# API Documentation

# API Documentation

# April 28, 2014

# Contents

Co	ontents	1
1	Package meet 1.1 Modules	<b>3</b>
2	Module meetcSPoC 2.1 Functions	
3	Module meetdot_new 3.1 Functions	
4	Module meetinterp 4.1 Functions	
5	Module meet.basic 5.1 Functions	
6	Module meet.cSPoC 6.1 Functions	
7	Module meet.eeg_viewer           7.1 Variables            7.2 Class plotEEG            7.2.1 Methods	22 22 23 23
8	Module meet.elm           8.1 Functions            8.2 Variables            8.3 Class ClassELM            8.3.1 Methods	
9	Module meet.iir	<b>32</b>

CONTENTS

9	.2 V	Variables			 	 	 	 			 						33
10 N 1	<b>Modu</b> 0.1 F 0.2 V	le meet unctions ariables	.spat 	filt 	 	 	 	 		 	 			 	 		34 35 38
11 N 1 1	<b>Modu</b> 1.1 F 1.2 V	le meet unctions ariables	.spho	e <b>re</b> 	 	 	 	 		 	 	 	 	 			<b>39</b> 40 48
<b>12</b> N 1	<b>Modu</b> 2.1 F 2.2 V	le meet unctions ariables	.tf 		 	 	 	 		 	 			 			<b>49</b> 50 51
Inde	ex																<b>52</b>

## 1 Package meet

citation.

This is the Modular EEg Toolkit (MEET) for Python 2.

```
***Disclosure:
                                                              ***
***----
                                                              ***
***This software comes as it is - there might be errors at runtime
                                                              ***
***and results might be wrong although the code was tested and did
***work as expected. Since resuluts might be wrong you must
***absolutely not use this software for a medical purpuse - decisions***
***converning diagnosis, treatment or prophylaxis of any medical
***condition mustn't rely on this software.
                                                              ***
****************************
Only Python 2 is supported at the moment, however modifications should
be easy to do.
Dependencies:
_____
-Python 2
-Numpy
-Scipy
-Matplotlib
Installation:
Using the usual procedure:
python setup.py build
python setup.py install (be sure that the python executable is Python 2)
Uninstallation:
if you use pip you can uninstall doing:
pip uninstall meet
Version Compatibility:
I try to avoid incompatibilities when updating functions,
this however cannot be totaly avoided from time to time. However
functions are thoroughly tested.
Citation:
```

If you use this software for scientific publications please give proper

G. Waterstraat, 2014. Modular EEg toolkit (MEET) for Python.

In the moment please cite as (or similar)

Modules Package meet

https://github.com/neurophysics/meet. Retrieved on <date>

There is a properly citable publication on the way as well which may be cited additionally.

#### License:

\_\_\_\_\_

Copyright (c) 2014 Gunnar Waterstraat

Permission is hereby granted, free of charge, to any person obtaining a copy of this software and associated documentation files (the "Software"), to deal in the Software without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Software, and to permit persons to whom the Software is furnished to do so, subject to the following conditions:

The above copyright notice and this permission notice shall be included in all copies or substantial portions of the Software.

THE SOFTWARE IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE SOFTWARE OR THE USE OR OTHER DEALINGS IN THE SOFTWARE.

### Author & Contact

\_\_\_\_\_

Written by Gunnar Waterstraat
email: gunnar[dot]waterstraat[at]charite.de

## 1.1 Modules

- \_cSPoC: Implements canonical Source Power Correlation analysis (cSPoC) (Section 2, p. 6)
- \_dot\_new: A drop in replacement for numpy.dot (Section 3, p. 10)
- \_interp: hidden functions for interpolating EEG (Section 4, p. 11)
- basic: Basic functions for reading binaries and EEG manipulation (Section 5, p. 12)
- **cSPoC**: Implements canonical Source Power Correlation analysis (cSPoC) (Section 6, p. 18)
- eeg\_viewer: Simple interactive EEG viewer (Section 7, p. 22)
- elm: Extreme Learning Machine Classification (Section 8, p. 24)
- iir: IIR Filtering (Section 9, p. 32)

Modules Package meet

- spatfilt: Spatial Filters (Section 10, p. 34)
- sphere: Spherical spline interpolation and CSD (Section 11, p. 39)
- tf: S transform (time-frequency transformation) (Section 12, p. 49)

# 2 Module meet.\_cSPoC

Implements canonical Source Power Correlation analysis (cSPoC)

### Reference:

-----

Dahne, S., et al., Finding brain oscillations with power dependencies in neuroimaging data, NeuroImage (2014), http://dx.doi.org/10.1016/j.neuroimage.2014.03.075

Hidden submodule of the Modular EEg Toolkit - MEET for Python. (Imported by spatfilt module)

This module implements some spatial filters such as CSP, CCA, CCAvReg, bCSTP and QCA.

### 2.1 Functions

## $\mathbf{pattern\_from\_filter}(\mathit{filter},\,X)$

Get a an activation pattern from the filter matrix and the input data  ${\tt X}.$ 

### Input:

----

filter - is a p (x k) numpy array, where p is the dimensionality of the data and k is the number of filters (if k == 1, the array may be 1-dimensional)

X - is an p x N (x tr) numpy array, where p is the dimensionality of the data, N is the number of datapoints (per trial, and tr is the number of trials)

If X is 3d, the patterns are computed by collapsing the last 2 axes

### Output:

-----

Functions Module meet.\_cSPoC

```
\mathbf{cSPoC}(X, Y, opt=\texttt{'max'}, num=1, log=\mathsf{True}, bestof=15)
canonical Soure Power Correlation analysis (cSPoC)
For the datasets X and Y, find a pair of linear filters wx and wy, such
that the correlation of the amplitude envelopes wx.T.dot(X) and
wy.T.dot(Y) is maximized.
Reference:
Dahne, S., et al., Finding brain oscillations with power dependencies
in neuroimaging data, NeuroImage (2014),
http://dx.doi.org/10.1016/j.neuroimage.2014.03.075
Notes:
_____
Datasets X and Y can be either 2d numpy arrays of shape
(channels x datapoints) or 3d array of shape
(channels x datapoints x trials). For 3d arrays the average envelope
in each trial is calculated. If log == True, then the log transform is
taken before the average inside the trial
The filters are in the columns of the filter matrices Wx and Wy,
for 2d input the data can be filtered as:
np.dot(Wx.T, X)
for 3d input:
np.tensordot(Wx, X, axes=(0,0))
Input:
____
-- X numpy array - the first dataset of shape px x N (x tr), where px
                   is the number of sensors, N the number of data-
                   points, tr the number of trials
-- Y is the second dataset of shape py x N (x tr)
-- opt {'max', 'min'} - determines whether the correlation coefficient
                        should be maximized - seeks for positive
                        correlations ('max', default);
                        or minimized - seeks for anti-correlations
                         ('min')
-- num int > 0 - determine the number of filter-pairs that will be
                 derived. This depends also on the ranks of X and Y,
                 if X and Y are 2d the number of filter pairs will be:
                 min([num, rank(X), rank(Y)]). If X and/or Y are 3d the
                 array is flattened into a 2d array before calculating
                 the rank
-- log {True, False} - compute the correlation between the log-
                       transformed envelopes, if datasets come in
                       epochs, then the log is taken before averaging
                       inside the epochs, defaults to True
-- bestof int > 0 - the number of resta\overline{r}ts for the optimization of the
                    individual filter pairs. The best filter over all
                    these restarts with random initializations is
```

chosen, defaults to 15.

