

18MAB203T-Probability and Stochastic Processes

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Random Variables

A Random Variable is a rule that assigns a real number to every outcome of the random experiment.

Random Process

A random process is a collection of random variables $\{X(s,t)\}$ that are functions of a real variable, namely time 't' where $s \in S$ (Sample space) and $t \in T$ (Parameter set or index set).

Classification of Random Process

- **Discrete Random Sequence**

If both S and T are discrete then the random process is called Discrete Random sequence.

Eg: No of books in Library at opening time.

- **Continuous Random Sequence**

If S is continuous and T is discrete, then the random process is called Continuous Random sequence.

Eg: Quantity of petrol in the petrol bank at opening time.

- **Discrete Random Process**

If S is discrete and T is continuous then the random process is called Discrete Random Process.

Eg: No of phone calls receiving in $(0, t)$.

- **Continuous Random Process**

If both S and T are continuous then the random process is called Continuous Random Process.

Eg: Stirring sugar in coffee.

Strict Sense Stationary Process

A random process is called a Stationary Process or Strictly Stationary Process or Strict Sense Stationary Process if all its finite dimensional distributions are invariant under transition of time parameter.

Example

Example1

If the random process $X(t)$ takes the value -1 with probability $\frac{1}{3}$ and takes the value 1 with probability $\frac{2}{3}$, Find whether $X(t)$ is a stationaery process or not.

Solution.

Given

$X(t)=n$	-1	1
p_n	$\frac{1}{3}$	$\frac{2}{3}$

To prove $X(t)$ is a SSS process (i.e.)

- 1 $E[X(t)] = \text{constant}$
- 2 $\text{Var}[X(t)] = \text{constant}$

Example

1

$$\begin{aligned} E[X(t)] &= \sum_{n=-1}^1 np_n \\ &= (-1)\left(\frac{1}{3}\right) + (1)\left(\frac{2}{3}\right) = \frac{-1}{3} + \frac{2}{3} = \frac{1}{3} = \text{constant} \end{aligned}$$

2

$$\begin{aligned} E[X^2(t)] &= \sum_{n=-1}^1 n^2 p_n \\ &= (-1)^2\left(\frac{1}{3}\right) + (1)^2\left(\frac{2}{3}\right) = \frac{1}{3} + \frac{2}{3} = 1 \\ \text{Var}[X(t)] &= E[X^2(t)] - [E[X(t)]]^2 \\ &= 1 - \left(\frac{1}{3}\right)^2 = 1 - \frac{1}{9} = \frac{8}{9} = \text{constant} \end{aligned}$$

Hence, $X(t)$ is a SSS process.

Example

Example2

Show that, If the process $X(t) = a\cos\omega t + b\sin\omega t$ is SSS, where a and b are independent random variables, then they are normal.

Solution.

Given $X(t) = a\cos\omega t + b\sin\omega t$

$$E[a] = E[b] = 0 \quad \text{and} \quad (1)$$

$$E[ab] = E[a]E[b] \quad \text{and} \quad (2)$$

$$E[a^2] = E[b^2] = \sigma^2 \quad (3)$$

1

$$\begin{aligned}
 E[X(t)] &= E[acos\omega t + bsin\omega t] \\
 &= E[a]cos\omega t + E[b]sin\omega t \\
 &= (0)cos\omega t + (0)sin\omega t = 0 \\
 &= \text{constant}
 \end{aligned}$$

2

$$\begin{aligned}
 E[X^2(t)] &= E[(acos\omega t + bsin\omega t)^2] \\
 &= E[a^2cos^2\omega t + b^2sin^2\omega t + 2abcos\omega tsin\omega t] \\
 &= E[a^2]cos^2\omega t + E[b^2]sin^2\omega t + 2E[ab]cos\omega tsin\omega t \\
 &= \sigma^2cos^2\omega t + \sigma^2sin^2\omega t + 0 \quad \text{by (2) and (3)} \\
 &= \sigma^2[cos^2\omega t + sin^2\omega t] = \sigma^2(1) = \sigma^2 \\
 Var[X(t)] &= E[X^2(t)] - [E[X(t)]]^2 \\
 &= \sigma^2 - 0 = \sigma^2 = \text{constant}
 \end{aligned}$$

Hence, $X(t)$ is a SSS process.

Wide Sense Stationary Process

A random process is called a wide sense stationary process or weakly stationary process or covariance stationary process if it satisfies the conditions

- 1 $E[X(t)] = \text{constant}.$
- 2 $R(t_1, t_2) = E[X(t_1)X(t_2)] = R(t_1 - t_2)$

Example

Example1

The process $\{X(t)\}$, whose probability distribution under certain conditions is given by

$$\begin{aligned} P\{X(t) = n\} &= \frac{(at)^{n-1}}{(1+at)^{n+1}}, n = 1, 2, 3, \dots \\ &= \frac{at}{1+at}, n = 0 \end{aligned}$$

Show that it is not stationary.

