[EEC3600-001] 수치해석		
소속: 전기전자공학부	학번: 12191529	이름: 장준영
Python Programming for Numerical Analysis		HW number: #3

- 3.1. (Matrix Condition) By evaluating the determinant, classify the following matrices as singular, ill conditione, or well conditioned:
 - a. 문제 내용

```
Problem 3.1 (Matrix condition) [Python only]

By evaluating the determinant, classify the following matrices as singular, ill conditioned, or well conditioned:

(a) \mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}

(b) \mathbf{A} = \begin{bmatrix} 2.11 & -0.80 & 1.72 \\ -1.84 & 3.03 & 1.29 \\ -1.57 & 5.25 & 4.30 \end{bmatrix}

(c) \mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}

(d) \mathbf{A} = \begin{bmatrix} 4 & 3 & -1 \\ 7 & -2 & 3 \\ 5 & -18 & 13 \end{bmatrix}
```

b. 파이썬 코드 및 결과

```
Code
    determinant(matrix):
     if len(matrix) == 1:
         return matrix[0][0]
     if len(matrix) == 2:
         return matrix[0][0]*matrix[1][1] - matrix[0][1]*matrix[1][0]
    det = 0
    for c in range(len(matrix)):
         minor = [row[:c] + row[c+1:] for row in matrix[1:]]
         det += ((-1) ** c) * matrix[0][c] * determinant(minor)
    return det
A_list = {
    'a': [[1, 2, 3], [2, 3, 4], [3, 4, 5]],
'b': [[2.11, -0.80, 1.72], [-1.84, 3.03, 1.29], [-1.57, 5.25, 4.30]],
'c': [[2, -1, 0], [-1, 2, -1], [0, -1, 2]],
'd': [[4, 3, -1], [7, -2, 3], [5, -18, 13]]
threshold = 1e-1
for key, mat in A_list.items():
    det = determinant(mat)
    print(f"Matrix {key}: Determinant = {det:.6f}", end=' -> ')
    if abs(det) < 1e-10:
print("Singular")
    elif abs(det) < threshold:</pre>
        print("Ill-conditioned")
         print("Well-conditioned")
```

Result

Matrix a: Determinant = 0.000000 -> Singular

Matrix b: Determinant = 0.058867 -> Ill-conditioned

Matrix c: Determinant = 4.000000 -> Well-conditioned

Matrix d: Determinant = 0.000000 -> Singular

c. 설명

: 라플라스 전개를 활용하여 각각의 행렬식을 구하였다(ill-contioned threshold 경계조건 = 0.1).

Problem 3.1 (Matrix condition) [Python only]

By evaluating the determinant, classify the following matrices as singular, ill conditioned, or

(a)
$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{bmatrix}$$

(b)
$$\mathbf{A} = \begin{bmatrix} 2.11 & -0.80 & 1.72 \\ -1.84 & 3.03 & 1.29 \\ -1.57 & 5.25 & 4.30 \end{bmatrix}$$

(c)
$$\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

(d)
$$\mathbf{A} = \begin{bmatrix} 4 & 3 & -1 \\ 7 & -2 & 3 \\ 5 & -18 & 13 \end{bmatrix}$$

(1)
$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{pmatrix}$$
 = (1) \cdot $\begin{pmatrix} -1 \end{pmatrix}^{(1)} \begin{pmatrix} 3 & 4 \\ 4 & 5 \end{pmatrix}$ + 2 \cdot $\begin{pmatrix} -1 \end{pmatrix}^{(1)} \begin{pmatrix} 2 & 4 \\ 3 & 5 \end{pmatrix}$ + 3 \cdot $\begin{pmatrix} -1 \end{pmatrix}^{(1)} \begin{pmatrix} 2 & 3 \\ 3 & 4 \end{pmatrix}$ = $\begin{pmatrix} -1 \\ -1 \end{pmatrix}$ - $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$ $\begin{pmatrix} -1 \\ 2 \end{pmatrix}$

(b)
$$\mathbf{A} = \begin{bmatrix} -1.84 & 3.03 & 1.29 \\ -1.57 & 5.25 & 4.30 \end{bmatrix}$$

(c) $\mathbf{A} = \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$
(2) $\begin{bmatrix} 2.11 & -0.80 & 1.02 \\ -1.84 & 3.07 & 1.29 \\ -1.59 & 5.25 & 4.30 \end{bmatrix}$
(2) $\begin{bmatrix} 2.11 & -0.80 & 1.02 \\ -1.84 & 3.07 & 1.29 \\ -1.59 & 5.25 & 4.30 \end{bmatrix}$

$$= (2.11)(-1)^{14} \begin{vmatrix} 3.03 & 1.29 \\ 5.25 & 4.20 \end{vmatrix} + (-0.86)(-1)^{142} \begin{vmatrix} -1.84 & 1.29 \\ -1.59 & 4.36 \end{vmatrix} + (1.92)(-1)^{143} \begin{vmatrix} -1.84 & 3.65 \\ -1.59 & 4.36 \end{vmatrix}$$

= 58.869 × 10-3 = 0.058869 (ill-conditioned)

