# Magnetostatics

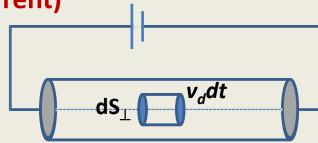
**Eelectrostatics: charges at rest** 

Magnetostatics: ??????

Magnetic field is produced by charges in flow (current)

n : number density; no. of charge carriers per unitvolume

 $v_d$ : additional velocity of charge carriers due to applied p.d.



 $dS_{\perp}$ : area of the pillbox  $\perp v$  $v_d dt$ : length of pillbox

Charge in the pillbox  $dQ = qn(v_d dt dS_\perp)$ 

Current flowing in the pillbox  $i = \frac{dQ}{dt} = qnv_d dS_\perp$ 

J: current density

Current density 
$$J=\frac{i}{dS_{\perp}}=qnv_d=\rho v_d$$
  $\rho=$  volume charge density (number of charges per unit volume

: volume current density = dI/dS

$$I = \int \vec{J}.\,\hat{n}\,dS$$

 $\hat{n}$  unit vector normal to the surface.

A current carrying wire with current density  $\vec{J} = C r \hat{z}$ (i.e, current along z direction)

C: constant, r: radial distance from the axis of the cylinder.

$$I = \int \vec{J} \cdot \hat{n} \, dS = \int_{0}^{R} Cr \left( r dr d\theta \right) = \frac{2\pi CR^{3}}{3}$$

Surface current density, 
$$K = \frac{dI}{dl_{\perp}} = \sigma v$$
 Similarly,  $I = \lambda v$ 

Magnetic force on a current carrying wire in a magnetic field B

$$F_{mag} = \int (\lambda \, dl) (\vec{v} \times \vec{B}) = \int (\vec{I} \times \vec{B}) dl$$

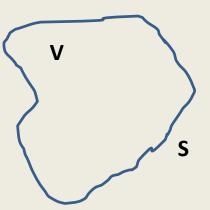
$$= \int I (\vec{dl} \times \vec{B}) = I \int (\vec{dl} \times \vec{B})$$

$$F_{mag} = \int (\vec{K} \times \vec{B}) dS$$

$$F_{mag} = \int (\vec{J} \times \vec{B}) d\tau$$

### **Continuity Equation and conservation of charge**

Surface S encloses volume V with total charge Q



Rate at which charges flow out = Rate at which charges deplete in the volume

$$\iint_{S} \vec{J} \cdot \hat{n} \, dS = -\frac{d}{dt} Q_{\text{inside}} = -\frac{d}{dt} \int_{\tau} \rho d\tau$$

$$\int_{\tau} (\vec{\nabla} \cdot \vec{J}) \ d\tau = -\int_{\tau} \frac{d\rho}{dt} d\tau \qquad \vec{\nabla} \cdot \vec{J} = -\frac{d\rho}{dt} \qquad \text{Continuity equation}$$

**Conservation of charge** 

IF 
$$\frac{d\rho}{dt} = 0$$
,  $\vec{\nabla} \cdot \vec{J} = 0$  Steady currents

Magneto-statics

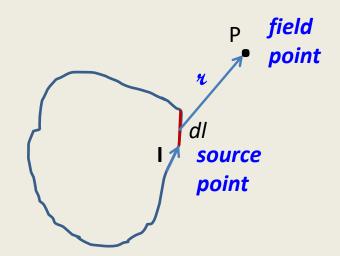
### **Biot-Savart's Law**

For steady currents,

$$\vec{B}(P) = \frac{\mu_0 I}{4\pi} \int_{L} \frac{\vec{dl} \times \hat{r}}{r^2}$$

$$\vec{B}(P) = \frac{\mu_0}{4\pi} \int_{L}^{\infty} \frac{\vec{K} \times \hat{r}}{r^2} ds$$

$$\vec{B}(P) = \frac{\mu_0}{4\pi} \int_{L} \frac{\vec{J} \times \hat{r}}{r^2} d\tau$$