The probability distribution of $\{X(t)\}$ is

$X(t)=n:$	0	1	2	3	...
$P_n :$	$\frac{at}{1+at}$	$\frac{1}{(1+at)^2}$	$\frac{at}{(1+at)^3}$	$\frac{(at)^2}{(1+at)^4}$...

Example

$$\begin{aligned}E\{X(t)\} &= \sum_{n=0}^{\infty} np_n \\&= \frac{1}{(1+at)^2} + \frac{2at}{(1+at)^3} + \frac{3(at)^2}{(1+at)^4} + \dots \\&= \frac{1}{(1+at)^2} \{1 + 2\alpha + 3\alpha^2 + \dots\}, \text{ where } \alpha = \frac{at}{1+at} \\&= \frac{1}{(1+at)^2} (1 - \alpha^{-2}) = \frac{1}{(1+at)^2} (1+at)^2 = 1\end{aligned}$$

$$\begin{aligned}E\{X^2(t)\} &= \sum_{n=0}^{\infty} n^2 p_n = \sum_{n=1}^{\infty} n^2 \frac{(at)^{n-1}}{(1+at)^{n+1}} \\&= \frac{1}{(1+at)^2} \left[\sum_{n=1}^{\infty} n(n+1) \left(\frac{at}{1+at}\right)^{n-1} - \sum_{n=1}^{\infty} n \left(\frac{at}{1+at}\right)^{n-1} \right]\end{aligned}$$

Example

$$= \frac{1}{(1+at)^2} \left[\frac{2}{\left(1 - \frac{at}{1+at}\right)^3} - \frac{1}{\left(1 - \frac{at}{1+at}\right)^2} \right]$$

$$= 1 + 2at$$

$$\text{Var}\{X(t)\} = 2at$$

If $\{X(t)\}$ is a stationary process, $E\{X(t)\}$ and $\text{Var}\{X(t)\}$ are constants. Since $\text{Var}\{X(t)\}$ is a function of t , the given process is not stationary.

Example

Example2

Show that the random process $X(t) = A\cos(\omega_0 t + \theta)$ is wide sense stationary, if a and ω_0 are constants and θ is a uniformly distributed RV in $(0, 2\pi)$

Since θ is uniformly distributed RV in $(0, 2\pi)$

$$\begin{aligned}f_0(\theta) &= \frac{1}{2\pi}, 0 \leq \theta \leq 2\pi \\E\{X(t)\} &= E\{A\cos(\omega_0 t + \theta)\} \\&= A \int_0^{2\pi} \frac{1}{2\pi} \cos(\omega_0 t + \theta) d\theta \\&= \frac{A}{2\pi} \{ \sin(2\pi + \omega_0 t) - \sin\omega_0 t \} \\&= 0 = a \text{ constant}\end{aligned}$$

Example

$$\begin{aligned}E\{X(t_1)\}X(t_2)\} &= E\{A^2 \cos(\omega_0 t_1 + \theta) \times \cos(\omega_0 t_2 + \theta)\} \\&= \frac{A^2}{2} E\{\cos[(t_1 + t_2)\omega_0 + 2\theta] \\&\quad + \cos(t_1 - t_2)\omega_0\} \\&= \frac{A^2}{2} \int_0^{2\pi} \frac{1}{2\pi} \{\cos[(t_1 + t_2)\omega_0 + 2\theta] \\&\quad + \cos(t_1 - t_2)\omega_0\} d\theta \\&= \frac{A^2}{2} \cos(t_1 - t_2)\omega_0 \\R(t_1, t_2) &= \text{a function of } (t_1 - t_2)\end{aligned}$$

Therefore, $\{X(t)\}$ is a WSS process.

Example

Example3

Given a RV Y with characteristic function

$$\begin{aligned}\phi(\omega) &= E\{e^{i\omega Y}\} \\ &= E\{\cos\omega Y + i\sin\omega Y\}\end{aligned}$$

and a random process defined by $X(t) = \cos(\lambda t + Y)$, show that $\{X(t)\}$ is stationary in the wide sense

$$\begin{aligned}\text{If } \phi(1) &= \phi(2) = 0 \\ E\{X(t)\} &= E\{\cos(\lambda t + Y)\} \\ &= \cos\lambda t \times E(\cos Y) - \sin\lambda t \times \cos E(\sin Y)\end{aligned}\tag{1}$$