(c)
$$\begin{pmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{pmatrix}$$

$$= (2) \cdot (-1)^{1+1} \begin{vmatrix} 2 & -1 \\ 0 & 2 \end{vmatrix} + (3)(-1)^{1+2} \begin{vmatrix} -1 & -1 \\ 0 & 2 \end{vmatrix}$$

$$= (4) \cdot (-1)^{104} \begin{vmatrix} 2 & -1 \\ -1 & 2 \end{vmatrix} + (4)(-1)^{102} \begin{vmatrix} -1 & -1 \\ 0 & 2 \end{vmatrix}$$

$$+ (0) \begin{vmatrix} -1 \\ -1 \end{vmatrix} \begin{vmatrix} 2 \\ 0 \end{vmatrix} - 1 \end{vmatrix}$$

$$= (4) \cdot (-1)^{104} \cdot \begin{vmatrix} -2 \\ -12 \end{vmatrix} \begin{vmatrix} 13 \\ 13 \end{vmatrix} + (5) \cdot (-1)^{102} \cdot \begin{vmatrix} 7 & 3 \\ 5 \end{vmatrix} \begin{vmatrix} 13 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} - 12 \end{vmatrix}$$

$$= (4) \cdot (-1)^{104} \cdot \begin{vmatrix} -2 \\ -12 \end{vmatrix} + (3) \cdot (-1)^{104} \cdot \begin{vmatrix} -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)(-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5 \end{vmatrix} + (-1)^{103} \cdot \begin{vmatrix} 7 & -2 \\ 5$$

(d)
$$\begin{pmatrix} 4 & 3 & -1 \\ 1 & -2 & 3 \\ 5 & -18 & 13 \end{pmatrix}$$

$$= (4) \cdot (-1)^{\frac{1}{2}+1} \cdot \begin{vmatrix} -2 & 3 \\ -12 & 13 \end{vmatrix} + (3) \cdot (-1)^{\frac{1}{2}+2} \cdot \begin{vmatrix} 1 & 3 \\ 5 & 13 \end{vmatrix} + (-1) \cdot (-1)^{\frac{1}{2}+3} \begin{vmatrix} 1 & -2 \\ 5 & -12 \end{vmatrix}$$

- 3.2. (Using LU factorization to solve a linear system) Use the results of LU decomposition to solve Ax=b:
 - a. 문제 내용

```
Problem 3.2 (Using LU factorization to solve a linear system) [Python & Hand-written] Use the results of LU decomposition \mathbf{A} = \mathbf{L}\mathbf{U} = \begin{bmatrix} 1 & 0 & 0 \\ 3/2 & 1 & 0 \\ 1/2 & 11/13 & 1 \end{bmatrix} \begin{bmatrix} 2 & -3 & -1 \\ 0 & 13/2 & -7/2 \\ 0 & 0 & 32/13 \end{bmatrix} to solve \mathbf{A}\mathbf{x} = \mathbf{b} where \mathbf{b} = \begin{bmatrix} 1 & -1 & 2 \end{bmatrix}^{\mathsf{T}}.
```

```
Code
      from fractions import Fraction
      # L과 U 행렬 (Fraction 사용)
          [Fraction(1), Fraction(0), Fraction(0)],
          [Fraction(1, 2), Fraction(11, 13), Fraction(1)]
          [Fraction(0), Fraction(0), Fraction(32, 13)]
      b = [Fraction(1), Fraction(-1), Fraction(2)]
      y = [Fraction(0) for _ in range(3)]
      y[0] = b[0]
      y[1] = b[1] - L[1][0] * y[0]
y[2] = b[2] - L[2][0] * y[0] - L[2][1] * y[1]
      print("Solution y =", y)
      x = [Fraction(0) for _ in range(3)]
      x[2] = y[2] / U[2][2]
      x[1] = (y[1] - U[1][2] * x[2]) / U[1][1]
      x[0] = (y[0] - U[0][1] * x[1] - U[0][2] * x[2]) / U[0][0]
      print("Solution x =", x)
                                Result
Solution y = [Fraction(1, 1), Fraction(-5, 2), Fraction(47, 13)]
Solution x = [Fraction(59, 32), Fraction(13, 32), Fraction(47, 32)]
```

Sol) O Forward substitution

$$\therefore Ly = b \longrightarrow \begin{pmatrix} 1 & 0 & 0 \\ 3/2 & 1 & 0 \\ 1/2 & 11/13 & 1 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} \qquad \therefore y_1 = 1 , \quad y_2 = -\frac{5}{2} , \quad y_3 = \frac{4n}{13}$$

: $\chi_1 = \frac{54}{32}$, $\chi_2 = \frac{13}{32}$, $\chi_3 = \frac{141}{32}$

3 Backward substitution

$$\frac{13}{2} x_2 - \frac{9}{2} x_{\frac{1}{32}} = -\frac{5}{2} ; x_2 = \frac{13}{32}$$

$$\frac{1}{3}2x_1 - \frac{39}{32} - \frac{49}{32} = |\frac{1}{3}2x_1 = |+\frac{16}{22} = \frac{118}{32}$$

- 3.3. (Gauss elimination to solve a linear system) Solve the equation AX=B by Gauss elimination:
 - a. 문제 내용

