

Analysis of continuous beam by force method

Input data

Span lengths - $\vec{l} = [4; 7; 3; 5] \cdot \text{m} = [4 \text{ m} \ 7 \text{ m} \ 3 \text{ m} \ 5 \text{ m}]$

Number of spans - $n = \text{len}(\vec{l}) = 4$

Coordinates of supports - $\vec{x} = [4 \text{ m} \ 11 \text{ m} \ 14 \text{ m} \ 19 \text{ m}]$

Total beam length - $L = \vec{x}_4 = 19 \text{ m}$

Load - $q = 10 \frac{\text{kN}}{\text{m}}$

Elastic modulus of the material - $E = 30 \text{ GPa}$

Cross section

Rectangular section with dimensions: $b = 250 \text{ mm}$, $h = 500 \text{ mm}$

Area - $A = b \cdot h = 125000 \text{ mm}^2$

Moment of inertia - $I = \frac{b \cdot h^3}{12} = 2604166667 \text{ mm}^4$

Shear area - $A_Q = \frac{5}{6} \cdot b \cdot h = 104167 \text{ mm}^2$

Solution

The solution will be performed by the force method with a primary system - simply supported beam with internal supports removed and replaced by unknown forces X_i

Bending moments

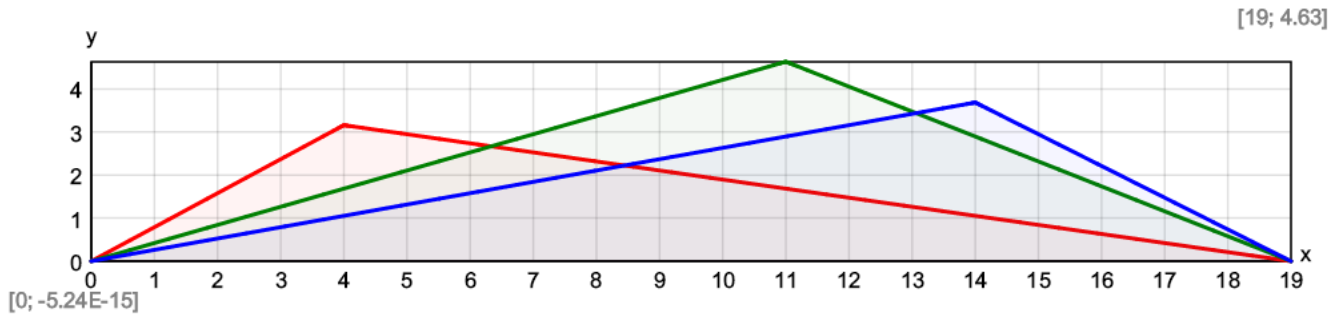
- in section a due to unit force at distance x from the beginning of the beam:

$$M_{1,max}(x) = \left(\frac{x}{L} - 1\right) \cdot x$$

$$M_{1,a}(a; x) = M_{1,max}(x) \cdot \begin{cases} \text{if } a < x: & \frac{a}{x} \\ \text{else:} & \frac{L-a}{L-x} \end{cases}$$

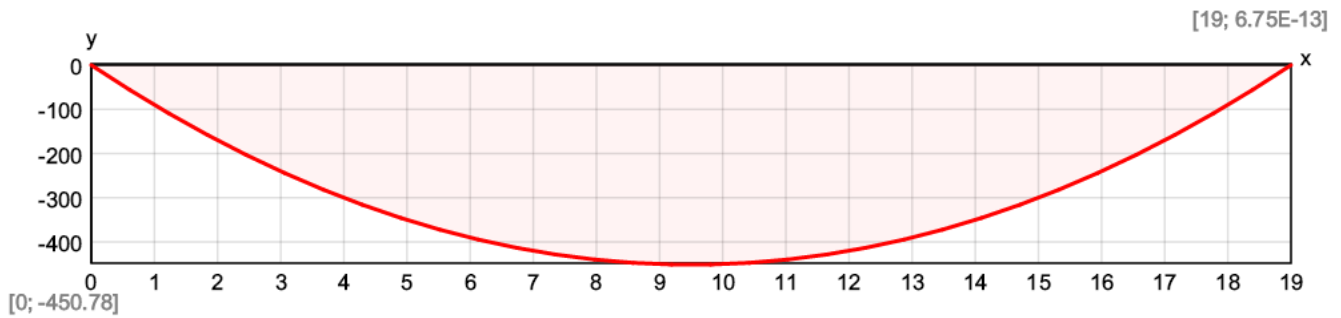
- in section a , due to unit force X_i :

$$M_1(a; i) = M_{1,a}(a; \vec{x}_i)$$



- due to external loads in primary system:

