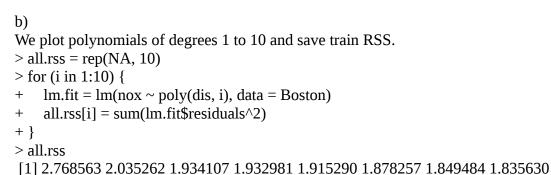
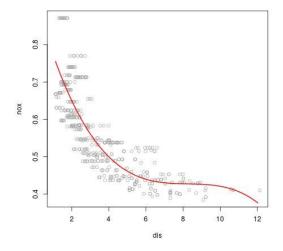
```
9)
a)
> set.seed(1)
> library(MASS)
> attach(Boston)
> lm.fit = lm(nox \sim poly(dis, 3), data = Boston)
> summary(lm.fit)
Call:
lm(formula = nox \sim poly(dis, 3), data = Boston)
Residuals:
   Min
           1Q Median
                           3Q
                                 Max
-0.121130 -0.040619 -0.009738 0.023385 0.194904
Coefficients:
        Estimate Std. Error t value Pr(>|t|)
(Intercept) 0.554695 0.002759 201.021 < 2e-16 ***
poly(dis, 3)1 -2.003096  0.062071 -32.271 < 2e-16 ***
poly(dis, 3)2 0.856330 0.062071 13.796 < 2e-16 ***
Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' '1
```

Residual standard error: 0.06207 on 502 degrees of freedom Multiple R-squared: 0.7148, Adjusted R-squared: 0.7131 F-statistic: 419.3 on 3 and 502 DF, p-value: < 2.2e-16

```
> dislim = range(dis)
> dis.grid = seq(from = dislim[1], to = dislim[2], by = 0.1)
> lm.pred = predict(lm.fit, list(dis = dis.grid))
> jpeg("9a.jpg")
> plot(nox ~ dis, data = Boston, col = "darkgrey")
> lines(dis.grid, lm.pred, col = "red", lwd = 2)
> dev.off()
```

Summary shows that all polynomial terms are significant while predicting nox using dis. Plot shows a smooth curve fitting the data fairly well.



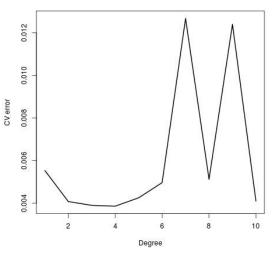


[9] 1.833331 1.832171

As expected, train RSS monotonically decreases with degree of polynomial.

c)
We use a 10-fold cross validation to pick the best polynomial degree.
> jpeg("9b.jpg")
> plot(1:10, all.deltas, xlab = "Degree", ylab = "CV error", type = "l", pch = 20, lwd = 2)
> dev.off()

A 10-fold CV shows that the CV error reduces as we increase degree from 1 to 3, stay almost constant till degree 5, and the starts increasing for higher degrees. We pick 4 as the best polynomial degree.



d)

We see that dis has limits of about 1 and 13 respectively. We split this range in roughly equal 4 intervals and establish knots at [4,7,11]. Note: bs function in R expects either df or knots argument. If both are specified, knots are ignored.

```
> library(splines)
> sp.fit = lm(nox ~ bs(dis, df = 4, knots = c(4, 7, 11)), data = Boston)
> summary(sp.fit)
```

Call:

 $lm(formula = nox \sim bs(dis, df = 4, knots = c(4, 7, 11)), data = Boston)$

Residuals:

Min 1Q Median 3Q Max -0.124567 -0.040355 -0.008702 0.024740 0.192920 Coefficients:

Estimate Std. Error t value Pr(>|t|)

```
(Intercept) 0.73926 0.01331 55.537 < 2e-16 *** bs(dis, df = 4, knots = c(4, 7, 11))1 -0.08861 0.02504 -3.539 0.00044 *** bs(dis, df = 4, knots = c(4, 7, 11))2 -0.31341 0.01680 -18.658 < 2e-16 *** bs(dis, df = 4, knots = c(4, 7, 11))3 -0.26618 0.03147 -8.459 3.00e-16 *** bs(dis, df = 4, knots = c(4, 7, 11))4 -0.39802 0.04647 -8.565 < 2e-16 *** bs(dis, df = 4, knots = c(4, 7, 11))5 -0.25681 0.09001 -2.853 0.00451 ** bs(dis, df = 4, knots = c(4, 7, 11))6 -0.32926 0.06327 -5.204 2.85e-07 *** ---
```

