

# Computer Organization Architecture



## **SIMPLE DIGITAL SYSTEMS**

- **Combinational and sequential circuits (learned in Chapters 1 and 2) can be used to create simple digital systems.**
- **These are the low-level building blocks of a digital computer.**
- **Simple digital systems are frequently characterized in terms of**
  - the registers they contain, and
  - the operations that they perform.
- **Typically,**
  - What operations are performed on the data in the registers
  - What information is passed between registers

# REGISTER TRANSFER AND MICROOPERATIONS

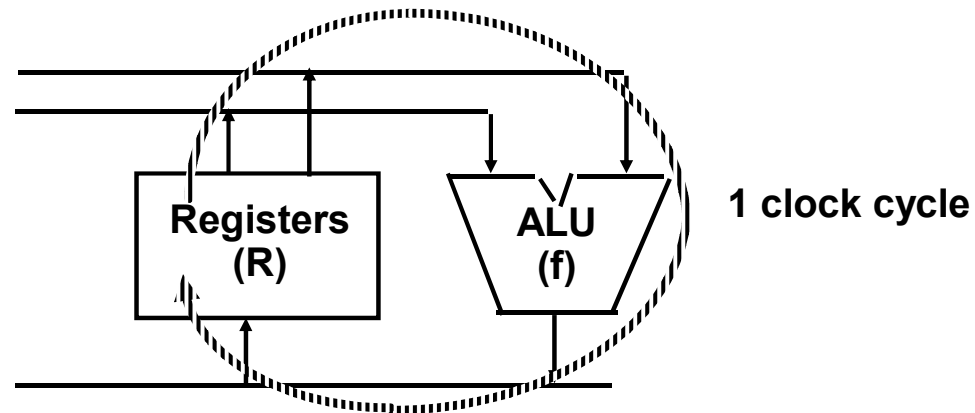
- **Register Transfer Language**
- **Register Transfer**
- **Bus and Memory Transfers**
- **Arithmetic Microoperations**
- **Logic Microoperations**
- **Shift Microoperations**
- **Arithmetic Logic Shift Unit**

## **MICROOPERATIONS (1)**

- The operations on the data in registers are called microoperations.
- The functions built into registers are examples of microoperations
  - Shift
  - Load
  - Clear
  - Increment
  - ...

## MICROOPERATION (2)

An elementary operation performed (during one clock pulse), on the information stored in one or more registers



$$R \leftarrow f(R, R)$$

**f:** shift, load, clear, increment, add, subtract, complement, and, or, xor, ...

## **ORGANIZATION OF A DIGITAL SYSTEM**

- **Definition of the (internal) organization of a computer**
  - **Set of registers and their functions**
  - **Microoperations set**
    - Set of allowable microoperations provided by the organization of the computer**
  - **Control signals that initiate the sequence of microoperations (to perform the functions)**

## REGISTER TRANSFER LEVEL

- Viewing a computer, or any digital system, in this way is called the register transfer level
- This is because we're focusing on
  - The system's registers
  - The data transformations in them, and
  - The data transfers between them.

## REGISTER TRANSFER LANGUAGE

- Rather than specifying a digital system in words, a specific notation is used, *register transfer language*
- For any function of the computer, the register transfer language can be used to describe the (sequence of) microoperations
- Register transfer language
  - A symbolic language
  - A convenient tool for describing the internal organization of digital computers
  - Can also be used to facilitate the design process of digital systems.



## DESIGNATION OF REGISTERS

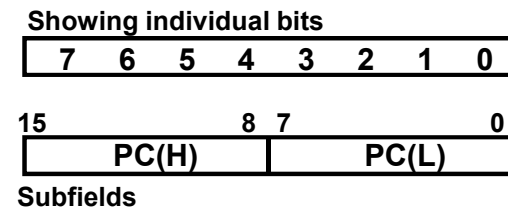
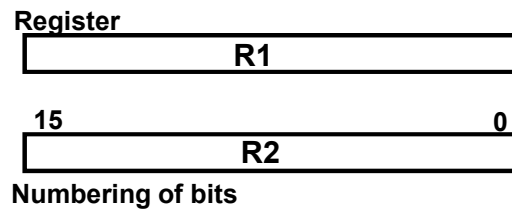
- Registers are designated by capital letters, sometimes followed by numbers (e.g., A, R13, IR)
- Often the names indicate function:
  - MAR      - memory address register
  - PC        - program counter
  - IR        - instruction register
- Registers and their contents can be viewed and represented in *various ways*
  - A register can be viewed as a single entity:



- Registers may also be represented showing the bits of data they contain

## DESIGNATION OF REGISTERS

- Designation of a register
  - a register
  - portion of a register
  - a bit of a register
- Common ways of drawing the block diagram of a register



## REGISTER TRANSFER

- Copying the contents of one register to another is a register transfer
- A register transfer is indicated as

**R2  $\leftarrow$  R1**

- In this case the contents of register R1 are copied (loaded) into register R2
- A simultaneous transfer of all bits from the source R1 to the destination register R2, during one clock pulse
- Note that this is a non-destructive; i.e. the contents of R1 are not altered by copying (loading) them to R2

## REGISTER TRANSFER

- A register transfer such as

$R3 \leftarrow R5$

Implies that the digital system has

- the data lines from the source register (R5) to the destination register (R3)
- Parallel load in the destination register (R3)
- Control lines to perform the action

## CONTROL FUNCTIONS

- Often actions need to only occur if a certain condition is true
- This is similar to an “if” statement in a programming language
- In digital systems, this is often done via a *control signal*, called a *control function*
  - If the signal is 1, the action takes place
- This is represented as:

