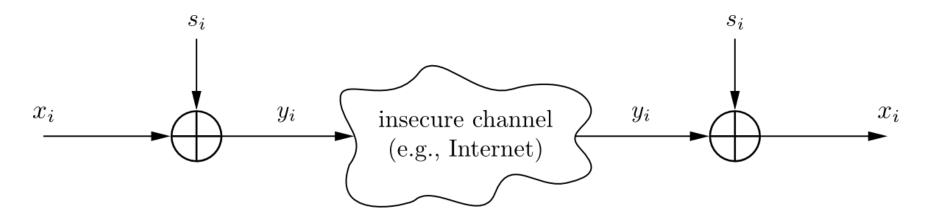
Privacy Final Review

Encryption & Decryption

Plaintext x_i , ciphertext y_i and key stream s_i consist of individual bits



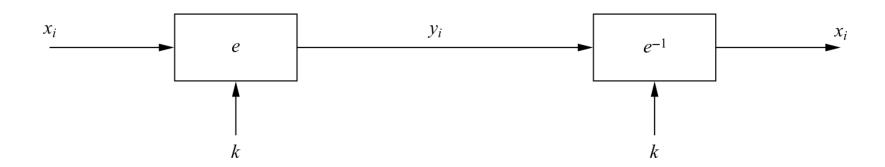
- Encryption and decryption are simple additions modulo 2 (aka XOR)
- Encryption and decryption are the same functions

Encryption: $y_i = e_{si}(x_i) = x_i + s_i \mod 2$, $x_i, y_i, s_i \in \{0,1\}$

Decryption: $x_i = e_{si}(y_i) = y_i + s_i \mod 2$

Electronic Code Book Mode (ECB)

- $e_k(x_i)$: the encryption of a b-bit plaintext block x_i with key k
- $e_k^{-1}(y_i)$: the decryption of b-bit ciphertext block y_i with key k
- Messages which exceed b bits are partitioned into b-bit blocks
- Each Block is encrypted separately



Encryption: $y_i = e_k(x_i), i \ge 1$ **Decryption**: $x_i = e_k^{-1}(y_i) = e_k^{-1}(e_k(x_i)), i \ge 1$

Extended Euclidean Algorithm (1)

- Extend the Euclidean algorithm to **find modular inverse** of $r_1 \mod r_0$
- EEA computes s, t, and the gcd :
- Take the relation $\mathbf{mod} r_0$

$$\gcd(r_0, r_1) = s \cdot r_0 + t \cdot r_1$$

 $s \cdot r_0 + t \cdot r_1 = 1$ $s \cdot 0 + t \cdot r_1 \equiv 1 \mod r_0$ $r_1 \cdot t \equiv 1 \mod r_0$

- ightarrow Compare with the definition of modular inverse: ι is the inverse of r_1 mod r_0
- Note that $gcd(r_0, r_1) = 1$ in order for the inverse to exist

Extended Euclidean Algorithm (2)

Extended Euclidean Algorithm (EEA)

Input: positive integers r_0 and r_1 with $r_0 > r_1$

Output: $gcd(r_0, r_1)$, as well as s and t such that $gcd(r_0, r_1) = s \cdot r_0 + t \cdot r_1$.

Initialization:

$$s_0 = 1$$
 $t_0 = 0$
 $s_1 = 0$ $t_1 = 1$
 $i = 1$

Algorithm:

```
1 DO

1.1 i = i+1

1.2 r_{i} = r_{i-2} \mod r_{i-1}

1.3 q_{i-1} = (r_{i-2} - r_{i})/r_{i-1}

1.4 s_{i} = s_{i-2} - q_{i-1} \cdot s_{i-1}

1.5 t_{i} = t_{i-2} - q_{i-1} \cdot t_{i-1}

WHILE r_{i} \neq 0 gcd(r_{0}, r_{1}) = gcd(r_{0} \mod r_{1}, r_{1})

\Rightarrow r_{2} = r_{0} \mod r_{1}, r_{0} = q_{1}r_{1} + r_{2}

\Rightarrow r_{1} = r_{1} = q_{1}r_{1} + r_{1}

\Rightarrow r_{1} = r_{1} - q_{1} - q
                                                                                  RETURN
                                                                                                                                                                          \gcd(r_0, r_1) = r_{i-1}
                                                                                                                                                                          s = s_{i-1}
```

 $t = t_{i-1}$

Remark of WHILE loop:

$$gcd(r_{0}, r_{1}) = gcd(r_{0} mod r_{1}, r_{1})$$

$$\rightarrow r_2 = r_0 \mod r_1, r_0 = q_1 r_1 + r_2$$

$$\rightarrow r_{i-2} = q_{i-1}r_{i-1} + r_{i}$$

$$\Rightarrow r_i = r_{i-2} - q_{i-1}r_{i-1} = [s_i]r_0 + [t_i]r_1$$

Example: EEA

- Calculate the modular Inverse of 12 mod 67:
- From magic table follows
- Hence 28 is the inverse of 12 mod 67.



