# Autoencoder asset pricing models

Shihao Gu, Bryan Kelly, Dacheng Xiu Journal of Econometrics, 2020

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#### **Outline**

- Introduction
- Research design
  - The Standard autoencoder
  - The conditional autoencoder
- Empirical study
- Monte Carlo simulations
- Conclusion

### 1. Introduction-- Background

- Kelly, Pruitt, and Su (KPS, 2019) provide empirical evidence that characteristics appear to predict returns because they help pinpoint compensated aggregate risk exposures.
- "instrumented" PCA (IPCA) assumes that the map from P characteristics to K betas is linear

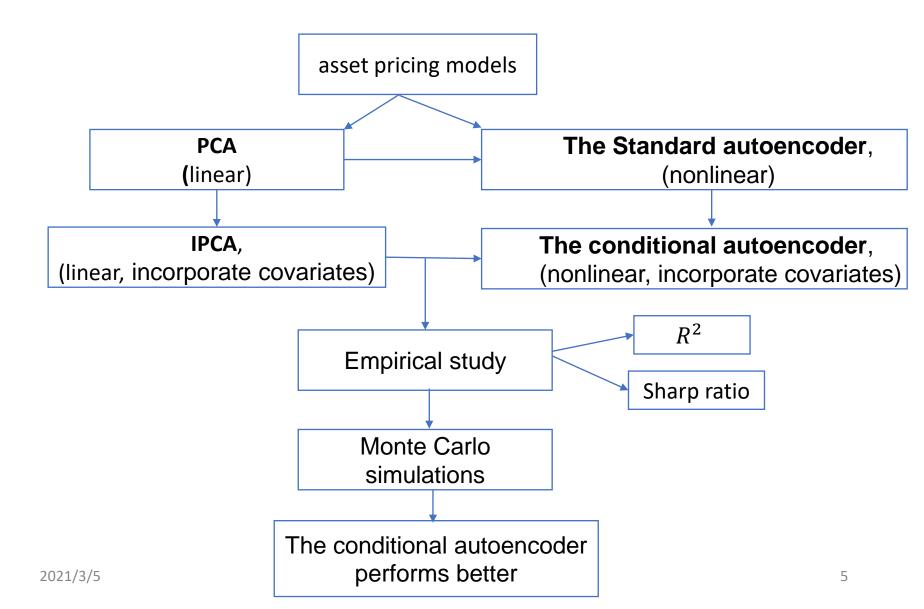
$$r_t = \beta f_t + u_t, \longrightarrow r_{i,t} = \beta(z_{i,t-1})' f_t + u_{i,t}$$
  
$$\beta(z_{i,t-1})' = z'_{i,t-1} \Gamma$$

The factors  $f_t$  are treated as latent, the  $\beta(Z_{i,t-1})'$  is  $K \times 1$  conditional factor exposure,  $Z_{i,t-1}$  is an  $P \times 1$  vector of asset characteristics, where P > K

#### 1. Introduction-- Motivation

- Like Kelly, Pruitt, and Su (KPS, 2019), our model allows for latent factors and factor exposures that depend on covariates such as asset characteristics.
- Unlike the linearity assumption of KPS, we model factor exposures
  as a flexible nonlinear function of covariates----the conditional
  autoencoder(AC).
- Our machine learning framework imposes the economic restriction of no-arbitrage.

#### 1. Introduction-- Framework



#### 1. Introduction-- Contribution

- 1. Using machine learning techniques to analyze the cross section of risk and return in financial markets.
- 2. We introduce a new conditional autoencoder model for individual stock returns which, like IPCA, allows covariates to help guide dimension reduction.
- 3. Our model delivers out-of-sample pricing errors that are far smaller (and generally insignificant) compared to other leading factor models.