Problem 3.3 (Gauss elimination to solve a linear system) [Python only] Solve the equations $\mathbf{AX} = \mathbf{B}$ by Gauss elimination, where $\mathbf{A} = \begin{bmatrix} 2 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \\ -1 & 2 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix} \quad \mathbf{B} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$

```
def gauss_elimination_fraction(A, B):
    n = len(A)
    # Deep copy to avoid modifying input
    A = [[Fraction(A[i][j]) for j in range(n)] for i in range(n)]
    B = [[Fraction(B[i][j]) for j in range(len(B[0]))] for i in range(n)]
           for j in range(i + 1, n):
    factor = A[j][i] / A[i][i]
    for k in range(i, n):
        A[j][k] -= factor * A[i][k]
    for k in range(len(B[0])):
        B[j][k] -= factor * B[i][k]
           # Back Substitution
X = [[Fraction(0) for _ in range(len(B[0]))] for _ in range(n)]
for i in reversed(range(n)):
    for j in range(len(B[0])):
        total = sum(A[i][k] * X[k][j] for k in range(i + 1, n))
        X[i][j] = (B[i][j] - total) / A[i][i]
# A, B \begin{bmatrix} 2, 0, -1, 0 \end{bmatrix}, \begin{bmatrix} 0, 1, 2, 0 \end{bmatrix}, \begin{bmatrix} -1, 2, 0, 1 \end{bmatrix}, \begin{bmatrix} 0, 0, 1, -2 \end{bmatrix}
B = [
 [1, 0],
 [0, 0],
 [0, 1],
 [0, 0]
X = gauss_elimination_fraction(A, B)
print("Solution X (as fractions):")
 for row in X:
    print([str(val) for val in row])
                                                                                            Code
```

Result

c. 설명

$$\begin{array}{c}
\text{sol} \\
\text{O} \\
\text{I} \\
\text{I} \\
\text{O} \\
\text{I} \\
\text{I} \\
\text{O} \\
\text{I} \\$$

- 3.4. (LU and Choleski's factorization) Find L and U so that using (a) Doolittle's decomposition; (b) Choleski's decomposition:
 - a. 문제 내용

```
Problem 3.4 (LU and Choleski's factorization) [Python & Hand-written] Find L and U so that \mathbf{A} = \mathbf{L}\mathbf{U} = \begin{bmatrix} 4 & -1 & 0 \\ -1 & 4 & -1 \\ 0 & -1 & 4 \end{bmatrix} using (a) Doolittle's decomposition; (b) Choleski's decomposition.
```

```
Code
       15 # (a) Doolittle's LU decomposition (Fraction)
          def doolittle fraction(A):
              n = A.shape[0]
              L = np.array([[Fraction(0) for in range(n)] for in range(n)])
              U = np.array([[Fraction(0) for in range(n)] for in range(n)])
              for i in range(n):
                 L[i][i] = Fraction(1)
                 for j in range(i, n):
                    U[i][j] = A[i][j] - sum(L[i][k]*U[k][j]  for k in range(i))
                 for j in range(i+1, n):
                    L[j][i] = (A[j][i] - sum(L[j][k]*U[k][i] \text{ for } k \text{ in } range(i))) / U[i][i]
                                     Result
(a)
       === Doolittle LU Decomposition (Fraction) ===
       L =
       [[Fraction(1, 1) Fraction(0, 1) Fraction(0, 1)]
        [Fraction(-1, 4) Fraction(1, 1) Fraction(0, 1)]
        [Fraction(0, 1) Fraction(-4, 15) Fraction(1, 1)]]
       U =
       [[Fraction(4, 1) Fraction(-1, 1) Fraction(0, 1)]
        [Fraction(0, 1) Fraction(15, 4) Fraction(-1, 1)]
         [Fraction(0, 1) Fraction(0, 1) Fraction(56, 15)]]
       LU =
       [[Fraction(4, 1) Fraction(-1, 1) Fraction(0, 1)]
        [Fraction(-1, 1) Fraction(4, 1) Fraction(-1, 1)]
         [Fraction(0, 1) Fraction(-1, 1) Fraction(4, 1)]]
```

```
Code
            def choleski(A_float):
                A = A_float.copy()
                n = len(A)
                for k in range(n):
                       A[k, k] = math.sqrt(A[k, k] - np.dot(A[k, :k], A[k, :k]))
                       raise ValueError("Matrix is not positive definite")
                    for i in range(k+1, n):
                       A[i, k] = (A[i, k] - np.dot(A[i, :k], A[k, :k])) / A[k, k]
                for k in range(1, n):
                   A[:k, k] = 0.0
            def choleskiSol(L, b):
                n = len(b)
                # [L]{y} = {b}
for k in range(n):
(b)
       64
       65
                   b[k] = (b[k] - np.dot(L[k, :k], b[:k])) / L[k, k]
                for k in range(n-1, -1, -1):
                   b[k] = (b[k] - np.dot(L[k+1:n, k], b[k+1:n])) / L[k, k]
                                        Result
         === Choleski Decomposition (Float) ===
         L =
          [[ 2.
                               0.
                                                 0.
           [-0.5]
                               1.93649167
                                                 0.
           [ 0.
                              -0.51639778 1.93218357]]
         L @ L.T =
          [[ 4. -1. 0.]
           [-1. 4. -1.]
           [ 0. -1. 4.]]
```

(a) Doolittle

(b)

