The Breadth-First Search (BFS) algorithm is a graph traversal method used to explore nodes and edges of a graph in a layer-by-layer manner. It is commonly used in applications like finding the shortest path in an unweighted graph, solving puzzles, and traversing trees.

#### **How BFS Works:**

- 1. Initialization:
  - Start with a source node and mark it as visited.
  - Use a queue data structure to keep track of nodes to explore.
- 2. **Processing**:
  - o Dequeue a node from the front of the queue.
  - Explore all its unvisited neighbors, marking them as visited and enqueuing them.
- 3. **Repeat**:
  - o Continue the process until the queue is empty.

# **Steps of BFS:**

- 1. Start with the source node.
- 2. Mark the source node as visited and enqueue it.
- 3. While the queue is not empty:
  - o Dequeue a node, process it, and enqueue all its unvisited neighbors.
- 4. End when all reachable nodes are visited.

### **BFS Pseudocode:**

### **Characteristics of BFS:**

- Time Complexity:
  - $\circ$  O(V+E)O(V + E)O(V+E), where VVV is the number of vertices and EEE is the number of edges.
- Space Complexity:
  - $\circ$  O(V)O(V)O(V), for the queue and visited list.
- Type:
  - o BFS is a complete and level-order traversal in graphs or trees.

# **Example:**

## For a graph:

```
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A: [B, C]
B: [A, D, E]
C: [A, F]
D: [B]
E: [B]
F: [C]
```

If starting at A, BFS traversal would visit nodes in this order:

```
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A -> B -> C -> D -> E -> F
```

Let's break the code and concepts step-by-step to make everything clear:

# 1. Graph Representation

- A **graph** is a collection of nodes (vertices) connected by edges.
- In the code, the graph is represented as an adjacency list, which is a dictionary where:
  - o **Keys**: Represent the nodes.
  - o Values: Are lists of neighboring nodes connected to the key node.

#### Example Graph:

```
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    A
    / \
    B    C
    / \
    D    E    F
```

#### Adjacency List Representation:

```
python
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graph = {
    'A': ['B', 'C'],  # Node 'A' is connected to 'B' and 'C'
    'B': ['A', 'D', 'E'],  # Node 'B' is connected to 'A', 'D', 'E'
    'C': ['A', 'F'],  # Node 'C' is connected to 'A' and 'F'
    'D': ['B'],  # Node 'D' is connected to 'B'
    'E': ['B'],  # Node 'E' is connected to 'B'
    'F': ['C']  # Node 'F' is connected to 'C'
}
```

## 2. Breadth-First Search (BFS) Overview

- BFS traverses a graph level-by-level starting from a source node.
- It visits all immediate neighbors of a node before moving deeper.
- BFS uses a **queue** to keep track of which nodes to explore next.

## 3. Key Data Structures

#### Queue:

- A queue is a **First-In-First-Out (FIFO)** data structure.
- Nodes are added to the back of the queue (enqueue) and removed from the front (dequeue).
- This ensures BFS explores nodes level-by-level.

### Example of Queue Operations:

• **Enqueue**: Add an element to the back of the queue.

```
python
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queue.append('A') # Queue becomes: ['A']
```

• **Dequeue**: Remove an element from the front of the queue.

```
python
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node = queue.popleft() # Removes 'A'; Queue becomes: []
```

# 4. Code Explanation

#### **BFS** Function:

```
python
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from collections import deque # Import deque for efficient queue operations
```

deque: A double-ended queue allows fast enqueue and dequeue operations.

```
Initialize BFS:
python
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def bfs(graph, start):
    visited = set()  # To keep track of visited nodes
    queue = deque([start])  # Initialize the queue with the start node
    visited.add(start)  # Mark the start node as visited
```

- **visited**: A set to store nodes that have been visited.
- queue: Starts with the source node, ensuring it's the first to be processed.

## BFS Traversal:

- popleft(): Removes and returns the first element of the queue.
- **Processing**: The node is printed, but it can be replaced with other operations.

### Visit Neighbors:

- Iterate over the neighbors of the dequeued node.
- If a neighbor hasn't been visited:
  - Mark it visited to avoid reprocessing.

o **Enqueue it** for exploration in the next levels.

Example Walkthrough (Graph BFS Starting at A):

```
1. Initialization:
      o visited = {'A'}
      o queue = ['A']
2. Step 1: Process A.
      o Dequeue: queue = []
      Neighbors of A: ['B', 'C'] (enqueue them).
      o visited = {'A', 'B', 'C'}
      o queue = ['B', 'C']
3. Step 2: Process B.
      o Dequeue: queue = ['C']
         Neighbors of B: ['A', 'D', 'E'] (enqueue D and E; A is already visited).
      o visited = {'A', 'B', 'C', 'D', 'E'}
      o queue = ['C', 'D', 'E']
4. Step 3: Process c.
      o Dequeue: queue = ['D', 'E']
          Neighbors of C: ['A', 'F'] (enqueue F; A is already visited).
      o visited = {'A', 'B', 'C', 'D', 'E', 'F'}
      o queue = ['D', 'E', 'F']
5. Step 4: Process D.
      o Dequeue: queue = ['E', 'F']
      Neighbors of D: ['B'] (already visited).
      o queue = ['E', 'F']
6. Step 5: Process E.
      o Dequeue: queue = ['F']
      Neighbors of E: ['B'] (already visited).
      o queue = ['F']
7. Step 6: Process F.
      o Dequeue: queue = []

    Neighbors of F: ['C'] (already visited).

      o queue = []
```

## **Final Output:**

```
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A B C D E F
```

# 5. Complexity Analysis

1. Time Complexity: O(V+E)O(V+E)O(V+E)

- o VVV: Number of nodes (vertices).
- o EEE: Number of edges.
- 2. **Space Complexity**: O(V)O(V)O(V)o To store visited nodes and the queue.