Example

Given $\phi(1) = 0$

$$(i, e.) \quad E\{\cos Y + i \sin Y\} = 0 \quad (2)$$

$$\therefore E(\cos Y) = 0 = E(\sin Y)$$

$$\text{Using (2) in (1), we get } E\{X(t)\} = 0 \quad (3)$$

$$\begin{aligned} E\{X(t_1) \times X(t_2)\} &= E\{\cos(\lambda t_1 + Y) \times \cos(\lambda t_2 + Y)\} \\ &= \cos \lambda t_1 \cos \lambda t_2 E(\cos^2 Y) + \sin \lambda t_1 \sin \lambda t_2 E(\sin^2 Y) \\ &\quad - \sin \lambda(t_1 + t_2) E(\sin Y \cos Y) \\ &= \cos \lambda t_1 \cos \lambda t_2 E\left(\frac{1}{2} + \frac{1}{2} \cos 2Y\right) \\ &\quad + \sin \lambda t_1 \sin \lambda t_2 E\left(\frac{1}{2} + \frac{1}{2} \cos 2Y\right) \\ &\quad - \frac{1}{2} \sin \lambda(t_1 + t_2) E(\sin 2Y) \end{aligned} \quad (4)$$

Example

Given $\phi(2) = 0$

$$(i, e.) \quad E\{\cos 2Y + i \sin 2Y\} = 0 \quad (5)$$

$$\therefore E(\cos 2Y) = 0 = E(\sin 2Y)$$

Using (5) in (4), we get

$$\begin{aligned} R(t_1, t_2) &= E\{X(t_1) \times X(t_2)\} \\ &= \frac{1}{2} \{\cos \lambda t_1 \cos \lambda t_2 + \sin \lambda t_1 \sin \lambda t_2\} \\ &= \frac{1}{2} \cos \lambda(t_1 - t_2) \end{aligned} \quad (6)$$

From (3) and (6) it follows that $\{X(t)\}$ is a WSS process.

Example

Example4

Show that the process $X(t) = A\cos\lambda t + B\sin\lambda t$ (where A and B are RV) is wide sense stationary, if

- 1 $E(A)=E(B)=0$
- 2 $E(A^2) = E(B^2)$
- 3 $E(AB)=0$

$$E\{X(t)\} = \cos\lambda t \times E(A) + \sin\lambda t \times E(B) \quad (1)$$

If $\{X(t)\}$ is to be a WSS process. $E\{X(t)\}$ must be a constant (i.e, independent of t).

In 1 if $E(A)$ and $E(B)$ are any constants other than zero, $E\{X(t)\}$ will be a function of t.

$$\therefore E(A) = E(B) = 0$$

Example

$$\begin{aligned} R(t_1, t_2) &= E\{X(t_1) \times X(t_2)\} \\ &= E\{(A\cos\lambda t_1 + B\sin\lambda t_1)(A\cos\lambda t_2 + B\sin\lambda t_2)\} \\ &= E(A_2)\cos\lambda t_1 \cos\lambda t_2 + E(B_2)\sin\lambda t_1 \sin\lambda t_2 \\ &\quad + E(AB)\sin\lambda(t_1 + t_2) \end{aligned} \tag{2}$$

If $\{X(t)\}$ is to be a WS process, $R(t_1, t_2)$ must be a function of $(t_1 - t_2)$.

\therefore In 2, $E(AB)=0$ and $E(A^2) = E(B^2) = k$

Then $R(t_1, t_2) = k\cos\lambda(t_1 - t_2)$

Example

Example5

If $X(t) = Y\cos\omega t + Z\sin\omega t$, where Y and Z are two independent normal RV with $E(Y) = E(Z) = 0$, $E(Y^2) = E(Z^2) = \sigma^2$ and ω is a constant, prove that $\{X(t)\}$ is a SSS process of order 2.

Since $\{X(t)\}$ is a linear combination of Y and Z , that are independent, $\{X(t)\}$ follows a normal distribution with

$$\begin{aligned}E\{X(t)\} &= \cos\omega t E(Y) + \sin\omega t E(Z) = 0 \\ \text{and } \text{Var}\{X(t)\} &= \cos^2\omega t E(Y^2) + \sin^2\omega t E(Z^2) \\ &= \sigma^2\end{aligned}$$

Since $\{X(t_1)\}$ and $\{X(t_2)\}$ are each $N(0, \sigma)$, $X(t_1)$ and $X(t_2)$ are jointly normal with the joint pdf given by

Example

$$f(x_1, x_2, t_1, t_2) = \frac{1}{2\pi\sigma^2\sqrt{1-r^2}} \exp \left\{ \frac{-(x_1^2 - 2rx_1x_2 + x_2^2)}{2(1-r^2)\sigma^2} \right\}; -\infty < x_1, x_2 < \infty \quad (1)$$

In (1)

