

Echelle: 1:2	

## TITRE : Abdomen\_supérieur

Nbr pcs: 01

Unité: mm

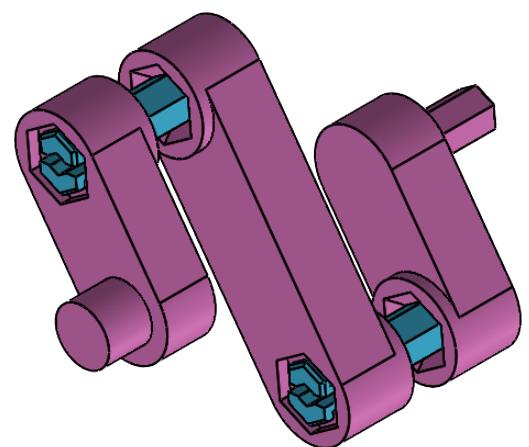
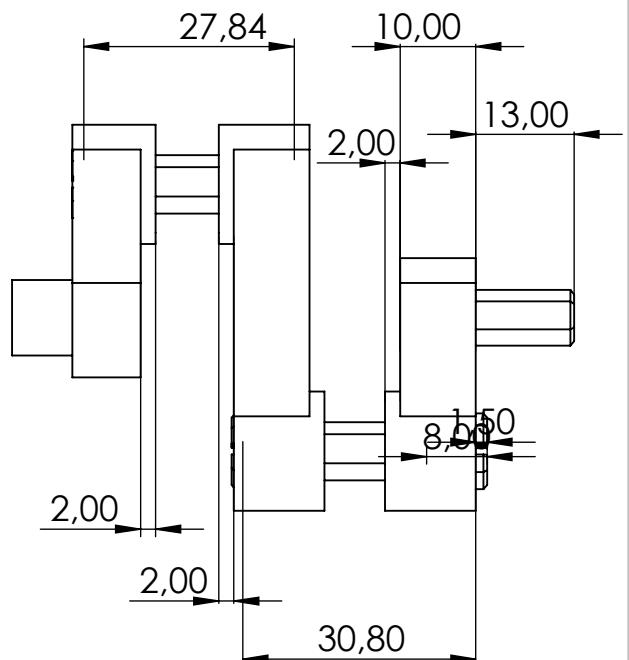
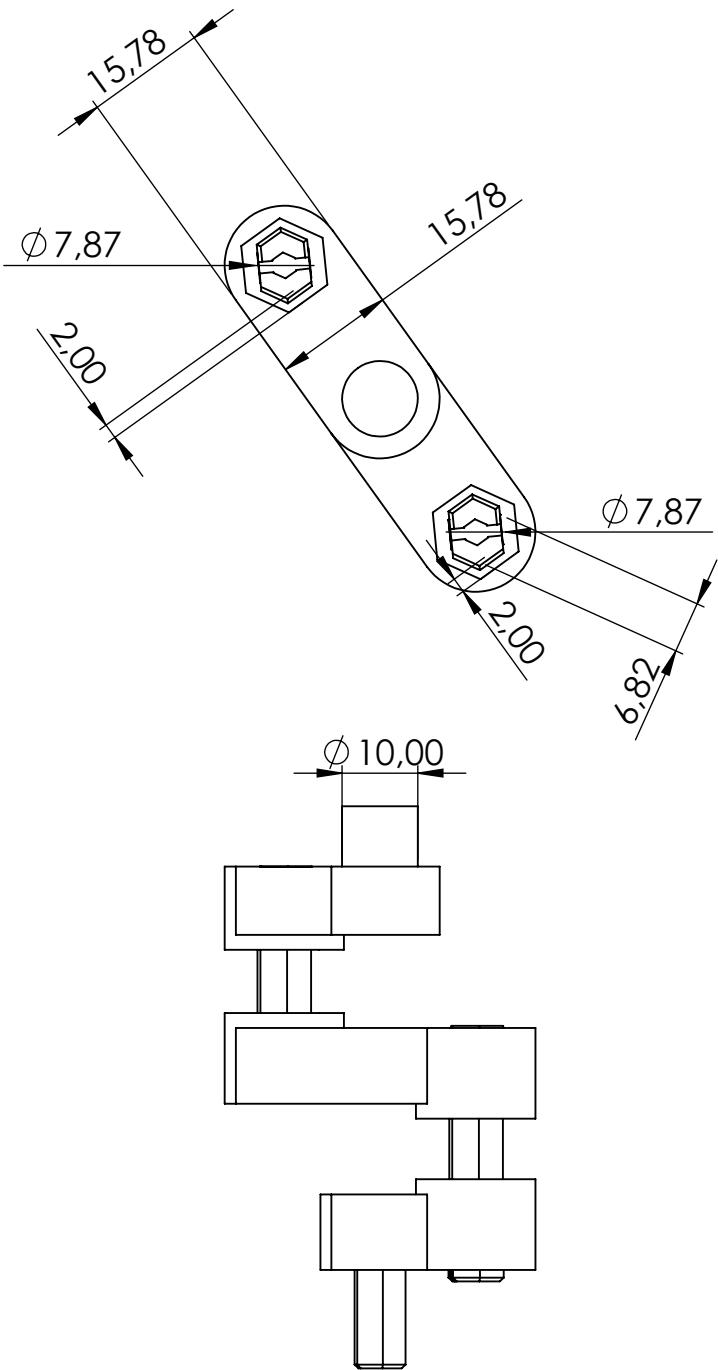
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle: 1:1



## TITRE: Assemblage cames

Matière: PLA

3A S1 ROBOTIQUE

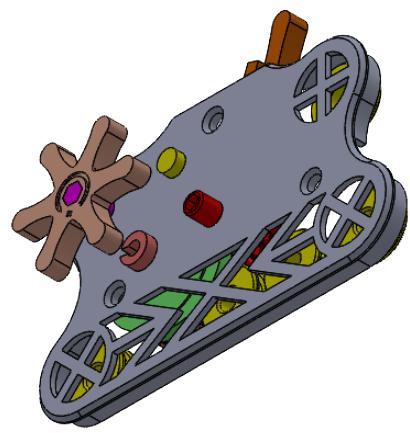
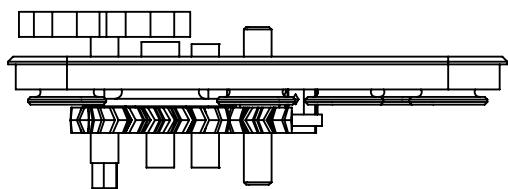
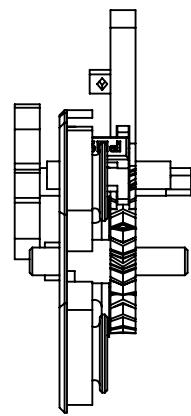
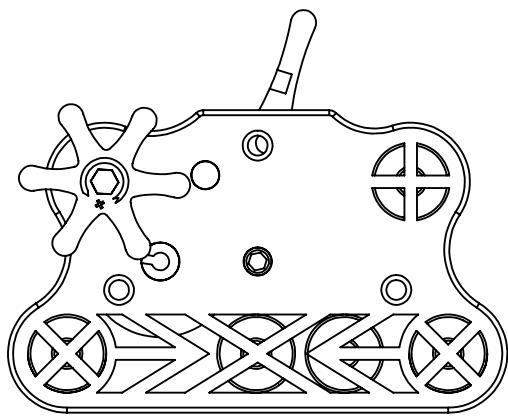


Encadré par:  
Mr DAVID FOFI

Nbr pcs: 01

Unité: mm

Date: 10/12/2025



Echelle:	1:2

## TITRE : Assemblage moteur

Nbr pcs: 01

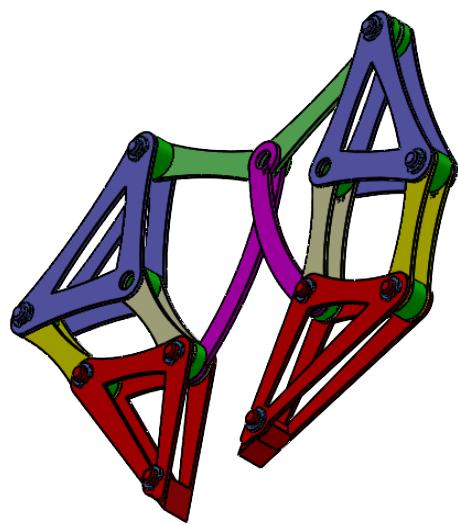
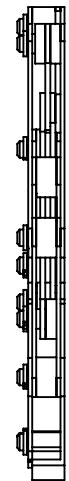
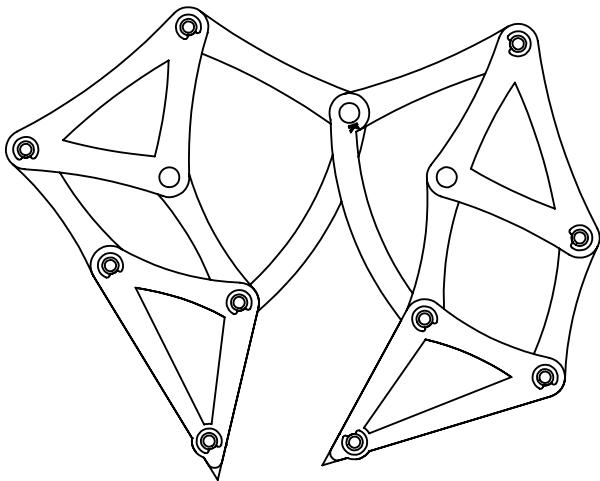
Unité: mm

Matière:	PLA
	3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOFI

Date: 10/12/2025



Echelle:	1:3

## TITRE: Assemblage pattes\_1P

Nbr pcs: 02  
Unité: mm

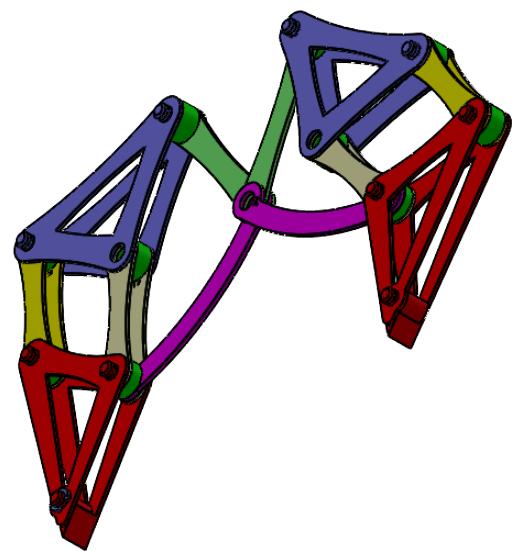
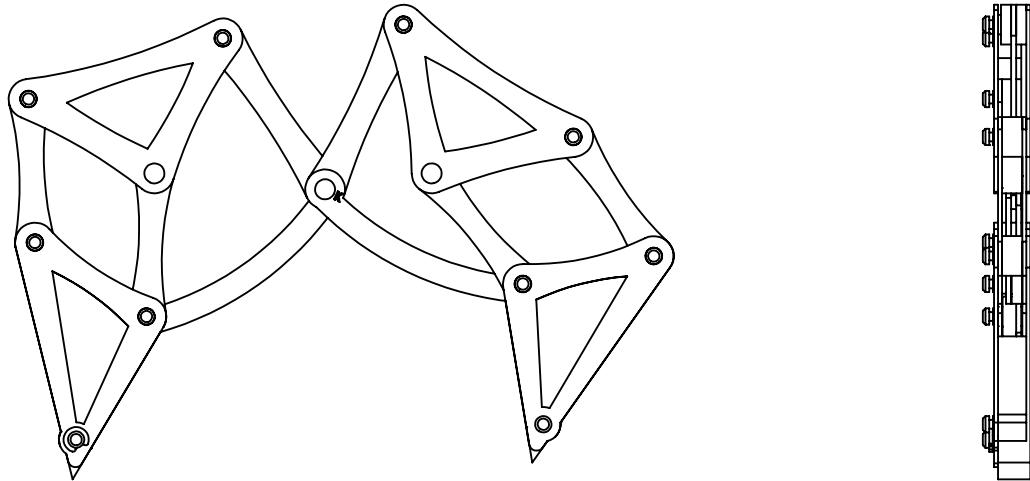
Matière: PLA

3A S1 ROBOTIQUE



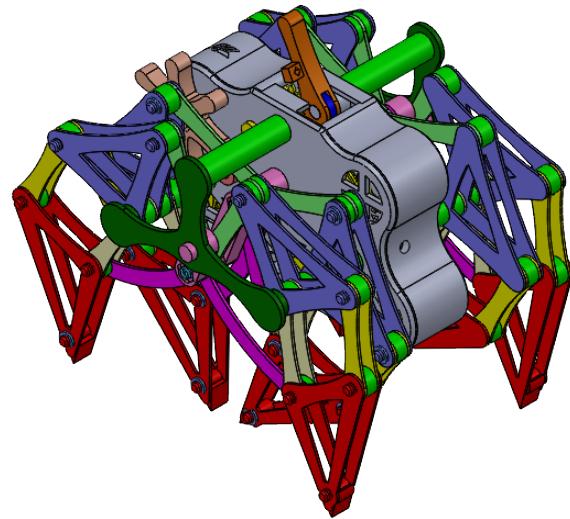
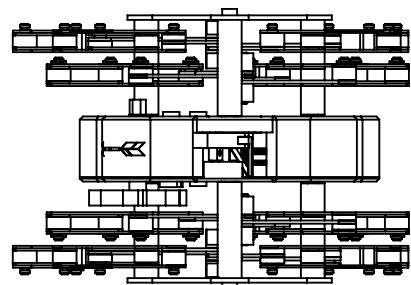
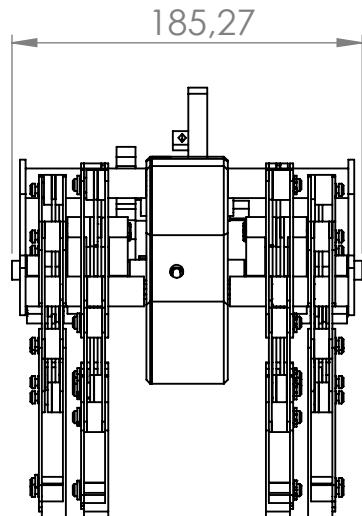
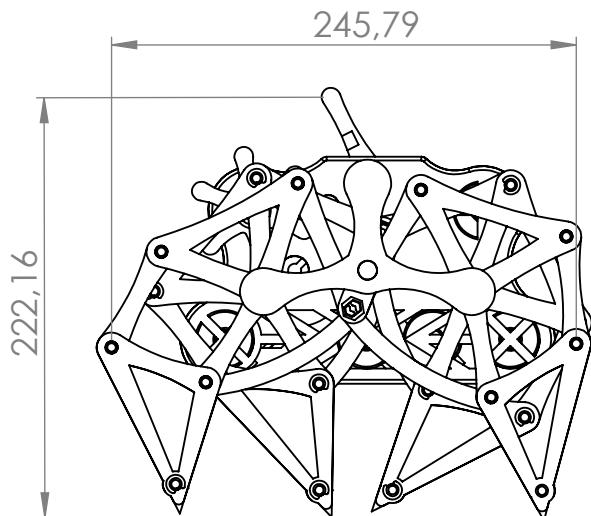
Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle: 1:3		Nbr pcs: 02
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOFI

## TITRE: Assemblage pattes\_2P



Echelle: 1:4	

## TITRE: Assemblage Strandbeest

Nbr pcs: 01  
Unité: mm

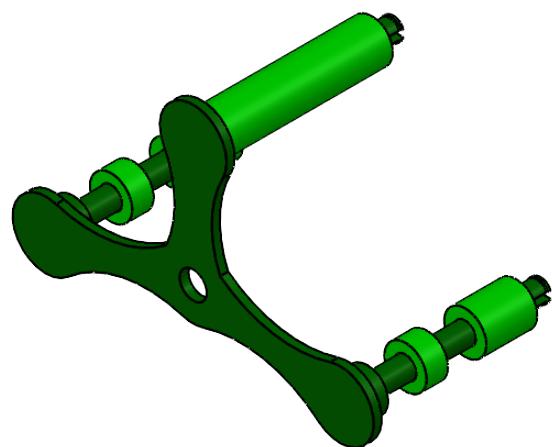
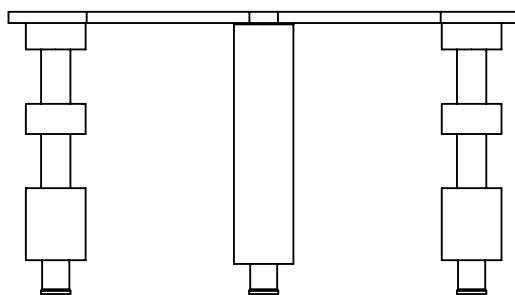
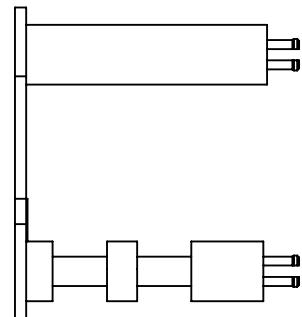
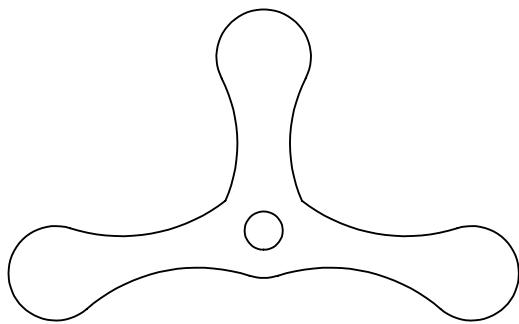
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOFI

Date: 10/12/2025



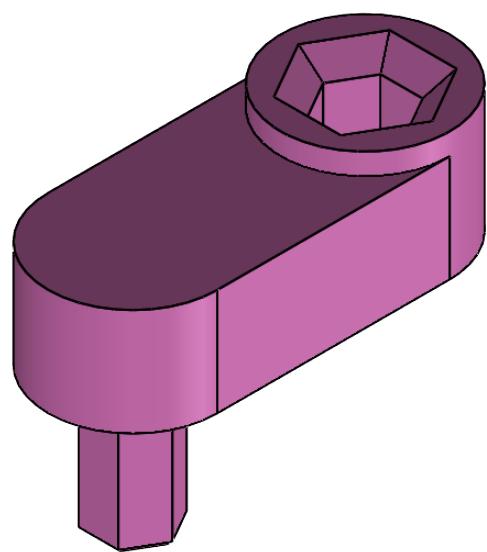
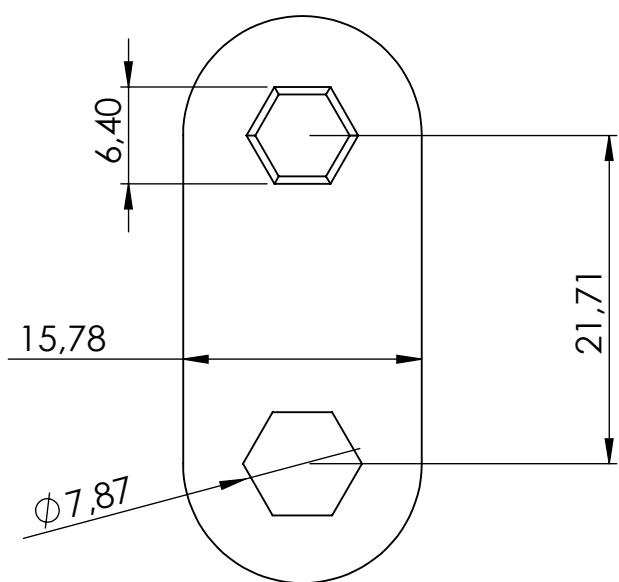
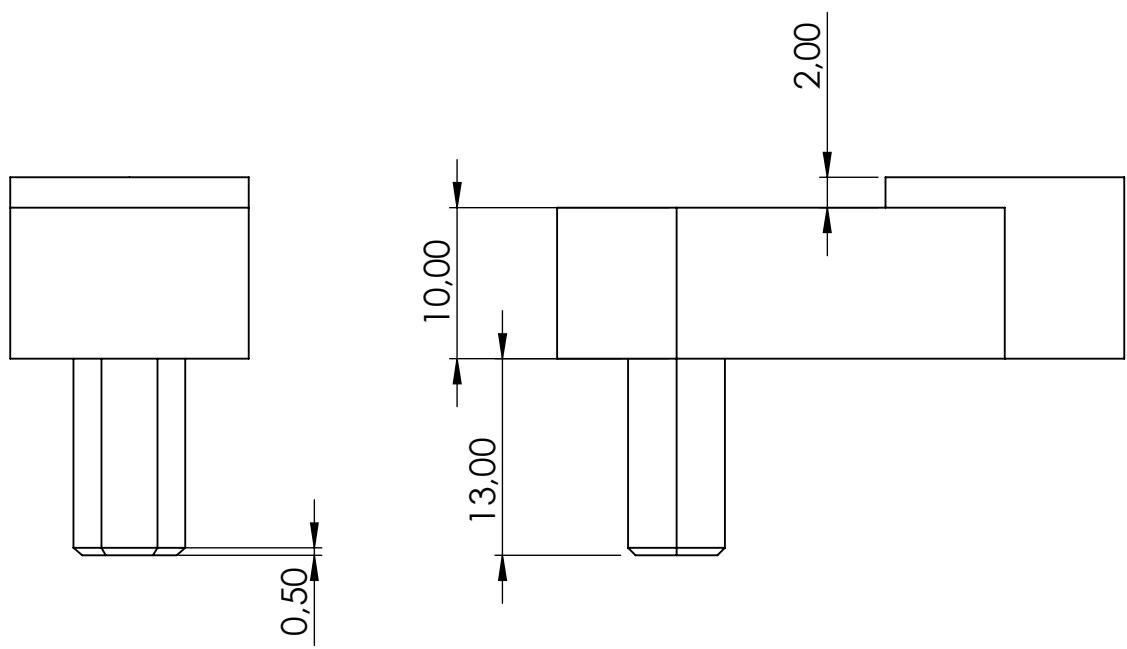
Echelle: 1:2	
Matière: PLA	3A S1 ROBOTIQUE

## TITRE: Assemblage support

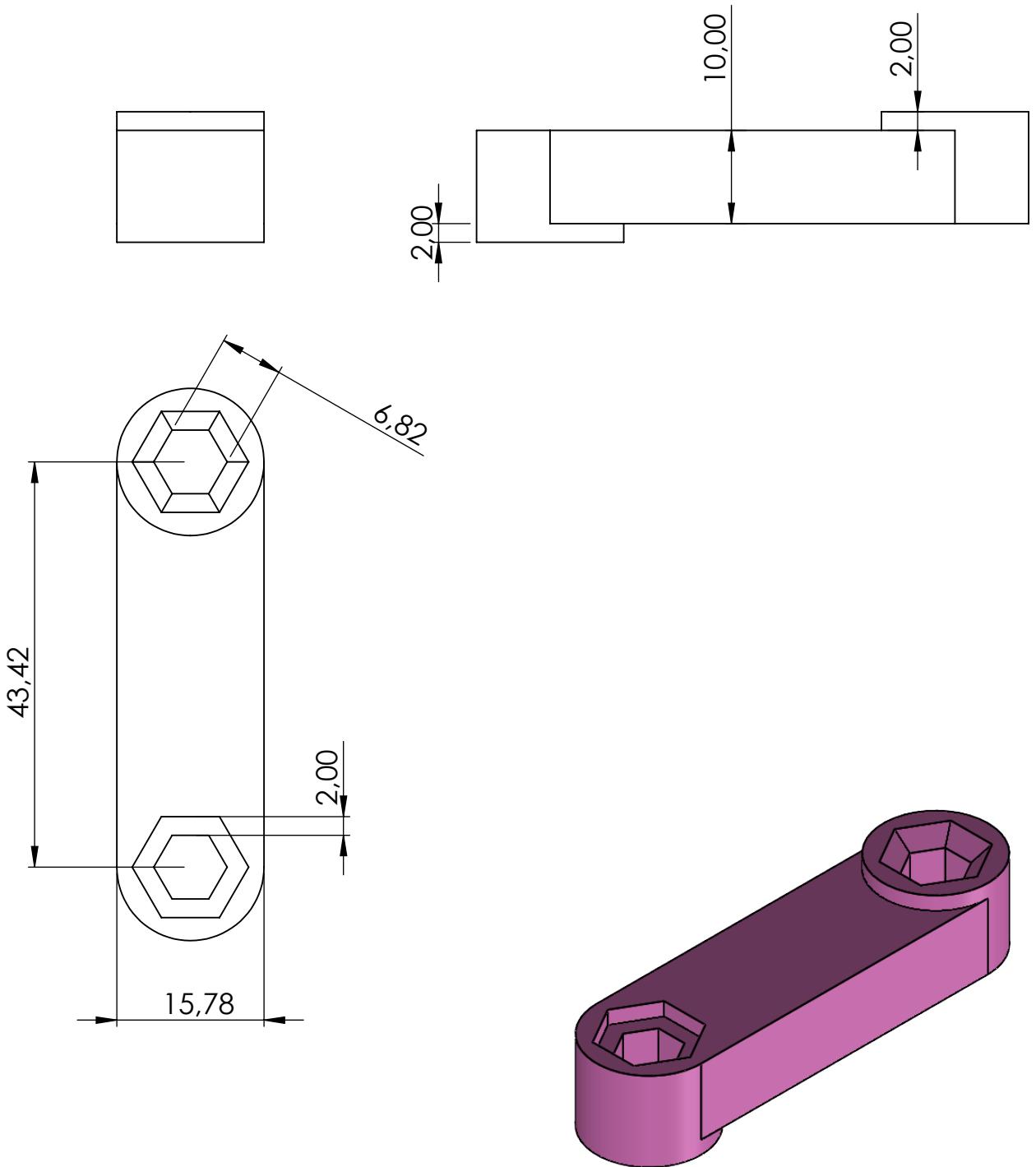


Encadré par:  
Mr DAVID FOIFI

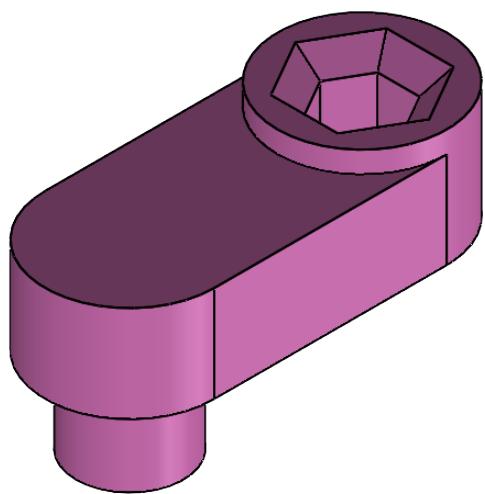
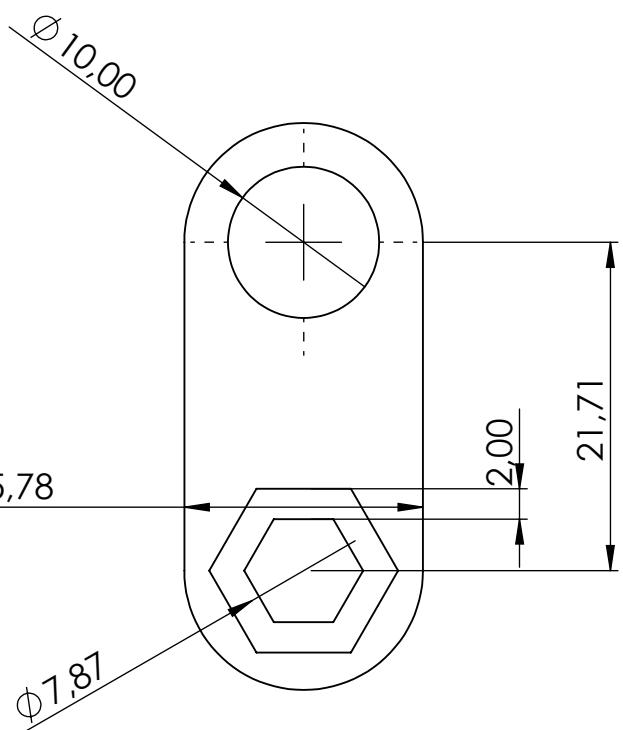
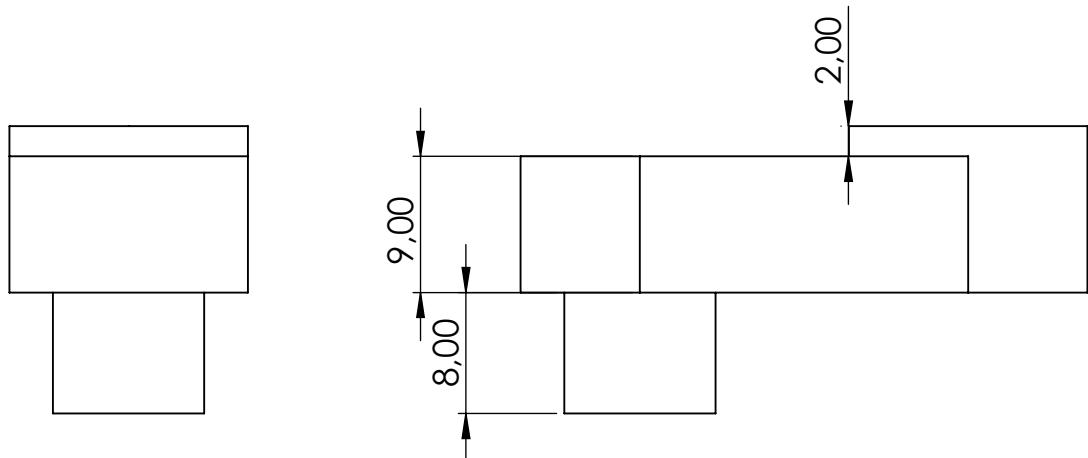
Nbr pcs: 02  
Unité: mm  
Date: 10/12/2025



Echelle: 2:1		Nbr pcs: 02
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI



Echelle: 1.5:1	<b>TITRE: Bielle_2P</b>		Nbr pcs: 02
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOIFI
			Date: 10/12/2025