(b) Chokski

$$A = LL^{T} = \begin{bmatrix} l_{11} & 0 & 0 \\ l_{21} & l_{22} & 0 \\ l_{21} & l_{22} & l_{23} \end{bmatrix} \begin{bmatrix} l_{11} & l_{21} & l_{21} \\ 0 & l_{22} & l_{22} \\ 0 & 0 & l_{22} \end{bmatrix} = \begin{bmatrix} l_{11}^{*} & l_{11}l_{21} & l_{11}l_{21} \\ l_{11}l_{21} & l_{21}l_{21} + l_{22}l_{22} \\ l_{11}l_{21} & l_{21}l_{21} + l_{22}l_{22} \end{bmatrix}$$

$$\mathbb{O} l_{11} = \overline{|A_{11}|} = 2 \implies l_{21} = \frac{A_{21}}{l_{11}} = -\frac{1}{2}, \quad l_{31} = \frac{A_{31}}{l_{41}} = 0$$

- 3.5. (Interpolation as a linear system solution) Determine the coefficients of the polynomial $y = a_0 + a_1x + a_2x^2 + a_3x^3$ that passes through the points (0,10), (1,35), (3,31), and (4,2).
 - a. 문제 내용

```
Problem 3.5 (Interpolation as a linear system solution) [Python & Hand-written]

Determine the coefficients of the polynomial y = a_0 + a_1x + a_2x^2 + a_3x^3 that passes through the points (0, 10), (1, 35), (3, 31), and (4, 2).
```

```
Code
   import numpy as np
   from fractions import Fraction
   points = [(0, 10), (1, 35), (3, 31), (4, 2)]
     A.append([Fraction(1), Fraction(x), Fraction(x^{**2}), Fraction(x^{**3})])
     b.append(Fraction(y))
  A = np.array(A)
b = np.array(b)
  coefficients = np.linalg.solve(A.astype(np.float64), b.astype(np.float64))
  print("=== Coefficients of the polynomial ===")
  print(f"a_{i} = {coef:.5f}")
  Result
=== Coefficients of the polynomial ===
a 0 = 10.00000
a 1 = 34.000000
a 2 = -9.000000
a_3 = 0.000000
Polynomial:
y = 10.000 + 34.000*x^1 + -9.000*x^2 + 0.000*x^3
```

- 3.6. (Gauss elimination for a complex linear system) What we learned also works with complex numbers. Use it (any one of what we studied in class) to solve Ax = b, where:
 - a. 문제 내용

```
Problem 3.6 (Gauss elimination for a complex linear system) [Python only]

What we learned also works with complex numbers. Use it (any one of what we studied in class) to solve \mathbf{A}\mathbf{x} = \mathbf{b}, where

\mathbf{A} = \begin{bmatrix} 5+i & 5+2i & -5+3i & 6-3i \\ 5+2i & 7-2i & 8-i & -1+3i \\ -5+3i & 8-i & -3-3i & 2+2i \\ 6-3i & -1+3i & 2+2i & 8+14i \end{bmatrix}
\mathbf{b} = \begin{bmatrix} 15-35i & 2+10i & -2-34i & 8+14i \end{bmatrix}^{\mathsf{T}}
```

```
Code
import numpy as np
def gauss elimination complex(A, b):
   A = A.astype(complex) # ensure complex type
   b = b.astype(complex)
   n = len(b)
    # Forward elimination
    for k in range(n):
        # Pivoting (partial, complex-compatible)
        max row = np.argmax(np.abs(A[k:, k])) + k
        if max row != k:
            A[[k, max_row]] = A[[max_row, k]]
            b[[k, max_row]] = b[[max_row, k]]
        for i in range(k + 1, n):
            factor = A[i, k] / A[k, k]
            A[i, k:] -= factor * A[k, k:]
            b[i] -= factor * b[k]
   x = np.zeros(n, dtype=complex)
    for i in reversed(range(n)):
        x[i] = (b[i] - np.dot(A[i, i + 1:], x[i + 1:])) / A[i, i]
    return x
A = np.array([
    [-5+3j, 8-1j, -3-3j, 2+2j],
   [6-3j, -1+3j, 2+2j, 8+14j]
], dtype=complex)
```

```
8 b = np.array([15 - 35j, 2 + 10j, -2 - 34j, 8 + 14j], dtype=complex)

8 # Solve the system

8 x = gauss_elimination_complex(A, b)

40 # 출력
42 for i, val in enumerate(x, 1):
43 print(f"x{i} = {val:.6f}")

Result

x1 = 2.401493+0.085197j
x2 = 0.174940-4.004007j
x3 = -0.576107+4.089776j
x4 = 0.209850+0.774904j
```

: 복소수 가우스 소거법을 사용한 후, Back Substitution을 사용하여 해를 구하였다.

