### CALCULUS AND LINEAR ALGEBRA

MATHEMATICS-I

(18MAB101T)

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### Introduction

Matrices find many applications in scientific field and useful in many practical real life problem. For example:

- It is useful in the study of electrical circuits, quantum mechanics and optics
- Matrices play a role in calculation of battery power outputs, resistor conversion of electrical energy into another useful energy using Kirchhoff law of voltage and current
- Matrices can play a vital role in the projection of three dimensional images into two dimensional screens, creating the realistic decreeing motion
- It is useful in wave equation associated with transmitting power through transmission lines
- It can be used to crack or deformities in a solid

### Introduction

- In machine learning we often have to deal with structural data, which is generally represented by matrix
- Car designers analyze eigenvalues in order to damp out noise so that the occupant have a quite ride
- It is also used in structural analysis to calculate buckling margins of safty
- Matrices are used in the ranking of web pages in the Google search
- It can also be used in generalization of analytical motion like experimental and derivatives to their high dimensional
- The usages of matrices in computer side application are encryption of message codes with the help of encryptions in the transmission of sensitive and private data
- Matrices are also used in robotics and automation in terms of base elements for the robot movements which are programmed with the calculation of matrices

**Definition:** Let A be a square matrix. If there exists a scalar  $\lambda$  and non-zero column matrix X such that  $AX = \lambda X$ , then the scalar  $\lambda$  is called an eigenvalue/characteristic value/latent value of A and X is called the corresponding eigenvector of A.

**How to find:** We can obtain the eigenvalues and eigenvectors through the following steps:

**Step 1:** Write the characteristic equation as

$$|A - \lambda I| = \lambda^n - S_1 \lambda^{n-1} + S_2 \lambda^{n-2} + \dots + (-1)^n S_n = 0, \quad n = 2, 3, 4 \cdot \dots,$$
 where

 $S_1 = \text{sum of the main diagonal elements of } A.$ 

 $S_2 = \mathsf{sum} \ \mathsf{of} \ \mathsf{the} \ \mathsf{of} \ \mathsf{minor} \ \mathsf{of} \ \mathsf{main} \ \mathsf{diagonal} \ \mathsf{elements} \ \mathsf{of} \ A \ \cdots \cdots$ 

 $S_n = \text{determinant of } A \text{ i.e } |A|.$ 

# Eigenvalues and Eigenvectors

## Unit-I

**Step 2:** Find the eigenvalues by factorizing the characteristic equation as  $(\lambda_1 - a_1)(\lambda_2 - a_2) \cdot \cdot \cdot \cdot (\lambda_n - a_n) = 0$  or by synthetic division.

**Step 3:** Find the eigenvectors X for each value of  $\lambda$  from the linear system of equation  $(A - \lambda_i I)X = 0$ ,  $i = 1, 2, 3 \cdot \cdot \cdot \cdot$ 

**Example:** Find the eigenvalues and eigenvectors of  $A = \begin{bmatrix} 2 & -2 & 3 \\ 1 & 1 & 1 \\ 1 & 3 & -1 \end{bmatrix}$ 

### **Solution:**

$$|A - \lambda I| = \begin{vmatrix} 2 - \lambda & -2 & 3 \\ 1 & 1 - \lambda & 1 \\ 1 & 3 & -1 - \lambda \end{vmatrix} = \lambda^3 - S_1 \lambda^2 + S_2 \lambda - S_3 = 0$$

$$S_1 = 2 + 1 - 1 = 2$$
,

$$S_2 = \begin{vmatrix} 1 & 1 \\ 3 & -1 \end{vmatrix} + \begin{vmatrix} 2 & 3 \\ 1 & -1 \end{vmatrix} + \begin{vmatrix} 2 & -2 \\ 1 & 1 \end{vmatrix} = -4 - 5 + 4 = -5$$

$$S_3 = |A| = \begin{vmatrix} 2 & -2 & 3 \\ 1 & 1 & 1 \\ 1 & 3 & -1 \end{vmatrix} = 6 \implies \lambda^3 - 2\lambda^2 - 5\lambda - 6 = 0$$