. .

Functions Module meet.\_cSPoC

```
\mathbf{cSPoAC}(X, tau=1, opt='max', num=1, log=True, bestof=15)
canonical Soure Power Auto-Correlation analysis (cSPoAC)
For the dataset X, find a linear filters wx, such
that the correlation of the amplitude envelopes wx.T.dot(X[:,:-tau])
and wx.T.dot(X[:,tau:]) is maximized, i.e. it seeks a spatial filter
to maximize the auto-correlation of amplitude envelopes for a shift
of tau.
The solution is inspired by and derived by the original cSPoC-Analysis
Reference:
Dahne, S., et al., Finding brain oscillations with power dependencies
in neuroimaging data, NeuroImage (2014),
http://dx.doi.org/10.1016/j.neuroimage.2014.03.075
Notes:
Dataset X can be either a 2d numpy array of shape
(channels x datapoints) or 3d a array of shape
(channels x datapoints x trials). For 2d array tau denotes a lag in
the time domain. For a 3d array the average envelope in each trial is
calculated and tau denotes a trial-wise lag.
If log == True, then the log transform is taken before the average
inside the trial
The filters are in the columns of the filter matrices Wx and Wy,
for 2d input the data can be filtered as:
np.dot(Wx.T, X)
for 3d input:
np.tensordot(Wx, X, axes=(0,0))
Input:
-- X numpy array - the dataset of shape px x N (x tr), where px is the
                   number of sensors, N the number of data-points, tr
                   the number of trials
-- tau int - the lag to calculate the autocorrelation , if X.ndim==2,
             this is a time-wise lag, if X.ndim==3, this is a trial-
             wise lag.
-- opt {'max', 'min'} - determines whether the correlation coefficient
                        should be maximized - seeks for positive
                        correlations ('max', default);
                        or minimized - seeks for anti-correlations
                        ('min')
-- num int > 0 - determine the number of filters that will be derived.
                 This depends also on the rank of X, if X is 2d, the
                 number of filter pairs 8will be: min([num, rank(X)]).
                 If X is 3d, the array is flattened into a 2d array
                 before calculating the rank
-- log {True, False} - compute the correlation between the log-
```

transformed envelopes, if datasets come in

Variables Module meet.\_cSPoC

Name	Description
_package_	Value: 'meet'

Variables Module meet.\_dot\_new

# 3 Module meet.\_dot\_new

A drop in replacement for numpy.dot

Avoid temporary copies of non C-contiguous arrays

The code is available here: http://pastebin.com/raw.php?i=M8TfbURi In future this will be available in numpy directly: https://github.com/numpy/numpy/pull/2730

## 3.1 Functions

dot(A, B, out=None)
A drop in replaement for numpy.dot Computes A.B optimized using fblas call
$test\_dot()$
$test_to_fix()$
1d array, complex and 3d

Name	Description
package	Value: 'meet'

# 4 Module meet.\_interp

hidden functions for interpolating EEG

Hidden submodule of the Modular EGg Toolkit - MEET for Python.

Author:

-----

Gunnar Waterstraat
gunnar[dot]waterstraat[at]charite.de

## 4.1 Functions

akima(x, y)	

 $\mathbf{mchi}(x, y)$ 

Monotone cubic hermite interpolation

Name	Description
package	Value: 'meet'

# 5 Module meet.basic

Basic functions for reading binaries and  $\ensuremath{\mathsf{EEG}}$  manipulation

Submodule of the Modular EEg Toolkit - MEET for Python.