• Check: $28 \cdot 12 = 336 \equiv 1 \mod 67$

i	q_{i-1}	r_i	$ s_i $	t_i
2		7	1	-5
3	1	5	-1	6
4	1	2	2	-11
5	2	1	-5	28

Euler's Phi Function (1)

- New problem, important for public-key systems, e.g., RSA:
 Given the set of the m integers {0, 1, 2, ..., m -1},
 How many numbers in the set are relatively prime to m?
- Answer: Euler's Phi function Φ(m)
- **Example** for the sets {0,1,2,3,4,5} (*m*=6) and {0,1,2,3,4} (*m*=5)

$$\gcd(0,6) = 6$$

 $\gcd(1,6) = 1$ $\gcd(2,6) = 2$
 $\gcd(3,6) = 3$
 $\gcd(4,6) = 2$
 $\gcd(5,6) = 1$ $\gcd(4,5) = 1$ $\gcd(4,5) = 1$ $\gcd(4,5) = 1$ $\gcd(4,5) = 1$

- ⇒ 1 and 5 relatively prime to m=6, hence $\Phi(6) = 2$
- Testing one gcd per number in the set is extremely slow for large m.

 $\Phi(5) = 4$

Euler's Phi Function (2)

- If canonical factorization of m known: $m = p_1^{e_1} \cdot p_2^{e_2} \cdot \ldots \cdot p_n^{e_n}$ (where p_i primes and e_i positive integers)
- **then** calculate Phi according to the relation: $\Phi(m) = \prod_{i=1}^{n} (p_i^{e_i} p_i^{e_i-1})$
- Phi especially easy for $e_i = 1$, e.g., $m = p \cdot q \rightarrow \Phi(m) = (p-1) \cdot (q-1)$
- Example $m = 899 = 29 \cdot 31$: $\Phi(899) = (29-1) \cdot (31-1) = 28 \cdot 30 = 840$
- Note: Finding $\Phi(m)$ is computationally easy if factorization of m is known (otherwise the calculation of $\Phi(m)$ becomes computationally infeasible for large numbers)

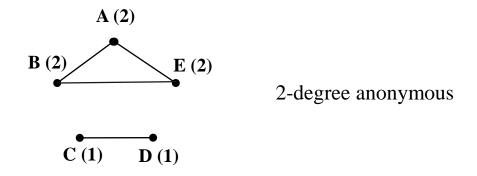
k-degree Anonymity

Assume that adversary A knows that B has
 327 connections in a social network!
 (background knowledge)

- If the graph is released by removing the identity of the nodes
 - A can find all nodes that have degree 327
 - If there is only one node with degree 327, A can identify this node as being **B**.

k-degree Anonymity

k-degree anonymity A graph G(V, E) is k-degree anonymous if every node in V has the same degree as k-1 other nodes in V.



Prop 1: If G is k1-degree anonymous, then it is also k2-degree anonymous, for every $k2 \le k1$

[Properties] It prevents the re-identification of individuals by adversaries with *a priori* knowledge of the degree of certain nodes.

K-Anonymity: Intuition

- The information for each person contained in the released table cannot be distinguished from at least k-1 individuals whose information also appears in the release
 - Example: you try to identify a man in the released table, but the only information you have is his birth date and gender. There are k men in the table with the same birth date and gender.
- Any quasi-identifier present in the released table must appear in at least k records

K-Anonymity Protection Model

- Private table: T
- Released table: RT
- Attributes: $A_1, A_2, ..., A_n$
- Quasi-identifier subset: A_i, ..., A_j

Let $RT(A_1,...,A_n)$ be a table, $QI_{RT} = (A_i,...,A_j)$ be the quasi-identifier associated with RT, $A_i,...,A_j \subseteq A_1,...,A_n$, and RT satisfy k-anonymity. Then, each sequence of values in $RT[A_x]$ appears with at least k occurrences in $RT[QI_{RT}]$ for x=i,...,j.

