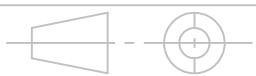

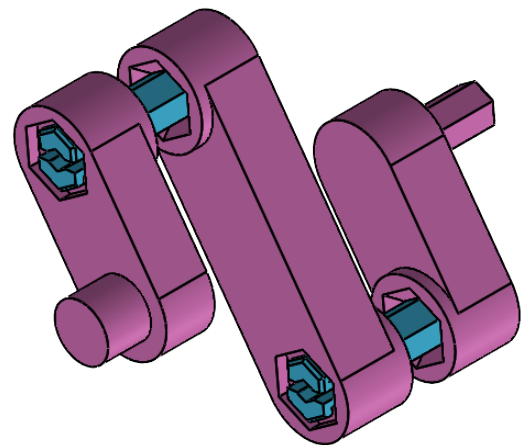
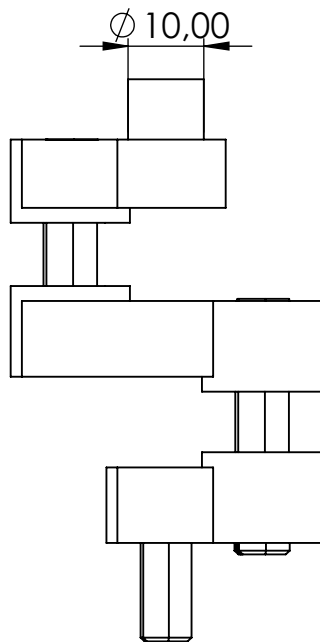
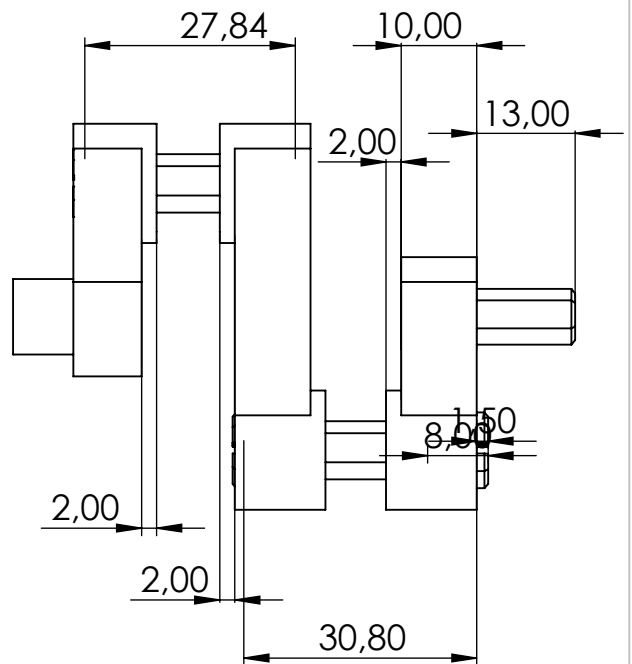
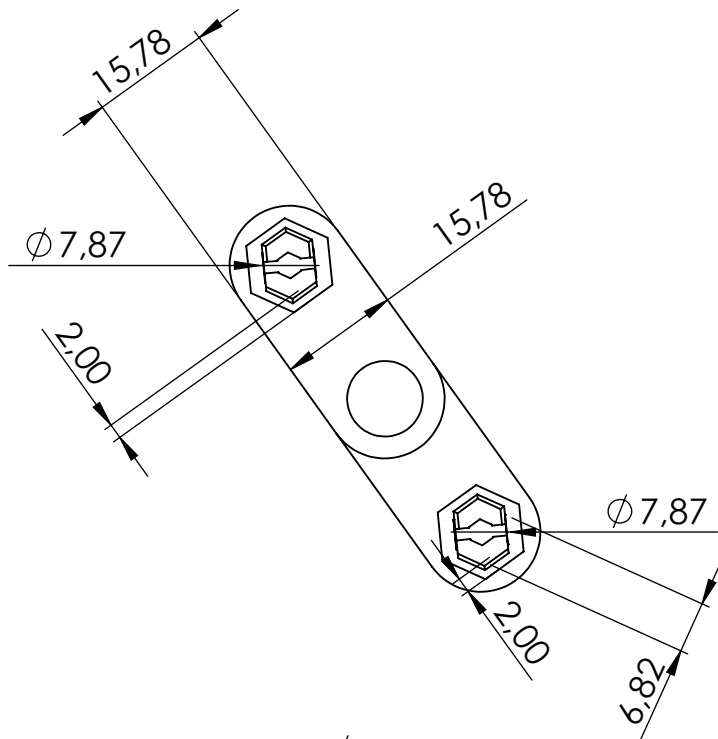


Echelle: 1:2	TITRE:Abdomen_supérieur			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH Nancy	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:1



TITRE: Assemblage comes

Nbr pcs: 01

Unité: mm

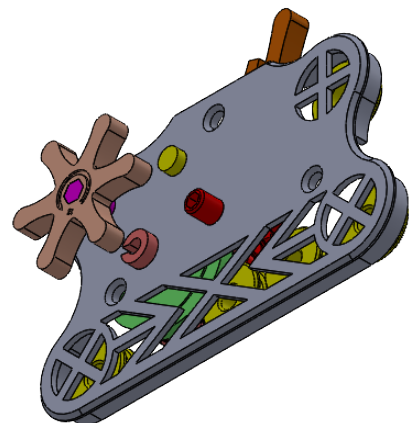
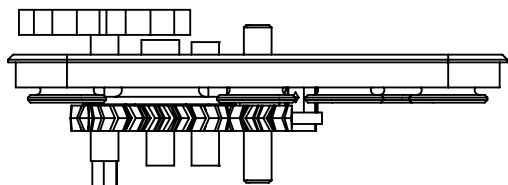
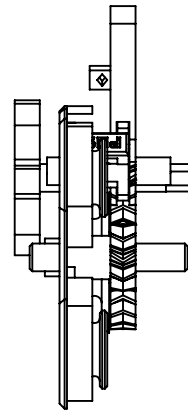
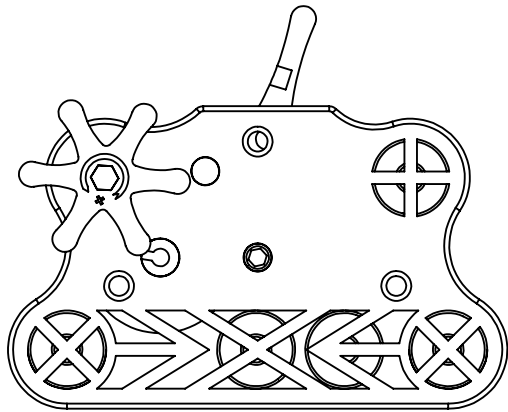
Matière: PLA

3A S1 ROBOTIQUE

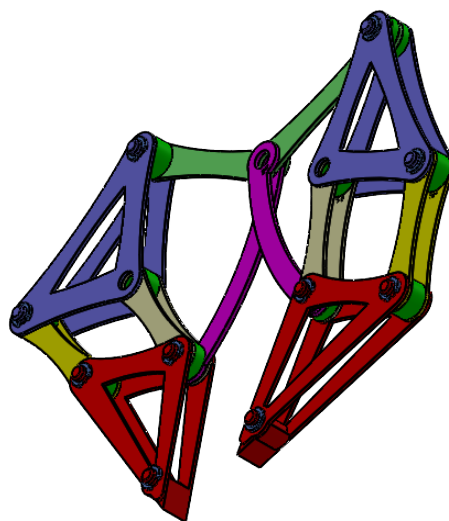
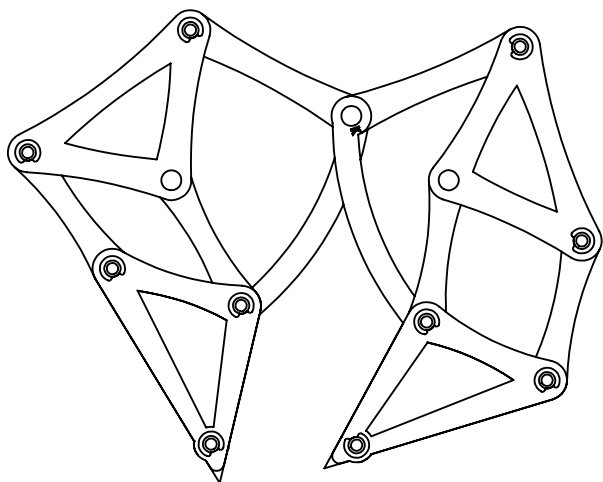


Encadré par:
Mr DAVID FOFI

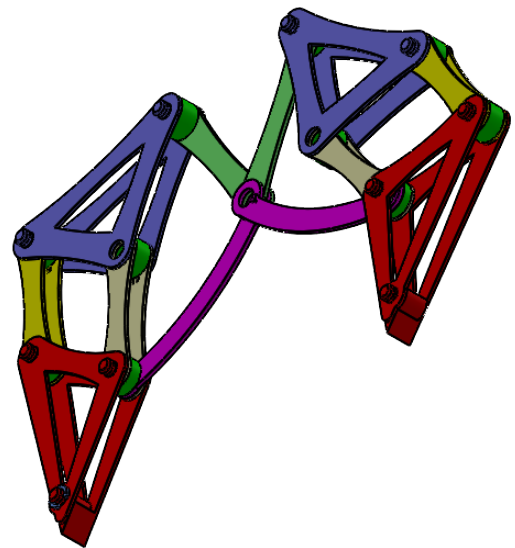
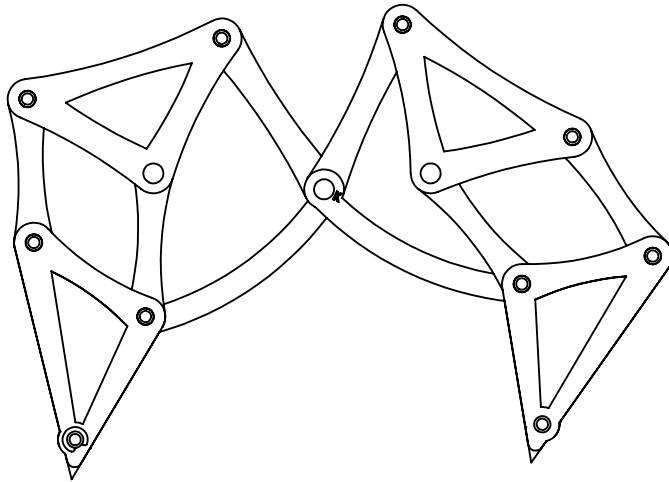
Date: 10/12/2025



Echelle: 1:2	TITRE:Assemblage moteur			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH lyon	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:3	TITRE:Assemblage pattes_1P			Nbr pcs: 02
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH univ	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:3



TITRE: Assemblage pattes_2P

Nbr pcs: 02

Unité: mm

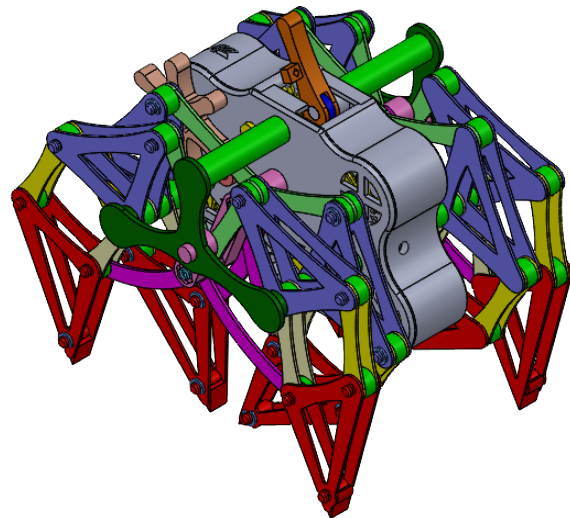
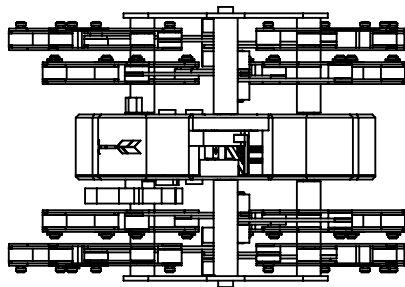
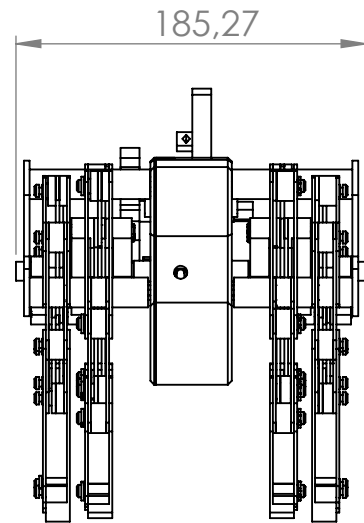
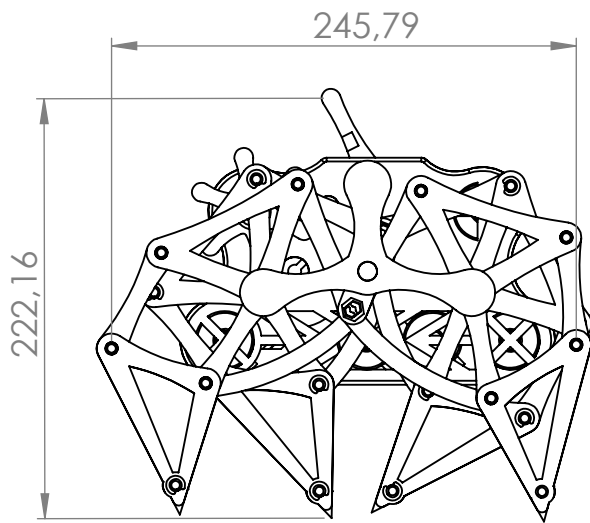
Matière: PLA

