} \quad (58)$$

We wish to choose δ, ϵ such that $P\left(\min_{\nu \in \mathcal{N}(\epsilon)} \|\Phi\nu\| \geq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}}\right) \geq 1 - \frac{\delta}{2}$, which implies

$$(1 + 2/\epsilon)^{(n_{\hat{x}} + n_{\hat{u}})^2} e^{\frac{-T}{324^2 \cdot 8}} = \frac{\delta}{2}$$

$$\Rightarrow \epsilon = \frac{2}{\exp\left(\frac{1}{(n_{\hat{x}} + n_{\hat{u}})^2} \log\left(\frac{\delta}{2}\right) + \frac{T}{(n_{\hat{x}} + n_{\hat{u}})^2 \cdot 324^2 \cdot 8}\right) - 1}. \quad (59)$$

Note that

$$\sigma_{\min}(\Phi) = \inf_{\|\nu\|=1} \|\Phi\nu\| \geq \min_{\nu \in \mathcal{N}(\epsilon)} \|\Phi\nu\| - \|\Phi\|\epsilon. \quad (60)$$

Since,

$$P\left(\|\Phi\| \geq \frac{2\sqrt{T}}{\sqrt{\delta}} \sqrt{6}((1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty})))\right) \leq \frac{\delta}{2},$$

$$P\left(\min_{\nu \in \mathcal{N}(\epsilon)} \|\Phi\nu\| \leq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}}\right) \leq \frac{\delta}{2},$$

taking a union bound yields that with probability $1 - \delta$,

$$\sigma_{\min}(\Phi) \geq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}} - \frac{2\epsilon\sqrt{T}}{\sqrt{\delta}} \sqrt{6}((1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty}))). \quad (61)$$

Substituting (59) in (61) and setting the RHS to be non-negative yields

$$\begin{aligned} & \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}} - \frac{2\epsilon\sqrt{T}}{\sqrt{\delta}} \sqrt{6}((1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty}))) \geq 0 \\ & \frac{\sigma_{\min}^2(C)}{324\sqrt{8}} \geq \frac{2 \cdot 2 \cdot \sqrt{6}}{\sqrt{\delta}} \frac{((1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty})))}{\exp\left(\frac{1}{(n_{\hat{x}} + n_{\hat{u}})^2} \log\left(\frac{\delta}{2}\right) + \frac{T}{(n_{\hat{x}} + n_{\hat{u}})^2 \cdot 324^2 \cdot 8}\right) - 1} \\ & \frac{1}{(n_{\hat{x}} + n_{\hat{u}})^2} \log\left(\frac{\delta}{2}\right) + \frac{T}{(n_{\hat{x}} + n_{\hat{u}})^2 \cdot 324^2 \cdot 8} \geq \\ & \log\left(1 + \frac{2 \cdot 2 \cdot \sqrt{6} \cdot 324 \cdot \sqrt{8}}{\sqrt{\delta}} \frac{((1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty})))}{\sigma_{\min}^2(C)}\right) \\ & T \geq 324^2 \cdot 8 \left((n_{\hat{x}} + n_{\hat{u}})^2 \log\left(1 + \frac{10368\sqrt{3}}{\sqrt{\delta}} \frac{(1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty})))}{\sigma_{\min}^2(C)}\right) + \log\left(\frac{2}{\delta}\right) \right) \end{aligned} \quad (62)$$

Substituting (62) in (59) yields

$$\epsilon = \frac{\sqrt{\delta}}{5184\sqrt{3}} \frac{\sigma_{\min}^2(C)}{(1 + \|K_{T_{\hat{Q}}}^{\top}\|^2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_{\infty}))).} \quad (63)$$

For the choice of ϵ according to (63) we can ensure that with probability $1 - \delta$,

$$\sigma_{\min}(\Phi) \geq \frac{\sigma_{\min}^2(C)\sqrt{T}}{324\sqrt{8}} - \frac{2\sigma_{\min}^2(C) \cdot \sqrt{2}\sqrt{T}}{2592} = \frac{\sigma_{\min}^2(C)\sqrt{T}}{648\sqrt{8}} \quad (64)$$

Note that if $\Sigma_i^{\hat{u}} = \sigma_\eta^2 \mathbb{I}$, $\Sigma_i^{\hat{x}} = \sigma_w^2 \mathbb{I}$, and $\sigma_\eta \leq \sigma_w$ then

$$\begin{aligned} \sigma_{\min}^2(C) &= \lambda_{\min}(C^\top C) = \lambda_{\min}(CC^\top) = \lambda_{\min} \left(\begin{bmatrix} \Sigma_i^{\hat{x}\frac{1}{2}} & 0 \\ K'_{T_{\hat{Q}}^i} \Sigma_i^{\hat{x}\frac{1}{2}} & \Sigma_i^{\hat{u}\frac{1}{2}} \end{bmatrix} \begin{bmatrix} \Sigma_i^{\hat{x}\frac{1}{2}} & \Sigma_i^{\hat{x}\frac{1}{2}} K'^\top_{T_{\hat{Q}}^i} \\ 0 & \Sigma_i^{\hat{u}\frac{1}{2}} \end{bmatrix} \right) \\ &\stackrel{(a)}{\geq} \frac{\sigma_\eta^2 \lambda_{\min}(\sigma_w^2 \mathbb{I})}{2\sigma_w^2 \|K'_{T_{\hat{Q}}^i} K'^\top_{T_{\hat{Q}}^i}\|_2 + \sigma_\eta^2} \\ &\stackrel{(b)}{\geq} \frac{\sigma_\eta^2 \sigma_w^2}{2\sigma_w^2 \|K'_{T_{\hat{Q}}^i} K'^\top_{T_{\hat{Q}}^i}\|_2 + 2\sigma_w^2} \\ &= \frac{\sigma_\eta^2}{2(1 + \|K'_{T_{\hat{Q}}^i}\|^2)}, \end{aligned} \quad (65)$$

where (a) follows from Lemma F.6 in Dean et al. (2018) and (b) is due to the assumption that $\sigma_\eta \leq \sigma_w$.

Therefore, by combining (64) and (65), we conclude that if $A_{T_{\hat{Q}}^i} + B_{T_{\hat{Q}}^i} K'^\top_{T_{\hat{Q}}^i}$ is (τ, ρ) -stable, $\Sigma_i^{\hat{u}} = \sigma_\eta^2 \mathbb{I}$, $\Sigma_i^{\hat{x}} = \sigma_w^2 \mathbb{I}$, and $\sigma_\eta \leq \sigma_w$, and

$$T \geq 324^2 \cdot 8 \left((n_{\hat{x}} + n_{\hat{u}})^2 \log \left(1 + \frac{10368\sqrt{3}}{\sqrt{\delta}} \frac{(1 + \|K'^\top_{T_{\hat{Q}}^i}\|_2)(\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_i^{\hat{x}}(0)\| + \text{Tr}(\mathfrak{P}_\infty))}{\sigma_{\min}^2(C)} \right) + \log\left(\frac{2}{\delta}\right) \right),$$

then for some $\delta > 0$, with probability $1 - \delta$,

$$\sigma_{\min}(\Phi) \geq \frac{\sigma_\eta^2 \sqrt{T}}{1296\sqrt{8}(1 + \|K'_{T_{\hat{Q}}^i}\|^2)}.$$

F.2. Upper bound of the numerator in (39)

