

Program No: 1**INTRODUCTION to MASM****EDITOR:**

An editor is a program, which allows you to create a file containing the assembly language statements for your program. As you type in your program the editor stores the ASCII codes for the letters and numbers in successive RAM locations. When you have typed in all of your programs you then save the file on a floppy or hard disk. This file is called source file. The next step is to process the source file with an assembler. In the MASM/TASM assembler you should give your source file name the extension .ASM

ASSEMBLER:

An assembler program is used to translate the assembly language mnemonics for instructions to the corresponding binary codes. When you run the assembler it reads the source file of your program the disk where you saved it after editing on the first pass through the source program the assembler determines the displacement of named data items the offset of labels and this information in a symbol table. On the second pass through the source program the assembler produces the binary code for each instruction and inserts the offset etc that is calculated during the first pass. The assembler generates two files on floppy or hard disk. The first file called the object file is given the extension. OBJ. The object file contains the binary codes for the instructions and information about the addresses of the instructions. The second file generated by the assembler is called assembler list file. The list file contains your assembly language statements the binary codes for each instructions and the offset for each instruction. In MASM/TASM assembler MASM source file name ASM is used to assemble the file. Edit source file name LST is used to view the list file which is generated, when you assemble the file.

LINKER :

A linker is a program used to join several object files into one large object file and convert to an **exe** file. The linker produces a link file, which contains the binary codes for all the combined modules. The linker however doesn't assign absolute addresses to the program, it assigns is said to be re-locatable because it can be put anywhere in memory to be run. In TASM/MASM LINK source filename is used to link the file.

DEBUGGER:

A debugger is a program which allows you to load your object code program into system memory, execute the program and troubleshoot are debug it the debugger allows you to look at the contents of registers and memory locations after your program runs. It allows you to change the contents of register and memory locations after your program runs. It allows you to change the contents of register and memory locations and return the program. A debugger also allows you to set a break point at any point in the program. If you inset a breakpoint the debugger will run the program up to the instruction where the breakpoint is set and stop execution. You can then examine register and memory contents to see whether the results are correct at that point. In MASM, MD filename is used to debug the file.

DEBUGGER FUNCTIONS:

1. Debugger allows to look at the contents of registers and memory locations.
2. We can extend 8-bit register to 16-bit register which the help of extended register option.
3. Debugger allows to set breakpoints at any point with the program.
4. The debugger will run the program up to the instruction where the breakpoint is set and then stop execution of program. At this point, we can examine registry and memory contents at that point.
5. With the help of dump we can view register contents.
6. we can trace the program step by step with the help of T.
7. We can execute the program completely at a time using G.

DEBUGGER COMMANDS

ASSEMBLE: To write assembly language program from the given address.

A starting address <cr>

Eg: a 4000 <cr>

Starts program at an offset of 4000.

DUMP: To see the specified memory contents

D memory location first address last address

(While displays the set of values stored in the specified range, which is given above)

Eg: d 2000, 2010 <cr>

Display the contents of memory locations from 2000 to 2010 (including).

GO: To execute the program

G: one instruction executes (address specified by IP)

G address <cr>: executes from current IP to the address specified

G first address last addresses <cr>: executes a set of instructions specified between the given addresses.

QUIT: To exit from the debugger.

Q < cr >

REGISTER: Shows the contents of Registers

R register name

Eg: r ax

Shows the contents of register.

TRACE: To trace the program instruction by instruction.

T = 2000 <cr>: traces only the current instruction. (Instruction specified by IP)

T = 1000 02 <cr>: Traces instructions from 100 to 101, here the second argument specifies the number of instructions to be traced.

UNASSEMBLE: To unassembled the program.

Shows the op-codes along with the assembly language program.

U 4000 <cr>: unassembled from 4000 onwards instructions.

U 5000 6000 <cr>: unassembles the lines from 5000 to 6000

Program No: 2 (a)**MULTY BYTE ADDITION****DATA SEGMENT**

N1 DB 55H, 66H, 77H

N2 DB 11H, 22H, 33H

RESULT DB 3H DUP (00)

DATA ENDS**CODE SEGMENT****ASSUME CS: CODE, DS: DATA**

```

START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        MOV BX, OFFSET RESULT
        CLC
        MOV CX, 0003H
        MOV AX, 0000H
BACK:   MOV AL, [SI]
        MOV DL, [DI]
        ADC AL, DL
        MOV [BX], AL
        INC SI
        INC DI
        INC BX
        DEC CX
        JNZ BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
CODE ENDS
END START

```

```

RESULT:  55H  66H  44H
         11H 22H 33H
         66H  88H  77H

```

Viva Questions:__

1. What is the Function of ADC ?
2. What is the purpose of BX register?
3. What is the Function of CLC?
4. What is the other instruction which can be used instead of MOV SI offset N1?
5. What is the function of MOV AH, 4CH & INT 21H?
6. What is the purpose of INT 3H?

Program No: 2(b)**MULTY BYTE SUBTRACTION****DATA SEGMENT**

N1 DB 55H, 66H, 77H, 88H

N2 DB 11H, 22H, 33H, 44H

RESULT DB 4H DUP(00)

DATA ENDS**CODE SEGMENT****ASSUME CS: CODE, DS: DATA**

```
START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        MOV BX, OFFSET RESULT
        CLC
        MOV CX, 0004H
        MOV AX, 0000H
BACK:   MOV AL, [SI]
        MOV DL, [DI]
        SBB AL, DL
        MOV [BX], AL
        INC SI
        INC DI
        INC BX
        LOOP BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START
```

```
RESULT: 55H  66H  77H  88H
         11H 22H 33H 44H
         44H  44H  44H  44H
```

Viva Questions:__

- 1 . Why subtract with carry instruction is used in the loop?
2. What is the purpose served by BX register?
3. Why subtraction is done with AL register why not with AX ?
4. What is the other instruction which can be used instead of
MOV DI, offset N2 ?

Program No: 2(c)**MULTY BYTE MULTIPLICATION****DATA SEGMENT**

N1 DB 05H, 04H, 02H

N2 DB 01H, 02H, 03H

RESULT DB 4H DUP (00)

DATA ENDS**CODE SEGMENT****ASSUME CS: CODE, DS: DATA**

```

START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        MOV BX, OFFSET RESULT
        MOV CL, 03H
        MOV AX, 0000H
        MOV DX, 0000H
BACK:   MOV AL, [SI]
        MOV CH, [DI]
        MUL DH
        MOV [BX], AL
        INC SI
        INC DI
        INC BX
        LOOP BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
CODE ENDS
END START

```

```

RESULT: 05H  04H  02H
         01H  02H  03H
         05H  08H  06H

```


Viva Questions:__

1. What is the use of stack pointer?
2. How many model assignment are the name them?
3. What is a directive?
4. What is a pseudo operation?
5. ORG 2000H implies what?
6. Al register is used why not AX?
7. What is the purpose of INT3 in the program?
8. What is the purpose of MOV AH, 4CH and INT 21H in the program?.