3A S1 ROBOTIQUE

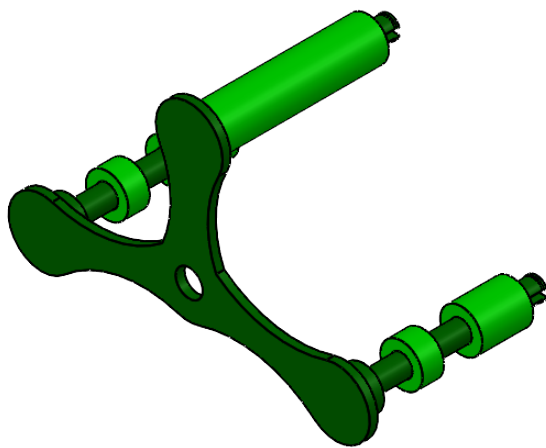
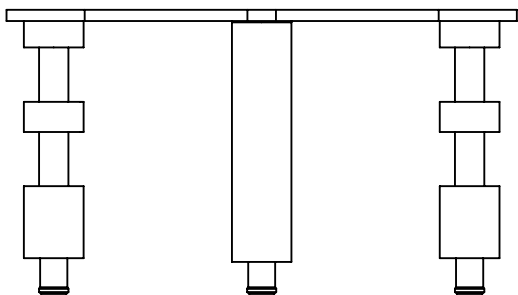
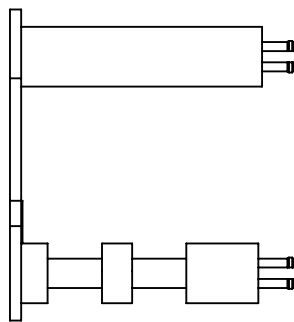
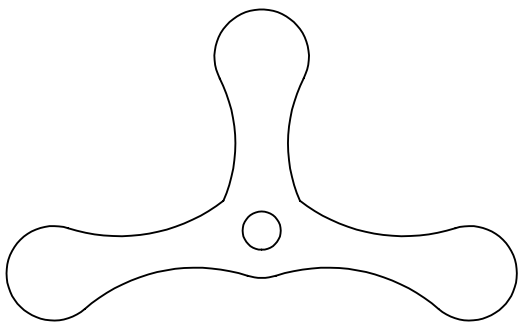


Encadré par:
Mr DAVID FOFI

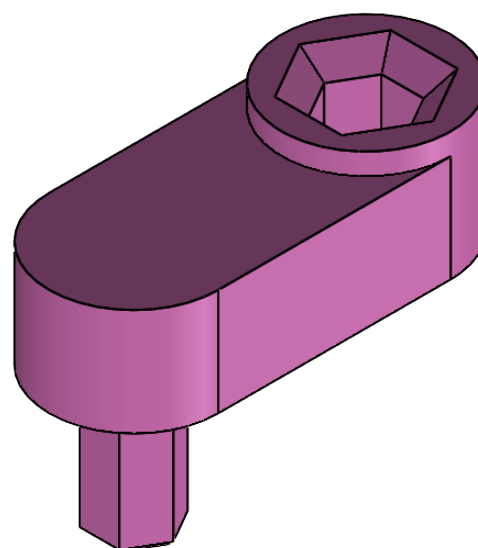
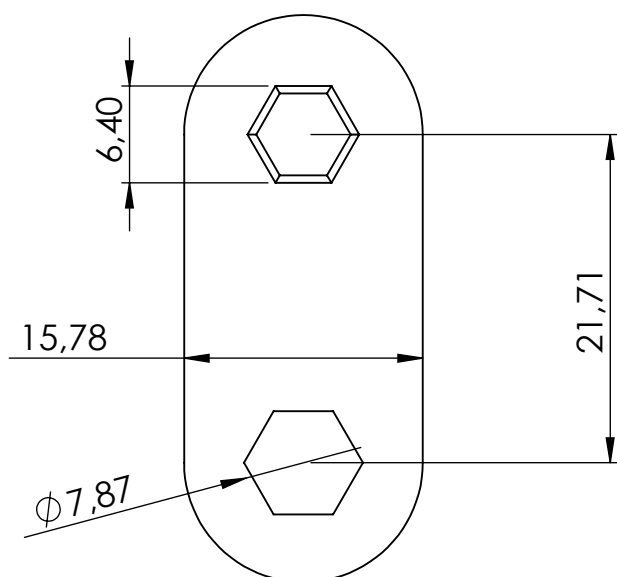
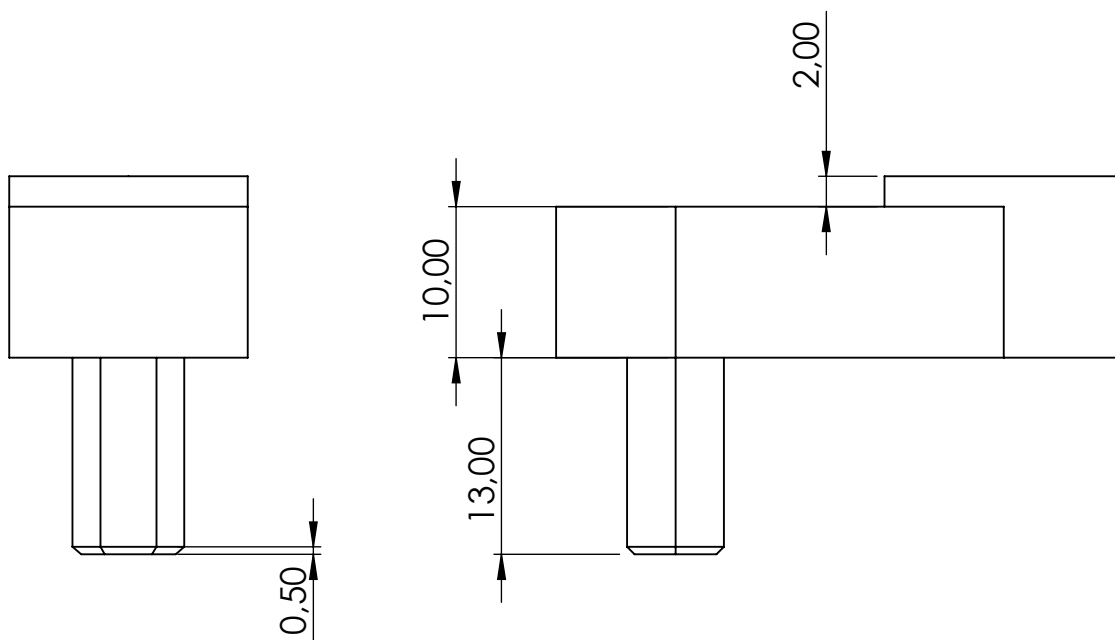
Date: 10/12/2025




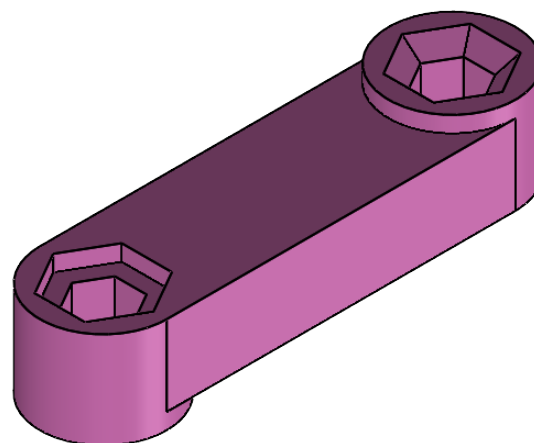
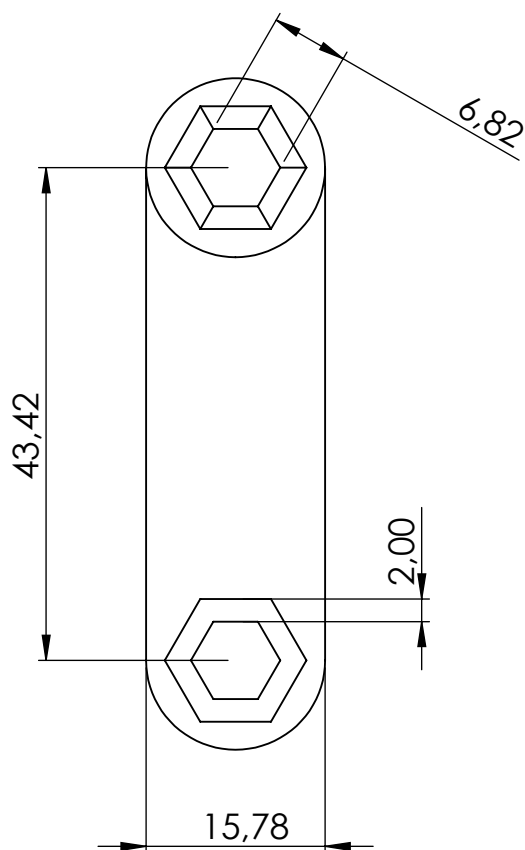
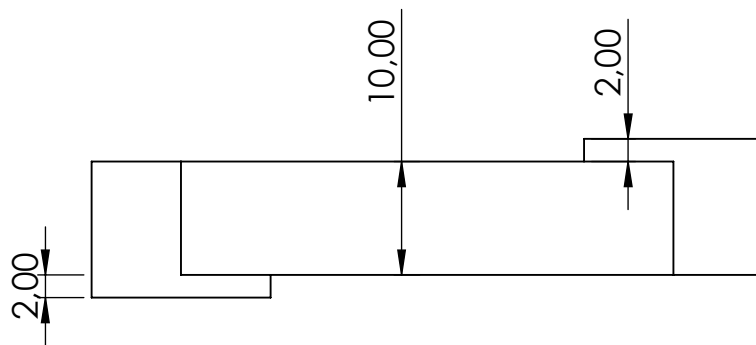
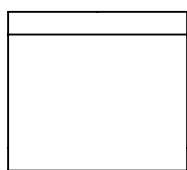
Echelle: 1:4	TITRE:Assemblage Strandbeest			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:2	TITRE:Assemblage support			Nbr pcs: 02
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH univ	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 2:1	TITRE: Bielle		Nbr pcs: 02
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH Nancy	Encadré par: Mr DAVID FOFI
Date: 10/12/2025			



Echelle: 1.5:1



TITRE: Bielle_2P

Nbr pcs: 02

Unité: mm

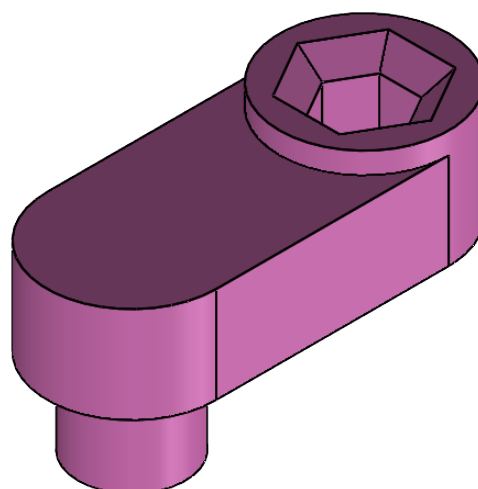
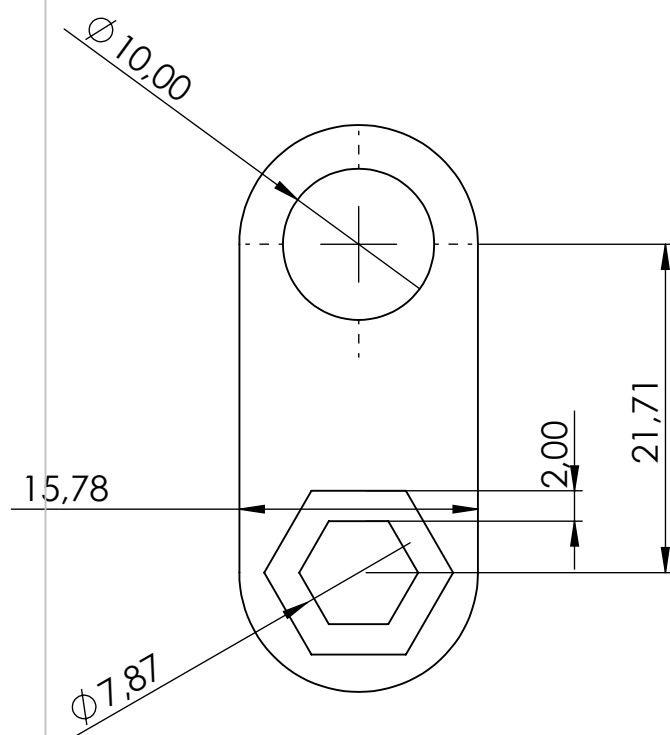
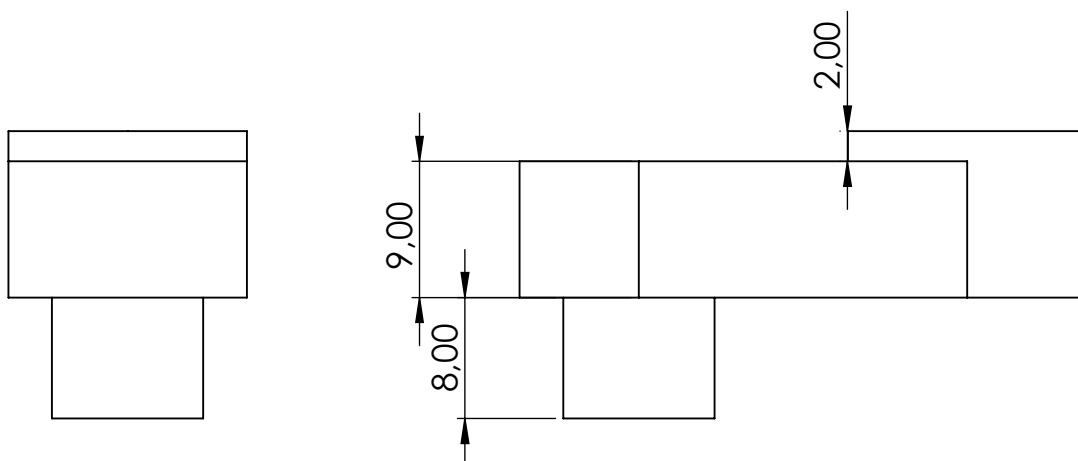
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 2:1



