Lab 3

Ex.No.3.Program to demonstrate decision making and looping operation.

3.1 Introduction:

The purpose of this experiment is to learn about the general purpose registers, instruction sets, addressing modes and logical operators of 8086 by sorting the sequence of numbers from the array stored in a memory location into ascending and descending series.

3.2 Hardware Requirement:

The 8086 Microprocessor kit, Power Supply.

3.3 Program Logic:

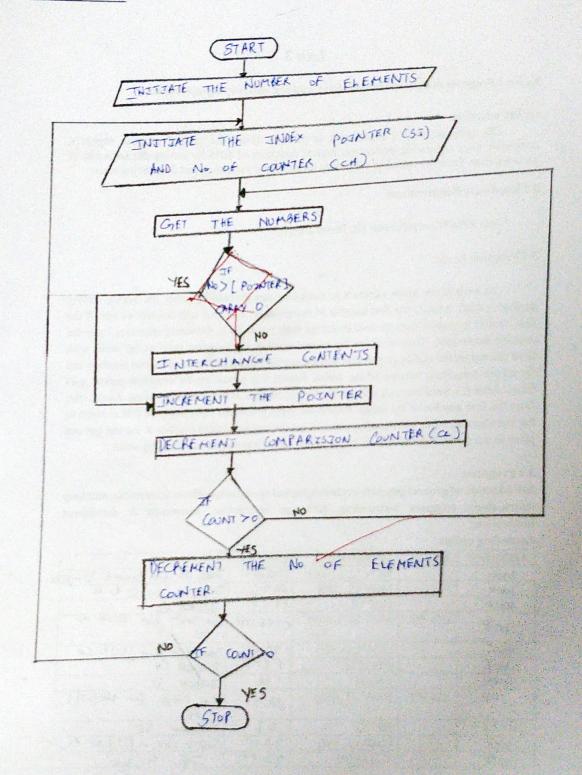
To arrange the given numbers in ascending and descending order, the bubble sorting method is used. Initially the first number of the series is compared with the second one. If the first number is greater than second, exchange their positions in the series otherwise leave the position unchanged. Then compare the second number in the recent form of the series with third and repeat the exchange part that you are carried out for the first and second number, and for all the remaining number of the series. Repeat this procedure for complete series (n-1) times. After n-1 iterations you will get the largest number at the end of the series. Again, start from the first number of the series. Repeat the same procedure right from the first element to the last element. After n-2 iteration you will get the second highest number at the last but one place in the series. Repeat this till the complete series is arranged in ascending order.

3.4 Program:

Introduction of general-purpose registers, logical operators, indirect addressing, and loop instructions, compare instruction, exchange instruction, increment & decrement instruction:

Ascending order:

ADDRESS	LABEL	MNEMONICS	OPCODE	COMMENTS
1000		MOV SI, 1200H	C7 Choo 12	Transfer Date from EDOOH to SI magi
1004	A Republica	MOV CL, [SI]	84 OC	Transport Date from Kanott to SIMG
1006		DEC CL	FE C9	Dalamed Cl
1008	LOOP3	MOV SI, 1200H	C1 C6 0012	Data Transfer from 1200H to SI
100C		MOV CH, [SI]	3A 2C	Die Though from [53] to CH
IDOE		DEC CH	FECD	Declement CH
1010		INC SI	46	Trainer SI
1011	LOOP2	MOV AL, [SI]	8A 04	Data these for given theo[SI] to
10 13		INC SI	46	Troppen 6J
1014		CMP AL, [SI]	3404	Compare Data in [5] and AL
1016		JC LOOP1	72 FF	Junh to 1610.



		Largue AL [SI]	8604	Exchange Dete Grom SI
1018		XCHG AL, [SI]		Exchange Data
AIOI		ACITO	FECD	Decement CH
101 D	LOOP1	DEC CH	250	Jump 15 1002
IDIF		JNZ LOOP2	FE C9	Dociomant CL
1021		DEC CL	FECT	Timb 10 1000
(023		JNZ LOOP3	716	Terminale Te Rogton
OLE		HLT	1-9	CHILITINE A