For the remainder of the proof, let $c_i \forall i$ denote universal constants. Define

$$V_1 := c_1 \frac{\sigma_\eta^4}{(1 + \|K'_{T_{\hat{Q}}^i}\|^2)^2} T \cdot \mathbb{I},$$

$$V_2 := c_2 \frac{T}{\delta} (1 + \|K'_{T_{\hat{Q}}^i}\|^2)^2 (\tau^2 \rho^2 n \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2 \cdot \mathbb{I}.$$

Then, by the above proposition and (56), define an event ζ_1 such that with atleast probability $1 - \delta$ we have that

$$V_1 \preceq \Phi^\top \Phi \preceq V_2.$$

For brevity, let $x_{\mathcal{I}_{\hat{Q}}}^i(t) = \hat{x}_t^i$, $u_{\mathcal{I}_{\hat{Q}}}^i(t) = \hat{u}_t^i$, $A_{\mathcal{I}_{\hat{Q}}}^i(t) = \hat{A}_t^i$, $B_{\mathcal{I}_{\hat{Q}}}^i(t) = \hat{B}_t^i$, and $K_{\mathcal{I}_{\hat{Q}}}^i(t) = \hat{K}_t^i$. Note that,

$$\begin{aligned} \mathbb{E}[\hat{x}_{t+1}^i \hat{x}_{t+1}^{i\top} | \hat{x}_t^i, \hat{u}_t^i] - \hat{x}_{t+1}^i \hat{x}_{t+1}^{i\top} &= \mathbb{E}[(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i + \hat{w}_t^i)(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i + \hat{w}_t^i)^\top | \hat{x}_t^i, \hat{u}_t^i] \\ &\quad - (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i + \hat{w}_t^i)(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i + \hat{w}_t^i)^\top, \\ &= (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top + \hat{\Sigma}_{w_t}^i - (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top \\ &\quad - \hat{w}_t^i(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top - (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) \hat{w}_t^{i\top} - \hat{w}_t^i \hat{w}_t^{i\top}. \end{aligned} \quad (66)$$

Therefore, it is straightforward to verify that

$$\begin{aligned} \mathbb{E}[\psi_{t+1} | \hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1} &= \\ \text{svec} \left(\begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} (\sigma_w^2 \mathbb{I} - \hat{w}_t^i(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top - (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) \hat{w}_t^{i\top} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top \right). \end{aligned} \quad (67)$$

Taking inner product of (67) with p yields

$$\begin{aligned} (\mathbb{E}[\psi_{t+1} | \hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1})^\top p &= \\ \text{Tr} \left((\sigma_w^2 \mathbb{I} - \hat{w}_t^i(\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top - (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) \hat{w}_t^{i\top} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \right) \\ &= \text{Tr} \left((\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \right) - 2 \hat{w}_t^{i\top} \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) \end{aligned} \quad (68)$$

Theorem F.1 (Hanson-Wright Inequality (Theorem 6.2.1, Vershynin (2018))) *Let $X = (X_1, \dots, X_n)$ $\in \mathbb{R}^n$ be a random vector with independent, mean zero, sub-Gaussian coordinates. Let A be a $n \times n$ matrix, and $K = \max_i \|X_i\|_{\psi_2}$. Then, $\forall t > 0$, we have*

$$P(|X^\top A X - \mathbb{E} X^\top A X| \geq t) \leq 2 \exp \left(-c \min \left(\frac{t^2}{K^4 \|A\|_F^2}, \frac{t}{K^2 \|A\|_{\text{op}}} \right) \right),$$

Let

$$\begin{aligned} \delta/T &= 2 \exp \left(-c \frac{t^2}{K^4 \|A\|_F^2} \right) \Rightarrow t^2 = \frac{K^4 \|A\|_F^2}{c} \log \left(\frac{2T}{\delta} \right), \text{ (or)} \\ \delta/T &= 2 \exp \left(-c \frac{t}{K^2 \|A\|_{\text{op}}} \right) \Rightarrow t = \frac{K^2 \|A\|_{\text{op}}}{c} \log \left(\frac{2T}{\delta} \right) \end{aligned} \quad (69)$$

From (69), (68) we have that with probability $1 - \frac{\delta}{T}$,

$$\begin{aligned} \left| \text{Tr} \left((\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \right) \right| &\leq \\ \min \left(\frac{K^2 \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \right\|}{c} \log \left(\frac{2T}{\delta} \right), \frac{K^2 \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}}^i \end{bmatrix} \right\|_F}{\sqrt{c}} \sqrt{\log \left(\frac{2T}{\delta} \right)} \right). \end{aligned} \quad (70)$$

Since, $\hat{w}_t^i \sim \mathcal{N}(0, \sigma_w^2 \mathbb{I})$, $K = \sigma_w$, and $\left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right\| \leq \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top \right\| \|P_i\| \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right\|$.

Note that

$$\left\| \begin{bmatrix} \mathbb{I} \\ \hat{K} \end{bmatrix} \right\| = \sqrt{\lambda_{\max}(\mathbb{I} + \hat{K}^\top \hat{K})} = \sqrt{\max_{x \in S_{n_{\hat{x}}}} \frac{x^\top (\mathbb{I} + \hat{K}^\top \hat{K}) x}{x^\top x}} = \sqrt{1 + \max_{x \in S_{n_{\hat{x}}}} \frac{x^\top \hat{K}^\top \hat{K} x}{x^\top x}} = \sqrt{1 + \lambda_{\max}(\hat{K}^\top \hat{K})}. \quad (71)$$

Since, $\|M\| = \|M^\top\|$ and $\|M\| \leq \|M\|_F$, we have that

$$\|A\| \leq (1 + \lambda_{\max}(\hat{K}^\top \hat{K})) \|P_i\| \leq (1 + \|\hat{K}\|^2) \|P_i\|_F, \quad (72)$$

Similarly, we have

$$\|A\|_F \leq (\sqrt{n_{\hat{x}}}) \|A\| \leq (\sqrt{n_{\hat{x}}}) (1 + \|\hat{K}\|^2) \|P_i\|_F. \quad (73)$$

Therefore, we have that

$$\begin{aligned} & \left| \text{Tr} \left((\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right) \right| \leq \\ & \min \left(\frac{\sigma_w^2 (1 + \|\hat{K}\|^2) \|P_i\|_F}{c} \log\left(\frac{2T}{\delta}\right), \frac{\sigma_w^2 (\sqrt{n_{\hat{x}}}) (1 + \|\hat{K}\|^2) \|P_i\|_F}{\sqrt{c}} \sqrt{\log\left(\frac{2T}{\delta}\right)} \right) \\ & \Rightarrow \left| \text{Tr} \left((\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right) \right| \leq c_1 \sigma_w^2 (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log\left(\frac{T}{\delta}\right), \end{aligned} \quad (74)$$

where c_1 is a universal constant.