Example of a k-Anonymous Table

[Race	Rirth	Gender	7.TP	Problem
t1	Black	1965	m	0214*	short breath
t2	Black	1965	m	0214*	chest pain
t3	Black	1965	İ	0213*	hypertension
t4	Black	1965	f	0213*	hypertension
t5	Black	1964	f	0213*	obesity
tб	Black	1964	f	0213*	chest pain
	White	1964	m	0213*	chest pain
t8	White	1964	m	0213*	obesity
t9	White	1964	m	0213*	short breath
t10	White	1967	m	0213*	chest pain
t11	White	1967	m	0213*	chest pain

Figure 2 Example of k-anonymity, where k=2 and $Ql=\{Race, Birth, Gender, ZIP\}$

1-Diversity

Caucas	787XX	Flu
Caucas	787XX	Shingles
Caucas	787XX	Acne
Caucas	787XX	Flu
Caucas	787XX	Acne
Caucas	787XX	Flu
Asian/AfrAm	78XXX	Flu
Asian/AfrAm	78XXX	Flu
Asian/AfrAm	78XXX	Acne
Asian/AfrAm	78XXX	Shingles
Asian/AfrAm	78XXX	Acne
Asian/AfrAm	78XXX	Flu

Sensitive attributes must be "diverse" within each quasi-identifier equivalence class

L-Diversity

- T*: the Anonymized Table
- q*: the generalized value of q in the published table T*
- s: a possible value of the sensitive attribute
- n(q*,s'): number of tuples with sensitive attribute s' and non-sensitive attribute q*
- q*-block: the set of tuples in T* whose non-sensitive attribute values generalize to q*

L-Diversity

• Lack diversity: lack of diversity in the sensitive attribute manifests itself as follows:

$$\forall s' \neq s, \quad n_{(q^*,s')} \ll n_{(q^*,s)}$$

L-Diversity

- Then, L-Diversity Principle can be defined as:
 - A q*-block is L-diverse if contains at least L "well-represented" values for the sensitive attribute S.
 - A table is L-diverse if every q*-block is L-diverse.

An example

	1	Von-Sen	Sensitive	
	Zip Code	Age	Nationality	Condition
1	130**	< 30	*	Heart Disease
2	130**	< 30	*	Heart Disease
3	130**	< 30	*	Viral Infection
4	130**	< 30	*	Viral Infection
5	1485*	≥ 40	*	Cancer
6	1485*	≥ 40	*	Heart Disease
7	1485*	≥ 40	*	Viral Infection
8	1485*	≥ 40	*	Viral Infection
9	130**	3*	*	Cancer
10	130**	3*	*	Cancer
11	130**	3*	*	Cancer
12	130**	3*	*	Cancer

	l l	Von-Sen	Sensitive	
	Zip Code	Age	Nationality	Condition
1	1305*	≤ 40	*	Heart Disease
4	1305*	≤ 40	*	Viral Infection
9	1305*	≤ 40	*	Cancer
10	1305*	≤ 40	*	Cancer
5	1485*	> 40	*	Cancer
6	1485*	> 40	*	Heart Disease
7	1485*	> 40	*	Viral Infection
8	1485*	> 40	*	Viral Infection
2	1306*	≤ 40	*	Heart Disease
3	1306*	≤ 40	*	Viral Infection
11	1306*	≤ 40	*	Cancer
12	1306*	≤ 40	*	Cancer

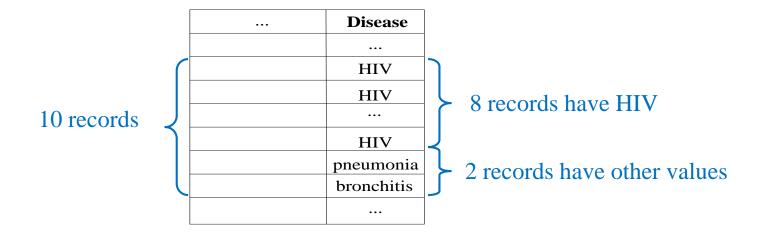
4-anonymous table

3 diverse table

- Using a 3-diverse table, we no longer are able to tell if Bob (a 31 year old American from zip code 13053) has cancer.
- We also cannot tell if Umeko(a 21 year old Japanese from zip code 13068) has a viral infection or cancer.