$r = \text{correlation coefficient between } \{X(t_1)\} \text{ and } \{X(t_2)\}$

$$\begin{aligned} &= \frac{C(t_1, t_2)}{\sqrt{\text{Var}\{X(t_1)\} \times \text{Var}\{X(t_2)\}}} \\ &= \frac{1}{\sigma^2} E\{X(t_1)\} \times \{X(t_2)\} \\ &= \frac{1}{\sigma^2} E[(Y\cos\omega t_1 + Z\sin\omega t_1)(Y\cos\omega t_2 + Z\sin\omega t_2)] \\ &= \frac{1}{\sigma^2} [E(Y^2)\cos\omega t_1\cos\omega t_2 + E(Z^2)\sin\omega t_1\sin\omega t_2] \end{aligned}$$

[since $E(YZ)=0$ as Y and Z are independent]

Example

Now, the joint pdf of $X(t_1 + h)$ and $X(t_2 + h)$ is given by a similar expressions as in 1, where

$$\begin{aligned} r &= \cos\omega\{(t_1 + h) - (t_2 + h)\} \\ &= \cos\omega(t_1 - t_2) \end{aligned}$$

Thus, the joint pdf of $\{X(t_1), X(t_2)\}$ and $\{X(t_1 + h), X(t_2 + h)\}$ are the same.

Therefore, $\{X(t_1)\}$ is a SSS process of order 2.

Example

Example6

Two random process $\{X(t)\}$ and $\{Y(t)\}$ are defined by $A\cos(\omega_0 t + B\sin\omega_0 t)$ and $B\cos(\omega_0 t - A\sin\omega_0 t)$. Show that $\{X(t)\}$ and $\{Y(t)\}$ are jointly wide-sense stationary, if A and B are uncorrelated RVs with zero means and the same variances and ω_0 is a constant.

$$E(A) = E(B) = 0; \text{Var}(A) = \text{Var}(B)$$
$$E(A^2) = E(B^2)$$

Since A and B are uncorrelated, $E(AB)=0$.

Therefore, by Example4, $\{X(t)\}$ and $\{Y(t)\}$ are individually WSS process. Now,

$$R(t_1, t_2) = E\{X(t_1) \times X(t_2)\}$$
$$= E\{(A\cos\omega_0 t_1 + B\sin\omega_0 t_1)(B\cos\omega_0 t_2 - A\sin\omega_0 t_2)\}$$

Example

$$\begin{aligned} &= E(B^2)\sin\omega_0 t_1 \cos\omega_0 t_2 - E(A^2)\cos\omega_0 t_1 \sin\omega_0 t_2 \\ &= \sigma^2 \sin\omega_0(t_1, t_2) \quad [\text{assuming } E(A^2) = E(B^2) = \sigma^2] \\ &= \text{a function of } (t_1 - t_2) \end{aligned}$$

Autocorrelation Function

If the process $\{X(t)\}$ is stationary either in the strict sense or in the wide sense, $E\{X(t)X(t-\tau)\}$ is a function of τ denoted by $R_{xx}(\tau)$ or $R(\tau)$ or $R_x(\tau)$. This function $R(\tau)$ is called Autocorrelation function of the process $\{X(t)\}$.

- ❶ **$R(t)$ is an even function of τ .**

Proof.

$$\begin{aligned}R(\tau) &= EX(t) \times X(t - \tau) \\R(-\tau) &= EX(t) \times X(t - \tau) \\&= EX(t + \tau) \times X(t) \\&= R(\tau)\end{aligned}$$

- ❷ **$R(\tau)$ is maximum at $\tau=0$ (i.e) $|R(\tau)| \leq R(0)$.**

Proof.

The Cauchy-Schwarz inequality is

$$E(XY)^2 \leq E(X)^2 \times E(Y)^2$$

Put $X=X(t)$ and $Y=X(t-\tau)$

Then

$$\begin{aligned} [E\{X(t) \times X(t - \tau)\}]^2 &\leq E\{X^2(t)X^2(t - \tau)\} \\ \{R(\tau)\}^2 &\leq [E\{X^2(t)\}]^2 \end{aligned}$$

[Since $E\{X(t)\}$ and $\{X(t)\}$ are constant for a stationary process]

$$(i, e.) \quad R(\tau)^2 \leq R(0)^2$$

Taking square root on both sides

$$|R(\tau)| \leq R(0)$$

[Since $R(0)=E\{X^2(t)\}$ is positive]

- 3 **If the autocorrelation function $R(t)$ of a real stationary process $\{X(t)\}$ is continuous at $\tau = 0$, it is continuous at every other point.**

Properties

Proof.

