

# UNIT - I

## DOUBLE AND TRIPLE INTEGRALS.

### Steps to Find

#### Limits of

#### Integration:

1. Sketch the region and label the bounding curves.
2. Imagine a vertical line (L) cutting through R. Mark the y-values where L enters and leaves. These are Y Limits.

3. Choose x-limits that include all the vertical lines through R.

#### Change in Order of Integration:

1. Identify the region of Integration.
2. Identify the Constant and Variable Limits.
3. Switch Variable  $\rightarrow$  Constant  
Constant  $\rightarrow$  Variable.
4. Use 'Steps to Find Limits of integration' to find new limits.

Eg:

Initially.



$$\iint_R f(x,y) dx dy$$



$$\int_{x_1}^{x_2} \int_{f(x_1)}^{f(x_2)} f(x,y) dy dx$$



$$\int_{y_1}^{y_2} \int_{f(y_1)}^{f(y_2)} f(x,y) dx dy$$

In CIO

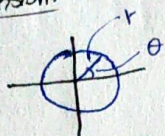


$$\iint_R f(x,y) dx dy$$



$$\int_{x_1}^{x_2} \int_{f(x_1)}^{f(x_2)} f(x,y) dy dx$$

### Double Integral on Polar Coordinates and Conversion.



Area is given by

$$\iint_R f(r,\theta) dr d\theta$$

Note:

$$x = r \cos \theta$$

$$y = r \sin \theta$$

$$x^2 + y^2 = r^2$$

$$dx dy = r dr d\theta$$



### DOUBLE AND TRIPLE INTEGRAL



Note: Double and Triple Integration more or less are the same process.

Area by Double Int.

$$A = \int_{y_1}^{y_2} \int_{x_1}^{x_2} dx dy$$

Area by Triple Int.

$$N = \int_{z_1}^{z_2} \int_{y_1}^{y_2} \int_{x_1}^{x_2} dx dy dz$$

### CARTOID:

$$r = a(1 - \cos \theta)$$

### TETRAHEDRON:

$$\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$$

$$V = \frac{abc}{6}$$

### DOUBLE INTEGRAL

$$\iint_R f(x,y) dA = \int \int f(x,y) dx dy$$

C Integration here is similar to partial diff. First it is integrated w.r.t x, keeping y constant, then integrated w.r.t y (keeping x const.).

#### Properties:

$$1. \iint_R k f(x,y) dA = k \iint_R f(x,y) dA$$

$$2. \iint_R (f \pm g) dA = \iint_R f dA \pm \iint_R g dA$$

$$3. \iint_R f(x,y) dA \geq 0$$

if,  $f(x,y) \geq 0$ .

$$4. \iint_R f(x,y) dA \geq \iint_R g(x,y) dA$$

if,  $f(x,y) \geq g(x,y)$ .

5.  $R_1, R_2 \rightarrow$  non overlapping regions.  
then,

$$\iint_R f(x,y) dA = \iint_{R_1} f(x,y) dA + \iint_{R_2} f(x,y) dA$$

$$\sqrt{a^2 - x^2}$$

$$= \frac{x}{2} \sqrt{a^2 - x^2} + \frac{a^2}{2} \sin^{-1} \left( \frac{x}{a} \right)$$





# UNIT - 2 VECTOR CALCULUS

## • Gradient of Scalar function

$\phi(x, y, z) \rightarrow$  Scalar fun.

$$\text{grad } \phi = \nabla \phi = \hat{i} \frac{d\phi}{dx} + \hat{j} \frac{d\phi}{dy} + \hat{k} \frac{d\phi}{dz}$$

## • Divergence of Vector function

$\vec{F}(x, y, z) \rightarrow$  ~~Scalar~~ Vector fun.

$$\text{div } \vec{F} = \nabla \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

Also if  $\text{div } \vec{F} = 0$   
then it is Solenoidal!

