

# Combining Mechanistic Models and Experimentation to Drive Pharmaceutical Innovation

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# Do We Need Mechanistic Models?



*"I can never satisfy myself until I can make a mechanical model of a thing. If I can make a mechanical model, I can understand it. As long as I cannot make a mechanical model all the way through I cannot understand."*

- Lord Kelvin

From a speech Kelvin presented at Johns Hopkins University in Baltimore on 'Molecular Dynamics and the Wave Theory of Light' (1884)

# How we Benefit from Models

- Mechanistic Understanding of a Process
  - Finding the CPPs
  - Sensitivity analysis
  - Guide for experimentation – risk reduction
- Scale-up and scale-down
  - Regime analysis
  - Scale-independence of design space
- Control
- Process optimization
- Scheduling

# What are the Steps?

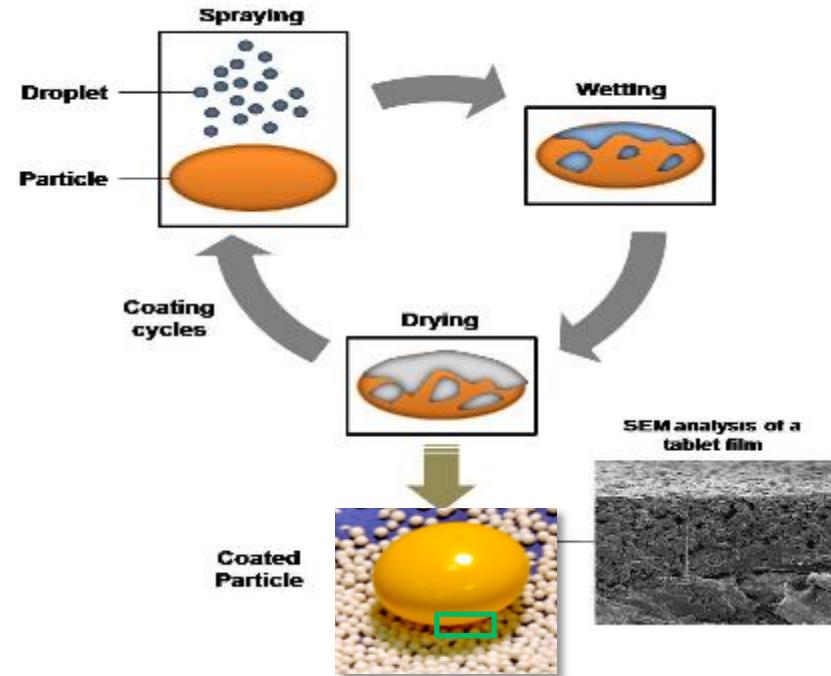
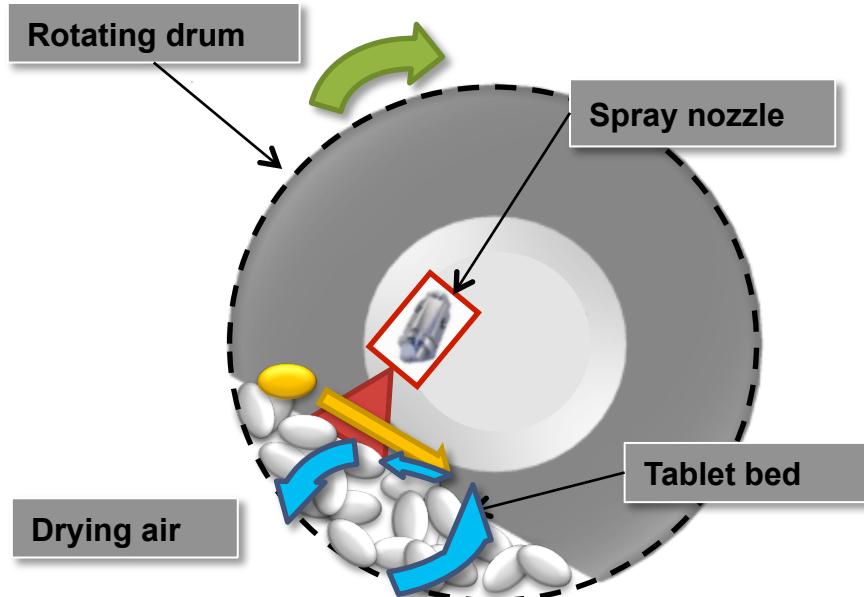
Critical steps model development:

- Aim & structure (cause-effect)
- Model formulation
- Model validation
- Model reduction
- Model life cycle

## A Few Examples

### Coating/Fluid Beds/Control

# Example 1- Tablet Coating



## Goal

- Application of a thin film around the tablet core
- Mostly, aqueous coating is used, producing polymer-based films

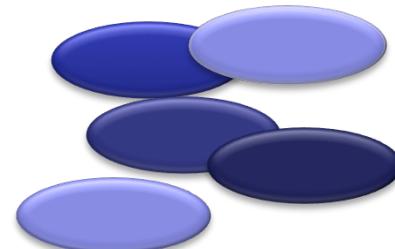
# Aim: Understanding the CQAs

- The central CQAs are coating **thickness** and **variability**:
  - *Intra-tablet*: coating thickness variation on one tablet
  - *Inter-tablet*: differences between the tablets

*Intra-tablet*



*Inter-tablet*



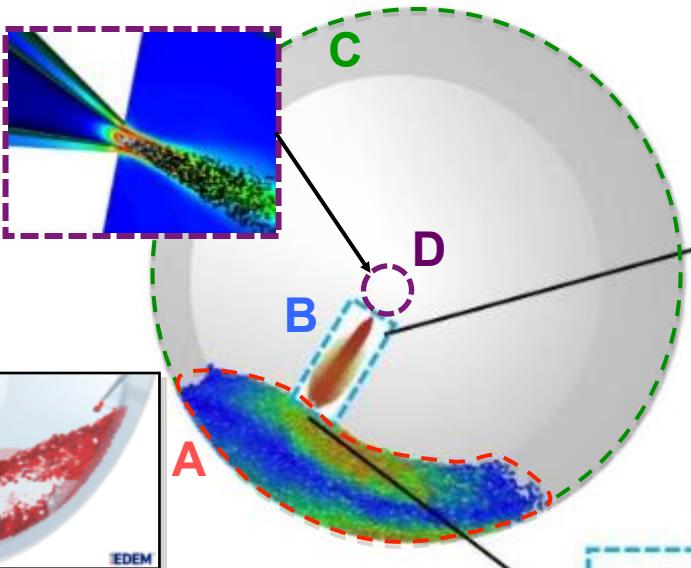
- Other CQAs are lack of
  - orange peeling
  - sticking / picking
  - bridging / filling etc.



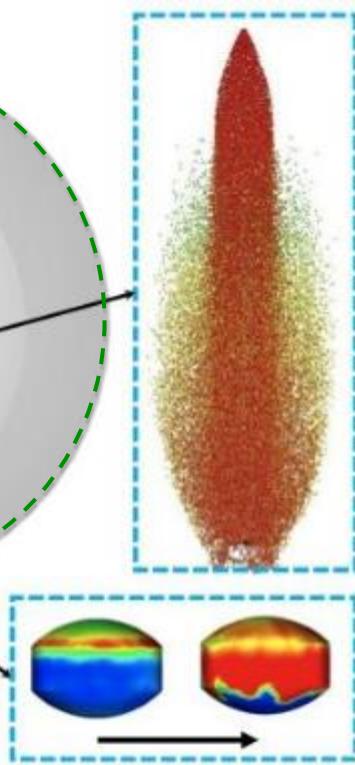
# Model Structure

## ■ Coating Effects

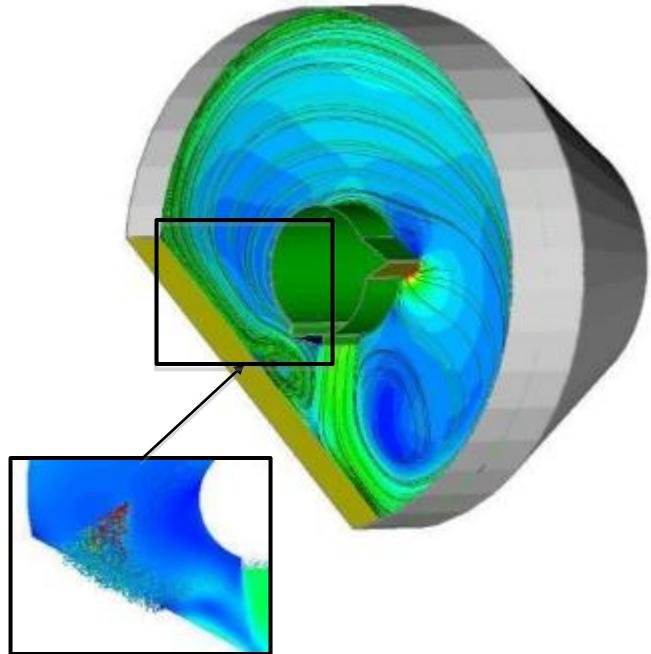
**B.** Spray Gun Simulation (CFD)



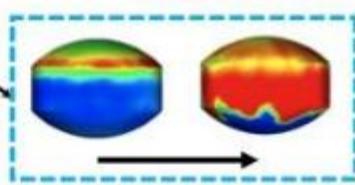
**C.** Detailed Spray/Tablet Simulation (CFD)



**D.** Coater Flow Simulation (CFD)



**A.** Tablet Mixing Simulation (DEM)



# Model Formulation: DEM Code

main equations solved in DEM

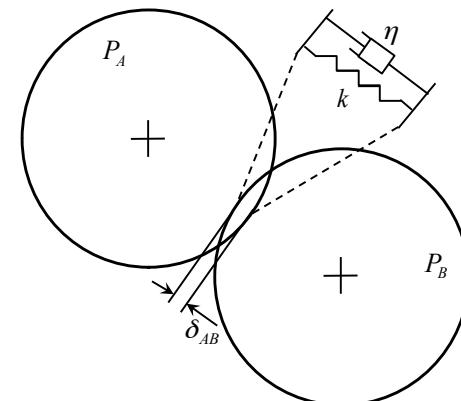
## DEM – running on GPU

- Newton's second law for each particle (particle interacting forces)

$$m_p \frac{d\mathbf{u}_p}{dt} = \beta(\mathbf{u}_f - \mathbf{u}_p) + \sum_{N_p} \mathbf{F}_{p \rightarrow p} + \sum_{N_w} \mathbf{F}_{p \rightarrow w} + m_p \mathbf{g}$$

- Rotation of the particles, angular momentum

$$I_p \frac{d\boldsymbol{\omega}_p}{dt} = \sum_{N_p} \mathbf{M}_p$$



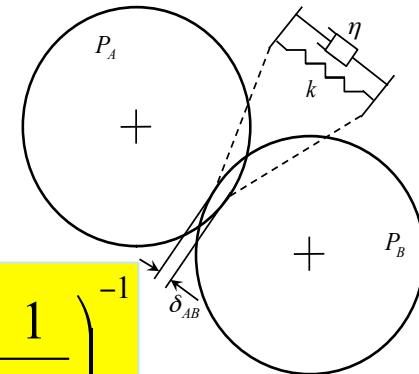
# DEM Basics

how forces between particles/walls are calculated

- Normal particle-particle and particle-wall interactions

$$\mathbf{F}_{p_A \rightarrow p_B} = [k\delta_{AB} - \eta(\mathbf{u}_A - \mathbf{u}_B) \cdot \mathbf{n}] \cdot \mathbf{n}$$

$$\eta = -2 \ln(e_{n,p \rightarrow p}) \frac{\sqrt{m_{AB} k}}{\sqrt{\pi^2 + (\ln(e_{n,p \rightarrow p}))^2}}, \quad \text{with} \quad m_{AB} = \left( \frac{1}{m_A} + \frac{1}{m_B} \right)^{-1}$$