• 2.1. Standard autoencoder

- ReLU Activation Function

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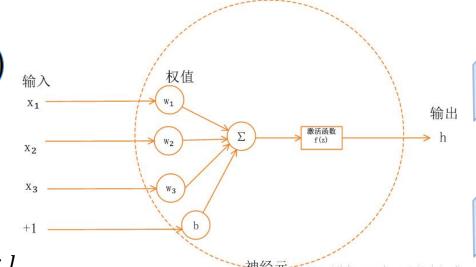
  -10.0 -7.5 -5.0 -2.5 0.0 25 5.0 7.5 10.0
- An autoencoder is a special neural network in which the outputs attempt to approximate the input variables --an unsupervised learning

Hidden layers

$$r^{(l)} = g \left( b^{(l-1)} + W^{(l-1)} r^{(l-1)} \right)$$

**Output layers** 

$$G(r, b, W) = b^{(L)} + W^{(L)}r^{(L)}$$



 $r_k^{(l)}$ : define the output of neuron k in layer l

 $r(l) = (r_1^{(l)}, \dots, r_{k^{(l)}}^{(l)})'$ : the vector of all outputs for this layer

 $g(\cdot)$ : a nonlinear activation function

$$g(y) = \max(y, 0)$$
:Relu

 $W^{(l-1)}$  is  $a K^{(l)} \times K^{(l-1)}$  matrix of weight parameters,  $b^{(l-1)}$  is a  $K^{(l)} \times 1$  vector of so-called bias parameters.

• 2.1. Standard autoencoder

- An autoencoder is a special neural network in which the outputs attempt to approximate the input variables --an unsupervised learning

Hidden layers

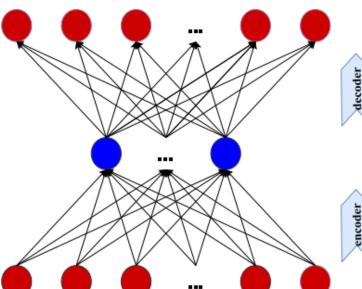
$$r^{(l)} = g \left( b^{(l-1)} + W^{(l-1)} r^{(l-1)} \right)$$

**Output layers** 

$$G(r, b, W) = b^{(L)} + W^{(L)}r^{(L)}$$

Output layer

Hidden layer(s)



 $r_k^{(l)}$ : define the output of neuron k in layer l

 $r(l) = (r_1^{(l)}, \dots, r_{k^{(l)}}^{(l)})'$ : the vector of all outputs for this layer

 $g(\cdot)$ : a nonlinear activation function  $g(y) = \max(y, 0)$ : Relu

$$W^{(l-1)}$$
 is  $a K^{(l)} \times K^{(l-1)}$  matrix of weight parameters,  $b^{(l-1)}$  is a  $K^{(l)} \times 1$  vector of so-called bias parameters.

- 2.1.1. Static linear factor models as a special case
- the most commonly studied models of asset returns assume a linear latent factor specification with static loadings

$$r_t = \beta f_t + u_t$$
,  $\xrightarrow{\text{matrix}} R = \beta F + U$ .

Estimated with PCA — using SVD

$$\bar{R} = \widehat{P}\Lambda\widehat{Q} + \widehat{U},$$

• The one-layer, linear autoencoder with *K* neurons

$$r_{t} = b^{(1)} + W^{(1)}(b^{(0)} + W^{(0)}r_{t}) + u_{t},$$

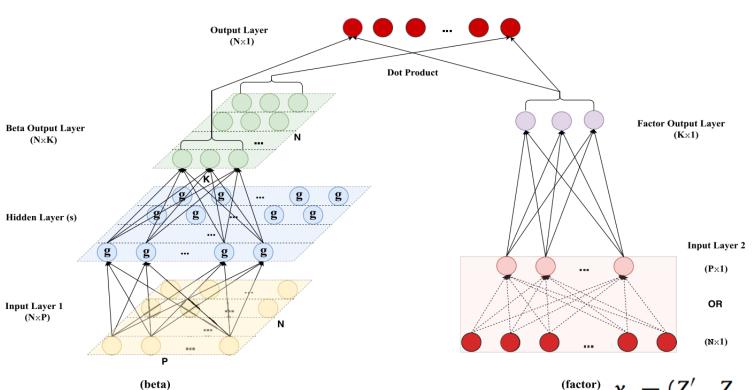
$$\min_{b,W} \left\| R - \left( b^{(1)}\iota' + W^{(1)}(b^{(0)}\iota' + W^{(0)}R) \right) \right\|_{F}^{2}$$