**P: R2  $\leftarrow$  R1**

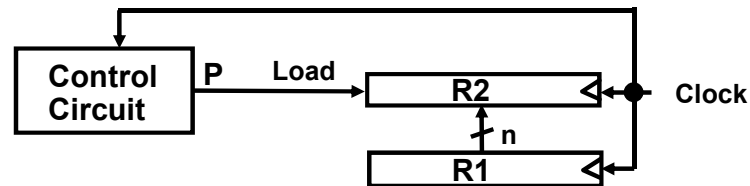
Which means “if P = 1, then load the contents of register R1 into register R2”, i.e., if (P = 1) then (R2  $\leftarrow$  R1)

## HARDWARE IMPLEMENTATION OF CONTROLLED TRANSFERS

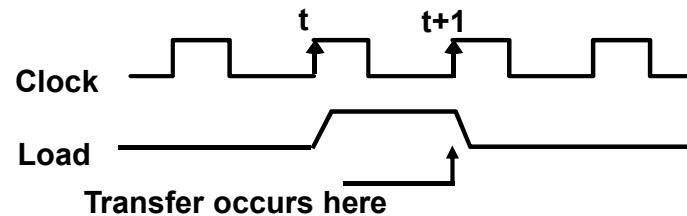
Implementation of controlled transfer

P:  $R2 \leftarrow R1$

Block diagram



Timing diagram



- The same clock controls the circuits that generate the control function and the destination register
- Registers are assumed to use *positive-edge-triggered* flip-flops

## **SIMULTANEOUS OPERATIONS**

- If two or more operations are to occur simultaneously, they are separated with commas

**P: R3  $\leftarrow$  R5, MAR  $\leftarrow$  IR**

- Here, if the control function P = 1, load the contents of R5 into R3, and at the same time (clock), load the contents of register IR into register MAR

## BASIC SYMBOLS FOR REGISTER TRANSFERS

Symbols	Description	Examples
Capital letters & numerals	Denotes a register	MAR, R2
Parentheses ()	Denotes a part of a register	R2(0-7), R2(L)
Arrow $\leftarrow$	Denotes transfer of information	R2 $\leftarrow$ R1
Colon :	Denotes termination of control function	P:
Comma ,	Separates two micro-operations	A $\leftarrow$ B, B $\leftarrow$ A



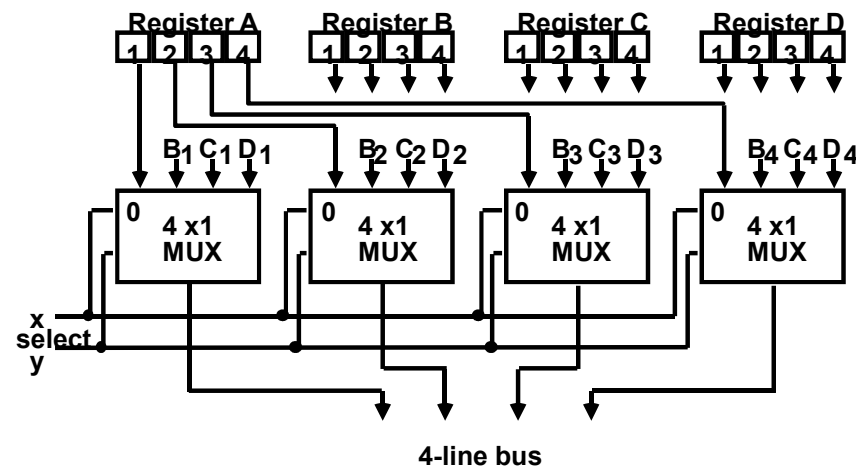
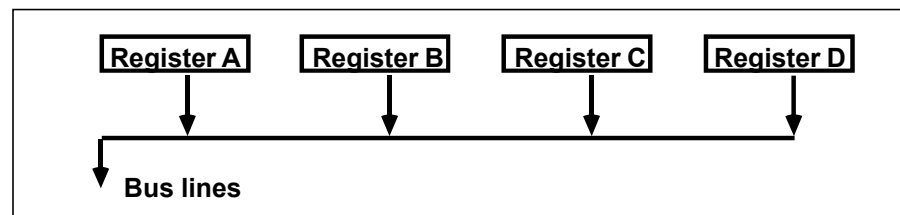
## CONNECTING REGISTERS

- In a digital system with many registers, it is impractical to have data and control lines to directly allow each register to be loaded with the contents of every possible other registers
- To completely connect  $n$  registers  $\rightarrow n(n-1)$  lines
- $O(n^2)$  cost
  - This is not a realistic approach to use in a large digital system
- Instead, take a different approach
- Have one centralized set of circuits for data transfer – the **bus**
- Have control circuits to select which register is the source, and which is the destination

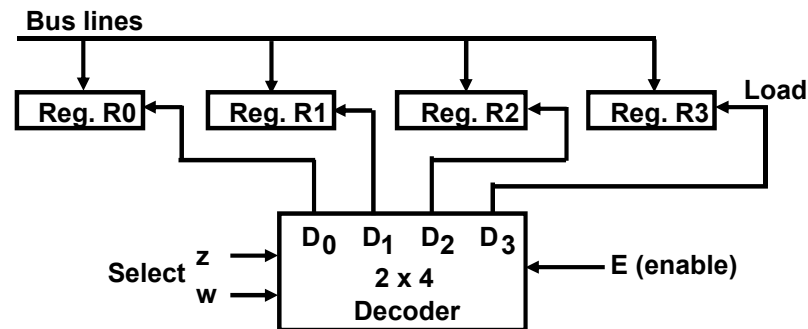
## BUS AND BUS TRANSFER

Bus is a path (of a group of wires) over which information is transferred, from any of several sources to any of several destinations.