- 3.7. (Random matrices and Gauss elimination) Test the function gaussElimin by solving Ax = b, where A is a $n \times n$ random matrix and $b_{ij} = \sum_{j=1}^{n} A_{ij}$ (sum of the elements in the i^{th} row of A). A random matrix can be generated with the rand function in the numpy.random module:
 - a. 문제 내용

```
Problem 3.7 (Random matrices and Gauss elimination) [Python only]

Test the function gaussElimin by solving \mathbf{A}\mathbf{x} = \mathbf{b}, where \mathbf{A} is a n \times n random matrix and b_i = \sum_{j=1}^n A_{ij} (sum of the elements in the i th row of \mathbf{A}). A random matrix can be generated with the rand function in the numpy random module:

from numpy random import ran \mathbf{a} = \text{rand}(\mathbf{n}, \mathbf{n})

The solution should be x = \begin{bmatrix} 1 & 1 & \cdots & 1 \end{bmatrix}^{\mathsf{T}}. Run the program with n = 200 or bigger.
```

```
Code
import numpy as np
def gaussElimin(A, b):
    A = A.astype(float)
    b = b.astype(float)
    n = len(b)
    for k in range(n):
       max_row = np.argmax(np.abs(A[k:, k])) + k
        if max row != k:
           A[[k, max_row]] = A[[max_row, k]]
            b[[k, max_row]] = b[[max_row, k]]
        for i in range(k+1, n):
           factor = A[i, k] / A[k, k]
            A[i, k:] -= factor * A[k, k:]
            b[i] -= factor * b[k]
    x = np.zeros(n)
    for i in reversed(range(n)):
        x[i] = (b[i] - np.dot(A[i, i+1:], x[i+1:])) / A[i, i]
    return x
```

```
def test_gaussElimin(n=200, seed=42):
       np.random.seed(seed) # 재현성을 위해 시드 고정
       A = np.random.rand(n, n)
       b = np.sum(A, axis=1) # 각 행의 합 -> x = [1, 1, ..., 1]이 해가 되게 함
       x = gaussElimin(A.copy(), b.copy())
       expected = np.ones(n)
       error = np.linalg.norm(x - expected)
36
       print(f"으차 = {error:.6e}")
       if error < 1e-6:
           print("정답과 거의 일치합니다.")
           print("오차가 큽니다. 수치 안정성 확인 필요.")
    test_gaussElimin(n=200)
                                Result
                   오차 = 5.290811e-13
                   정답과 거의 일치합니다.
```

- : 이 테스트는 b를 "특별하게" 만들어서 해가 모두 1인 벡터가 되도록 설계함.
- 1) 랜덤 행렬 생성 (테스트 입력 구성)
 - : A = np.random.rand(n, n), b = np.sum(A, axis=1)
- 2) 가우스 소거법 수행 (gaussElimin)
- 3) 해 비교 및 오차 출력
 - : 정답 벡터(expected = np.ones(n)), 실제 해와의 차이 계산 (error = np.linalg.norm(x expected))

- 3.8. (Matrix condition number) Write a function that returns the condition number of a matrix based on the euclidean norm. Test the function by computing the condition number of the ill-conditioned matrix. Use the function inv(A) in numpy.linalg to determine the inverse of A.
 - a. 문제 내용

```
Problem 3.8 (Matrix condition number) [Python only]
```

Write a function that returns the condition number of a matrix based on the euclidean norm. Test the function by computing the condition number of the ill-conditioned matrix:

$$\mathbf{A} = \begin{bmatrix} 1 & 4 & 9 & 16 \\ 4 & 9 & 16 & 25 \\ 9 & 16 & 25 & 36 \\ 16 & 25 & 36 & 49 \end{bmatrix}$$

Use the function inv(A) in numpy. linalg to determine the inverse of A.

```
Code
     import numpy as np
    # 주어진 ill-conditioned matrix
    A = np.array([
        [1, 4, 9, 16],
        [4, 9, 16, 25],
        [9, 16, 25, 36],
        [16, 25, 36, 49]
     ], dtype=float)
     # (1) Condition number 함수 직접 구현
     def condition number(A):
        A norm = np.linalg.norm(A, 2)
        A inv = np.linalg.inv(A)
        A inv norm = np.linalg.norm(A inv, 2)
        cond = A norm * A inv norm
         return A norm, A inv, A inv norm, cond
    # (2) 함수 호출
     A_norm, A_inv, A_inv_norm, cond_custom = condition_number(A)
20
     cond numpy = np.linalg.cond(A, 2)
21
```

```
Result
=== Condition Number Analysis ===
Matrix A:
[[ 1. 4. 9. 16.]
[ 4. 9. 16. 25.]
 [ 9. 16. 25. 36.]
[16. 25. 36. 49.]]
2-Norm of A:
9.01480e+01
Inverse of A:
[[ 4.69124961e+13 -1.40737488e+14 1.40737488e+14 -4.69124961e+13]
[-1.40737488e+14 4.22212465e+14 -4.22212465e+14 1.40737488e+14]
 [ 1.40737488e+14 -4.22212465e+14 4.22212465e+14 -1.40737488e+14]
[-4.69124961e+13 1.40737488e+14 -1.40737488e+14 4.69124961e+13]]
2-Norm of A-inverse:
9.38250e+14
Condition Number (Custom):
8.45813e+16
Condition Number (NumPy built-in):
cond(A) = 5.34183e+16
```

c. 코드 설명

- $\kappa(A) = ||A||_2 \cdot ||A^{-1}||_2$
- $\|A\|_2 = \sigma_{max}(A) = \sqrt{\lambda_{max}(A^TA)}$, $\|A^{-1}\|_2 = \frac{1}{\sigma_{min}(A)} = \frac{1}{\sqrt{\lambda_{min}(A^TA)}}$ 방법을 통해 연산 복잡도를 더 간단히 할 수 있으나, 이번 과제에서는 역행렬을 직접 구하여보는 쪽으로 코드를 작성하였다.

