

Course Code	18ECC104T	Course Name	SIGNALS AND SYSTEMS	Course Category	C	Professional Core			
						L	T	P	C
						3	1	0	4

Pre-requisite Courses	Nil	Co-requisite Courses	18MAB201T	Progressive Courses	18ECC204J, 18ECS201T, 18ECE240T, 18ECE241J				
Course Offering Department	Electronics and Communication Engineering			Data Book / Codes/Standards	Nil				

Course Learning Rationale (CLR):		The purpose of learning this course is to:			Learning			Program Learning Outcomes (PLO)																
CLR-1 :	Know about requirements of signal and system analysis in communication.				Level of Thinking (Bloom)	1	2	3	Engineering Knowledge	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
CLR-2 :	Understand the analysis of Periodic and Aperiodic Continuous time Signals using Fourier series and transforms																							
CLR-3 :	Educate about Continuous time system through Laplace transform and Convolution integral																							
CLR-4 :	Understand the characterization of the Discrete time signals and system through DTFT, Convolution sum																							
CLR-5 :	Understand the concept of Z-Transform for the analysis of DT system																							
CLR-6 :	Develop expertise in time-domain and frequency domain approaches to the analysis of continuous and discrete systems and also the ability to apply modern computation software tool for the analysis of electrical engineering problems																							
Course Learning Outcomes (CLO):		At the end of this course, learners will be able to:																						
CLO-1 :	Acquire knowledge of various classifications of Signals and Systems					1	85	70	H	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-
CLO-2 :	Analyze Periodic and Aperiodic Continuous time Signals using Fourier series and Fourier Transform					2	85	70	H	M	-	-	M	-	-	-	-	-	-	-	-	-	-	
CLO-3 :	Analyze and characterize the Continuous time system through Laplace transform and Convolution integral.					2	85	70	H	M	-	-	M	-	-	-	-	-	-	-	-	-	-	
CLO-4 :	Analyze and characterize the Discrete time signals and system through DTFT, Convolution sum					2	85	70	H	M	-	-	M	-	-	-	-	-	-	-	-	-	-	
CLO-5 :	Analyze and characterize the Discrete time system using Z transform					2	85	70	H	M	-	-	M	-	-	-	-	-	-	-	-	-	-	
CLO-6 :	Present the mathematical techniques used for continuous-time signal and discrete-time signal and system analysis					3	85	70	H	M	-	-	-	-	-	-	-	-	L	L	-	-	-	

Duration (hour)	Classification of Signals and Systems		Analysis of Continuous Time Signals	Analysis of LTI CT System	Analysis of DT Signals and Systems	Analysis of LTI DT System using Z-Transform
	12		12	12	12	12
S-1	SLO-1	Introduction to signals and systems	Introduction to Fourier series	System modeling	Representation of sequences	Z transform – introduction
	SLO-2	Requirements of signal and system analysis in communication	Representation of Continuous time Periodic signals	Description of differential equations	Discrete frequency spectrum and range	Region of convergence of finite duration sequences
S-2	SLO-1	Continuous time signals (CT signals)	Fourier series: Trigonometric representation	Solution of Differential equation	Discrete Time Fourier Transform (DTFT) – Existence	Properties of ROC
	SLO-2	Discrete time signals (DT signals)	Fourier series: Trigonometric representation	Differential equation: Zero initial conditions	DTFT of standard signals	Properties of ROC
S-3	SLO-1	Representation of signals: Step, Ramp, Pulse, Impulse	Fourier series: Cosine representation	Differential equation: Zero state response	Properties of DTFT	Properties of Z transform
	SLO-2	Representation of signals: Sinusoidal, Exponential	Fourier series: Cosine representation	Differential equation: Zero Input response	Properties of DTFT	Properties of Z transform
S-4	SLO-1	Basic operation on the signals	Symmetry conditions	Total Response	Inverse DTFT	Unilateral z transforms
	SLO-2	Problems on signal operations	Properties of Continuous time Fourier series	Step response	Practice on IDTFT	Properties of z transform
S-5	SLO-1	Classification of CT and DT signals: Periodic & Aperiodic signals.	Practice problems on Fourier series	Impulse response	Impulse response of a system with DTFT	Bilateral Z transforms
	SLO-2	Classification of CT and DT signals: Deterministic & Random signals.	Practice problems on Fourier series	Frequency response	Frequency response of a system with DTFT	Properties of z transform