### Magnetic field along the axis due to current carrying circular loop

$$\widehat{r} = -\widehat{\rho} + \widehat{k}$$

$$\overrightarrow{dl} = dl \widehat{\phi}$$

$$\overrightarrow{dl} \times \widehat{r} = dl(\widehat{k} + \widehat{\rho})$$

$$\vec{B}(P) = \frac{\mu_0 I}{4\pi} \int_{L} \frac{\vec{dl} \times \hat{r}}{r^2} = \hat{k} \frac{\mu_0 I}{4\pi} \frac{\cos \alpha}{r^2} \int_{L} dl$$

$$= \hat{k} \frac{\mu_0 I}{2} \frac{R^2}{r^3} = \hat{k} \frac{\mu_0 I}{2} \frac{R^2}{(R^2 + z^2)^{\frac{3}{2}}}$$

Magnetic field at the centre of the ring

$$\vec{B} = \hat{k} \frac{\mu_0 I}{2R}$$

Magnetic field due to current carrying wire (finite length)

$$\overrightarrow{dl} = dx \, \hat{i}$$

$$\widehat{r} = -\hat{i} + \hat{j}$$

$$\overrightarrow{B}(P) = \frac{\mu_0 I}{4\pi} \int_L \frac{\overrightarrow{dl} \times \widehat{r}}{r^2} = \widehat{k} \frac{\mu_0 I}{4\pi} \int_L \frac{dx}{x^2 + d^2}$$

$$\overrightarrow{B}(P) = \widehat{k} \frac{\mu_0 I}{4\pi d} \int_{\alpha_1} \cos \alpha \, d\alpha = \widehat{k} \frac{\mu_0 I}{4\pi d} (\sin \alpha_2 - \sin \alpha_1)$$

For an infinite wire,

$$\alpha_2 = \frac{\pi}{2}$$
,  $\alpha_1 = -\frac{\pi}{2}$   $\vec{B}(P) = \hat{k} \frac{\mu_0 I}{2\pi d}$  direction : right hand thumb rule

$$\overrightarrow{B} = \widehat{\phi} \; \frac{\mu_0 \; I}{2\pi d}$$
, IF  $I = I \, \widehat{k}$  Take  $\oint \overrightarrow{B} \cdot \overrightarrow{dl}$  along a circular loop of radius r



$$\overrightarrow{B} = \widehat{\phi} \; \frac{\mu_0 \; I}{2\pi d}$$
, IF  $I = I \, \widehat{k}$  Take  $\oint \overrightarrow{B} \cdot \overrightarrow{dl}$  along a circular loop of radius r 
$$\oint \overrightarrow{B} \cdot \overrightarrow{dl} = \oint \frac{\mu_0 \; I}{2\pi r} \; \widehat{\phi} \cdot dl \, \widehat{\phi} = \frac{\mu_0 \; I}{2\pi r} \; 2\pi r = \mu_0 \; I$$



### Need not be a circular loop as long as the loop goes around the current

$$\oint \vec{B} \cdot \vec{dl} = \oint \frac{\mu_0 I}{2\pi r} \hat{\phi} \cdot (dr \hat{r} + r d\phi \hat{\phi} + dz \hat{z})$$

$$= \frac{\mu_0 I}{2\pi} 2\pi = \mu_0 I_{\text{encl}}$$

$$\oint (\vec{\nabla} \times \vec{B}) \cdot \vec{dS} = \mu_0 \iint \vec{J} \cdot \vec{dS} \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J}$$

What about other current configurations?

$$\vec{\nabla} \times \vec{B} = \vec{\nabla} \times \frac{\mu_0}{4\pi} \int_{\tau} \frac{\vec{J} \times \hat{r}}{r^2} d\tau = \frac{\mu_0}{4\pi} \int_{\tau} \vec{\nabla} \times \left( \vec{J} \times \frac{\hat{r}}{r^2} \right) d\tau$$

$$B = B(x, y, z) \qquad J = J(x', y', z')$$

$$d\tau = dx'dy'dz'$$

field

point

point

$$\vec{r} = (x - x')\hat{\imath} + (y - y')\hat{\jmath} + (z - z')\hat{k}$$

$$\vec{\nabla} \times \left( \vec{j} \times \frac{\hat{r}}{r^2} \right) = \vec{j} \left( \vec{\nabla} \cdot \frac{\hat{r}}{r^2} \right) - \left( \vec{j} \cdot \vec{\nabla} \right) \frac{\hat{r}}{r^2}$$

$$4\pi \delta^3(r)$$

$$\vec{\nabla} \times \vec{B} = \frac{\mu_0}{4\pi} \int_{\tau} J(r') 4\pi \delta^3(r - r') d\tau = \mu_0 J(r)$$

$$\vec{\nabla} \cdot \left( \vec{J} \times \frac{\hat{r}}{r^2} \right) = \frac{\hat{r}}{r^2} \cdot (\vec{\nabla} \times \vec{J}) - \vec{J} \cdot \left( \vec{\nabla} \times \frac{\hat{r}}{r^2} \right) \vec{\nabla} \cdot \vec{B} = 0$$