Normal forces and  
tangential component/  
forces  
Interaction forces

- Tangential component via Coulomb-type friction law

$$\mathbf{F}_{p_A \rightarrow p_B,t} = \begin{cases} -k_t \boldsymbol{\delta}_t - \eta_t \mathbf{u}_{AB,t} \\ -\mu_{fr,p \rightarrow p} |\mathbf{F}_{p_A \rightarrow p_B,n}| \mathbf{t}_{AB} \end{cases}$$

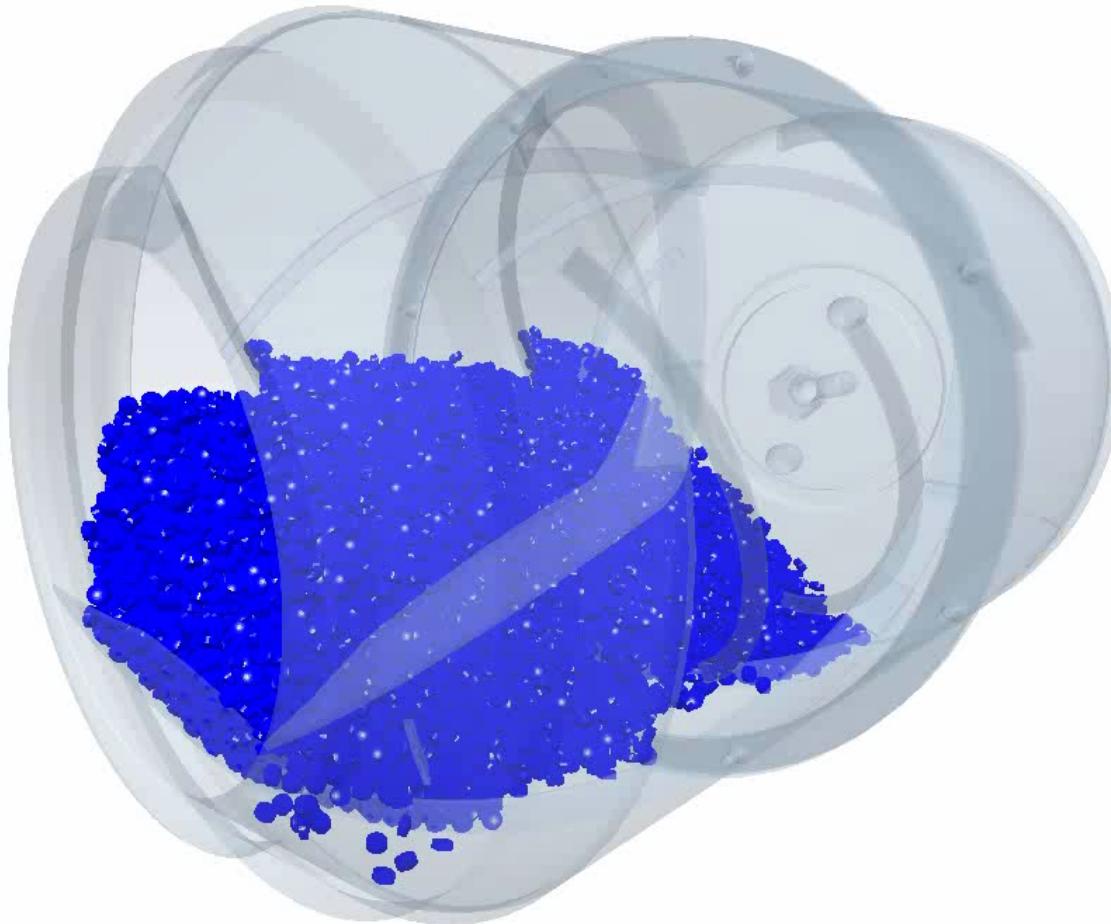
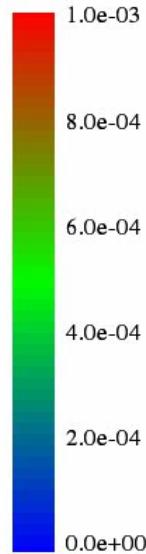
$$\begin{aligned} &\text{if } |\mathbf{F}_{p_A \rightarrow p_B,t}| \leq |\mathbf{F}_{p_A \rightarrow p_B,n}| \\ &\text{if } |\mathbf{F}_{p_A \rightarrow p_B,t}| > |\mathbf{F}_{p_A \rightarrow p_B,n}| \end{aligned}$$

$$\eta_t = -2 \ln(e_{t,p \rightarrow p}) \frac{\sqrt{\frac{2}{7} m_{AB} k_t}}{\sqrt{\pi^2 + (\ln(e_{t,p \rightarrow p}))^2}}$$

$k$  - spring stiffness  
 $\eta$  - damping parameter  
 subscript  $t$  referring to tangential component

# Coater Simulation Including Spray

Coating Mass (kg)



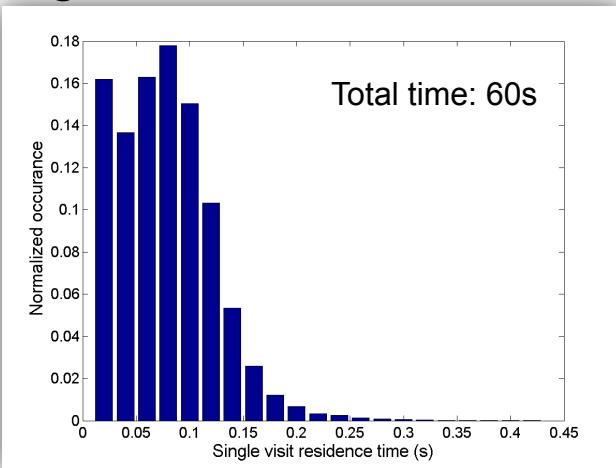
## Simulation data

- 14272 convex tablets
- each tablet from 8 spheres
- 10-20 rpm
- Spray rate: 2.4 mio. drops/sec
- Elliptical spray zone

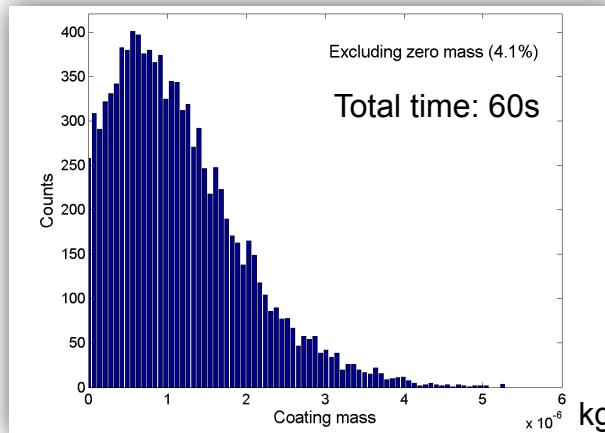
# Results: Coating Distribution

examples of outcome of simulation

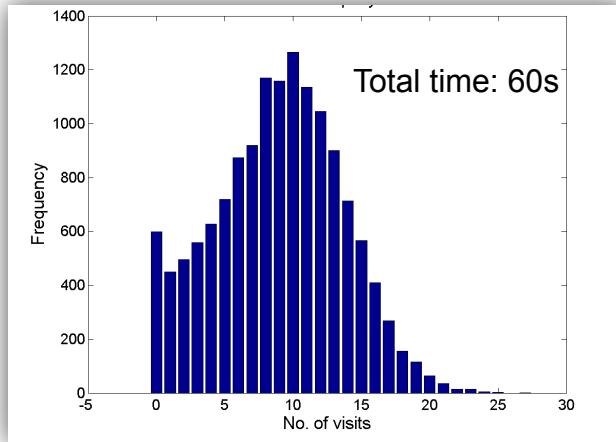
## Single visit residence time



## Coating mass distribution

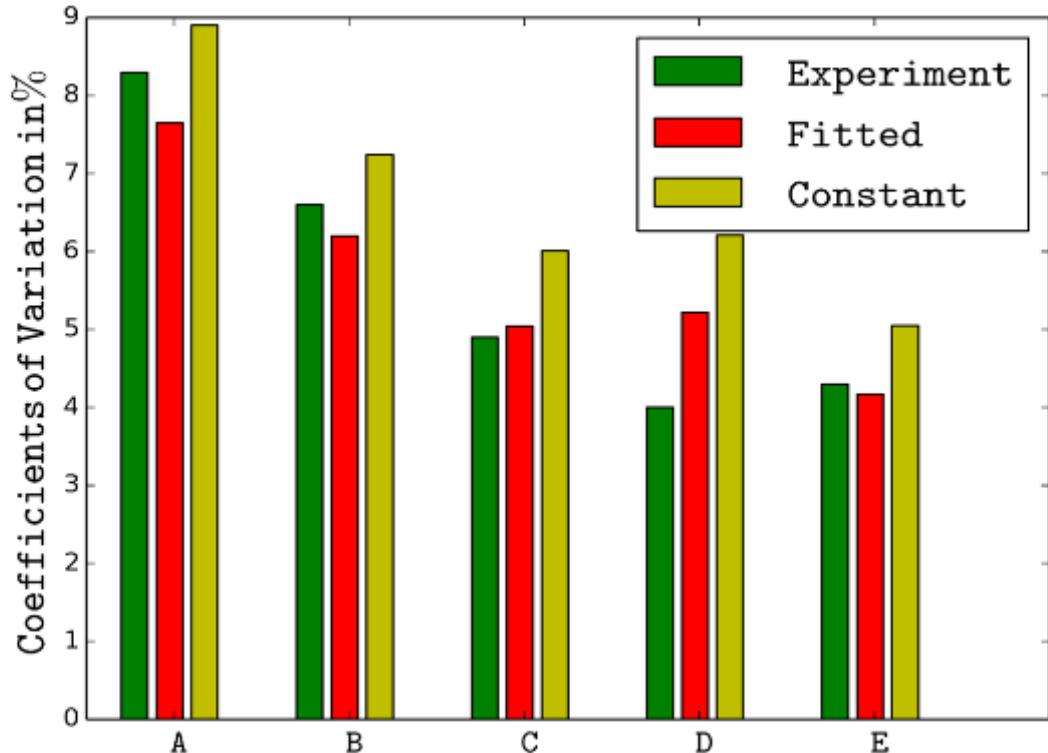


## Nr. of visits to the spray zone



- **Different layers of information** are available
  - Single visit residence time
  - Nr. of visits to the spray zone
  - Coating mass distribution
- From the coating mass distribution, the **Relative Standard Deviation (RSD)** is calculated to show the coating uniformity