Which can be factorize as

$$(\lambda - 1)(\lambda - 3)(\lambda + 2) = 0 \quad \Rightarrow \quad \lambda = 1, \quad -2, \quad 3.$$

i.e. 
$$\begin{bmatrix} 1 & -2 & 3 \\ 1 & 0 & 1 \\ 1 & 3 & -2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}.$$

$$x_1 - 2x_2 + 3x_3 = 0$$
  
 $x_1 + 0 + x_3 = 0$   
 $x_1 + 3x_2 - 2x_3 = 0$ 

$$\Rightarrow \frac{x_1}{-3} = -\frac{x_2}{-3} = \frac{x_1}{3} \Rightarrow \frac{x_1}{-1} = \frac{x_2}{1} = \frac{x_1}{1} \Rightarrow X_1 = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}.$$

$$4x_1 - 2x_2 + 3x_3 = 0$$
  
$$x_1 + 3x_2 + x_3 = 0.$$

Solving the above equation as  $x_3 = -(x_1 + 3x_3) \Rightarrow x_1 - 11x_2 = 0$ , then

we get 
$$X_2 = \begin{bmatrix} 11 \\ 1 \\ -14 \end{bmatrix}$$
.

## Unit-I

**Eigenvector for** 
$$\lambda = 3$$
:

$$-x_1 - 2x_2 + 3x_3 = 0$$
  

$$x_1 - 2x_2 + x_3 = 0$$
  

$$x_1 + 3x_2 - 4x_3 = 0$$

$$\Rightarrow \quad \frac{x_1}{5} = -\frac{x_2}{-5} = \frac{x_1}{5} \quad \Rightarrow \quad \frac{x_1}{1} = \frac{x_2}{1} = \frac{x_1}{1} \quad \Rightarrow \quad X_3 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

**Example:** Find the eigenvalues and eigenvectors of  $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ 

### Solution:

$$|A - \lambda I| = \begin{vmatrix} 1 - \lambda & 0 & 0 \\ 0 & 1 - \lambda & 1 \\ 0 & 1 & 1 - \lambda \end{vmatrix} = \lambda^3 - S_1 \lambda^2 + S_2 \lambda - S_3 = 0$$

$$S_1 = 1 + 1 + 1 = 3$$
,  $S_2 = \begin{vmatrix} 1 & 1 \\ 1 & 1 \end{vmatrix} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} = 0 + 1 + 1 = 2$ 

$$S_3 = |A| = \begin{vmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{vmatrix} = 0 \implies \lambda^3 - 3\lambda^2 + 2\lambda = 0 \implies \lambda(\lambda - 1)(\lambda - 2) = 0$$

 $\Rightarrow \lambda = 0, 1, 2.$ 

Eigenvector for 
$$\lambda = 0$$
: 
$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$x_1 + 0x_2 + 0x_3 = 0$$
  
 $0x_1 + x_2 + x_3 = 0$   
 $0x_1 + x_2 + x_3 = 0$ .

$$\Rightarrow x_1 = 0$$
 and  $x_2 = -x_3$ . If we take  $x_3 = k \Rightarrow x_2 = -k$ 

$$\Rightarrow \quad X_1 = \left[ \begin{array}{c} 0 \\ -k \\ k \end{array} \right] = \left[ \begin{array}{c} 0 \\ -1 \\ 1 \end{array} \right].$$

Eigenvector for 
$$\lambda = 1$$
: 
$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$0x_1 + 0x_2 + 0x_3 = 0$$
$$0x_1 + 0x_2 + x_3 = 0$$

$$\Rightarrow$$
  $x_2 = 0$  and  $x_3 = 0$ . Taking  $x_1 = k$   $\Rightarrow$   $X_2 = \begin{bmatrix} k \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$ .