- 3.9. (Solving a linear system with a tridiagonal coefficient matrix) Solve the tridiagonal equations Ax = b by Doolittle's decomposition method, where:
 - a. 문제 내용

```
Problem 3.9 (Solving a linear system with a tridiagonal coefficient matrix)

Solve the tridiagonal equations \mathbf{A}\mathbf{x} = \mathbf{b} by Doolittle's decomposition method, where

\mathbf{A} = \begin{bmatrix} 6 & 2 & 0 & 0 & 0 \\ -1 & 7 & 2 & 0 & 0 \\ 0 & -2 & 8 & 2 & 0 \\ 0 & 0 & 3 & 7 & -2 \\ 0 & 0 & 0 & 3 & 5 \end{bmatrix} \quad \mathbf{b} = \begin{bmatrix} 2 \\ -3 \\ 4 \\ -3 \\ 1 \end{bmatrix}
```

```
Code
            rom fractions import Fraction
           import numpy as np
          def LUdecomp3_full(c_in, d_in, e_in):
                 n = len(d_in)
                 # 원본 보존을 위해 복사
c = c_in.copy()
                 d = d_{in.copy()}
                 e = e_in.copy()
                 # LU 병합 저장용
                  L = np.eye(n, dtype=object)
                 U = np.zeros((n, n), dtype=object)
                  for k in range(n):
                         if k == 0:
                                U[k][k] = d[k]
U[k][k+1] = e[k]
                                e:

L[k][k-1] = c[k-1] / d[k-1]

d[k] = d[k] - L[k][k-1] * e[k-1]

U[k-1][k] = e[k-1]
                                 U[k][k] = d[k]
        def LUdecomp3(c, d, e):
             n = len(d)
             f = len(u)
for k in range(1, n):
    lam = c[k-1] / d[k-1]
    d[k] = d[k] - lam * e[k-1]
    c[k-1] = lam
return c, d, e
       # LU 해법
38
        def LUsolve3(c, d, e, b):
             n = len(d)
             for k in range(1, n):

| b[k] -= c[k-1] * b[k-1]

b[n-1] = b[n-1] / d[n-1]

for k in range(n-2, -1, -1):

| b[k] = (b[k] - e[k] * b[k+1]) / d[k]
              return b
       # 입력 (분수로 표현)
c = [Fraction(-1), Fraction(-2), Fraction(3), Fraction(3)] # sub-diagonal
d = [Fraction(6), Fraction(7), Fraction(8), Fraction(7), Fraction(5)] # main
e = [Fraction(2), Fraction(2), Fraction(-2)] # super
b = [Fraction(2), Fraction(-3), Fraction(4), Fraction(-3), Fraction(1)] # RHS
       L, U = LUdecomp3_full(c.copy(), d.copy(), e.copy())
```

```
# LU 분해 (값 반영)
      c, d, e = LUdecomp3(c, d, e)
      x = LUsolve3(c, d, e, b.copy())
    print("=== L 행렬 ===")
      for row in L:
        print([str(val) for val in row])
     print("\n=== U 행렬 ===")
      for row in U:
         print([str(val) for val in row])
     print("\n=== 해 x (분수 기반) ===")
      for i, xi in enumerate(x):
          print(f"x[\{i\}] = \{xi\} \quad (approx. \ \{float(xi):.4f\})")
                                       Result
=== L 행렬 ===
['1', '0', '0', '0', '0']
['-1/6', '1', '0', '0', '0']
['0', '-3/11', '1', '0', '0']
['0', '0', '33/94', '1', '0']
['0', '0', '0', '141/296', '1']
=== U 행렬 ===
['6', '2', '0', '0', '0']
['0', '22/3', '2', '0', '0']
['0', '0', '94/11', '2', '0']
['0', '0', '0', '296/47', '-2']
['0', '0', '0', '0', '881/148']
=== 해 x (분수 기반) ===
x[0] = 1/2 (approx. 0.5000)
x[1] = -1/2 (approx. -0.5000)
x[2] = 1/2 (approx. 0.5000)
x[3] = -1/2 (approx. -0.5000)
x[4] = 1/2 (approx. 0.5000)
```

: 위 과정은 Doolittle's Method를 Tridiagonal Matrix LU decomposition 방법에 최적화하여 LU 분해를 한 과정이다. 이후는 Forward Substitution, Backward Substitution을 통해 해를 구했다.