# Model Validation 1

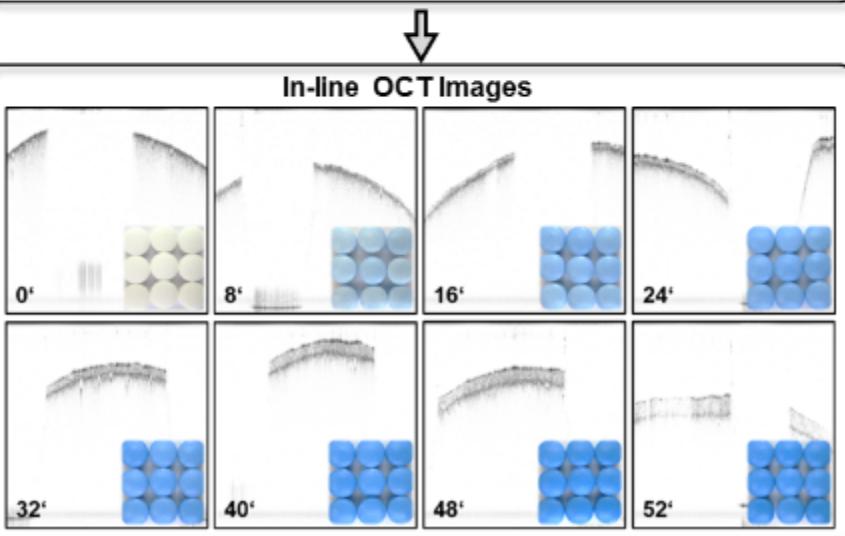
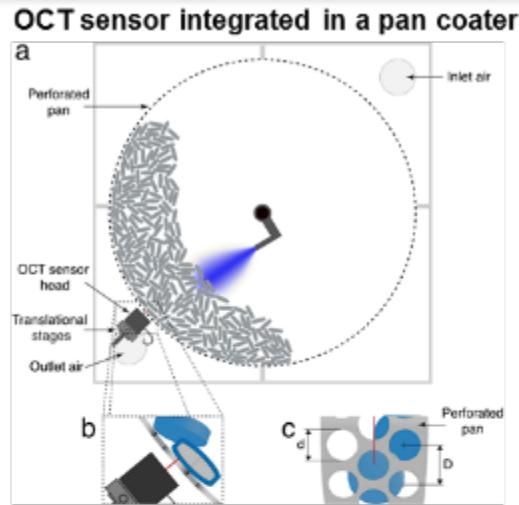


A: 260 kg 9 rpm 172 min  
B: 240 kg 9 rpm 248 min  
C: 250 kg 9 rpm 368 min  
D: 250 kg 9 rpm 345 min  
E: 250 kg 9 rpm 522 min

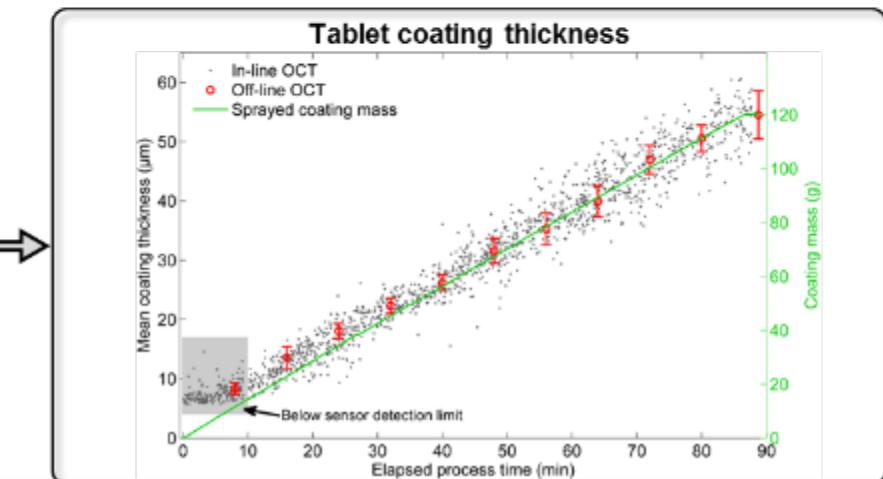
A,B,C etc variantions

- Experimental results (at Bayer) **match closely** the extrapolated results
- The calculated decay exponent matches the results very closely

# Model Validation II: Comparison to Coherence Tomography (OCT)

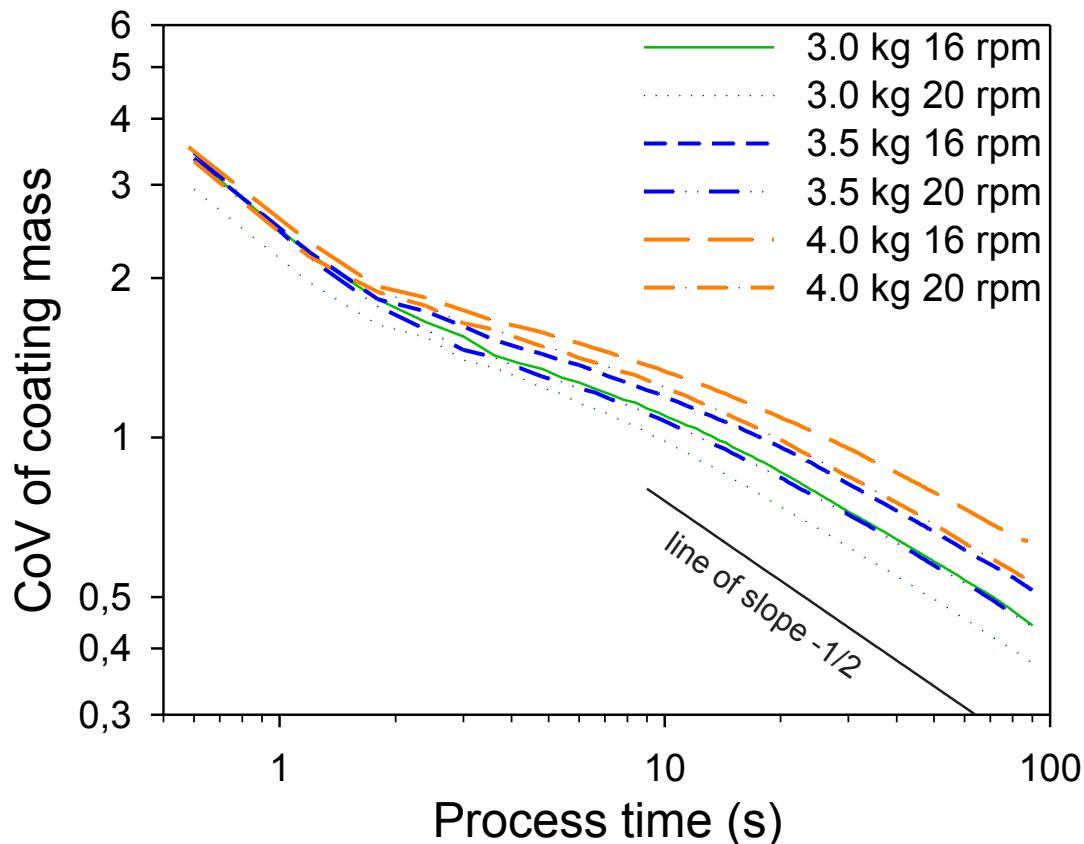


- **Real-time monitoring:**
  - Mean coating thickness of a single particle
  - Inter-particle coating variability
  - Intra-particle coating variability
  - Roughness analysis (core and coating)



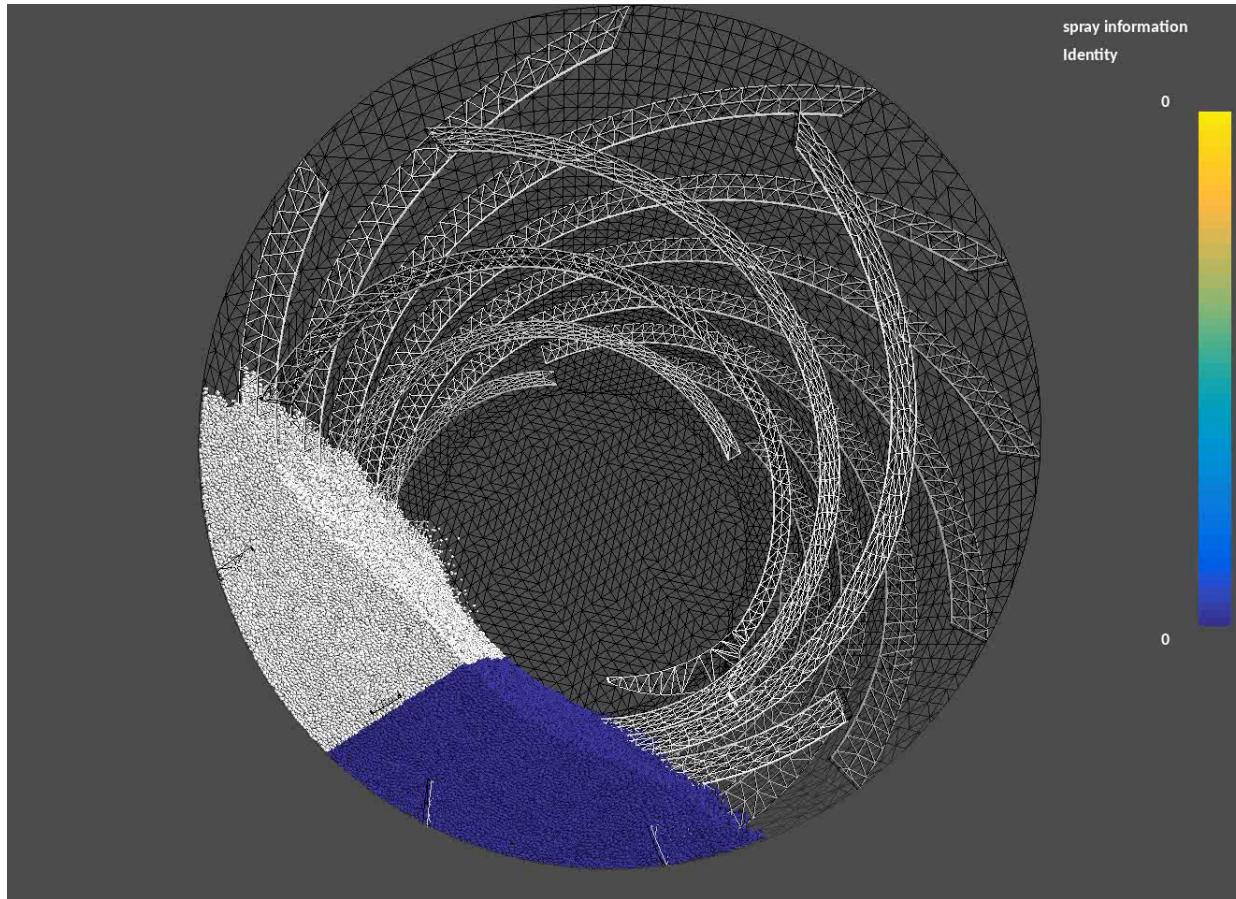
# Model Reduction: Prediction of COV (Extrapolation)

**Coefficient of Variation (COV) = RSD = Coating Variability**



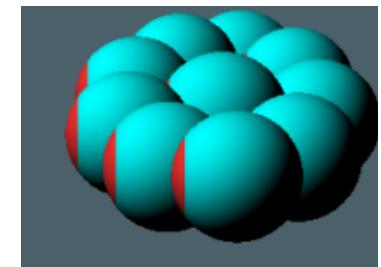
- Random mixing models predict a decrease inversely proportional to the square root of time (shown by the line of slope of  $-1/2$ )
- Here coating is slightly better
- Can be used to develop simplified model
- Simplified model predicts COV based on 90s of simulation