$$M_F(x) = \frac{q \cdot x}{2} \cdot (L - x)$$



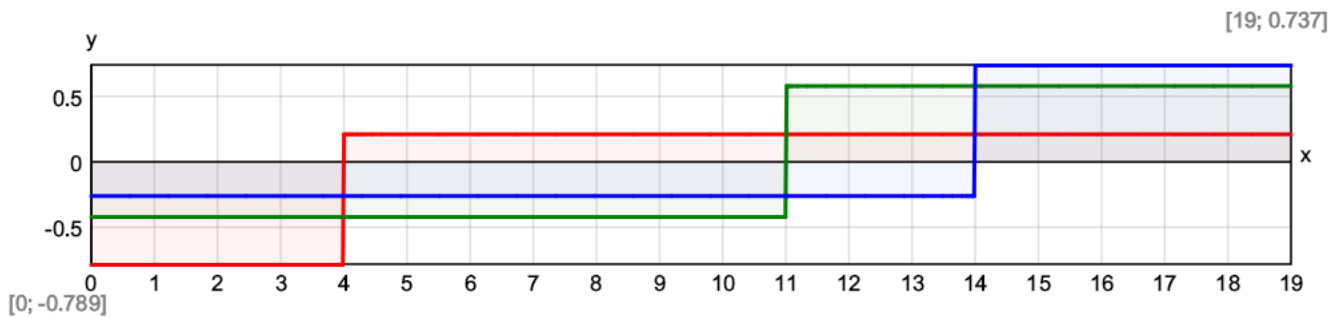
Shear forces

- in section a due to unit force at distance x from the beginning of the beam:

$$V_{1,a}(a; x) = \begin{cases} \text{if } a < x: & \frac{x}{L} - 1 \\ \text{else:} & \frac{x}{L} \end{cases}$$

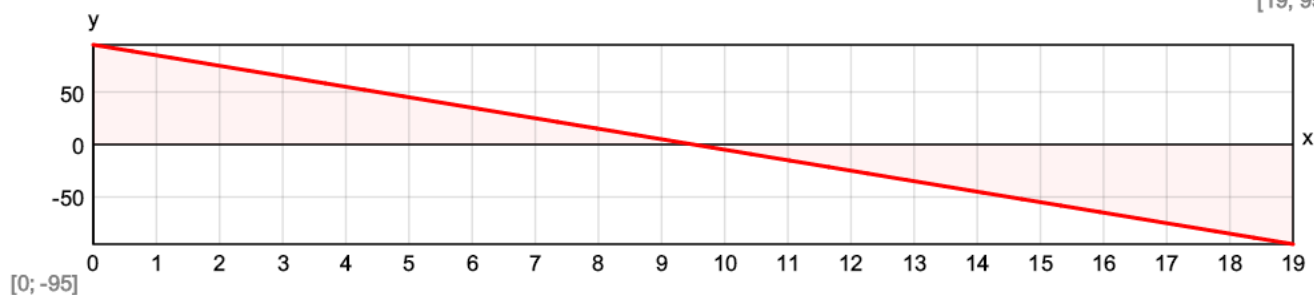
- in section a , due to unit force X_i :

$$V_1(a; i) = V_{1,a}(a; \vec{x}_i)$$



- due to external loads in primary system:

$$V_F(x) = q \cdot \left(\frac{L}{2} - x \right)$$



Number of unknowns by force method - $n_1 = n - 1 = 3$

Flexibility coefficients

$$\delta(i; j) = \int_{0\text{ m}}^L \frac{M_1(x; i) \cdot M_1(x; j)}{E \cdot I} dx + \int_{0\text{ m}}^L \frac{V_1(x; i) \cdot V_1(x; j)}{E \cdot A_Q} dx$$

$$\Delta_F(i) = \int_{0\text{ m}}^L \frac{M_1(x; i) \cdot M_F(x)}{E \cdot I} dx + \int_{0\text{ m}}^L \frac{V_1(x; i) \cdot V_F(x)}{E \cdot A_Q} dx$$

$$\delta = \text{symmetric}(n_1) = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \vec{\Delta}_F = \text{vector}(n_1) = [0 \ 0 \ 0]$$

$$\text{Repeat}\{\text{Repeat}\{\delta_{i,j} = \delta(i; j); i = 1 \dots n_1\}; j = 1 \dots n_1\} = 0.0011 \text{ m/kN}$$

$$\text{Repeat}\{\vec{\Delta}_{F,i} = \Delta_F(i); i = 1 \dots n_1\} = -0.161 \text{ m}$$

