

Ans 1

$$P(x_1, x_2, \dots, x_n | \mu) = \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-\sum_{i=1}^n \frac{0.5(x_i - \mu)^2}{\sigma^2}\right)$$

To maximize the likelihood  $f_{x^n}$  we have to minimize  $\sum_{i=1}^n (x_i - \mu)^2$  w.r.t  $\mu$ .

$$\frac{d}{d\mu} \sum_{i=1}^n (x_i - \mu)^2 = \sum_{i=1}^n \frac{d}{d\mu} ((x_i - \mu)^2) = \sum_{i=1}^n -2(x_i - \mu) = 0$$
$$\Rightarrow \sum_{i=1}^n x_i - n\mu = 0$$
$$\Rightarrow \mu = \frac{\sum_{i=1}^n x_i}{n}$$
$$\frac{d^2}{d\mu^2} \left( \sum_{i=1}^n (x_i - \mu)^2 \right) > 0$$

thus it is a minima.

Thus

$$\hat{\mu}_{ML} = \frac{\sum_{i=1}^n x_i}{n}$$

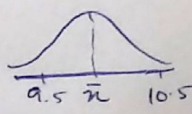
For map1 the posterior will also be a gaussian with mean

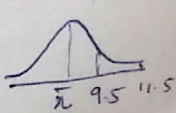
$$\hat{\mu}_{map1} = \frac{\left( \frac{\sum_{i=1}^n x_i}{n} \right) \sigma_{prior}^2 + \mu_{prior} \frac{\sigma_{true}^2}{n}}{\sigma_{prior}^2 + \sigma_{true}^2/n}$$

For  $\hat{\mu}_{map2}$   $P(\theta) = \begin{cases} \frac{1}{2} & \text{if } \theta \in (9.5, 11.5) \\ 0 & \text{otherwise} \end{cases}$

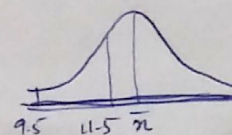
$$\text{Posterior} = P(\theta | x_1, x_2, \dots, x_n) = \frac{P(x_1, x_2, \dots, x_n | \theta) P(\theta)}{P(x_1, x_2, \dots, x_n)}$$

$$\begin{cases} \propto \frac{1}{(\sqrt{2\pi}\sigma)^n} \exp\left(-0.5 \sum_{i=1}^n \frac{(x_i - \theta)^2}{\sigma^2}\right) * \frac{1}{2} & \text{if } \theta \in (9.5, 11.5) \\ = 0 & \text{otherwise} \end{cases}$$

Thus if  $\frac{\sum_{i=1}^n x_i}{n} \in (9.5, 11.5)$  then  $\hat{\mu}_{map2} = \frac{\sum_{i=1}^n x_i}{n}$  

Otherwise if  $\frac{\sum_{i=1}^n x_i}{n} < 9.5$  then  $\hat{\mu}_{map2} = 9.5$  

if  $\frac{\sum_{i=1}^n x_i}{n} > 11.5$  then  $\hat{\mu}_{map2} = 11.5$



- (i) In general as  $N$  increases the error decreases for maximum likelihood estimate because sample mean approaches true means as  $n$  becomes larger & larger.

For ~~the~~  $\hat{\mu}_{map1}$ ,  $\hat{\mu}_{map2}$ , for smaller values of  $n$ , prior dominates but as  $n$  becomes larger the data starts dominating the posterior distribution due to which there might be some fluctuations in errors as  $n$  increases but in general as  $n$  increases, errors decrease.

- (ii) We will prefer the  $\hat{\mu}_{map1}$  <sup>estimate</sup> ~~value~~ because it has lesser relative error than the other two estimates.