### Author:

\_\_\_\_\_

Gunnar Waterstraat
gunnar[dot] waterstraat[at] charite.de

## 5.1 Functions

```
readBinary(fname, num_channels, channels='all', readnum_dp='all',
data_type='float4', buffermem=512)
Read EEG from a binary file and output as numpy array.
The binary of a signal with k channels and n datapoints must be
of the type:
       t0 t1 ... tn-1
         k ... (n-1)*k
          k+1 ... (n-1)*k+1
ch_1 | 1
                  . . . . . .
... | ... ...
ch_{k-1} k-1 2*k-1 ... n*k-1
The endianess of the runtime system is used.
Input:
-- fname - (str) - input file name
-- num_channels - int - total number of channels in the file
-- channels - numpy array OR 'all' - iterable of channels to read
             (starting with 0) if 'all', all channels are read
-- readnum_dp - int OR 'all' - number of datapints to read
-- data_type - str - any of 'int2', 'int4', 'int8', 'float4',
                    'float8', 'float16' where the digit determins
                    the number of bytes (= 8 bits) for each element
-- buffermem - float - number of buffer to us in MegaBytes
Output:
-- data - numpy array - data shaped k x n where k is number of
                       channels and n is number of datapoints
Example:
>>> readBinary(_path.join(_path.join(_packdir, 'test_data'),
                                                                        'sample.dat'), 2, data_ty
array([[0, 2, 4, 6, 8],
       [1, 3, 5, 7, 9]])
```

```
interpolateEEG(data, markers, win, interpolate_type='mchs')
Interpolates segemnets in the data
Input:
-- data - one or two dimensional array
         1st dimension: channels (can be ommitted if single channel)
         2nd dimension: datapoints
-- markers - marker positions arranged in 1d array
-- win - iterable of len 2 - determining the window in datapoints to
        be interpolated (win[0] is in, win[1] is out of the window)
-- interpolate_type: ['linear', 'mchs', 'akima'] - linear or
                   Monotone Cubic Hermite Spline
  or Akima interpolation
Output:
interpolated dataset
Examples:
>>> data = _np.arange(20, dtype=float).reshape(2,-1)
>>> interpolateEEG(data, [5], [-1,2], 'linear')
array([[ 0., 1.,
                   2., 3., 4., 5., 6.,
                                               7., 8.,
                                                          9.],
      [ 10., 11., 12., 13., 14., 15., 16., 17., 18., 19.]])
>>> interpolateEEG(data, [5], [-1,2], 'mchs')
                                               7., 8.,
                                                          9.],
array([[ 0., 1., 2.,
                        3., 4., 5., 6.,
      [ 10., 11., 12., 13., 14., 15., 16., 17., 18., 19.]])
>>> interpolateEEG(data, [5], [-1,2], 'akima')
                          2. , 3. , 3.625, 5. ,
array([[ 0.
              , 1. ,
                        9.
         7.
                8.
                              ],
                        12.
                              , 13. , 13.625, 15. , 16.375,
      [ 10.
              , 11.
        17.
                18.
                         19.
                              ]])
```

```
epochEEG(data, marker, win)
Arange the dataset into trials (=epochs) according to the marker and
window.
markers and the window borders are sorted in ascending order.
Input:
-- data - numpy array - 1st dim channels (can be ommitted if single
                                         channel)
                       2nd dim datapoints
-- marker - iterable - the marker
-- win - iterable of len 2 - determing the start and end of epchos
        in dp (win[0] is in, win[1] is out of the window)
Output:
-- epochs - numpy array - dimension one more then data input
                       - 1st dim: channel (might be ommited - see
                                           above)
                       - 2nd dim: epoch length = win[1] - win[0]
                       - 3rd dim: number of epochs
Example:
-----
>>> data = _np.arange(20, dtype=float).reshape(2,-1)
>>> epochEEG(data, [3,5,7], [-2,2])
array([[[ 1.,
               3., 5.],
        [ 2.,
                4., 6.],
                     7.],
        [ 3.,
               5.,
        [ 4.,
               6.,
                     8.]],
<BLANKLINE>
      [[ 11., 13., 15.],
       [ 12., 14., 16.],
        [ 13., 15., 17.],
        [ 14., 16., 18.]])
```

```
calculateRMS(data, axis=-1)
Calculate rms value of the input data along the indicated axis
Input:
-- data - numpy array - input data
-- axis - int - axis along which the rms is calculated; if None, the
               flattened array is used
Output:
-----
-- rms value along the indicated axis
Example:
>>> data = _np.arange(20, dtype=float).reshape(2,-1)
>>> calculateRMS(data, None)
11.113055385446435
>>> calculateRMS(data, 0)
array([ 7.07106781, 7.81024968, 8.60232527, 9.43398113,
       10.29563014, 11.18033989, 12.08304597, 13.
       13.92838828, 14.86606875])
>>> calculateRMS(data, 1)
array([ 5.33853913, 14.7817455])
```

```
getMarker(marker, width=50, mindist=100)
Gets position of markers from the trigger channel
GetMarkerPosFromData(marker)
input:
-- marker - one-dimensional array with trigger channel - each
            impulse or zero crossing is treated a marker
--width - int - calculates the local mean in window of size width
               - defaults to 50
--mindist - int - minimal distance between triggers in dp
                 - defaults to 100
output:
-- marker - one-dimensional array containing trigger positions
Example:
_____
>>> x = np.ones(1000)
>>> x[200:400] = -1
>>> x[600:800] = -1
>>> getMarker(x)
array([200, 400, 600, 800])
```

Variables Module meet.basic

Name	Description
package	Value: 'meet'

# 6 Module meet.cSPoC

Implements canonical Source Power Correlation analysis (cSPoC)

### Reference:

\_\_\_\_\_

Dahne, S., et al., Finding brain oscillations with power dependencies in neuroimaging data, NeuroImage (2014), http://dx.doi.org/10.1016/j.neuroimage.2014.03.075

Functions Module meet.cSPoC

### 6.1 Functions

```
\mathbf{cSPoC}(X, Y, opt=\texttt{'max'}, num=1, log=\mathsf{True}, bestof=15)
canonical Soure Power Correlation analysis (cSPoC)
For the datasets X and Y, find a pair of linear filters wx and wy, such
that the correlation of the amplitude envelopes wx.T.dot(X) and
wy.T.dot(Y) is maximized.
Reference:
_____
Dahne, S., et al., Finding brain oscillations with power dependencies
in neuroimaging data, NeuroImage (2014),
http://dx.doi.org/10.1016/j.neuroimage.2014.03.075
Notes:
Datasets X and Y can be either 2d numpy arrays of shape
(channels x datapoints) or 3d array of shape
(channels x datapoints x trials). For 3d arrays the average envelope
in each trial is calculated. If log == True, then the log transform is
taken before the average inside the trial
The filters are in the columns of the filter matrices Wx and Wy,
for 2d input the data can be filtered as:
np.dot(Wx.T, X)
for 3d input:
np.tensordot(Wx, X, axes=(0,0))
Input:
-- X numpy array - the first dataset of shape px x N (x tr), where px
                   is the number of sensors, N the number of data-
                   points, tr the number of trials
-- Y is the second dataset of shape py x N (x tr)
-- opt {'max', 'min'} - determines whether the correlation coefficient
                        should be maximized - seeks for positive
                        correlations ('max', default);
                        or minimized - seeks for anti-correlations
                         ('min')
-- num int > 0 - determine the number of filter-pairs that will be
                 derived. This depends also on the ranks of X and Y,
                 if X and Y are 2d the number of filter pairs will be:
                 min([num, rank(X), rank(Y)]). If X and/or Y are 3d the
                 array is flattened into a 2d array before calculating
                 the rank
-- log \{ \mbox{True, False} \} - compute the correlation between the log-
                       transformed envelopes, if datasets come in
                       epochs, then the dog is taken before averaging
                       inside the epochs, defaults to True
-- bestof int > 0 - the number of restarts for the optimization of the
                    individual filter pairs. The best filter over all
```

these restarts with random initializations is

Variables Module meet.cSPoC

### $pattern\_from\_filter(filter, X)$

Get a an activation pattern from the filter matrix and the input data  ${\tt X}.$ 

### Input:

-----

filter - is a p  $(x \ k)$  numpy array, where p is the dimensionality of the data and k is the number of filters (if k == 1, the array may be 1-dimensional)

X - is an p x N (x tr) numpy array, where p is the dimensionality of the data, N is the number of datapoints (per trial, and tr is the number of trials)

If X is 3d, the patterns are computed by collapsing the last 2 axes

### Output:

-----

Name	Description
package	Value: 'meet'

# 7 Module meet.eeg\_viewer

Simple interactive EEG viewer

Submodule of the Modular EEg Toolkit - MEET for Python.