TITRE: Bielle_terminale

Nbr pcs: 02

Unité: mm

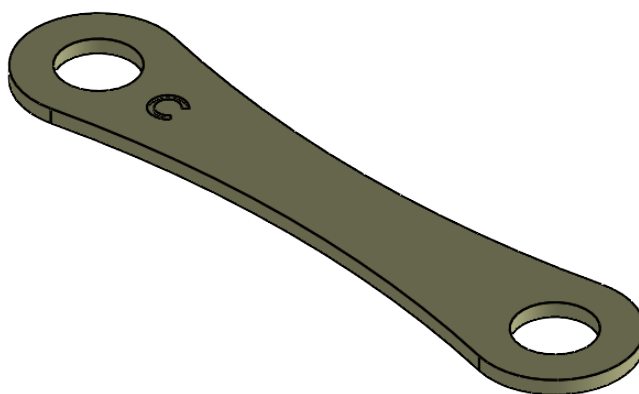
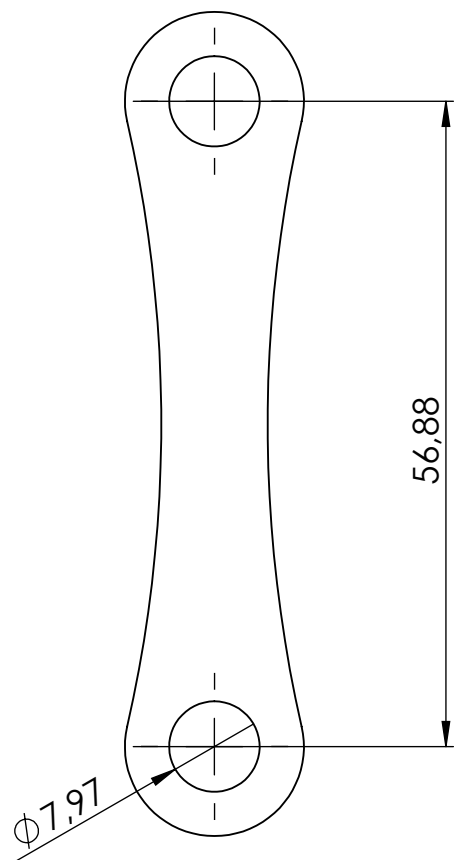
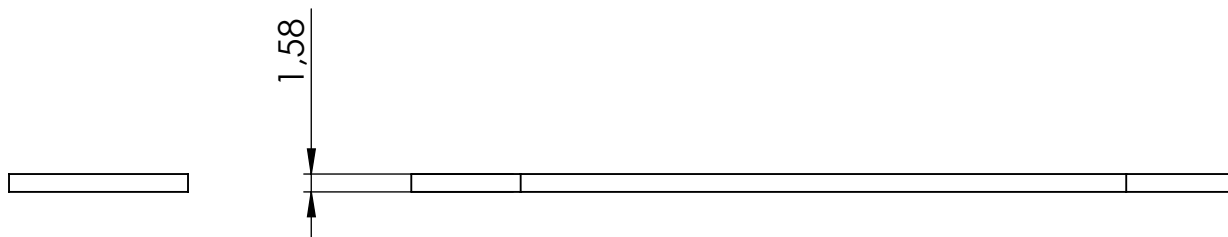
Matière: PLA

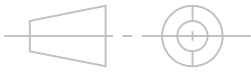

3A S1 ROBOTIQUE

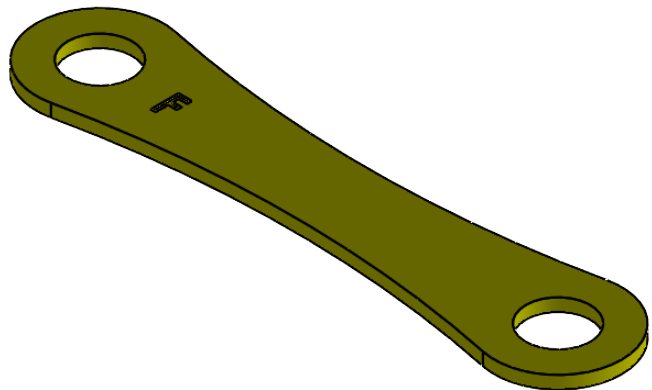
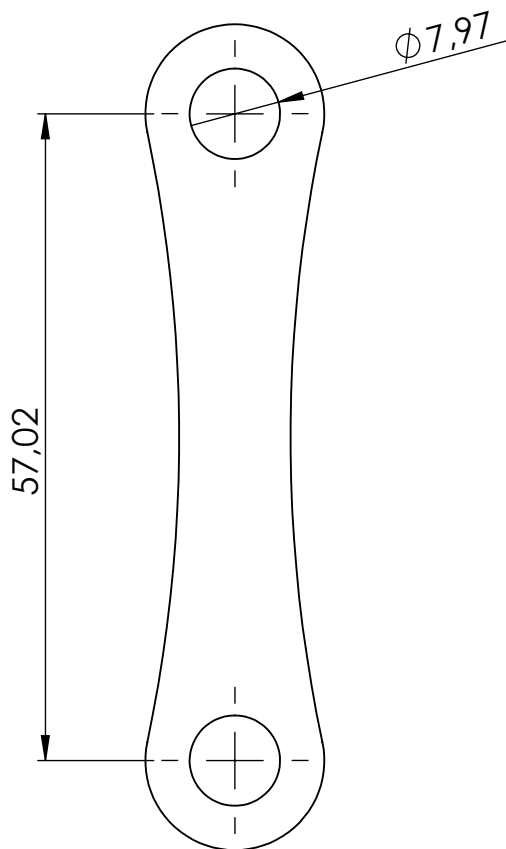
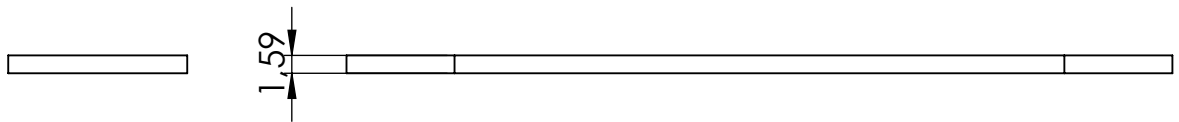




Encadré par:
Mr DAVID FOFI

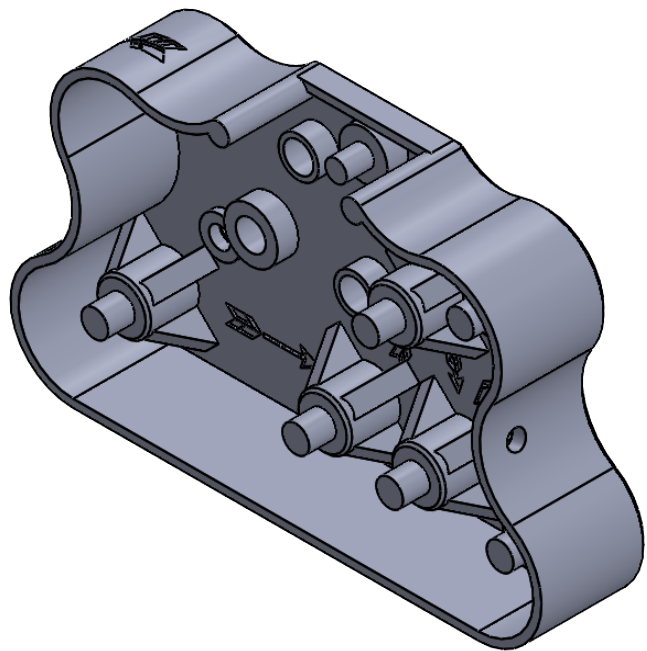
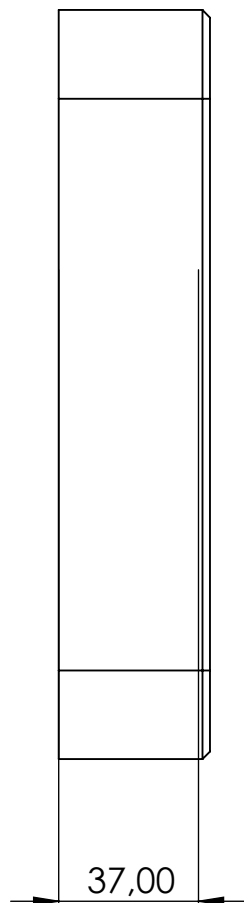
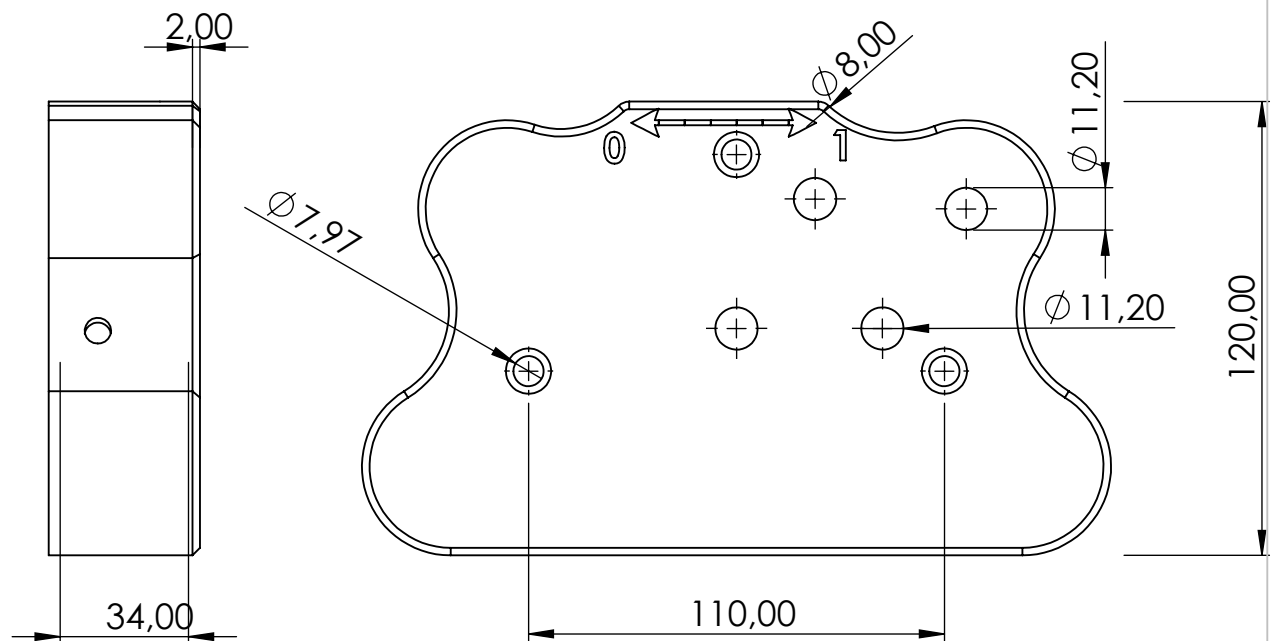
Date: 10/12/2025



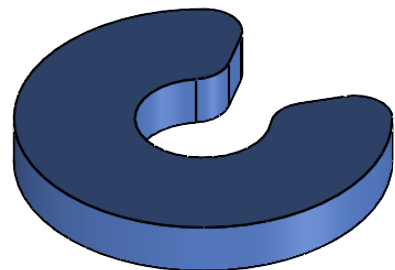
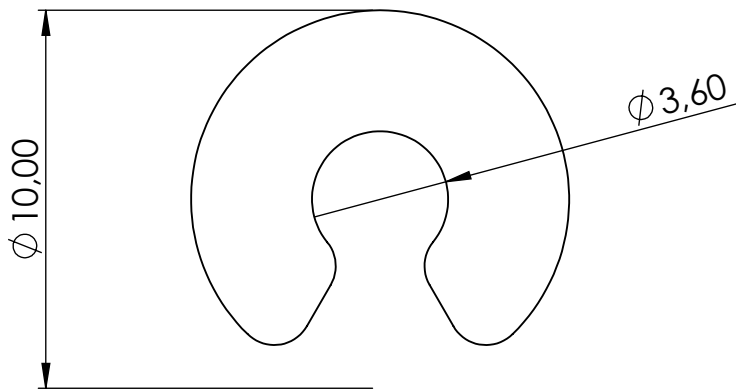
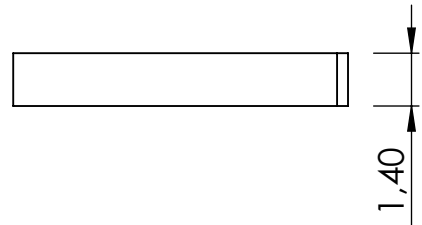
Echelle: 1.5:1	TITRE: Fémur C		Nbr pcs: 16
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
			Date: 10/12/2025



Echelle: 1.5:1	TITRE: Fémur F		Nbr pcs: 16
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
			Date: 10/12/2025



Echelle: 1:2	TITRE:Abdomen_inferieur			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 5:1



TITRE: Circlip

Nbr pcs: 40

Unité: mm

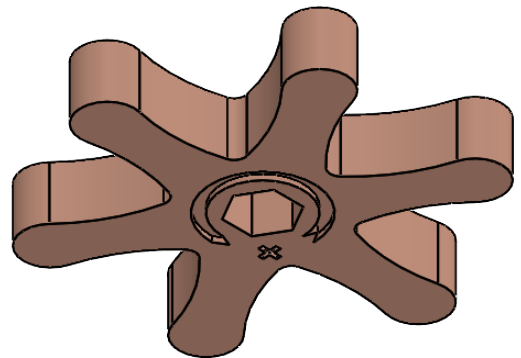
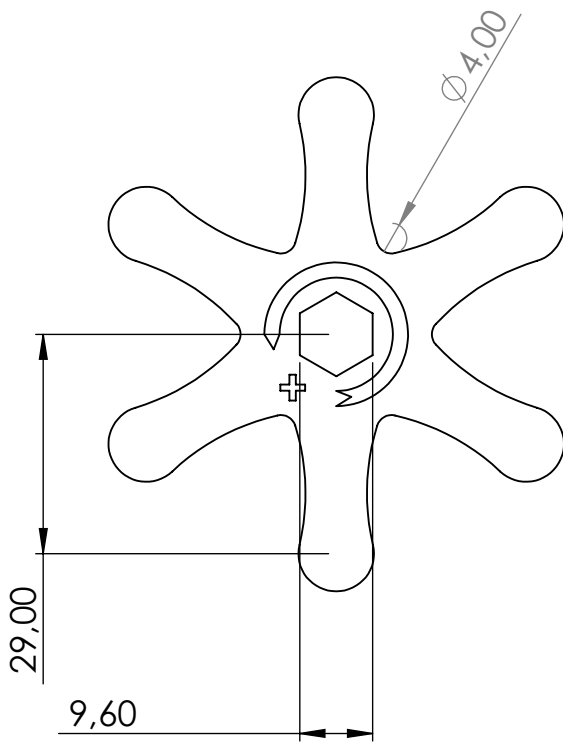
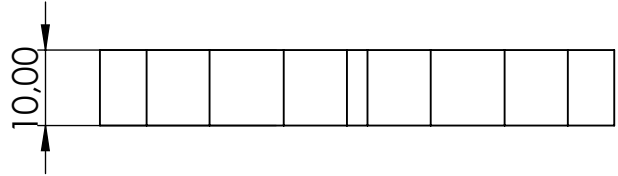
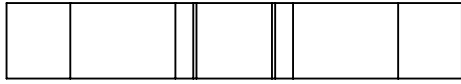
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 1:1