From proposition 4.7 in [Tu and Recht \(2018\)](#), with probability $1 - \delta/T$,

$$\begin{aligned} & \left| w_t^\top \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} (Ax_t + Bu_t) \right| \leq \\ & \min \left(\frac{\left\| \Sigma_w^{\hat{x}_{\frac{1}{2}}} \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \Sigma_{t+1}^{\hat{x}_{\frac{1}{2}}} \right\|_F \sqrt{\log(2T/\delta)}}{\sqrt{c}}, \frac{\left\| \Sigma_w^{\hat{x}_{\frac{1}{2}}} \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \Sigma_{t+1}^{\hat{x}_{\frac{1}{2}}} \right\|_F}{c} \log(2T/\delta) \right) \end{aligned} \quad (75)$$

Let $L' = \hat{A}^i + \hat{B}^i \hat{K}^n$. Then, observe that

$$\begin{aligned} & \left\| \Sigma_w^{\hat{x}_{\frac{1}{2}}} \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \Sigma_{t+1}^{\hat{x}_{\frac{1}{2}}} \right\|_F \leq \left\| \Sigma_w^{\hat{x}_{\frac{1}{2}}} \right\|_F \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right\|_F \left\| \Sigma_{t+1}^{\hat{x}_{\frac{1}{2}}} \right\|_F \\ & \leq \|\sigma_w I\|_F \sqrt{n_{\hat{x}}} (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\text{Tr}(L^{t+1} \Sigma_i^{\hat{x}}(0) (L^\top)^{t+1}) + \text{Tr}(\mathfrak{P}_{t+1})} \\ & \quad \text{(From (73), (51))} \\ & = n_{\hat{x}} \sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\text{Tr}(L^{t+1} \Sigma_i^{\hat{x}}(0) (L^\top)^{t+1}) + \text{Tr}(\mathfrak{P}_t) + \text{Tr}(\sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top)}. \end{aligned} \quad (76)$$

Similarly, it is straightforward to show that

$$\begin{aligned}
 & \left\| \Sigma_w^{\hat{x}^{\frac{1}{2}}} \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \Sigma_{t+1}^{\hat{x}^{\frac{1}{2}}} \right\| \leq \left\| \Sigma_w^{\hat{x}^{\frac{1}{2}}} \right\| \left\| \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} \right\| \left\| \Sigma_{t+1}^{\hat{x}^{\frac{1}{2}}} \right\| \\
 & \leq \|\sigma_w I\| (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\|L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1} + \mathfrak{P}_{t+1}\|} \\
 & \quad \text{(From (72), (51), and using } \|M^{\frac{1}{2}}\| = \|M\|^{\frac{1}{2}}, \forall \text{ symmetric, p.s.d } M.) \\
 & = \sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\|L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1} + L \mathfrak{P}_t L^\top + \sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top\|}. \tag{77}
 \end{aligned}$$

Therefore, combining (76), (77) yields

$$\begin{aligned}
 & \left| w_t^\top \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} (Ax_t + Bu_t) \right| \leq \\
 & \sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \\
 & \min \left(\frac{n_{\hat{x}} \sqrt{\text{Tr}(L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1}) + \text{Tr}(L \mathfrak{P}_t L^\top) + \text{Tr}(\sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top)}}{\sqrt{c}} \sqrt{\log(2T/\delta)}, \right. \\
 & \quad \left. \frac{\sqrt{\|L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1} + L \mathfrak{P}_t L^\top + \sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top\|}}{c} \log(2T/\delta) \right) \tag{78}
 \end{aligned}$$

Since, $\|\cdot\| \leq \|\cdot\|_F$, and $\min(\log(2T/\delta)/c, \sqrt{\log(2T/\delta)/c}) \leq \log(2T/\delta)/c$. Thus, we have that

$$\begin{aligned}
 & \left| w_t^\top \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix}^\top P_i \begin{bmatrix} I \\ K_{\mathcal{I}_{\hat{Q}}^i} \end{bmatrix} (Ax_t + Bu_t) \right| \leq \frac{\sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F}{c} \sqrt{\|L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1} + L \mathfrak{P}_t L^\top + \sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top\|} \\
 & \leq c_1 \sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\|L^{t+1} \Sigma_i^{\hat{x}}(0)(L^\top)^{t+1}\| + \|L \mathfrak{P}_t L^\top\| + \|\sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top\| \log(2T/\delta)} \\
 & \stackrel{(a)}{\leq} c_1 \sigma_w (1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \sqrt{\tau^2 \rho^{2(t+1)} \|\Sigma_i^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \|\sigma_\eta^2 \hat{B} \hat{B}^\top\| \log(2T/\delta)}, \tag{79}
 \end{aligned}$$

where (a) is due to $\mathfrak{P}_t \preceq \mathfrak{P}_\infty$, $(\hat{A}^i + \hat{B}^i \hat{K}^i) \mathfrak{P}_\infty (\hat{A}^i + \hat{B}^i \hat{K}^i)^\top \preceq \mathfrak{P}_\infty$, and $(\hat{A}^i + \hat{B}^i \hat{K}^i)$ is (τ, ρ) -stable.

From (68), (74), and (79) we obtain that

$$\begin{aligned}
 & (\mathbb{E}[\psi_{t+1}|\hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1})^\top p \leq \\
 & c_2(\sigma_w^2 + \sigma_w \sqrt{\tau^2 \rho^{2(t+1)} \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B\|^2})(1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log(T/\delta) \\
 & \stackrel{(a)}{\leq} c'_3 \sigma_w \sqrt{\tau^2 \rho^{2(t+1)} \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B\|^2}(1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log(T/\delta) \\
 & \leq c'_3 \sigma_w \sqrt{\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B\|^2}(1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log(T/\delta), \quad \forall t \geq 1 \\
 & \leq \frac{\left(c_3 \sigma_w \sqrt{\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B\|^2}(1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log(T/\delta) \right)^2}{2} \quad (80)
 \end{aligned}$$

where the inequality (a) holds because $\mathfrak{P}_\infty \succeq \sigma_w^2 \mathbb{I}$ and hence $\sigma_w \leq \|\mathfrak{P}_\infty\|^{\frac{1}{2}}$.
Therefore, $\forall \lambda \in \mathbb{R}$ and $t \geq 1$, (80) can be rewritten as

$$\begin{aligned}
 & e^{\lambda(\mathbb{E}[\psi_{t+1}|\hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1})^\top p} \leq e^{\frac{\lambda^2 R^2}{2}} \\
 & \Rightarrow \mathbb{E}[e^{\lambda(\mathbb{E}[\psi_{t+1}|\hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1})^\top p}] \leq e^{\frac{\lambda^2 R^2}{2}}, \quad (81)
 \end{aligned}$$

where $R = c_3 \sigma_w \sqrt{\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B\|^2}(1 + \|K_{\mathcal{I}_{\hat{Q}}^i}\|^2) \|P_i\|_F \log(T/\delta)$.

Therefore, for any fixed $v \in \mathbb{R}^{n_{\hat{x}} + n_{\hat{u}}}$, $(\mathbb{E}[\psi_{t+1}|\hat{x}_t^i, \hat{u}_t^i] - \psi_{t+1})^\top v$ is R -sub-Gaussian.

