# PH108: Electricity and Magnetism: Division 1

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 Suggested Textbook: Introduction to Electrodynamics, by D. J. Griffiths



# Syllabus

- Review of vector calculus: Spherical polar and cylindrical coordinates; gradient, divergence and curl; Divergence and Stokes' theorems; Divergence and curl of electric field
- Electric potential, properties of conductors; Poisson's and Laplace's equations, uniqueness theorems, boundary value problems, separation of variables, method of images, multipole expansion
- Polarization and bound charges, Gauss' law in the presence of dielectrics, Electric displacement D and boundary conditions, linear dielectrics

# Syllabus Continued

- Divergence and curl of magnetic field, Vector potential and its applications; Magnetization, bound currents, Ampere's law in magnetic materials, Magnetic field H, boundary conditions, classification of magnetic materials; Faraday's law in integral and differential forms, Motional emf, Energy in magnetic fields, Displacement current, Maxwell's equations.
- Electromagnetic (EM) waves in vacuum and media, Energy and momentum of EM waves, Poynting's theorem; Reflection and transmission of EM waves across linear media.

# Coordinate Systems in Two and Three Dimensions

#### Outline

- Coordinate systems in 2-dimensions: Cartesian and plane polar coordinate systems and their relationship. Length and area elements
- 2 Coordinate systems in 3-dimensions: Cylindrical and Spherical Polar Coordinate systems, line, surface and volume elements

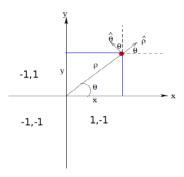
# **Objectives**

- To learn to use symmetry adapted coordinate systems
- To understand as to how to construct line, surface, and volume elements for various coordinate systems

# Using Symmetries in Physics

- Using a coordinate system which is consistent with the symmetry of the physical system simplifies calculations
- If a planar system has circular symmetry, use of plane-polar coordinate system will simplify calculations
- For systems with cylindrical symmetry, use of cylindrical polar coordinates is advised
- Likewise for spherical systems, use of spherical polar coordinate system will be beneficial

# Coordinate Systems in Two Dimensions



#### Cartesian Coordinates:

- Location of a point in a flat plane is given by coordinates (x,y).
- Differential line element **dl** is given by  $\mathbf{dl} = dx\hat{i} + dy\hat{j}$



#### 2D Coordinates Continued

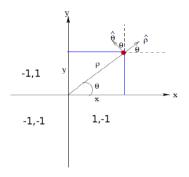
- A general vector is given by  $\mathbf{A} = A_x \hat{i} + A_y \hat{j}$ .
- Infinitesimal area element  ${\bf dS}_{12}$  in a plane described by orthogonal coordinates 1 and 2 can be computed for any coordinate system as

$$\mathsf{dS}_{12} = \mathsf{dI}_1 \times \mathsf{dI}_2 \tag{1}$$

For Cartesian coordinates it yields

$$dS = dx\hat{i} \times dy\hat{j} = dxdy\hat{k}$$
 or  $dS = dxdy$ 

#### 2D Coordinates...



#### Plane Polar Coordinates:

- Location of a point in a flat plane is given by coordinates  $(\rho, \theta)$ .
- Differential line element **dl** is given by  $\mathbf{dl} = d\rho \hat{\rho} + \rho d\theta \hat{\theta}$
- Infinitesimal surface area is  $d\mathbf{S} = d\rho\hat{\rho} \times \rho d\theta\hat{\theta} = \rho d\rho d\theta\hat{k}$ , or  $dS = \rho d\rho d\theta$

# Relationship between Cartesian and Plane Polar Coordinates

- $x = \rho \cos \theta$ ,  $y = \rho \sin \theta$
- $\rho = \sqrt{x^2 + y^2}$ ,  $\theta = \tan^{-1}\left(\frac{y}{x}\right)$ , where  $-\infty \le x, y \le \infty$ ;  $0 \le \rho \le \infty$ ,  $0 \le \theta \le 2\pi$ .
- And unit vectors are related as  $\hat{\rho} = \cos\theta \hat{i} + \sin\theta \hat{j}$ , and  $\hat{\theta} = -\sin\theta \hat{i} + \cos\theta \hat{j}$
- $\hat{i} = \cos\theta \hat{\rho} \sin\theta \hat{\theta}$ ,  $\hat{j} = \sin\theta \hat{\rho} + \cos\theta \hat{\theta}$
- Using these relations, one can easily transform vectors expressed in one coordinate system, into the other one.
- ullet Area of a circle of radius R,  $A=\int_0^R 
  ho\,d
  ho\int_0^{2\pi}d heta=\pi R^2$



### Coordinate Systems in Three Dimensions

#### Cartesian Coordinates:

- Location of a point is is given by coordinates (x, y, z).
- Differential line element **dl** is given by  $\mathbf{dl} = dx\hat{i} + dy\hat{j} + dz\hat{k}$
- Infinitesimal area element depends upon the plane. For xy plane it will be