From a register to bus:  $\text{BUS} \leftarrow R$

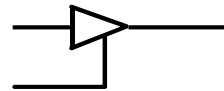


## TRANSFER FROM BUS TO A DESTINATION REGISTER



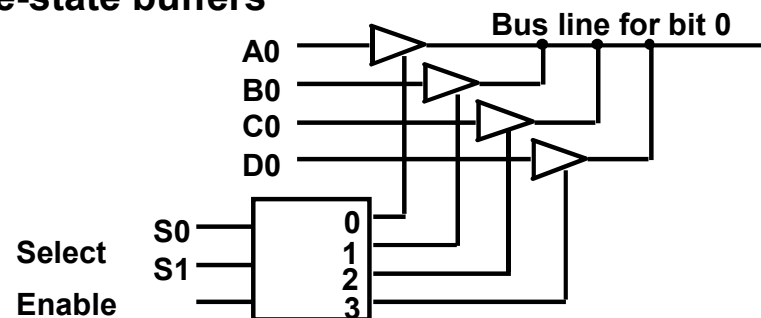
### Three-State Bus Buffers

Normal input A  
Control input C



Output Y=A if C=1  
High-impedance if C=0

### Bus line with three-state buffers



## **BUS TRANSFER IN RTL**

- Depending on whether the bus is to be mentioned explicitly or not, register transfer can be indicated as either

**$R2 \leftarrow R1$**

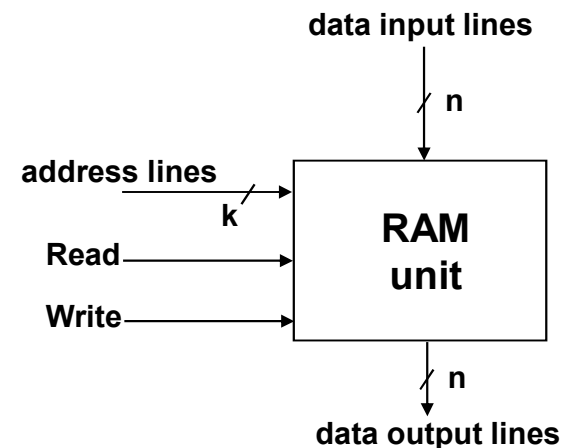
**or**

**$BUS \leftarrow R1, R2 \leftarrow BUS$**

- In the former case the bus is implicit, but in the latter, it is explicitly indicated

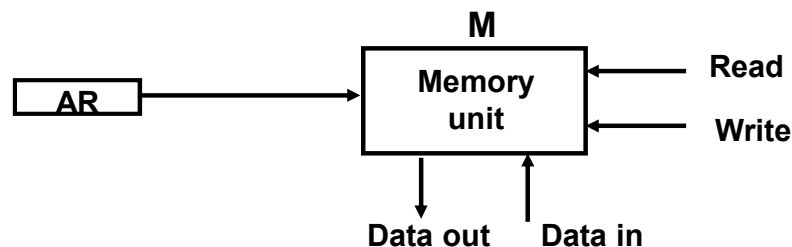
## MEMORY (RAM)

- Memory (RAM) can be thought as a sequential circuits containing some number of registers
- These registers hold the *words* of memory
- Each of the  $r$  registers is indicated by an *address*
- These addresses range from 0 to  $r-1$
- Each register (word) can hold  $n$  bits of data
- Assume the RAM contains  $r = 2^k$  words. It needs the following
  - $n$  data input lines
  - $n$  data output lines
  - $k$  address lines
  - A Read control line
  - A Write control line



## MEMORY TRANSFER

- Collectively, the memory is viewed at the register level as a device, M.
- Since it contains multiple locations, we must specify which address in memory we will be using
- This is done by indexing memory references
- Memory is usually accessed in computer systems by putting the desired address in a special register, the *Memory Address Register (MAR, or AR)*
- When memory is accessed, the contents of the MAR get sent to the memory unit's address lines



## MEMORY READ

- To read a value from a location in memory and load it into a register, the register transfer language notation looks like this:

**$R1 \leftarrow M[MAR]$**

- This causes the following to occur
  - The contents of the MAR get sent to the memory address lines
  - A Read (= 1) gets sent to the memory unit
  - The contents of the specified address are put on the memory's output data lines
  - These get sent over the bus to be loaded into register R1

## MEMORY WRITE

- To write a value from a register to a location in memory looks like this in register transfer language:

**$M[MAR] \leftarrow R1$**

- This causes the following to occur
  - The contents of the MAR get sent to the memory address lines
  - A Write (= 1) gets sent to the memory unit
  - The values in register R1 get sent over the bus to the data input lines of the memory
  - The values get loaded into the specified address in the memory



## SUMMARY OF R. TRANSFER MICROOPERATIONS

$A \leftarrow B$	Transfer content of reg. B into reg. A
$AR \leftarrow DR(AD)$	Transfer content of AD portion of reg. DR into reg. AR
$A \leftarrow \text{constant}$	Transfer a binary constant into reg. A
$ABUS \leftarrow R1,$ $R2 \leftarrow ABUS$	Transfer content of R1 into bus A and, at the same time, transfer content of bus A into R2
AR	Address register
DR	Data register
M[R]	Memory word specified by reg. R
M	Equivalent to M[AR]
$DR \leftarrow M$	Memory <i>read</i> operation: transfers content of memory word specified by AR into DR
$M \leftarrow DR$	Memory <i>write</i> operation: transfers content of DR into memory word specified by AR

# **MICROOPERATIONS**

- **Computer system microoperations are of four types:**
  - **Register transfer microoperations**
  - **Arithmetic microoperations**
  - **Logic microoperations**
  - **Shift microoperations**