• The linear autoencoder is equivalent to PCA since they have the same factor loading matrix  $\hat{p}$ 

$$\widehat{W}^{(1)} = \widehat{P}A, \quad \widehat{W}^{(0)} = (\widehat{W}^{(1)'}\widehat{W}^{(1)})^{-1}\widehat{W}^{(1)'}, \quad \widehat{b}^{(1)} = \overline{r} - \widehat{W}^{(1)}\widehat{b}^{(0)} - \widehat{W}^{(1)}\widehat{W}^{(0)}\overline{r}, \quad \widehat{b}^{(0)} = a,$$

2.2. Extending the autoencoder model to include covariates

$$r_{i,t} = \beta'_{i,t-1}f_t + u_{i,t}.$$



$$z_{i,t-1}^{(0)} = z_{i,t-1}, \qquad r_t^{(0)} = r_t, \\ z_{i,t-1}^{(l)} = g\left(b^{(l-1)} + W^{(l-1)}z_{i,t-1}^{(l-1)}\right), \quad l = 1, \dots, L_{\beta}, \quad r_t^{(l)} = \widetilde{g}\left(\widetilde{b}^{(l-1)} + \widetilde{W}^{(l-1)}r_t^{(l-1)}\right), \quad l = 1, \dots, L_f, \\ \beta_{i,t-1} = b^{(L_{\beta})} + W^{(L_{\beta})}z_{i,t-1}^{(L_{\beta})}. \qquad \qquad \widetilde{\beta}_t = \widetilde{b}^{(L_f)} + \widetilde{W}^{(L_f)}r_t^{(L_f)}.$$

- 2.2.1. Conditional linear factor models as a special case
- IPCA solves the optimization problem:

$$\min_{\Gamma,F} \sum_{t=1}^{T} \sum_{i=1}^{N} \|r_{i,t} - z'_{i,t-1} \Gamma' f_t\|^2 = \min_{\Gamma,F} \sum_{t=1}^{T} \|r_t - Z_{t-1} \Gamma' f_t\|^2.$$
 (17)

the estimation objective of the conditional autoencoder is:

$$\beta'_{i,t} = Z_{t-1}W'_0 \qquad f_t = W_1x_t$$

$$\min_{W_0, W_1} \sum_{t=1}^{T} \|r_t - Z_{t-1}W'_0W_1x_t\|^2.$$
(18)

- The solution to (18) is equivalent to the solution of (17) if  $Z'_t Z_t = \Sigma$  for a constant matrix  $\Sigma$
- In the general case where  $\mathbf{Z}_t'\mathbf{Z}_t$  is non-constant, the two estimators are similar but no longer equivalent

- 2.3. Regularized autoencoder learning
- 2.3.1. Training, validation, and testing
- 2.3.2. Regularization techniques

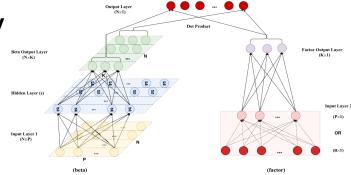
$$\mathcal{L}(\theta;\cdot) = \frac{1}{NT} \sum_{t=1}^{T} \sum_{i=1}^{N} \left\| r_{i,t} - \beta'_{i,t-1} f_t \right\|^2 + \phi(\theta;\cdot),$$
$$\phi(\theta;\lambda) = \lambda \sum_{i} |\theta_i|.$$