Program No: 2 (d)**MULTY BYTE DIVISION**

DATA SEGMENT

N1 DB 55H, 66H, 99H

N2 DB 11H, 22H, 33H

RESULT DB 3H DUP(00)

DATA ENDS

CODE SEGMENT

ASSUME CS:CODE, DS:DATA

```

START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        MOV BX, OFFSET RESULT
        MOV CL, 03H
        MOV AX, 0000H
        MOV DX, 0000H
BACK:   MOV AL, [SI]
        MOV CH, [DI]
        DIV CH
        MOV [BX], AL
        INC SI
        INC DI
        INC BX
        LOOP BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START

```

```

RESULT: 55H 66H 99H
        11H 02H 03H
        05H 33H 33H

```

Viva Questions:__

1. What AL has been used and not AX ?
2. What happens if num1 contains 0AAH and num2 contains 0FFH. ?
3. How do you account for the difference obtained in previous question?
4. Why should AX be used not AL. ?
5. What happens if num1 and num2 values are interchanged?
6. If carry is set to 1 before subtraction what is the instruction to be used?
7. What is an extended accumulator?
8. AL and BL are used for multiplying why not AX & BX?
9. Instead of using MOV BL is it not possible to MUL num2?
10. What is the instruction used for signed multiplication?

Program No: 3(a)**SIGNED MULTIPLICATION****DATA SEGMENT**

N1 DB 09H
N2 DB 02H
N3 DB 02H DUP(00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

START: MOV AX, DATA
 MOV DS, AX
 SUB AX, AX
 MOV AL, N1
 MOV CH, N2
 MOV BX, OFFSET N3
 IMUL CH
 MOV [BX], AL
 MOV AH, 4CH
 INT 21H
 INT 3H
 CODE ENDS
 END START

RESULT: 09H
 02H
 18H

Viva Questions:

1. What is the difference between IMUL and MUL?
2. What is the use of instruction CBW?
3. What is the use of instruction CWD?
4. What is the use of instruction pointer?
5. What is the use of index pointers?

Program No: 3(b)**SIGNED DIVISION****DATA SEGMENT**

```
N1 DB 40H
N2 DB 20H
N3 DB 02H DUP (00H)
```

DATA ENDS**CODE SEGMENT**

```
ASSUME CS:CODE, DS:DATA
```

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV AL, N1
        CBW
        MOV CH, N2
        MOV BX, OFFSET N3
        IDIV CH
        MOV [BX], AL
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START
```

```
RESULT: 40H
         20H
         800H
```

Viva Questions:

1. What is the purpose of SUB AX,AX?
2. What is the difference between IDIV and DIV?
3. What is the use of instruction CBW & CWD?
4. What is the importance of segmentation?
5. What is the difference between signed & unsigned numbers?

Program No: 4(a)**ASCII ADDITION****DATA SEGMENT**

N1 DB 14H

N2 DB 04H

N3 DB 2H DUP (00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV AL, N1
        MOV CL, N2
        MOV BX, OFFSET N3
        ADD AL, CL
        AAA
        MOV [BX], AL
        MOV AH, 4CH
        INT 21H
        INT 3H
```

CODE ENDS**END START**

Viva Questions:

1. What is the purpose of AAA instruction?
2. What is the importance of ASCII addition?
3. What is the difference between addition and ASCII addition?
4. What is the importance of INT 21H?
5. What is meant by pipe lining?

Program No: 4(b)**ASCII SUBTRACTION****DATA SEGMENT**

```
N1 DB 04H
N2 DB 02H
N3 DB 02H DUP (00)
```

DATA ENDS**CODE SEGMENT**

```
ASSUME CS:CODE, DS:DATA
```

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV AL, N1
        MOV BX, OFFSET N3
        SUB AL, N2
        AAS
        MOV [DL], AL
        MOV AH, 4CH
        INT 21H
        INT 3H
```

CODE ENDS

```
END START
```

Viva Questions:

1. What is the purpose of ASCII subtraction?
2. What is the instruction used for ASCII subtraction? _
3. What is the purpose of AAS?
4. What is difference between AAS and AAA?
5. What is the importance of ASCII No's?

Program No: 4(c)**ASCII MULTIPLICATION****DATA SEGMENT**

N1 DB 04H

N2 DB 03H

N3 DB 02H DUP(00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV AL, N1
        MOV BX, OFFSET N3
        MUL N2
        AAM
        MOV [BL], AL
        MOV AH, 4CH
        INT 21H
        INT 3H
```

CODE ENDS**END START**

Viva Questions:

1. What is the purpose of XCHG instruction is ASCII adjust after multiplication. ?
2. Why is ASCII adjust after multiply cab be called as 1 byte binary to BCD conversion?
3. What does AL & AH contains?

Program No: 4(d)**ASCII DIVISION****DATA SEGMENT**

N1 DB 06H
N2 DB 04H
N3 DB 02H DUP (00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

START: MOV AX, DATA
 MOV DS, AX
 XOR AX, AX
 MOV AL, N1
 MOV BX, N3
 AAD
 DIV N2
 MOV [BX], AL
 MOV AH, 4CH
 INT 21H
 INT 3H
CODE ENDS
END START

Viva Questions:

1. What is the ASCII instruction, which is used before the arithmetic operation?
2. Why is ASCII adjust before division is done before actual division?
3. What does AL & AH contains?

Program No: 5(a)**PACKED TO UNPACKED BCD****DATA SEGMENT**

N1 DB 56H, 49H, 33H

N2 DB 06H DUP(00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```

START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        MOV CX, 0003H
BACK:   MOV AL, [SI]
        MOV BL, AL
        AND AL, 0F0H
        MOV CL, 04H
        ROR BL, CL
        AND BL, 0FH
        MOV [DI], AL
        INC DI
        MOV [DI], BL
        INC SI
        INC DI
        DEC CX
        JNZ BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
CODE ENDS
END START

```

RESULT:

I/P :	56H	49H	33H
O/P :	05H,06H,	04H,09H,	03H,03H

Viva Questions:

1. What is the purpose of the instruction ROR AL, CL?
2. What is the purpose of the instruction AND AL, 0FH .?
3. What is the expansion of UPBCD?
4. What is the use of DAA instruction?
5. What is the reason for packing unpacked BCD?
6. What is common between unpacked BCD and ASCII?

Program No: 5(b)**UNPACKED BCD TO PACKED****DATA SEGMENT**

N1 DB 05H, 06H

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV AL, N1
        MOV BL, AL
        MOV CL, 04H
        ROR BL, CL
        OR AL, BL
        MOV AH, 4CH
        INT 21H
        INT 3H
```

CODE ENDS**END START****RESULT:**

I/P : 05H 06H

O/P : 56H

Viva Questions:

1. What are the flags effects in this program?
2. What is the purpose of XOR AX, AX ?
3. What is the use of INT 21H?
4. Why AX is called as accumulator?
5. How many segments & what is the use of Extra Segment?