TITRE: Clé

Nbr pcs: 01

Unité: mm

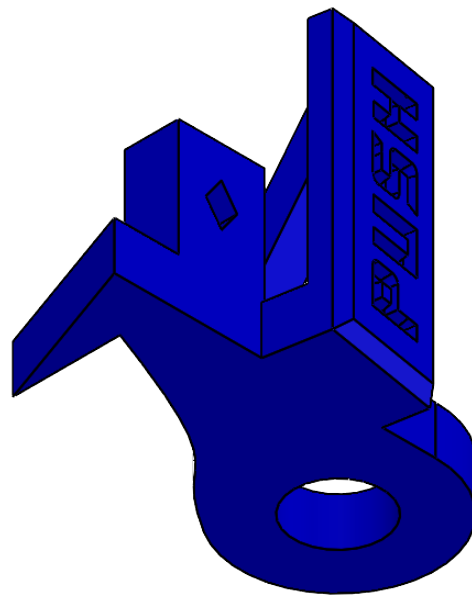
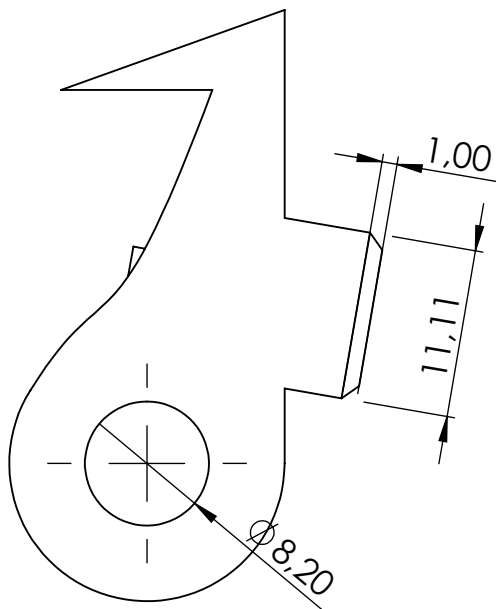
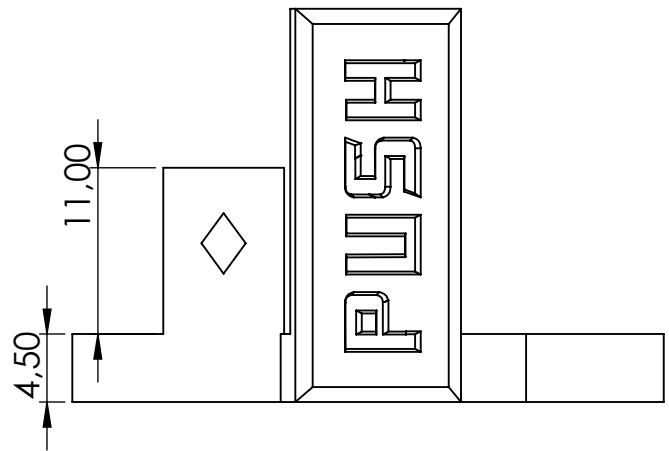
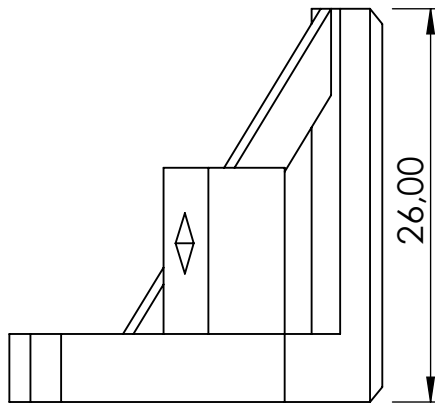
Matière: PLA



3A S1 ROBOTIQUE

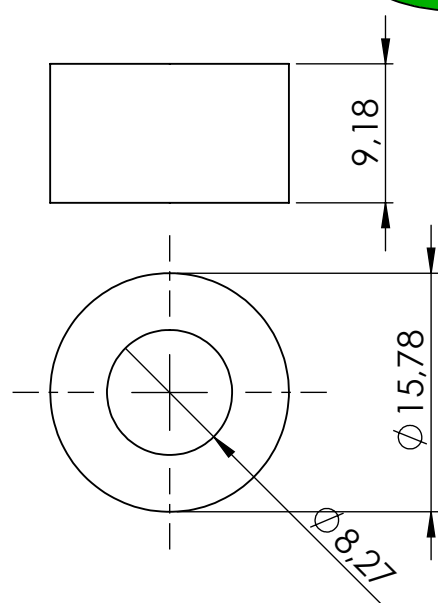
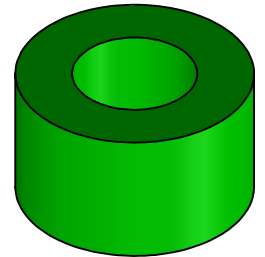
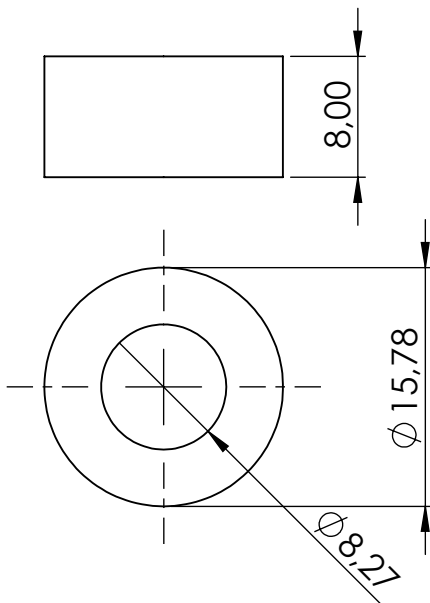
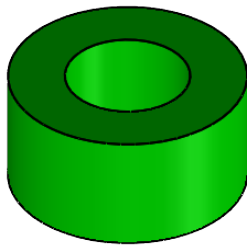
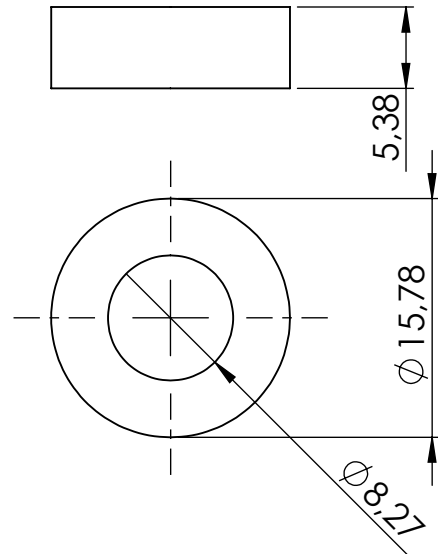
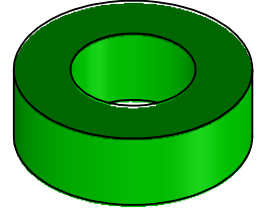
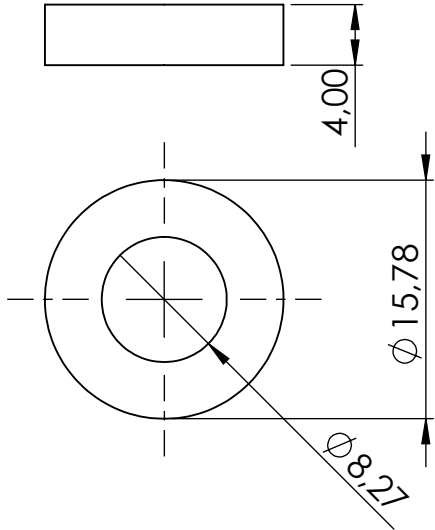
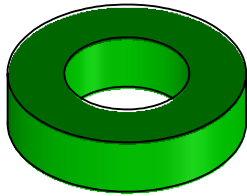


Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 2:1	TITRE : Crochet			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH univ	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 2:1



TITRE: Entroises

Nbr pcs: 48

Unité: mm

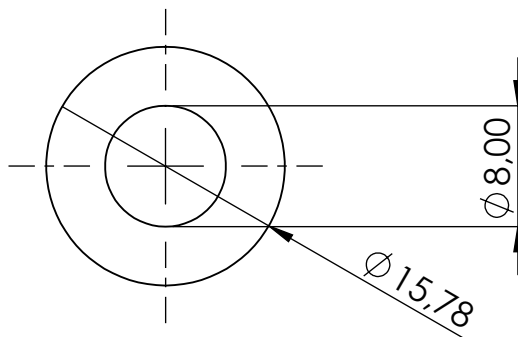
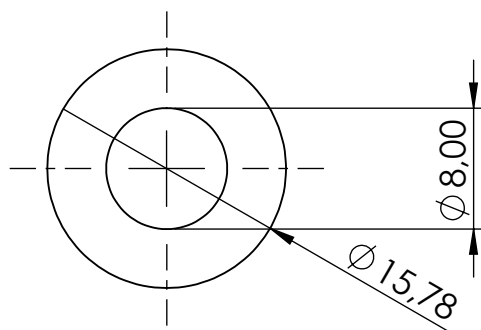
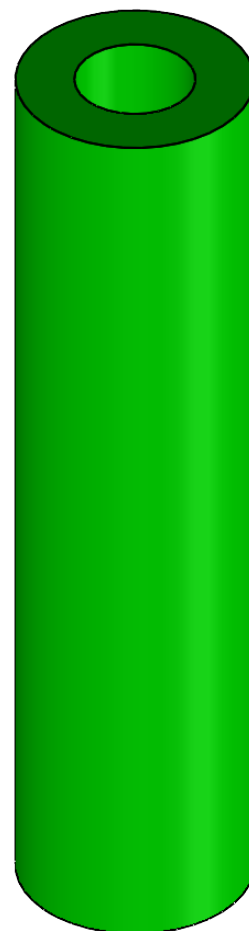
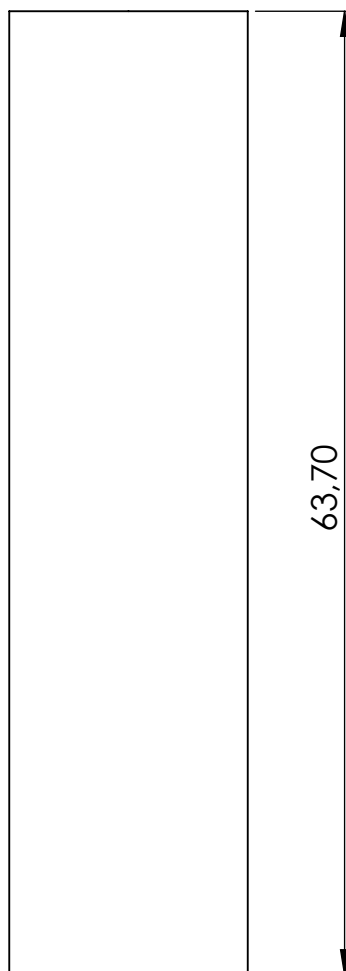
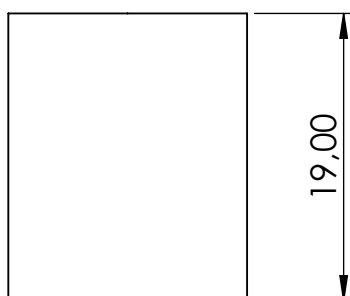
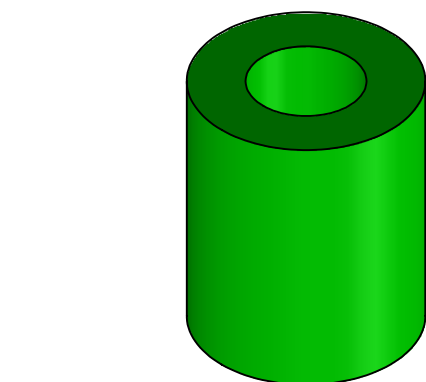
Matière: PLA