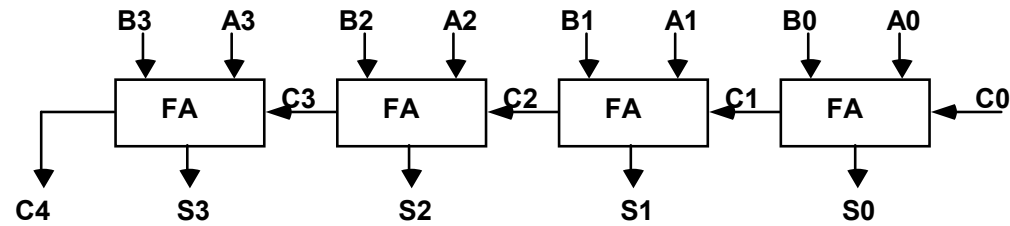
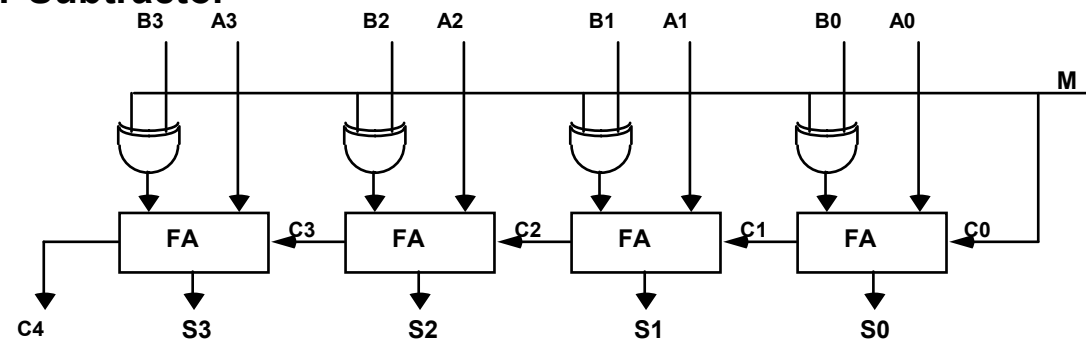
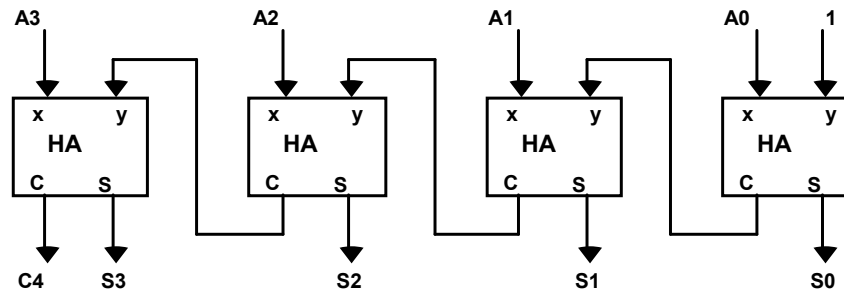
## ARITHMETIC MICROOPERATIONS

- The basic arithmetic microoperations are
  - Addition
  - Subtraction
  - Increment
  - Decrement
- The additional arithmetic microoperations are
  - Add with carry
  - Subtract with borrow
  - Transfer/Load
  - etc. ...

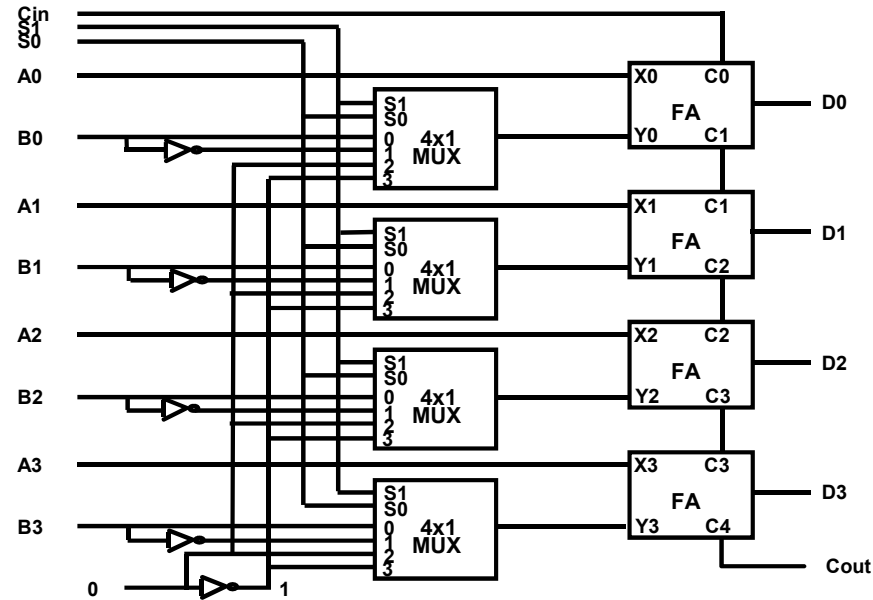
### Summary of Typical Arithmetic Micro-Operations

$R3 \leftarrow R1 + R2$	Contents of R1 plus R2 transferred to R3
$R3 \leftarrow R1 - R2$	Contents of R1 minus R2 transferred to R3
$R2 \leftarrow R2'$	Complement the contents of R2
$R2 \leftarrow R2' + 1$	2's complement the contents of R2 (negate)
$R3 \leftarrow R1 + R2' + 1$	subtraction
$R1 \leftarrow R1 + 1$	Increment
$R1 \leftarrow R1 - 1$	Decrement

# BINARY ADDER / SUBTRACTOR / INCREMENTER

**Binary Adder****Binary Adder-Subtractor****Binary Incrementer**

# ARITHMETIC CIRCUIT



S1	S0	Cin	Y	Output	Microoperation
0	0	0	B	$D = A + B$	Add
0	0	1	B	$D = A + B + 1$	Add with carry
0	1	0	B'	$D = A + B'$	Subtract with borrow
0	1	1	B'	$D = A + B' + 1$	Subtract
1	0	0	0	$D = A$	Transfer A
1	0	1	0	$D = A + 1$	Increment A
1	1	0	1	$D = A - 1$	Decrement A
1	1	1	1	$D = A$	Transfer A