Program No: 5(C)**BCD to ASCII CONVERSION**

DATA SEGMENT

 N1 DB 56H
 N2 DB 02H DUP (00)

DATA ENDS

 CODE SEGMENT

 ASSUME CS:CODE, DS:DATA

 START: MOV AX, DATA
 MOV DS, AX
 XOR AX, AX
 MOV AL, N1
 MOV SI, OFFSET N2
 MOV BL, AL
 AND AL, 0F0H
 ADD AL, 30H
 MOV CL, 4H
 ROR BL, CL
 AND BL, 0FH
 ADD BL, 30H
 MOV [SI], BL
 MOV AH, 4CH
 INT 21H
 INT 3H
 CODE ENDS
 END START

RESULT:

 I/P : 56H
 O/P: 35H,36H

Viva Questions:

1. What is the difference between adding 30h and OR 30H to a BCD number to conversion to ASCII?
2. Why unpacking is necessary during the conversion?
3. What is the ASCII character for symbol A?
4. What is the ASCII character for symbol zero '0'?
5. What is ROR instruction will do?

Program No: 5(d) ASCII to BCD CONVERSION

DATA SEGMENT

N1 DB 35H

N2 DB 02H DUP (00)

DATA ENDS

CODE SEGMENT

ASSUME CS: CODE, DS: DATA

```
START:    MOV AX, DATA
          MOV DS, AX
          XOR AX, AX
          MOV AL, N1
          AND AL, 0FH
          MOV AH, 4CH
          INT 21H
          INT 3H
          CODE ENDS
          END START
```

RESULT:

I/P : 35H

O/P : 05H

Viva Questions:

1. What is the use of DAA instruction?
2. What is the reason for packing & Un-Packed BCD?
3. What is the ASCII instruction, which is used before the arithmetic operation?
4. What is the Expansion of BCDIP?
5. What is the need for segmentation?

Application Programs**Program No: 6 (a) EVEN AND ODD NUMBERS****DATA SEGMENT**

N1 DB 56H, 49H, 33H

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```
START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV SI, OFFSET N1
        MOV DX, 0000H
        MOV BX, 0000H
        MOV CX, 0003H
BACK:   MOV AL, [SI]
        ROR AL, 01H
        JC  X
        INC BX
        JMP Y
X:      INC DX
Y:      INC SI
        DEC CX
        JNZ BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
CODE ENDS
END START
```

RESULT:

I/P : 56H 49H 33H
O/P : BX=0001H,DX=0002H

Viva Questions:

1. What is the function of Bx?
2. What are the branch instructions?
3. What is the difference between conditional and unconditional jump instructions?
4. What is the function of Ax in the program?
5. What is significance of accumulator?

Programm:6 (b) POSITIVE AND NEGATIVE NUMBER**DATA SEGMENT**

N1 DB 51H, 20H, 33H, 80H, 19H

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```

START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV SI, OFFSET N1
        MOV DX, 0000H
        MOV BX, 0000H
        MOV CX, 0005H
BACK:   MOV AL, [SI]
        ROL AL, 01H
        JC  X
        INC BX
        JMP Y
X:      INC DX
Y:      INC SI
        DEC CX
        JNZ BACK
        MOV AH, 4CH
        INT 21H
        INT 3H
CODE ENDS
END START

```

RESULT:

I/P : 56H 49H 33H
O/P : BX=0004H, DX=0001H

Viva Questions:

- 1.** What is the function of ROL?
- 2.** What are the branch instructions?
- 3.** What is the difference between conditional and unconditional jump instructions?
- 4.** What is the function of JC in the program?
- 5.** What is significance of accumulator?

Program No: 7(a)**ASCENDING ORDER****DATA SEGMENT**

N1 DB 56H, 49H, 33H, 05H, 12H, 17H, 08H

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```

START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV BX, 0006H
Z:      MOV SI, OFFSET N1
        MOV CX, 0006H
BACK:   MOV AL, [SI]
        INC SI
        CMP AL, [SI]
        JBE Y
        XCHG AL, [SI]
        DEC SI
        MOV [SI], AL
        INC SI
Y:      DEC CX
        JNZ BACK
        DEC BX
        JNZ Z
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START

```

RESULT:

I/P : 56H, 49H, 33H, 05H, 12H, 17H, 08H
 O/P : 05H, 08H, 12H, 17H, 33H, 49H, 56H,

Viva Questions:

1. What is the function of JBE ?
2. What is the need of CMP instructions?
3. What is the difference between conditional and unconditional jump instructions?
4. What is the function of XCHG in the program?
5. What is the significance of accumulator?

Program No: 7(b)**DESCENDING ORDER****DATA SEGMENT**

N1 DB 56H, 49H, 33H, 05H, 12H, 17H, 08H

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```

START:  MOV AX, DATA
        MOV DS, AX
        XOR AX, AX
        MOV BX, 0006H
Z:      MOV SI, OFFSET N1
        MOV CX, 0006H
BACK:   MOV AL, [SI]
        INC SI
        CMP AL, [SI]
        JAE Y
        XCHG AL, [SI]
        DEC SI
        MOV [SI], AL
        INC SI
Y:      DEC CX
        JNZ BACK
        DEC BX
        JNZ Z
        MOV AH, 4CH
        INT 21H
        INT 3H

```

CODE ENDS**END START****RESULT:**

I/P : 56H, 49H, 33H, 05H, 12H, 17H, 08H

O/P : 56H, 49H, 33H, 17H, 12H, 08H, 05H

Viva Questions:

1. What is the function of JAE?
2. What IS the need of CMP instructions?
3. What is the difference between conditional and unconditional jump instructions?
4. What is the function of XCHG in the program?
5. What is significance of accumulator?