- 3.10. (Solving a linear system with a symmetric and tridiagonal coefficient matrix) Solve the symmetric, tridiagonal equations with n = 10:
 - a. 문제 내용

```
Problem 3.10 (Solving a linear system with a symmetric and tridiagonal coefficient matrix) Solve the symmetric, tridiagonal equations 4x_1-x_2=9\\ -x_{i-1}+4x_i-x_{i+1}=5,\quad i=2,\ldots,n-1\\ -x_{n-1}+4x_n=5 with n=10.
```

```
Code
 from fractions import Fraction
def LUdecomp3(c, d, e):
    n = len(d)
     for k in range(1, n):
         lam = c[k-1] / d[k-1]

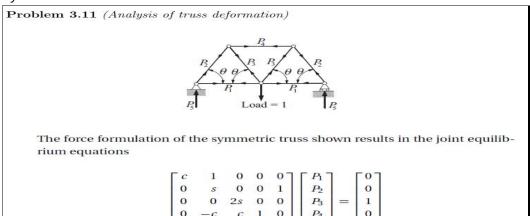
d[k] = d[k] - lam * e[k-1]
         c[k-1] = lam
def LUsolve3(c, d, e, b):
     n = len(d)
     # Forward substitution: Ly = b
     for k in range(1, n):
         b[k] -= c[k-1] * b[k-1]
     b[n-1] = b[n-1] / d[n-1]
     for k in range(n-2, -1, -1):
b[k] = (b[k] - e[k] * b[k+1]) / d[k]
     return b
# 문제 3.10 설정 (n = 10)
n = 10
c = [Fraction(-1)] * (n - 1) # 하삼각 부분
d = [Fraction(4)] * n # 주대각
e = [Fraction(-1)] * (n - 1) # 상삼각 부분
b = [Fraction(9)] + [Fraction(5)] * (n - 1) # 우변 벡터
# LU 분해 및 풀이
c, d, e = LUdecomp3(c, d, e)
x = LUsolve3(c, d, e, b)
# 결과 출력
print("=== 문제 3.10 해 (분수 기반) ===")
for i, xi in enumerate(x):
    print(f"x[{i+1}] = {xi} (approx. {float(xi):.6f})")
```

```
Result
=== 문제 3.10 해 (분수 기반) ===
                       (approx. 2.901919)
x[1] = 1638769/564719
    = 1472605/564719
                       (approx. 2.607677)
x[3] = 1428056/564719
                       (approx. 2.528790)
x[4] = 1416024/564719
                       (approx. 2.507484)
                      (approx. 2.528790)
x[3] = 1428056/564719
x[4] = 1416024/564719
                       (approx. 2.507484)
                       (approx. 2.507484)
x[4] = 1416024/564719
x[5] = 1412445/564719
                       (approx. 2.501147)
                       (approx. 2.497102)
x[6] = 1410161/564719
x[7] = 1404604/564719
                       (approx. 2.487262)
                       (approx. 2.451945)
x[8] = 1384660/564719
x[9] = 1310441/564719
                       (approx. 2.320519)
x[10] = 1033509/564719 (approx. 1.830130)
```

: Tridiagonal Matrix LU Decomposition 알고리즘 최적화를 위해 Hard coding을 하였다.

$$d_k = d_k - (c_{k-1}/d_{k-1})e_{k-1}$$
$$c_{k-1} = c_{k-1}/d_{k-1}$$

- 3.11. (Analysis of truss deformation) $P_i(i=1,2,...,5)$ 를 구하는 프로그램 코드를 짜서 P_i 를 구하여라:
 - a. Python 코드



where $s = \sin \theta$, $c = \cos \theta$, and P_l are the unknown forces. Write a program that computes the forces, given the angle θ . Run the program with $\theta = 53^{\circ}$.

```
Code
     import numpy as np
     import math
     theta_deg = 53
     theta_rad = math.radians(theta_deg)
    s = math.sin(theta_rad)
     c = math.cos(theta_rad)
     A = np.array([
                   0, 0, 0],
15
        [0, 0, 2*s, 0, 0],
        [0, -c, c, 1, 0],
                   s, 0, 0]
     ], dtype=float)
     b = np.array([0, 0, 1, 0, 0], dtype=float)
    P = np.linalg.solve(A, b)
     print("=== 문제 3.11: Truss 구조 해석 결과 ===")
     for i, p in enumerate(P, start=1):
        print(f"P{i} = {p:.6f}")
```

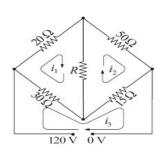
```
Result
=== 문제 3.11: Truss 구조 해석 결과 ===
P1 = 1.040299
P2 = -0.626068
P3 = 0.626068
P4 = -0.753554
P5 = 0.500000
```

: 이번 문제에서는 이미 계수행렬이 정해졌으므로, numpy의 linalg.solve 메서드를 사용하여 해를 구하였다. 만약 Hard-coding을 수행한다면, 이전 문제처럼 Doolittle's Method의 Tridiagonal Matrix LU decomposition 최적화 알고리즘을 사용하여 구현할 수 있을 것이다.

3.12. (Electrical circuit analysis) $i_j(j=1,2,3)$ 을 구하는 프로그램 코드를 짜서 i_j 를 구하여라:

a. 문제 내용

Problem 3.12 (Electrical circuit analysis)



The electrical network shown can be viewed as consisting of three loops. Applying Kirchoff's law (\sum voltage drops = \sum voltage sources) to each loop yields the following equations for the loop currents i_1 , i_2 and i_3 :

$$(50 + R)i_1 - Ri_2 - 30i_3 = 0$$
$$-Ri_1 + (65 + R)i_2 - 15i_3 = 0$$
$$-30i_2 - 15i_2 + 45i_3 = 120$$

- 1. Determine the loop currents i_1 , i_2 and i_3 for R=5 Ohm.
- 2. Determine the loop currents i_1 , i_2 and i_3 for R = 10 Ohm.
- 3. Determine the loop currents i_1 , i_2 and i_3 for R=20 Ohm.