Consider

$$\begin{aligned} [E\{X(t) - X(t - \tau)\}]^2 &= E\{X^2(t)\} + E\{X^2(t - \tau)\} - 2E\{X(t) \times X(t - \tau)\} \\ &= R(0) + R(0) - 2R(\tau) \\ &= 2[R(0) - R(\tau)] \end{aligned} \tag{7}$$

Since $R(\tau)$ is continuous at $\tau = 0$, $\lim_{\tau \rightarrow 0} R(\tau) = R(0)$

(i.e.) $\lim_{\tau \rightarrow 0} \{R.S.of 7\} = 0$

$\therefore \lim_{\tau \rightarrow 0} \{L.S.of 7\} = 0$

$$\lim_{\tau \rightarrow 0} \{X(t - \tau)\} = X(t) \tag{8}$$

(i.e.) $X(t)$ is continuous for all t

Consider $R(\tau + h) - R(\tau)$

$$= E[\{X(t) \times X\{t - (\tau + h)\}\}] - E\{X(t) \times X(t - \tau)\}$$

$$= E[X(t)\{X(t - \tau - h) - X(t - \tau)\}] \quad (9)$$

Now, $\lim_{h \rightarrow 0} [X\{(t - \tau) - h\} - X(t - \tau)] = 0$, by 8

$$\therefore \lim_{h \rightarrow 0} \{R.S.of 9\} = 0$$

$$\therefore \lim_{h \rightarrow 0} \{L.S.of 9\} = 0$$

$$(i, e.) \lim_{h \rightarrow 0} \{R(\tau + h)\} = R(\tau)$$

(i.e.) $R(\tau)$ is continuous for all τ

- ④ **If $R(\tau)$ is the autocorrelation function of a stationary process $X(t)$ with no periodic component, then $\lim_{\tau \rightarrow \infty} R(\tau) = \mu_x^2$, provided the limit exists.**

Proof.

$$R(\tau) = E\{X(t) \times X(t - \tau)\}$$

When τ is large, $X(t)$ and $X(t - \tau)$ are two sample functions of the process $\{X(t)\}$ observed at a very long interval of time.

Therefore, $X(t)$ and $X(t - \tau)$ tend to become independent [$X(t)$ and $X(t - \tau)$ may be dependent, when $X(t)$ contains a periodic component, which is not true].

$$\begin{aligned}\therefore \lim_{\tau \rightarrow \infty} R(\tau) &= E\{X(t) \times X(t - \tau)\} \\ &= \mu_x^2 \quad [\text{Since } E\{X(t)\} \text{ is a constant}]\end{aligned}$$

$$i, e. \quad \mu_x = \sqrt{\lim_{\tau \rightarrow \infty} R(\tau)}$$

Example

Example1

Check whether the following functions are valid autocorrelation functions

- ① $R_{xx}(\tau) = \frac{25\tau^2}{4 + 5\tau^2}$
- ② $R_{xx}(\tau) = \tau^3 + \tau^2$
- ③ $R_{xx}(\tau) = \cos(\tau) + \frac{|\tau|}{T}$

①

$$\begin{aligned} R_{xx}(\tau) &= \frac{25\tau^2}{4 + 5\tau^2} \\ R_{xx}(-\tau) &= \frac{25 - \tau^2}{4 + 5 - \tau^2} = \frac{25\tau^2}{4 + 5\tau^2} \\ R_{xx}(\tau) &= R_{xx}(-\tau) \end{aligned}$$

$\therefore R_{xx}(\tau)$ is a autocorrelation function.

Example

2

$$R_{xx}(\tau) = \tau^3 + \tau^2$$

$$R_{xx}(-\tau) = -\tau^3 + -\tau^2 = -\tau^3 + \tau^2$$

$$R_{xx}(\tau) \neq R_{xx}(-\tau)$$

$\therefore R_{xx}(\tau)$ is not a autocorrelation function.

3

$$R_{xx}(\tau) = \cos(\tau) + \frac{|\tau|}{T}$$

$$R_{xx}(-\tau) = \cos(-\tau) + \frac{|-\tau|}{T}$$

$$= \cos(\tau) + \frac{|\tau|}{T}$$

$$R_{xx}(\tau) = R_{xx}(-\tau)$$

$\therefore R_{xx}(\tau)$ is a autocorrelation function.

Cross-Correlation Function

If the processes $\{X(t)\}$ and $\{Y(t)\}$ are jointly wide-sense stationary, then $E\{X(t) \times X(t - \tau)\}$ is a function of τ , denoted by $R_{xy}(\tau)$. This function is $R_{xy}(\tau)$ is called the cross-correlation function of the processes $\{X(t)\}$ and $\{Y(t)\}$.