# Life Cycle 1: GPU Multisphere Approach

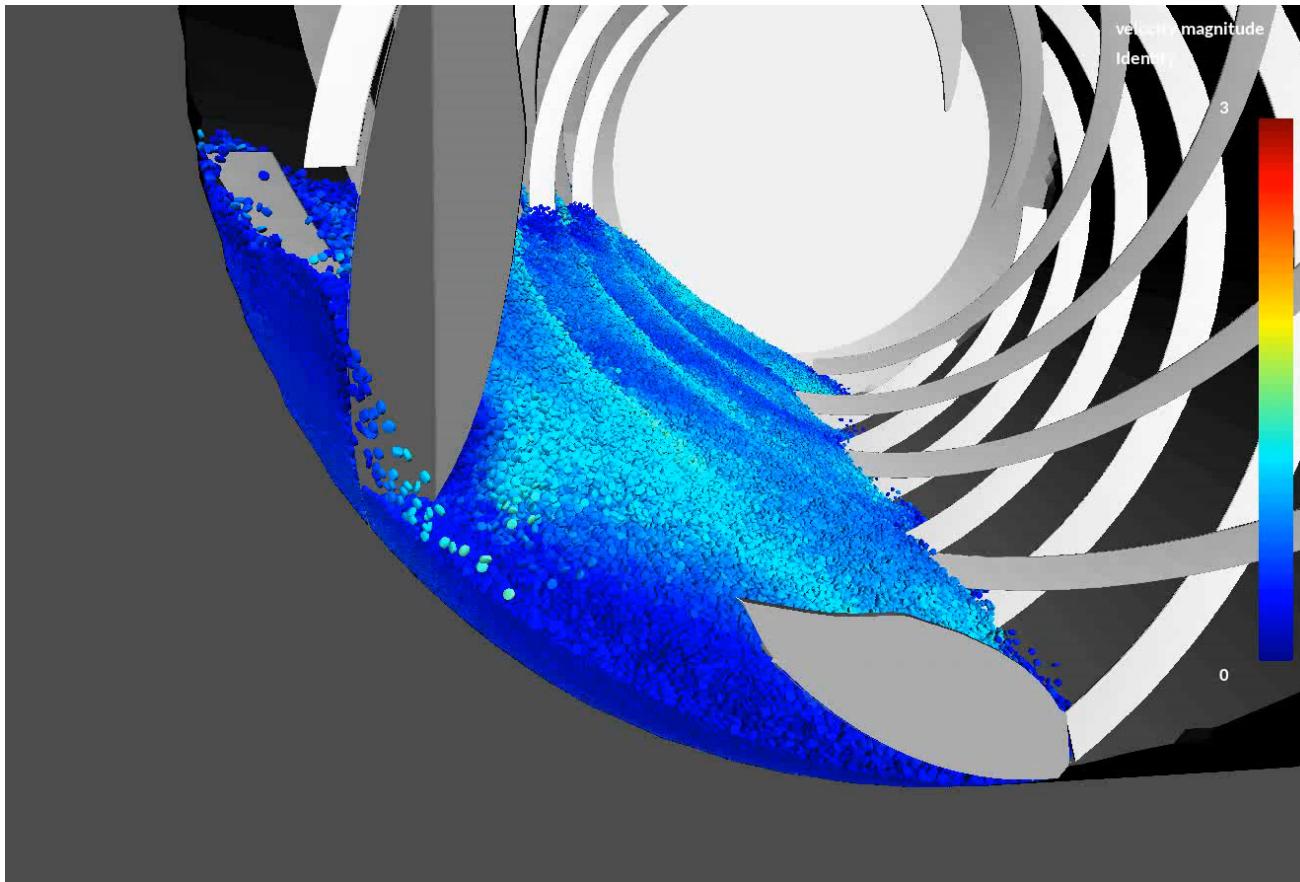


## Included:

- 1.4 million tablets
- 8 spheres/tablet
- 400 kg total mass
- 5 fan-shaped sprays
- Convective heat
- Conductive heat
- Spray cooling

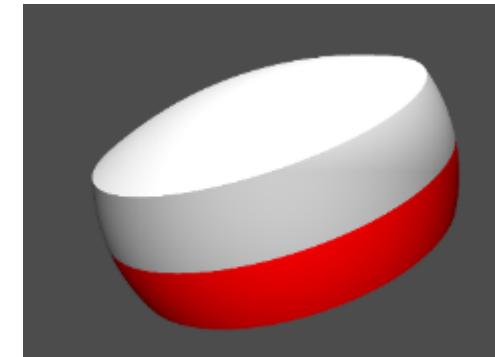


# Life Cycle 2: True-Shape DEM



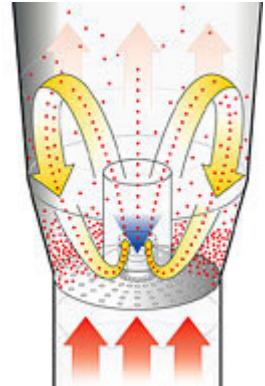
## Included:

- 1.8 Mio TS objects
- 500 kg total mass
- 5 fan-shaped sprays
- Convective heat
- Conductive heat
- Spray cooling



# Example 2: Fluidized Beds

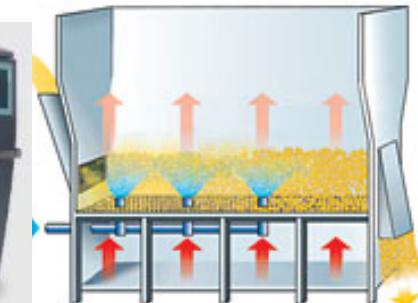
- Fluidized beds in the pharmaceutical industry are mainly used for **drying, agglomeration, pelletization and coating**
- In other industries:
  - Catalytic reactions (e.g., cracking, CFB).
  - Non-catalytic reactions (e.g., gasification, combustion)
  - Adsorption-desorption
- Aim: Understanding, scale-up, optimization, control



Glatt Wurster  
Coater



GEA Consigma



Glatt Continuous FB

# Structure/Formulation: CFD-DEM

## ■ Theoretical Background

### CFD code

#### CPU

##### Gas flow

$$\frac{\partial}{\partial t} (\varepsilon_f \rho_f) + \nabla \cdot (\varepsilon_f \rho_f \mathbf{u}_f) = 0$$

$$\frac{\partial}{\partial t} (\varepsilon_f \rho_f \mathbf{u}_f) + \nabla \cdot (\varepsilon_f \rho_f \mathbf{u}_f \mathbf{u}_f) = -\varepsilon_f \nabla p - \nabla \cdot (\varepsilon_f \tau_f) + \varepsilon_f \rho_f \mathbf{g} + \mathbf{S}_p$$

$\mathbf{S}_p \rightarrow$  Drag force source term

### DEM code

#### GPU

##### Particle motion

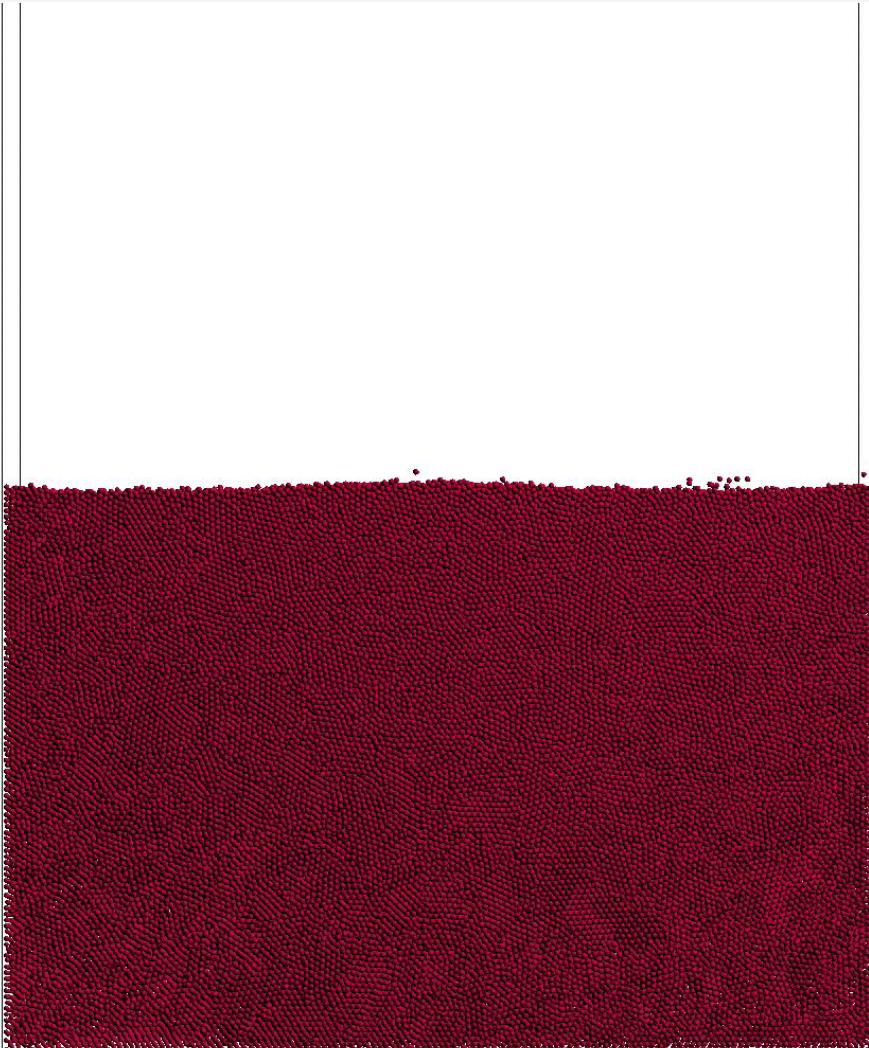
$$m_p \frac{d\mathbf{u}}{dt} = \beta \frac{V_p}{\varepsilon_p} (\mathbf{u}_f - \mathbf{u}_p) + m_p \mathbf{g} + \sum_{N_p} \mathbf{F}_{p \rightarrow p} + \sum_{N_p} \mathbf{F}_{p \rightarrow w}$$

$$I_p \frac{d\boldsymbol{\omega}_p}{dt} = \sum_{N_p} \mathbf{M}_p$$

- Solves Navier-Stokes equations in a multiphase setup
- Turbulence modeling via the k- $\zeta$ -f model
- Code is Fire (AVL)
- Coupling via drag force

- Spring-dashpot model (Hertz-Mindlin)
- Coulomb-friction (slider) is included
- Particle rotation may be turned off
- Coupling via drag force