## LOGIC MICROOPERATIONS

- **Specify binary operations on the strings of bits in registers**
  - Logic microoperations are bit-wise operations, i.e., they work on the individual bits of data
  - useful for bit manipulations on binary data
  - useful for making logical decisions based on the bit value
- **There are, in principle, 16 different logic functions that can be defined over two binary input variables**

A	B	F <sub>0</sub>	F <sub>1</sub>	F <sub>2</sub>	...	F <sub>13</sub>	F <sub>14</sub>	F <sub>15</sub>
0	0	0	0	0	...	1	1	1
0	1	0	0	0	...	1	1	1
1	0	0	0	1	...	0	1	1
1	1	0	1	0	...	1	0	1

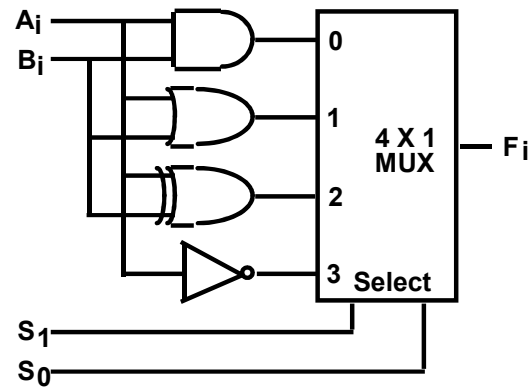
- **However, most systems only implement four of these**
  - AND ( $\wedge$ ), OR ( $\vee$ ), XOR ( $\oplus$ ), Complement/NOT
- **The others can be created from combination of these**

## LIST OF LOGIC MICROOPERATIONS

- Truth tables for 16 functions of 2 variables and the corresponding 16 logic micro-operations

x	y	Boolean Function	Micro-Operations	Name
0	0	$F_0 = 0$	$F \leftarrow 0$	Clear
0	0	$F_1 = xy$	$F \leftarrow A \wedge B$	AND
0	0	$F_2 = xy'$	$F \leftarrow A \wedge B'$	
0	0	$F_3 = x$	$F \leftarrow A$	Transfer A
0	1	$F_4 = x'y$	$F \leftarrow A' \wedge B$	
0	1	$F_5 = y$	$F \leftarrow B$	Transfer B
0	1	$F_6 = x \oplus y$	$F \leftarrow A \oplus B$	Exclusive-OR
0	1	$F_7 = x + y$	$F \leftarrow A \vee B$	OR
1	0	$F_8 = (x + y)'$	$F \leftarrow (A \vee B)'$	NOR
1	0	$F_9 = (x \oplus y)'$	$F \leftarrow (A \oplus B)'$	Exclusive-NOR
1	0	$F_{10} = y'$	$F \leftarrow B'$	Complement B
1	0	$F_{11} = x + y'$	$F \leftarrow A \vee B$	
1	1	$F_{12} = x'$	$F \leftarrow A'$	Complement A
1	1	$F_{13} = x' + y$	$F \leftarrow A' \vee B$	
1	1	$F_{14} = (xy)'$	$F \leftarrow (A \wedge B)'$	NAND
1	1	$F_{15} = 1$	$F \leftarrow \text{all 1's}$	Set to all 1's

## HARDWARE IMPLEMENTATION OF LOGIC MICROOPERATIONS



**Function table**

$S_1$	$S_0$	Output	$\mu$ -operation
0	0	$F = A \wedge B$	AND
0	1	$F = A \vee B$	OR
1	0	$F = A \oplus B$	XOR
1	1	$F = A'$	Complement



# Special Symbols

Special symbols will be adopted for the logic microoperations OR, AND, and complement, to distinguish them from the corresponding symbols used to express Boolean functions. The symbol  $\vee$  will be used to denote an OR microoperation and the symbol  $\wedge$  to denote an AND microoperation. The complement microoperation is the same as the 1's complement and uses a bar on top of the symbol that denotes the register name. By using different symbols, it will be possible to differentiate between a logic microoperation and a control (or Boolean) function. Another reason for adopting two sets of symbols is to be able to distinguish the symbol  $+$ , when used to symbolize an arithmetic plus, from a logic OR operation. Although the  $+$  symbol has two meanings, it will be possible to distinguish between them by noting where the symbol occurs. When the symbol  $+$  occurs in a microoperation, it will denote an arithmetic plus. When it occurs in a control (or Boolean) function, it will denote an OR operation. We will never use it to symbolize an OR microoperation. For example, in the statement

$$P + Q: R1 \leftarrow R2 + R3, R4 \leftarrow R5 \vee R6$$

the  $+$  between  $P$  and  $Q$  is an OR operation between two binary variables of a control function. The  $+$  between  $R2$  and  $R3$  specifies an add microoperation. The OR microoperation is designated by the symbol  $\vee$  between registers  $R5$  and  $R6$ .

## APPLICATIONS OF LOGIC MICROOPERATIONS

- Logic microoperations can be used to manipulate individual bits or a portions of a word in a register
- Consider the data in a register A. In another register, B, is bit data that will be used to modify the contents of A

- |                        |                                |
|------------------------|--------------------------------|
| – Selective-set        | $A \leftarrow A + B$           |
| – Selective-complement | $A \leftarrow A \oplus B$      |
| – Selective-clear      | $A \leftarrow A \cdot B'$      |
| – Mask (Delete)        | $A \leftarrow A \cdot B$       |
| – Clear                | $A \leftarrow A \oplus B$      |
| – Insert               | $A \leftarrow (A \cdot B) + C$ |
| – Compare              | $A \leftarrow A \oplus B$      |
| – . . .                |                                |

## SELECTIVE SET

- In a selective set operation, the bit pattern in B is used to set certain bits in A

$$\begin{array}{rcl} 1\ 1\ 0\ 0 & A_t & \\ 1\ 0\ 1\ 0 & B & \\ \hline 1\ 1\ 1\ 0 & A_{t+1} & (A \leftarrow A + B) \end{array}$$