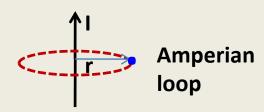
Magnetic field at a distance r from the current carrying wire (infinite length)

$$\vec{\nabla} \times \vec{B} = \mu_0 \vec{J} \qquad \qquad \oint \vec{B} \cdot \vec{dl} = \mu_0 \; I_{\text{encl}}$$

$$\overrightarrow{B} = B\widehat{\phi}, \ \overrightarrow{dl} = dl\widehat{\phi}$$

$$\oint \overrightarrow{B} \cdot \overrightarrow{dl} = B \oint dl = B 2\pi r = \mu_0 I_{\text{encl}}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$



### **Symmetries involved:**

Straight line currents

Cylinder

Plane sheets

Solenoids and torroids

A current carrying wire with current density J = Cr

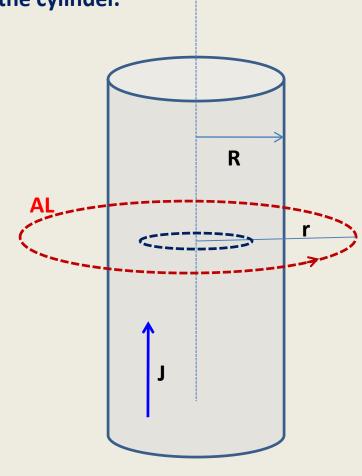
$$\oint \overrightarrow{B} \cdot \overrightarrow{dl} = B \oint dl = B 2\pi r = \mu_0 I_{\text{encl}}$$

$$I = \int \vec{J} \cdot \hat{n} \, dS = \int_{0}^{R} Cr \left( r dr d\theta \right) = \frac{2\pi CR^{3}}{3}$$

$$B \ 2\pi r = \mu_0 \frac{2\pi C R^3}{3} \qquad \overrightarrow{B}_{\text{out}} = \frac{\mu_0 C R^3}{3r} \widehat{\phi}$$

$$B_{\rm in} 2\pi r = \mu_0 \frac{2\pi C r^3}{3} \qquad \overrightarrow{B}_{\rm in} = \frac{\mu_0 C r^2}{3} \widehat{\phi}$$

C: constant, r: radial distance from the axis of the cylinder.



**Sheet current (surface current)** 

$$\vec{B}(P) = \frac{\mu_0}{4\pi} \int\limits_{L} \frac{\vec{K} \times \hat{r}}{r^2}$$

$$\hat{\mathscr{T}} = -\hat{\imath} - \hat{\jmath} + \hat{k}$$

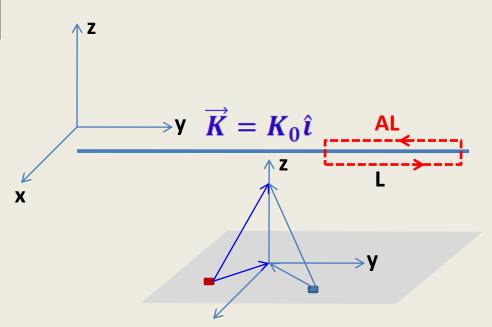
$$\vec{K} \times \hat{r} = K_0 \hat{\imath} \times (-\hat{\imath} - \hat{\jmath} + \hat{k}) = K_0 (-\hat{k} - \hat{\jmath})$$

$$\hat{\mathcal{C}} = -\hat{\imath} + \hat{\jmath} + \hat{k}$$

$$\vec{K} \times \hat{\mathcal{C}} = K_0 \hat{\imath} \times (-\hat{\imath} + \hat{\jmath} + \hat{k}) = K_0 (+\hat{k} - \hat{\jmath})$$

$$\oint \vec{B} \cdot \vec{dl} = B_{\text{above}} L + B_{\text{below}} L = \mu_0 K_0 L \qquad B_{\text{above}} = B_{\text{below}} = B$$