# Example: Triple-spouted Bed

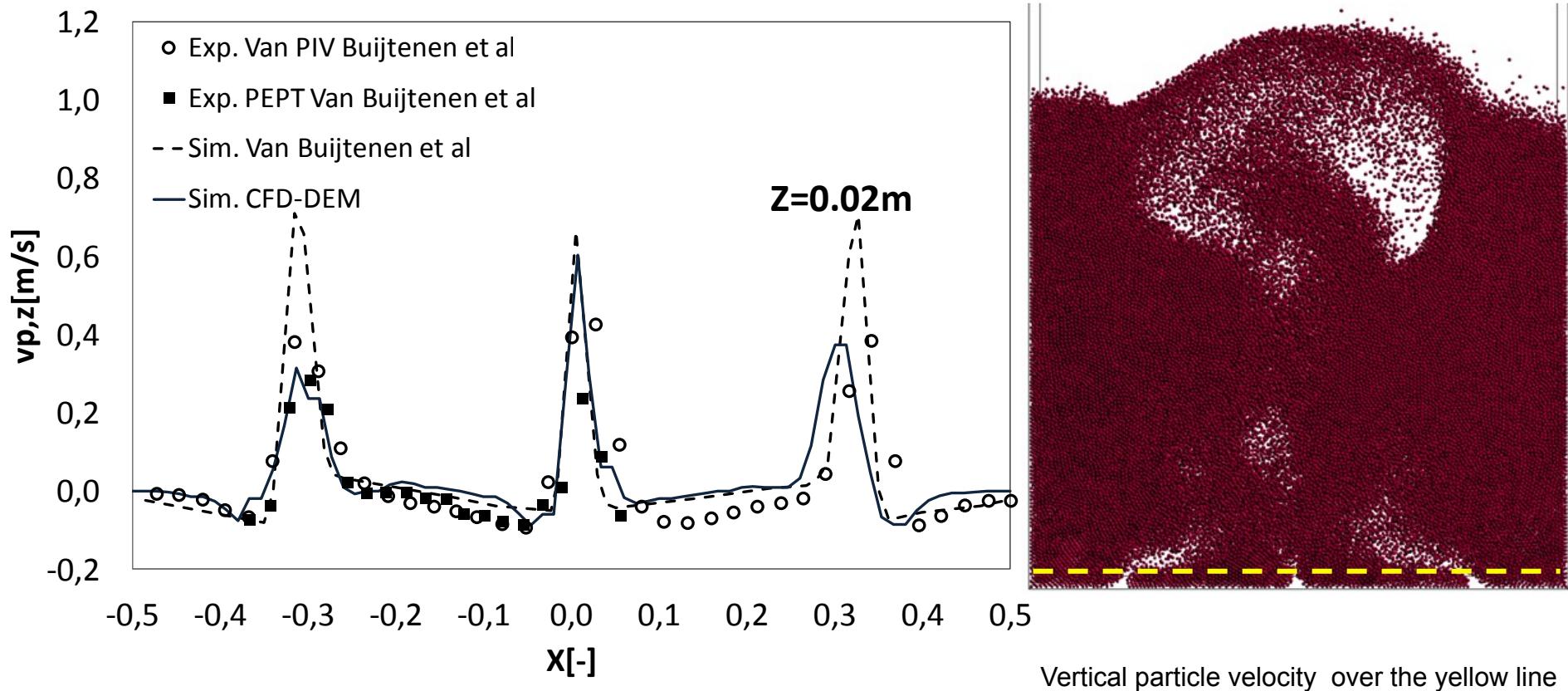


$$n_p = 100,000$$
$$d_p = 3\text{mm}$$

**Reference:** Jajcevic D., C. Radeke and J.G. Khinast, Large-scale simulation of fluidized beds, Chem. Eng. Sci (2013)

# Results and Validation

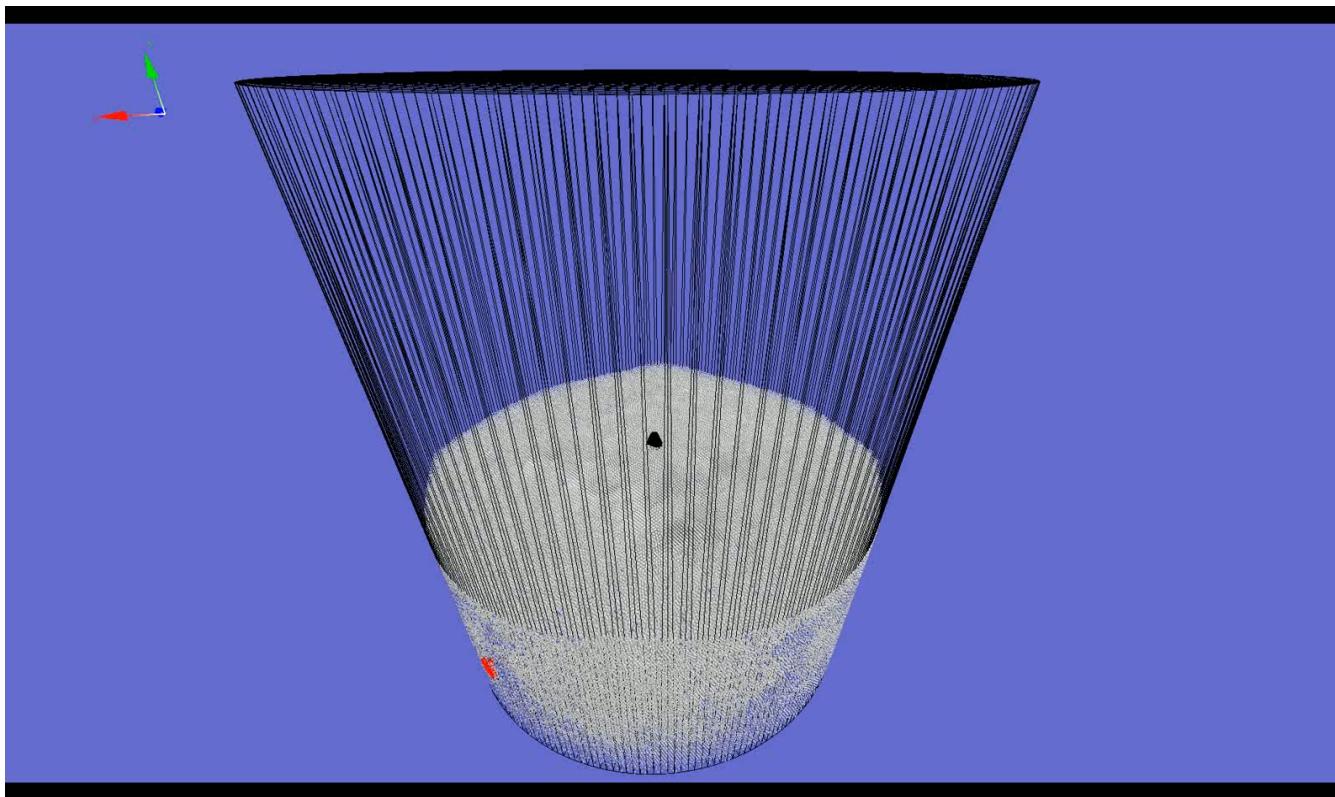
## ■ Validation – Triple Spout Fluidized Bed



Ref: "Numerical and experimental study on multiple-spout fluidized beds", Van Buijtenen et al., 2011

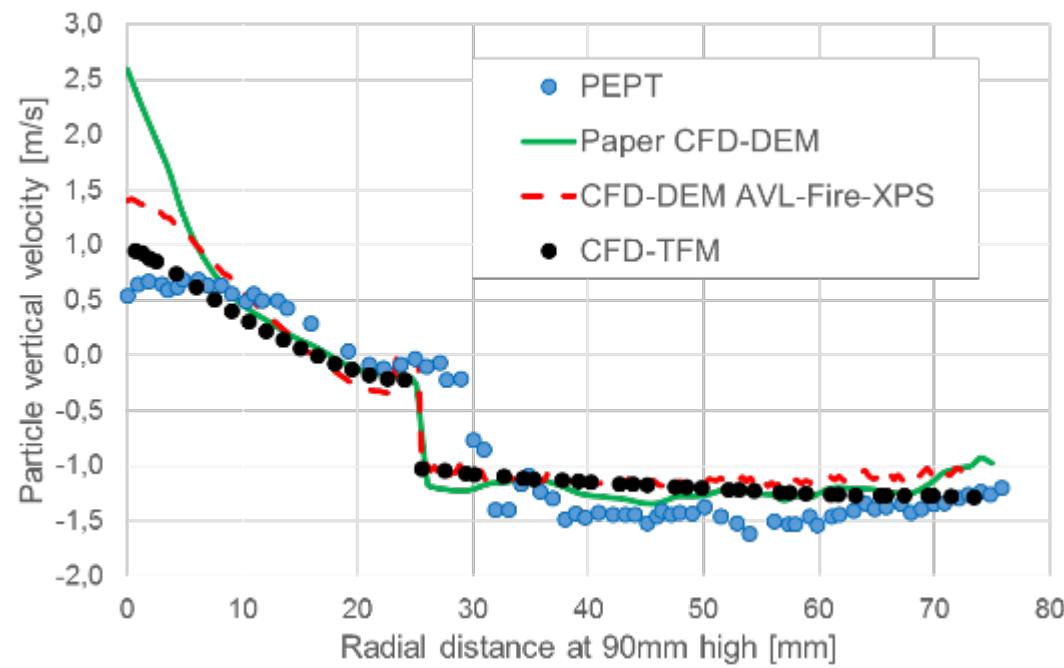
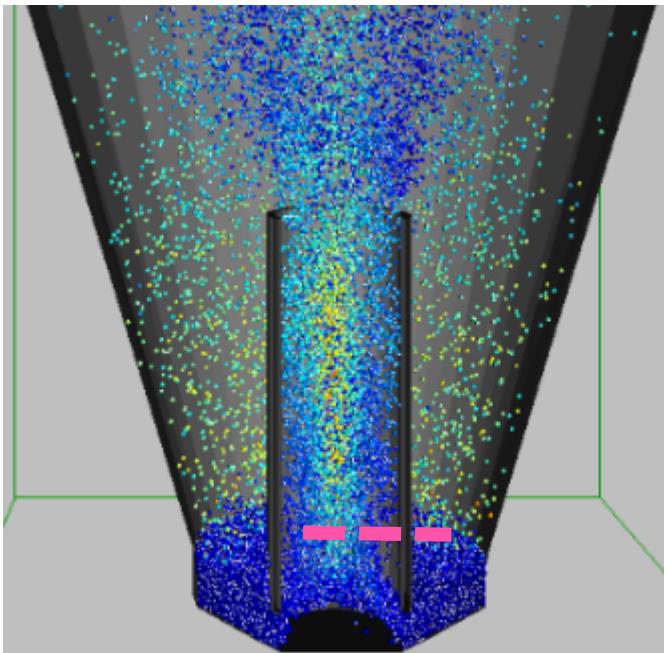
# Application: Fluidized Bed

- Fluidized bed system with two spray nozzles



$n_p = 7 \text{ million}$   
 $d_p = 1.6 \text{ mm}$   
 $\rho = 600 \text{ kg/m}^3$   
Air flow:  $1020 \text{ Nm}^3/\text{h}$

# Life Cycle: New Model based on CFD-TFM vs. CFD-DEM



# Example 3: Control



## Level 1 – Input Output

Considers the total Input/Outputs. The CQAs that are visible at the I/O level are the CQA's of the final product.



## Level 2 – Intermediate

Considers the interactions between the unit operations.



## Level 3 – Process Unit

Represents the process at the most detailed level.  
Separate considerations for every involved unit.