Echelle: 2:1



## TITRE: Bielle\_terminale

Nbr pcs: 02

Unité: mm

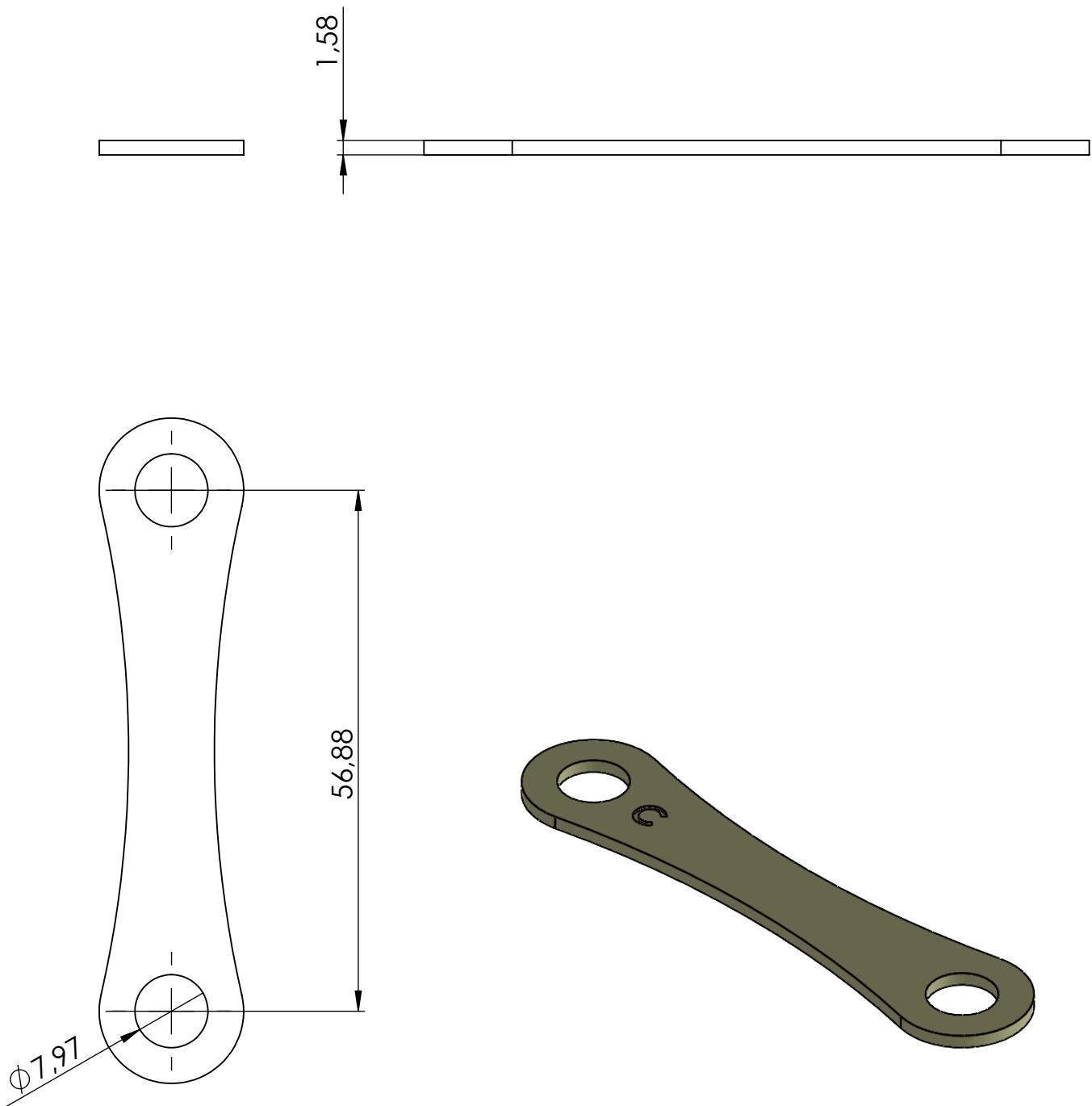
Matière: PLA

3A S1 ROBOTIQUE

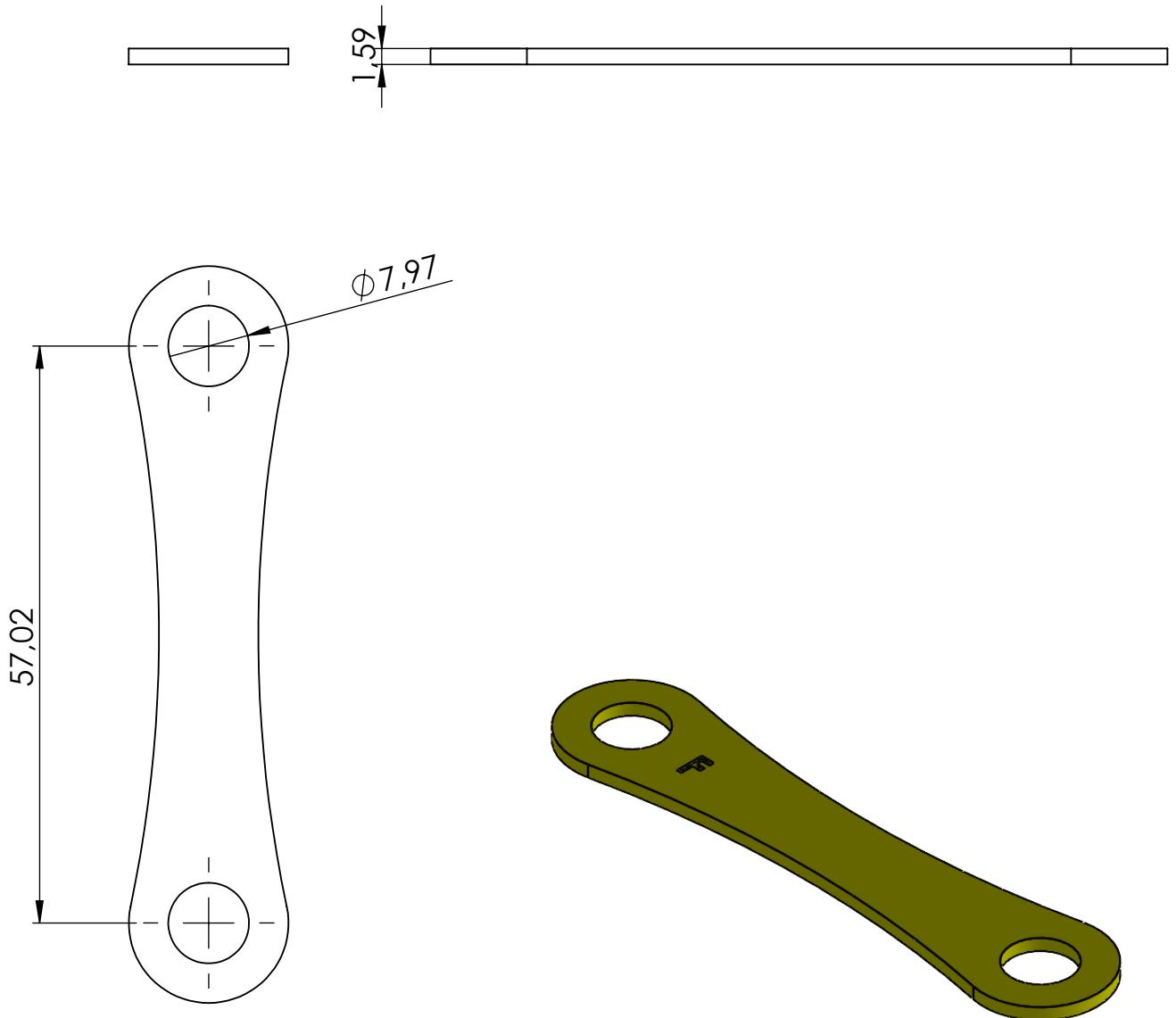


Encadré par:  
Mr DAVID FOFI

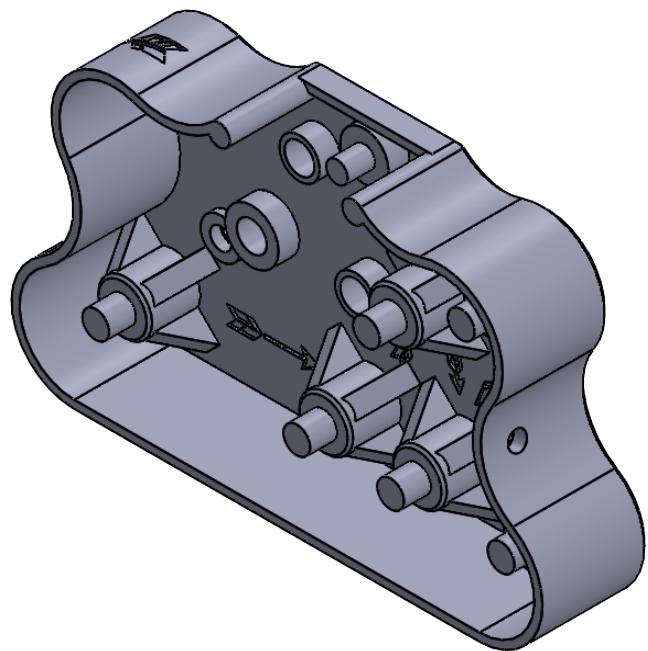
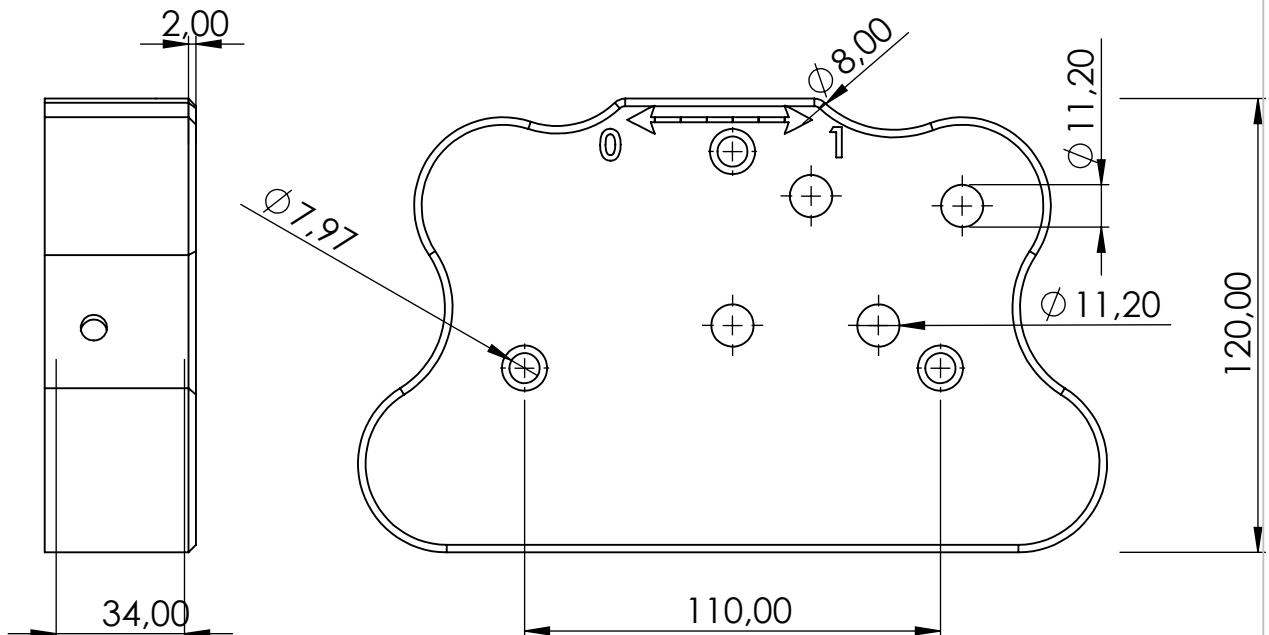
Date: 10/12/2025



Echelle: 1.5:1	TITRE: Fémur C	Nbr pcs: 16
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	POLYTECH nancy
		Encadré par: Mr DAVID FOIFI
		Date: 10/12/2025



Echelle: 1.5:1	TITRE: Fémur F	Nbr pcs: 16
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI
		Date: 10/12/2025



Echelle: 1:2	

## TITRE : Abdomen\_inférieur

Nbr pcs: 01  
Unité: mm

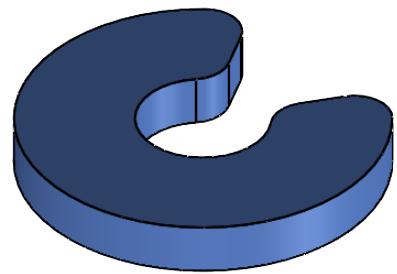
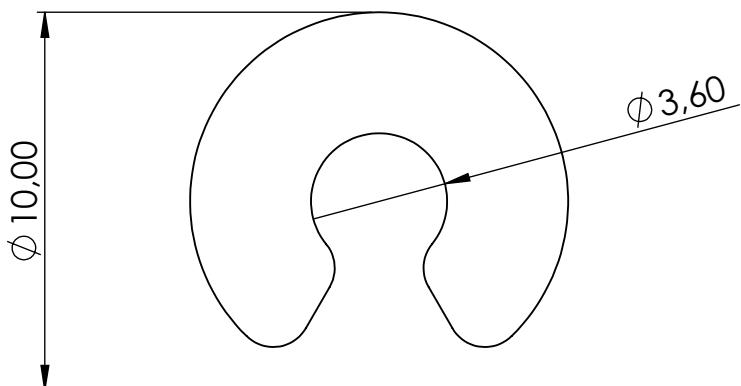
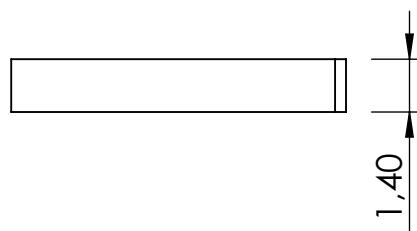
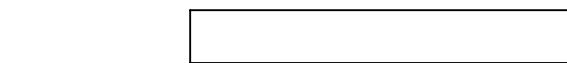
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 5:1



Nbr pcs: 40

Unité: mm

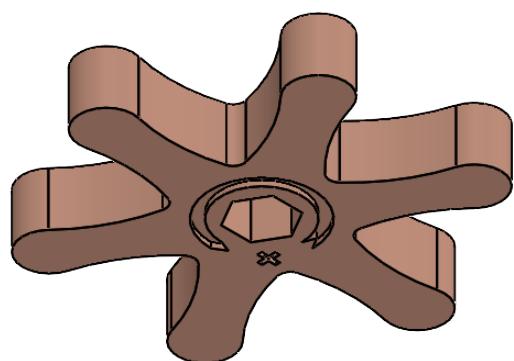
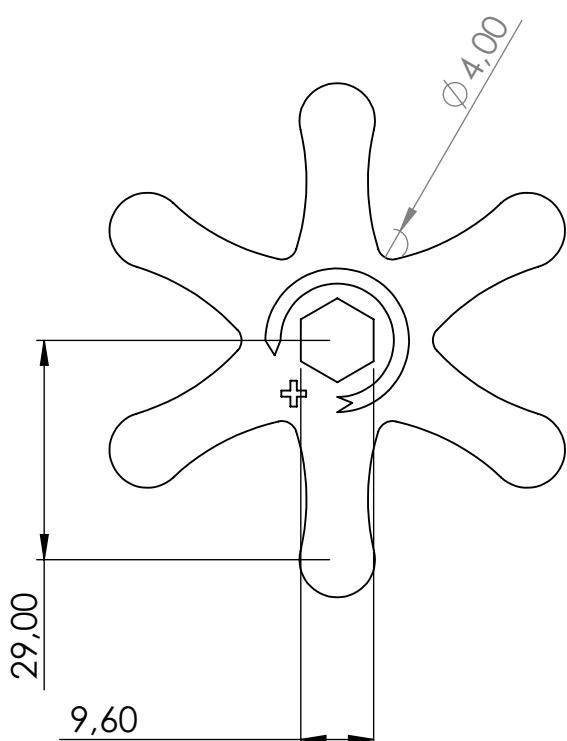
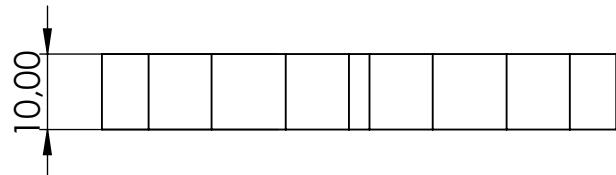
Matière: PLA