Author:

\_\_\_\_\_

Gunnar Waterstraat
gunnar[dot]waterstraat[at]charite.de

Name	Description
package	Value: 'meet'

## 7.2 Class plotEEG

### 7.2.1 Methods

```
\_init\_(self, signals, ylabels, t, t_res=30, title=False)
Function to Plot EEG-Signals in of several channels
Def: PlotEEG(signals, ylabels, t, t_res, title = False)
Interaction:
PageUp -> Go backward a big step
PageDown -> Go forward a big step
Up -> Go backward a small step
Down -> go forward a small step
i -> Zoom in (show smaller temporal window)
o -> Zoom out (show larger temporal window)
+ -> increase gain
- -> decrease gain
Pos1 -> Go to start
End \rightarrow Go to end
LeftMouseClick -> saves the x coordinate in self.clicks
Input:
    -signals: 2d array of input data
    -ylabels: list of channel names in same order as in
              'signals' (unit is presumed to be mikro V)
    -t: array of time values in s
    -t_res: mm per second (standard: 30 mm / s)
    -title: title string
Output:
    -EEG_viewer class: plot with EEG.show()
     clicks are saved in self.clicks
```

```
change_gain(self, new_offset)
```

```
\mathbf{change\_t}(self,\ new\_t0,\ new\_t\_show)
```

```
\mathbf{show}(\mathit{self})
```

## 8 Module meet.elm

Extreme Learning Machine Classification

Submodule of the Modular EEg Toolkit - MEET for Python.

This module implements regularized Extreme Learning Machine Classification and Weighted Extreme Learning Machine Classification.

Classification is implemented in the ClassELM class

For faster execution of dot product the module dot\_new is imported since it avoids the need of temporary copy and calls fblas directly. The code is available here: http://pastebin.com/raw.php?i=M8TfbURi In future this will be available in numpy directly: https://github.com/numpy/numpy/pull/2730

- 1. Extreme Learning Machine for Regression and Multiclass Classification Guang-Bin Huang, Hongming Zhou, Xiaojian Diang, Rui Zhang IEEE Transactions of Systems, Man and Cybernetics Pat B: Cybernetics, Vol. 42, No. 2. April 2012
- 2. Weighted extreme learning machine for imbalance learning. Weiwei Zong, Guang-Bin Huang, Yiqiang Chen Neurocomputing 101 (2013) 229-242

Author & Contact

Written by Gunnar Waterstraat

email: gunnar[dot]waterstraat[at]charite.de

Functions Module meet.elm

## 8.1 Functions

# accuracy(conf\_matrix) Measure of the performance of the classifier. The Accuracy is the proportion of correctly classified items in relation to the total number of items. You should be aware that this is very sensitive to imbalanced data (data with very unequal sizes of each class): Imagine a sample with 99% of the items belonging to class 0 and 1% of items belonging to class 1. A classifier might have an accuracy of 99% by just assigning all items to class 0. However, the sensitivity for class 1 is 0% in that case. It depends on your needs if this is acceptable or not. Input: conf\_matrix - shape ny x ny, where ny is the number of classes the rows belong to the actual, the columns to the predicted class: item ij is hence predicted as class j, while it would have belonged to class i Output: float - the accuracy

### $G_{-}mean(conf_{-}matrix)$

The G-mean is the geometric mean of the per-class-sensitivities. It is much more stable to imbalance of the dataset than the global accuray. However it depends on your needs, which measure of performance of the classifier to use.

### Input:

\_\_\_\_

## Output:

\_\_\_\_\_

the geometric mean of per-class sensitivities

Functions Module meet.elm

### Matthews(conf\_matrix)

The Matthews correlation coefficient is used in machine learning as a measure of the quality of binary (two-class) classifications. It takes into account true and false positives and negatives and is generally regarded as a balanced measure which can be used even if the classes are of very different sizes. The MCC is in essence a correlation coefficient between the observed and predicted binary classifications; it returns a value between -1 and +1. A coefficient of +1 represents a perfect prediction, O no better than random prediction and -1 indicates total disagreement between prediction and observation.

Source: Wikipedia (2013-09-25)

## Input:

\_\_\_\_\_

conf\_matrix - shape 2 x 2, where 2 is the number of classes
 the rows belong to the actual, the columns to the
 predicted class: item ij is hence predicted as class j,
 while it would have belonged to class i
 AN ERROR IS THROWN IF THE SHAPE OF THE MATRIX IS NOT
 CORRECT

### Output:

\_\_\_\_

float - the the Matthews Correlation Coefficient

### $PPV(conf\_matrix)$

Calculate the Positive Predictive Value

### Input:

-----

conf\_matrix - shape 2 x 2, where 2 is the number of classes
 the rows belong to the actual, the columns to the
 predicted class: item ij is hence predicted as class j,
 while it would have belonged to class i
 AN ERROR IS THROWN IF THE SHAPE OF THE MATRIX IS NOT
 CORRECT

### Output:

\_\_\_\_\_

float - the PPV

```
Ssk_cv(data, labels, folds=3)

Cut data into folds with method:
shuffled, stratified, k-folds cross-validation

Input:
-----
data - numpy array - shape n x p, with n items anf p features

Output:
-----
returns a list, with each list-element including the indices of one fold
```

### 8.2 Variables

Name	Description
package	Value: 'meet'

### 8.3 Class ClassELM

Class for Extreme Learning Machine Classification

Input:

L - (int) - dimensionality of the feature space (defaults to 1000) change\_alg - (int) - number of samples to change from implementation