# Types of Controls

- **Open system:**
  - No active controls but may trigger external action
  - Needs clear rules of engagement with the process. (e.g., separation of non-conforming material and/or operator adjustment).
- **Feed back:**
  - Output information is used to automatically trigger upstream action
- **Feed forward:**
  - Input/output information used to automatically trigger control action
  - Need knowledge of process dynamics (i.e., a model) to automatically adjust process in order to compensate for the event. (e.g., run the press differently, if detected granule density is high).
  - MPC is advanced form of feed-forward control and is most suitable

# Types of Models

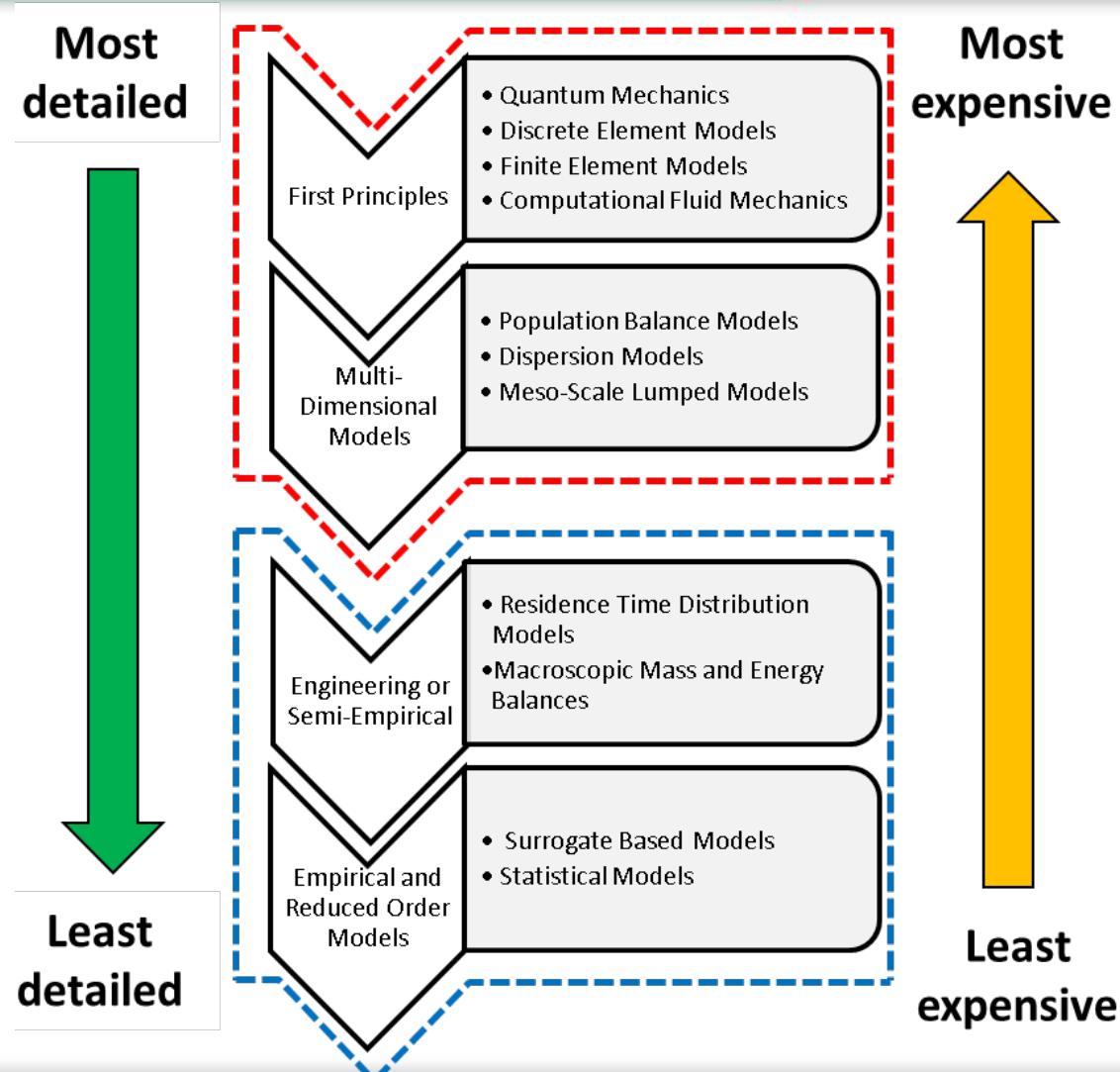


Figure courtesy Ierapetritou group at Rutgers University

# Model Simplification

## First principles



(granular & fluidized systems)



(extruders, melts, mixing)



(tableting, compaction)

Model  
simplification

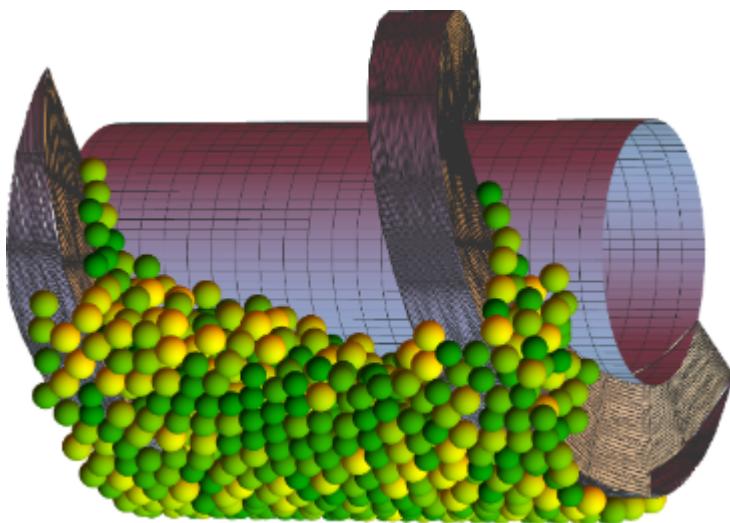
## Fast control models

- Fluid bed granulator
- Fluid bed dryer
- Fluid bed coater
- GEA coater
- Drum coaters
- Hot-melt extruder
- Wet extruder
- Tableting
- Blenders/hoppers/feeders

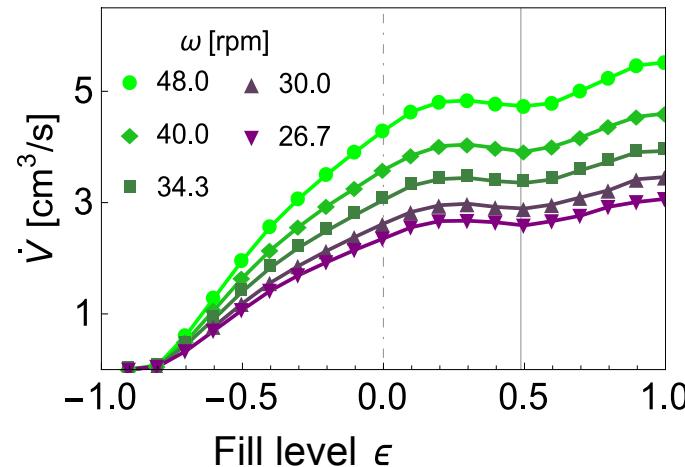


# DEM Model of a Screw Conveyer for Powder Feeding/Mixing

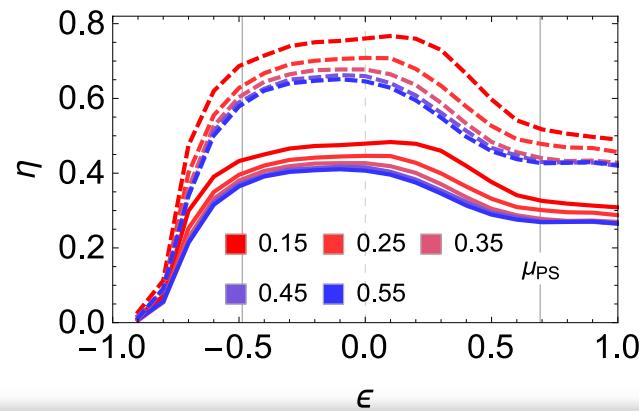
**DEM simulation of powder  
transport in screw**



**Throughput:**



**Feeding Efficiency:**



# RTD Model of a Screw Conveyer for Powder Feeding/Mixing

**Model:** Fokker-Planck Equation (FPE):

$$\partial C / \partial \theta + \partial C / \partial \xi = 1/P_e \partial^2 C / \partial \xi^2$$

**Solution:**

$$C(\xi, \theta) = C_0 P_e^{1/2} / (4\pi\theta)^{1/2} e^{-P_e(\xi-\theta)/4\theta}$$

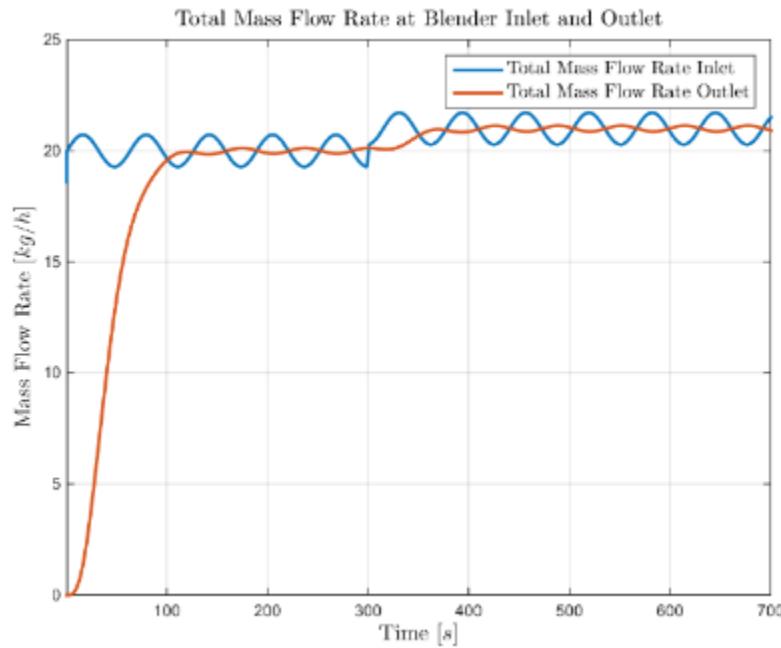
$$\theta = t - t_0 / \tau, \quad \xi = z / l$$

$\theta$  and  $\xi$  are dimensionless time and space

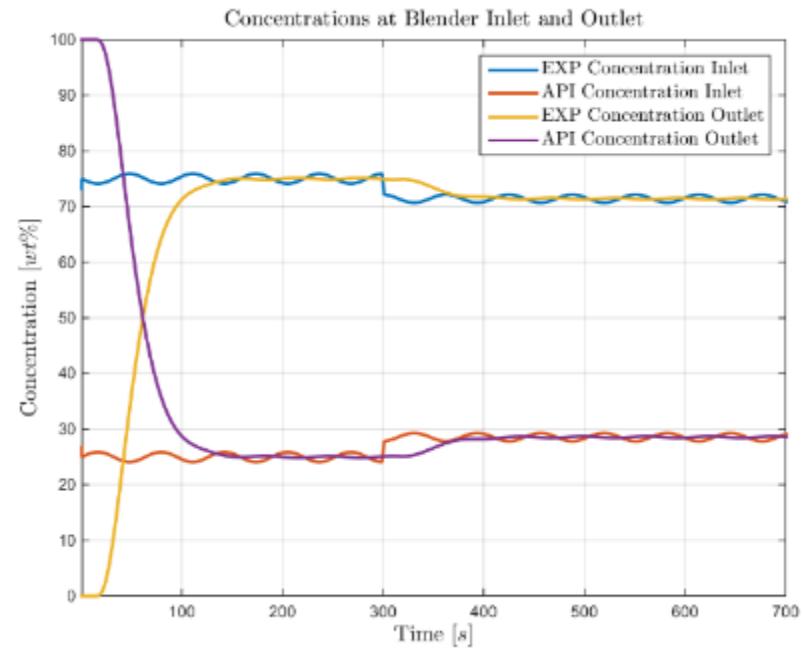
- Describes mixing and transport of material.  $P_e$  is a function of blender geometry and rotation speed, material properties and powder velocity.
- **Approximation with transfer function.**
- $P_e$  is determined via experiments or DEM

# Impact of Feeder Fluctuations

(a)



(b)

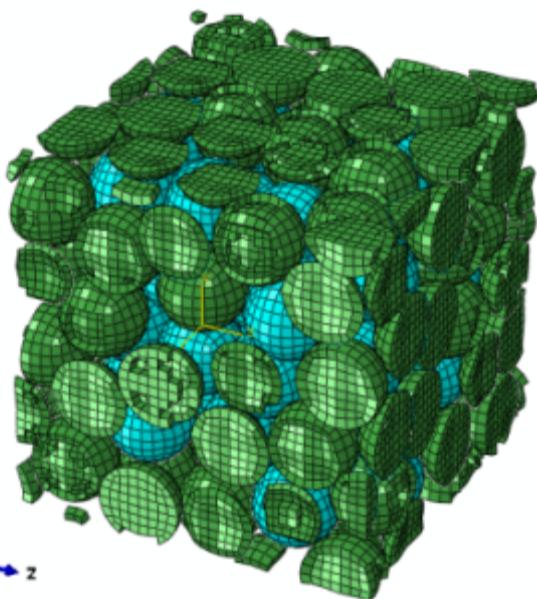


(a) Total mass flow rate at blender inlet and outlet. (b) inlet and outlet concentrations of API (lower lines) and EXC (upper lines) are shown.