To upper bound $(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p$, note that as

$$V_1 \preceq (\Phi^\top \Phi) \Rightarrow V_1 + \Phi^\top \Phi \preceq 2(\Phi^\top \Phi) \Rightarrow (V_1 + \Phi^\top \Phi)^{-1} \succeq \frac{1}{2}(\Phi^\top \Phi)^{-1} \Rightarrow \|2(V_1 + \Phi^\top \Phi)^{-1}\| \geq \|(\Phi^\top \Phi)^{-1}\|.$$

From Corollary 1 in Abbasi-Yadkori et al. (2011) we have that w.p $1 - \delta/2$,

$$\begin{aligned}
 & \| (V_1 + (\Phi^\top \Phi))^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p \| \leq \| (V_1 + (\Phi^\top \Phi))^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p \| \\
 & \leq 2\sqrt{2}R \sqrt{\log \left(2 \cdot 5^{(n_{\hat{x}} + n_{\hat{u}})((n_{\hat{x}} + n_{\hat{u}} + 1)/2)} \cdot \frac{\det \left((V_1 + (\Phi^\top \Phi))^{\frac{1}{2}} V_1^{-\frac{1}{2}} \right)}{\delta} \right)} \\
 & \leq \sqrt{2}R \left[\sqrt{\log (2 \cdot 5^{(n_{\hat{x}} + n_{\hat{u}})((n_{\hat{x}} + n_{\hat{u}} + 1)/2)})} + \sqrt{\log \left(\frac{\det ((V_1 + (\Phi^\top \Phi)) V_1^{-1})^{\frac{1}{2}}}{\delta} \right)} \right] \\
 & \leq c_4 R(n_{\hat{x}} + n_{\hat{u}}) + R c_5 \sqrt{\log \left(\frac{\det ((V_1 + (\Phi^\top \Phi)) V_1^{-1})^{\frac{1}{2}}}{\delta} \right)}, \quad (82)
 \end{aligned}$$

where the last inequality follows from $(n_{\hat{x}} + n_{\hat{u}})((n_{\hat{x}} + n_{\hat{u}} + 1)/2) \leq (n_{\hat{x}} + n_{\hat{u}})^2$, Call this event \mathcal{E}_2 .

For the remainder of the proof we consider the case where $\mathcal{E}_1 \cap \mathcal{E}_2$ occurs with probability $1 - \delta$. Therefore, by application of Lemma A.5 in [Krauth et al. \(2019\)](#), we have that

$$\begin{aligned}
 & \|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p\| \leq \sqrt{2} \left\| (V_1 + (\Phi^\top \Phi))^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p \right\| \\
 & \leq c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7R \sqrt{\log \left(\frac{\det \left((V_1 + (\Phi^\top \Phi))^{\frac{1}{2}} V_1^{-\frac{1}{2}} \right)}{\delta} \right)} \\
 & \leq c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7R \sqrt{\log \left(\frac{\det \left((V_1 + V_2)^{\frac{1}{2}} V_1^{-\frac{1}{2}} \right)}{\delta} \right)} \\
 & = c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7R \sqrt{\log \left(\frac{\det \left((V_1 + V_2) V_1^{-1} \right)^{\frac{1}{2}}}{\delta} \right)} \\
 & = c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7R \sqrt{\log \left(\frac{\det \left((\mathbb{I} + c_1^{-1} c_2 \frac{1}{\delta \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2 \cdot \mathbb{I}) \right)^{\frac{1}{2}}}{\delta} \right)} \\
 & = c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7R \sqrt{\log \left(\left(\frac{1}{\delta^{\frac{2}{(n_{\hat{x}} + n_{\hat{u}})^2}}} (1 + c_1^{-1} c_2 \frac{1}{\delta \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2) \right)^{\frac{(n_{\hat{x}} + n_{\hat{u}})^2}{2}} \right)} \\
 & = c_6(n_{\hat{x}} + n_{\hat{u}})R \\
 & \quad + c_7R \frac{(n_{\hat{x}} + n_{\hat{u}})}{\sqrt{2}} \sqrt{\frac{2}{(n_{\hat{x}} + n_{\hat{u}})^2} \log \left(\frac{1}{\delta} \right) + \log \left((1 + c_1^{-1} c_2 \frac{1}{\delta \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2) \right)} \\
 & \leq c_6(n_{\hat{x}} + n_{\hat{u}})R \\
 & \quad + c_7R \frac{(n_{\hat{x}} + n_{\hat{u}})}{\sqrt{2}} \sqrt{\log \left(\frac{1}{\delta} \right) + \log \left((1 + c_1^{-1} c_2 \frac{1}{\delta \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2) \right)} \quad (\because n_{\hat{x}}, n_{\hat{u}} \geq 1) \\
 & = c_6(n_{\hat{x}} + n_{\hat{u}})R + c_7 \frac{(n_{\hat{x}} + n_{\hat{u}})}{\sqrt{2}} R \sqrt{\log \left(\frac{1}{\delta} + \frac{1}{\delta^2 \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2 \right)} \\
 & \text{Note that } \forall \zeta \in \mathbb{R}_{>0}, \exists \text{ a sufficiently large } M \in \mathbb{R}, \text{ such that } \log \left(\frac{1}{\delta} + \frac{\zeta}{\delta^2} \right) \leq M^2 \log \left(\frac{\zeta}{\delta} \right), \text{ Therefore, we have that} \\
 & \leq c_6(n_{\hat{x}} + n_{\hat{u}})R + c_8(n_{\hat{x}} + n_{\hat{u}})R \sqrt{\log \left(\frac{1}{\delta \sigma_\eta^4} (1 + \|K'_{\mathcal{I}_{\hat{Q}}} \|^2)^4 (\tau^2 \rho^2 n_{\hat{x}} \|\Sigma_0\| + \text{Tr}(\mathfrak{P}_\infty))^2 \right)} \\
 & \leq c(n_{\hat{x}} + n_{\hat{u}})R \text{ polylog} \left(\frac{1}{\delta}, \frac{1}{\sigma_\eta^4}, \tau, n_{\hat{x}}, \|\Sigma_0\|, \|K'_{\mathcal{I}_{\hat{Q}}}\|, \|\mathfrak{P}_\infty\| \right) \tag{83}
 \end{aligned}$$

Next, consider

$$\begin{aligned}
 \|\mathbb{E}[\psi_{t+1}|x_t, u_t] - \psi_{t+1}\| &\leq \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix} (\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}) \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix}^\top \right\| + \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix} \hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix}^\top \right\|_F \\
 &\quad (\text{By triangle inequality and the identity } \|\cdot\| \leq \|\cdot\|_F) \\
 &= \|(\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top})\| \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix}^\top \right\| \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix} \right\| + \|\hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top\| \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix}^\top \right\|_F \left\| \begin{bmatrix} I \\ K_{T_{\hat{Q}}^i} \end{bmatrix} \right\|_F \\
 &\quad [\text{By sub-multiplicativity.}] \\
 &\leq (1 + \|K_{T_{\hat{Q}}^i}\|^2) (\|\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}\| + n_{\hat{x}} \|\hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top\|_F) \quad (84)
 \end{aligned}$$

By Corollary 5.50 in [Vershynin \(2010\)](#), we have that w.p $1 - \delta/T$

$$\begin{aligned}
 \|\sigma_w^2 \mathbb{I} - \hat{w}_t^i \hat{w}_t^{i\top}\| &\leq c_9 \sigma_w^2 \max \left(\sqrt{n_{\hat{x}} + \log(2T/\delta)}, n_{\hat{x}} + \log(2T/\delta) \right) \\
 &= c_9 \sigma_w^2 (n_{\hat{x}} + \log(2T/\delta)). \quad (85)
 \end{aligned}$$

Next, consider

$$\begin{aligned}
 \|\hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top\|_F &= \sqrt{\text{Tr} \left((\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) (\hat{w}_t^i)^\top \hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top \right)} \\
 &= \sqrt{\text{Tr} \left((\hat{w}_t^i)^\top \hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i) \right)} \quad (\text{By cyclic property of trace.}) \\
 &= \|\hat{w}_t^i\|_2 \left\| \hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i \right\|_2. \quad (86)
 \end{aligned}$$