Probabilistic inference attacks over 1-Diversity

• Each equivalence class has at least I well-represented sensitive values



- Doesn't prevent probabilistic inference attacks
 - Infer: the patient has HIV with large possibility

t-Closeness overview

- Privacy is measured by the information gain of an observer.
- We assume:
 - B0: Alice believes that Bob has the virus because he has been acting sick.
 - B1: Alice gets a summary report of the table and learns that only 1% of the population has the virus. This distribution is Q, the distribution of the sensitive attribute in the whole table. She believes that Bob is in that one percent.
 - B2: Alice takes a look at the table, and finds that Bob is in equivalence class 3 because he is 32 and lives in zip code 47623. She learns P, the distribution of the sensitive attribute values in this class. Based on P she decides that it is actually quite likely that Bob has the virus.

t-Closeness overview

- l-diversity limits the gain between B0 (belief before any knowledge of the table) and B2 (belief after examining the table and the relevant equivalence class) by requiring that P (distribution in the equivalence class) has diversity.
- Q (global distribution in the table) should be treated as public information.
- If the change from B0 to B1 is large, means that the Q contains lots of new information. But we can't control people's access to Q, so we shouldn't worry about it.
- Therefore should focusing on limiting the gain between B1 and B2. We can do so by limiting the difference between P and Q. The closer P and Q are, the closer B1 and B2 are.

t-Closeness definition

- An equivalence class is said to have **t-closeness**
 - if the distance between the distribution of a sensitive attribute (P) in this class and the distribution of the attribute in the whole table(Q) is no more than a threshold t.
 - A table is said to have t-closeness if all equivalence classes have t-closeness.

t-Closeness

Caucas	787XX	Flu
Caucas	787XX	Shingles
Caucas	787XX	Acne
Caucas	787XX	Flu
Caucas	787XX	Acne
Caucas	787XX	Flu
Asian/AfrAm	78XXX	Flu
Asian/AfrAm	78XXX	Flu
Asian/AfrAm	78XXX	Acne
Asian/AfrAm	78XXX	Shingles
Asian/AfrAm	78XXX	Acne
Asian/AfrAm	78XXX	Flu

Distribution of sensitive attributes within each quasi-identifier group should be "close" to their distribution in the entire original database

Distance measurement

- Now that we've confirmed that limiting the difference between *P* and *Q* is the key to privacy, we need a way to measure the distance.
 - m: the number of sensitive values in an equivalence class
 - $P=(p_1,p_2,...,p_m), Q=(q_1,q_2,...,q_m)$
- Here are some naive measurements:
 - Method 1: variational distance

$$\mathsf{D}[\mathbf{P},\mathbf{Q}] = \sum_{i=1}^m rac{1}{2} |p_i - q_i|.$$

Distance measurement

Example

	ZIP Code	Age	Salary	Disease
1	47677	29	3K	gastric ulcer
2	47602	22	4K	gastritis
3	47678	27	5K	stomach cancer
4	47905	43	6K	gastritis
5	47909	52	11K	flu
6	47906	47	8K	bronchitis
7	47605	30	7K	bronchitis
8	47673	36	9K	pneumonia
9	47607	32	10K	stomach cancer

Table 3. Original Salary/Disease Table

	ZIP Code	Age	Salary	Disease
1	476**	2*	3K	gastric ulcer
2	476**	2*	4K	gastritis
3	476**	2*	5K	stomach cancer
4	4790*	≥ 40	6K	gastritis
5	4790*	≥ 40	11K	flu
6	4790*	≥ 40	8K	bronchitis
7	476**	3*	7K	bronchitis
8	476**	3*	9K	pneumonia
9	476**	3*	10K	stomach cancer

Table 4. A 3-diverse version of Table 3

- Overall distribution of the Income attribute:

$$Q = \{3k, 4k, 5k, 6k, 7k, 8k, 9k, 10k, 11k\}$$

- The first equivalence class in Table 4 has distribution:

$$P1 = \{3k, 4k, 5k\}$$

- The second equivalence class has distribution:

$$P2 = \{6k, 8k, 11k\}$$

$$D(P1,Q)=0.5*(|1/3-1/9|+|1/3-1/9|+|1/3-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|0-1/9|+|$$

We have D(P1,Q) = D(P2,Q)

Distance measurement

- Here are some naive measurements:
 - Method 2: Kullback-Leibler (KL) distance

$$\mathsf{D}[\mathbf{P}, \mathbf{Q}] = \sum_{i=1}^m p_i \log rac{p_i}{q_i} = H(\mathbf{P}) - H(\mathbf{P}, \mathbf{Q})$$