Eigenvector for 
$$\lambda = 2$$
: 
$$\begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$-x_1 + 0x_2 + 0x_3 = 0$$
  

$$0x_1 - x_2 + x_3 = 0$$
  

$$0x_1 + x_2 - x_3 = 0$$

$$\Rightarrow x_1 = 0 \text{ and } x_2 = x_3. \text{ If } x_3 = k \Rightarrow x_2 = k \Rightarrow X_3 = \begin{bmatrix} 0 \\ k \\ k \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}.$$

**Example:** Find the eigenvalues and eigenvectors of  $A = \begin{bmatrix} 2 & 1 & 1 \\ 2 & 3 & 2 \\ 2 & 2 & 4 \end{bmatrix}$ 

**Solution:** Here  $|A - \lambda I| = \lambda^3 - 9\lambda^2 + 15\lambda - 7 = 0 \Rightarrow \lambda = 1, 1, 7,$ some eigenvalues are repeated. Therefore we find the eigenvectors as:

$$\Rightarrow \quad \frac{x_1}{12-6} = -\frac{x_2}{-6-6} = \frac{x_3}{6+12} \quad \Rightarrow \quad \frac{x_1}{1} = \frac{x_2}{2} = \frac{x_3}{3} \quad \Rightarrow \quad X_1 = \left[ \begin{array}{c} 1 \\ 2 \\ 3 \end{array} \right].$$

Here we observe that all rows are linearly dependent

$$\Rightarrow x_1 + x_2 + x_3 = 0.$$

Now we will construct two linearly independent eigenvectors from the same equation assuming the followings:

Assume 
$$x_1 = 0 \implies x_3 = -x_2$$
 hence  $X_2 = \begin{bmatrix} 0 \\ k \\ -k \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix}$ .

Similarly assuming

$$x_2 = 0 \Rightarrow x_3 = -x_1$$
 hence  $X_3 = \begin{vmatrix} k \\ 0 \\ -k \end{vmatrix} = \begin{vmatrix} 1 \\ 0 \\ -1 \end{vmatrix}$ .

**Symmetric Matrix:** A real matrix A is said to be symmetric if  $A = A^T$ . where T stands for transpose.

**Orthogonal Matrix:** Let  $X_1$  and  $X_2$  be two column matrices of same order. Then  $X_1$  and  $X_2$  are said to be orthogonal if  $X_1^T X_2 = 0$ 

**Example:** Find the eigenvalues and eigenvectors of

$$A = \left[ \begin{array}{rrr} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{array} \right]$$

**Solution:** Here we can see that  $A = A^T$ , which implies it is a symmetric matrix.

Now  $|A - \lambda I| = \lambda^3 - 12\lambda^2 + 36\lambda - 32 = 0 \Rightarrow \lambda = 2$ , 8, some eigenvalues are repeated. Therefore we find the eigenvectors as:

Eigenvector for 
$$\lambda = 8$$

Eigenvector for 
$$\lambda = 8$$
: 
$$\begin{bmatrix} -2 & -2 & 2 \\ -2 & -5 & -1 \\ 2 & -1 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

# Symmetric matrix with repeated eigenvalues

Unit-l

$$\Rightarrow \frac{x_1}{25-1} = -\frac{x_2}{10+2} = \frac{x_3}{2+10} \Rightarrow \frac{x_1}{2} = \frac{x_2}{-1} = \frac{x_3}{1} \Rightarrow X_1 = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}.$$

**Eigenvector for** 
$$\lambda = 2$$
:

Eigenvector for 
$$\lambda = 2$$
: 
$$\begin{bmatrix} 4 & -2 & 2 \\ -2 & 1 & -1 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$
 Here one

can observe that all rows are linearly dependent  $\Rightarrow -2x_1 + x_2 - x_3 = 0$ .

Assume 
$$x_1 = 0 \implies x_3 = x_2$$
 hence  $X_2 = \begin{bmatrix} 0 \\ k \\ k \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$ .

For the nest eigenvalue 
$$\lambda = 2$$
, we consider  $X_3 = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$ 

As the matrix A is symmetric, so the eigenvectors are orthogonal.

$$\therefore X_1^T X_3 = 0 \implies \begin{bmatrix} 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0 \implies 2a - b + c = 0. \text{ again}$$
$$X_2^T X_3 = 0 \implies \begin{bmatrix} 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 0 \implies b + c = 0.$$

Solving the above two equations we get a=b=-c  $\Rightarrow X_3=\begin{bmatrix} 1\\1\\-1 \end{bmatrix}$ .