Program No: 8 BLOCK TRANSFER**DATA SEGMENT****N1 DB 01H,02H,03H****DATA ENDS****EXTRA SEGMENT****N2 DB 03H DUP (00)****EXTRA ENDS****CODE SEGMENT****ASSUME CS:CODE, DS:DATA, ES:EXTRA**

```
START:  MOV AX, DATA
        MOV DS, AX
        MOV AX, EXTRA
        MOV ES, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        CLD
        MOV CX, 0003H
REP     MOVSB
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START
```

RESULT:

I/P : 01H, 02H, 03H

O/P : 01H, 02H, 03H

Viva Questions:

- 1. If the DF=1, will the SI and DI register decremented?
 2. The destination memory is pointed by which register combination?
 3. The source is pointed to by which register combination?
 4. What is the purpose of instruction pointer?
 5. What is the purpose of stack pointer?

Program No: 9(a) READ A CHARACTER WITH & WITH OUT ECHO

ASSUME CS:CODE,

```
START :    MOV AH, 01H
           INT 21H
           MOV AH, 4CH
           INT 21H
           INT 3H
           CODE END
           END START
```

RESULT:

INPUT: 'a'
OUPUT:'a'

ASSUME CS:CODE,

```
START :    MOV AH, 07H
           INT 21H
           MOV AH, 4CH
           INT 21H
           INT 3H
           CODE END
           END START
```

RESULT:

INPUT: 'a'
OUPUT:-

Viva Questions:

1. What is the difference between a character with & without echo?
2. What is the use of MOV AH, 01H and MOV AH, 07H?
3. What are the general purposes registers?
4. What is the use of Extra segment?
5. What is the purpose of Instruction pointer?

Program No: 9(b)**DISPLAY CHARACTER**

ASSUME CS CODE:

```
START:  MOV AX,DATA
        MOV DS, AX
        MOV CX, 0005H
X:      MOV AH, 02H
        MOV DL, 'Z'
        INT 21H
        MOV AH, 02H
        MOV DL, 20H
        INT 21H
        DEC CX
        JNZ X
        INT3H
        CODE END
        END START
```

RESULT:

```
INPUT      : 'Z'
OUTPUT     : Z Z Z Z Z
```

Viva Questions:

—

1. What is the need of Segments?
2. What is the difference between INT 21H and INT 3H?
3. What is the use of Base Pointer?
4. What is the use of Index Register?
5. What is the use of addressing modes?

Program No: 10**STRING REVERSAL****DATA SEGMENT**

N1 DB 'MLRIT\$'

N2 DB 05H DUP (00)

DATA ENDS**CODE SEGMENT**

ASSUME CS:CODE, DS:DATA

```
START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET N1
        MOV DI, OFFSET N2
        ADD DI, 0005H
        CLD
        MOV AH, '$'
X:      CMP AH, [SI]
        JE Y
        MOV AL, [SI]
        MOV [DI], AL
        INC SI
        DEC DI
        LOOP X
        MOV AH, 4CH
        INT 21H
Y:      INT 3H
CODE ENDS
END START
```

Viva Questions:

1. Why BX register is added with '5'?
2. Why MOVS instruction is not used?
3. What is the function of LODS and STOS instructions?
4. What is the use of segmentation?
5. What is the length of instruction pointer?

Program No: 11 STRING INSERTION**DATA SEGMENT**

STRING1 DB 'EMPTY VESSELS MORE NOISE\$'

STRLEN EQU (\$-STRING1)

DATA ENDS**EXTRA SEGMENT**

STRING2 DB STRLEN+5 DUP (0)

EXTRA ENDS**CODE SEGMENT**

ASSUME CS: CODE, DS: DATA, ES: EXTRA

```
START:  MOV AX, DATA
        MOV DS, AX
        MOV SI, OFFSET STRING1
        MOV DI, OFFSET STRING2
        CLD
        MOV CX, 14
        REP MOVSB
        MOV DL, 5
BACK:   MOV AH, 01
        INT 21H
        STOS STRING2
        DEC DL
        JNZ BACK
        MOV CX, 11
        REP MOVSB
        NOP
        MOV AH, 4CH
        INT 21H
        INT 3H
        CODE ENDS
        END START
```

Viva Questions:__

1. Why register 'DI' is loaded with 5?
2. What is the function of rep movsb?
3. What is the purpose of mov ah, 01h / int 21h?
4. What is meant flag register?
5. What is the use of SI and DI registers?

Program No: 12 STRING DELETION**.MODEL TINY****DATA SEGMENT**

STRING1 DB 'EMPTY VESSELS MAKE MORE NOISE\$'
STRLEN EQU (\$-STRING1)

DATA ENDS**EXTRA SEGMENT**

STRING2 DB STRLEN-5 DUP (0)

EXTRA ENDS**CODE SEGMENT**

ASSUME CS: CODE, DS: DATA, ES: EXTRA

```
START:  MOV AX, DATA
        MOV DS, AX
        MOV AX, EXTRA
        MOV ES, AX
        MOV SI, OFFSET STRING1
        MOV DI, OFFSET STRING2
        CLD
        MOV CX, 13
        REP MOVSB
        CLD
        MOV SI, 18
        MOV CX, 12
        REP MOVSB
        MOV AH, 4CH
        INT 21H
        INT 3H
```

CODE ENDS**END START**

Viva Questions:—

1. What is the purpose of string length?
2. What does 'equ' stands for?
3. What is the purpose of label start after the end directive?

Program No: 13 LENGTH OF THE STRING**DATA SEGMENT**

```
STRING1 DB 'EMPTY VESSELS MAKE MORE NOISE$'  
STRLEN EQU ($-STRING1)  
RES DB 0  
CORT DB 'STRLENGTH FOUND CORRECT$'  
INCORT DB 'STRLENGTH FOUND INCORRECT$'
```

DATA ENDS**CODE SEGMENT**

```
ASSUME CS:CODE, DS:DATA
```

```
START:  MOV AX, DATA  
        MOV DS, AX  
        SUB CL, CL  
        MOV BL, STRLEN  
        MOV SI, OFFSET STRING1  
BACK:   LODSB  
        INC CL  
        CMP AL, '$'  
        JNZ BACK  
        MOV RES, CL  
        CMP CL, BL  
        JZ CORRECT  
        MOV DX, OFFSET INCORT  
        MOV AH, 09  
        INT 21H  
CORRECT: MOV DX, OFFSET CORT  
        MOV AH, 09  
        INT 21H  
        MOV AH, 4CH  
        INT 21H  
        INT 3H  
CODE ENDS  
END START
```

Viva Questions:

1. What is the operation performed by the instruction `cmp al,$` ?
2. What is function `09h / int 21h` performed?
3. Why `SI` is not been incremented in the program?