Properties

① $R_{yx}(\tau) = R_{xy}(-\tau)$

Proof.

$$R_{xy}(\tau) = E[X(t)Y(t + \tau)]$$

$$R_{xy}(-\tau) = E[X(t)Y(t - \tau)]$$

substitutet $t_1 = t - \tau$

$$= E[Y(t_1)X(t_1 + \tau)]$$

$$= R_{yx}(\tau)$$

② $|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) \times R_{yy}(0)}$

Proof. For any real number α , we know that

$$E[\alpha X(t) + Y(t + \tau)]^2 \geq 0$$

$$E[\alpha^2 X^2(t) + Y^2(t + \tau) + 2\alpha X(t)Y(t + \tau)] \geq 0$$

$$E[\alpha^2 X^2(t)] + E[Y^2(t + \tau)] + E[2\alpha X(t)Y(t + \tau)] \geq 0$$

$$\alpha^2 E[X^2(t)] + E[Y^2(t + \tau)] + 2\alpha E[X(t)Y(t + \tau)] \geq 0$$

Properties

Since $\{X(t)\}$ and $\{Y(t)\}$ are jointly WSS, each is a WSS process
Hence the second order moments are constants. But $E(X^2(t)) = R_{xx}(0)$
by the property of autocorrelation function and $E(Y^2(t + \tau)) = R_{yy}(0)$.
 $\alpha^2 R_{xx}(0) + R_{yy}(0) + 2\alpha R_{xy}(\tau) \geq 0 \quad \forall \alpha$
Since $R_{xx}(0) > 0$ and α is any real number, the discriminant is ≤ 0 .

$$4(R_{xy}(\tau))^2 - 4R_{xx}(0)R_{yy}(0) \leq 0$$

$$(R_{xy}(\tau))^2 - R_{xx}(0)R_{yy}(0) \leq 0$$

$$|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0)R_{yy}(0)}$$

3 $|R_{xy}(\tau)| \leq \frac{1}{2} \{R_{xx}(0) + R_{yy}(0)\}$

Proof.

We know that $R_{xx}(0)$ and $R_{yy}(0)$ are positive numbers so their

$$\frac{A.M \geq G.M}{\frac{R_{xx}(0) + R_{yy}(0)}{2}} \geq \sqrt{R_{xx}(0)R_{yy}(0)}$$

By Property 2, $|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) + R_{yy}(0)}$

$$|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) + R_{yy}(0)} \leq \frac{R_{xx}(0) + R_{yy}(0)}{2}$$

$$|R_{xy}(\tau)| \leq \frac{R_{xx}(0) + R_{yy}(0)}{2}$$

4 If the process $\{X(t)\}$ and $\{Y(t)\}$ are orthogonal, then $R_{xy}(\tau) = 0$

5 If the process $\{X(t)\}$ and $\{Y(t)\}$ are independent, then

$$R_{xy}(\tau) = \mu_x \times \mu_y$$

Example

Example1

Consider 2 random processes $X(t) = 3\cos(\omega t + \theta)$ and $Y(t) = 2\cos(\omega t + \theta - \frac{\pi}{2})$ where θ is a random variable uniformly distributed in $(0, 2\pi)$ Prove that $|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0) + R_{yy}(0)}$

Solution.

$$\begin{aligned} R_{xx}(t, t + \tau) &= E[X(t)X(t + \tau)] \\ &= E[3\cos(\omega t + \theta).3\cos(\omega t + \theta)] \\ &= \frac{9}{2}E[\cos(2\omega t + 2\theta + \omega\tau) + \cos(-\omega\tau)] \\ &= \frac{9}{2}\int_0^{2\pi} E[\cos(2\omega t + 2\theta + \omega\tau)\frac{1}{2\pi}d\theta + \frac{9}{2}E(\cos\omega\tau)] \end{aligned}$$

Example

$$\begin{aligned} &= \frac{9}{4\pi} \left[\frac{\sin(2\omega t + 2\theta + \omega\tau)}{2} \right]_0^{2\pi} + \frac{9}{2} \cos\omega\tau \\ &= \frac{9}{4\pi} \left[\frac{\sin(2\omega t + \omega\tau) - \sin(2\omega t + \omega\tau)}{2} \right] + \frac{9}{2} \cos(\omega\tau) \\ &= \frac{9}{2} \cos(\omega\tau) \\ R_{xx}(\tau) &= \frac{9}{2} \cos\omega\tau \\ R_{xx}(0) &= \frac{9}{2} \end{aligned}$$

In a similar manner prove $R_{yy}(\tau) = 2\cos\omega\tau \implies R_{yy}(0) = 2$

$$\begin{aligned} R_{xy}(t, t + \tau) &= E[X(t)Y(t + \tau)] \\ &= E\left[3\cos(\omega t + \theta) \cdot 2\cos(\omega t + \omega\tau + \theta - \frac{\pi}{2})\right] \end{aligned}$$