• H(P) is the entropy of P

$$H(\mathbf{P}) = \sum_{i=1}^{m} p_i \log p_i$$

• H (P, Q) is the cross-entropy of P and Q

$$H(\mathbf{P}, \mathbf{Q}) = \sum_{i=1}^{m} p_i \log q_i$$

0

D1

D2

D3

0.1

0.2

0.9

1

0.9

8.0

0.1

Definition

Differential Privacy

• A mechanism \mathcal{A} satisfies (ε, δ) -differential privacy if for any neighboring databases D, D' differing in only one tuple and any output $S \in O(\mathcal{A})$ which represents the possible output set of \mathcal{A} ,

$$\Pr[\mathcal{A}(D) \in S] \le e^{\varepsilon} \times \Pr[\mathcal{A}(D') \in S] + \delta.$$

• If $\delta = 0$, \mathcal{A} satisfies ε -differential privacy

We mainly focus on ε -differential privacy, as most studies do ...

Global sensitivity

• For any query function $f: D \to R^d$, where D is a dataset and R^d is a d-dimension real-valued vector, the global sensitivity of f is defined as

$$\Delta f = \max_{D, D'} ||f(D) - f(D')||_1$$

where D and D' denote neighboring databases—differing in only one tuple and $||\cdot||_1$ denotes I_1 norm.

 $|l_1 \text{ norm: } ||v||_1 = \sum_{1 \le i \le d} |v_i|$

Tips

- The global sensitivity means the maximal change of query result when changing a tuple (extreme case).
- The global sensitivity is only related to query function, and has nothing to do with database itself.

Name	Salary
Hunter	50000
Alice	50000
Bob	20000
Eric	100000
_	

60000

Frank

Name	Salary
Pedro	80000
Alice	50000
Mata	10000
Eric	100000
Frank	60000

• Example: Count function: $\Delta f = 1$

Name	Flu		Name	Flu		Name	Flu
Hunter	1		Hunter	1		Hunter	1
Alice	0	Neighboring	Alice	0	Neighboring	Alice	0
Eric	0		Bob	1		Bob	0
Frank	1		Eric	0		Eric	0
			Frank	1		Frank	1
Count	z(1)=2		Coun	t(1)=3		Coun	t(1)=2

• Example: Histogram Query $\Delta f = 2$

Name	Flu		Name	Flu		Name	Flu
Hunter	1		Hunter	1		Hunter	1
Alice	0	Neighboring	Alice	0	Neighboring	Alice	0
Eric	0		Bob	1		Bob	0
Frank	1		Eric	0		Eric	0
			Frank	1		Frank	1
4			4			4	
2			2			2 —	
	Flu			Flu			Flu
■0	1			1			1
Hist =	< 2, 2 >		Hist =	< 2, 3 >		Hist =	< 3, 2 >
$ < 2, 2 > - < 2, 3 > _1 = 1$ $ < 2, 3 > - < 3, 2 > _1 = 2$							$ _1 = 2$

- Example: Median
 - Suppose extreme case D:(0,0,0,n,n)
 - A neighboring database D': (0, 0, n, n, n)
 - Med(D) = 0
 - Med(D') = n
 - $\Delta f = n$ (the maximal possible element)

- Local sensitivity
 - For any query function $f: D \to R^d$, the local sensitivity of f is defined as

$$LS_f(D) = \max_{D'} ||f(D) - f(D')||_1$$

where D and D' denote neighboring databases differing in only one tuple and $||\cdot||_1$ denotes I_1 norm.

Local sensitivity

Bounded neighboring is considered

- *f* : Compute the maximal salary difference
- Valid salary: [10000, 100000]

Salary	
50000	
50000	
20000	
10000	
60000—	→ 100000
	50000 50000 20000 10000

Name	Salary	
Pedro	80000	
Alice	50000	
Mata	70000	
Eric	15000 —	→ 50000
Frank	60000	

$$LS_f(D_1) = 90000 - 50000$$

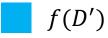
= 40000

$$LS_f(D_2) = 65000 - 30000$$
$$= 35000$$

Name	Salary	
Pedro	80000	
Alice	60000	
Mata	75000	
Eric	100000	
Frank	60000	10000

$$LS_f(D_3) = 90000 - 40000$$
$$= 50000$$

f(D)



- Example
 - Median:
 - Suppose $D: (x_1, x_2, ..., x_{n-1}, x_n), n$ is odd
 - $Med(D) = x_m, m = (n+1)/2$
 - $LS_f(D) = \max(x_m x_{m-1}, x_{m+1} x_m)$