Program No: 14 STRING COMPARISION

```

DATA SEGMENT
    STRING1 DB 'EMPTY'
    STRLEN EQU ($-STRING1)
    NOTSFUL DB 'STRINGS ARE UNEQUAL$'
    SFUL DB 'STRINGS ARE EQUAL$'
DATA ENDS
EXTRA SEGMENT
    STRING2 DB 'EMPTY'
EXTRA ENDS
CODE SEGMENT
    ASSUME CS:CODE, DS:DATA, ES:EXTRA

                START:    MOV AX, DATA
                        MOV DS, AX
                        MOV AX, EXTRA
                        MOV ES, AX
                        MOV SI, OFFSET STRING1
                        MOV DI, OFFSET STRING2
                        CLD
                        MOV CX,LENGTH STRING1
                        MOV CX, STRLEN
                        REP CMPSB
                        JZ FORW
                        MOV AH, 09H
                        MOV DX, OFFSET NOTSFUL
                        INT 21H
                        JMP EXITP
                        FORW:MOV AH,09H
                        MOV DX, OFFSET SFUL
                        INT 21H
                        EXITP:
                        NOP
                        MOV AH, 4CH
                        INT 21H
                        INT 3H
CODE ENDS
END START

```

Viva Questions:

—

1. What is the significance of CLD?
2. How does CMPSB perform the comparison?

Program No: 15**LEFT ENTRY DECODED MODE**

```

DATA SEGMENT
CTRL EQU 3002H ;control word
DAT EQU 3000H ;data word
DATA SEGMENT
TBL: DB 3FH, 06H, 5BH, 4FH
      DB 66H, 6DH, 7DH, 07H
DATA ENDS
CODE SEGMENT
      ORG 0000: 4000H
      ASSUME CS: CODE , DS:DATA
START:
      MOV AL, 09H ;LE 8 bit char. display
      MOV DX, CTRL
      OUT DX, AL
      MOV AL, 31H ;clock dividing factor
      OUT DX, AL

LE: MOV AL, D0H ; clear display
      OUT DX, AL
      MOV CX, 0FFFFH ;wait till display is cleared
L1: LOOP L1
      MOV AL, 01H ;control word for 8 chars
      OUT DX, AL ;left entry mode. 8 no. of chars
      MOV AH, 08 ;will be displayed
      MOV BX, OFFSET TBL ;char displayed are stored
      MOV AL, 90H ;control word for writing to
      OUT DX, AL ; display auto increment
RPT:
      MOV AL, [BX]
      MOV DX, DAT
      OUT DX, AL
      MOV CX, 0FFFFH ; delay
L2: LOOP L2
      INC BX
      DEC AH
      JNZ RPT
      MOV CX, 0FFFFH
L3: LOOP L3
      INT 3
CODE ENDS
END

```

Program No: 16**RIGHT ENTRY ENCODED MODE**

DATA SEGMENT

CTRL EQU 3002H ;control word

DAT EQU 3000H ;data word

DATA SEGMENT

ORG 0000H:3000H

TBL: DB 3FH,06H,5BH,4FH

DB 66H,6DH,7DH,07H

DATA ENDS

CODE SEGMENT

ORG 0000:4000H

ASSUME CS:CODE,DS:DATA

START:

MOV AL, 08H ;RE 8 bit char. display

MOV DX, CTRL

OUT DX, AL

MOV AL, 31H ;clock dividing factor

OUT DX, AL

RE: MOV AL, D0H ; display clear

OUT DX, AL

MOV CX, 0FFFFH

L1: LOOP L1

MOV AL, 10H ; control word for rt entry mode

OUT DX, AL

MOV AH, 08

MOV BX, OFFSET TBL

MOV AL, 90H

OUT DX, AL

RPT:

MOV AL, [BX]

MOV DX, DAT

OUT DX, AL

MOV CX, 0FFFFH

L2: LOOP L2

INC BX

DEC AH

JNZ RPT

MOV CX, 0FFFFH

L3: LOOP L3

INT 3

CODE ENDS

END START

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Program No: 17 8255 OPERATING IN STROBED OUTPUT MODE (MODE 1)

```

PORTA EQU 3000H
PORTB EQU 3002H
PORTC EQU 3004H
CTLP_55 EQU 3006H
CMD59 EQU FFD8H
DATA59 EQU FFDAH
DATA SEGMENT
    ORG 0:3000H
IBYTE: DB 0
DATA ENDS

```

```

CODE SEGMENT
    ORG 0000:4000H

```

```

    ASSUME CS:CODE ,DS:DATA

```

```

START:
    MOV AX,00H
    MOV SS,AX      ;Stack segment initialisation
    MOV SP,2000H

```

```

    CLI
    CLD

```

```

    MOV AX,00H      ;data segment initialisation
    MOV DS,AX

```

```

    MOV BX,202H
    PUSH CS
    POP AX          ;initialisation of interrupt vector
    MOV [BX],AX
    MOV BX,200H
    LEA AX,CS:SERVICE
    MOV [BX],AX

```

```

    MOV DX,CMD59    ;ICW1
    MOV AL,13H
    OUT DX,AL

```

```

    MOV DX,DATA59   ;ICW2(interrupt vector address)
    MOV AL,80H      ;initialisation of PIC 8259A
    OUT DX,AL
    MOV AL,0FH
    OUT DX,AL

```

```
MOV AL,FEH
OUT DX,AL
```

```
MOV DX,CTLP_55 ;initialise 8255 in mode1.
MOV AL,B4H      ;portA i/p and portB o/p
OUT DX,AL
```

```
MOV AL,05H      ;enable INTE flip flop which is
MOV DX,CTLP_55  ;controlled by bit set/reset of PC2
OUT DX,AL
```

```
MOV AL,0AH
OUT DX,AL        ;IBF(PC5) taken low
MOV AL,0FH
OUT DX,AL        ;OBF2*(PC7) taken high
```

```
MOV AL,IBYTE
MOV CL,AL
MOV DX,PORTB     ;output data on portB
OUT DX,AL
```

```
STI
BACK1: MOV DX,PORTC
      IN AL,DX
      AND AL,01
      CMP AL,01
      JNZ BACK1
```

```
BACK: JMP BACK
```

```
SERVICE:
      MOV AL,CL
      NOT AL      ;Complement the value and
      MOV CL,AL   ;output it to portB
      MOV DX,PORTB
      OUT DX,AL
RETURN:STI
      IRET
```

```
CODE ENDS
END
```