 $\theta$  summarizes the weight parameters in the loading and factor networks

- Early stopping:optimization is terminated when the validation sample errors begin to increase
- use multiple random seeds, and predicted by averaging estimates
- 2.3.3. Optimization algorithms
  - stochastic gradient descent (SGD)---Adam

- 3.1. Data
- The same dataset studied in Gu et al. (2019)
- Sample period:1957.3-2016.12
- Sample data:94 characteristics, monthly individual stock returns from the CRSP, for all firms listed in NYSE, AMEX, and NASDAQ.
- The risk-free rate :the Treasury bill rate
- Training sample:18 years (1957–1974); validation sample:12 years of (1975–1986); testing sample:30 years (1987–2016)

- 3.2. Models comparison set
- Conditional autoencoder (CA) :



- CA<sub>0</sub>, uses a single linear layer in both the beta and factor networks.
- CA<sub>1</sub>, CA<sub>2</sub> and CA<sub>3</sub> add a first, second and third hidden layer in the beta network.
- CA<sub>0</sub> through CA<sub>3</sub> all maintain a one-layer linear specification on the factor side of the model, the number of neurons range from 1 to 6
- FF:1 to 6 factors. the excess market return, SMB, HML, and UMD, sequentially. The five-factor model is the market, SMB, HML, CMA, and RMW, and the six-factor model again appends UMD.

• 3.3. Statistical performance evaluation

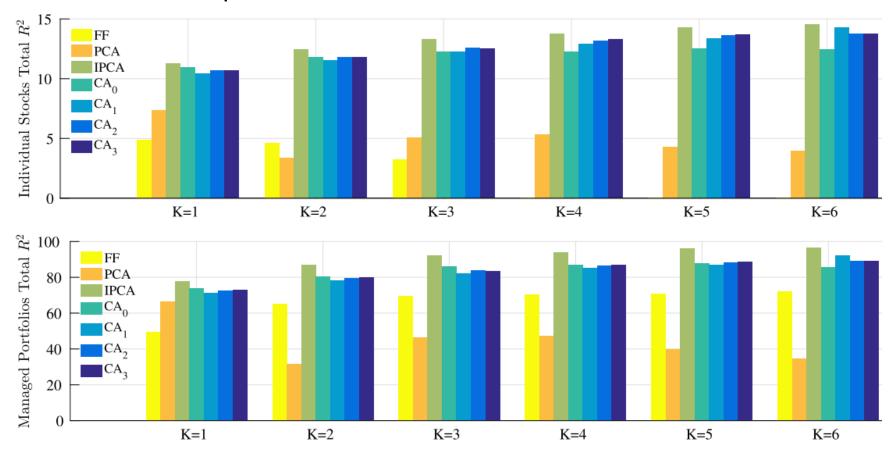
$$R_{\text{total}}^{2} = 1 - \frac{\sum_{(i,t) \in OOS} (r_{i,t} - \widehat{\beta}'_{i,t-1} \widehat{f}_{t})^{2}}{\sum_{(i,t) \in OOS} r_{i,t}^{2}}$$

 quantifies the explanatory power of contemporaneous factor realizations, and assesses the model's description of individual stock riskiness

$$R_{\text{pred}}^{2} = 1 - \frac{\sum_{(i,t) \in OOS} (r_{i,t} - \widehat{\beta}'_{i,t-1} \widehat{\lambda}_{t-1})^{2}}{\sum_{(i,t) \in OOS} r_{i,t}^{2}},$$