## 8.3.1 Methods

 $\_$ init $\_$ (self, L=1000, kernel='sigmoid')

```
cv(self, data, labels, method='ssk_cv', C_array=None, folds=3,
precision_func='accuracy', scale=True, weights=True, mem_size=512, verbose=True)
Perform Cross-Validation of Extreme Learning Machine parameter C
Input:
data - numpy array - shape (n x p) with n being sample number
       and p being number of features
labels - numpy array - shape (n) with the class labels
         0,1,\ldots,ny-2,ny-1, where ny is the number of classes
method - string - cross-validation method
                - 'ssk_cv' - shuffled stratified k-folds
                  cross-validation
C_{-}array - numpy array - default is None - the C's which are
                        cross-validated
                      - if None from 2**(-25), 2**(-24), ...,
                                      2**(24), 2**(25)
folds - integer - default 3 - number of folds
precision_func - string or function - standard is 'accuray' -
                 Measure of performance
               - as string implemented: 'accuracy' -
                                           proportion of
                                           correctly classified
                                           to total number of
                                           samples
                                         'G_mean' - geometric
                                           mean of per-class
                                           accuracies
                                         'Matthews' - Matthews
                                           Correlation
                                           Coefficient - Only
                                           for binary
                                           classification
                                         'PPV' - Positive
                                           Predictive Value -
                                           Only for binary
                                           classification
               - if function: with confusion matrix as single
                 input and float (0,1) as single output
scale - bool (True | False) - whether data should be scaled to
                              range (-1,1)
weights - can be: - bool (True | False): - standard is True
                                            if True, data is
                                            re-weighted to a
                                            class ratio of 1.0
                                            if False, data is not
                                            re-weighted
                  - float in half-open interval [0,1)
                        - data is re-weighted such that the
                          minority / majority ratio is this
                          float
                        - minority clas@es are the ones having
                          less members than on average, majority
                          classes have more than average
                        - Zong et al. proposed to use the golden
                          ratio (approx. 0.618 -
```

```
train(self, data, labels, C, scale=True, weights=True, mem_size=512)
Train the ELM Classifier
Input:
data - (numpy array) - shape n x p
                       n - number of observations
                       p - number of dimensions
       if data.ndim > 2, the array is reshaped as (n,-1)
labels - array with integer labels
C - regularization parameter
scale - bool (True | False) - standard is True
                            - switch, if the features of the
                              dataset should be scaled
                              to the interval (-1,1)
weights - can be: - bool (True | False): - standard is True
                                           if True, data is re
                                           weighted to a class
                                           ratio of 1.0 if
                                           False, data is not
                                           re-weighted
                  - float in half-open interval [0,1)
                        - data is re-weighted such that the
                          minority / majority ratio is this
                          float
                        - minority classes are the ones having
                          less members than on average, majority
                          classes have more than average
                        - Zong et al. proposed to use the golden
                        ratio (approx. 0.618 -
                        scipy.Constants.golden) as a good value
                  - numpy array with weights for each sorted
                  unique class in labels, each class weight is
                  expected to be in half-open interval [0,1)
mem_size - number - memory size of temporary array in Mb -
                    defaulte to 512
Output:
No user ouput (Weights are generated and stored in the Class as
self._beta) self.istrained is set to True
```

# 9 Module meet.iir

```
IIR Filtering
Submodule of the Modular EEg Toolkit - MEET for Python.
So far only butterworth filtering is implemented
Author:
-----
Gunnar Waterstraat
gunnar[dot]waterstraat[at]charite.de
```

Variables Module meet.iir

## 9.1 Functions

```
butterworth(data, fp, fs, s_rate, gpass=3, gstop=8, axis=-1, zero_phase=True,
return_param=False)
Apply a butterworth filter to the data.
fp is the passband frequency in Hz
fs is the stopband frequency in Hz
Example of Notations:
For fs = 10, fp = 15 a high-pass filter is applied with the
  transition band between 10-15 Hz
For fs = 15, fp = 10 a low-pass filter is applied with the
  transition band between 10-15 Hz
For fs = [10, 40], fp = [20,30] a bandpass-filter with the passband
  20-30 Hz and transitions between 10-20 Hz and 30-40 Hz is applied
For fs = [20, 30], fp = [10,40] a bandstop-filter with the stopband
   20-30 Hz and transitions between 10-20 Hz and 30-40 Hz is applied
Input:
_____
-- data - numpy array
-- fp - float - pass-band frequencies
-- fs - float - stop-band frequencies
-- s_rate - float - the sampling rate in Hz
-- gpass - float - maximal attenuation in the passband (in dB)
-- gstop - float - minimal attenuation in the passband (in dB)
-- axis - int -along which axis the filter is applied
-- zero_phase - bool - if zero phase filter is applied by filtering
                in both directions
-- return_param - bool - if the order, b, and a shoud be returned
Output:
-- data - numpy array - the filtered data array
if return_param:
   -- data
   -- ord - int - filter order (this must be doubled for the
                  zero_phase implementation)
   -- (b, a) - Numerator ('b') and denominator ('a') polynomials of
               the IIR filter.
```

Name	Description
package	Value: 'meet'

# 10 Module meet.spatfilt

Spatial Filters

Submodule of the Modular EEg Toolkit - MEET for Python.

This module implements some spatial filters such as CSP, CCA, CCAvReg, bCSTP and QCA.

Author & Contact

-----

Written by Gunnar Waterstraat

email: gunnar[dot]waterstraat[at]charite.de

Functions Module meet.spatfilt

### 10.1 Functions

```
CSP(data1, data2, center=True)
Common Spatial Pattern (CSP)
This takes the multivariate data in two conditions and finds the
spatial filters which minimize the variance in condition 2, while
simultaneously maximizing the variance in condition one.
The algorithm uses Singular Value Decomposition since this is more
stable than the Eigenvalue Decomposition of the Covariance Matrices
The filters are scaled such, that Var(cond1) + Var(cond2) = 1. The
eigenvalues give the variance in condition 1.
The filters are in the columns of the filter matrix. Patterns can be
obtained by inverting the filter matrix and are located in the rows
of the inverted filter matrix.
filter, eigval = CSP(data1, data2)
filtered_data = filter.T.dot(data1)
Input:
-- data1 - 2d array - data in condition 1 (variables in rows,
     observations in columns)
-- data2 - 2d array - data in condition 2 (variables in rows,
     observations in columns)
  The number of variables in data1 and data2 must be equal
-- center - bool - if data should be centered, defaults to True
Output:
-- filter - where the individual filters are in the columns of the
     matrix (in order of decreasing eigenvalues)
-- eigvals - eigenvalues in decreasing order
```

### $\mathbf{CCA\_data}(X, Y)$

Cannonical Correlation Analysis - by a combination of QR decomposition and Singular Value Decomposition  $\,$ 

The filters are scaled to give unit variance in the components and are given in the order of decreasing canonical correlations.

Patterns can be obtained by inverting the filter matrices.

