Define the linear transformation T as follows,

$$T(a, b, c, d, e, f, g, h, i) = [i, a, b + i, c, d, e, f, g, h]$$
(1)

We can see that T is a transition function that maps the current day's state to the next day's state. a is the number of fish with internal timer 8, b is the number of fish with internal timer 7 and so on...

The matrix representation of T is,

$$A_{T} = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \end{bmatrix}$$

$$(2)$$

Let $\vec{v_1}$ be the state on day 1. We wish to compute $\vec{v_{256}}$, which can be expressed as

$$\vec{v}_{256} = (A_T)^{256} \vec{v}_1 \tag{3}$$

Computing $(A_T)^{256}$ is incredibly expensive. Let us diagonalize A_T by computing it's eigenvectors

$$A_T \vec{v} = \lambda v \tag{4}$$

$$\det(A_T - \lambda I) = 0 \tag{5}$$

$$\det \begin{bmatrix}
-\lambda & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\
1 & -\lambda & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & -\lambda & 0 & 0 & 0 & 0 & 0 & 1 \\
0 & 0 & 1 & -\lambda & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & -\lambda & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1 & -\lambda & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 & -\lambda & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 1 & -\lambda & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 1 & -\lambda & 0 \\
0 & 0 & 0 & 0 & 0 & 0 & 1 & -\lambda & 0
\end{bmatrix} = -\lambda^9 + \lambda^2 + 1 = 0 \tag{6}$$

You get the point, I'm not solving a nonic-polynomial...