3A S1 ROBOTIQUE

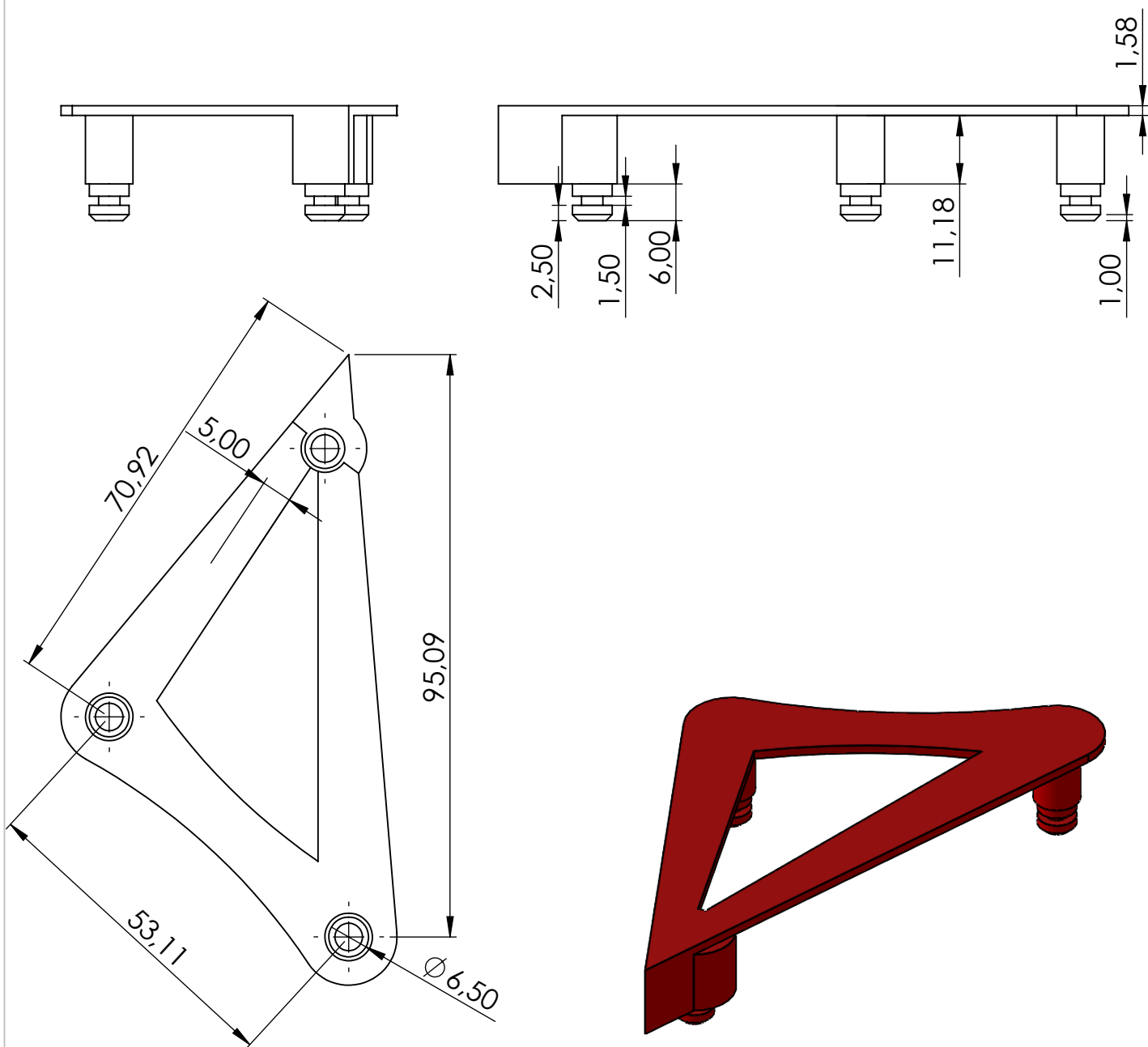


Encadré par:
Mr DAVID FOFI

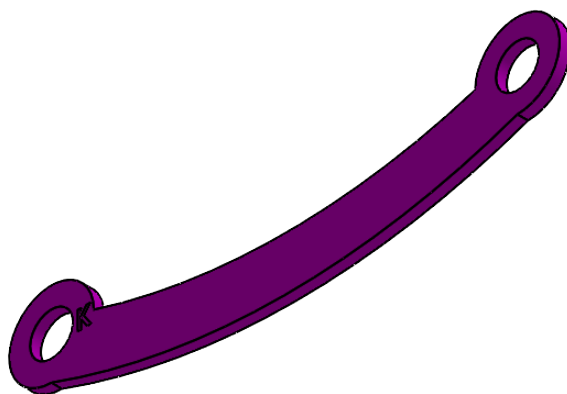
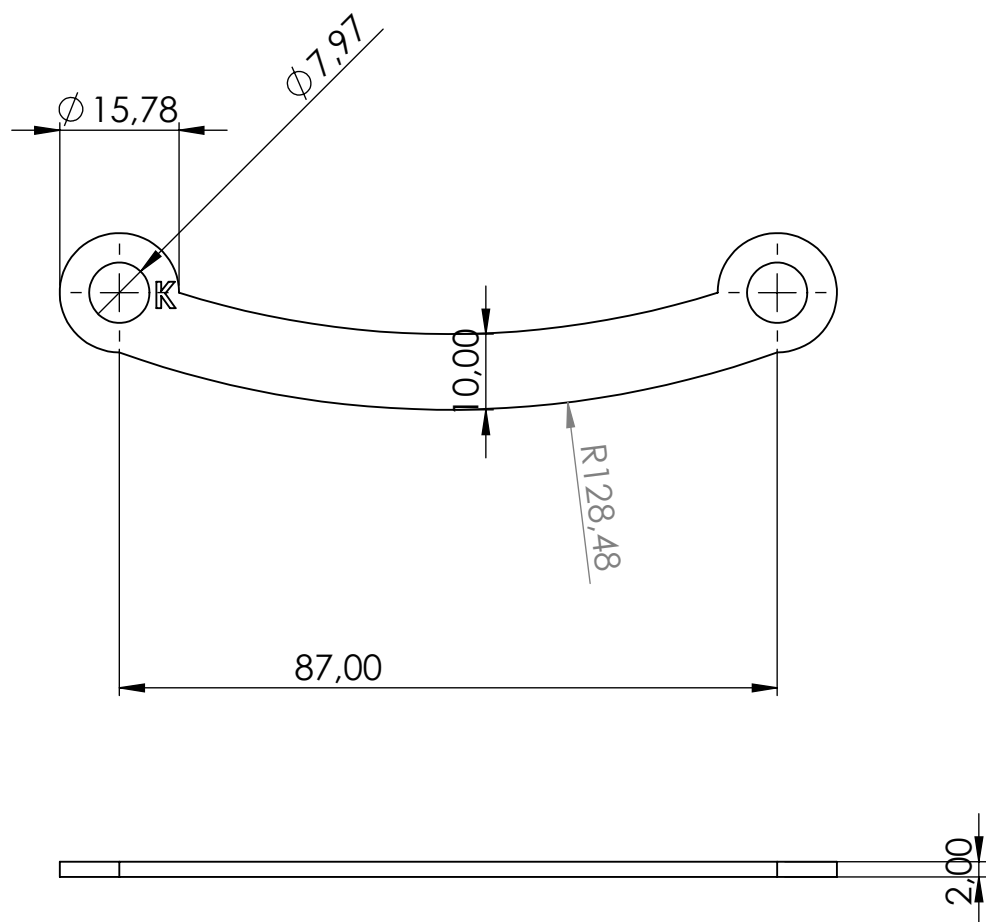
Date: 10/12/2025



Echelle: 2:1	TITRE:Entroises longues			Nbr pcs: 06
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH UNIVERSITÉ	Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:1	TITRE: Griffe		Nbr pcs: 08
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOFI
Date: 10/12/2025			



Echelle: 1:2



TITRE: Tibia

Nbr pcs: 08

Unité: mm

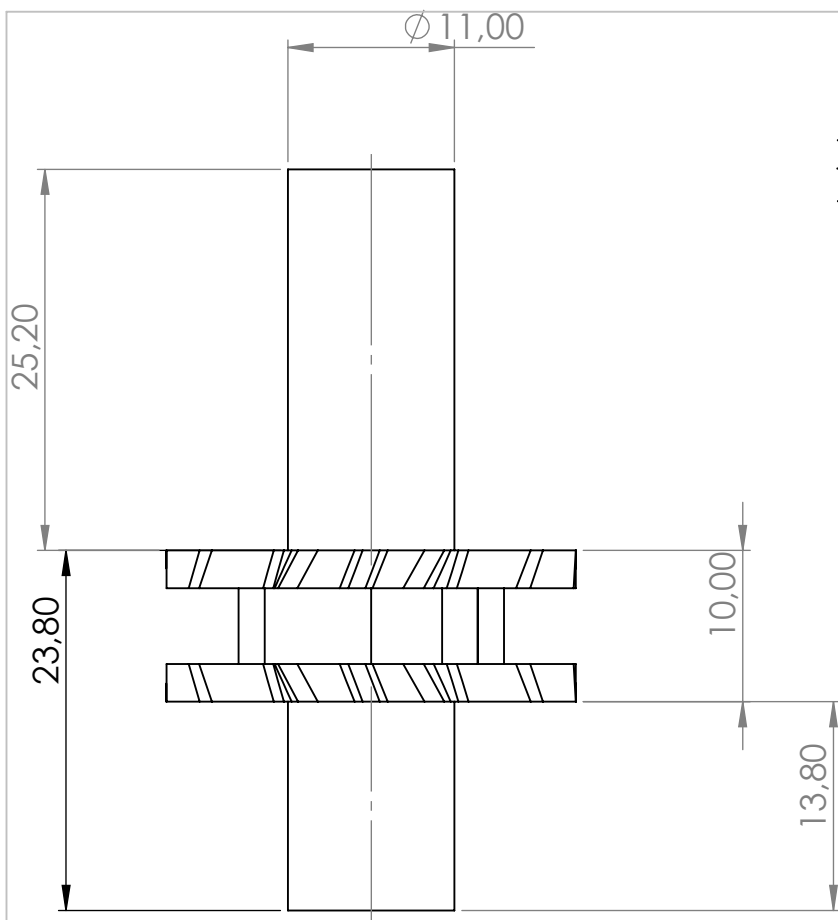
Matière: PLA

3A S1 ROBOTIQUE



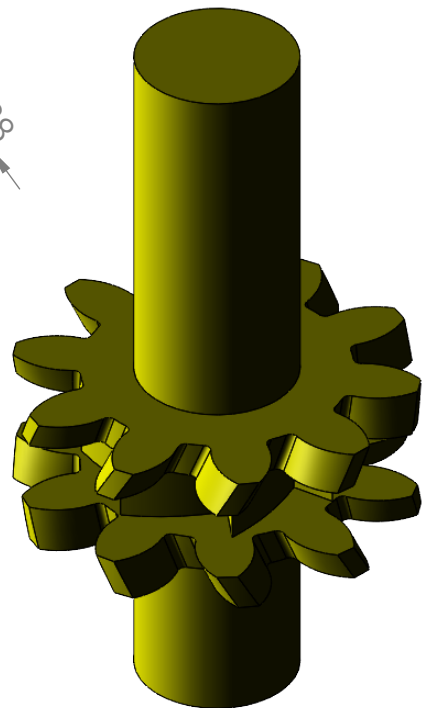
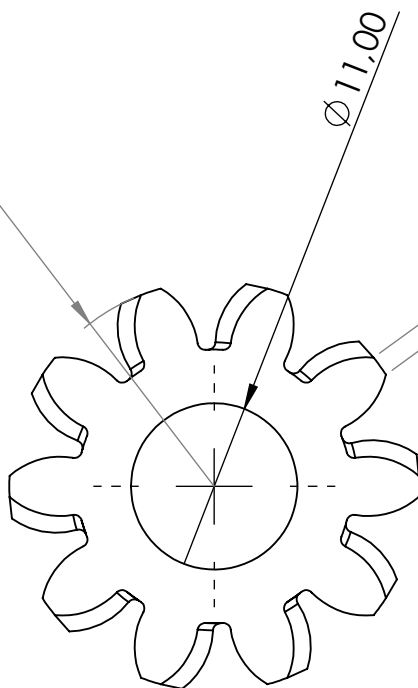
Encadré par:
Mr DAVID FOFI

Date: 10/12/2025

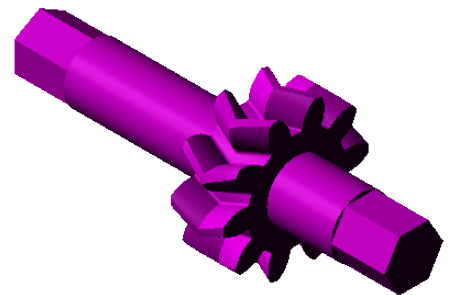
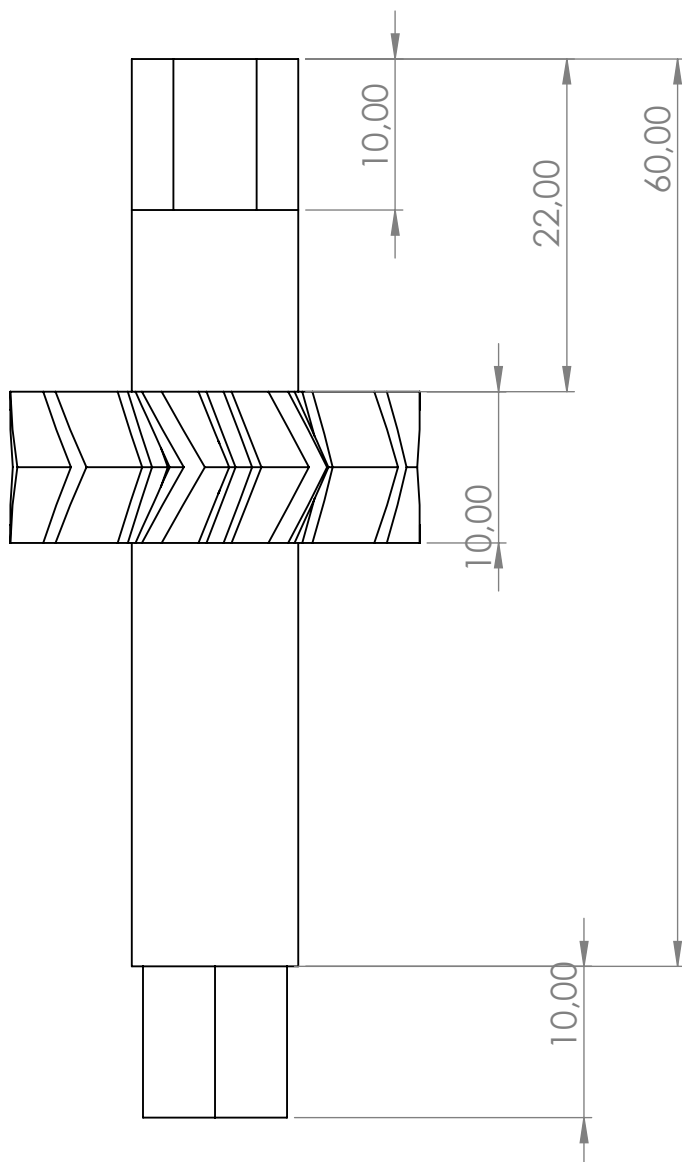
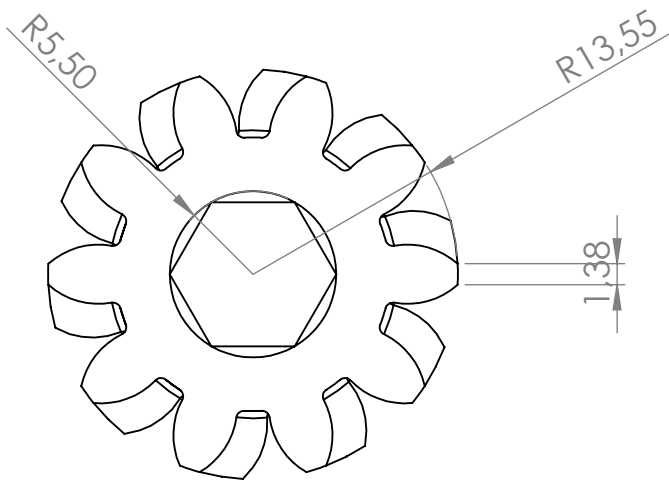