### Inputs:

\_\_\_\_\_

- ${\tt X}$  shaped p1 x  ${\tt N}$  variables in rows, obervations in columns
- Y shaped p2 x N variables in rows, obervations in columns

### Outputs:

\_\_\_\_\_

- a filters for X (shape p1 x d), where d is min(rank(X), rank(Y)), each filter is in one column
- b filters for Y (shape  $p2 \times d$ ), where d is min(rank(X), rank(Y)), each filter is in one column
- s canonical correlations in non-increasing order, each corresponding to the respective colum in a and b

# $\mathbf{CCAvReg}(trials)$ Canonical Correlation Average Regression Calculate the CCA between trials and their average across trials The filters are scaled to give unit variance in the components and are given in the order of decreasing canonical correlations. Patterns can be obtained by inverting the filter matrices. notably, all single trials can be filtered at once by: \_np.tensordot(a, trials, axes=(0,0)) the filtered average can be obtained as: \_np.dot(b.T, trials.mean(-1)) Input: -- trials - 3d numpy array - 1st dim: channels - 2nd dim: epoch length - 3rd dim: number of epochs Output: -- a - 2d numpy array (channel x channel) - spatial filters for single trials, each filter is in one column -- b - 2d numpy array (channel x channel) - spatial filters for

average, each filter is in one column

-- s - the canonical correlations between single trials and averages

```
bCSTP(trials1, trials2, num_iter=30, s_keep=2, t_keep=2, verbose=True)
bilinear Common Spatial-Temporal Patterns
In each iteration the number of kept patterns is reduced by one,
in the last 5 iterations the finally desired number of patterns is
The minimal number of iterations must therefor be > 10
Filter matrices won't be square if the data was rank deficient,
patterns can then be obtained by using the pseudo-inverse
(numpy.linalg.pinv)
Input:
-- trials1 - 3d numpy array - 1st dim: channels
                            - 2nd dim: epoch length
                            - 3rd dim: number of epochs
  variance in condition 1 is maximized
-- trials2 - 3d numpy array - 1st dim: channels
                            - 2nd dim: epoch length
                            - 3rd dim: number of epochs
  variance in condition 2 is minimized
-- num_iter - int - number of iterations to do, defaults to 30
                    (minimum 10)
-- s_keep - int - number of spatial patterns to keep, defaults to 2
-- t_keep - int - number of temporal patterns to keep, defaults to 2
-- verbose - bool - if number of iterations should be printed during
                    execution
Output:
-- W - list of 2d arrays - spatial filter matrix for each iteration,
      the final spatial filters are in W[-1]
-- V - list of 2d arrays - temporal filter matrix for eachiteration,
                           the final temporal filters are in V[-1]
-- s_eigvals - list of 1d array - spatial eigenvalues,
               the final spatial eigenvalues are in s_eigvals[-1]
-- t_eigvals - list of 1d array - temporal eigenvalues, the final
               temporal eigenvalues are in s_eigvals[-1]
```

### 10.2 Variables

Name	Description
package	Value: 'meet'

'C4', 'P2', 'P4'])

vector for testing

'C4', 'P2', 'P4'])

are on the surface of a

are on the surface of a

random vector for testin

output is in data-unit/m\*\*

# 11 Module meet.sphere

```
Spherical spline interpolation and CSD
```

Submodule of the Modular EEg Toolkit - MEET for Python.

Algorithm from Perrin et al., Electroenceph Clin Neurophysiol 1989, 72:184-187, Corrigenda in 1990, 76: 565-566

While the implementation was done independently, the code was tested using the sample data of the CSD Toolbox for Matlab (http://psychophysiology.cpmc.columbia.edu/Software/CSDtoolbox/) and results are the same. Thanks a lot th Juergen Kayer for sharing his work there.

### Example:

-----

For Plotting a scalp map:

```
>>> import numpy as _np
```

- >>> coords = getStandardCoordinates(['Fp1', 'Fp2', 'C1', 'C2', 'C3',
- >>> coords = projectCoordsOnSphere(coords) # be sure that these coords
- >>> data = \_np.random.random(coords.shape[0]) # just create a random
- >>> X, Y, Z = potMap(coords, data) # interpolate using spherical splines

For Calculating current source densities:

```
>>> import numpy as _np
```

- >>> coords = getStandardCoordinates(['Fp1', 'Fp2', 'C1', 'C2', 'C3',
- >>> coords = projectCoordsOnSphere(coords) # be sure that these coords
- >>> data = \_np.random.random([coords.shape[0], 1000]) # just create a
- >>> CSD = calcCSD(coords, data) # get CSD using spherical splines -

#### Author:

-----

Gunnar Waterstraat
gunnar[dot] waterstraat[at] charite.de

39

### 11.1 Functions

addHead(ax, lw=2.0, ec='k', \*\*kwargs)

```
Add a path representing a a head consisting of a circle with center (0,0) and r = 1 to the axis.

Input:
-----
--ax - a matplotlib axes instance into which the head will be drawn
--lw - linewidth - defaults to 2.0
--ec - edgecolor - defaults to black ('k')

Output:
-----
Nothing

Notes:
-----
Kwargs are matplotlib patches kwargs and are passed to matplotlib.patches.PathPatch

Parts of the code (for drawing the circle) are from: https://sourcegraph.com/github.com/matplotlib/matplotlib/symbols/python/lib/matplotlib/path/Path/c
```

Module meet.sphere

```
getStandardCoordinates(elecnames, fname='standard')
Read (cartesian) Electrode Coordinates from tab-seperated text file
The standard is plotting_1005.txt obtained from:
http://robertoostenveld.nl/electrode/plotting_1005.txt (however 1st
and 2nd column were exchanged to get x,y,z order)
Thanks to Robert Oostenveld for sharing these files!!!
Input:
-- elecnames - iterable - list of Electrode names
-- fname - str - filename from which positions should be read
              - this is a tab delimeed file with the UPPERCASE
                electrode names in first column
                x,y,z in subsequent columns
                T7, T8, Oz, Fpz and Cz must be included!
Output:
-- coords - 2D array containing the cartesian coordinates in rows
               - 1st column: x
               - 2nd column: y
               - 3rd column: z
Example:
>>> getStandardCoordinates(['fc3', 'FC1', 'xx']) # 'xx' is not a
                                                                             valid electrode
                                           ],
array([[-0.6638 , 0.3610691 , 0.6545
      [-0.3581 , 0.37682936, 0.8532
                                            ],
      Γ
                            nan, nan]])
              nan,
```

Module meet.sphere

### projectCoordsOnSphere(coords)

```
The input coordinates are projected onto a sphere with center
(0,0,0) and radius 1.
For the input coordinates it is believed that they lie on a
sphere with center (0,0,0) and radius r = x**2 + y**2 + Z**2.
Subsequently this radius is scaled th 1, preserving altitude
and azimuth of the original coordinates.
Input:
--coords - 3D array containing the points in rows
          - 1st column: x
          - 2nd column: y
          - 3rd column: z
Output:
-- out_coords - 3D array containing the coordinates in rows
Examples:
-----
>>>  coords = _{np.array}([[0,0,1], [0,1,0], [1,1,1]]) # the last one
>>> projectCoordsOnSphere(coords)
array([[ 0. , 0. , 1.
                                            ],
      [ 0.
                  , 1.
                               , 0.
                                            ],
```

is not on a spheri

[ 0.57735027, 0.57735027, 0.57735027]])