Program No:18 PROGRAM TO TEST 8255 IN MODE 2 (BIDIRECTIONAL INPUT MODE)

```

PORTA EQU 3000H    ;8255 PORTA address
PORTB EQU 3002H    ;8255 PORTB address
PORTC EQU 3004H    ;8255 PORTC address
CTLP_55 EQU 3006H  ;8255 CONTROL PORT address
DBDT EQU 0F800:4F1FH ;routine to display
CMD59 EQU FFD8H
DATA59 EQU FFDAH

```

```

DATA SEGMENT
    ORG 0000:3000H
MSG DB '8255 in md2 I/P ',0h
DATA ENDS

```

```

CODE SEGMENT
    ORG 0000:4000H
    ASSUME CS:CODE,DS:DATA

```

```

START:
    MOV AX,00H
    MOV SS,AX    ;stack segment initialisation
    MOV SP,2000H

    CLI
    CLD

    MOV AX,00H    ;data segment initialisation
    MOV DS,AX

    MOV BX,202H
    PUSH CS
    POP AX
    MOV [BX],AX    ;interrupt vector initialisation
    MOV BX,200H
    LEA AX,CS:SERVICE
    MOV [BX],AX

    MOV DX,CMD59    ;ICW1 H
    MOV AL,13H
    OUT DX,AL
    MOV DX,DATA59    ;ICW2(interrupt vector address)
    MOV AL,80H    ;initialisation of PIC 8259A
    OUT DX,AL
    MOV AL,0FH

```

```
OUT DX,AL
MOV AL,FEH
OUT DX,AL
```

```
MOV AL,C1H      ;initialise 8255 in mode 2
MOV DX,CTLP_55   ;portA i/p & o/p,portC lower i/p.
OUT DX,AL
```

```
MOV AL,09H      ;enable INTE2 flip flop which is
MOV DX,CTLP_55   ;controlled by bit set/reset of pc4
OUT DX,AL
```

```
STI              ;enable interrupt
```

```
BACK: JMP BACK
```

;When STB* pulse is given by pressing the switch,STB* line
;goes low & IBF goes high & INTR line goes high and data is
;read by 8255. Then control jumps to interrupt service routine
;to perform read operation.O/P the same on portB and display.

```
SERVICE:
```

```
MOV DX,PORTA
IN AL,DX
MOV CL,AL
MOV DX,PORTB
OUT DX,AL
```

```
MOV CH,00H
MOV SI,CX
```

```
STI
IRET
```

```
CODE ENDS
END
```

**Program No: 19 PROGRAM TO TEST 8255 IN MODE 2 (BIDIRECTIONAL
OUTPUT MODE)**

```
PORTA EQU 3000H
PORTB EQU 3002H
PORTC EQU 3004H
CTLP_55 EQU 3006H
CMD59 EQU FFD8H
DATA59 EQU FFDAH
```

```
DATA SEGMENT
    ORG 0000:3000H
IBYTE DB 0
DATA ENDS
```

```
CODE SEGMENT
    ORG 0000:4000H
    ASSUME CS:CODE ,DS:DATA
```

```
START:
    MOV AX,00H
    MOV SS,AX ;stack segment initialisation
    MOV SP,2000H
```

```
CLI
CLD
```

```
MOV AX,00H ;data segment initialisation
MOV DS,AX
```

```
MOV BX,202H
PUSH CS
POP AX
MOV [BX],AX ;interrupt vector initialisation
MOV BX,200H
LEA AX,CS:SERVICE
MOV [BX],AX
```

```
MOV DX,CMD59 ;ICW1
MOV AL,13H
OUT DX,AL
MOV DX,DATA59 ;ICW2(interrupt vector address)
MOV AL,80H ;initialisation of PIC 8259A
OUT DX,AL
MOV AL,0FH
OUT DX,AL
MOV AL,FEH
```

OUT DX,AL

MOV AL,C1H ;initialise 8255 in mode 2
MOV DX,CTLP_55 ;port A i/p & o/p,port C lower i/p
OUT DX,AL

MOV AL,0DH ;enable INTE flip flop
MOV DX,CTLP_55
OUT DX,AL

MOV AL,03H ;OBF1* taken high
OUT DX,AL

STI ;enable interrupt

BACK: JMP BACK

SERVICE:

MOV AL,IBYTE
MOV DX,PORTA
OUT DX,AL
STI
IRET

CODE ENDS
END

Program No:20 PROGRAM TO TEST 8255 IN MODE 1 (STROBED I/O MODE)

```

PORTA EQU 3000H
PORTB EQU 3002H
PORTC EQU 3004H
CTLP_55 EQU 3006H
CMD59 EQU FFD8H
DATA59 EQU FFDAH

```

```

DATA SEGMENT
DATA ENDS

```

```

CODE SEGMENT

```

```

    ORG 0000:4000H

```

```

    ASSUME CS:CODE ,DS:DATA

```

```

START:

```

```

    MOV AX,00H    ;initialisation of stack pointer
    MOV SS,AX
    MOV SP,2000H

```

```

    CLI
    CLD

```

```

    MOV AX,00H    ;data segment initialisation
    MOV DS,AX

```

```

    MOV BX,202H   ;initalisation of interrupt vector
    PUSH CS
    POP AX
    MOV [BX],AX
    MOV BX,200H
    LEA AX,CS:SERVICE
    MOV [BX],AX

```

```

    MOV DX,CMD59  ;ICW1
    MOV AL,13H
    OUT DX,AL

```

```

    MOV DX,DATA59 ;ICW2(interrupt vector address)
    MOV AL,80H
    OUT DX,AL

```

```
MOV AL,0FH
OUT DX,AL      ;ICW4

MOV AL,0FEH
OUT DX,AL      ;OCW1(IR0 mask reset)

MOV AL,0B4H    ;initialisation of 8255 for mode1
MOV DX,CTLP_55 ;input operation
OUT DX,AL

MOV AL,09H     ;to enable INTE flip flop which is
OUT DX,AL      ;controlled by bit set/reset of pc4

MOV AL,03H     ;OBF1(PC1) is set
OUT DX,AL

MOV AL,0AH     ;IBF(PC5) is reset
OUT DX,AL

MOV AL,0FH     ;OBF2(PC7) is set
OUT DX,AL
MOV DX,PORTC
BACK1:
IN AL,DX
AND AL,08
CMP AL,08
JNZ BACK1

STI            ;enable interrupt bit

BACK: JMP BACK

SERVICE:

MOV DX,PORTA
IN AL,DX
MOV DX,PORTB
OUT DX,AL
STI
IRET

CODE ENDS
END
```

Program No:21**PROGRAM TO TEST 8255 IN MODE 0 (BASIC I/O)**

```

PORTA EQU 3000H ;8255 PORT A address
PORTB EQU 3002H ;8255 PORT B address
PORTC EQU 3004H ;8255 PORT C address
CTLP_55 EQU 3006H ;8255 control port address