Observe that $\|\hat{w}_t^i\|_2^2 = \frac{1}{2} [a \ b] \begin{bmatrix} 0 & \sigma_w^2 \\ \sigma_w^2 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$, $\left\| \hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i \right\|_2^2 = \frac{1}{2} [a \ b] \begin{bmatrix} 0 & \Sigma_{t+1}^{\hat{x}} \\ \Sigma_{t+1}^{\hat{x}} & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$, where a, b are isotropic Gaussian random variables. Then, by Hanson-Wright inequality ([Theorem F.1](#)), we have that w.p $1 - \delta/T$

$$\begin{aligned}
 \|\hat{w}_t^i\|_2^2 &\leq \min \left(\frac{\sigma_w^2 \|\mathbb{I}\|_F}{\sqrt{c_{10}}} \sqrt{\log(2T/\delta)}, \frac{\sigma_w^2 \|\mathbb{I}\|}{c_{10}} \log(2T/\delta) \right) \stackrel{(a)}{\leq} c_{10} \sigma_w^2 \log(T/\delta), \\
 \left\| \hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i \right\|_2^2 &\leq \min \left(\frac{\|\Sigma_{t+1}^{\hat{x}}\|_F}{\sqrt{c_{11}}} \sqrt{\log(2T/\delta)}, \frac{\|\Sigma_{t+1}^{\hat{x}}\|}{c_{11}} \log(2T/\delta) \right) \stackrel{(b)}{\leq} c_{11} \left\| \Sigma_{t+1}^{\hat{x}} \right\| \log(T/\delta),
 \end{aligned}$$

where (a), (b) are due to the identities $\|\cdot\| \leq \|\cdot\|_F$, $\min(\log(2T/\delta)/c, \sqrt{\log(2T/\delta)/c}) \leq \log(2T/\delta)/c$. Therefore, from [\(86\)](#) we have that w.p $1 - \delta/T$,

$$\begin{aligned}
 \|\hat{w}_t^i (\hat{A}_t^i \hat{x}_t^i + \hat{B}_t^i \hat{u}_t^i)^\top\|_F &\leq \sqrt{c_{10} \sigma_w^2 \log(T/\delta)} \sqrt{c_{11} \left\| \Sigma_{t+1}^{\hat{x}} \right\| \log(T/\delta)} \\
 &= \sqrt{c_{10} c_{11}} \sigma_w \log(T/\delta) \sqrt{\left\| L^{t+1} \Sigma_i^{\hat{x}}(0) (L^\top)^{t+1} + \mathfrak{P}_{t+1} \right\|} \\
 &= \sqrt{c_{10} c_{11}} \sigma_w \log(T/\delta) \sqrt{\left\| L^{t+1} \Sigma_i^{\hat{x}}(0) (L^\top)^{t+1} + L \mathfrak{P}_t L^\top + \sigma_w^2 \mathbb{I} + \sigma_\eta^2 \hat{B} \hat{B}^\top \right\|} \\
 &\stackrel{(a)}{\leq} \sqrt{c_{10} c_{11}} \sigma_w \log(T/\delta) \sqrt{\tau^2 \rho^{2(t+1)} \left\| \Sigma_i^{\hat{x}}(0) \right\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \left\| \sigma_\eta^2 \hat{B} \hat{B}^\top \right\|}, \quad (87)
 \end{aligned}$$

where $L = \hat{A} + \hat{B}\hat{K}'$, and (a) follows from the (τ, ρ) –stability assumption of L , $\mathfrak{P}_t \preceq \mathfrak{P}_\infty$, and $L\mathfrak{P}_\infty L^\top \preceq \mathfrak{P}_\infty$.

Combining (84), (85), and (87) yields

$$\begin{aligned} & \|\mathbb{E}[\psi_{t+1}|x_t, u_t] - \psi_{t+1}\| \leq \\ & (1 + \|K_{T_{\hat{Q}}}^i\|^2) \left(c_9 \sigma_w^2 (n_{\hat{x}} + \log(2T/\delta)) + n_{\hat{x}} \sqrt{c_{10}c_{11}} \sigma_w \log(T/\delta) \sqrt{\tau^2 \rho^{2(t+1)} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \|\sigma_\eta^2 \hat{B}\hat{B}^\top\|} \right) \\ & \stackrel{(a)}{\leq} 2\sqrt{c_{10}c_{11}} \sigma_w (n_{\hat{x}}) \log(T/\delta) \sqrt{\tau^2 \rho^{2(t+1)} \|\Sigma_{\hat{i}}^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \|\sigma_\eta^2 \hat{B}\hat{B}^\top\|}, \end{aligned} \quad (88)$$

where (a) follows from $\sigma_w^2 \mathbb{I} \leq \mathfrak{P}_\infty$ which implies $\sigma_w^2 \leq \|\mathfrak{P}_\infty\|^{\frac{1}{2}}$.

F.3. Obtaining the final bound

Next, observe that we can lower bound $\sigma_{\min}(\mathbb{I} - L \otimes_s L)$ using (τ, ρ) –stability of $\hat{A} + \hat{B}\hat{K}$ because for $k \geq 1$, we have

$$\begin{aligned} \|L^k\| &= \left\| \begin{bmatrix} A_{T_{\hat{Q}}}^i & B_{T_{\hat{Q}}}^i \\ K_{T_{\hat{Q}}}^i A_{T_{\hat{Q}}}^i & K_{T_{\hat{Q}}}^i B_{T_{\hat{Q}}}^i \end{bmatrix} \right\|^k = \left\| \begin{bmatrix} \mathbb{I} \\ \hat{K} \end{bmatrix} (\hat{A} + \hat{B}\hat{K})^{k-1} \begin{bmatrix} \hat{A} & \hat{B} \end{bmatrix} \right\| \\ &\leq \left\| \begin{bmatrix} \mathbb{I} \\ \hat{K} \end{bmatrix} \right\| \|(\hat{A} + \hat{B}\hat{K})^{k-1} \begin{bmatrix} \hat{A} & \hat{B} \end{bmatrix}\| \quad (\text{Sub-multiplicativity}) \\ &\stackrel{(a)}{\leq} 2\tau\rho^{k-1} \max(1, \|\hat{K}\|) \left\| \begin{bmatrix} \hat{A} & \hat{B} \end{bmatrix} \right\| \\ &\leq \frac{2\tau\rho^k \|\hat{K}\|_+ \sqrt{(\|\hat{A}\|^2 + \|\hat{B}\|^2)}}{\rho} \quad (\text{See Appendix H}), \end{aligned} \quad (89)$$

where $\|\cdot\|_+ = \max(1, \|\cdot\|)$. The inequality (a) above follows from the identity that

$$\begin{aligned} \left\| \begin{bmatrix} \mathbb{I} \\ \hat{K} \end{bmatrix} \right\| &= \sqrt{\lambda_{\max}(\mathbb{I} + \hat{K}^\top \hat{K})} = \sqrt{\max_{x \in S_{n_{\hat{x}}}} \frac{x^\top (\mathbb{I} + \hat{K}^\top \hat{K}) x}{x^\top x}} = \sqrt{1 + \max_{x \in S_{n_{\hat{x}}}} \frac{x^\top \hat{K}^\top \hat{K} x}{x^\top x}} \\ &= \sqrt{1 + \lambda_{\max}(\hat{K}^\top \hat{K})} \leq 2 \max \left(1, \sqrt{\lambda_{\max}(\hat{K}^\top \hat{K})} \right) = 2 \max(1, \|\hat{K}\|). \end{aligned} \quad (90)$$