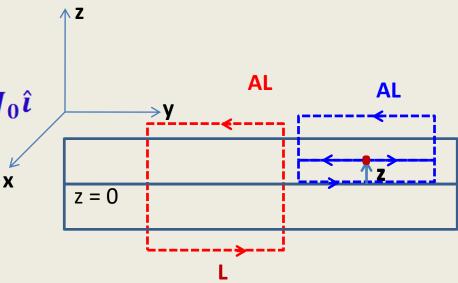
$$B_{\text{above}} = \frac{\mu_0 K_0}{2} (-\hat{j}) \qquad B_{\text{below}} = \frac{\mu_0 K_0}{2} (+\hat{j})$$



current carrying slab, thickness 2d

$$\vec{J} = J_0 \hat{\iota}$$

- **B**-outside is constant;
- -y direction above and
- +y direction below



$$\oint \overrightarrow{B} \cdot \overrightarrow{dl} = B \ 2L = \mu_0 J_0(2dL)$$

$$B_{\text{above}} = \mu_0 J_0 d(-\hat{j})$$
  $B_{\text{below}} = \mu_0 J_0 d(+\hat{j})$ 

From symmetry, on z = 0 plane, B = 0.

-y direction above z = 0 and +y direction below z = 0

$$B_{\text{above}}L - BL = \mu_0 J_0 (d - z)L$$

$$\mu_0 J_0 d + \mathbf{B} = \mu_0 J_0 (d - \mathbf{z})$$

$$B = \mu_0 J_0 z$$

# Magnetic vector potential

#### **Electrostatics**

$$\overrightarrow{\nabla} \times \overrightarrow{E} = \mathbf{0} \quad \Rightarrow \quad \overrightarrow{E} = -\overrightarrow{\nabla} \mathbf{V}$$
 scalar potential V

#### **Magnetostatics**

$$\overrightarrow{\nabla} \times \overrightarrow{B} \neq 0 \implies \overrightarrow{B} \neq -\overrightarrow{\nabla}$$
? NO scalar potential

However,

$$\vec{\nabla} \cdot \vec{B} = 0 \implies \vec{B} = \vec{\nabla} \times \vec{A}$$
 vector called Magnetic Vector Potential

Not as useful as **V**, since **A** is also a vector

However, much more useful quantity than B itself in em theory

$$\overrightarrow{\nabla} \times \overrightarrow{B} = \overrightarrow{\nabla} \times \overrightarrow{\nabla} \times \overrightarrow{A} = \overrightarrow{\nabla} (\overrightarrow{\nabla} \cdot \overrightarrow{A}) - \nabla^2 \overrightarrow{A} = \mu_0 J$$

To define  $\overrightarrow{A}$  completely, we need to define  $\overrightarrow{\nabla} \cdot \overrightarrow{A}$  also

## For magnetostatics, we take $\vec{\nabla} \cdot \vec{A} = 0$ without affecting **B**: Coloumb gauge

In electrodynamics, Lorenz gauge,  $\vec{\nabla} \cdot \vec{A} = -\mu_0 \varepsilon_0 \frac{\partial V}{\partial t}$ 

$$\nabla^2 \vec{A} = -\mu_0 J$$
 three equations!

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{\tau} \frac{\vec{J}d\tau}{r}$$

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{S} \frac{\vec{K}dS}{r} \qquad \vec{A} = \frac{\mu_0 I}{4\pi} \oint_{S} \frac{\vec{dl}}{r}$$

Non – uniqueness of  $\overline{A}$ 

Adding a scalar constant to A does not affect B

Assume vector potentials A and A' gives same B

$$\vec{\nabla} \times \vec{A} = \vec{B} = \vec{\nabla} \times \vec{A}'$$

$$\vec{\nabla} \times (\vec{A}' - \vec{A}) = 0 \implies \vec{A}' - \vec{A} = \vec{\nabla} \lambda$$

$$\vec{A}' = \vec{A} + \vec{\nabla} \lambda$$

 $\nabla^2 V = -\frac{\rho}{\varepsilon_0} \Rightarrow V = \frac{1}{4\pi\varepsilon_0} \int \frac{\rho d\tau}{r}$ 