# projectCircleOnSphere(coords, projection='stereographic') Project 2d coordinates inside a unit circle on a sphere with center (0,0) and radius 1. Stereographic projection: Where the given circle is believed to be the on the plane crossing the equator (z=0) and the perspective point is the southpole (0,0,-1). Points inside the circle are projected onto the northern hemisphere, points outside the circle on the souther hemisphere. Orthographic projection: All points have to lie inside the circle and are projected on the northern hemisphere by keeping the xy coordinates and adding a z coordinate to result in a radius of 1. Poinst outside the circle result in nans. Input: -- coords - 2D array containing the coordinates in rows - 1st column: x - 2nd column: y -- projection - str - 'stereographic' (standard) or 'orthographic' (explanations see above) Output: -- sphere\_coords - masked 3D array containing the coordinates in rows - 1st column: x - 2nd column: y - 3rd column: z (all coordinates outside a unit sphere are masked)

```
projectSphereOnCircle(sphere_coords, projection='stereographic')
Project coordinates that lie on the surface of a unit sphere
with center (0,0,0) and radius 1 into a unit circle
If projection == 'stereographic':
The vertex of the sphere is (0,0,1). The projection is done from
the "southpole" (0,0,-1) onto the plane with z=0.
The northern hemisphere is hereby projected into the unit circle,
the souther hemisphere outside the unit circle.
If projection == 'orthographic':
Only the northern hemisphere is mapped onto a plane through the
equator by keeping the xy-coordinates. For coordinates on the
southern hemisphere nan is returned.
Input:
_____
-- sphere_coords - 2D array containing the coordinates in rows
          - 1st column: x
          - 2nd column: y
         - 3rd column: z
-- projection - str - 'stereographic' (standard) or 'orthographic'
                      (explanations see above)
Output:
_____
-- coords - 2D array containing the coordinates in rows
                 - 1st column: x
                 - 2nd column: y
```

```
potMap(RealCoords, data, diameter\_samples=200, n=(7, 7), m=4, smooth=0,
projection='stereographic')
Get a scalp map of potentials interpolated on a sphere.
If projection == 'stereographic':
The vertex of the sphere is (0,0,1). The projection is done from
the "southpole" (0,0,-1) onto the plane with z=0.
The northern hemisphere is hereby projected into the unit circle,
the souther hemisphere outside the unit circle.
If projection == 'orthographic':
Only the northern hemisphere is mapped onto a plane through the
equator by keeping the xy-coordinates. For coordinates on the
southern hemisphere nan is returned.
Input:
_____
-- RealCoords - array of shape channels x \ 3 - (x,y,z) cartesian
                coordinates of physical electrodes on a sphere with
                center (0,0,0) and radius 1
-- data - array of shape channels x datapoints - containing values
         at electrodes in same order as in 'RealCoords'
-- diameter_samples - int - number of points along the diameter of
                      the scalp to interpolate
-- n - tuple of ints - how many terms of the Legendre-Polynomial
       should be calculated, defaults to (7,7)
-- m - int - order of the spherical spline interpolation, defaults
       to 4
-- smooth - float - amount of smoothing, defaults to 0
-- projection - str - 'stereographic' (standard) or 'orthographic'
                      (explanations see above)
Output:
-- X, Y, Z - grid containing the X and Y coordinates and the
             interpolated values where everything outside the unit
             circle is masked.
```

```
csdMap(RealCoords, data, diameter\_samples=200, n=(7, 20), m=4, smooth=1e-05,
projection='stereographic')
Get a scalp map of CSDs calculated from spherical splines.
If projection == 'stereographic':
The vertex of the sphere is (0,0,1). The projection is done from
the "southpole" (0,0,-1) onto the plane with z=0.
The northern hemisphere is hereby projected into the unit circle,
the souther hemisphere outside the unit circle.
If projection == 'orthographic':
Only the northern hemisphere is mapped onto a plane through the
equator by keeping the xy-coordinates. For coordinates on the
southern hemisphere nan is returned.
Input:
_____
-- RealCoords - array of shape channels x \ 3 - (x,y,z) cartesian
                coordinates physical electrodes on a sphere with
                center (0,0,0) and radius 1
-- data - array of shape channels x datapoints - containing values
          at electrodes in same order as in 'RealCoords'
-- diameter_samples - int - number of points along the diameter of
                      the scalp to interpolate
-- n - tuple of ints - how many terms of the Legendre-Polynomial
       should be calculated, defaults to (7,20)
-- m - int - order of the spherical spline interpolation,
       defaults to 4
-- smooth - float - amount of smoothing, defaults to 1E-5
-- projection - str - 'stereographic' (standard) or 'orthographic'
                      (explanations see above)
Output:
-- X, Y, Z - grid containing the X and Y coordinates and the
             interpolated values where everything outside the unit
             circle is masked. the unit of z is data_unit / m**2
```

```
calcCSD(Coords, data, n=(7, 20), m=4, smooth=1e-05, buffersize=64)
Calculate current source densities at the same electrode posisionts
as in the original data set
Input:
-- Coords - 2d array - channels x (x,y,z) cartesian coordinates of
           physical electrodes
-- data - array containing values at electrodes in same order as in
         'Coords'
   -- 1st dim: channels
   -- 2nd dim: datapoints
-- n - tuple of ints - How many terms of the Legendre-Polynomial
      should be calculated, defaults to (7, 20) - 7 for the first
       and 20 for the 2nd polynomial
-- m - order of the spherical spline interpolation, defaults to 4
-- smooth - float - amount of smoothing, defaults to 1E-5
-- buffersize - float - determine the size of a buffer in MB to do
               the calculations
Output:
-- pot - array containing CSD-values in data-unit / m**2
Example:
>>> Coords = getStandardCoordinates(['C1', 'C3'])
>>> Coords = projectCoordsOnSphere(Coords) # be sure that the
                                                                           points are on a sphere
>>> data = _np.arange(6, dtype=float).reshape(2,-1)
>>> calcCSD(Coords, data)
array([[-3.5474569 , -3.5474569 , -3.5474569 ],
       [ 3.60884286, 3.60884286, 3.60884286]])
```