Example

$$\begin{aligned} &= 3E[\sin(2\omega t + 2\theta + \omega\tau) + \sin(\omega\tau)] \\ &= 3 \int_0^{2\pi} \sin(2\omega t + 2\theta + \omega\tau) \frac{1}{2\pi} d\theta + 3E(\sin\omega\tau) \\ &= \frac{3}{2\pi} \left[\frac{\cos(2\omega t + 2\theta + \omega\tau)}{2} \right]_0^{2\pi} + 3\sin\omega\tau \\ &= \frac{-3}{2\pi} \left[\frac{\sin(2\omega t + \omega\tau + 4\pi) - \sin(2\omega t + \omega\tau)}{2} \right] + 3\sin(\omega\tau) \\ R_{xy}(\tau) &= 3\sin\omega\tau \end{aligned}$$

Hence $\{X(t)\}$ and $\{Y(t)\}$ are jointly WSS.

$$\text{Now } R_{xx}(0)R_{yy}(0) = 9 \implies \sqrt{R_{xx}(0)R_{yy}(0)} = 3$$

$$R_{xy}(\tau) = 3\sin\omega\tau \implies |R_{xy}(\tau)| = |3\sin\omega\tau| \leq 3$$

$$|R_{xy}(\tau)| \leq \sqrt{R_{xx}(0)R_{yy}(0)}$$

Example

Example2

Two random processes $\{X(t)\}$ and $\{Y(t)\}$ are defined by $X(t) = A\cos\omega t + B\sin\omega t$ and $Y(t) = A\cos\omega t - B\sin\omega t$. Show that $\{X(t)\}$ and $\{Y(t)\}$ are jointly WSS if A & B are uncorrelated random variables with zero means and the same variances and ω is a constant.

Proof.

Given $X(t) = A\cos\omega t + B\sin\omega t$ and $Y(t) = A\cos\omega t - B\sin\omega t$ where A & B are uncorrelated random variables with zero means.

So $E(A) = 0$, $E(B) = 0$ and $E(AB) = E(A)E(B) = 0$

Given $\text{Var}(A) = \text{Var}(B) = \sigma^2$

Then $E(A^2) = E(B^2) = \sigma^2$

Given $X(t) = A\cos\omega t + B\sin\omega t$

$$E(X(t)) = E(A\cos\omega t + B\sin\omega t)$$

$$\begin{aligned}\text{Then } E(X(t)) &= E(A)\cos\omega t + E(B)\sin\omega t \\ &= 0 \text{ as } E(A) = E(B) = 0\end{aligned}$$

Example

$$\begin{aligned}R_{xx}(t, t + \tau) &= E[X(t)X(t + \tau)] \\&= E[(A\cos\omega t + B\sin\omega t) + (A\cos\omega(t + \tau) + B\sin\omega(t + \tau))] \\&= E[A^2\cos\omega t\cos\omega(t + \tau)] + E[AB\cos\omega t\sin\omega(t + \tau)] \\&\quad + E[B^2\sin\omega t\sin\omega(t + \tau)] + E[AB\sin\omega t\cos\omega(t + \tau)] \\&= E(A^2)\cos\omega t\cos\omega(t + \tau) + E(AB)\cos\omega t\sin\omega(t + \tau) \\&\quad + E(B^2)\sin\omega t\sin\omega(t + \tau) + E(AB)\sin\omega t\cos\omega(t + \tau)\end{aligned}$$

But $E(AB) = 0$ and $E(A^2) = E(B^2) = \sigma^2$

$$\begin{aligned}R_{xx}(t, t + \tau) &= E(A^2)\cos\omega t\cos\omega(t + \tau) + E(B^2)\sin\omega t\sin\omega(t + \tau) \\&= \sigma^2\cos(\omega t + \omega\tau - \omega t) \\&= \sigma^2\cos(\omega\tau)\end{aligned}$$

Example

Hence $\{X(t)\}$ is a WSS.

In a similar manner prove $\{X(t)\}$ is also a WSS. Now to show their cross correlation is a function of τ .

$$\begin{aligned}R_{xy}(t, t + \tau) &= E[X(t)Y(t + \tau)] \\&= E[(A\cos\omega t + B\sin\omega t) + (B\cos\omega(t + \tau) - A\sin\omega(t + \tau))] \\&= E[AB\cos\omega t\cos\omega(t + \tau)] - E[A^2\cos\omega t\sin\omega(t + \tau)] \\&\quad + E[B^2\sin\omega t\cos\omega(t + \tau)] - E[AB\sin\omega t\sin\omega(t + \tau)] \\&= E(AB)\cos\omega t\cos\omega(t + \tau) - E(A^2)\cos\omega t\sin\omega(t + \tau) \\&\quad + E(B^2)\sin\omega t\cos\omega(t + \tau) - E(AB)\sin\omega t\sin\omega(t + \tau)\end{aligned}$$

But $E(AB) = 0$ and $E(A^2) = E(B^2) = \sigma^2$

Example

$$\begin{aligned}R_{xy}(t, t + \tau) &= \sigma^2 (\sin \omega t \cos \omega(t + \tau) - \cos \omega t \sin \omega(t + \tau)) \\&= \sigma^2 \sin(\omega t + \omega \tau - \omega t) \\&= \sigma^2 \sin(-\omega \tau) \\&= -\sigma^2 \sin(\omega \tau)\end{aligned}$$

This is a function τ of only.