Eg: 
$$\overrightarrow{B} = B_0 \widehat{k}$$

$$B_{x} = 0 \Rightarrow \frac{\partial A_{z}}{\partial y} = \frac{\partial A_{y}}{\partial z}$$

$$B_{y} = 0 \Rightarrow \frac{\partial A_{x}}{\partial z} = \frac{\partial A_{z}}{\partial x}$$

$$B_{z} = B_{0} \Rightarrow \frac{\partial A_{y}}{\partial x} - \frac{\partial A_{x}}{\partial y} = B_{0}$$

$$\vec{\nabla} \times \vec{A} = \begin{vmatrix} \hat{\mathbf{i}} & \hat{\mathbf{j}} & \hat{\mathbf{k}} \\ \frac{\partial}{\partial \mathbf{x}} & \frac{\partial}{\partial \mathbf{y}} & \frac{\partial}{\partial \mathbf{y}} \\ A_{\mathbf{x}} & A_{\mathbf{y}} & A_{\mathbf{z}} \end{vmatrix}$$

#### **Solutions**

$$A_z = 0,$$
  $A_y = 0,$   $A_x = -B_0 y$   
 $A_z = 0,$   $A_x = 0,$   $A_y = B_0 x$   
 $A_z = 0,$   $A_y = \frac{1}{2}B_0 x,$   $A_x = -\frac{1}{2}B_0 y$ 

OR a linear combination of these solutions!

Even though A is not unique, as long the two conditions are satisfied,

$$\overrightarrow{
abla} imes \overrightarrow{A} = \overrightarrow{B}$$
 $\overrightarrow{
abla} \cdot \overrightarrow{A} = \mathbf{0}$  we

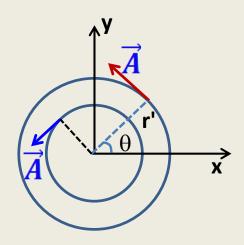
we can make use of the solution

**Consider the solution** 

Az = 0, 
$$A_y = \frac{1}{2}B_0x$$
,  $A_x = -\frac{1}{2}B_0y$ 

$$\vec{A} = (-\hat{\imath})\frac{1}{2}B_0y + (\hat{\jmath})\frac{1}{2}B_0x$$

$$= \frac{1}{2}B_0r'(\sin\theta\,(-\hat{\imath}) + \cos\theta\,(\hat{\jmath}))$$



$$|\overrightarrow{A}| = \frac{1}{2} r' B_0$$
 AND  $A \perp r' \Rightarrow \overrightarrow{A} = \frac{1}{2} \overrightarrow{B} \times \overrightarrow{r'}$ 

IF 
$$\vec{B} = B_0 \hat{k}$$
, THEN  $\vec{A} = A_0 \hat{\phi}$  A rotates about the z-axis

We can make use of this situation. If **B** is uniform along a particular direction, then **A** circulates around that direction

$$\oint \vec{A} \cdot \vec{dl} = \int_{S} (\vec{\nabla} \times \vec{A}) \cdot \vec{dS} = \int_{S} \vec{B} \cdot \vec{dS} = \Phi \qquad \text{Ampere's law for vector potential}$$

If B is uniform along a particular direction, circulation of A around a closed loop = flux of B enclosed by the loop

$$A 2\pi r' = B_0 \pi r'^2 \Rightarrow A = \frac{1}{2}B_0 r'$$

### Vector potential for a long solenoid

#### Magnetic field inside and outside

$$B_1L - B_2L = 0 \Rightarrow B_1 = B_2$$
  
 $r \to \infty, B = 0 \Rightarrow B_1 = B_2 = 0$ 

$$B_{\rm out} = 0$$

$$BL = \mu_0 NIL \Rightarrow B = \mu_0 NI$$

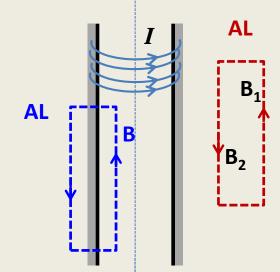
$$B_{in} = constant$$

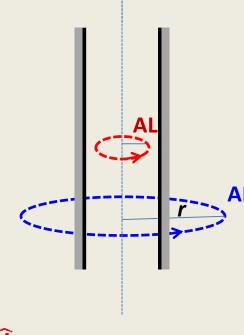
### **Vector potential**

$$\oint \vec{A} \cdot \vec{dl} = \Phi \qquad A \ 2\pi r = B \ \pi r^2 = \mu_0 NI \ \pi r^2$$