 $LS_f(D)$ is usually much smaller than Δf which is the maximal possible element

$$x_1$$
 x_{m+t} x_{m-1} x_m x_{m+t} x_n

- Smooth Sensitivity
 - Motivation
 - Avoid to employ global sensitivity
 - Databases with smaller local sensitivity could be calibrated with smaller noise
 - Add instance-specified noise while differential privacy is preserved at the same time

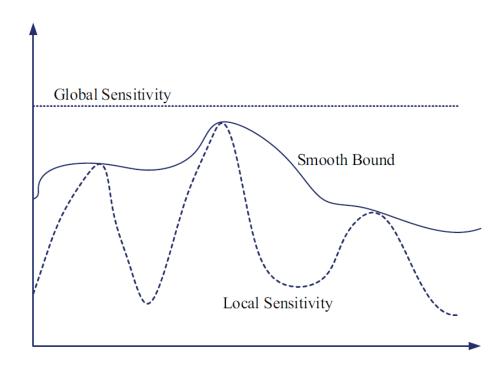
- Smooth Sensitivity
 - Requirement
 - The difference of smooth sensitivity for neighboring databases should be bounded
 - No smaller than local sensitivity
 - No larger than global sensitivity

Smooth Bound

- For $\beta > 0$, a smooth function $S: D \to R^+$ is a β -smooth upper bound on the local sensitivity of f if it satisfies the following requirements:
 - $S(D) \ge LS_f(D)$
 - $S(D) \le e^{\beta} LS_f(D)$

A function S that is an upper bound on LS_f at all points and such that $\ln(S(\cdot))$ has low sensitivity

Smooth Bound



Note that the constant function $S(x) = \Delta f$ meets the requirements with $\beta = 0$.

- Smooth sensitivity
 - For any query function $f: D \to R^d$, the smooth sensitivity of f is defined as

$$S_{f,\beta}^*(D) = \max_{D'} (LS_f(D') \cdot e^{-\beta d(D,D')})$$

where $d(D,D^\prime)$ denotes the Hamming distance between neighboring databases D and D^\prime .

- Property of Smooth Sensitivity
 - $S_{f,\beta}^*$ is a β -smooth upper bound on LS_f . In addition, $S_{f,\beta}^*(D) \leq S(D)$ for all database D for every β -smooth upper bound S on LS_f .
 - Key Points
 - $S_{f,\beta}^*(D) \ge LS_f(D)$
 - $S_{f,\beta}^*(D) \le e^{\beta} L S_f(D)$
 - $S_{f,\beta}^*$ is the smallest β -smooth upper bound on LS_f

- Smooth Sensitivity Brings Differential Privacy
 - 1-Dimensional Case
 - Let $f: D \to \mathbb{R}$ be any real-valued function and let $S: \mathbb{D} \to \mathbb{R}$ be a β -smooth upper bound on the local sensitivity of f then
 - If $\beta \leq \frac{\varepsilon}{2(\gamma+1)}$ and $\gamma > 1$, the algorithm $x \mapsto f(x) + \frac{2(\gamma+1)S(x)}{\varepsilon} \eta$, where η is sampled from distribution with density $h(z) \propto \frac{1}{1+|z|^{\gamma}}$, is ε -differentially private

Added noise —

 α and β are parameters of the noise distribution

- Smooth Sensitivity Brings Differential Privacy
 - 1-Dimensional Case
 - Let $f: D \to \mathbb{R}$ be any real-valued function and let $S: \mathbb{D} \to \mathbb{R}$ be a β -smooth upper bound on the local sensitivity of f then
 - If $\beta \leq \frac{\varepsilon}{2\ln(\frac{2}{\delta})}$ and $\delta \in (0,1)$, the algorithm $x \mapsto f(x) + \frac{2S(x)}{\varepsilon} \eta$, where $\eta \sim Lap(1)$ (ε, δ) -differentially private



 α and β are parameters of the noise distribution

$$S_{f,\beta}^*(D) = \max_{D'} (LS_f(D') \cdot e^{-\beta d(D,D')})$$

- Example of Calculating Smooth Sensitivity
 - Median:
 - Suppose $D: (x_1, x_2, ..., x_{n-1}, x_n), n$ is an odd
 - $Med(D) = x_{m} m = (n+1)/2$
 - $LS_f(D) = \max(x_m x_{m-1}, x_{m+1} x_m)$
 - Let k denotes up to k tuples changed
 - The smooth sensitivity of the median is