Module meet.sphere

```
smoothSP(Coords, data, n=(7, 7), m=4, smooth=1e-05, buffersize=64)
Calculate spatially smoothed potential values at the same electrode
positions as in the original data set
Input:
-- Coords - 2d array - channels x (x,y,z) cartesian coordinates of
           physical electrodes
-- data - array containing values at electrodes in same order as in
         'Coords'
   -- 1st dim: channels
   -- 2nd dim: datapoints
-- n - tuple of ints - How many terms of the Legendre-Polynomial
       should be calculated, defaults to (7, 7) - 7 for the first
       and 7 for the 2nd polynomial
-- m - order of the spherical spline interpolation, defaults to 4
-- smooth - float - amount of smoothing, defaults to 1E-5
-- buffersize - float - determine the size of a buffer in MB to do
               the calculations
Output:
-- pot - array containing the spatially smoothed potentials
Example:
>>> Coords = getStandardCoordinates(['C1', 'C3'])
>>> Coords = projectCoordsOnSphere(Coords) # be sure that the
                                                                      points are on a sphere
>>> data = _np.arange(6, dtype=float).reshape(2,-1)
>>> smoothSP(Coords, data)
array([[ 0.01220571, 1.01220571, 2.01220571],
       [ 2.98778429, 3.98778429, 4.98778429]])
```

### 11.2 Variables

Name	Description
package	Value: 'meet'

# 12 Module meet.tf

```
S transform (time-frequency transformation)
Submodule of the Modular EEg Toolkit - MEET for Python.
the 'standard' S transform:
Stockwell, Robert Glenn, Lalu Mansinha, and R. P. Lowe. "Localization of
the complex spectrum: the S transform." Signal Processing,
IEEE Transactions on 44.4 (1996): 998-1001.
as well as
the fast dyadic S transform:
-----
Brown, Robert A., M. Louis Lauzon, and Richard Frayne. "A general
description of linear time-frequency transforms and formulation of a
fast, invertible transform that samples the continuous S-transform
spectrum nonredundantly." Signal Processing, IEEE Transactions on 58.1
(2010): 281-290.
Author:
_____
Gunnar Waterstraat
gunnar[dot]waterstraat[at]charite.de
Example for a standard S transform:
_____
>>> import matplotlib.pyplot as plt
>>> import numpy as np
>>> data = np.random.random(1000) # generate a random 1000 dp signal
>>> tf_coords, S = gft(data, sampling='full')
>>> S = S.reshape(-1, data.shape[0]) # for the full transform no
                                                                      interpolation is needed -> j
>>> plt.imshow(_np.abs(S), aspect='equal', origin='lower') #plot the
Example for a dyadic S transform:
-----
>>> import matplotlib.pyplot as plt
>>> import numpy as np
>>> data = np.random.random(1000) # generate a random 1000 dp signal
>>> tf_coords, S = gft(data, sampling='dyadic')
>>> t, f, S_interp = interpolate_gft(tf_coords, S, (data.shape[0]//2,
                                                                          data.shape[0]), data.shap
                                                                      extent=[t[0], t[-1], f[0], f
>>> plt.imshow(_np.abs(S_interp), aspect='equal', origin='lower',
```

Functions Module meet.tf

### 12.1 Functions

```
gft(sig, window='gaussian', axis=-1, sampling='full', full=False, hanning=True)
Calculate the discrete general fourier family transform
Inputs:
-----
-- sig - signal of interest - 1 or 2 dimensional
-- window - window function, standard is gaussian
-- axis - axis along which transform should be performed
-- sampling - 'full' | 'dyadic' - should the S-domain be sampled
              completely, i.e. redundant or dyadic
-- full - True False - return also negative frequencies, standard
         is False
-- hanning - True False - Apply a hanning window to 5% first and
             last datapoints
Outputs:
-- Coords - (frequency, time) Coordinates of each point in S
-- S - complex S transform array
  if sampling is dyadic interpolate_gft should be used to
   interpolate the result onto a regular grid
   if sampling is full, this can be easily done by reshaping each {\tt S}
  transform to the shape (-1, sig.shape[axis])
```

Variables Module meet.tf

```
interpolate_gft(Coords, S, IM_shape, data_len, kindf='nearest', kindt='nearest')
Interpolate the result of a gft-transform - standard is nearest
neighbor interpolation
Input:
-- Coords, Coords as output by the gft command
-- S - A gft result list
-- IM\_shape - requested shape of the interpolated matrix
      1st axis frequency
       2nd axis time
-- data_len - length of inital data
-- kindf - interpolation method along frequency axis - any of
           ['nearest', 'linear']
-- kindt - interpolation method along time axis - any of
           ['nearest', 'linear']
Output:
-- wanted times - time point array
-- wanted freqs - frequency array
-- IM - interpolated matrix
```

### 12.2 Variables

Name	Description
package	Value: 'meet'

# Index

```
meet (package), 3–5
                                                            meet.sphere.projectSphereOnCircle (function),
    meet._cSPoC (module), 6–9
      meet._cSPoC.cSPoAC (function), 7
                                                            meet.sphere.smoothSP (function), 47
      meet._cSPoC.cSPoC (function), 6
                                                          meet.tf (module), 49–51
      meet._cSPoC.pattern_from_filter (function), 6
                                                            meet.tf.gft (function), 50
    meet._dot_new (module), 10
                                                            meet.tf.interpolate_gft (function), 50
      meet._dot_new.dot (function), 10
      meet._dot_new.test_dot (function), 10
      meet._dot_new.test_to_fix (function), 10
    meet._interp (module), 11
      meet._interp.akima (function), 11
      meet._interp.mchi (function), 11
    meet.basic (module), 12–17
      meet.basic.calculateRMS (function), 15
      meet.basic.epochEEG (function), 14
      meet.basic.getMarker (function), 16
      meet.basic.interpolateEEG (function), 13
      meet.basic.readBinary (function), 13
    meet.cSPoC (module), 18–21
      meet.cSPoC.cSPoC (function), 20
      meet.cSPoC.pattern_from_filter (function), 20
    meet.eeg_viewer (module), 22–23
      meet.eeg_viewer.plotEEG (class), 22–23
    meet.elm (module), 24–31
      meet.elm.accuracy (function), 25
      meet.elm.ClassELM (class), 27–31
      meet.elm.G_mean (function), 25
      meet.elm.get_conf_matrix (function), 27
      meet.elm.Matthews (function), 25
      meet.elm.PPV (function), 26
      meet.elm.ssk_cv (function), 26
    meet.iir (module), 32–33
      meet.iir.butterworth (function), 33
    meet.spatfilt (module), 34–38
      meet.spatfilt.bCSTP (function), 37
      meet.spatfilt.CCA_data (function), 35
      meet.spatfilt.CCAvReg (function), 36
      meet.spatfilt.CSP (function), 35
    meet.sphere (module), 39–48
      meet.sphere.addHead (function), 40
      meet.sphere.calcCSD (function), 46
      meet.sphere.csdMap (function), 45
      meet.sphere.getChannelNames (function), 41
      meet.sphere.getStandardCoordinates (function),
        40
      meet.sphere.potMap (function), 44
      meet.sphere.projectCircleOnSphere (function),
      meet.sphere.projectCoordsOnSphere (function),
        42
```