

# Lesson 9: Heuristic Search Algorithms

Reviewer

## What Is Heuristic Search?

- **Intelligent Shortcuts:** A **heuristic** is a technique to solve problems faster than classic methods or find approximate solutions when exact ones are too costly.
- **Speed Over Perfection:** Heuristics prioritize speed, often trading optimality or completeness for a quicker, informed solution.
- **Guided Estimation:** It uses a **heuristic function** to estimate how close a state is to the goal, intelligently guiding the search.

## Why Do We Need Heuristics?

- **Tackling Complexity:** Many problems boast **exponentially large search spaces**, rendering exhaustive search methods impractical and time-consuming.
- **Efficiency Boost:** Heuristics dramatically reduce search time by focusing on promising paths, enabling solutions within a reasonable timeframe.

## Hill Climbing Algorithm: Climbing Towards the Goal

- **Greedy Approach:** A greedy heuristic search that moves step-by-step to states with incrementally better scores.
- **Potential Pitfalls:** While simple and fast, it can get stuck at **local maxima**, **plateaus**, or **ridges**, preventing it from reaching the global optimum.
- **Example:** Navigating a car through the streets of Washington, D.C., always moving closer to the monument, but potentially getting stuck in a traffic loop.

## A\* Search Algorithm

1. **Combined Evaluation:**  $A^*$  combines the actual cost so far  $g(n)$  and the heuristic estimate  $h(n)$  into a single function:
$$f(n) = g(n) + h(n)$$
2. **Optimality Guarantee:** It guarantees an optimal solution if the heuristic used is **admissible** (meaning it never overestimates the true cost to the goal).
3. **Versatile Applications:** Widely employed in critical fields such as pathfinding, robotics, and advanced AI planning due to its effectiveness.

## Example: A\* Search in Action

Starting at node A and aiming for node H, the  $A^*$  algorithm systematically evaluates potential paths.

It calculates the total estimated cost  $f(n)$  for each node by summing the cost already incurred  $g(n)$  and the estimated cost to the goal  $h(n)$ . By always choosing the path with the lowest  $f(n)$ ,  $A^*$  efficiently and effectively identifies the shortest path to the destination.

## Characteristics of Good Heuristics

- **Admissible:** A good heuristic should **never overestimate** the true cost to reach the goal.
- **Consistent (Monotonic):** The estimated cost from the current node to a neighbor, plus the neighbor's heuristic, must always be greater than or equal to the current node's heuristic.
- **Domain-Specific:** Incorporating knowledge specific to the problem domain significantly enhances the quality of the heuristic and, consequently, the efficiency of the search.

## Heuristic Search Powers Efficient AI

- **Accelerated Problem Solving:** Heuristics empower AI to rapidly solve complex problems by strategically focusing on the most promising solutions.
- **Balancing Act:** Algorithms like Hill Climbing, Best-First Search, and  $A^*$  skillfully balance speed and accuracy in their quest for solutions.
- **Key to Advancement:** The understanding and masterful design of effective heuristics are fundamental to driving the progress of intelligent systems.

## Greedy Algorithms

**Greedy Algorithm:** An algorithmic paradigm that follow the problem solving approach of making the **locally optimal choice** at each stage with the hope of finding a global optimum.

*Note: The source material includes a diagram with various numerical values and nodes (e.g., gas 3 cost 42, 53, 43, 70, 8, etc.) illustrating a specific graph instance.*

## When to use greedy approach?

Problems with greedy approach work has two properties:

1. **Greedy - choice property:** A global optimum can be arrived at by selecting a local optimum.
2. **Optimal Substructure:** An optimal solution to the problem contains an optimal solution to subproblems.

## Greedy Best-First Search

Formula:

$$f(n) = h(n)$$

## Concept

**Greedy Best-First Search** always expands the node that is estimated to be closest to the goal.

## Diagram Components

- Node[cost]
- Closed List
- Nodes represented: P, M, R, C, U, A
- Values associated: (10), [9], [8], [4], (6), (8), (11), (9), (4)

## Pros & Cons

- **Pros:** Very fast. Efficient in many simple cases.
- **Cons:** Can get stuck in loops. Not optimal (may not find the shortest path).

## Application of heuristic search algorithm

- **GPS Navigation:**  $A^*$  is the backbone of finding the shortest route in maps (Google Maps, Waze).
- **Robotics:** Path planning for autonomous robots in warehouses (Amazon Kiva).
- **Video Games:** NPC movement and AI pathfinding.
- **Network Routing:** Optimizing data packet paths across the internet.