- If a bit in B is set to 1, that same position in A gets set to 1, otherwise that bit in A keeps its previous value

## SELECTIVE COMPLEMENT

- In a selective complement operation, the bit pattern in B is used to *complement* certain bits in A

1 1 0 0	$A_t$	
1 0 1 0	B	
<hr/>		
0 1 1 0	$A_{t+1}$	$(A \leftarrow A \oplus B)$

- If a bit in B is set to 1, that same position in A gets complemented from its original value, otherwise it is unchanged

## SELECTIVE CLEAR

- In a selective clear operation, the bit pattern in B is used to *clear* certain bits in A

$$\begin{array}{rcl} 1\ 1\ 0\ 0 & A_t & \\ 1\ 0\ 1\ 0 & B & \\ \hline 0\ 1\ 0\ 0 & A_{t+1} & (A \leftarrow A \cdot B') \end{array}$$

- If a bit in B is set to 1, that same position in A gets set to 0, otherwise it is unchanged

## MASK OPERATION

- In a mask operation, the bit pattern in B is used to *clear* certain bits in A

$$\begin{array}{rcl} 1\ 1\ 0\ 0 & A_t & \\ 1\ 0\ 1\ 0 & B & \\ \hline 1\ 0\ 0\ 0 & A_{t+1} & (A \leftarrow A \cdot B) \end{array}$$

- If a bit in B is set to 0, that same position in A gets set to 0, otherwise it is unchanged

## CLEAR OPERATION

- In a clear operation, if the bits in the same position in A and B are the same, they are cleared in A, otherwise they are set in A

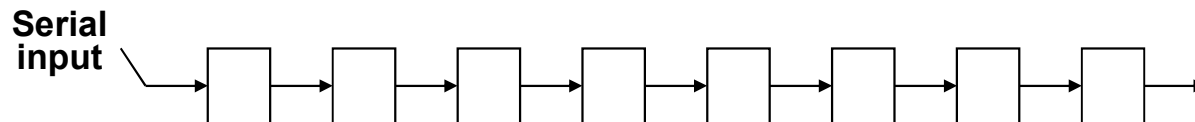
1 1 0 0	$A_t$	
1 0 1 0	B	
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0 1 1 0	$A_{t+1}$	$(A \leftarrow A \oplus B)$



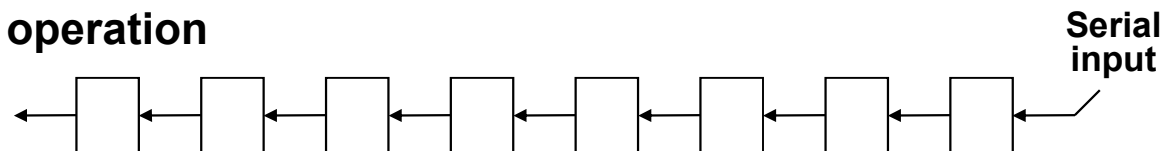


## SHIFT MICROOPERATIONS

- There are three types of shifts
  - *Logical shift*
  - *Circular shift*
  - *Arithmetic shift*
- What differentiates them is the information that goes into the serial input
- A right shift operation

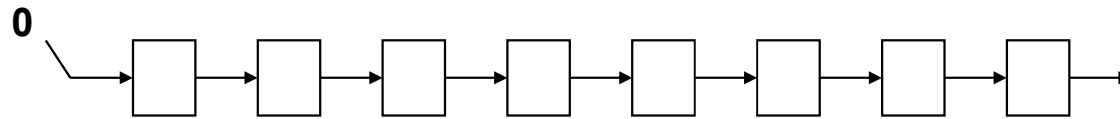


- A left shift operation

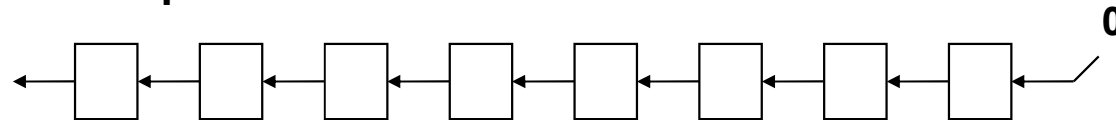


## LOGICAL SHIFT

- In a logical shift the serial input to the shift is a 0.
- A right logical shift operation:



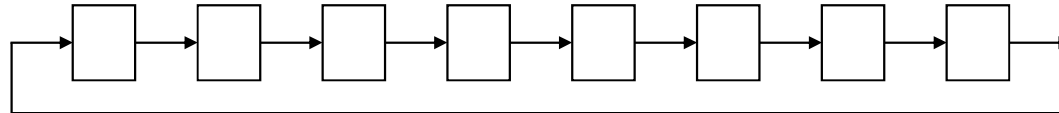
- A left logical shift operation:



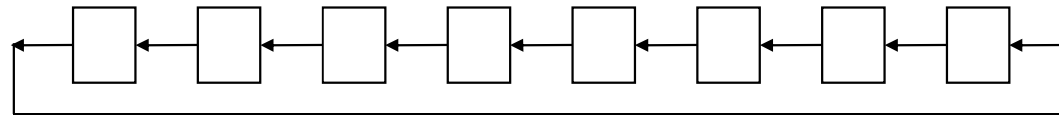
- In a Register Transfer Language, the following notation is used
  - *shl* for a logical shift left
  - *shr* for a logical shift right
  - Examples:
    - »  $R2 \leftarrow shr\ R2$
    - »  $R3 \leftarrow shl\ R3$

## CIRCULAR SHIFT

- In a circular shift the serial input is the bit that is shifted out of the other end of the register.
- A right circular shift operation:



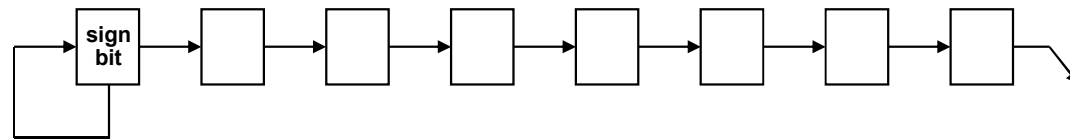
- A left circular shift operation:



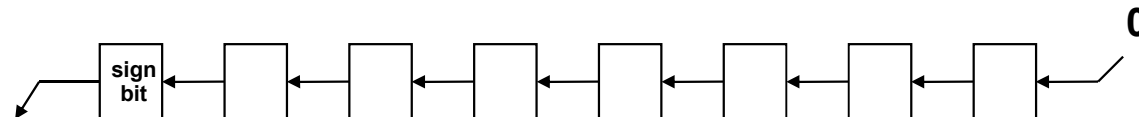
- In a RTL, the following notation is used
  - *cil* for a circular shift left
  - *cir* for a circular shift right
  - Examples:
    - »  $R2 \leftarrow cir\ R2$
    - »  $R3 \leftarrow cil\ R3$

## ARITHMETIC SHIFT

- An arithmetic shift is meant for signed binary numbers (integer)
  - An arithmetic left shift **multiplies** a signed number **by two**
  - An arithmetic right shift **divides** a signed number **by two**
  - The main distinction of an arithmetic shift is that it must keep the sign of the number the same as it performs the multiplication or division
- 
- A right arithmetic shift operation:

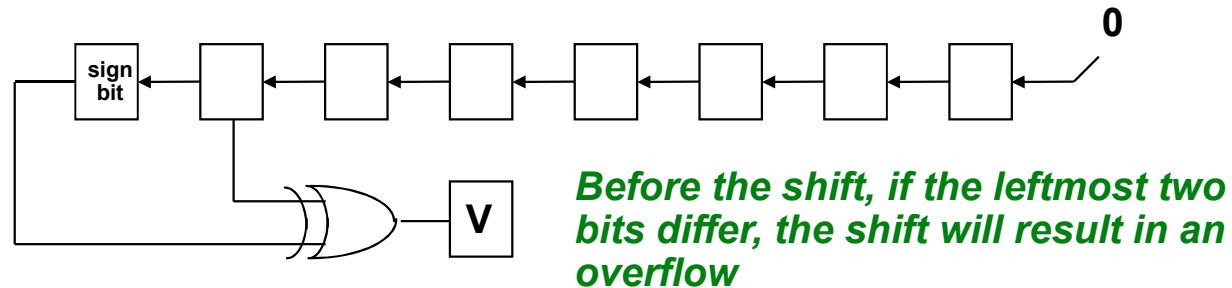


- A left arithmetic shift operation:



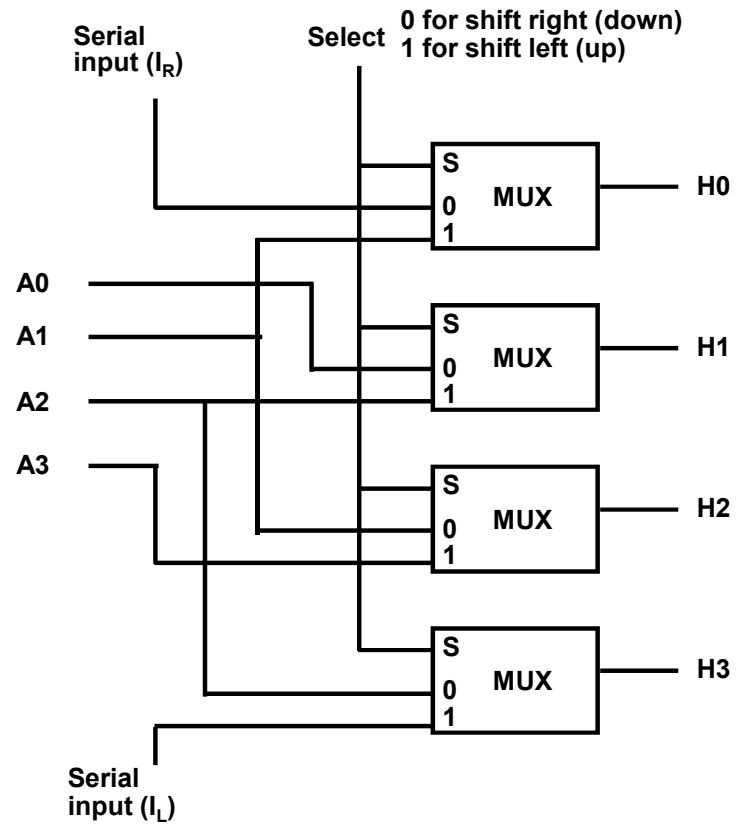
## ARITHMETIC SHIFT

- An left arithmetic shift operation must be checked for the **overflow**

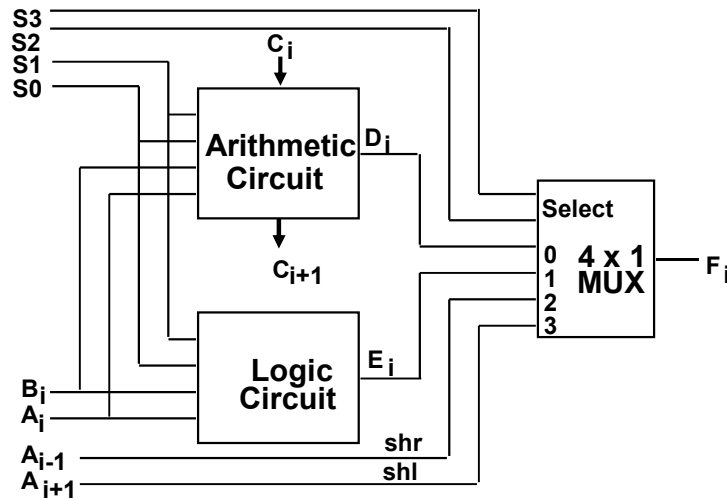


- In a RTL, the following notation is used
  - *ashl* for an arithmetic shift left
  - *ashr* for an arithmetic shift right
  - Examples:
    - »  $R2 \leftarrow ashr R2$
    - »  $R3 \leftarrow ashl R3$