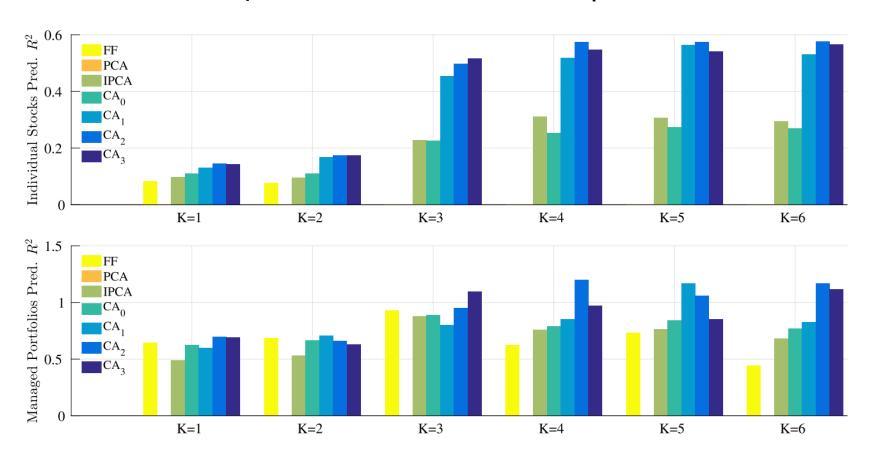
- where  $\hat{\lambda}_{t-1}$  is the prevailing sample average of  $\hat{f}$  up to month t-1.
- quantifies the predictions of future individual excess stock returns.
   assesses a model's ability to explain panel variation in risk compensation.

• 3.3. Statistical performance evaluation-- total R<sup>2</sup>



➤ IPCA provides the best fit , total R² at the portfolio-level tends to be far higher

• 3.3. Statistical performance evaluation—pred. R<sup>2</sup>



➤ CA1, CA2, and CA3 dramatically outperform the FF, PCA and IPCA models

#### • 3.4. Economic performance evaluation

**Table 3**Out-of-sample sharpe ratios of long-short portfolios.

<b>Equal-weight</b>	K						
	1	2	3	4	5	6	
FF	-0.66	-0.85	-0.40	-0.30	0.36	-0.21	
PCA	0.28	0.09	0.13	-0.08	-0.12	0.15	
IPCA	0.20	0.19	1.26	2.16	2.31	2.25	
$CA_0$	0.23	0.32	1.34	1.87	2.10	2.18	
CA <sub>1</sub>	0.30	0.39	2.12	2.63	2.67	2.60	
$CA_2$	0.30	0.38	2.16	2.64	2.68	2.63	
$CA_3$	0.31	0.38	2.19	2.57	2.57	2.59	
Value-weight	K						
	1	2	3	4	5	6	
FF	-0.82	-1.13	-0.69	-0.60	0.18	-0.53	
PCA	0.12	-0.18	0.05	-0.10	-0.30	<u>-0.0</u> 8	
IPCA	-0.15	-0.07	0.59	0.81	1.05	0.96	
$CA_0$	-0.11	-0.03	0.41	0.81	0.83	0.88	
$CA_1$	-0.03	0.11	0.91	1.30	1.48	1.40	
$CA_2$	-0.03	0.08	0.92	1.39	1.45	1.53	
CA <sub>3</sub>	-0.02	0.08	1.09	1.41	1.34	1.51	

CA<sub>2</sub> outperforms others. Following the nonlinear conditional autoencoders, the best model is IPCA

- 3.4. Economic performance evaluation
- To evaluate the multi-factor mean—variance efficiency
   Table 4

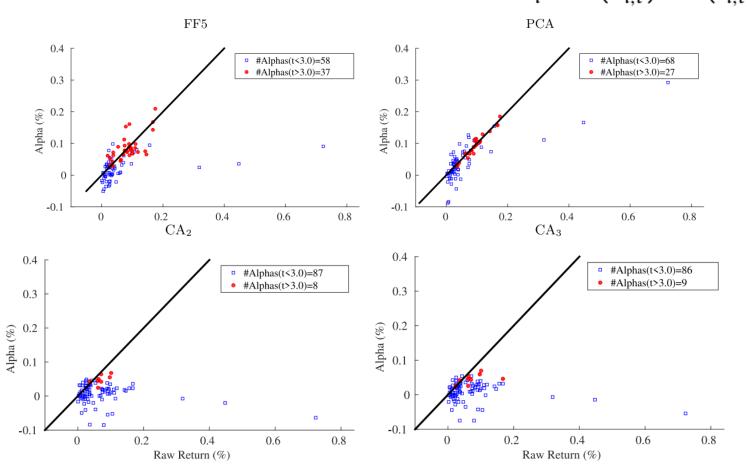
Out-of-sample factor tangency portfolio sharpe ratios.

