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#### **EDUCATION**

# Nanyang Technological University, Singapore Renaissance Engineering Programme

Aug 2023 - Apr 2027

- Specialization in Computer Science
- Master of Science in Technology Management

## **WORK EXPERIENCE**

**DSTA** May 2023 - Jul 2023

Software Intern. Computer Vision Team

- Evaluated computer vision-based security systems in live, large-scale event settings (up to 1000 pax), deploying person re-identification and facial recognition technologies to detect potential threats.
- Contributed to the deployment of surveillance enhancements during NDP 2023, improving identification accuracy in high-traffic, occluded crowd environments.
- Applied and benchmarked state-of-the-art deep learning models including ArcFace and AdaFace for real-time recognition tasks.

NTU-A\*STAR Research May 2024 - Jul 2024

Research Intern (3D Diffusion & Generative Models)

- Engineered and benchmarked 3D generative pipelines (SDFusion, Diffusion-SDF, DreamFusion, Magic3D), optimizing model fidelity, controllability, and generation speed for production-ready 3D assets.
- Evaluated models' ability to capture concrete attributes (e.g., 3-legged vs. 4-legged chairs) and abstract styles (e.g., vintage vs. modern cars)
- Generated 3D meshes, repaired artifacts using Blender, and prepared models for mass production via PLA and resin
   3D printing
- Showcased final printed 3D artifacts at the IEEE Conference 2024

#### **DSO National Laboratories**

May 2025 - Aug 2025

Al Research Intern (LLM Reasoning & Inversion)

- Integrated **System 2-style fine-tuning** with **context-parametric inversion** research to improve factual reasoning in large language models.
- Designed and implemented novel reasoning augmentations including **summarization**, **salient fact extraction**, and **knowledge correction** techniques to refine parametric memory.
- Contributed toward advancing interpretability and reliability of LLM responses through modular cognitive pipelines.

## **ACCOMPLISHMENTS**

### Google Al Hackathon 2024 – 3<sup>rd</sup> Place

Designed an image-to-speech translation system that converts medical documents into dialects commonly used by elderly patients, improving accessibility in healthcare.

Technologies: Speech-to-text, text-to-speech, dialect translation models

#### LTA Hackathon – 3<sup>rd</sup> Place

Developed a real-time safety alert system to notify both cyclists and pedestrians when bicycles encroach on pedestrian paths. Aimed at enhancing shared path safety in Singapore.

**Technologies:** YOLOv5, Flask, WebSockets, GPS integration

## E-Waste Recycling & Community Platform

Created a web app that helps users locate nearby electronic waste recycling points. Integrated a Reddit-like forum for questions and discussions, with sentiment analysis for harmful content moderation.

Technologies: React, Flask, PostgreSQL

## HACKX 2024 – Autonomous Ship Berthing System

Engineered a smart system to assist with autonomous ship berthing, combining real-time computer vision and hardware control.

Technologies: Arduino, YOLOv5, React, Flask, 3D Printing

## Support Donation Recovery Platform

Created a platform to aid individuals recovering from addiction through donation-based support. Integrated OpenLedger's Open-Payment API for secure transactions and featured recovery tracking dashboards.

Technologies: Flask, PostgreSQL, OpenLedger API

## • AngelHack 2024 - Volunteer Connect Platform

Built a web-based platform to match volunteers with community initiatives and help organizers source manpower efficiently. Integrated NLP for matching and automated communication.

Technologies: React, Flask, PostgreSQL, NLP

#### SUTD What The Hack 2023

Developed a voice-powered mobile payment assistant tailored for elderly users, reducing UI complexity through speech interface.

Technologies: Speech-to-text, text-to-speech

#### Telegram Matchmaking Bot

Built a Telegram bot that connects users based on social compatibility and food preferences.

Technologies: Flask, PostgreSQL

#### **RESEARCH WORK**

## Undergraduate Research Experience on Campus (URECA) Research on Real-Time Semantic Segmentation for Autonomous Robots

Aug 2024 - Dec 2024

- Developed real-time vision system integrating YOLOv11 tracking with semantic segmentation (DeepLabV3+, MobileNet), improving segmentation accuracy and temporal consistency in dynamic environments.
- Improved segmentation accuracy and temporal consistency in dynamic environments such as Cityscapes
- Achieved strong generalization to unseen datasets (e.g., VSPW) with zero-shot domain transfer capability
- Enhanced performance over baseline models without additional fine-tuning on new domains

#### **SKILLS**

- Languages: Proficient in English, Chinese
- Technical skills: C, Java, Python, React, Flask, SQL, AutoCAD, Microsoft Office