Therefore $\{X(t)\}$ and $\{X(t)\}$ are jointly WSS.

Definition

Time average

If $\{X(t)\}$ is a random process, then $\frac{1}{2T} \int_{-T}^T X(t)dt$ is called the time average of $\{X(t)\}$ over $(-T, T)$ and denoted by \bar{X}_T .

Ergodic Process

A random process $\{X(t)\}$ is said to be ergodic, if its ensemble averages are equal to appropriate time averages.

Mean-Ergodic Process

If the random process $\{X(t)\}$ has a constant mean $\{X(t)\} = \mu$ and if $\bar{X}_T = \frac{1}{2T} \int_{-T}^T X(t)dt \rightarrow \mu$, as $T \rightarrow \infty$, then $\{X(t)\}$ is said to be mean-ergodic.

Theorem

Mean-Ergodic Theorem

If $\{X(t)\}$ is a random process with constant mean μ and if

$\bar{X}_T = \frac{1}{2T} \int_{-T}^T X(t)dt$, then $\{X(t)\}$ is mean-ergodic, provided

$$\lim_{T \rightarrow \infty} \{Var \bar{X}_T\} = 0$$

Proof:

$$\begin{aligned}\bar{X}_T &= \frac{1}{2T} \int_{-T}^T X(t)dt \\ E\bar{X}_T &= \frac{1}{2T} \int_{-T}^T E\{X(t)\}dt \\ &= \mu\end{aligned}\tag{10}$$

By Tchebycheff's inequality,

$$P\{|\bar{X}_T - E\bar{X}_T| \leq \epsilon\} \geq 1 - \frac{Var(\bar{X}_T)}{\epsilon^2}\tag{11}$$

Theorem

Taking Limits as $T \rightarrow \infty$ and using 10 we get

$$p\{|\lim_{T \rightarrow \infty} (\bar{X}_T) - \mu| \leq \epsilon\} \geq 1 - \frac{\lim_{T \rightarrow \infty} \text{Var}(\bar{X}_T)}{\epsilon^2}$$

\therefore when $\lim_{T \rightarrow \infty} \text{Var}(\bar{X}_T) = 0$, 11 becomes

$$p\{|\lim_{T \rightarrow \infty} (\bar{X}_T) - \mu| \leq \epsilon\} \geq 1$$

(i.e.) $\lim_{T \rightarrow \infty} (\bar{X}_T) = E\{X(t)\}$ with probability 1.

Example

Example1

Prove that the random process $\{X(t)\}$ with constant mean is mean ergodic if $\lim_{T \rightarrow \infty} \left[\frac{1}{4T^2} \int_{-T}^T \int_{-T}^T C(t_1, t_2) dt_1 dt_2 \right] = 0$

Proof.

By mean-ergodic theorem, the condition for the mean-ergodicity of the process $\{X(t)\}$ is

$$\lim_{T \rightarrow \infty} \text{Var}(\bar{X}_T) = 0$$

$$\bar{X}_T = \frac{1}{2T} \int_{-T}^T X(t) dt \text{ and } E\bar{X}_T = E(X_T)$$

$$\bar{X}_T^2 = \frac{1}{4T^2} \int_{-T}^T \int_{-T}^T X(t_1)X(t_2) dt_1 dt_2$$

Example

$$E\{\bar{X}_T^2\} = \frac{1}{4T^2} \int_{-T}^T \int_{-T}^T R(t_1, t_2) dt_1 dt_2$$

$$\begin{aligned} \text{Var}(\bar{X}_T) &= E\{\bar{X}_T^2\} - E^2(\bar{X}_T) \\ &= \frac{1}{4T^2} \int_{-T}^T \int_{-T}^T [R(t_1, t_2) - E\{X(t_1)E\{X(t_1)\}] dt_1 dt_2 \\ &= \frac{1}{4T^2} \int_{-T}^T \int_{-T}^T C(t_1, t_2) dt_1 dt_2 \end{aligned}$$

Therefore, the condition $\lim_{T \rightarrow \infty} \text{Var}(\bar{X}_T) = 0$ is equivalent to the condition

$$\lim_{T \rightarrow \infty} \left[\frac{1}{4T^2} \int_{-T}^T \int_{-T}^T C(t_1, t_2) dt_1 dt_2 \right] = 0$$

Hence the result.