**Example:** Find the eigenvalues and eigenvectors of

$$A = \left[ \begin{array}{rrr} 2 & -1 & 1 \\ -1 & 2 & -1 \\ 1 & -1 & 2 \end{array} \right].$$

**Property 1:** Every square matrix and it's transpose has same eigenvalues.

**Example:** If 
$$A = \begin{bmatrix} 1 & -2 \\ -5 & 4 \end{bmatrix} \Rightarrow \lambda^2 - 5\lambda - 6 = 0 \Rightarrow \lambda = 6, -1.$$

$$A^T = \begin{bmatrix} 1 & -5 \\ -2 & 4 \end{bmatrix} \Rightarrow \lambda^2 - 5\lambda - 6 = 0 \Rightarrow \lambda = 6, -1.$$

**Property 2:** If  $\lambda_1, \ \lambda_2, \ \lambda_3, \dots \lambda_n$  are the eigenvalues of the matrix A then  $\frac{1}{\lambda_1}, \ \frac{1}{\lambda_2}, \ \frac{1}{\lambda_3}, \dots \frac{1}{\lambda_n}$  are the eigenvalues of  $A^{-1}$ .

**Proof:** Let  $\lambda$  be the eigenvalue of a matrix  $A \Rightarrow AX = \lambda X$ , where X is an eigenvector  $X \neq 0$ . If we multiply  $A^{-1}$  with  $AX = \lambda X$  as below:

$$A^{-1}AX = A^{-1}\lambda X \quad \Rightarrow IX = \lambda A^{-1}X \quad \Rightarrow \tfrac{1}{\lambda}X = A^{-1}X.$$

 $\therefore \frac{1}{\lambda}$  is the eigenvalue of  $A^{-1}$ .

**Property 3:** If  $\lambda_1, \ \lambda_2, \ \lambda_3, \dots \lambda_n$  are the eigenvalues of the matrix A, then  $\lambda_1^2, \ \lambda_2^2, \ \lambda_3^2, \dots \lambda_n^2$  are the eigenvalues of  $A^2$ .

**Proof:** Let  $\lambda$  be the eigenvalue of a matrix A.  $\therefore AX = \lambda X$ , where X is an eigenvector  $X \neq 0$ . If we multiply A with  $AX = \lambda X$  as below:

$$AAX = A\lambda X \Rightarrow A^2X = \lambda AX \Rightarrow A^2X = \lambda^2X$$
.

 $\therefore \lambda^2$  is the eigenvalue of  $A^2$ .

**Property 4:** If  $\lambda_1, \ \lambda_2, \ \lambda_3, \dots \lambda_n$  are the eigenvalues of the matrix A, then  $k\lambda_1, \ k\lambda_2, \ k\lambda_3, \dots k\lambda_n$  are the eigenvalues of kA.

**Proof:** Let  $\lambda$  be the eigenvalue of a matrix A.

$$\therefore AX = \lambda X \quad \Rightarrow \quad kAX = k(\lambda X) = (k\lambda)X.$$

 $\therefore k\lambda$  is the eigenvalue of kA.

**Property 5:** The eigenvalues of a real symmetric matrix are all real.

**Proof:** Let  $\lambda$  be the eigenvalue of a matrix A.

$$AX = \lambda X \tag{1}$$

Taking conjugate on both sides of (1) we get  $\bar{A}\bar{X}=\bar{\lambda}\bar{X}$ . As A is real  $\therefore A=\bar{A} \Rightarrow A\bar{X}=\bar{\lambda}\bar{X}$ . Taking transpose on both side one can get  $(A\bar{X})^T=(\bar{\lambda}\bar{X})^T \Rightarrow \bar{X}^TA^T=\bar{\lambda}^T\bar{X}^T \Rightarrow \bar{X}^TA=\bar{\lambda}\bar{X}^T$  ( $\because A$  is symmetric  $A=A^T$  and  $\lambda$  is a scalar). Now post multiply by X

$$\bar{X}^T A X = \bar{\lambda} \bar{X}^T X \quad \Rightarrow \bar{X}^T \lambda X = \bar{\lambda} \bar{X}^T X \quad \Rightarrow \lambda \bar{X}^T X = \bar{\lambda} \bar{X}^T X \quad \Rightarrow \lambda = \bar{\lambda}.$$