$$\Rightarrow \vec{A}_{in} = \frac{1}{2} \mu_0 NI r \hat{\phi}$$

$$A \ 2\pi r = \mu_0 NI \ \pi R^2$$





$$\vec{A}_{\rm in} = \frac{1}{2} \mu_0 N I r \hat{\phi}$$

$$\vec{\nabla} \times \vec{A} = \frac{1}{r} \left( \frac{\partial}{\partial r} r A_{\phi} \right) \hat{k}$$

$$=\frac{1}{r}\left(\frac{\partial}{\partial r}r\frac{1}{2}\mu_0NIr\right)\widehat{k}=\mu_0NI\widehat{k}$$

$$\vec{\nabla} \cdot \vec{A} = 0$$

$$\vec{A}_{\text{out}} = \frac{\mu_0 NIR^2}{2r} \hat{\phi}$$

$$=\frac{1}{r}\left(\frac{\partial}{\partial r}r\frac{\mu_0NIR^2}{2r}\right)\widehat{k}=0$$

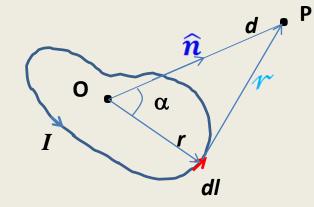
$$\overrightarrow{\nabla} \cdot \overrightarrow{A} = \mathbf{0}$$

### **Multipole expansion for Vector potential**

$$\frac{1}{r^{2}} = \frac{1}{\sqrt{r^{2} + d^{2} - 2dr\cos\alpha}}$$

$$= \frac{1}{d} + \frac{1}{d^{2}}r\cos\alpha + \frac{1}{d^{3}}r^{2}\left(\frac{3}{2}\cos^{2}\alpha - \frac{1}{2}\right)$$

$$+ \cdots$$



$$\vec{A} = \frac{\mu_0 I}{4\pi} \oint \frac{\vec{dl}}{r} = \frac{\mu_0 I}{4\pi} \left\{ \frac{1}{d} \oint \vec{dl} + \frac{1}{d^2} \oint r \cos \alpha \, \vec{dl} + \dots \right\}$$

$$\oint \overrightarrow{dl} = 0$$
 1st term (Monopole term) is ZERO

Dipole term 
$$\overrightarrow{A}_{\text{dipole}} = \frac{\mu_0 I}{4\pi d^2} \oint r \cos \alpha \, \overrightarrow{dl} = \frac{\mu_0 I}{4\pi d^2} \oint (\overrightarrow{r} \cdot \widehat{n}) \, \overrightarrow{dl}$$

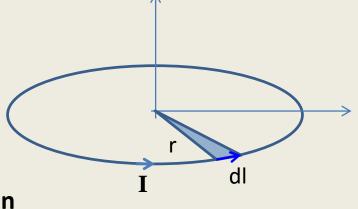
$$= \frac{\mu_0 I}{4\pi d^2} \left\{ -\frac{1}{2} \, \widehat{n} \times \oint \overrightarrow{r} \times \, \overrightarrow{dl} \right\} = \frac{\mu_0}{4\pi d^2} (\overrightarrow{m} \times \widehat{n})$$

#### Magnetic dipole moment

$$\overrightarrow{m} = \frac{I}{2} \oint \overrightarrow{r} \times \overrightarrow{dl}$$

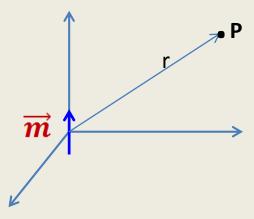
#### Special case for a plane loop

 $\frac{1}{2}(\vec{r} \times \vec{dl})$  becomes the area of the shaded portion



$$\overrightarrow{m} = \frac{I}{2} \oint \overrightarrow{r} \times \overrightarrow{dl} = I\overrightarrow{a}$$

Any plane current loop can be replaced by a magnetic moment  $\overrightarrow{m}$ 



$$\vec{A}_{\text{dipole}} = \frac{\mu_0}{4\pi d^2} (\vec{m} \times \hat{n}) = \frac{\mu_0 m \sin \theta}{4\pi r^2} \ \hat{\phi}$$

$$\vec{B} = \vec{\nabla} \times \vec{A} = \frac{\mu_0 m}{4\pi r^3} \{ 2\cos\theta \, \hat{r} + \sin\theta \, \hat{\theta} \}$$
$$= \frac{\mu_0}{4\pi r^3} \{ 3(\vec{m} \cdot \hat{r}) - \vec{m} \}$$