	K						
	1	2	3	4	5	6	
FF	0.51	0.41	0.53	0.71	0.71	0.82	
PCA	0.35	0.23	0.25	0.38	0.48	0.55	
IPCA	0.39	0.44	1.81	3.14	3.71	3.72	
$CA_0$	0.42	0.48	1.47	1.76	1.94	1.97	
$CA_1$	0.56	0.91	3.18	3.82	3.63	4.58	
$CA_2$	0.54	0.75	3.56	4.26	4.72	2.77	
CA <sub>3</sub>	0.54	0.77	3.94	4.75	4.94	4.37	

➤ The most dominant overall model on this dimension is CA₃ with five factors

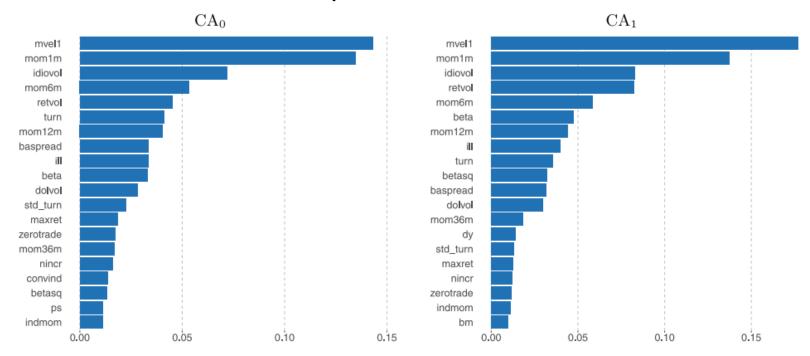
• 3.5. Risk premia vs. mispricing

Out-of-sample pricing errors (alphas) :  $\alpha_i := E(u_{i,t}) = E(r_{i,t}) - E(\beta'_{i,t-1}f_t).$ 



For FF5, 37 of the 95 managed portfolios have alpha t-statistics in excess of 3.0. For CA2, that number drops to 8 out of 95.

• 3.6. Characteristics importance-- the reduction in total R<sup>2</sup>



- The first is a price trend category, which includes short-term reversal (mom1m), stock momentum (mom12m).
- ➤ The second category includes liquidity variables, such as turnover and turnover volatility (turn, std\_turn), dollar volume (dolvol).
- Risk measures constitute the third influential group, including total and idiosyncratic return volatility (retvol, idiovol), market beta (beta), and betasquared (betasq).

  Resk

#### 4. Monte Carlo simulations

• We simulate a conditional factor model for excess returns  $r_t$ , for t = 1, 2, ..., T:

$$r_{i,t} = \beta_{i,t-1} f_t + \varepsilon_{i,t}, \quad \beta_{i,t-1} = g^*(c_{i,t-1}; \theta), \quad f_t = W x_t + \eta_t$$
  
 $x_t \sim \mathcal{N}(0.03, 0.1^2 \times \mathbb{I}_{P_X}), \, \eta_t \sim \mathcal{N}(0, 0.01^2 \times \mathbb{I}_3) \text{ and } \varepsilon_{i,t} \sim t_5(0, 0.1^2),$ 

The panel of characteristics

$$c_{ij,t} = \frac{2}{n+1} \operatorname{rank}(\bar{c}_{ij,t}) - 1, \quad \bar{c}_{ij,t} = \rho_j \bar{c}_{ij,t-1} + \epsilon_{ij,t},$$
$$\rho_j \sim \mathcal{U}[0.9, 1], \text{ and } \epsilon_{ij,t} \sim \mathcal{N}(0, 1),$$