$$S_{f_{med,\varepsilon}}^*(D) = \max_{k=0,\dots,n} (e^{-k\beta} \cdot \max_{t=0,\dots,k+1} \max(x_{m+t} - x_{m+t-k-1}, x_{m+t+1} - x_{m+t}))$$
 It can be computed in $O(n^2)$

$$S_{f,\beta}^*(D) = \max_{D'} (LS_f(D') \cdot e^{-\beta d(D,D')})$$

- An Idea of Computing $S_{f,\beta}^*(D)$
 - Suppose we change up to k tuples

$$A^{(k)}(D) = \max_{D' \in \mathbb{D}: d(D,D') \le k} LS_f(D')$$

• Smooth sensitivity could be expressed using $A^k(D)$

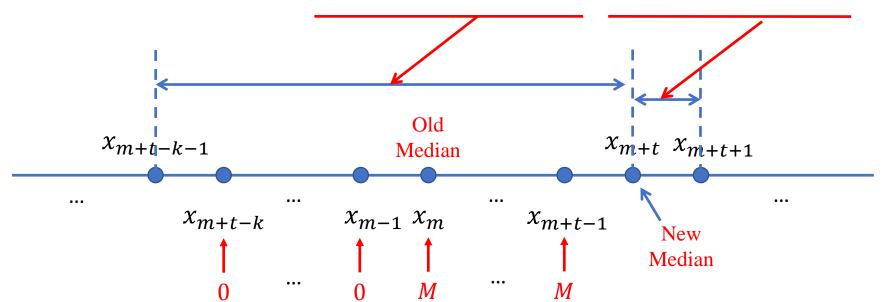
$$S_{f,\beta}^{*}(D) = \max_{k=0,...,n} e^{-k\beta} (\max_{D' \in \mathbb{D}: d(D,D') \le k} LS_{f}(D'))$$

$$= \max_{k=0,...,n} e^{-k\beta} A^{k}(D)$$

- Computing $S_{f_{med,\varepsilon}}^*(D)$
 - For f = Median

Median
$$A^{(k)}(D) = \max_{D' \in \mathbb{D}: d(D,D') \le k} LS_f(D')$$

$$= \max_{t=0,\dots,k} \max(x_{m+t} - x_{m+t-k-1}, x_{m+t+1} - x_{m+t})$$



- Computing $S_{f_{med,\varepsilon}}^*(D)$
 - For f = Median

$$A^{(k)}(D) = \max_{D' \in \mathbb{D}: d(D,D') \le k} LS_f(D')$$

Data range: [0, 10], $Med(D) = x_5 = 5$

$$D = (1,2,3,4,5,6,7,8,9)$$

	x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9	
What is th	1	2	2	1	5	6	7	Q	٥	D to
מוא(ח חי	$j \geq \kappa$	/	3	4	3	U	,	O	9	

- To Compute the Maximum $LS_f(D')$
 - Solution to get maximum candidates
 - Let t = 0, ..., k
 - Change t tuples to 10, starting from x_5 to the right
 - Change k t tuples to 0, starting from x_4 to the left
 - Change 0 tuple

• $\max_{D' \in \mathbb{D}: d(D,D') \le k} LS_f(D') = LS_f(D) = \max\{x_5 - x_4, x_6 - x_5\}$

Change 1 tuple

• Case 1: k = 1, t = 0

x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	<i>x</i> ₉
1	2	3	0	5	6	7	8	9

_	x_4	x_1	x_2	x_3	x_5	x_6	x_7	x_8	x_9
	0	1	2	3	5	6	7	8	9

- $LS_f(D') = \max\{x_5 x_3, x_6 x_5\}$
 - Case 2: k = 1, t = 1

	x_1	x_2	x_3	x_4	x_5	x_6	<i>x</i> ₇	x_8	x_9	x_1	x_2	x_3	x_4	x_6	x_7	x_8	x_9	x_5
• <i>I</i>	1	2	3	4	10	6	7	8	9	1	2	3	4	6	7	8	9	10

$$S_{f_{med,\varepsilon}}^*(D) = \max_{k=0,\dots,n} (e^{-k\beta} \cdot \max_{t=0,\dots,k+1} \max(x_{m+t} - x_{m+t-k-1}, x_{m+t+1} - x_{m+t}))$$

Sensitivity Change 2 tuple

• Case 1: k = 2, t = 0

x_1	x_2	x_3	x_4	x_5	x_6	x_7	x_8	x_9		x_4	x_3	x_1	x_2	x_5	x_6	x_7	<i>x</i> ₈	<i>x</i> ₉
1	2	0	0	5	6	7	8	9	5}	0	0	1	2	5	6	7	8	9