escending ord	TADEL	MNEMONICS	OPCODE	A A March 1 March 1 March 1 July 1
ADDRESS	LABEL	MOV SI, 1200H	C11 60012	Date Theogle from LSE) to a
1000		MOV CL, [SI]	SAOC	Data Heaght provides
1004		DEC CL	FIC9	Operanent OL
1006		MOV SI,1200H	C1Cbao12	Data tosen 1200 + to
Imt	LOOP3	MOV 31,120011	CICV	SJ. (17) 30
1008		MON CH [SI]	FA2C	Date theafar (nom [SI] to C
100C		MOV CH, [SI]	FECD	Degement Cit
100 t		DEC CH	46	CT
1010		INC SI		Data truster from [S]
	LOOP2	MOV AL, [SI]	8A 04	t AL
1011			46	Trap man ST
1013		INC SI		Company Al 40 Cos
1014		CMP AL, [SI]	3A04 13 05	Time 15 1010
1016		JNC LOOP1	8604	Exchange DAG in [SIJonIAL
1018		XCHG AL, [SI]		Escourse Det
101A		XCHG [SI-1], AL	86 44 FF	Decke ment CH
1012	LOOP1	DEC CH	FECD	Jump to 1010
1010		JNZ LOOP2	77F6 C	Jump 18 CL
JOIF		DEC CL	FEC9	Decrement I was
1021		JNZ LOOP3	7563	Jump to 1000
1023 102 E		HLT	F4	Terminate the Rogican.

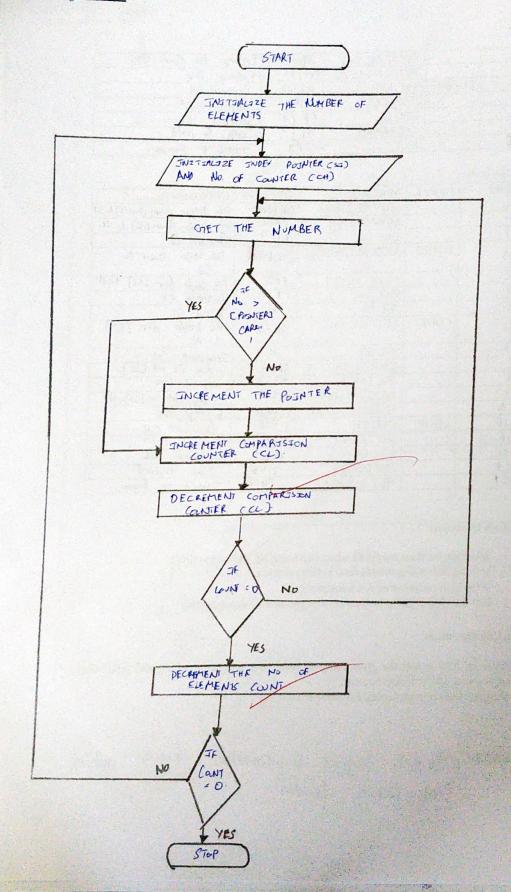
3.5 Pre-Lab Questions:

- What are the flags modified while executing XCHG instruction? 1.
- List the addressing modes used in this program. 2.
- What is the purpose of AAA instruction? 3.
- List the type of jump instruction that are used in this program. 4.

3.6 Post-Lab Questions:

- 1. Write an ALP to sort the given array of 16-bit numbers in ascending and descending order using 8086 microprocessor.
- 2. Simulate the programs using emulator 8086.

Verified program to temportrate tecision making ont looping operation Result:



Pre- hob

Soln

What are the glags motified while executing XCHC instruction? In general, each time the processor executs on instruction the Orago one albed to reflect the result but while executing XCHG intraction, no plan is modified

2 List the addressing motes used in this program?

Soln

The authorsis modes used in this program is register indirect mode (NOV Ax, CSJ]), indexed makes [DFG 5], and register modes.

What is the of AAA instruction?

Isla.

AAA instruction is only useful when it bollows on AAA instructions B? Whoer somes a gik result at the register that add 2

Soln.

hist the type of jump instruction that are used in this program. Those are 3 type of jump instructors used in the program

O JC - Jump carry

- (2) JAC Jump Ne Carry
- (3) JNZ Jump No Zero.

Post - Lat

1. Write on ALP to got the given array of 16 tot now assends and descends order while using 2016 Micro process.

Seln.

Ascending. MOV SI, 1200H MOV CL, [SI] DEC CL Rooks MOV SI, 1200H NOV CH, [SI] DEC CH INC SI MOV AX, [S]; Lop 2 INC SI INC SI CMP AX, [S] Il left 1 XCHG AX, [SI] XC46 [SJ-2], AX log 1 DEC CH INZ Rop 2 DEC CL INZ Sop 3. HLT.

Descending MON SJ, 1200 H MOV CL, [53] DEC CL toop 3; MOV SJ , 1200H. MOY CH, [S] DEC CH INC SI MOV AX, CSIJ; gop2 INC SJ JING SJ. CMP AX , CS3). INC Soop 1 XCHG AX, [SJ] loop 1; DEC CIV INZ Roops DEC CL INZ ROOK 3 HLT.