- Weight matrix  $W = \begin{bmatrix} 1 & 0 & 0 & \dots & 0 \\ 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \end{bmatrix}$ •  $g^*(\cdot)$  functions:
- Linear  $g^*(c_{i,t};\theta) = (1.2 \times c_{i1,t}, c_{i2,t}, 0.8 \times c_{i3,t})'$ .
  - nonlinear  $g^*(c_{i,t};\theta) = (c_{i1,t}^2, 2 \times (c_{i1,t} \times c_{i2,t}), 0.6 \times \text{sgn}(c_{i3,t}))'$ .

#### 4. Monte Carlo simulations

**Table 6** Comparison of total  $R^2(\%)$ s and predictive  $R^2(\%)$ s in simulations.

			. ,			
Model (a)	K					
Total. R <sup>2</sup>	1	2	3	4	5	6
PCA	3.5	4.7	5.5	6.3	7.1	7.8
IPCA	18.6	32.2	40.7	41.0	41.4	41.7
$CA_0$	15.6	26.7	33.7	33.5	33.4	33.2
$CA_1$	17.6	30.3	38.1	37.7	37.3	37.1
$CA_2$	17.7	29.2	36.8	36.5	36.3	35.9
CA <sub>3</sub>	17.6	25.6	30.0	29.5	26.3	23.4
Pred. R <sup>2</sup>						
PCA	0.17	0.10	0.04	0.01	-0.01	<u>-0.0</u> 3
IPCA	2.20	2.93	3.33	3.32	3.32	3.32 3.13
$CA_0$	2.04	2.84	3.17	3.14	3.12	3.13
$CA_1$	2.11	2.93	3.27	3.29	3.26	3.26
$CA_2$	2.10	2.85	3.22	3.22	3.23	3.22
CA <sub>3</sub>	2.06	2.57	2.89	2.86	2.58	2.39

 $\triangleright$  IPCA delivers the best OOS total and predictive  $R^2s$ . Because the true model is sparse and linear in the input covariates.

#### 4. Monte Carlo simulations

Model (b)	K					
Total. $R^2$	1	2	3	4	5	6
PCA	3.4	5.1	6.0	6.6	7.3	7.9
IPCA	11.0	11.4	11.9	12.3	12.7	13.1
$CA_0$	8.5	8.2	7.9	7.6	7.4	7.2
$CA_1$	15.0	24.6	31.8	32.0	31.9	31.8
$CA_2$	15.7	23.5	30.9	31.8	30.2	28.2
CA <sub>3</sub>	15.9	15.6	14.6	14.0	11.2	9.2
Pred. R <sup>2</sup>						
PCA	0.15	0.19	0.15	0.12	0.10	0.09
IPCA	0.84	0.82	0.81	0.80	0.79	0.79
$CA_0$	0.80	0.76	0.77	0.76	0.72	0.70
$CA_1$	1.83	2.31	2.70	2.70	2.71	2.73
$CA_2$	1.95	2.24	2.73	2.80	2.69	2.53
CA <sub>3</sub>	1.77	1.43	1.32	1.26	1.06	0.86

> CA models clearly beat IPCA, because the latter cannot capture the nonlinearity in the model.

#### 4. Conclusion

- Firstly, our conditional autoencoder model dominates competing asset pricing models, including Fama—French models, PCA methods, and linear conditioning methods such as IPCA.
- Secondly, the pricing errors in our model (likewise measured on an outof-sample basis) are a fraction of the magnitude of those from traditional Fama–French factor models.

#### 5. Inspiration

- This paper enriches the asset pricing model, by combining machine learning and asset pricing model.
- This paper simultaneously considers features and labels to predict labels, which can be used to solve other similar problems, or designs other models to try to consider features and labels at the same time to predict for time series data.
- Change return into fundamentals for fundamental extrapolation