• Case 2: k = 2, t = 1

1	2	3	0	10	6	7	8	9	6	0	1	2	3
		_	Cas	C J.	r -	4. L							

x_4	x_1	x_2	x_3	x_6	x_7	x_8	<i>X</i> 9	x_5
0	1	2	3	6	7	8	9	10

x_1	x_2	x_3	x_4	<i>x</i> ₅	x_6	x_7	<i>x</i> ₈	<i>x</i> ₉	7}
1	2	3	4	10	10	7	8	9	

x_1	x_2	x_3	x_4	<i>x</i> ₇	x_8	<i>x</i> ₉	x_5	x_6
1	2	3	4	7	8	9	10	10

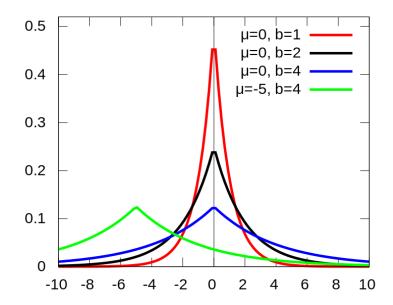
$$S_{f_{med,\varepsilon}}^*(D) = \max_{k=0,\dots,n} (e^{-k\beta} \cdot \max_{t=0,\dots,k+1} \max(x_{m+t} - x_{m+t-k-1}, x_{m+t+1} - x_{m+t}))$$

- Mechanism
 - Definition of Laplace Mechanism
 - Given any function $f: \mathbb{N}^{|\mathcal{X}|} \to \mathbb{R}^k$, the **Laplace Mechanism** is defined as: $\mathcal{M}(D, f(.), \varepsilon) = f(D) + (Y_1, ..., Y_k)$

where Y_i is independent and identically distributed random variables drawn from $Lap(\Delta f/\epsilon)$.

Laplace Mechanism works for real valued functions

- Mechanism
 - $Lap(\Delta f/\varepsilon)$: noise in Laplace Mechanism
 - Larger Δf brings larger noise
 - Smaller ε brings larger noise



Question:

Which Laplace Distribution brings the smallest noise?

$$Lap(x) = \frac{1}{2b} \exp(-\frac{|x|}{b})$$
$$b = \Delta f/\varepsilon$$

- Example
 - Among 10000 family names, which is the most common?
 - Utilization of histogram queries
 - Set $\varepsilon = 1$
 - To count the number of each family name, add independent noise $Y_i \sim Lap(1)$ ($\Delta f = 1, \varepsilon = 1$)
 - $Pr[|Y_i| < ?] \ge 95\%$
 - Is it a small error for large population, say 300000 persons
 - Report the family name with the largest count

- Example
 - $\Delta f = 1$, $\varepsilon = 1$, k = 10000, set $\delta = 0.05$
 - Recall the property of Laplace Distribution

$$\Pr[||f(D) - y||_{\infty} \ge \ln(\frac{k}{\delta}) \times (\frac{\Delta f}{\varepsilon})] \le \delta$$

- $\Pr[||f(D) y||_{\infty} \ge \ln(\frac{k}{\delta}) \times (\frac{\Delta f}{\varepsilon})] \le \delta$ We can get $\Pr[Y_i \ge \ln(\frac{10000}{0.05}) \times \frac{1}{1}] \le 0.05$, that is $\Pr[Y_i < \ln(\frac{10000}{0.05})] \ge 95\%$
- $\ln\left(\frac{10000}{0.05}\right) \approx 12.2$

It is a small error for large population, say 300000 persons

Location Privacy

- Existing Notions of Privacy
 - Expected Distance Error
 - A natural way to quantify the accuracy by which an adversary can guess the real location



Three locations and their prior probability

Location Preserving Mechanism

Mechanism design: Maximizing the expected distance error

Adversary's guessing strategy

Expected Distance Error:

At
$$a: 0.8 \times 0 + 0.1 \times 12 + 0.1 \times 10 = 2.2$$

At
$$b: 0.1 \times 12 + 0.6 \times 0 + 0.3 \times 6 = 3$$

At
$$c: 0.2 \times 10 + 0.3 \times 6 + 0.5 \times 0 = 3.8$$

Overall: $0.2 \times 2.2 + 0.3 \times 3 + 0.5 \times 3.8 = 3.24$

Location Privacy

- Existing Notions of Privacy
 - Expected Distance Error
 - Inaccuracy estimation of adversary's side information leads to poorly designed mechanism