Denture en chevron
Module : 2
Nb dents : 10

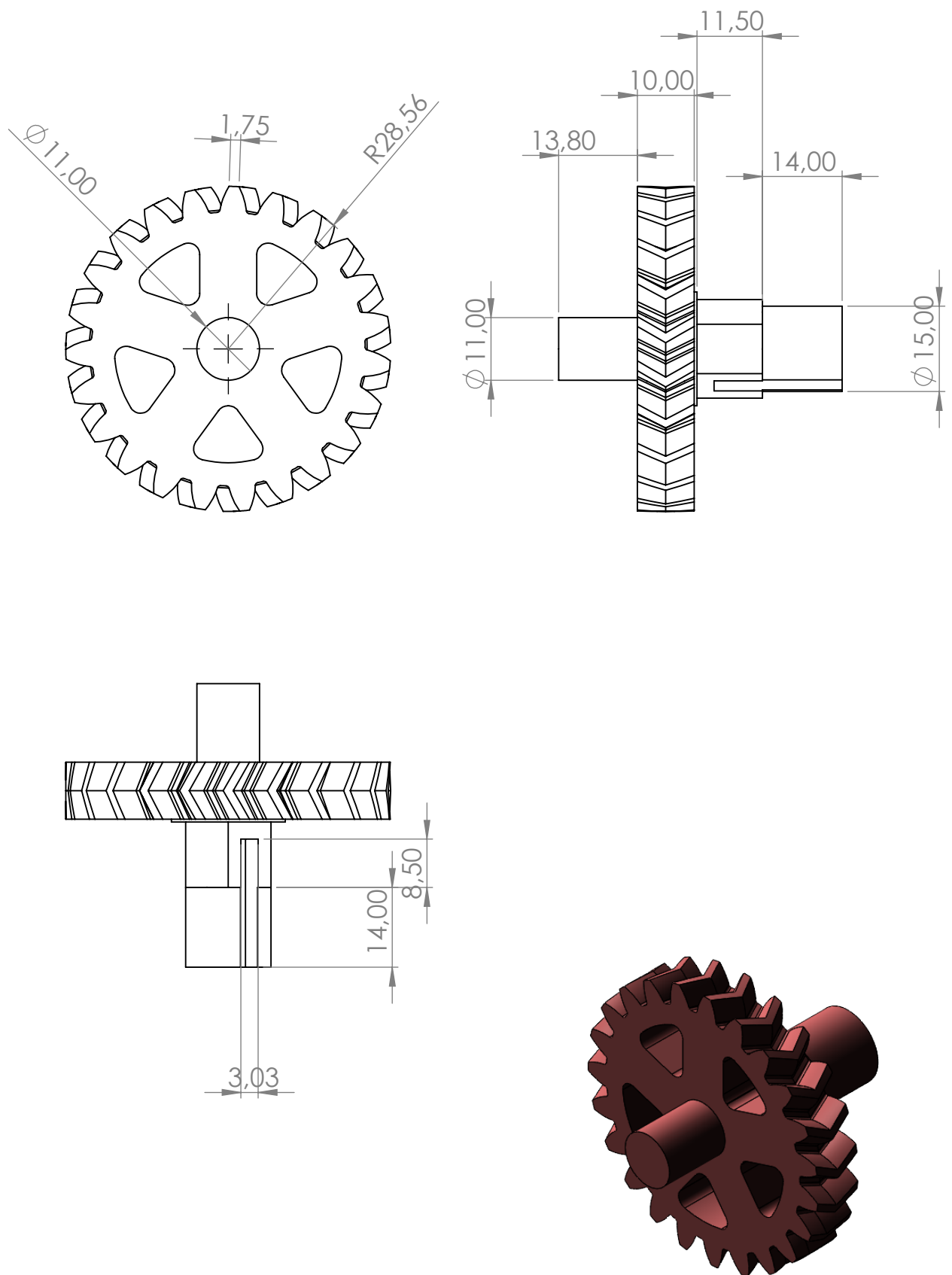
R13,55



Echelle: 1:1	TITRE: Roue libre			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:1	TITRE: Roue d'entrée		Nbr pcs: 01
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
			Date: 10/12/2025



Echelle: 1:1



TITRE: Roue d'enroulement

Nbr pcs: 01

Unité: mm

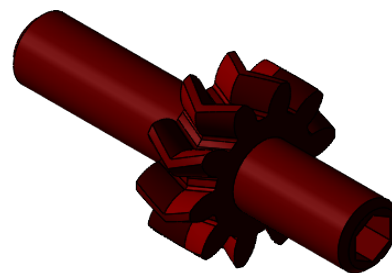
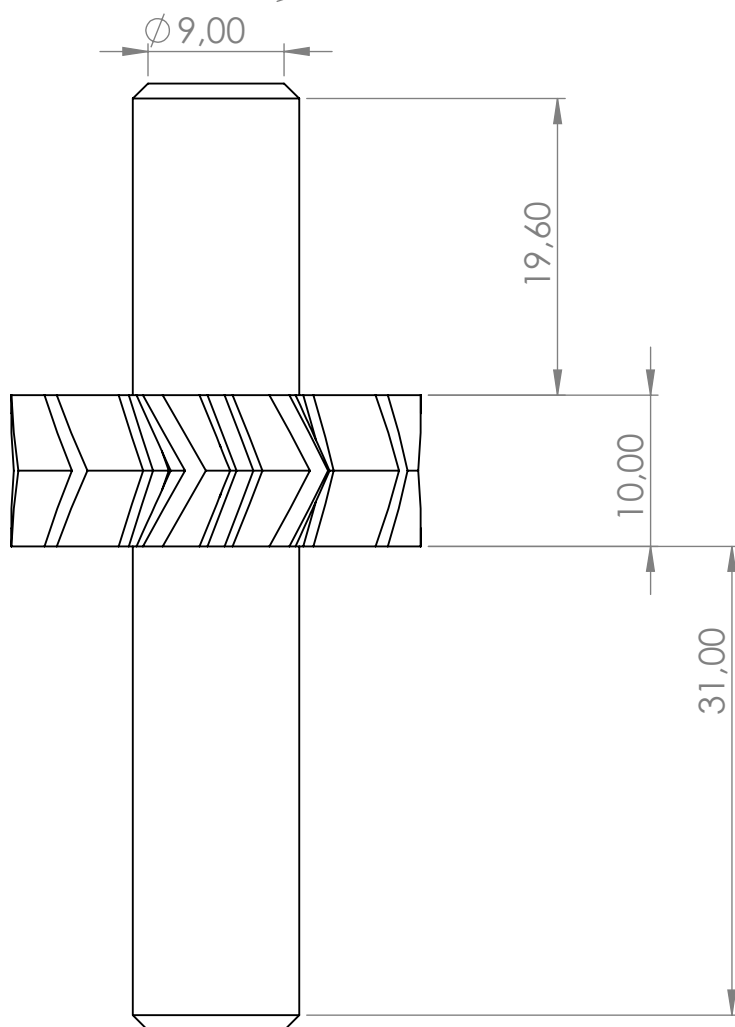
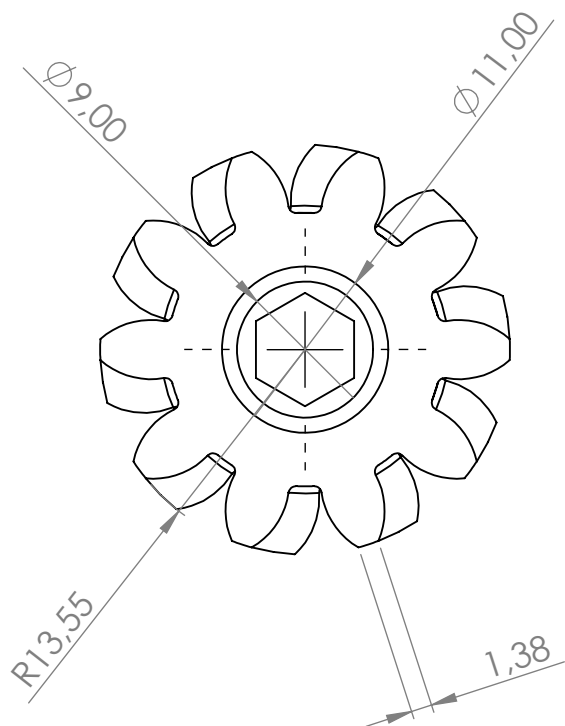
Matière: PLA

3A S1 ROBOTIQUE

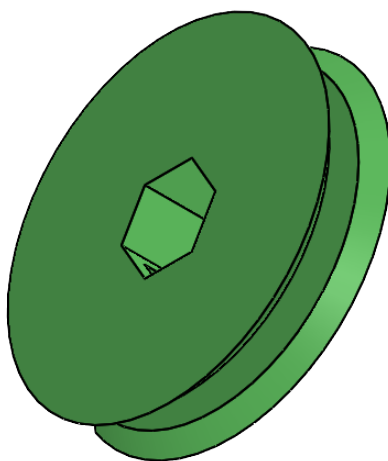
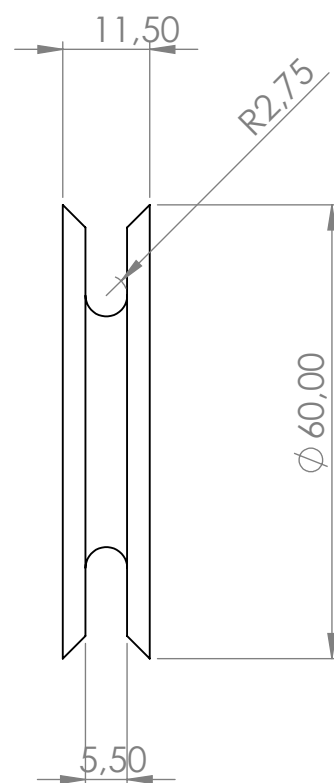
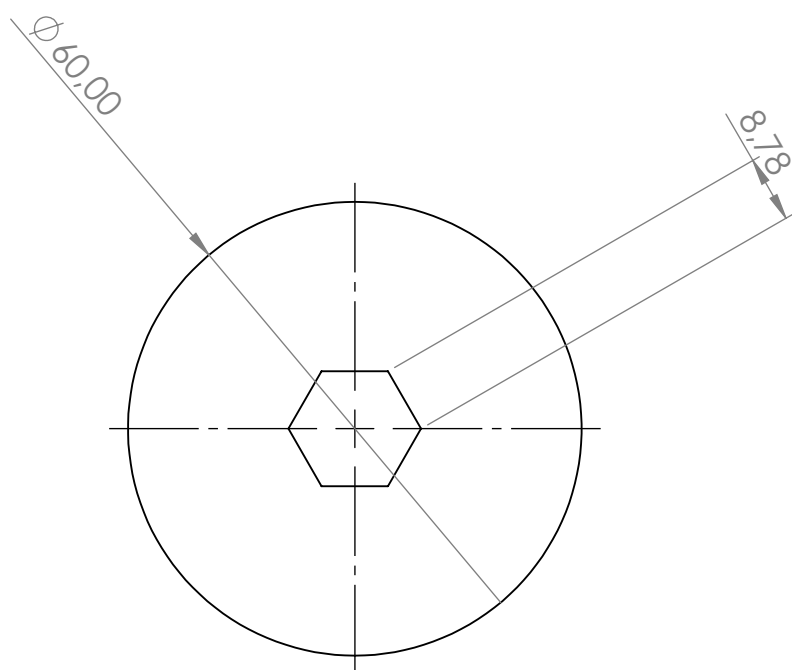


Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 2:1	TITRE: Roue de sortie			Nbr pcs: 01
				Unité: mm
Matière: PLA	3A S1 ROBOTIQUE		Encadré par: Mr DAVID FOFI	Date:10/12/2025



Echelle: 1:1



TITRE: Poulie

Nbr pcs: 01

Unité: mm

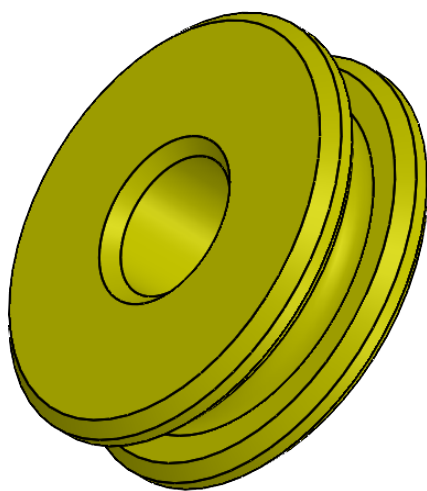
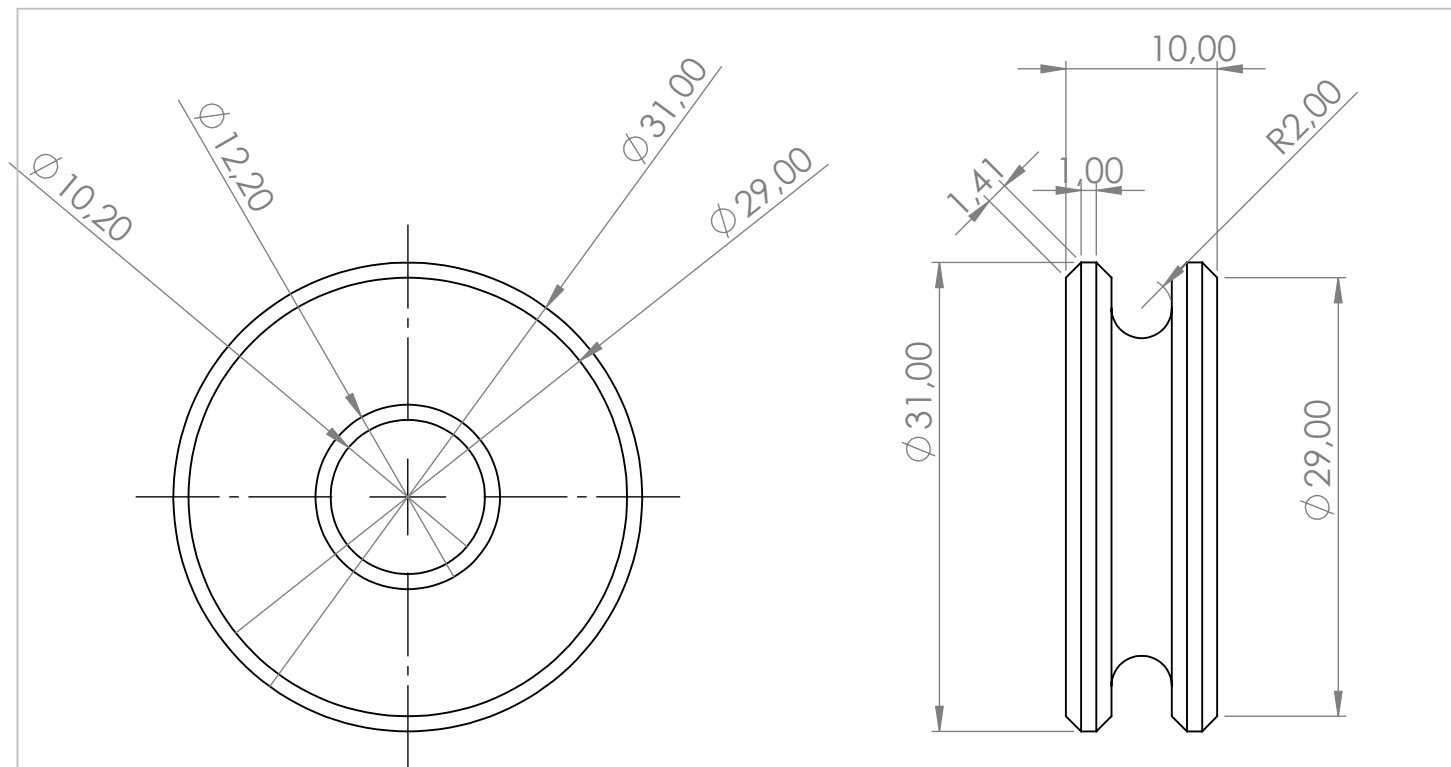
Matière: PLA