## • Directional Derivation

$$\frac{\nabla \phi \cdot \vec{a}}{|\vec{a}|} \rightarrow \text{direction vector}$$

## • Unit Normal Vector

$$\hat{n} = \frac{\nabla \phi}{|\nabla \phi|} \rightarrow \text{grad } \phi$$

## • Angle b/w two Surfaces

$$\cos \theta = \frac{\nabla \phi_1 \cdot \nabla \phi_2}{|\nabla \phi_1| |\nabla \phi_2|}$$

## • Gauss Divergence Theorem

$$\iint_S \vec{F} \cdot \hat{n} \, ds = \iiint_V \nabla \cdot \vec{F} \, dv$$

$\downarrow$   
div V

• Convergence is  
irrigally ( $\text{div } \vec{F} < 0$ )

## • Curl of Vector function

$\vec{F}(x, y, z) \rightarrow$  Vector fun.

$$\text{Curl } \vec{F} = \nabla \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix}$$

If  $\text{Curl } \vec{F} = 0$   
then it is Irrational!

## • Vector Differential Operator (DEL) ( $\nabla$ )

$$\nabla = \hat{i} \frac{d}{dx} + \hat{j} \frac{d}{dy} + \hat{k} \frac{d}{dz}$$

(partial derivatives)

## • Laplace operator ( $\nabla^2$ )

$$\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} = \nabla \cdot \nabla$$

## • Additional Identities

If Vector is conservative

$$\rightarrow \nabla \times \vec{F} = 0$$

$$\rightarrow \nabla \times (\nabla \phi) = 0$$

$$\rightarrow \nabla \cdot (\nabla \times \vec{F}) = 0$$

# VECTOR CALCULUS

## • Green's Theorem

$$\oint_C P dx + Q dy = \iint_R \left[ \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right] dx dy$$

## • Stokes Theorem (Circulation)

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \text{Curl } \vec{F} \cdot \hat{n} \, ds$$

## • Area by Green's Theorem

$$\frac{1}{2} \oint_C x dy - y dx$$

## • Line Integrals

$$\int_C \vec{F} \cdot d\vec{r} \quad \text{Curve parametric}$$

$x = x(t), y = y(t), z = z(t)$

where

$$d\vec{r} = \vec{i} dx + \vec{j} dy + \vec{k} dz$$

1. Substitute  $dx$  and  $dy$  and dot product
2. Substitute the parametric form
3. Integrate

## • Surface Integrals

$$\iint_S \vec{F} \cdot \hat{n} \, ds = \iint_R \frac{\vec{F} \cdot \hat{n}}{|\hat{n} \cdot \hat{k}|} \, dx dy$$

$$\iint_S \vec{F} \cdot d\vec{s} = \iint_D \vec{F}(x(u, v)) \|\vec{r}_u \times \vec{r}_v\| \, du dv$$



# UNIT - 3

## LAPLACE TRANSFORMATION

### • Important Results

$$\rightarrow L[e^{at}] = \frac{1}{s-a} \quad s > a$$

$$\rightarrow L[e^{-at}] = \frac{1}{s+a} \quad s > -a$$

$$\rightarrow L[\cos at] = \frac{s}{s^2 + a^2}$$

$$\rightarrow L[\sin at] = \frac{a}{s^2 + a^2}$$

$$\rightarrow L[\cosh at] = \frac{s}{s^2 - a^2}$$

$$\rightarrow L[\sinh at] = \frac{a}{s^2 - a^2}$$

$$\rightarrow L[1] = \frac{1}{s}$$

$$\rightarrow L[t^n] = \frac{n!}{s^{n+1}} \quad \text{or} \quad \frac{n!}{s^{n+1}} \quad \text{Gamma Function}$$

$$(T^{n+1}) = n! T^n$$

### • Laplace Transform of Derivatives

$$1. L[f'(t)] = sL[f(t)] - f(0)$$

$$2. L[f''(t)] = s^2L[f(t)] - sf(0) - f'(0)$$

$$3. L[f'''(t)] = s^3L[f(t)] - s^2f(0) - sf'(0) - f''(0)$$

### • First Shifting Theorem

$$L[f(t)] = F(s)$$

then,

$$L[e^{at}f(t)] = F(s-a)$$

$$L[e^{-at}f(t)] = F(s+a)$$

### • Laplace Transform of Integrals

$$F(s) = L[f(t)] = \int_0^\infty e^{-st} f(t) dt, t > 0$$

### • Second Shifting Theorem

$$\text{If } L[f(t)] = F(s)$$

$$\text{and } G(t) = \begin{cases} f(t-a), & t > a \\ 0, & t < a \end{cases}$$

then,

$$L[G(t)] = e^{-as} F(s) \quad (\text{or})$$

$$L[f(t-a)] = e^{-as} F(s)$$

## LAPLACE TRANSFORMATION

### • For Piece wise Functions

L of Piecewise func.