# Compaction: Multi-particle FE-Model (finite element model)

- Use a Representative Volume Element (RVE) to minimize computational costs
- Use periodic boundary conditions to avoid boundary effects

**3D periodic box of meshed particles**

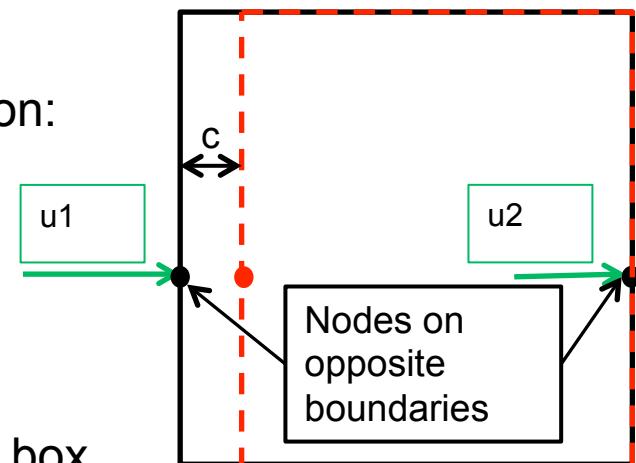


Constraint equation:

$$u_2 - u_1 = c$$

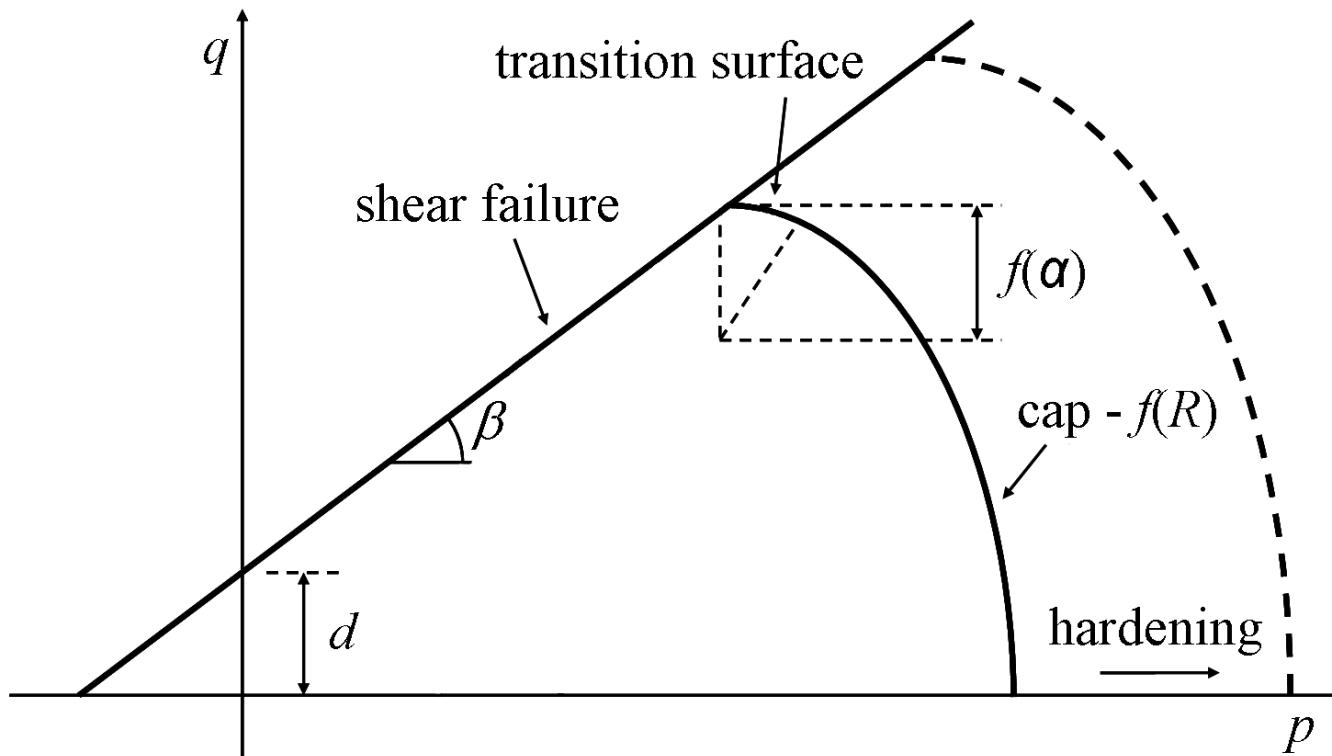
u...displacements  
c...deformation of box

**2D periodic box**

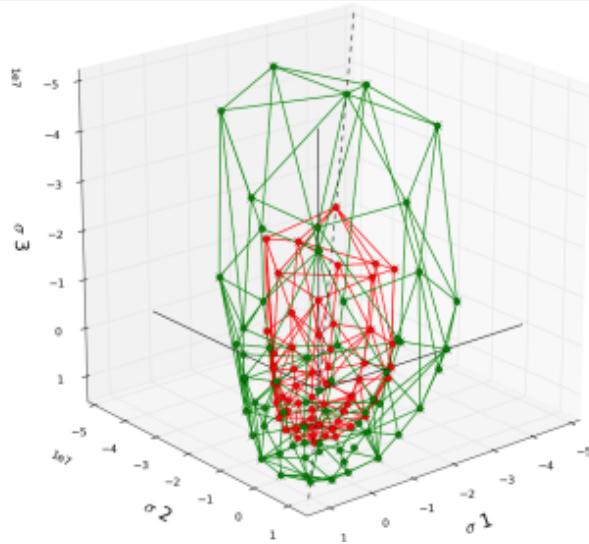


# Compaction: Drucker-Prager Cap Model

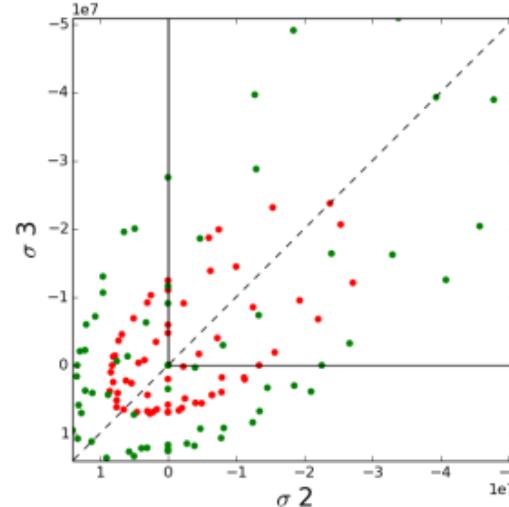
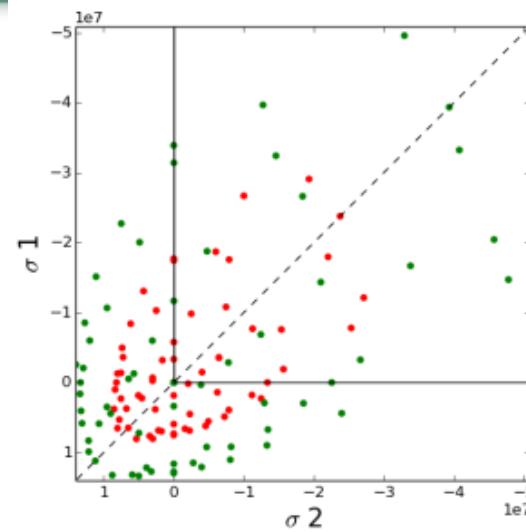
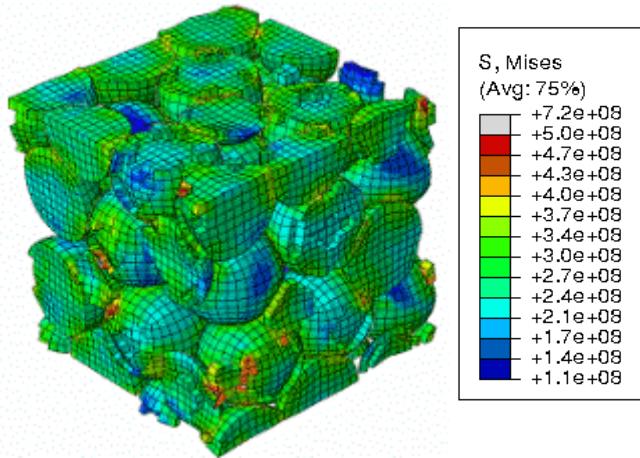
- Determined from experiments



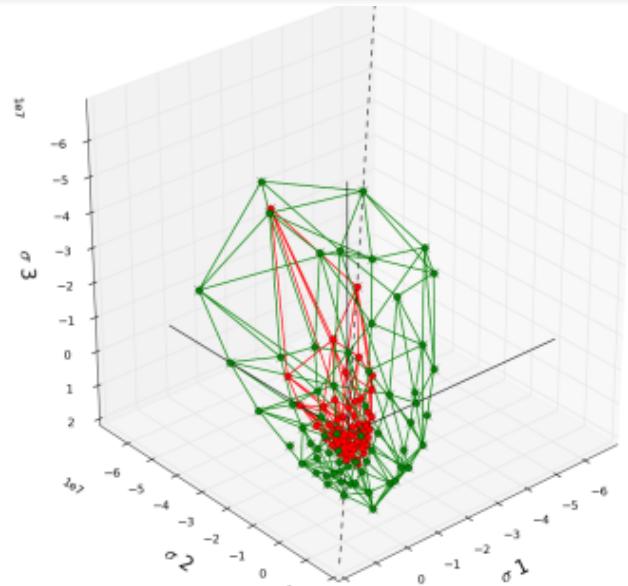
# Yield Surfaces for Isostatic Compaction