S-6	SLO-1	Energy signal	Gibb's Phenomenon	Convolution integral	Practice problems	Relation between DTFT and Z transform
	SLO-2	Power signal	Parseval's relation for power signals	Properties of convolution	Practice problems	Practice problems
S-7	SLO-1	Even & Odd signals	Power density spectrum,	Practice Problems	Solution of linear constant coefficient difference equations	condition for causality in Z domain
	SLO-2	Even & Odd signals	Frequency spectrum.	Practice Problems	Initial conditions	condition for stability in Z domain
S-8	SLO-1	CT systems and DT systems	Fourier transform: Introduction	Signal and system analysis with Laplace transform	Solution of difference equations	Inverse Z transform
	SLO-2	Classification of systems: Static & Dynamic	Representation of Continuous time signals	Convergence of Laplace Transform	Zero input response	Power series expansion
S-9	SLO-1	Superposition theorem	Properties of Continuous time Fourier transform	Properties of Laplace transform	Solution of difference equations with Zero state response	Inverse Z transform with Partial fraction
	SLO-2	Linear & Nonlinear system	Properties of Continuous time Fourier transform	Properties of Laplace transform	Total response	Inverse Z transform with Partial fraction
S-10	SLO-1	Time-variant & Time-invariant system	Parseval's relation for energy signals	Inverse Laplace transform	Evaluation of Impulse response	Residue method
	SLO-2	Time-invariant system	Energy density spectrum	Problems	Evaluation of Step response	Convolution method
S-11	SLO-1	Causal system	Analysis of LTI system using Fourier Transform	Analysis and characterization of LTI system using Laplace transform	Convolution Properties	Analysis and characterization of DT system using Z-transform
	SLO-2	Noncausal system	Analysis of LTI system using Fourier Transform	Analysis and characterization of LTI system using Laplace transform	Convolution Sum	Analysis and characterization of DT system using Z-transform
S-12	SLO-1	Stable & Unstable, LTI System	Practice problems on Fourier Transform	Practice problems on Laplace transform	Circular convolution	Practice problems on LTI-DT systems in Z transform
	SLO-2	Unstable, LTI System	Practice problems on Fourier Transform	Practice problems on Laplace transform	Frequency response	Practice problems on LTI-DT systems in Z transform

Learning Resources	1. Alan V Oppenheim, Ronald W. Schaffer Signals & Systems, 2 nd ed., Pearson Education, 2015	5. John G. Proakis, Manolakis, Digital Signal Processing, Principles, Algorithms and Applications, 4 th ed., Pearson Education, 2007.
	2. P.Ramakrishna Rao, Shankar Prakriya, Signals & Systems, 2 nd ed., McGraw Hill Education, 2015	6. Software: Matlab Student Version Release 2011a, Mathworks, Inc. The Matlab Student Version and toolboxes may be purchased through the Mathworks website at http://www.mathworks.com/
	3. Simon Haykin, Barry Van Veen, Signals and Systems, 2 nd ed., John Wiley & Sons Inc., 2007	
	4. Lathi B.P., Linear Systems & Signals, 2 nd ed., Oxford Press, 2009	

Learning Assessment											
	Bloom's Level of Thinking	Continuous Learning Assessment (50% weightage)								Final Examination (50% weightage)	
		CLA – 1 (10%)		CLA – 2 (15%)		CLA – 3 (15%)		CLA – 4 (10%)#			
		Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice	Theory	Practice
Level 1	Remember	40 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Understand										
Level 2	Apply	40 %	-	40 %	-	40 %	-	40 %	-	40%	-
	Analyze										
Level 3	Evaluate	20 %	-	30 %	-	30 %	-	30 %	-	30%	-
	Create										
	Total	100 %		100 %		100 %		100 %		100 %	

CLA – 4 can be from any combination of these: Assignments, Seminars, Tech Talks, Mini-Projects, Case-Studies, Self-Study, MOOCs, Certifications, Conf. Paper etc.,

Course Designers		
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