## TITRE: Circlip



Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle:	1:1
Matière:	PLA

## TITRE : Clé

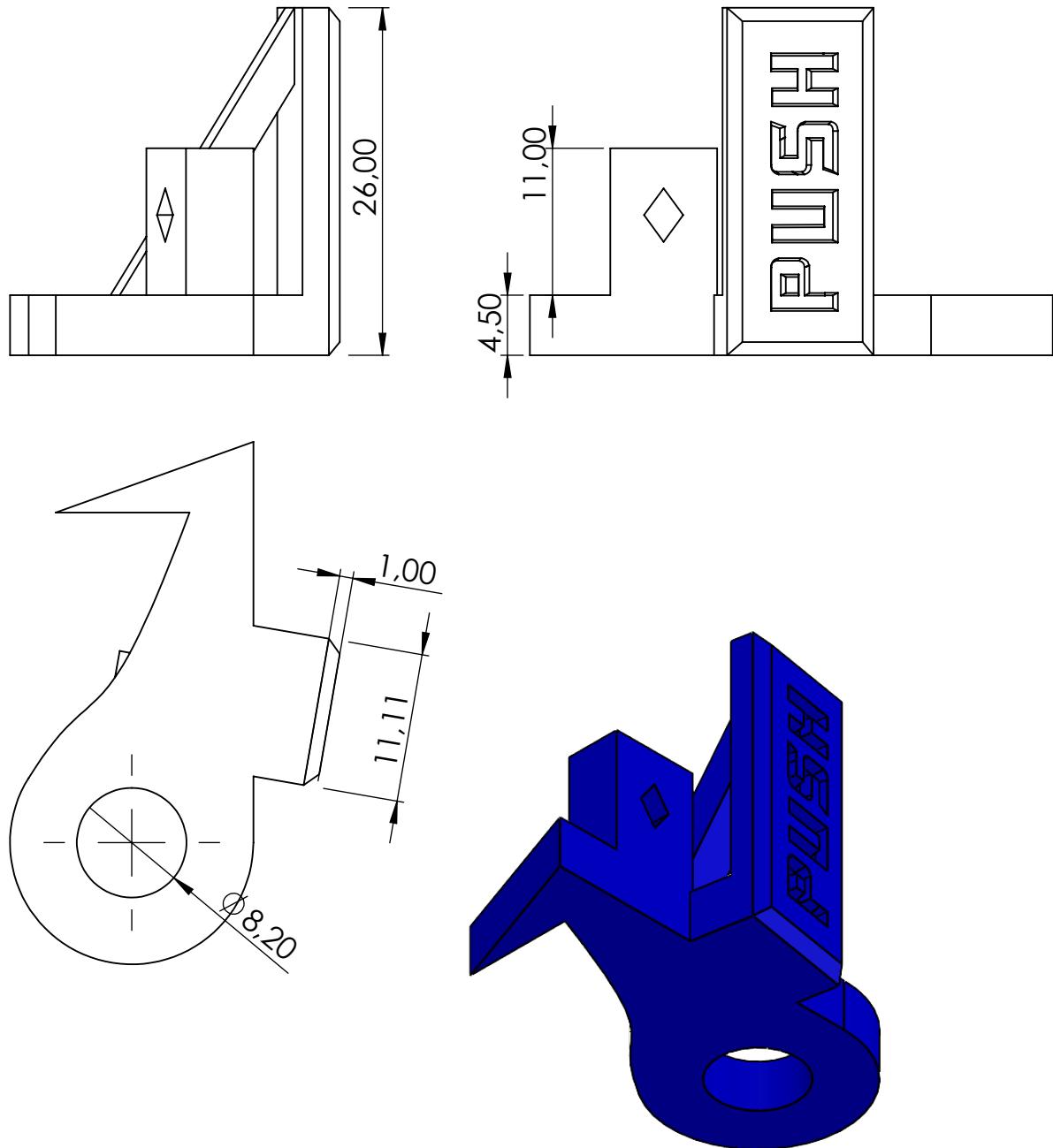
Nbr pcs: 01  
Unité: mm

3A S1 ROBOTIQUE

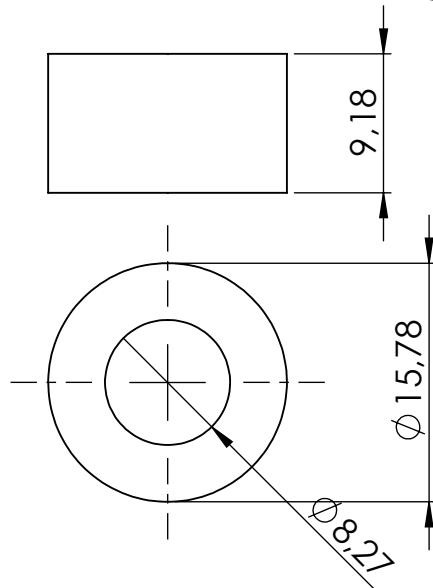
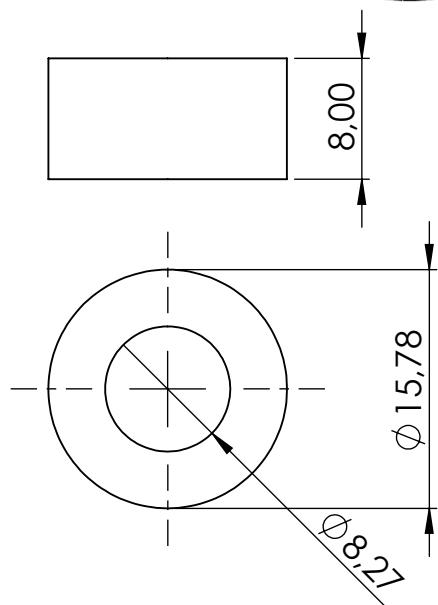
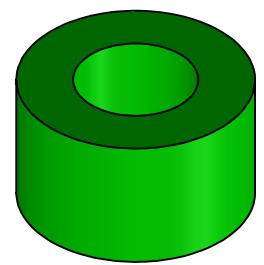
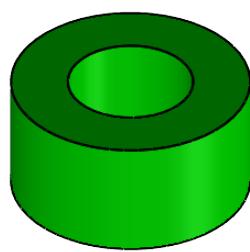
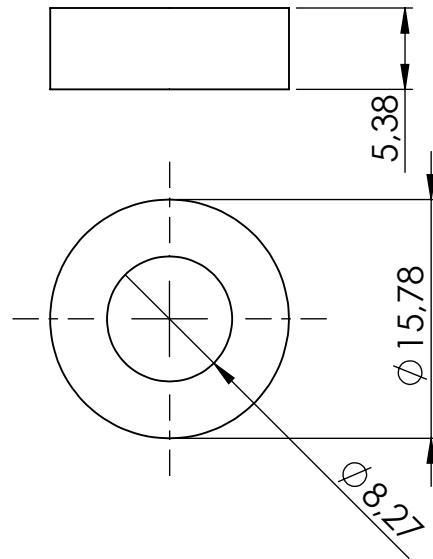
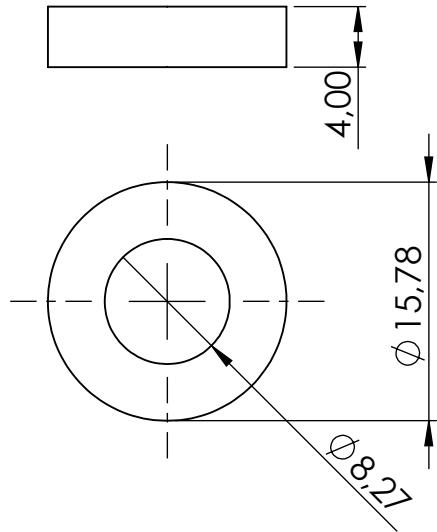
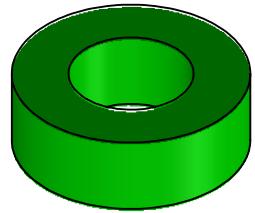
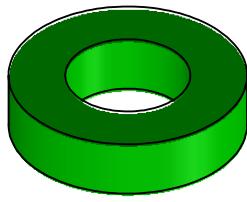


Encadré par:  
Mr DAVID FOIFI

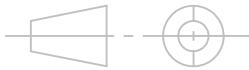
Date: 10/12/2025



Echelle: 2:1	TITRE : Crochet	Nbr pcs: 01
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI
		Date: 10/12/2025



Echelle: 2:1



Nbr pcs: 48

Unité: mm

Matière: PLA

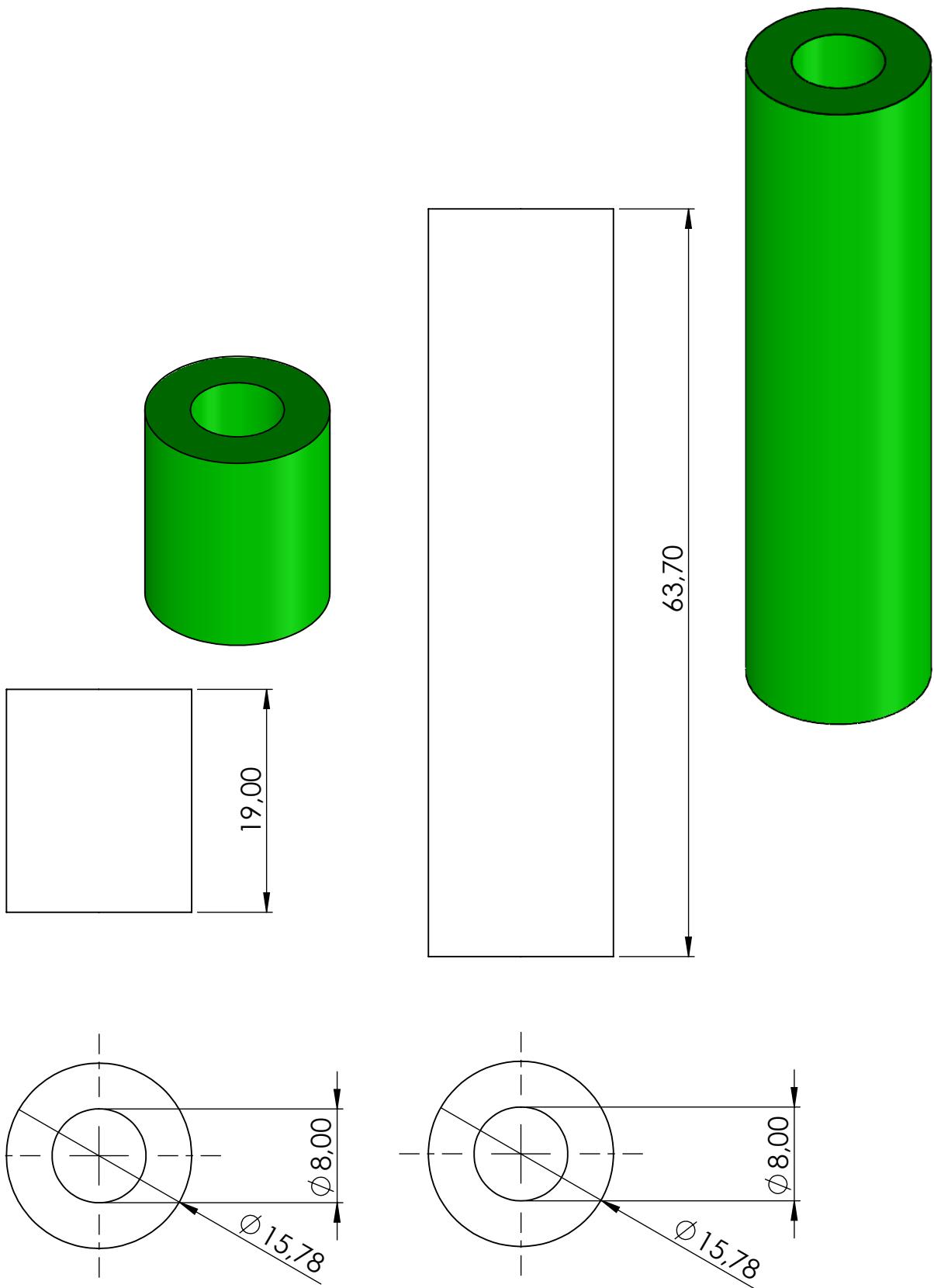
3A S1 ROBOTIQUE



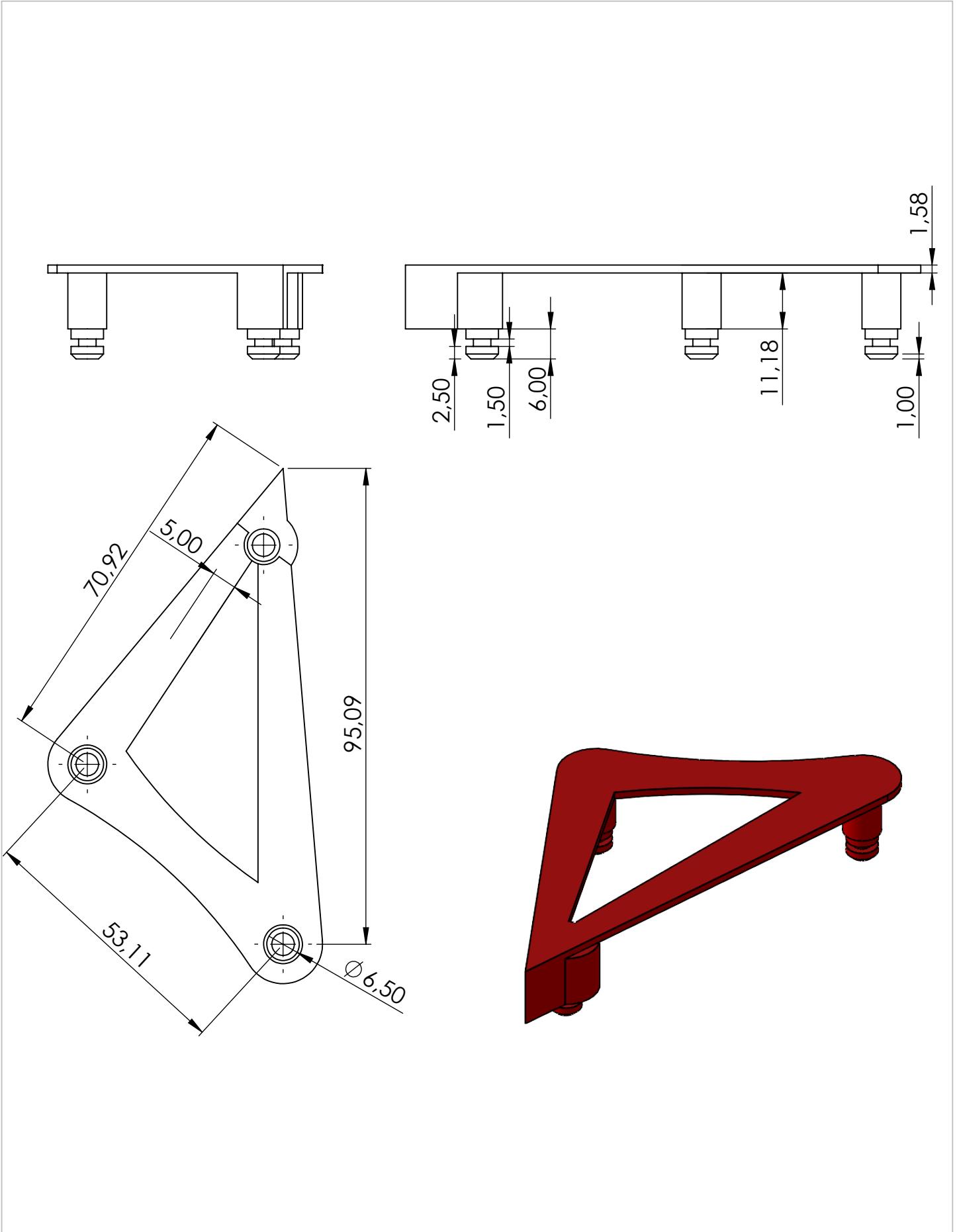
Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025