Therefore, from (89) we conclude that L is $(\frac{2\tau\rho^k \|\hat{K}\|_+ \sqrt{(\|\hat{A}\|^2 + \|\hat{B}\|^2)}}{\rho}, \rho)$ –stable. Next, we know by definition of singular value that $\sigma_{\min}(\mathbb{I} - L \otimes_s L) = \frac{1}{\|(\mathbb{I} - L \otimes_s L)^{-1}\|}$. Therefore, for any unit norm

vector v ,

$$\begin{aligned}
 \|(\mathbb{I} - L \otimes_s L)^{-1} \text{svec}(\text{smat}(v))\| &= \|(\sum_{k=0}^{\infty} (L \otimes_s L)^k \text{svec}(\text{smat}(v)))\| \left(\because (\mathbb{I} - M)^{-1} = \sum_{k=0}^{\infty} M^k, \text{ See Section 3.4, Peter} \right) \\
 &= \left\| \sum_{k=0}^{\infty} L^k \text{smat}(v) (L^\top)^k \right\| \quad (\text{By definition of } \otimes_s) \\
 &\leq \sum_{k=0}^{\infty} \|L^k\| \|\text{smat}(v)\|_F \|(L^\top)^k\| \quad (\text{By triangle inequality, sub-multiplicativity of } \|\cdot\|, \text{ and } \|\cdot\| \leq \|\cdot\|_F) \\
 &\leq \frac{4\tau^2 \|\hat{K}\|_+^2 (\|\hat{A}\|^2 + \|\hat{B}\|^2)}{\rho^2} \sum_{k=0}^{\infty} \rho^{2k} \\
 &= \frac{4\tau^2 \|\hat{K}\|_+^2 (\|\hat{A}\|^2 + \|\hat{B}\|^2)}{\rho^2 (1 - \rho^2)}. \tag{91}
 \end{aligned}$$

Therefore, we have that

$$\sigma_{\min}(\mathbb{I} - L \otimes_s L) \geq \frac{\rho^2 (1 - \rho^2)}{4\tau^2 \|\hat{K}\|_+^2 (\|\hat{A}\|^2 + \|\hat{B}\|^2)}. \tag{92}$$

From (62), (65), we have that as long as $T \geq \tilde{O}(1)(n_{\hat{x}} + n_{\hat{u}})^2$

$$\sigma_{\min}(\Phi) \geq c \frac{\sigma_\eta^2 \sqrt{T}}{\|\hat{K}'\|_+^2}. \tag{93}$$

By combining (83), (92), (93) and the condition in (39) we obtain that

$$\begin{aligned}
 &\frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) \|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} < \frac{1}{2} \\
 &\Rightarrow \frac{\tilde{O}(1) n_{\hat{x}} (n_{\hat{x}} + n_{\hat{u}}) \|\hat{K}'\|_+^2}{\sigma_\eta^2 \sqrt{T}} \sigma_w \sqrt{\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|\hat{B}\|^2} \|\hat{K}\|_+^2 \frac{4\tau^2 \|\hat{K}\|_+^2 (\|\hat{A}\|^2 + \|\hat{B}\|^2)}{\rho^2 (1 - \rho^2)} \leq \frac{1}{2} \\
 &\Rightarrow T \geq \frac{\tilde{O}(1) n_{\hat{x}}^2 (n_{\hat{x}} + n_{\hat{u}})^2 \|\hat{K}'\|_+^4}{\sigma_\eta^4} \sigma_w^2 (\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|\hat{B}\|^2) \frac{\tau^4 \|\hat{K}\|_+^8 (\|\hat{A}\|^2 + \|\hat{B}\|^2)^2}{\rho^4 (1 - \rho^2)^2} \\
 &\tag{94}
 \end{aligned}$$

If T satisfies (94), then from (39) we have that

$$\begin{aligned}
 \|p - \hat{p}\| &\leq 2 \frac{\|(\Phi^\top \Phi)^{-\frac{1}{2}} \Phi^\top (\Xi - \Psi_+) p\|}{\sigma_{\min}(\Phi) \sigma_{\min}(\mathbb{I} - L \otimes_s L)} \\
 \|p - \hat{p}\| &\leq \frac{\tilde{O}(1) (n_{\hat{x}} + n_{\hat{u}}) \|\hat{K}'\|_+^2}{\sigma_\eta^2 \sqrt{T}} \sigma_w \sqrt{\tau^2 \rho^4 \|\Sigma^{\hat{x}}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|\hat{B}\|^2} \|P_i\|_F \frac{\tau^2 \|\hat{K}\|_+^4 (\|\hat{A}\|^2 + \|\hat{B}\|^2)}{\rho^2 (1 - \rho^2)}. \\
 &\tag{95}
 \end{aligned}$$

For sample complexity analysis, we are usually interested in finding the sufficient samples required to achieve ϵ -optimal critic estimate i.e., $\|p - \hat{p}\| \leq \epsilon$.

Set $\epsilon = \frac{\tilde{O}(1)W(n_{\hat{x}} + n_{\hat{u}}^i)}{\sigma_\eta^2\sqrt{T}}\|P_i\|_F$, which implies $T = \frac{(\tilde{O}(1))^2W^2(n_{\hat{x}} + n_{\hat{u}}^i)^2}{\sigma_\eta^4\epsilon^2}\|P_i\|_F^2 \leq \frac{(\tilde{O}(1))^2W^2(n_{\hat{x}} + n_{\hat{u}}^i)^3}{\sigma_\eta^4\epsilon^2}\|P_i\|_F$

Observe that

$$\tilde{O}(1)(n_{\hat{x}} + n_{\hat{u}}^i)^2 \leq \frac{(\tilde{O}(1))^2W^2(n_{\hat{x}} + n_{\hat{u}}^i)^3}{\sigma_\eta^4\epsilon^2}\|P_i\|^2, \quad (96)$$

but $\frac{(\tilde{O}(1))^2W^2(n_{\hat{x}} + n_{\hat{u}}^i)^3}{\sigma_\eta^4\epsilon^2}\|P_i\|^2$ may not be greater than $\frac{\tilde{O}(1)W^2(n_{\hat{x}} + n_{\hat{u}}^i)^4}{\sigma_\eta^4}$.

Therefore, we can conclude that to achieve $\|q_i - \hat{q}_i\| \leq \epsilon$, we require only

$$T \leq \max \left(\frac{(\tilde{O}(1))^2W^2(n_{\hat{x}} + n_{\hat{u}}^i)^3}{\sigma_\eta^4\epsilon^2}\|P_i\|^2, \frac{\tilde{O}(1)W^2(n_{\hat{x}} + n_{\hat{u}}^i)^4}{\sigma_\eta^4} \right) \text{ samples.} \quad (97)$$

Appendix G. Analysis of the indirect case

Define $n_x^i = n_x|\mathcal{I}_Q^i|$, and $n_u^i = n_u|\mathcal{I}_Q^i|$.