```

```

DATA SEGMENT
DATA ENDS

```

```

CODE SEGMENT

```

```

ORG 0000:4000H

```

```

ASSUME CS:CSEG,DS:DSEG

```

```

; displaying message on LCD

```

```

START:

```

```

MOV AL,90H ;control word to initialise 8255
MOV DX,CTLP_55 ;portA as i/p, portB and portC as o/p
OUT DX,AL

```

```

LOOP1:

```

```

MOV DX,PORTA
IN AL,DX
NOT AL
MOV DX,PORTB
OUT DX,AL

```

```

MOV AL,02H ;reset pc1 bit
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY

```

```

MOV AL,03H ;set pc1 bit
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY

```

```

MOV AL,0AH ;reset pc5 bit
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY

```

```

MOV AL,0BH ;set pc5 bit

```

```
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY

MOV AL,0EH    ;reset pc7 bit
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY

MOV AL,0FH    ;set pc7 bit
MOV DX,CTLP_55
OUT DX,AL
CALL DELAY
;    MOV DX,PORTA
;    IN  AL,DX
;    NOT AL
;                ;This program can be executed for
JMP LOOP1     ;different switch settings

DELAY:MOV CX,7FFFH
NEXT:LOOP NEXT    ;loop for delay
RET

CODE ENDS
END
```

Program No:22 PROGRAM TO TEST 8251 RECEIVING PART

```

CLOCK_FREQ EQU 1536000 ;8253 clock frequency
CTL_8251 EQU 3402H ;8251 control port address
DATA_8251 EQU 3400H ;8251 data port address
TMR1_8253 EQU 3002H ;8253 timer1 address
CTL_8253 EQU 3006H ;8253 control port address
EXT_RAM_LC EQU 0:FF00H ;RAM location
DBDT EQU F800:4F1FH ;routine for display on data field

```

```

CNT_BAUD_9600_MODE16 EQU 000AH
CNT_BAUD_4000_MODE01 EQU 0140H
CNT_BAUD_2400_MODE16 EQU 0028H
CNT_BAUD_1200_MODE64 EQU 0014H
CNT_BAUD_0300_MODE64 EQU 0050H

```

```

MODE_WORD16 EQU CEH
MODE_WORD1 EQU CDH
MODE_WORD64 EQU CFH

```

```

DATA SEGMENT
    ORG 0000:3000H
DATA ENDS

```

```

CODE SEGMENT
    ORG 0000:4000H
    ASSUME CS:CODE,DS:DATA

```

```

START:
    MOV AX,00H ;initialisation of stack pointer
    MOV SS,AX
    MOV SP,2000H
    MOV DS,AX
    CLI
    CLD
    MOV BX,0202H ;initialisation of interrupt vector
    PUSH CS
    POP AX
    MOV [BX],AX
    MOV BX,200H
    LEA AX,CS:SRVC2
    MOV [BX],AX

    MOV DX,FFD8H ;ICW1
    MOV AL,13H
    OUT DX,AL

```

```

MOV DX,FFDAH    ;ICW2(interrupt vector address)
MOV AL,80H
OUT DX,AL

MOV AL,0FH
OUT DX,AL      ;ICW4

MOV AL,0FEH
OUT DX,AL      ;OCW1(IR0 mask reset)

MOV BX,EXT_RAM_LC ;BX points to RAM location where the
                  ; Character read from 8251 is stored

MOV DX,CTL_8253  ;initialize timer1 in mode2
MOV AL,76H
OUT DX,AL

MOV DX,TMR1_8253
MOV AL,<CNT_BAUD_9600_MODE16 ;load LSB in count reg
OUT DX,AL
MOV AL,>CNT_BAUD_9600_MODE16 ;load MSB in count reg
OUT DX,AL

STI             ;enable interrupt

MOV DX,CTL_8251 ;send 0's to guarantee,device is in
MOV AL,00H      ;command instruction format before
OUT DX,AL       ;the RESET command is issued.

NOP
NOP
NOP
NOP
OUT DX,AL

NOP
NOP
NOP
NOP
OUT DX,AL

MOV DX,CTL_8251 ;send internal RESET command to
MOV AL,40H      ;return device to idle state
OUT DX,AL
NOP
NOP
NOP
NOP

```

```

MOV DX,CTL_8251 ;load mode control word
MOV AL,MODE_WORD16
OUT DX,AL
NOP
NOP
NOP
NOP

```

```

MOV DX,CTL_8251 ;load command word
MOV AL,36H
OUT DX,AL

```

```

BACK1: NOP
      JMP BACK1

```

```

SRVC2:
  MOV DX,DATA_8251
  IN AL,DX ;In the service routine data is
  IN AL,DX ;read from 8251,check whether typed
  NOP ;character is 0DH.If yes it indicates
  NOP ;it is the last char and is displayed
  NOP ;in the data field of the display and
  NOP ;reinitialise pointer to the starting
  CMP AL,0DH ;address of RAM location.
  JNZ AHEAD2

```

```

MOV AH,00
MOV SI,AX
CALL FAR DBDT
MOV BX,EXT_RAM_LC
JMP TERM

```

```

AHEAD2:MOV [BX],AL ;If typed char is other than 0DH
      INC BX ;then store the char in RAM loc.
TERM: STI
      IRET
CODE ENDS
END

```

Program No:23 TEST PROGRAM TO TEST THE 8259 ON THE 8086 UNI KIT

```

CLRDSF EQU 0F800:4BB1H
OP      EQU 0F000:1000H
DATA    SEGMENT

```

```

    ORG 0000:3000H

```

```

MSG    DB  'HELLO .....',0H
MSG1   DB  ' I GOT INTR 0 ',0H
MSG2   DB  ' I GOT INTR 1 ',0H
MSG3   DB  ' I GOT INTR 2 ',0H
MSG4   DB  ' I GOT INTR 3 ',0H
MSG5   DB  ' I GOT INTR 4 ',0H
MSG6   DB  ' I GOT INTR 5 ',0H
MSG7   DB  ' I GOT INTR 6 ',0H
MSG8   DB  ' I GOT INTR 7 ',0H

```

```

DSEG   ENDS

```

```

CODE    SEGMENT
    ASSUME CS:CODE ,DS:DATA

```

```

    ORG 0:4000H
START:
    PUSH CS
    POP  ES
    CALL FAR CLRDSF ;
    MOV  AX,0000H
    MOV  DS,AX
    MOV  BX,0202H
    MOV  CX,08H
FILL_CS:
    MOV  WORD PTR [BX],00H
    ADD  BX,4
    LOOP FILL_CS
    MOV  BX,0200H
    LEA  AX,CS:SERV1
    MOV  [BX],AX
    ADD  BX,4
    LEA  AX,CS:SERV2
    MOV  [BX],AX
    ADD  BX,4
    LEA  AX,CS:SERV3
    MOV  [BX],AX
    ADD  BX,4
    LEA  AX,CS:SERV4