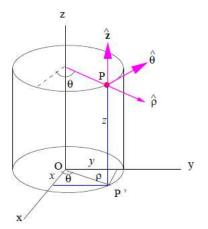
$$\mathsf{dS}_{xy} = dxdy\,\hat{k}$$

 Infinitesimal volume element for any orthogonal 3D coordinate system is given by

$$dV = dl_1 dl_2 dl_3$$
 for this case  $dV = dx dy dz$ 

# Cylindrical Coordinates:

ullet Location of a point specified by three coordinates (
ho, heta, z)

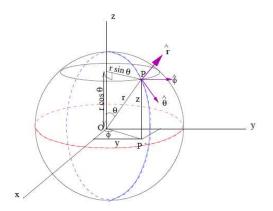


# 3D Coordinate System....

- Relationship with Cartesian coordinates  $x = \rho \cos \theta$ ,  $y = \rho \sin \theta$ , z = z
- Inverse relationship  $ho=\sqrt{x^2+y^2}$ ,  $heta= an^{-1}\left(rac{y}{x}
  ight)$ , z=z
- Differential line element **dl** is given by  $\mathbf{dl} = d\rho \hat{\rho} + \rho d\theta \hat{\theta} + dz \hat{k}$
- Area element in different planes can be obtained using the relation  $d\mathbf{S}_{12} = d\mathbf{I}_1 \times d\mathbf{I}_2$
- Volume element  $dV = dl_1 dl_2 dl_3 = \rho d\rho d\theta dz$
- Volume of a cylinder of height L, and radius R  $V = \int_{\rho=0}^{R} \rho \, d\rho \int_{z=0}^{L} dz \int_{\theta=0}^{2\pi} d\theta = \pi R^2 L$

# **Spherical Polar Coordinates:**

• Location of a point is specified by three coordinates  $(r, \theta, \phi)$ , as shown below



• What is the range of r,  $\theta$ , and  $\phi$ ?



#### 3D Coordinates...

- Clearly  $0 \le r \le \infty$ ,  $0 \le \theta \le \pi$ ,  $0 \le \phi \le 2\pi$
- Relationship with Cartesian coordinates  $x = r \sin \theta \cos \phi$ ,  $y = r \sin \theta \sin \phi$ ,  $z = r \cos \theta$
- Inverse relationship

$$r = \sqrt{x^2 + y^2 + z^2}$$

$$\theta = \tan^{-1} \left( \frac{\sqrt{x^2 + y^2}}{z} \right)$$

$$\phi = \tan^{-1} \frac{y}{x}$$

- Differential line element **dl** is given by  $\mathbf{dl} = dr\hat{r} + rd\theta\hat{\theta} + r\sin\theta d\phi\hat{\phi}$
- $m{\bullet}$  Cross products given by  $\hat{m{ heta}} imes\hat{m{\phi}}=\hat{m{r}}$ ,  $\hat{m{\phi}} imes\hat{m{r}}=\hat{m{ heta}}$ , and  $\hat{m{r}} imes\hat{m{ heta}}=\hat{m{\phi}}$



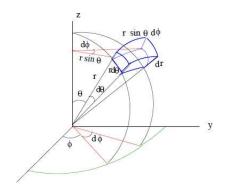
# Spherical Polar Coordinates...

Relationship between Cartesian and Spherical unit vectors

$$\begin{split} \hat{r} &= \sin\theta\cos\phi\,\hat{i} + \sin\theta\sin\phi\,\hat{j} + \cos\theta\,\hat{k} \\ \hat{\theta} &= \cos\theta\cos\phi\,\hat{i} + \cos\theta\sin\phi\,\hat{j} - \sin\theta\,\hat{k} \\ \hat{\phi} &= -\sin\phi\,\hat{i} + \cos\phi\,\hat{j} \end{split}$$

- Area element on the surface of a sphere or radius R,  $\mathbf{dS}_{\theta\phi} = \mathbf{dI}_{\theta} \times \mathbf{dI}_{\phi} = Rd\theta \hat{\theta} \times R \sin\theta d\phi \hat{\phi} = R^2 \sin\theta d\theta d\phi \hat{r}$
- Area of the surface of a sphere  $A = R^2 \int_0^{\pi} \sin \theta d\theta \int_0^{2\pi} d\phi = 4\pi R^2$

# Spherical Polar Coordinates...



- Elementary volume element  $dV = dI_r dI_\theta dI_\phi = drrd\theta r \sin\theta d\phi = r^2 \sin\theta drd\theta d\phi$
- Volume of a sphere of radius R

$$V = \int_0^R r^2 dr \int_0^\pi \sin\theta d\theta \int_0^{2\pi} d\phi = \frac{4}{3}\pi R^3$$