Corollary 1 Consider $\delta \in (0, 1)$. Let the initial global state and the global control (during sample generation) $\forall t$ satisfy $x(0) \sim \mathcal{N}(x_0, \Sigma_0)$, $u(t) = K^{play}x(t) + \eta t$, $\eta(t) \sim \mathcal{N}(\mathbf{0}, \sigma_\eta^2\mathbb{I})$, and $\sigma_\eta \leq \sigma_w$. For each $i \in \mathcal{V}$, let $K_{\mathcal{I}_Q^i}^{play}$, $K_{\mathcal{I}_Q^i}$ stabilize $(A_{\mathcal{I}_Q^i}, B_{\mathcal{I}_Q^i})$. Assume that $A_{\mathcal{I}_Q^i} + B_{\mathcal{I}_Q^i}K_{\mathcal{I}_Q^i}$ and $A_{\mathcal{I}_Q^i} + B_{\mathcal{I}_Q^i}K_{\mathcal{I}_Q^i}^{play}$ are (τ, ρ) -stable. Let $\mathfrak{P}_\infty = \mathcal{L} \left(A_{\mathcal{I}_Q^i} + B_{\mathcal{I}_Q^i}K_{\mathcal{I}_Q^i}, \sigma_w^2\mathbb{I} + \sigma_\eta^2B_{\mathcal{I}_Q^i}B_{\mathcal{I}_Q^i}^\top \right)$ and $\bar{\sigma}_i = \sqrt{\tau^2\rho^4\|\Sigma^x(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2\|B_{\mathcal{I}_Q^i}\|^2}$. Further, $\forall i \in \mathcal{V}$, let T_i denote the minimum number of samples required during learning. Suppose that

$$T_i \geq \tilde{O}(1) \max \left\{ (n_x^i + n_u^i)^2, \frac{(n_x^i)^2(n_x^i + n_u^i)^2\|K_{\mathcal{I}_Q^i}^{play}\|_+^4}{\sigma_\eta^4} \sigma_w^2 \bar{\sigma}_i^2 \frac{\tau_i^4\|K_{\mathcal{I}_Q^i}^j\|_+^8(\|A_{\mathcal{I}_Q^i}\|^2 + \|B_{\mathcal{I}_Q^i}\|^2)^2}{\rho_i^4(1 - \rho_i^2)^2} \right\}.$$

Then, with probability $1 - \delta$,

$$\|\hat{q}_i^{true} - \hat{q}_i^{indirect}\| \leq \sum_{j \in \mathcal{I}_{GD}^i} \frac{\tilde{O}(1)(n_x^j + n_u^j)\|K_{\mathcal{I}_Q^j}^{play}\|_+^2}{\sigma_\eta^2\sqrt{T}} \sigma_w \bar{\sigma}_j \|Q_j^{true}\|_F \frac{\tau_j^2\|K_{\mathcal{I}_Q^j}\|_+^2(\|A_{\mathcal{I}_Q^j}\|^2 + \|B_{\mathcal{I}_Q^j}\|^2)}{\rho_j^2(1 - \rho_j^2)}$$

whenever $T \geq \max \{T_j\}_{j \in \mathcal{I}_{GD}^i}$, where $\tilde{O}(1)$ hides polylog $\left(\frac{T}{\delta}, \frac{1}{\sigma_\eta^4}, \tau, n_x, \|\Sigma_0\|, \|K_{\mathcal{I}_Q^i}^{play}\|, \|\mathfrak{P}_\infty\| \right)$.

Proof Employing a linear architecture, the Q-function for each agent i can be expressed as

$$\begin{aligned} c_i(x_{\mathcal{I}_Q^i}(t), u_{\mathcal{I}_Q^i}(t)) = \\ \lambda + \left[\text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_Q^i}(t) \\ u_{\mathcal{I}_Q^i}(t) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_Q^i}(t) \\ u_{\mathcal{I}_Q^i}(t) \end{bmatrix}^\top \right) - \mathbb{E} \left[\text{svec} \left(\begin{bmatrix} x_{\mathcal{I}_Q^i}(t+1) \\ u_{\mathcal{I}_Q^i}(t+1) \end{bmatrix} \begin{bmatrix} x_{\mathcal{I}_Q^i}(t+1) \\ u_{\mathcal{I}_Q^i}(t+1) \end{bmatrix}^\top \right) \right] \right]^\top \text{svec}(Q_i), \end{aligned} \quad (98)$$

where $\lambda \in \mathbb{R}$ is a free parameter to satisfy the fixed point equation. Let $\lambda = \left\langle Q_i, \begin{bmatrix} \sigma_w^2 \mathbb{I}_{n_x | I_Q^i} & \sigma_w^2 K_{I_Q^i}^\top \\ \sigma_w^2 K_{I_Q^i} & \sigma_w^2 K_{I_Q^i} K_{I_Q^i}^\top \end{bmatrix} \right\rangle$.

For brevity, in the remainder of the proof denote $\phi_t = \text{svec} \left(\begin{bmatrix} x_{I_Q^i}(t) \\ u_{I_Q^i}(t) \end{bmatrix} \begin{bmatrix} x_{I_Q^i}(t) \\ u_{I_Q^i}(t) \end{bmatrix}^\top \right)$,
 $\psi_t = \text{svec} \left(\begin{bmatrix} x_{I_Q^i}(t) \\ K_{I_Q^i} x_{I_Q^i}(t) \end{bmatrix} \begin{bmatrix} x_{I_Q^i}(t) \\ K_{I_Q^i} x_{I_Q^i}(t) \end{bmatrix}^\top \right)$, $f = \text{svec} \left(\begin{bmatrix} \Sigma_{I_Q^i}^x & \Sigma_{I_Q^i}^x K_{I_Q^i}^\top \\ K_{I_Q^i} \Sigma_{I_Q^i}^x & K_{I_Q^i} \Sigma_{I_Q^i}^x K_{I_Q^i}^\top \end{bmatrix} \right)$, and $\xi_t =$
 $\mathbb{E} \left[\text{svec} \left(\begin{bmatrix} x_{I_Q^i}(t+1) \\ u_{I_Q^i}(t+1) \end{bmatrix} \begin{bmatrix} x_{I_Q^i}(t+1) \\ u_{I_Q^i}(t+1) \end{bmatrix}^\top \right) \right]$.

For a single trajectory $\{x_{I_Q^i}(t), u_{I_Q^i}(t), x_{I_Q^i}(t+1)\}_{t=1}^{T_i}$, the bellman equation for agent i can be expressed in matrix form as

$$\mathbf{c} = (\mathbf{\Phi} - \mathbf{\Xi} + \mathbf{F})q_i, \quad (99)$$

$$\text{where } \mathbf{\Phi} = \begin{bmatrix} \phi_1^\top \\ \phi_2^\top \\ \vdots \\ \phi_{T_i}^\top \end{bmatrix}, \mathbf{\Xi} = \begin{bmatrix} \xi_1^\top \\ \xi_2^\top \\ \vdots \\ \xi_{T_i}^\top \end{bmatrix}, \mathbf{c} = \begin{bmatrix} c_i(1) \\ c_i(2) \\ \vdots \\ c_i(T_i) \end{bmatrix}, \mathbf{F} = \begin{bmatrix} f^\top \\ f^\top \\ \vdots \\ f^\top \end{bmatrix}$$

Observe that (99) is analogous to (30). Thus, we can conclude that if T_i satisfies

$$T_i \geq \tilde{O}(1) \max \left\{ (n_x^i + n_u^i)^2, \frac{(n_x^i)^2 (n_x^i + n_u^i)^2 \|K_{I_Q^i}^{\text{play}}\|_+^4}{\sigma_\eta^4} \sigma_w^2 \bar{\sigma}_i^2 \frac{\tau_i^4 \|K_{I_Q^i}\|_+^8 (\|A_{I_Q^i}\|^2 + \|B_{I_Q^i}\|^2)^2}{\rho_i^4 (1 - \rho_i^2)^2} \right\}, \quad (100)$$

where $\bar{\sigma}_i = \sqrt{\tau^2 \rho^4 \|\Sigma^x(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B_{I_Q^i}\|^2}$. Then,

$$\|q_i - \hat{q}_i\| \leq \frac{\tilde{O}(1)(n_x^i + n_u^i) \|K_{I_Q^i}^i\|_+^2}{\sigma_\eta^2 \sqrt{T_i}} \sigma_w \bar{\sigma}_i \|K_{I_Q^i}^i\|_+^2 \|Q_i\|_F \frac{\tau_i^2 \|K_{I_Q^i}^i\|_+^4 (\|A_{I_Q^i}^i\|^2 + \|B_{I_Q^i}^i\|^2)}{\rho_i^2 (1 - \rho_i^2)} \quad (101)$$