## Magnetic Dipole in a UNIFORM magnetic field

Replace the magnetic dipole by a square current loop in the *x-y* plane

$$\overrightarrow{m} = Ia^2 \widehat{k}$$

Let 
$$\vec{B} = B_0(\cos\theta \hat{k} + \sin\theta \hat{j})$$

Force experienced by side (1)

$$\vec{F}_1 = I \int \vec{dl} \times \vec{B} = IB_0 \int dx \left\{ \hat{\imath} \times \left( \cos \theta \, \hat{k} + \sin \theta \, \hat{\jmath} \right) \right\}$$
$$= IB_0 a \left( \cos \theta \, (-\hat{\jmath}) + \sin \theta \, \hat{k} \right)$$

Force experienced by side (2)

$$\vec{F}_2 = IB_0 a(\cos\theta \ (\hat{\imath}))$$

### F<sub>1</sub> produces a Torque

$$\vec{\tau} = \vec{r} \times \vec{F} = (Ia^2)B_0 \sin \theta (-\hat{\iota})$$
$$= \vec{m} \times \vec{B}$$

If a magnetic dipole is kept in a uniform magnetic field, it experiences a torque, resulting in a ROTATION to align along the field

What happens if a material is kept in a magnetic field?

Material becomes magnetized; tiny magnetic dipoles are created which align along some direction

M = magnetic dipole moment per unit volume

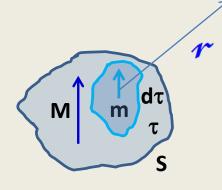
Magnetic field produced by a "Magnetized object"

Vector potential due to a single dipole m

$$\frac{d\vec{A}_{\text{dipole}}}{4\pi} = \frac{\mu_0}{4\pi} \frac{(\vec{m} \times \hat{r})}{r^2} \qquad d\vec{A} = \frac{\mu_0}{4\pi} \frac{(\vec{M} \times \hat{r})}{r^2} d\tau$$

$$\overrightarrow{A} = \frac{\mu_0}{4\pi} \int_{\tau} \frac{(\overrightarrow{M} \times \widehat{r})}{r^2} d\tau$$

$$\overrightarrow{A} = \frac{\mu_0}{4\pi} \int_{\tau} \overrightarrow{M} \times \overrightarrow{\nabla} \left(\frac{1}{r}\right) d\tau$$
(differentiation is w.r.t. source coordinates)



$$\overrightarrow{\nabla}\left(\frac{1}{r}\right) = \frac{\widehat{r}}{r^2}$$

$$\overrightarrow{A} = \frac{\mu_0}{4\pi} \int_{\tau} \overrightarrow{M} \times \overrightarrow{\nabla} \left(\frac{1}{r}\right) d\tau$$

$$\overrightarrow{A} = \frac{\mu_0}{4\pi} \left\{ \int_{\tau} \frac{1}{r} (\overrightarrow{\nabla} \times \overrightarrow{M}) d\tau - \int_{\tau} \overrightarrow{\nabla} \times \left(\frac{1}{r} \overrightarrow{M}\right) d\tau \right\}$$
Problem 1.61(b) in Griffiths
$$\overrightarrow{A} = \frac{\mu_0}{4\pi} \left\{ \int_{\tau} \frac{1}{r} (\overrightarrow{\nabla} \times \overrightarrow{M}) d\tau + \oint_{S} \frac{1}{r} (\overrightarrow{M} \times \overrightarrow{dS}) \right\}$$

 $\overrightarrow{\nabla} \times \overrightarrow{M} = \overrightarrow{I}_{h}$ 

$$\vec{A} = \frac{\mu_0}{4\pi} \int_{\tau} \frac{\vec{J}_b}{r} d\tau + \frac{\mu_0}{4\pi} \int_{S} \frac{\vec{K}_b}{r} dS$$

 $\overrightarrow{M} \times \widehat{n} = \overrightarrow{K}_h$ 

$$\int_{\tau} (\vec{\nabla} \times \vec{v}) d\tau = -\oint_{S} (\vec{v} \times \vec{dS})$$

#### **Bound currents**

volume current density  $J_b$ 

Surface current density  $K_h$ 

$$oldsymbol{
ho}_b = -\overrightarrow{
abla} \cdot \overrightarrow{P}$$
 $oldsymbol{\sigma}_b = \overrightarrow{P} \cdot \widehat{n}$