**Property 6:** If  $\lambda_1, \ \lambda_2, \ \lambda_3, \cdots \lambda_n$  are the eigenvalues of the matrix A, then trace of A=sum of eigenvalues  $= \lambda_1 + \lambda_2 + \lambda_3, \cdots + \lambda_n$  and product of eigenvalues of A= $|\ A\ |$  i.e  $|\ A\ | = \lambda_1.\lambda_2.\lambda_3, \cdots + \lambda_n$ .

**Property 6:** Eigenvalues of a triangular matrix are just the diagonal elements of the matrix.

**Proof:** Let 
$$A = \begin{bmatrix} a_{11} & 0 & 0 \\ a_{21} & a_{22} & 0 \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\Rightarrow |A - \lambda I| = \begin{vmatrix} a_{11} - \lambda & 0 & 0 \\ a_{21} & a_{22} - \lambda & 0 \\ a_{31} & a_{32} & a_{33} - \lambda \end{vmatrix} = 0$$

$$\Rightarrow (a_{11}-\lambda)(a_{22}-\lambda)(a_{33}-\lambda)=0.$$

$$\Rightarrow \lambda = a_{11}, \quad a_{22}, \quad a_{33}.$$

**Example:** Find the sum and product of the eigenvalues of a matrix

$$A = \begin{bmatrix} -2 & 2 & -3 \\ 2 & 1 & 6 \\ -1 & -2 & 0 \end{bmatrix}.$$

**Proof:** We know sum of eigenvalues of A=Sum of he leading diagonal elements of A=trace of A=-2+1+0=-1.

Product of the

eigenvalues=
$$|A| = -2(0-12) - 2(0-6) - 3(-4+1) = 45.$$

**Example:** Two of the eigenvalues of  $A = \begin{bmatrix} 3 & -1 & 1 \\ -1 & 5 & -1 \\ 1 & -1 & 3 \end{bmatrix}$  are 3 and 6.

Find the eigenvalues of  $A^{-1}$ .

**Solution:** Let  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  are eigenvalues of A.

$$\Rightarrow \lambda_1 + \lambda_2 + \lambda_3 = 3 + 5 + 3 = 11$$

As 
$$\lambda_1 = 3$$
,  $\lambda_2 = 6 \Rightarrow \lambda_3 = 2$ 

 $\therefore$  Eigenvalues of  $A^{-1}$  are  $\frac{1}{2}$ ,  $\frac{1}{3}$ ,  $\frac{1}{6}$ .

**Example:** If 2 and 3 are eigenvalues of  $A = \begin{bmatrix} 3 & 10 & 5 \\ -2 & -3 & -4 \\ 3 & 5 & 7 \end{bmatrix}$ . Find the

eigenvalues of  $A^{-1}$  and  $A^3$ .

**Solution:** Let  $\lambda_1$ ,  $\lambda_2$ ,  $\lambda_3$  are eigenvalues of A.

$$\Rightarrow \lambda_1 + \lambda_2 + \lambda_3 = 3 + 2 + \lambda_3 = 3 - 3 + 7 = 7 \quad \Rightarrow \lambda_3 = 2$$

 $\therefore$  Eigenvalues of  $A^{-1}$  are  $\frac{1}{2}$ ,  $\frac{1}{2}$ ,  $\frac{1}{3}$ .

and eigenvalues of  $A^3$  are  $2^3$ ,  $2^3$ ,  $3^3$ .