Define an operator $M = \text{ssmat}(m, S, n)$ that maps $m \in \mathbb{R}^d$ to the corresponding entries $M_{ij} \forall \{(i, j) \in S \times S | i \leq j\}$. It is straightforward to verify that $\|m\| = \|\text{svec}(\text{ssmat}(m, \cdot, \cdot))\|$. Similar to [Syed and Bai \(2025\)](#), let Y denote the transformation that maps a vector to its non-zero subset and Y' be its inverse transformation. Hence, $Y'(m) = \text{svec}(\text{ssmat}(m, \cdot, \cdot))$, $Y(\text{svec}(\text{ssmat}(m, \cdot, \cdot))) = m$.

Then, the error in estimation of decomposed \hat{Q}_i function can be expressed as

$$\begin{aligned}
 \|q_{\hat{Q}}^{\text{dec},i} - \hat{q}_{\hat{Q}}^{\text{dec},i}\| &= \left\| Y \left(\text{svec} \left(\sum_{j \in \mathcal{I}_{\text{GD}}^i} \text{ssmat}(q_j, \mathcal{I}_Q^j, \hat{n}_x + \hat{n}_u) \right) \right) - Y \left(\text{svec} \left(\sum_{j \in \mathcal{I}_{\text{GD}}^i} \text{ssmat}(\hat{q}_j, \mathcal{I}_Q^j, \hat{n}_x + \hat{n}_u) \right) \right) \right\| \\
 &= \left\| \sum_{j \in \mathcal{I}_{\text{GD}}^i} Y \left(\text{svec} \left(\text{ssmat}(q_j, \mathcal{I}_Q^j, \hat{n}_x + \hat{n}_u) \right) - \text{svec} \left(\text{ssmat}(\hat{q}_j, \mathcal{I}_Q^j, \hat{n}_x + \hat{n}_u) \right) \right) \right\| \\
 &\leq \sum_{j \in \mathcal{I}_{\text{GD}}^i} \|q_j - \hat{q}_j\| \quad (\text{Using triangle inequality, and } \|m\| = \|\text{svec}(\text{ssmat}(m, \cdot, \cdot))\|).
 \end{aligned} \tag{102}$$

Combining (100), (101), and (102), we obtain that whenever the length of trajectory (number of samples) satisfies

$$T \geq \max \{T_j\}_{j \in \mathcal{I}_{\text{GD}}^i} \tag{103}$$

then

$$\begin{aligned}
 \|q_{\hat{Q}}^{\text{dec},i} - \hat{q}_{\hat{Q}}^{\text{dec},i}\| &\leq \\
 \sum_{j \in \mathcal{I}_{\text{GD}}^i} \frac{\tilde{O}(1)(n_x^j + n_u^j) \|K_Q^{j'}\|_+^2}{\sigma_\eta^2 \sqrt{T_j}} \sigma_w \sqrt{\tau_j^2 \rho_j^4 \|\Sigma_Q^{x,j}(0)\| + \|\mathfrak{P}_\infty\| + \sigma_w^2 + \sigma_\eta^2 \|B_Q^j\|^2 \|K_Q^j\|_+^2 \|Q_j\|_F} \frac{\tau_j^2 \|K_Q^j\|_+^2 (\|A_Q^j\|^2 + \rho_j^2)}{\rho_j^2 (1 - \rho_j^2)}
 \end{aligned} \tag{104}$$

Let $g_i = |\mathcal{I}_{\text{GD}}^i|$. Then, define $w_1, w_2, \dots, w_{g_i} \in [0, 1]$ such that $\sum_k^{g_i} w_k = 1$. Then, from (??), we conclude that to achieve $\|q_{\hat{Q}}^{\text{dec},i} - \hat{q}_{\hat{Q}}^{\text{dec},i}\| \leq \epsilon$, we require only

$$T \leq \max_{j \in \mathcal{I}_{\text{GD}}^i} \left(\max \left(\frac{(\tilde{O}(1))^2 W_j^2 (n_x^j + n_u^j)^3}{\sigma_\eta^4 w_j^2 \epsilon^2} \|Q_j\|^2, \frac{\tilde{O}(1) W_j^2 (n_x^j + n_u^j)^4}{\sigma_\eta^4} \right) \right) \text{ samples.} \tag{105}$$

Therefore, from (97), (105), we can conclude that the decomposition of the Q-function is sample efficient provided that $\max_{j \in \mathcal{I}_{\text{GD}}^i} (n_x^j + n_u^j) < (n_{\hat{x}} + n_{\hat{u}})$ and the worst case sample complexity of the decomposition is equal to the undecomposed case.

Appendix H. Bound on spectral norm of a block matrix

<https://math.stackexchange.com/questions/2006773/spectral-norm-of-concatenation->

Define $M = \begin{bmatrix} A^\top A & A^\top B \\ B^\top A & B^\top B \end{bmatrix}$. Then, observe that $\left\| \begin{bmatrix} \hat{A} & \hat{B} \end{bmatrix} \right\| = \sqrt{\lambda_{\max}(M)}$. Since M is symmetric, by Courant-Fischer theorem, we have that

$$\lambda_{\max}(M) = \max_{x: \|x\|=1} \frac{x^\top M x}{x^\top x}.$$

Let $x = [u^\top \ v^\top]$, where u, v are eigenvectors of $A^\top A, B^\top B$ respectively. **Note that** $\|u\|^2 + \|v\|^2 = 1$, **so you should be able to tighten the bound.** Then,

$$\begin{aligned}
 x^\top M x &= u^\top A^\top A u + v^\top B^\top B v + u^\top A^\top B v + v^\top B^\top A u \\
 &\leq u^\top A^\top A u + 2\|Au\| \|Bv\| + v^\top B^\top B v \text{ (By Cauchy-Schwarz inequality)} \\
 &\leq 2\|Au\|^2 + 2\|Bv\|^2 \text{ (Since, } 2\|Au\| \|Bv\| \leq \|Au\|^2 + \|Bv\|^2 \text{.)} \\
 &\leq 2\|A\|^2\|u\|^2 + 2\|B\|^2\|v\|^2 \\
 &\leq 2(\|A\|^2 + \|B\|^2)(\|u\|^2 + \|v\|^2) \text{ (}\because \|A\|^2 + \|B\|^2 \geq \{\|A\|^2, \|B\|^2\} \text{.)} \\
 x^\top M x &= \|A\|^2 + \|B\|^2 \text{ (}\because \|u\|^2 + \|v\|^2 = 1 \text{.)} \\
 \Rightarrow \lambda_{\max}(M) &= \|A\|^2 + \|B\|^2 \\
 \Rightarrow \left\| \begin{bmatrix} \hat{A} & \hat{B} \end{bmatrix} \right\| &\leq \sqrt{(\|A\|^2 + \|B\|^2)}. \tag{106}
 \end{aligned}$$

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