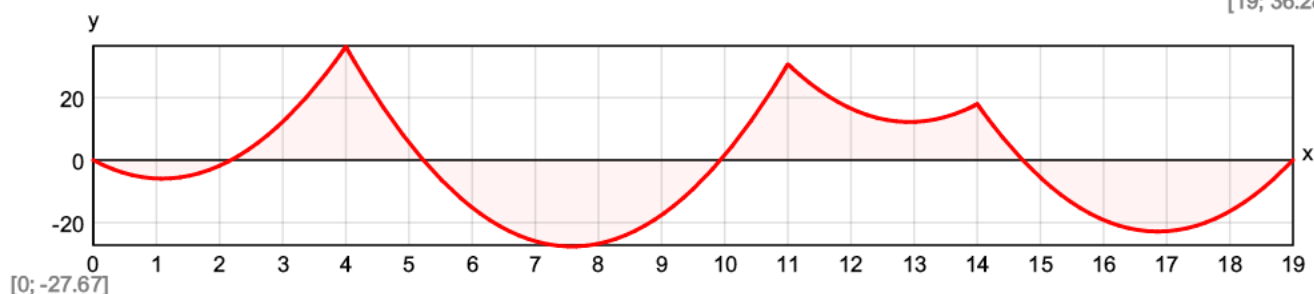
$$\delta = \begin{bmatrix} 0.000809 \text{ m/kN} & 0.00101 \text{ m/kN} & 0.000719 \text{ m/kN} \\ 0.00101 \text{ m/kN} & 0.00174 \text{ m/kN} & 0.00133 \text{ m/kN} \\ 0.000719 \text{ m/kN} & 0.00133 \text{ m/kN} & 0.0011 \text{ m/kN} \end{bmatrix}, \vec{\Delta}_F = [-0.135 \text{ m} \quad -0.211 \text{ m} \quad -0.161 \text{ m}]$$

Calculation of the unknown forces X_i

$$\vec{X} = -\text{clsolve}(\delta; \vec{\Delta}_F) = [64.9 \text{ kN} \quad 53.47 \text{ kN} \quad 39.33 \text{ kN}]$$

Results

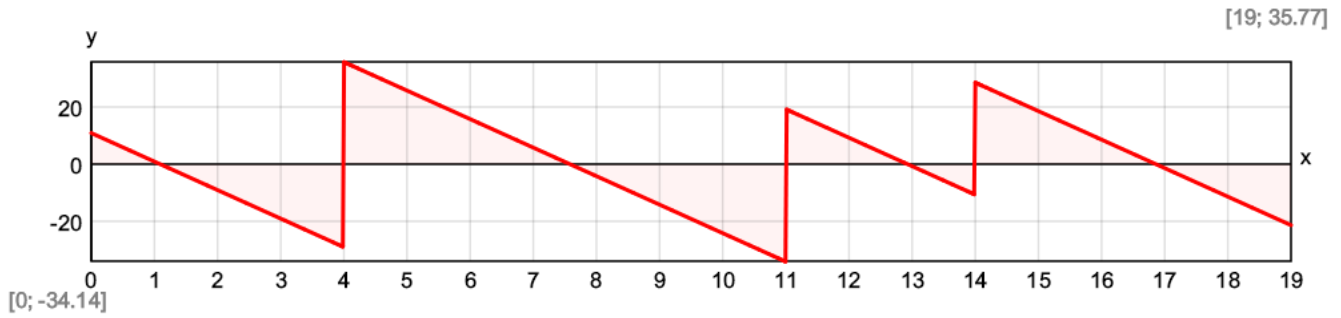
Bending moment diagram - $M(x) = M_F(x) + \sum_{i=1}^{n_1} M_1(x; i) \cdot X_i$



$$\vec{M}_{max} = [5.94 \text{ kNm} \quad 27.69 \text{ kNm} \quad -12.23 \text{ kNm} \quad 22.91 \text{ kNm}]$$

$$\vec{M}_{min} = [-36.39 \text{ kNm} \quad -30.79 \text{ kNm} \quad -17.98 \text{ kNm}]$$

$$\text{Shear force diagram} - V(x) = V_F(x) + \sum_{i=1}^{n_1} V_1(x; i) \cdot \vec{X}_i$$



$$\vec{V}_{max} = [10.9 \text{ kN} \quad 35.8 \text{ kN} \quad 19.27 \text{ kN} \quad 28.6 \text{ kN}]$$

$$\vec{V}_{min} = [-29.1 \text{ kN} \quad -34.2 \text{ kN} \quad -10.73 \text{ kN} \quad -21.4 \text{ kN}]$$