$$f(T+t) = f(t)$$

Period  $T > 0$

$$\text{Eg } f(t + 2\pi) = \sin t = f(t)$$

$$L[f(t)] = \frac{1}{1 - e^{-Ts}} \int_0^T e^{-st} f(t) dt$$

### • Inverse Laplace

$$\rightarrow L^{-1} \left[ \frac{1}{(s^2 - a^2)} \right] = t e^{at}$$

$$\rightarrow L^{-1} \left[ \frac{n!}{s^{n+1}} \right] = t^n$$

### • Change of Scale of Property

$$\text{If } L[f(t)] = F(s)$$

then,

$$L[f(at)] = \frac{1}{a} F\left(\frac{s}{a}\right)$$

### • Initial Value Theorem

$$\text{If } L[f(t)] = F(s)$$

$$\lim_{t \rightarrow 0} f(t) = \lim_{s \rightarrow \infty} s F(s)$$

### • Final Value Theorem

$$\lim_{t \rightarrow \infty} f(t) = \lim_{s \rightarrow 0} s F(s)$$

### • When t is multiplied to f(t)

$$L[t f(t)] = -\frac{d}{ds} F(s)$$

$$L[t^n f(t)] = (-1)^n \frac{d^n}{ds^n} F(s)$$

### • When t is divided to f(t)

given that  $\lim_{t \rightarrow 0} \frac{f(t)}{t}$  exists.

then

$$L\left[\frac{f(t)}{t}\right] = \int_s^\infty F(s) ds$$



### • First Shifting Property:

$$L^{-1}[F(s+a)] = e^{-at} L^{-1}[F(s)]$$

### • Inverse Laplace of Derivatives and Integrals

$$L^{-1}[F'(s)] = -t(L^{-1}[F(s)])$$

$$L^{-1}[sF(s)] = \frac{d}{dt} L^{-1}[F(s)]$$

$$L^{-1}\left[\frac{F(s)}{s}\right] = \int_0^t L^{-1}[F(s)] \cdot dt$$

$$L^{-1}[e^{-as}F(s)] = L^{-1}[F(s)]_{t \rightarrow t-a} H(t-a) \\ = f(t-a) H(t-a)$$

### • Method of Partial Fractions:

$$1. \frac{f_n}{s(s+a)} = \frac{A}{s} + \frac{B}{s+a}$$

$$2. \frac{f_n}{s(s^2+2as+a^2)} = \frac{A}{s} + \frac{Bs+C}{(s^2+2as+a^2)}$$

$$3. \frac{f_n}{(s+a)^3} = \frac{A}{(s+a)} + \frac{B}{(s+a)^2} + \frac{C}{(s+a)^3}$$

$$4. \frac{f_n}{(s^2+a^2)^2(s^2+b^2)} = \frac{As+B}{(s^2+a^2)} + \frac{Cs+D}{(s^2+a^2)^2} + \frac{Fs+F}{(s^2+b^2)}$$

### • Convolution:

Convolution of  $f(t)$  and  $g(t)$  is defined as

$$\int_0^t f(u)g(t-u) \cdot du$$

$$f(t) * g(t) = \int_0^t f(u)g(t-u) \cdot du$$

### Convolution Theorem:

$$\rightarrow L[f(t) * g(t)] \\ = L[f(t)] \cdot L[g(t)]$$

$$\rightarrow f(t) * g(t) \\ = L^{-1}[F(s)] \cdot L^{-1}[G(s)]$$

$$\rightarrow L^{-1}[F(s)] * L^{-1}[G(s)] \\ = L^{-1}[F(s)] \cdot L^{-1}[G(s)]$$

$$L^{-1}[1] = \delta(t)$$