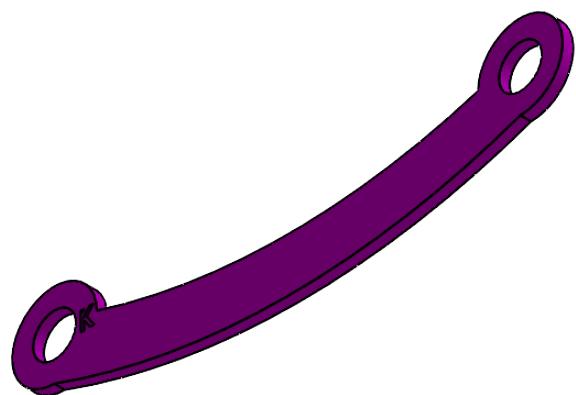
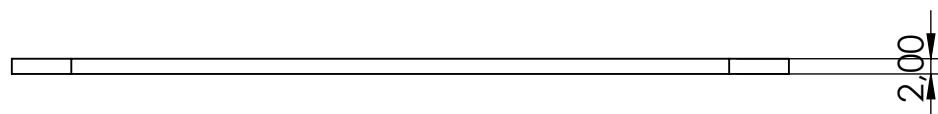
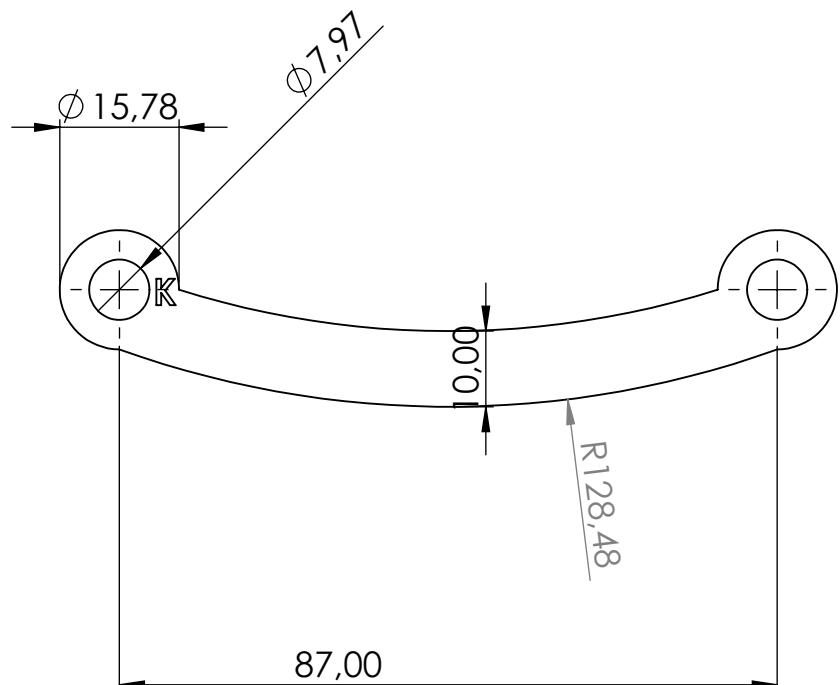
# TITRE : Entroises



Echelle: 2:1	TITRE: Entroises longues	Nbr pcs: 06
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOFI
		Date: 10/12/2025



Echelle: 1:1	TITRE : Griffe	Nbr pcs: 08
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI
		Date: 10/12/2025



Echelle: 1:2



## TITRE : Tibia

Nbr pcs: 08

Unité: mm

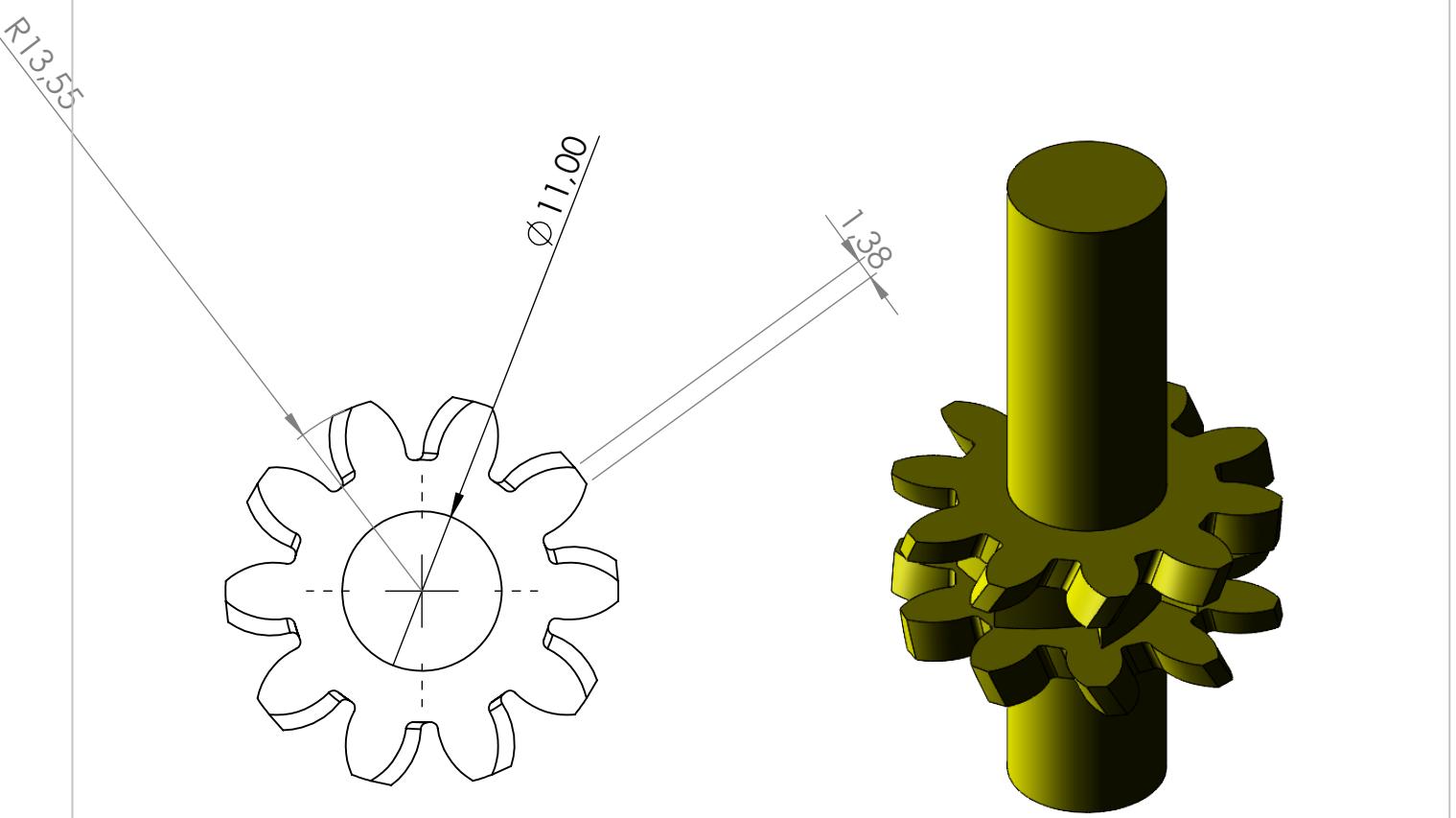
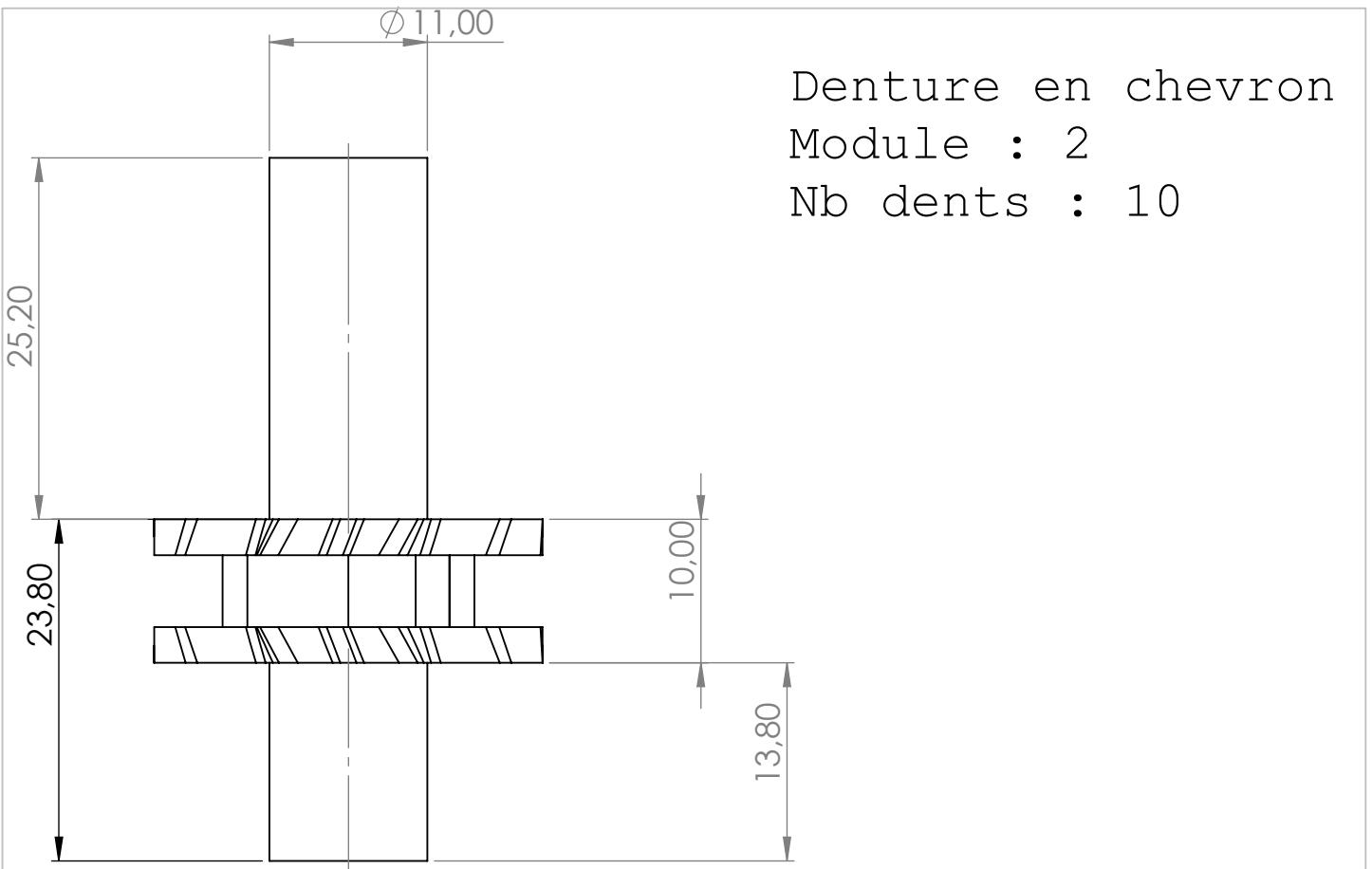
Matière: PLA

3A S1 ROBOTIQUE

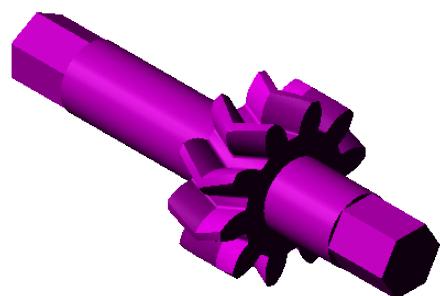
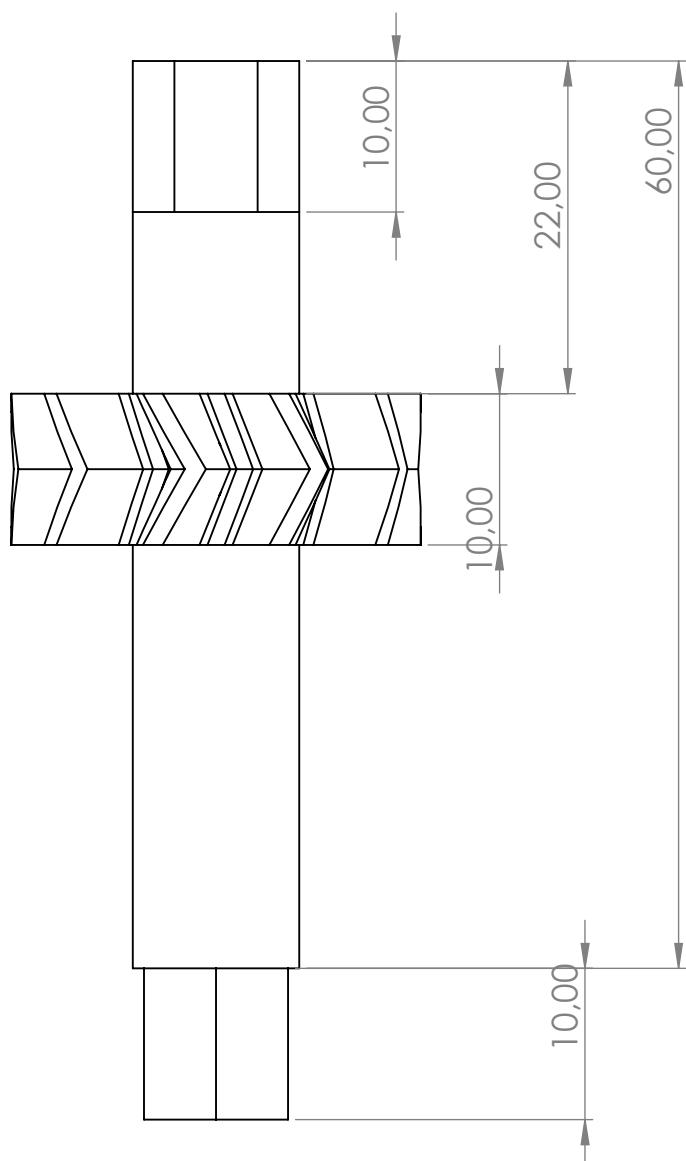
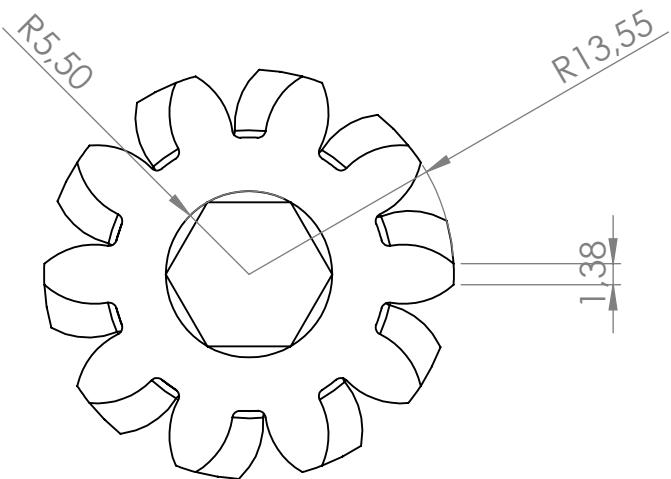


Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle: 1:1	TITRE: Roue libre	Nbr pcs: 01
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI
		Date: 10/12/2025



Echelle: 1:1



## TITRE: Roue d'entrée

Nbr pcs: 01

Unité: mm

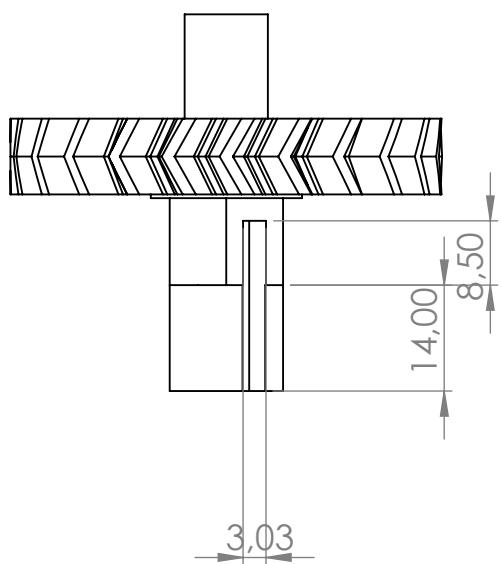
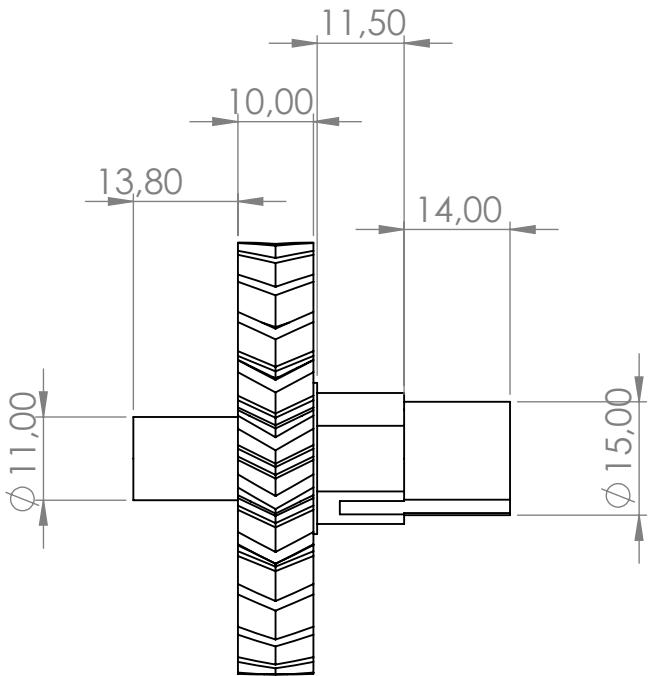
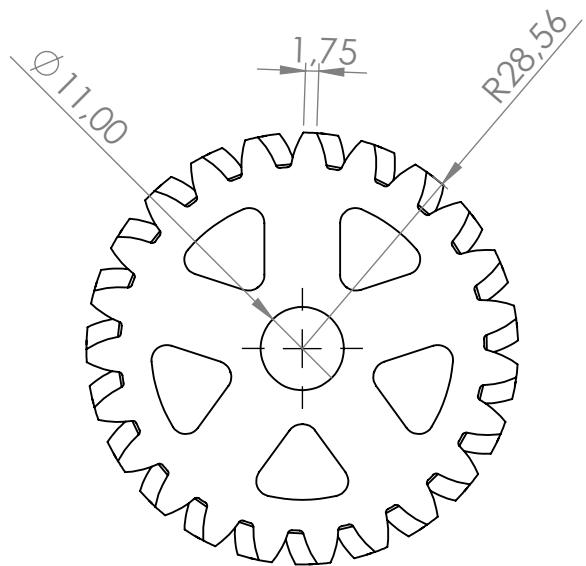
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



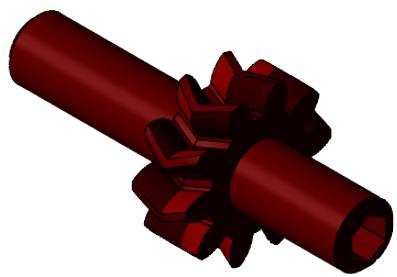
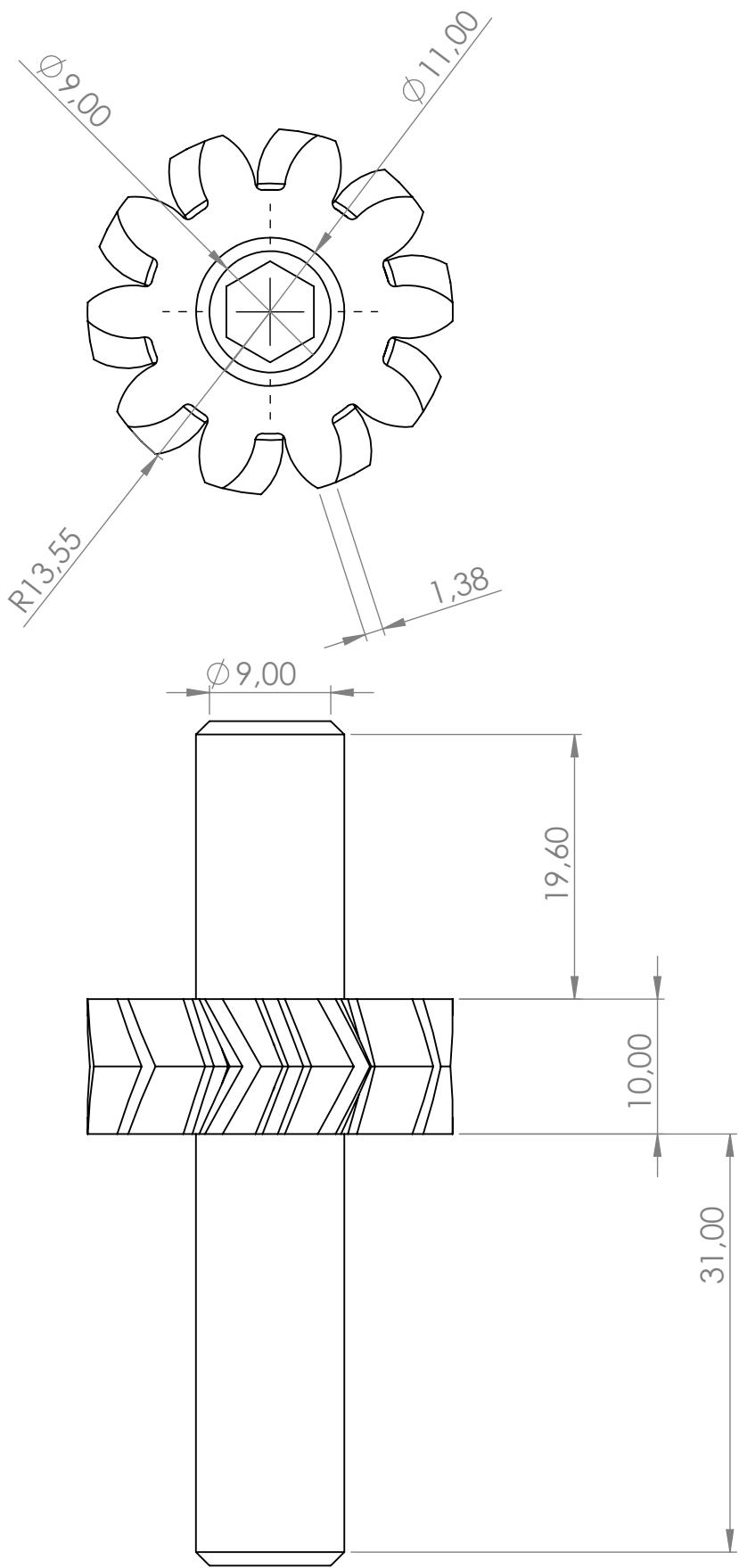
Echelle: 1:1	
Matière: PLA	3A S1 ROBOTIQUE

## TITRE: Roue d'enroulement



Encadré par:  
Mr DAVID FOFI

Nbr pcs: 01  
Unité: mm  
Date: 10/12/2025



Echelle: 2:1



## TITRE: Roue de sortie

Nbr pcs: 01

Unité: mm

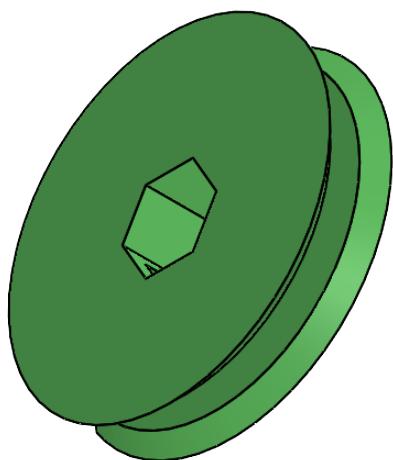
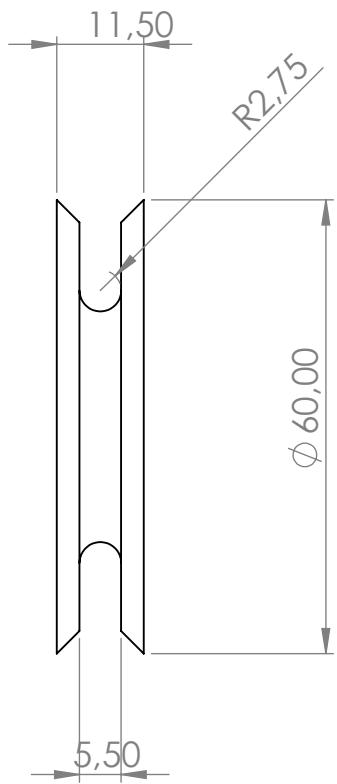
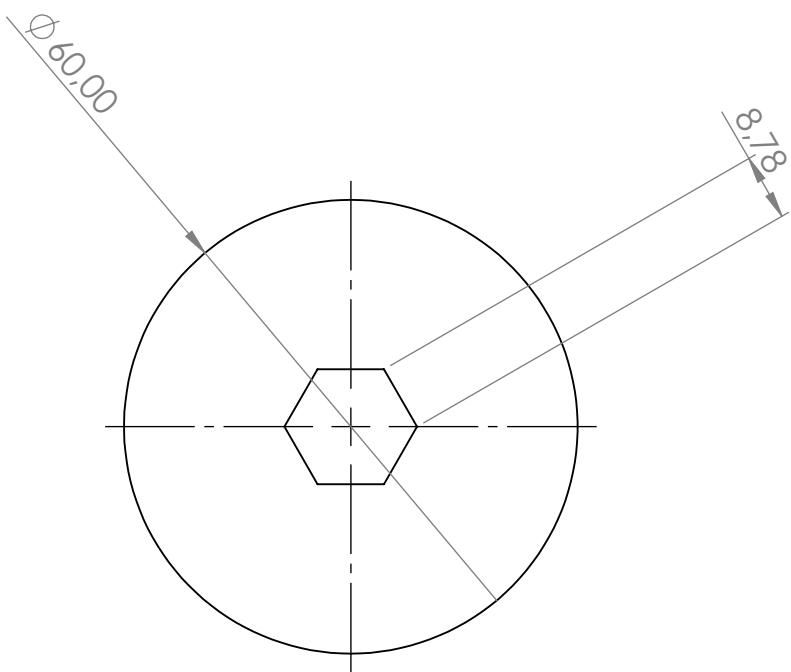
Matière: PLA

