

1. Basics of Group Theory: (for non-mathematics majors)

Group G : A set with an operation \circ satisfying:

- closure: $g, h \in G \Rightarrow g \circ h \in G$

- Associativity: $(g \circ h) \circ k = g \circ (h \circ k) = g$

- identity: There exists $e \in G$

$$\text{s.t. } e \circ g = g \circ e = g$$

- Inverses: for all $g \in G$, there exists

$$g^{-1} \in G \text{ with } g \circ g^{-1} = e$$

- Group Action on a set:

$$X: G \times X \rightarrow X \quad (g, x) \mapsto g \cdot x \text{ satisfying}$$

- $e \cdot x = x$

- $(g \circ h) \cdot x = g \cdot (h \cdot x)$

2. Equivariance and invariance:

- A function $f: X \rightarrow Y$ is equivariant w.r.t group G if for all $g \in G$

$$f(g \cdot x) = P_g(g) f(x)$$

where P_g is a representation of G on output space Y .

- invariance is a special case where

$$P_g(g) = \text{id} \text{ so}$$

$$f(g \cdot x) = f(x)$$

3. Group Equivariant CNNs :

Traditional CNNs are translationally equivariant,



shifting the input to a network, the output will also shift in the same direction and by the same amount.

equivariance
mapping

↳ preserves the algebraic structure of transformation.

Suppose the existence of new neural network layer given as an operator ϕ on images / feature maps f and it has the following properties.

↳ linear $\phi(\alpha f + \beta f') = \alpha \phi(f) + \beta \phi(f')$

↳ shift-equivariant $\phi(m, n S(f)) = m, n S(\phi(f))$

↳ impulse response h (not a constraint)

when operator is applied to a Dirac impulse δ, δ_p centered at the origin $(0, 0)$:

$$h = \phi(\delta, \delta_p)$$

Expressing the image as a linear combination of Dirac impulses p at different locations.

$$[\phi(f)](x, y) = \left[\phi \sum_{m=-M/2}^{M/2} \sum_{n=-N/2}^{N/2} f(m, n) m, n p \right](x, y)$$

This was an essence for showing how traditional CNNs are translationally equivariant.

Coming Back to (g-CNNs)

[Traditional CNNs : $[L_x f](x) = f(x-t)$]

$$(f * \psi)(x) = \int f(y) \psi(x-y) dy$$

satisfies:

$$L_t(f * \psi) = (L_t f) * \psi$$

Group Convolution

generalizes this for group G :

$$[F * \psi](g) = \int_G F(h) \psi(g^{-1}h) d\mu(h)$$

$d\mu$ is the Haar measure of G

discrete groups (like rotations / reflections), the integral is replaced by \sum (trivial)

• lie group Equivariant networks

lie groups \rightarrow continuous groups with smooth manifold structure.

group convolution uses the Haar measure on the lie group

$$[f * \psi](g) = \int_G f(h) \psi(g^{-1}h) d\mu(h)$$

$f(g) \rightarrow$ infinite dimensional (spherical harmonics)

$\psi \rightarrow$ steerable filter

$$\psi(g, x) = f(g) \psi(x)$$

lie algebra \mathfrak{g} is the tangent space at identity
(used to parametrize infinitesimal transformations)

5. Gauge Equivariant CNNs :

Gauge symmetry \rightarrow local symmetry
group transformations vary smoothly over a manifold M .

Data f is a section of fiber bundle over M
with fibers carrying a representation of group G .

(#) Gauge Transformation

$g(x)$ acts locally on fibers

$$f(x) \mapsto g(x) f(x)$$

Convolution must be modified with a gauge
~~conv~~ connection A to parallel transport filters

$$[f * \psi](x) = \int_M g(U_{x \leftarrow y}) f(y) \psi(d(x, y)) dy$$

$U_{x \leftarrow y}$: parallel transport operator along a path
($y \rightarrow x$)

$$[g(y(x)) f] * \psi = g(y(x)) [f * \psi]$$

* Terminologies I used :

Haar Measure = Locally compact topological group is a
[Translation invariant] Borel measure invariant under translations,
for Borel sets finite on compact sets.

fiber = set of all possible values on "states" attached
to a point in space (or manifold)

fiber bundle theory

Base space : M

fiber : a space F

Total space (E) all combinations (x, v) $x \in M$ $v \in F$

Projection : $\pi : E \rightarrow M$