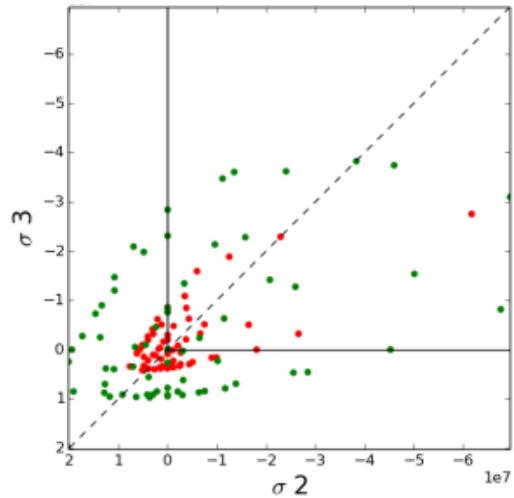
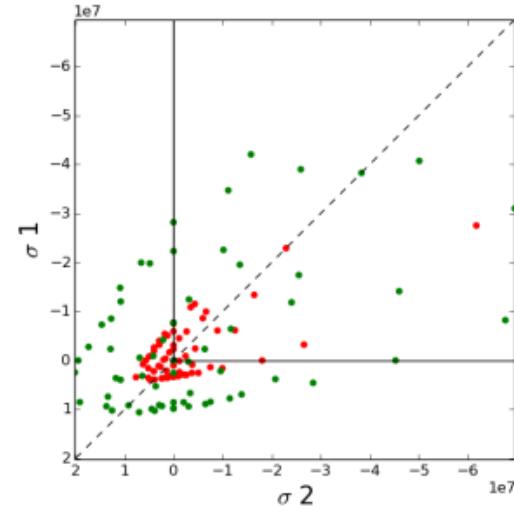
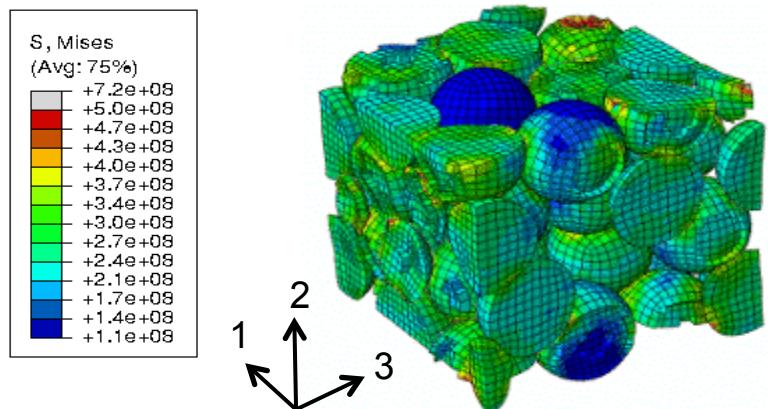
- Porosity 0.25
- Porosity 0.15



# Yield Surfaces for Closed-Die Compaction

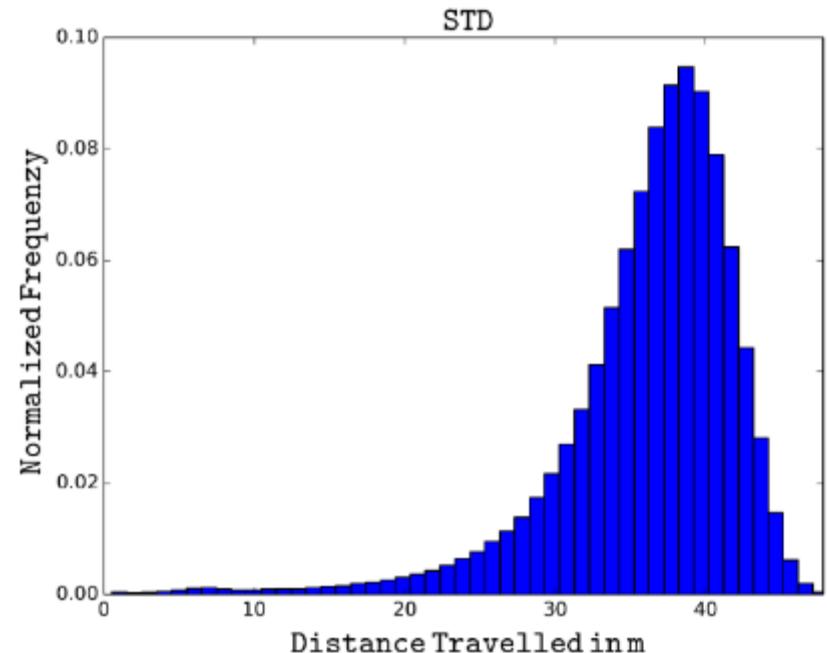
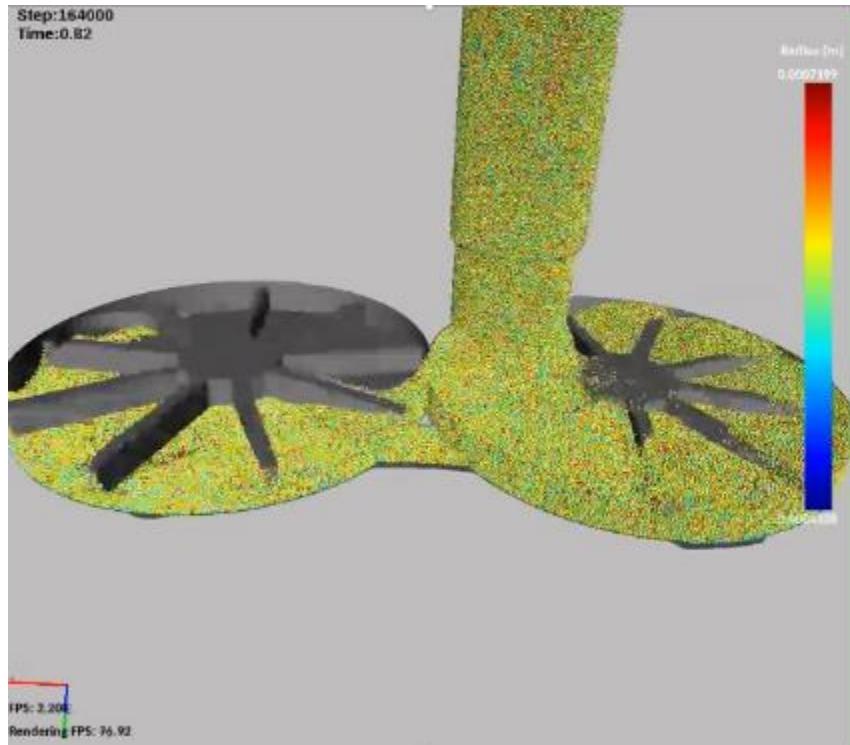


- Porosity 0.25
- Porosity 0.15



# Feed Frame Analysis

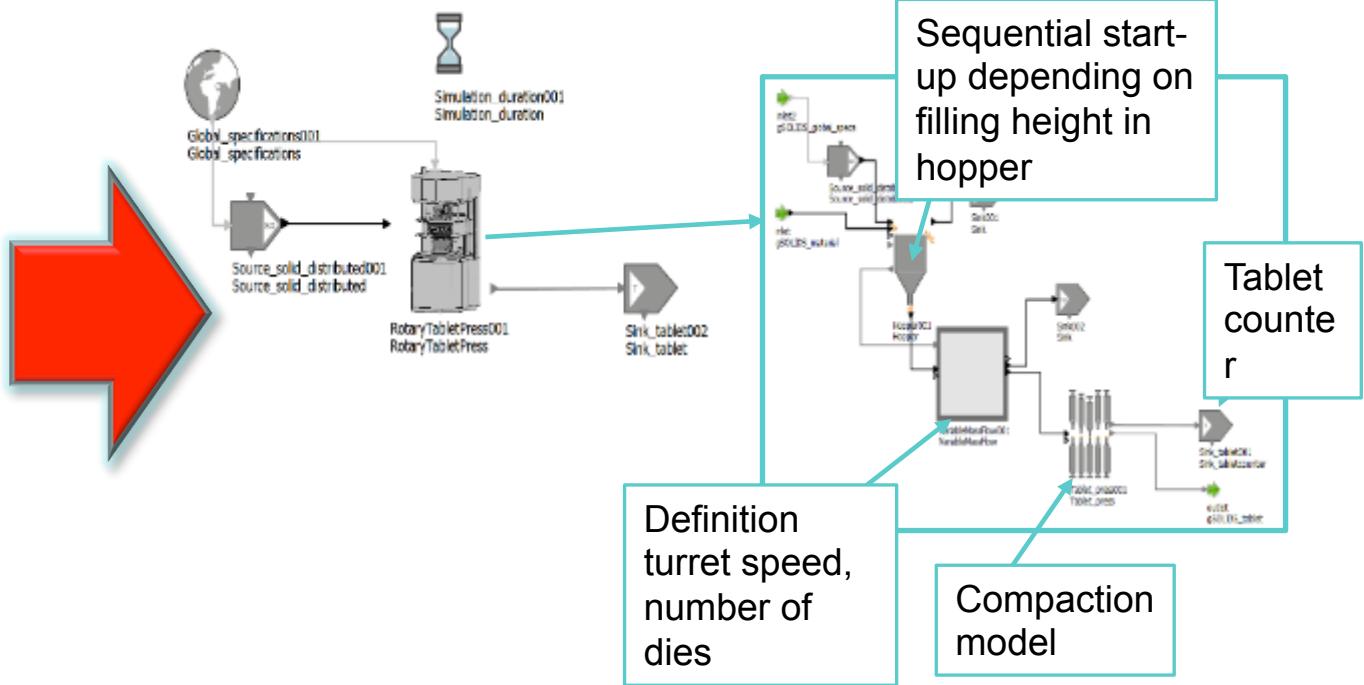
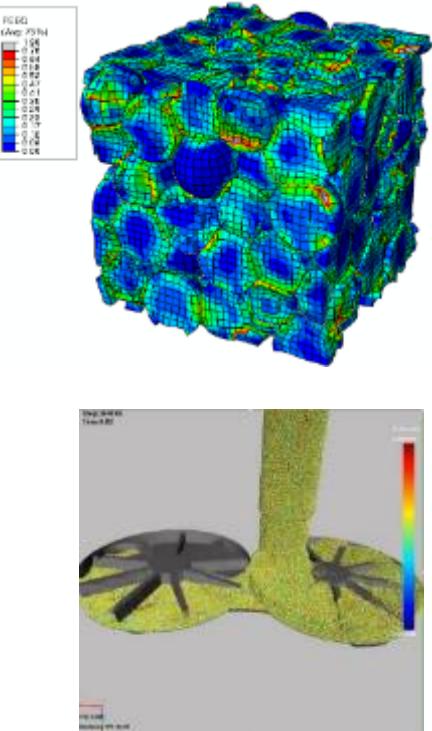
## CFD/DEM



# Rotary Tablet Press Model

## Detailed Model (PowCom)

### gsolids rotary tablet press model



# Acknowledgement

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- Prof. Peter Kleinebudde
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- Dr. Marcos LLusa (RCPE, Austria)
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# Science and commercial combined offerings



- PSE and RCPE announce that we will be setting up a **Centre of Excellence (“CoE”)** aimed at bringing combined model-based analytical technology and **services** to the **pharmaceuticals industry** and more in general to **life science** field of application
  
- PSE-RCPE CoE will be started **1<sup>st</sup> July 2016**, offering advanced simulation science and tools:
  - **Fit-for-purpose models** that combine **detailed mechanistic models at multiple length scales**
  - **Targeted and integrated experimentation** to reduce time and cost
  - Combination and integration of **most advanced modelling tools available** from PSE and RCPE
  - **Model-based workflows** that help you design robust products and processes rapidly and effectively
  - Combined and **integrated capacity and expertise**
  - **Integrated commercialization stream**