Signif. codes: 0 '***' 0.001 '**' 0.01 '*' 0.05 '.' 0.1 ' ' 1

Residual standard error: 0.06185 on 499 degrees of freedom Multiple R-squared: 0.7185, Adjusted R-squared: 0.7151 F-statistic: 212.3 on 6 and 499 DF, p-value: < 2.2e-16

```
> sp.pred = predict(sp.fit, list(dis = dis.grid))
> jpeg("9c.jpg")
> plot(nox ~ dis, data = Boston, col = "darkgrey")
> lines(dis.grid, sp.pred, col = "red", lwd = 2)
> dev.off()
```

The summary shows that all terms in spline fit are significant. Plot shows that the spline fits data well except at the extreme values of disdis, (especially dis>10).

```
e)
We fit regression splines with dfs between 3 and 16.
> all.cv = rep(NA, 16)
> for (i in 3:16) {
+ lm.fit = lm(nox ~ bs(dis, df = i), data = Boston)
+ all.cv[i] = sum(lm.fit$residuals^2)
+ }
> all.cv[-c(1, 2)]
[1] 1.934107 1.922775 1.840173 1.833966 1.829884 1.816995 1.825653 1.792535
[9] 1.796992 1.788999 1.782350 1.781838 1.782798 1.783546
```

Train RSS monotonically decreases till df=14 and then slightly increases for df=15 and df=16.

0.8

0.5

0.4

nox

f)
Finally, we use a 10-fold cross validation to find best df.
We try all integer values of df between 3 and 16.

```
> all.cv = rep(NA, 16)

> for (i in 3:16) {

+ lm.fit = glm(nox ~ bs(dis, df = i), data = Boston)

+ all.cv[i] = cv.glm(Boston, lm.fit, K = 10)$delta[2]

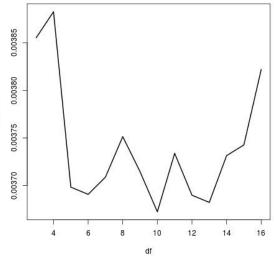
+ }

> jpeg("9f.jpg")

> plot(3:16, all.cv[-c(1, 2)], lwd = 2, type = "l", xlab = "df", ylab = "CV error")

> dev.off()
```

CV error is more jumpy in this case, but attains minimum at df=10. We pick 1010 as the optimal degrees of freedom.



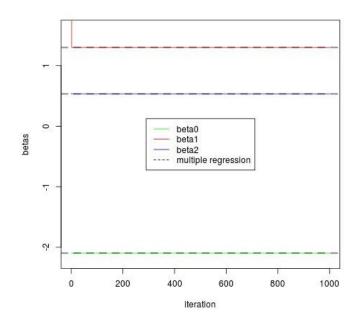
```
a)
We create variables according to the equation Y=-2.1+1.3X_1+0.54X_2.
> set.seed(1)
> X1 = rnorm(100)
> X2 = rnorm(100)
> eps = rnorm(100, sd = 0.1)
> Y = -2.1 + 1.3 * X1 + 0.54 * X2 + eps
b)
Create a list of 1000 beta^0, beta^1 and beta^2. Initialize first of the \beta^1 to 10.
> beta0 = rep(NA, 1000)
> beta1 = rep(NA, 1000)
> beta2 = rep(NA, 1000)
> beta1[1] = 10
c, d, e)
Accumulate results of 1000 iterations in the beta arrays.
> for (i in 1:1000) {
    a = Y - beta1[i] * X1
    beta2[i] = lm(a \sim X2)$coef[2]
    a = Y - beta2[i] * X2
    lm.fit = lm(a \sim X1)
    if (i < 1000) \{+
                          beta1[i + 1] =
lm.fit$coef[2]
    beta0[i] = lm.fit$coef[1]
+ }
> ipeg("9cde.jpg")
> plot(1:1000, beta0, type = "l", xlab = "iteration",
                                                                                  heta1
ylab = "betas", ylim = c(-2.2,
    1.6), col = "green")
> lines(1:1000, beta1, col = "red")
> lines(1:1000, beta2, col = "blue")
> legend("center", c("beta0", "beta1", "beta2"), lty
= 1, col = c("green", "red",
    "blue"))
                                                                     200
                                                                                    600
                                                                                            800
                                                                                                   1000
> dev.off()
                                                                               iteration
```

The coefficients quickly attain their least square values.

```
f) > lm.fit = lm(Y \sim X1 + X2)
```

11)

Dotted lines show that the estimated multiple regression coefficients match exactly with the coefficients obtained using backfitting.



g) When the relationship between Y and X's is linear, one iteration is sufficient to attain a good approximation of true regression coefficients.