3A S1 ROBOTIQUE



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Date: 10/12/2025



Echelle: 2:1



TITRE: Poulie renvoi d'angle

Nbr pcs: 06

Unité: mm

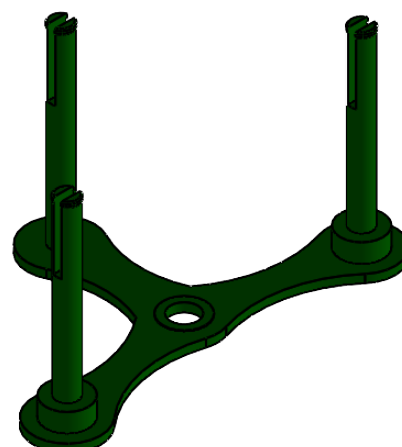
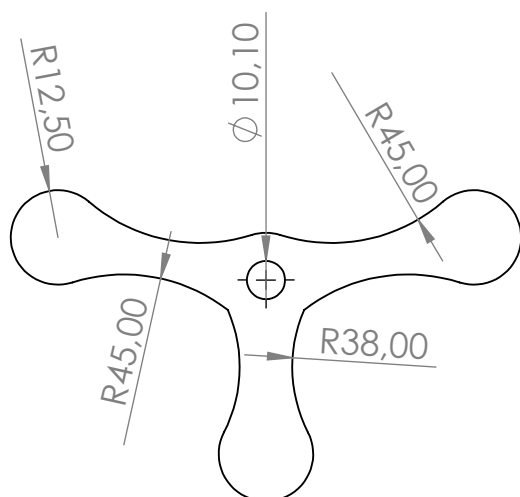
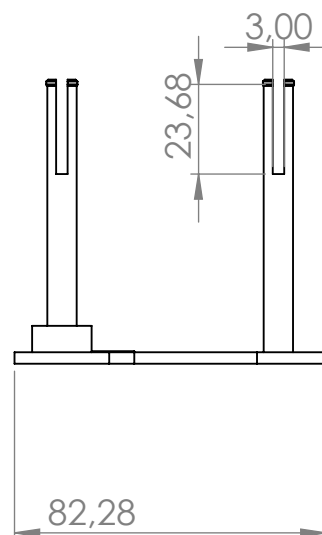
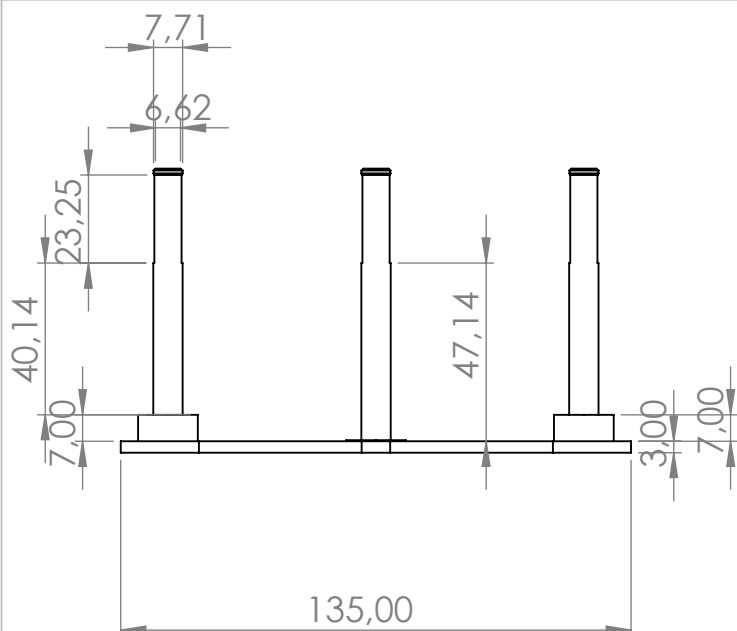
Matière: PLA

3A S1 ROBOTIQUE



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Date: 10/12/2025



Echelle: 1:2



TITRE: Pédicelle

Nbr pcs: 02

Unité: mm

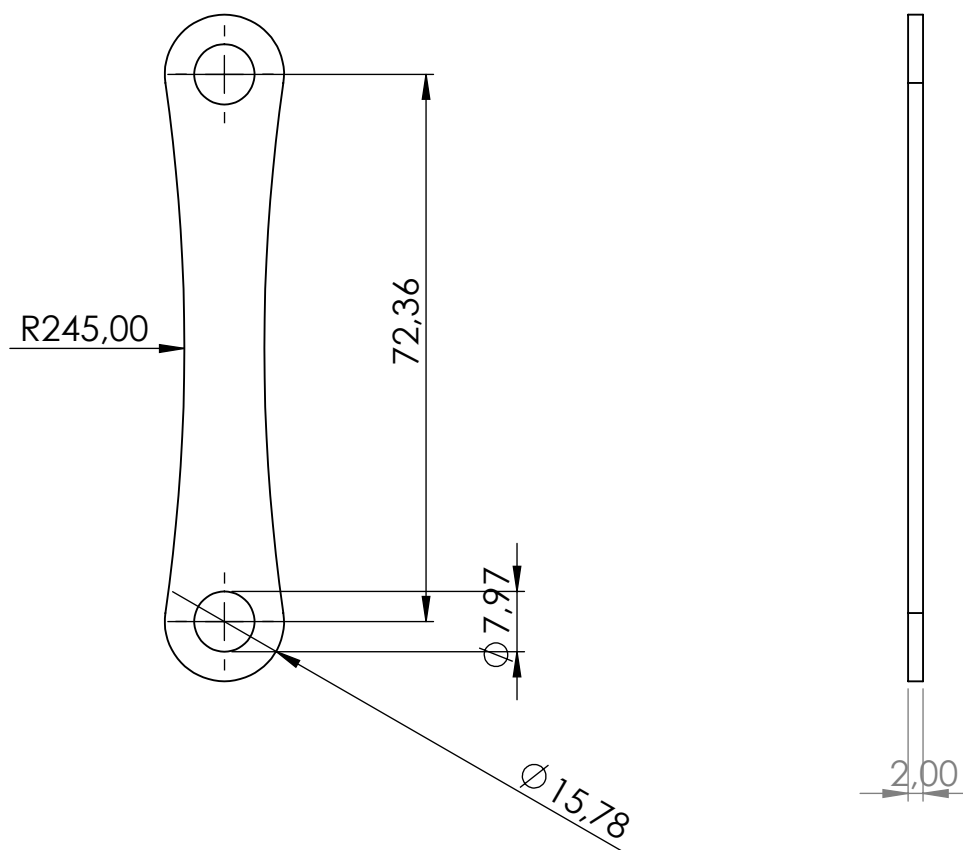
Matière: PLA

3A S1 ROBOTIQUE



Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 1:1



TITRE: Patella J

Nbr pcs: 08

Unité: mm

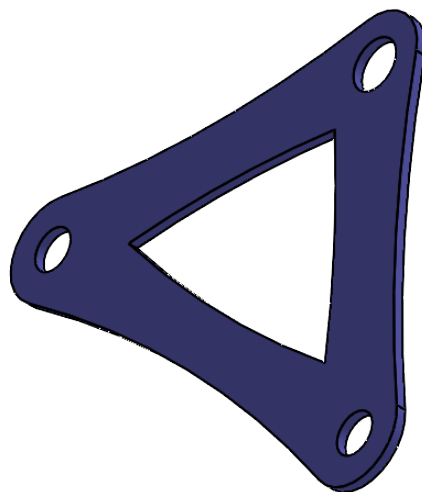
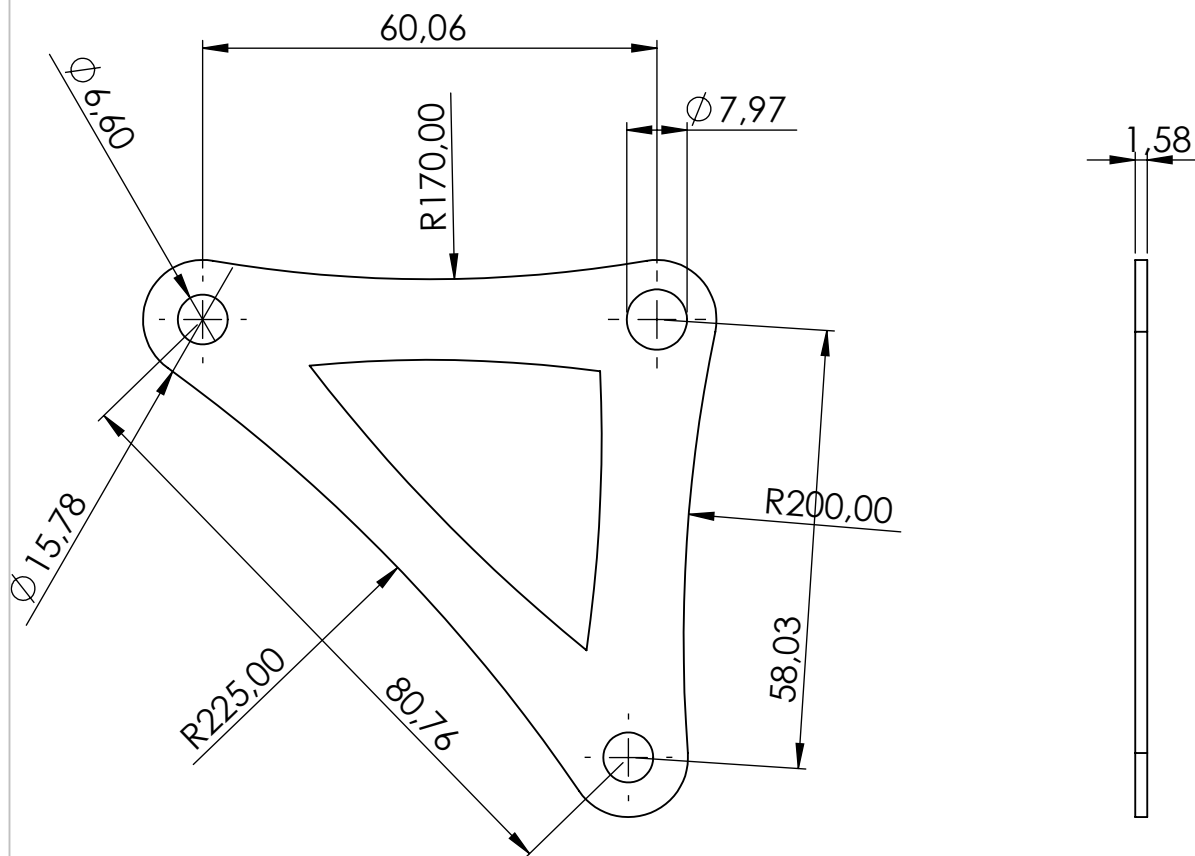
Matière: PLA