```



```
MOV    [BX],AX
ADD    BX,4
LEA    AX,CS:SERV5
MOV    [BX],AX
ADD    BX,4
LEA    AX,CS:SERV6
MOV    [BX],AX
ADD    BX,4
LEA    AX,CS:SERV7
MOV    [BX],AX
ADD    BX,4
LEA    AX,CS:SERV8
MOV    [BX],AX
ADD    BX,4
MOV    DX,03000H
MOV    AL,13H
OUT    DX,AL
MOV    DX,03002H
MOV    AL,80H
OUT    DX,AL
MOV    AL,0FH
OUT    DX,AL
MOV    AL,00H
OUT    DX,AL
MOV    DI,80H
MOV    SI,OFFSET MSG
CALL   FAR OP
STI
BCK:   JMP    BCK

      ORG    0:6000H

SERV1: MOV    DI,0C0H
      MOV    SI,OFFSET MSG1
      CALL   FAR OP
      STI
      IRET

      ORG    0:600DH
SERV2: MOV    DI,0C0H
      MOV    SI,OFFSET MSG2
      CALL   FAR OP
      STI
      IRET

      ORG    0:601AH
SERV3: MOV    DI,0C0H
      MOV    SI,OFFSET MSG3
      STI
      IRET

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```

```
CALL FAR OP
STI
IRET

ORG 0:6027H
SERV4: MOV DI,0C0H
MOV SI,OFFSET MSG4
CALL FAR OP
STI
IRET

ORG 0:6034H
SERV5: MOV DI,0C0H
MOV SI,OFFSET MSG5
CALL FAR OP
STI
IRET

ORG 0:6041H

SERV6: MOV DI,0C0H
MOV SI,OFFSET MSG6
CALL FAR OP
STI
IRET

ORG 0:604EH
SERV7: MOV DI,0C0H
MOV SI,OFFSET MSG7
CALL FAR OP
STI
IRET

ORG 0:605BH
SERV8: MOV DI,0C0H
MOV SI,OFFSET MSG8
CALL FAR OP
STI
IRET

CSEG ENDS
ENDS
```

COMMAND LINE (DOS) :

1. Edit the program using 'EDIT' editor
2. Save as name .A51
3. Assemble using A51.EXE
C: A51 name .A51
Result: name .LST, name .OBJ
4. LINK & Convert to Hex format using OH51.EXE
C: OH51 name .OBJ
Result: name .HEX
5. Simulate Using SIM31.EXE

C: SIM31**Using Integrated Design Environment (IDE)****KEIL μ Vision – (Windows)**

1. Select START\PROGRAMS\KEIL <Left Click>
2. Create New project
Select PROJECT\NEW\<Left Click> "enter name"<Left Click>
Choose TARGET\INTEL\8051 <Left Click>
Choose BUILD OOPTIONS
Check Box HEX <OK><Left Click>
3. Create File <ALT><F><N> 'name of file .ASM' <Left Click>
Edit File & Save
4. SELECT PROJECT WINDOW – ADD FILE – SELECT - <Left Click>
5. PROJECT\BUILD\ <Left Click>
If no errors go to 7 else 3
6. DEBUG\START\ <Left Click>

**PROGRAM (a): TRANSFERRING A BLOCK OF DATA FROM INTERNAL
ROM TO INTERNAL RAM**

```
ORG 0000H
LJMP START
ORG 000BH
RETI
ORG 0013H
RETI
ORG 001BH
RETI
ORG 0023H
RETI
ORG 0023H
RETI
ORG 0026H
RETI
ORG 200H
START: MOV DPTR,#MESSAGE
      MOV R0,#20H
      MOV R7,#11
REP:  MOV A,#00H
      MOVC A,@A+DPTR
      MOV @R0,A
      INC R0
      INC DPTR
      DJNZ R7,REP

MESSAGE: DB "HELLO WORLD"
      END
```

Viva Questions: __

1. What are the two registers in 8051, which are used for indirect addressing?
2. What are the 16 bit registers available in 8051?
3. Which register cannot be decremented?
4. 8051 is a ----- bit microcontroller?

PROGRAM: (b) INTERNAL ROM TO EXTERNAL RAM

```
                                ORG 0000H

START:  MOV A,#00
        MOV SP,#07H
        MOV R3,#11
        MOV DPTR,#200H
        PUSH DPL
        PUSH DPH
REP:    MOV DPTR,#MESSAGE
        MOV R2,A
        MOVC A,@A+DPTR
        POP DPH
        POP DPL
        MOVX @DPTR,A
        INC DPTR
        PUSH DPL
        PUSH DPH
        INC R2
        MOV A,R2
        DJNZ R3,REP
MESSAGE: DB "HELLO WORD"
        END
```

Viva Questions:__

1. What does “jnz” instruction do?
2. What is the purpose of DPTR ?
3. How many 8 bit registers are available in 8051?
4. What is the purpose of R2?
5. What is the purpose of R3?

PROGRAM:(c) INTERNAL ROM TO EXTERNAL RAM**ORG 200H****START:** MOV R0,#40H
 MOV A,#30H
 MOV R6,#10**REP:** MOV @R0,A
 INC A
 INC R0
 DJNZ R6,**REP**
 MOV R1,#40H
 MOV DPTR,#400H
 MOV R7,#00H**REP1:** MOV A,@R0
 MOVX @DPTR,A
 INC DPTR
 INC R1
 INC R7
 CJNE R7,#10,**REP1****END**

Viva Questions: __

1. What is DPTR relative addressing?
2. What is the purpose of R7?
3. What is the purpose of R0?
4. What does “jnz” instruction do?
5. The stack pointer of 8051 grows upwards or downwards?

PROGRAM: (d) UNDERSTANDING THREE MEMORY AREAS OF 00-FF

ORG 0000H
LJMP START

ORG 200H

START: MOV A,#41H
MOV 20H,A
MOV A,#42H
MOV R0,#20H
MOV @R0,A
MOV A,#43H
MOV 80H,A
MOV A,#44H
MOV R0,#80H
MOV @R0,A

END

Viva Questions:__

1. What is the instruction used for loading accumulator from code memory?
2. What is the purpose of register R0?
3. What are the two registers in 8051 which are used for indirect addressing?