## HARDWARE IMPLEMENTATION OF SHIFT MICROOPERATIONS



# ARITHMETIC LOGIC SHIFT UNIT



Truth Table of Arithmetic Circuit

S1	S0	Cin	Y	Output	Microoperation
0	0	0	B	$D = A + B$	Add
0	0	1	B	$D = A + B + 1$	Add with carry
0	1	0	$B'$	$D = A + B'$	Subtract with borrow
0	1	1	$B'$	$D = A + B' + 1$	Subtract
1	0	0	0	$D = A$	Transfer A
1	0	1	0	$D = A + 1$	Increment A
1	1	0	1	$D = A - 1$	Decrement A
1	1	1	1	$D = A$	Transfer A

Truth Table of Logic Circuit

$S_1$	$S_0$	Output	$\mu$ -operation
0	0	$F = A \wedge B$	AND
0	1	$F = A \vee B$	OR
1	0	$F = A \oplus B$	XOR
1	1	$F = A'$	Complement

Truth Table of  
Arithmetic Logic Shift  
Unit

S3	S2	S1	S0	Cin	Operation	Function
0	0	0	0	0	$F = A$	Transfer A
0	0	0	0	1	$F = A + 1$	Increment A
0	0	0	1	0	$F = A + B$	Addition
0	0	0	1	1	$F = A + B + 1$	Add with carry
0	0	1	0	0	$F = A + B'$	Subtract with borrow
0	0	1	0	1	$F = A + B' + 1$	Subtraction
0	0	1	1	0	$F = A - 1$	Decrement A
0	0	1	1	1	$F = A$	Transfer A
0	1	0	0	X	$F = A \wedge B$	AND
0	1	0	1	X	$F = A \vee B$	OR
0	1	1	0	X	$F = A \oplus B$	XOR
0	1	1	1	X	$F = A'$	Complement A
1	0	X	X	X	$F = \text{shr } A$	Shift right A into F
1	1	X	X	X	$F = \text{shl } A$	Shift left A into F

# Previous GTU Questions

**2015**

- Explain how complement number system is useful in computer system. Discuss any one complement number system with example. 07
- Define RTL. Explain how register transfer takes place in basic computer system 07
- What is a micro operation? List and explain its categories. 07
- What do you mean by register transfer? Explain in detail. Also discuss three-state bus buffer.



## 2016

- Represent the following conditional control statement(s) by two register transfer statements with control function. If ( $P = 1$ ) then ( $R1 \leq R2$ ) else if ( $Q=1$ ) then ( $R1 \leq R3$ )
- Which information is stored by Program Counter (PC)?
- State true or false: With floating point numbers, the divide overflow imposes no problem(s).
- State true or false: In binary number system,  $B - A$  is equivalent to  $B + \bar{A} + 1$ .
- Design a digital circuit for 4-bit binary adder. 03
- Explain hardware implementation of common bus system using three- 04 2 state buffers. Mention assumptions if required
- Draw and explain flowchart for addition and subtraction operations with sign-magnitude data.

## 2017

- Define term RTL.
- What is PSW (flag)
- What is computer organization?
- Explain Accumulator.
- Explain Micro operation.
- Explain Gray Code. 03
- Explain BCD Adder with its block diagram 07
- Write down RTL statements for the fetch and decode operation of basic computer. 03
- Explain how  $(r-1)$ 's complement is calculated. Calculate 9's complement of 546700.
- Define RTL. Give block diagram and timing diagram of transfer of R1 to R2 when  $P=1$ .
- Explain BCD adder with diagram. 07
- Define RTL. Give an example of register transfer of data through accumulator. 04
- Explain the role of tri-state buffer with example. 03
- What is multiplexing? Explain the multiplexing of control signals in ALU. 07
- List and explain types of shift operations on accumulator. 07
- What is PSW? Explain each bit of it. 03

## **2018**

1. How negative integer number represented in memory? Explain with suitable example
2. Explain floating point representation. 04
3. Explain shift micro operations and Draw neat and clean diagram for 4- bit combinational circuit shifter
4. Explain the significance of every bit of Program Status Word (PSW). 04
5. Represent  $(8620)_{10}$  in (1) binary (2) Excess-3 code and (3) 2421 code. 03
6. Explain 4-bit adder-subtractor with diagram. 04
7. Explain selective set, selective complement and selective clear. 03
8. Draw the block diagram of 4-bit arithmetic circuit and explain it in detail. 07
9. Explain logical shift, circular shift and arithmetic shift micro operations. 03
10. Explain Three-state bus buffer. 03
11. Explain BCD adder in brief. 04

### **2019**

1. What is Tri-State buffer? Why it is useful to form a bus system?
2. Explain arithmetic shift left operation. Describe how overflow is handled
3. Explain BCD adder with diagram. 07

### **2020**

1. What is combinational circuit? Explain multiplexer in detail. How many NAND gates are needed to implement 4 x 1 MUX
2. What is RAM and ROM? 03

### **2021**

1. What is PSW? Explain each bit of it 03
2. Design a digital circuit for 4-bit binary adder 03
3. Explain 4 bit arithmetic circuit with suitable diagram. 04
4. Explain BCD adder in brief 04
5. Explain hardware implementation of common bus system using threeState buffers. Mention assumptions if required. 04

**2022**

1. Explain three state buffers. 03
2. Construct a 4-bit adder-subtractor circuit. 04