# Problems based on properties

## Unit-I

**Example:** Find the constant a and b such that  $\begin{bmatrix} a & 4 \\ 1 & b \end{bmatrix}$  matrix has 3 and -2 as eigenvalues.

**Solution:** 
$$a + b = 3 - 2 = 1$$
 and  $ab - 4 = 3 \times -2 = -6$ 

$$\therefore b = 1 - a \implies a(1 - a) - 4 = -6 \implies a(1 - a) = -2$$
$$\Rightarrow a = 2, -1 \implies b = -1, 2.$$

**Example:** Two eigenvalues of  $A = \begin{bmatrix} 4 & 6 & 6 \\ 1 & 3 & 2 \\ -1 & -5 & -2 \end{bmatrix}$  are equal and they

are double the third. Find the eigenvalues of  $A^2$ .

**Solution:** Let the third eigenvalue is  $\lambda$ . Therefore the three eigenvalues are  $\lambda$ ,  $2\lambda$ ,  $2\lambda$ .  $\Rightarrow \lambda + 2\lambda + 2\lambda = 4 + 3 - 2$   $\Rightarrow 5\lambda = 5$   $\Rightarrow \lambda = 1$ 

 $\therefore$  The eigenvalues are 1, 2, 2 and eigenvalues of  $A^2$  are 1, 4, 4.

**Statement:** Every square matrix satisfies it's own characteristics equation. i.e If A is any  $n \times n$  matrix and

$$\lambda^{n} - S_{1}\lambda^{n-1} + S_{2}\lambda^{n-2} - S_{3}\lambda^{n-3} \cdot \cdot \cdot \cdot + (-1)^{n}S_{n} = 0$$

is the characteristic equation then

$$A^{n} - S_{1}A^{n-1} + S_{2}A^{n-2} - S_{3}A^{n-3} \cdot \cdot \cdot \cdot \cdot + (-1)^{n}S_{n} = 0.$$

**Example:** Verify Cayley-Hamilton theorem and hence find  $A^{-1}$  for

$$A = \begin{bmatrix} 8 & -8 & 2 \\ 4 & -3 & -2 \\ 3 & -4 & 1 \end{bmatrix}.$$

**Solution:** The characteristic equation can be obtain from

$$\begin{vmatrix} 8 - \lambda & -8 & 2 \\ 4 & -3 - \lambda & -2 \\ 3 & -4 & 1 - \lambda \end{vmatrix} = 0 \Rightarrow \lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

Now we need to show that  $A^3 - 6A^2 + 11A - 6I = 0$ . For that we find the followings:

$$A^{2} = A.A = \begin{bmatrix} 8 & -8 & 2 \\ 4 & -3 & -2 \\ 3 & -4 & 1 \end{bmatrix} \begin{bmatrix} 8 & -8 & 2 \\ 4 & -3 & -2 \\ 3 & -4 & 1 \end{bmatrix} = \begin{bmatrix} 26 & -32 & -2 \\ 14 & -15 & -4 \\ 11 & -16 & 3 \end{bmatrix}$$

$$A^{3} = A^{2}.A = \begin{bmatrix} 26 & -32 & -2 \\ 14 & -15 & -4 \\ 11 & -16 & 3 \end{bmatrix} \begin{bmatrix} 8 & -8 & 2 \\ 4 & -3 & -2 \\ 3 & -4 & 1 \end{bmatrix} = \begin{bmatrix} 74 & -104 & 10 \\ 40 & -51 & -24 \\ 33 & -52 & 13 \end{bmatrix}$$

Now 
$$A^3 - 6A^2 + 11A - 6I = \begin{bmatrix} 74 & -104 & 10 \\ 40 & -51 & -24 \\ 33 & -52 & 13 \end{bmatrix} - \begin{bmatrix} 156 & -192 & -12 \\ 84 & -90 & -24 \\ 66 & -93 & 18 \end{bmatrix} + \begin{bmatrix} 156 & -192 & -12 \\ 84 & -90 & -24 \\ 66 & -93 & 18 \end{bmatrix}$$

$$\begin{bmatrix} 88 & -88 & -22 \\ 44 & -33 & -22 \\ 33 & 44 & 11 \end{bmatrix} - \begin{bmatrix} 6 & 0 & 0 \\ 0 & 6 & 0 \\ 0 & 0 & 6 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = 0.$$