3A S1 ROBOTIQUE

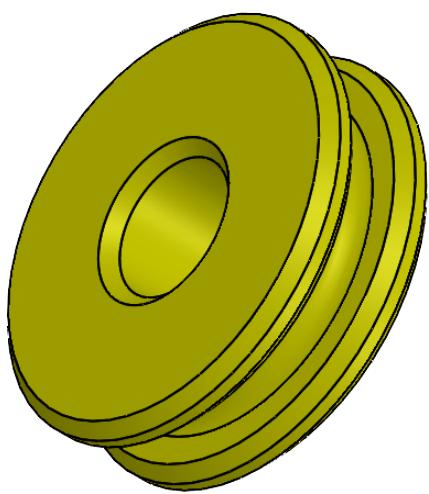
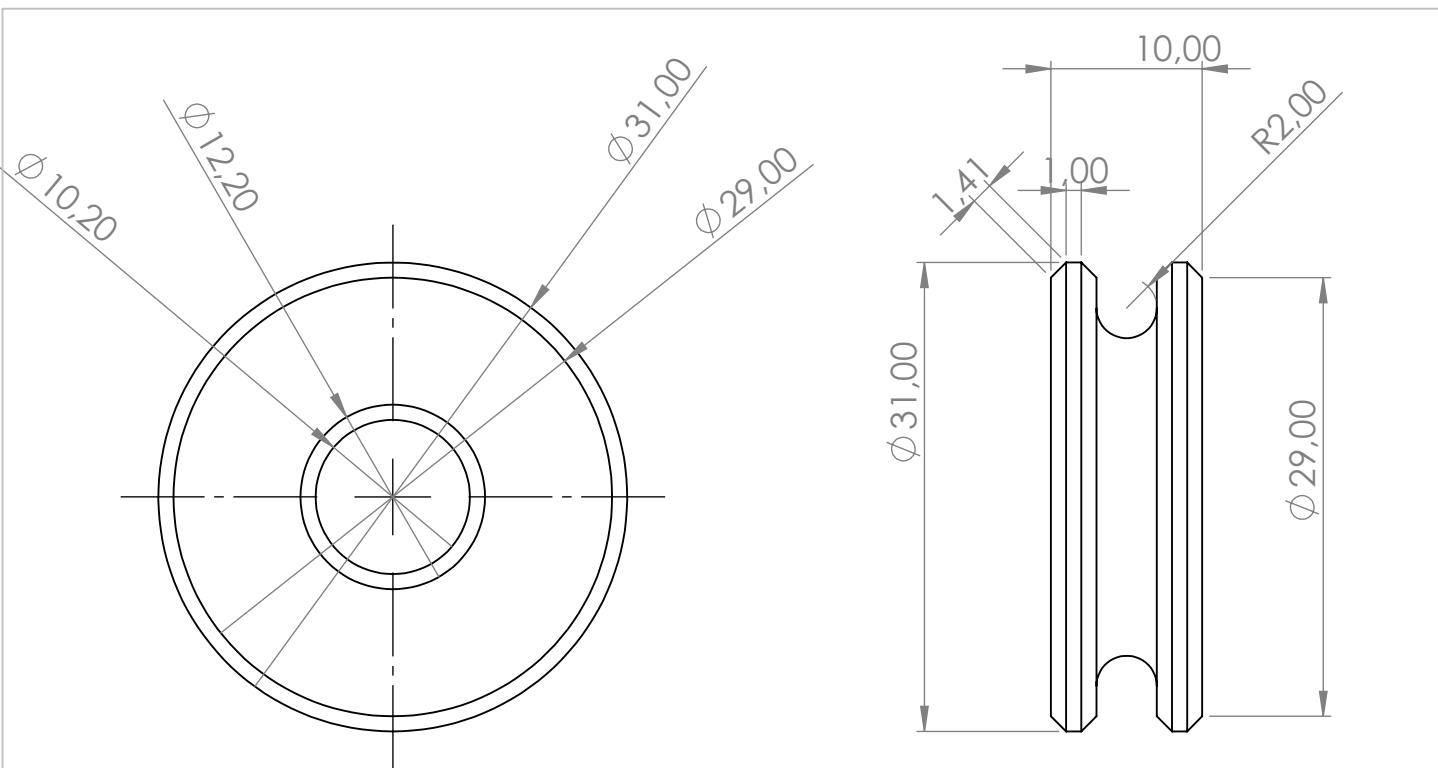


Encadré par:  
Mr DAVID FOIFI

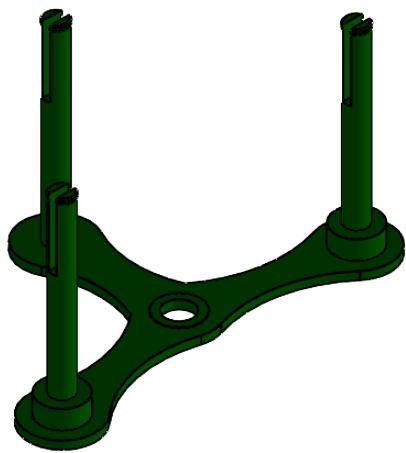
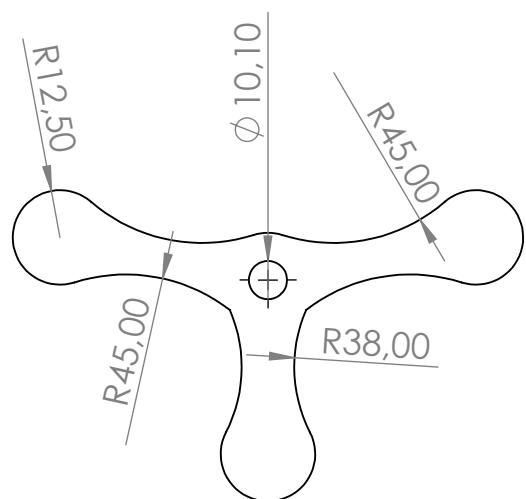
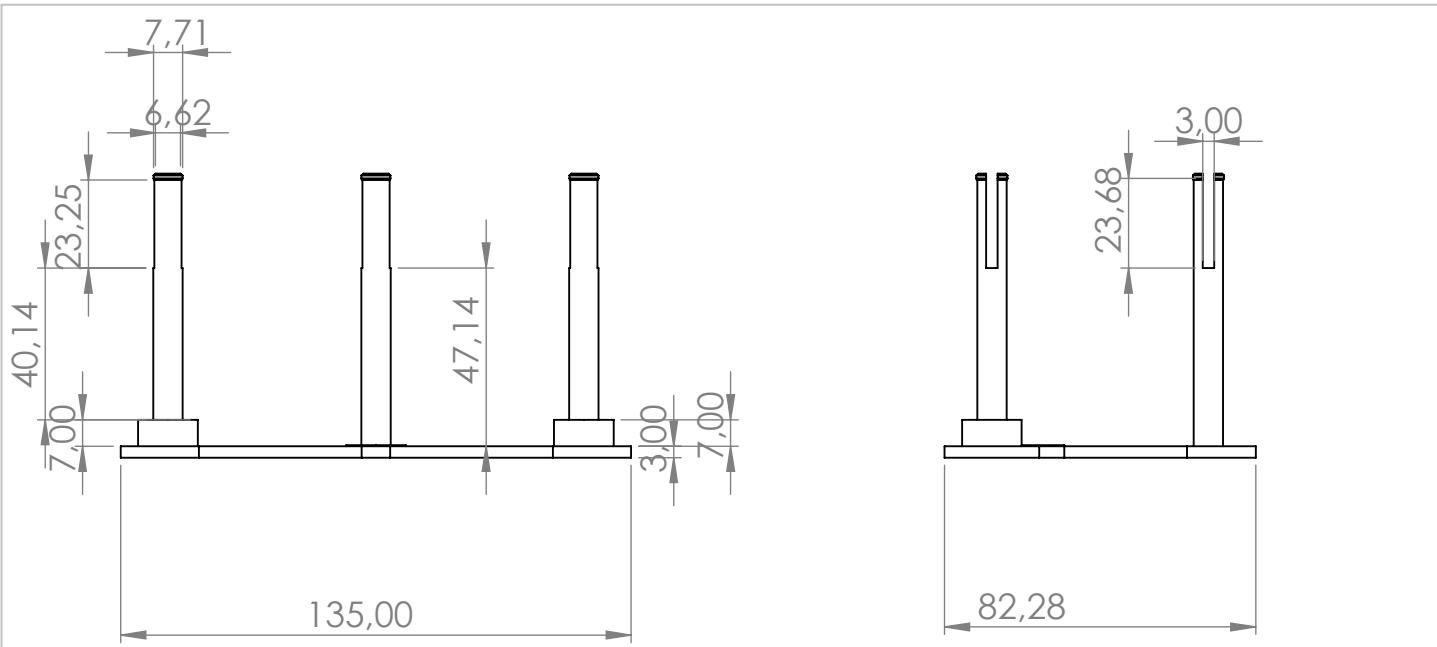
Date: 10/12/2025



Echelle: 1:1		Nbr pcs: 01
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI

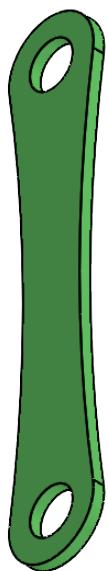
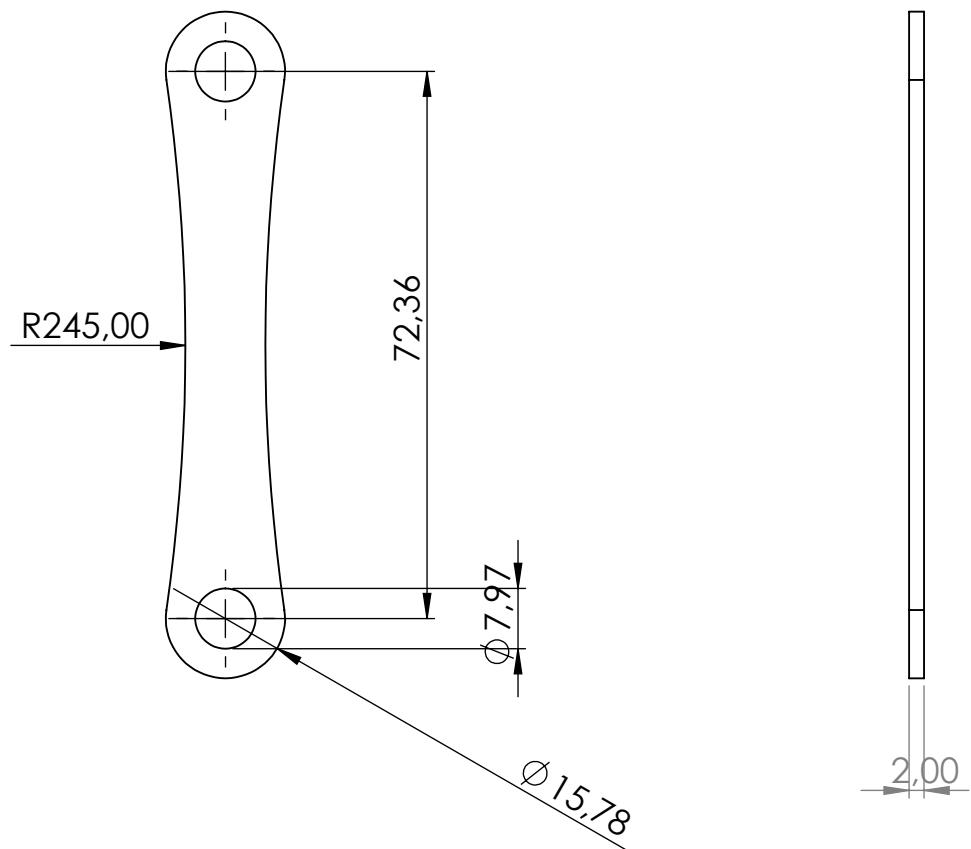


Echelle: 2:1	TITRE: Poulie renvoi d'angle	Nbr pcs: 06
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOFI
		Date: 10/12/2025



Echelle: 1:2	
Matière: PLA	3A S1 ROBOTIQUE

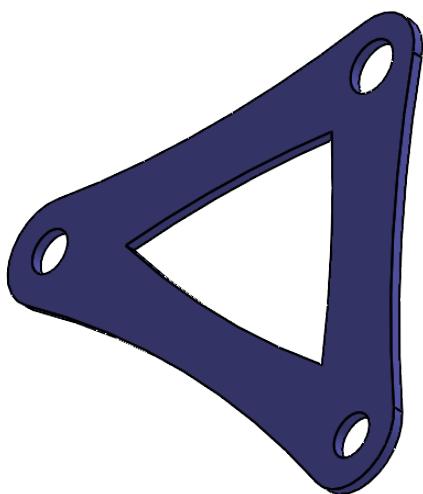
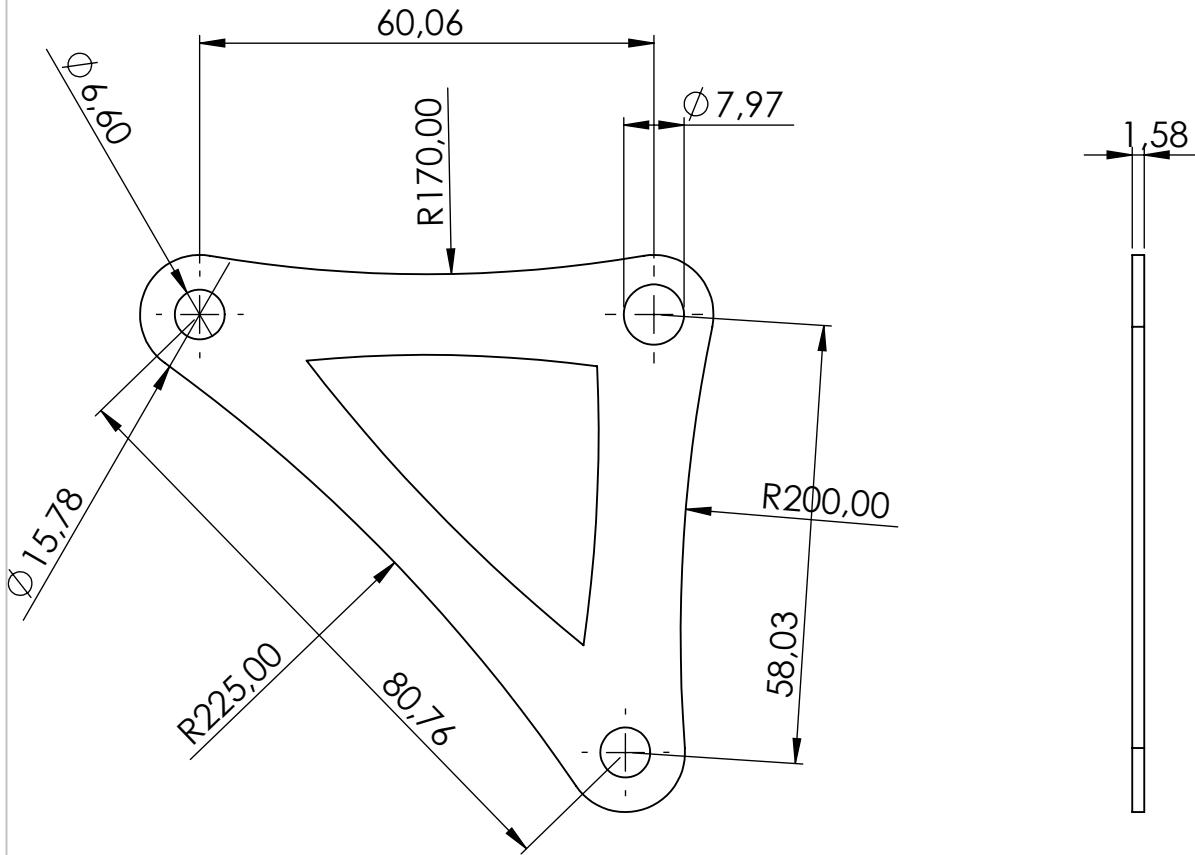
## TITRE: Pédicelle



Echelle: 1:1		Nbr pcs: 08
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOFI

**TITRE:** Patella J





Echelle: 1:1



Nbr pcs: 08

Unité: mm

## TITRE : Métatarse supérieure

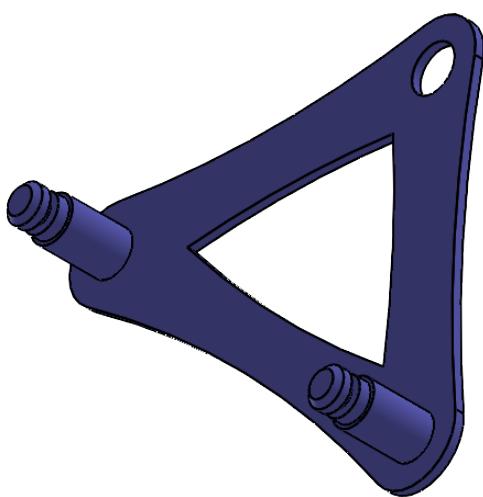
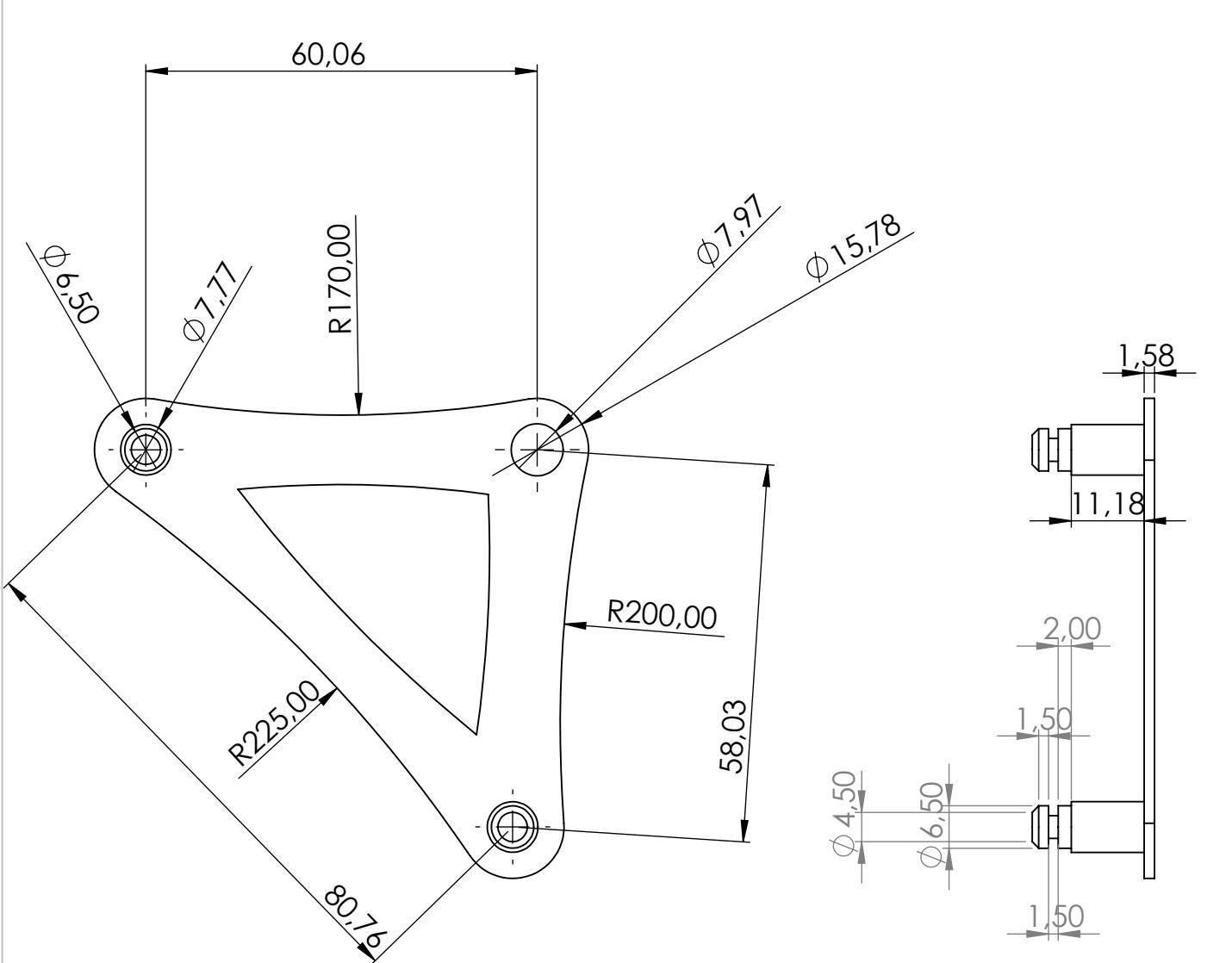
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 1:1	

## TITRE : Métatarse inférieure

Nbr pcs: 08

Unité: mm

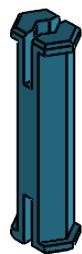
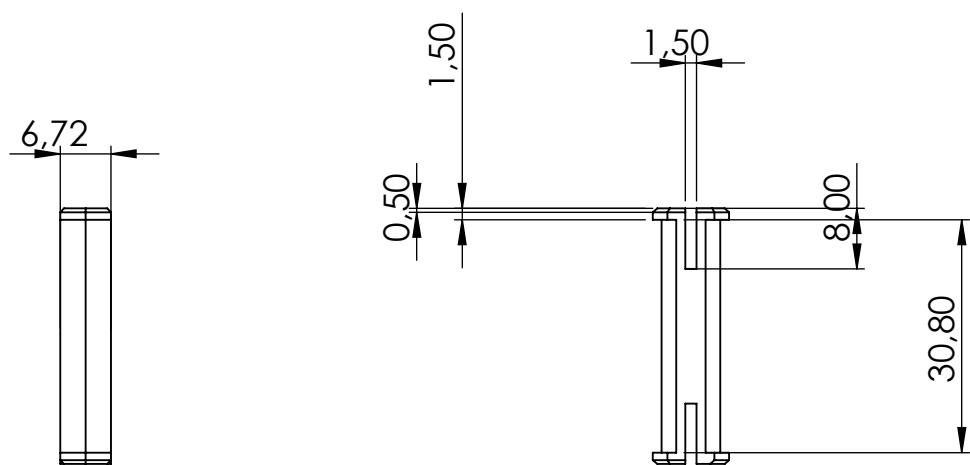
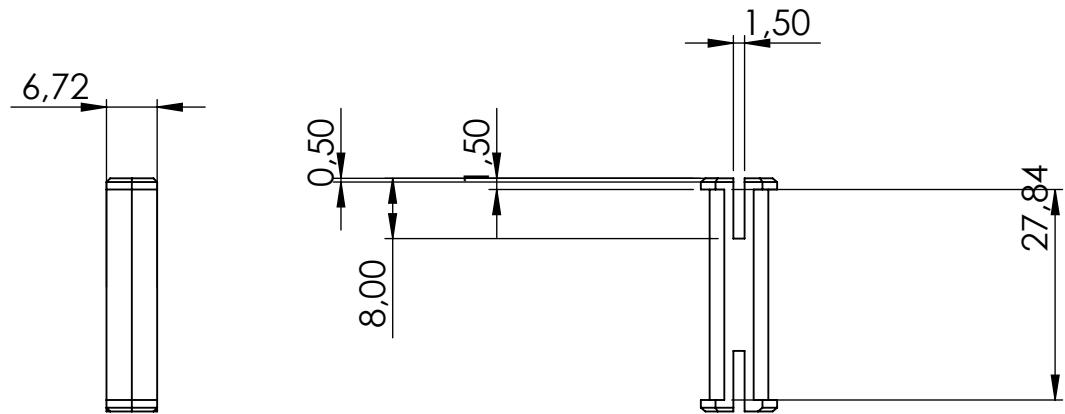
Matière: PLA

3A S1 ROBOTIQUE



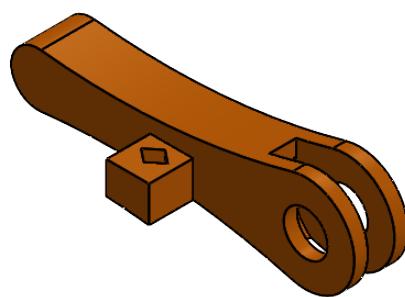
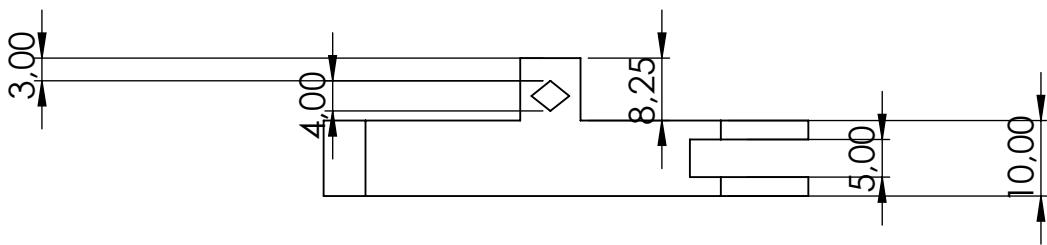
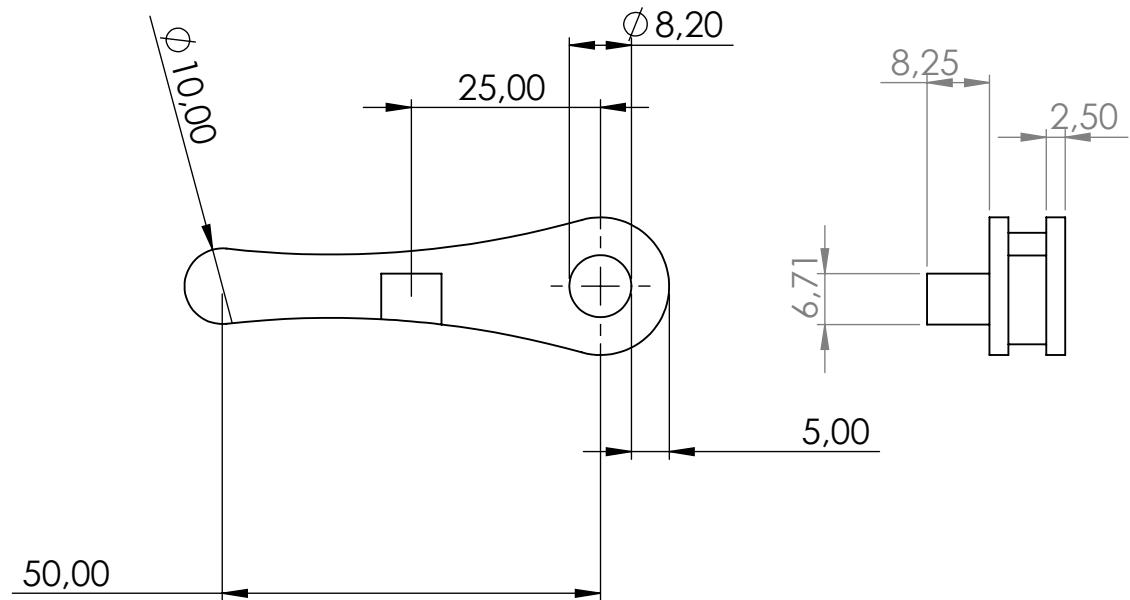
Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle: 1:1		Nbr pcs: 04
		Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	Encadré par: Mr DAVID FOIFI

## TITRE: Manivelle



Echelle: 1:1



## TITRE: Levier

Nbr pcs: 01

Unité: mm

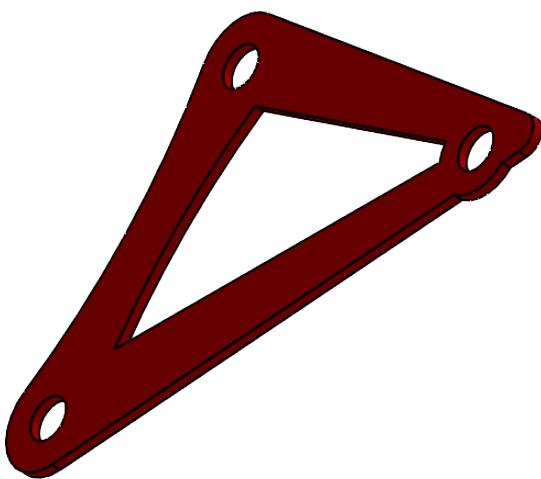
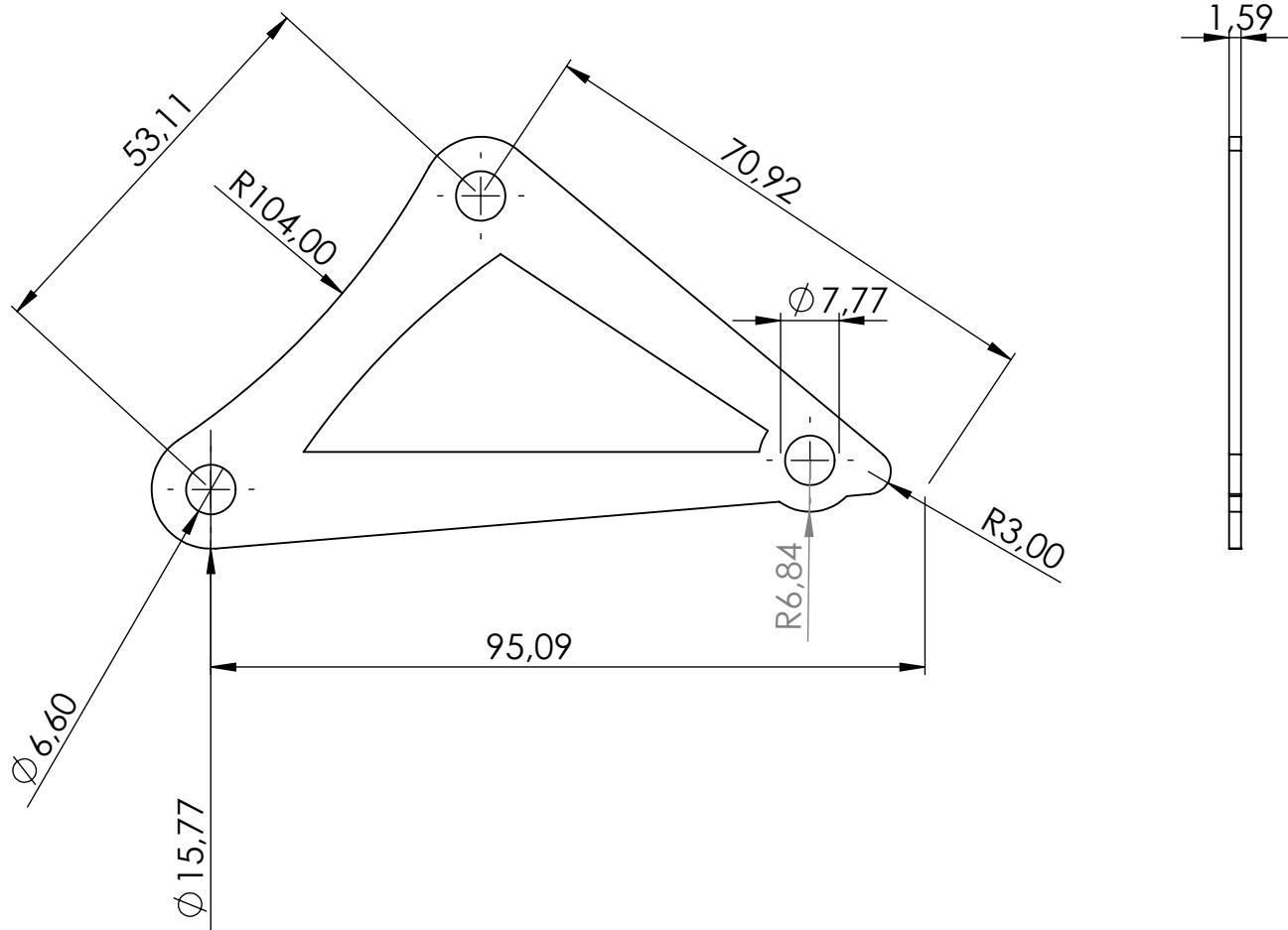
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025



Echelle: 1:2	

## TITRE: Griffe supérieure

Nbr pcs: 08

Unité: mm

Matière: PLA

3A S1 ROBOTIQUE



Encadré par:  
Mr DAVID FOIFI

Date: 10/12/2025