3A S1 ROBOTIQUE

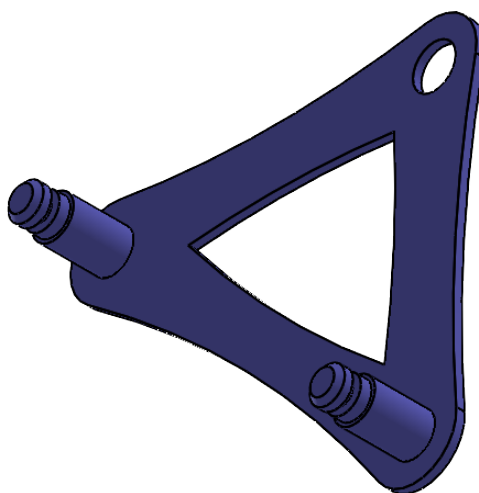
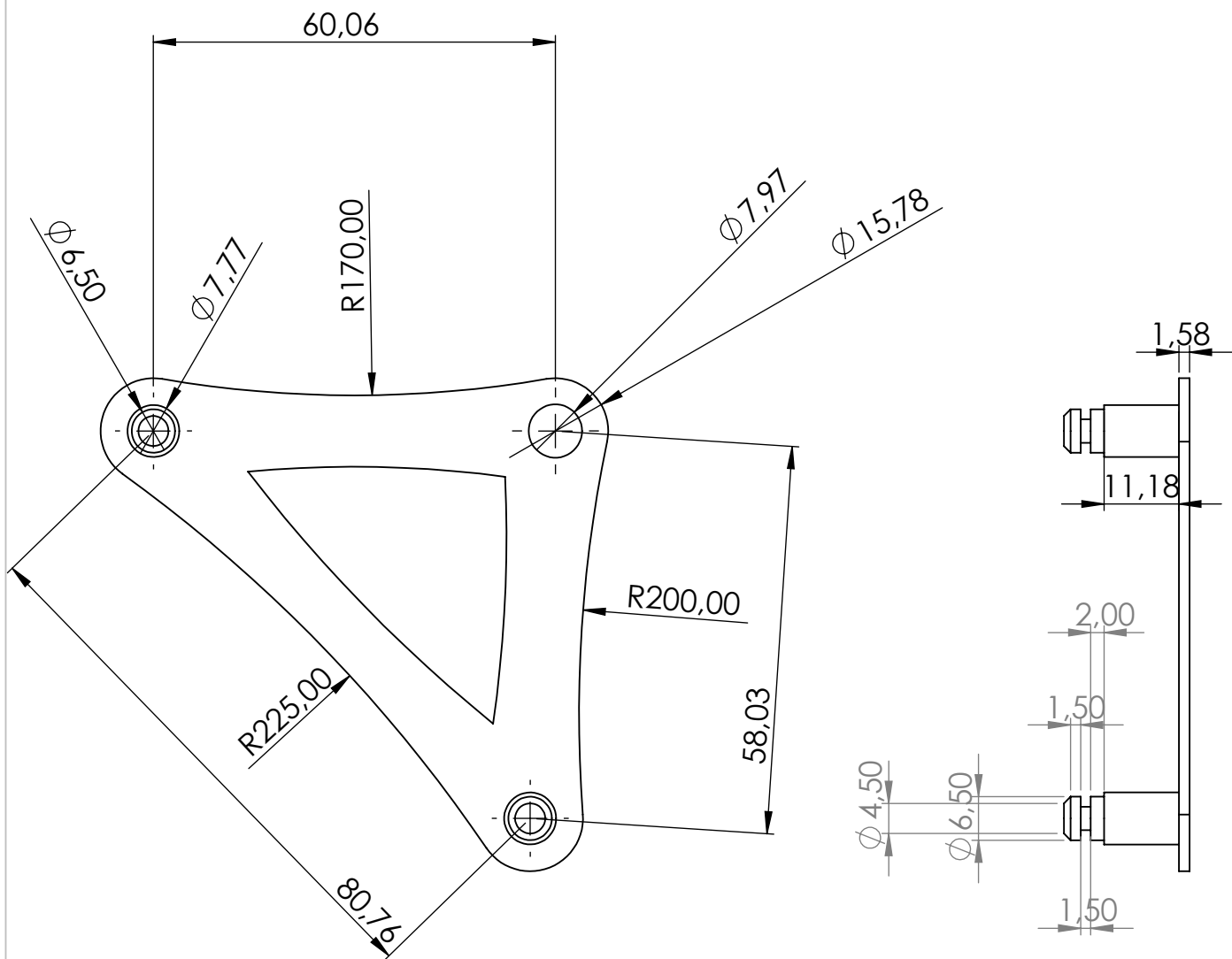


Encadré par:
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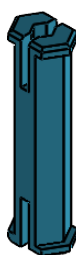
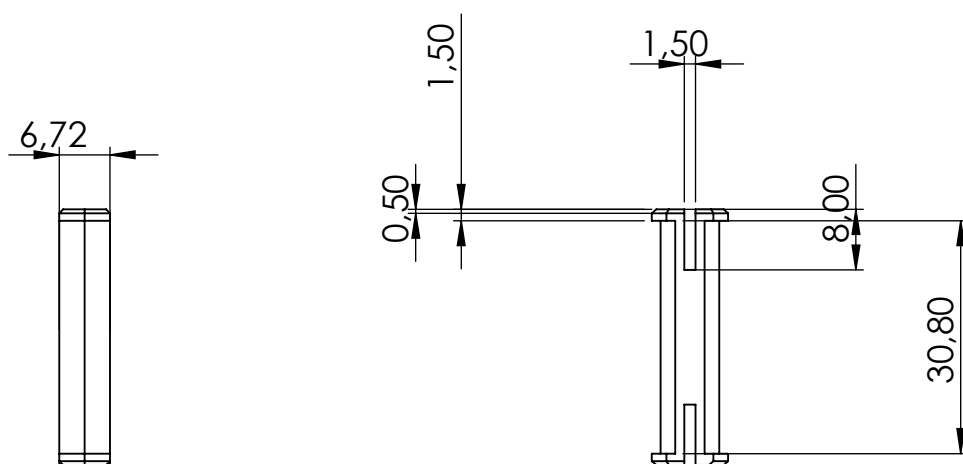
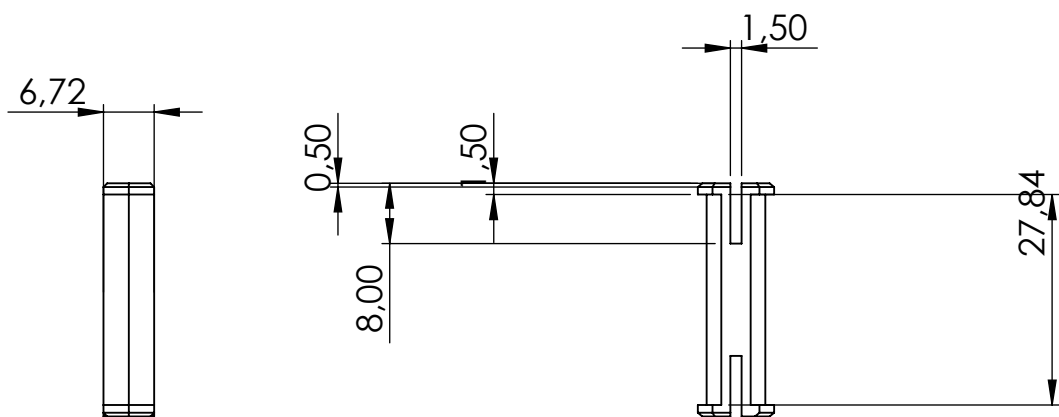
Date: 10/12/2025



Echelle: 1:1	TITRE: Métatarses supérieure		Nbr pcs: 08
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
			Date: 10/12/2025



Echelle: 1:1	TITRE: Métatarses inférieures		Nbr pcs: 08
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
			Date: 10/12/2025



Echelle: 1:1



TITRE: Manivelle

Nbr pcs: 04

Unité: mm

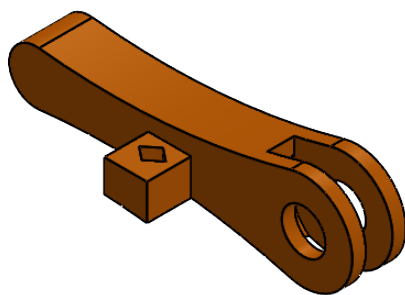
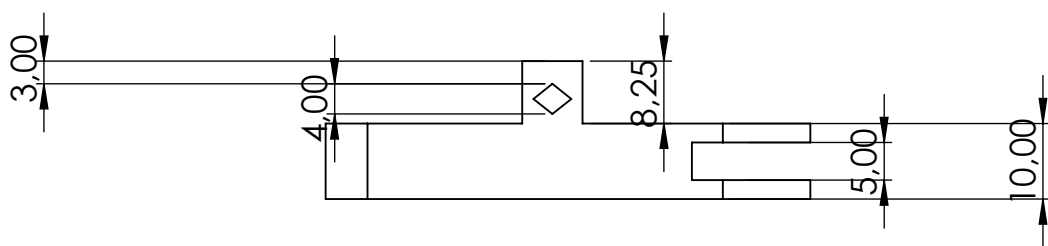
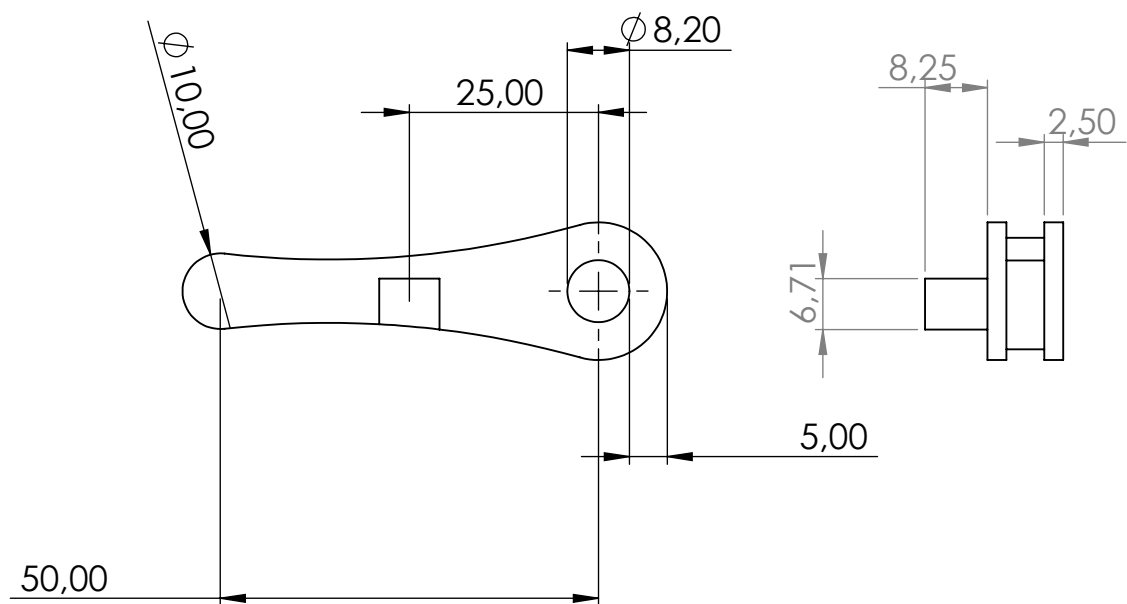
Matière: PLA

3A S1 ROBOTIQUE

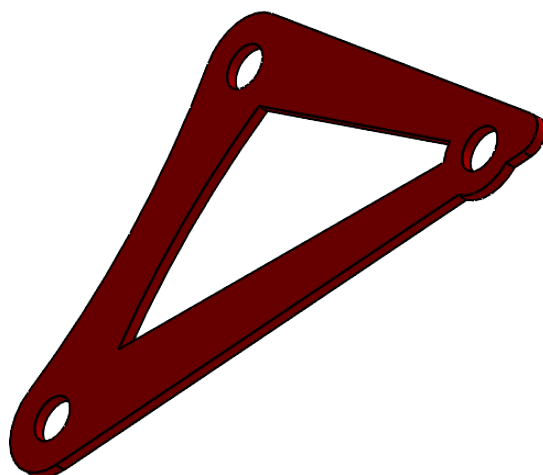
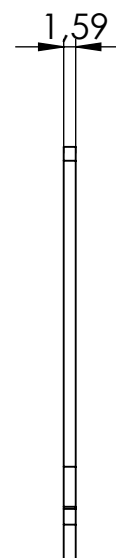
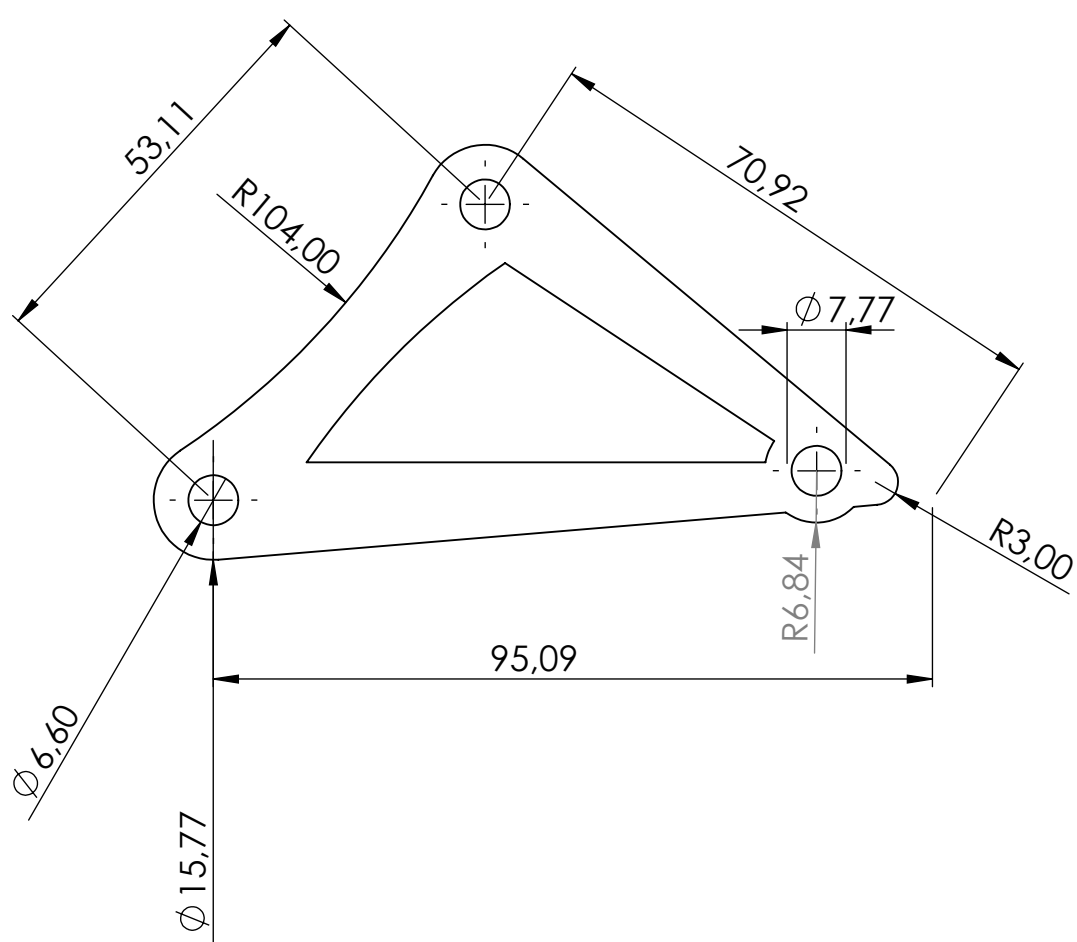


Encadré par:
Mr DAVID FOFI

Date: 10/12/2025



Echelle: 1:1	TITRE: Levier		Nbr pcs: 01
			Unité: mm
Matière: PLA	3A S1 ROBOTIQUE	 POLYTECH	Encadré par: Mr DAVID FOFI
Date: 10/12/2025			



Echelle: 1:2



TITRE: Griffe supérieure

Nbr pcs: 08

Unité: mm

Matière: PLA

3A S1 ROBOTIQUE



Encadré par:
Mr DAVID FOFI

Date: 10/12/2025