**Finding**  $A^{-1}$ : Let us premultiply the equation  $A^3 - 6A^2 + 11A - 6I = 0$  by  $A^{-1}$ , then we get:  $A^2 - 6A + 11I - 6A^{-1} = 0 \implies 6A^{-1} = [A^2 - 6A + 11I]$ .

$$\Rightarrow 6A^{-1} = \begin{bmatrix} 26 & -32 & -2 \\ 14 & -15 & -4 \\ 11 & -16 & 3 \end{bmatrix} - \begin{bmatrix} 48 & -48 & -12 \\ 24 & -18 & -12 \\ 18 & -24 & 6 \end{bmatrix} + \begin{bmatrix} 11 & 0 & 0 \\ 0 & 11 & 0 \\ 0 & 0 & 11 \end{bmatrix}$$
$$\Rightarrow A^{-1} = \frac{1}{6} \begin{bmatrix} -11 & 16 & 10 \\ -10 & 14 & 8 \\ -7 & 8 & 8 \end{bmatrix}.$$

**Example:** Using Cayley-Hamilton theorem find the inverse of

$$A = \begin{bmatrix} 2 & 1 \\ 1 & -5 \end{bmatrix}.$$

Solution: The characteristic equation can be obtain from

$$\begin{vmatrix} 2-\lambda & 1\\ 1 & -5-\lambda \end{vmatrix} = 0 \Rightarrow \lambda^2 + 3\lambda - 11 = 0 \Rightarrow A^2 + 3A - 11I = 0.$$

$$\Rightarrow A + 3I = 11A^{-1}$$
  $\Rightarrow A^{-1} = \frac{1}{11}[A + 3I] = \frac{1}{11}\begin{bmatrix} 5 & 1 \\ 1 & -2 \end{bmatrix}.$ 

**Example:** Verify Cayley-Hamilton theorem for the matrix

$$A = \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix}$$
 and use it to find  $A^{-1}$  and  $A^4$ .

**Solution:** The characteristic equation can be obtain from

$$\begin{vmatrix} 1 - \lambda & 2 & -2 \\ -1 & 3 - \lambda & 0 \\ 0 & -2 & 1 - \lambda \end{vmatrix} = 0 \implies \lambda^3 - 5\lambda^2 + 9\lambda - 1 = 0$$

$$A^{2} = A.A = \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 12 & -4 \\ -4 & 7 & 2 \\ 2 & -8 & 1 \end{bmatrix}$$

# Cayley-Hamilton Theorem

## Unit-I

$$A^{3} = A^{2}.A = \begin{bmatrix} -1 & 12 & -4 \\ -4 & 7 & 2 \\ 2 & -8 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix} = \begin{bmatrix} -13 & 42 & -2 \\ -11 & 9 & 10 \\ 10 & -22 & -3 \end{bmatrix}$$

Now 
$$A^3 - 5A^2 + 9A - I = \begin{bmatrix} -13 & 42 & -2 \\ -11 & 9 & 10 \\ 10 & -22 & -3 \end{bmatrix} - 5 \begin{bmatrix} -1 & 12 & -4 \\ -4 & 7 & 2 \\ 2 & -8 & 1 \end{bmatrix} + 9 \begin{bmatrix} 1 & 2 & -2 \\ -1 & 3 & 0 \\ 0 & -2 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} = 0.$$

Multiplying by 
$$A^{-1}$$
 gives  $A^{-1} = A^2 - 5A + 9I = \begin{bmatrix} 3 & 2 & 6 \\ 1 & 1 & 2 \\ 2 & 2 & 5 \end{bmatrix}$ 

Multiplying by A gives 
$$A^4 = 5A^3 - 9A^2 + A = \begin{bmatrix} -55 & 104 & 24 \\ -20 & -15 & 32 \\ 32 & -42 & -23 \end{bmatrix}$$
.