Deflections

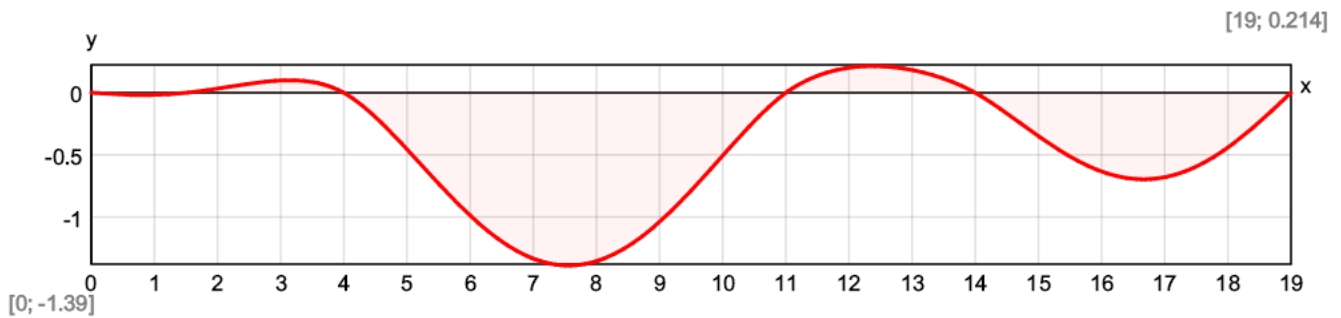
- in section a , due to unit force X_i :

$$d_1(a; i) = \int_{0 \text{ m}}^L \frac{M_{1,a}(x; a) \cdot M_1(x; i)}{E \cdot I} dx + \int_{0 \text{ m}}^L \frac{V_{1,a}(x; a) \cdot V_1(x; i)}{E \cdot A_Q} dx$$

- due to external loads in primary system:

$$d_F(a) = \int_{0 \text{ m}}^L \frac{M_{1,a}(x; a) \cdot M_F(x)}{E \cdot I} dx + \int_{0 \text{ m}}^L \frac{V_{1,a}(x; a) \cdot V_F(x)}{E \cdot A_Q} dx$$

$$d(x) = d_F(x) + \sum_{i=1}^{n_1} d_1(x; i) \cdot \vec{X}_i$$

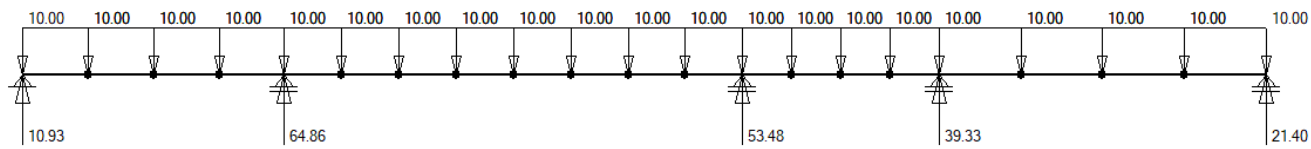


$$\text{Maximum deflection} - d_{max} = \text{Inf}\{d(x); x \in [0 \text{ m}; L]\} = -1.39 \text{ mm}$$

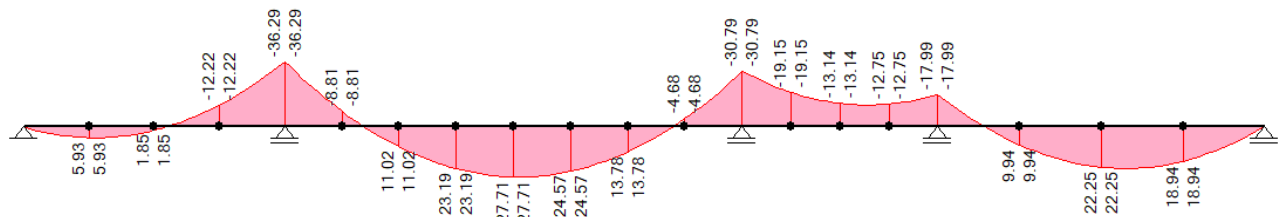
$$\text{At a distance from the origin} - x_{inf} = 7.56 \text{ m}$$

Comparison with Stady 6.0 structural analysis software

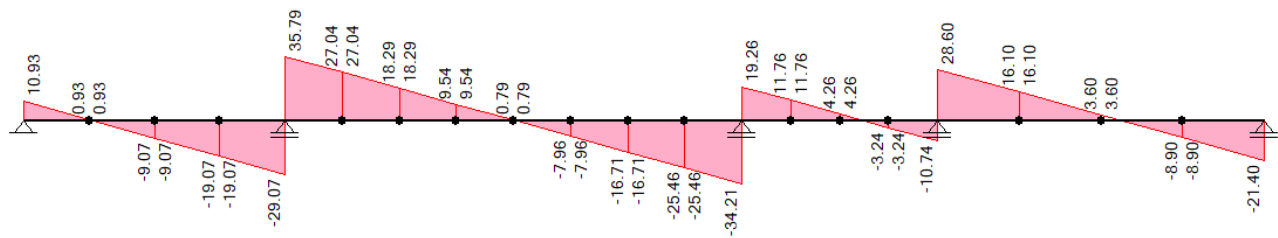
Loads and support reactions, kN



Bending moments, kNm



Shear forces, kN



Deflections, mm