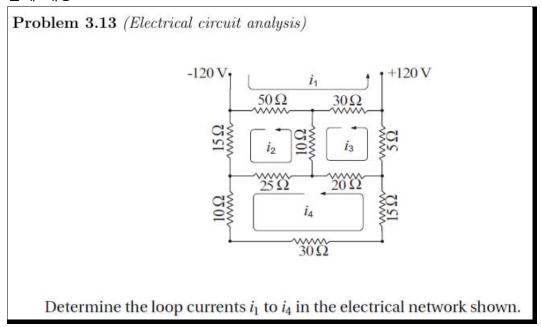
Result

R = 5 Ohm -> i1 = 3.0526 A, i2 = 1.3684 A, i3 = 5.3684 A R = 10 Ohm -> i1 = 3.0000 A, i2 = 1.5000 A, i3 = 5.5000 A R = 20 Ohm -> i1 = 2.9231 A, i2 = 1.6923 A, i3 = 5.6923 A

c. 설명

- 1) Symmetric 하지 않으므로, Doolittle 방식을 사용.
- 2) 이 문제에서는 np.linalg 에서 제공하는 solve 메서드를 사용.

- 3.13. (Electrical circuit analysis) $i_j(j=1,2,3,4)$ 을 구하는 프로그램 코드를 짜서 i_j 를 구하여라:
 - a. 문제 내용



Code

```
import numpy as np
     A = np.array([
          [80, -50, -30,
          [-50, 100, -10, -25],
          [-30, -10, 65, -20],
         [0, -25, -20, 100]
      ], dtype=float)
     b = np.array([120, 0, 0, 0], dtype=float)
     def is_positive_definite(A):
          for k in range(1, A.shape[0] + 1):
              if np.linalg.det(A[:k, :k]) <= 0:</pre>
     def cholesky_decomposition(A):
          n = A.shape[0]
         L = np.zeros_like(A)
          for i in range(n):
              for j in range(i+1):
                  sum_val = sum(L[i][k] * L[j][k] for k in range(j))
                      L[i][j] = (A[i][i] - sum_val) ** 0.5
                      L[i][j] = (A[i][j] - sum_val) / L[j][j]
         return L
     def forward_substitution(L, b):
         n = L.shape[0]
         y = np.zeros_like(b)
         for i in range(n):
             y[i] = (b[i] - np.dot(L[i,:i], y[:i])) / L[i,i]
         return y
     def backward_substitution(U, y):
         n = U.shape[0]
         x = np.zeros_like(y)
         for i in reversed(range(n)):
             x[i] = (y[i] - np.dot(U[i,i+1:], x[i+1:])) / U[i,i]
         return x
     if is positive definite(A):
         print("Positive definite -> Cholesky decomposition 사용")
         L = cholesky_decomposition(A)
         y = forward_substitution(L, b)
         x = backward_substitution(L.T, y)
         print("Not positive definite -> Doolittle decomposition 사용")
68
         L, U = doolittle_decomposition(A)
         y = forward substitution(L, b)
         x = backward_substitution(U, y)
     for i, val in enumerate(x, 1):
         print(f"i{i} = {val:.6f}")
```

Result Positive definite -> Cholesky decomposition 小용 i1 = 4.182395 i2 = 2.664552 i3 = 2.712133 i4 = 1.208565

c. 설명

$$\begin{array}{c} () - |20 + 50(\lambda_1 - \lambda_2) + 30(\lambda_1 - \lambda_3) = |20 \\ + 30\lambda_1 - 50\lambda_2 - 30\lambda_3 = 240 \\ (2) 50(\lambda_2 - \lambda_1) + |5\lambda_2 + 25(\lambda_2 - \lambda_3) + |0(\lambda_2 - \lambda_3) = 0 \\ + -50\lambda_1 + |00\lambda_2 - |0\lambda_3 - 25\lambda_4 = 0 \end{array}$$

$$\begin{array}{c} () - |20 + 50(\lambda_1 - \lambda_3) + 30(\lambda_1 - \lambda_3) = |20 \\ + -50\lambda_1 + |00\lambda_2 - |0\lambda_3 - 25\lambda_4 = 0 \end{array}$$

$$\begin{array}{c} () - |20 + 50(\lambda_1 - \lambda_3) + |20(\lambda_2 - \lambda_3) = |20 \\ + -30\lambda_1 - |0\lambda_2 + |5\lambda_3 - 20\lambda_4 = 0 \end{array}$$

$$\begin{array}{c} () - |20 + 50(\lambda_1 - \lambda_3) + |20(\lambda_2 - \lambda_3) = |20 \\ + -30\lambda_1 - |0\lambda_2 + |5\lambda_3 - 20\lambda_4 = 0 \end{array}$$

$$\begin{array}{c} () - |20 + 50(\lambda_1 - \lambda_3) + |20(\lambda_1 - \lambda_3) = |20 + |20(\lambda_1 - \lambda_3) = |2$$

이후:

- 1) Symmetric 여부 & Positive Definite 판정 -> (O)
- 2) Choleski Method 사용하여 LU 분해 -> Forward&Backward Substitution 사용하여 해를 도출.