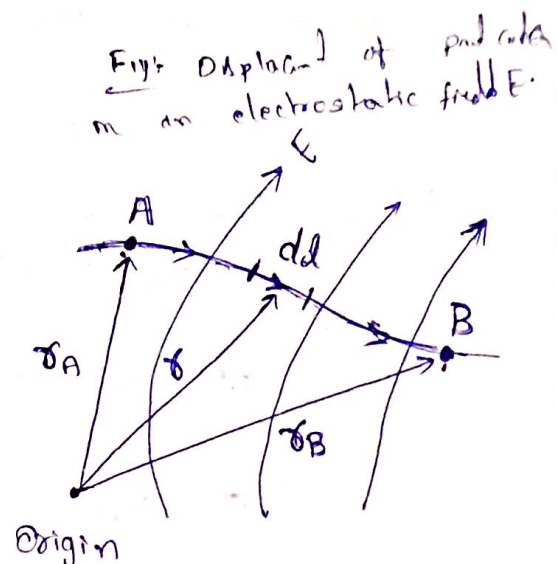


## \*. ELECTRIC POTENTIAL:-

$E$  can be obtained from Coulomb's law in general or Gauss's law when the charge distribution is symmetric.

' $E$ ' can be obtained from the electric scalar potential ' $V$ '. It is easy to handle scalar when compared to vector.



Point charge  $q$  from A to B in  $E$ , From Coulomb's law, the force on  $q$  is  $F = qE$ , so the work done in displacing charge by  $dd$  is

$$dW = -F \cdot dd = -qE \cdot dd \longrightarrow (1)$$

The -ve sign indicates the work is being done by an external agent.

total work done or potential energy required, in moving  $q$  from A to B is

$$W = -q \int_A^B E \cdot dd \longrightarrow (2)$$

dividing  $W$  by  $q$  gives the potential energy per unit charge. This quantity is denoted by  $V_{AB}$ , is known as potential difference b/w points A & B. Thus

$$V_{AB} = \frac{W}{q} = - \int_A^B E \cdot dd$$

Note:- In  $V_{AB}$ , A is initial point and B is the final point.

• If  $V_{AB}$  is -ve, there is a loss in P.E. in moving  $q$  from A to B, this implies that the work is being done by the field. However, if  $V_{AB}$  is +ve, there is a gain in P.E. in the movement; an external agent performs the work.

•  $V_{AB}$  is independent of the path taken.

•  $V_{AB}$  is measured in joules per Coulomb, commonly referred to as volts (V).

$E$  due to a point charge  $Q$  located at the origin can be written as

$$E = \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r$$

$$\therefore V_{AB} = - \int_{r_A}^{r_B} \frac{Q}{4\pi\epsilon_0 r^2} \hat{a}_r \cdot d\mathbf{r} \hat{a}_r = - \frac{Q}{4\pi\epsilon_0} \int_{r_A}^{r_B} \frac{1}{r^2} dr = \frac{Q}{4\pi\epsilon_0} \left[ \frac{1}{r} \right]_{r_A}^{r_B}$$

$$\Rightarrow V_{AB} = \frac{Q}{4\pi\epsilon_0} \left[ \frac{1}{r_B} - \frac{1}{r_A} \right] \longrightarrow (5)$$

$$\Rightarrow V_{AB} = \frac{Q}{4\pi\epsilon_0 r_B} - \frac{Q}{4\pi\epsilon_0 r_A}$$

$$\Rightarrow \boxed{\therefore V_{AB} = V_B - V_A}$$

$V_B$  &  $V_A$  are potentials at B & A, respectively. Thus the potential difference  $V_{AB}$  regarded as the potential at B with reference to A. In problems involving point charges, it is customary to choose infinity as reference; that is we assume the potential at infinity is zero.  $V_A = \frac{Q}{4\pi\epsilon_0 r_A}$ ,  $r_A \rightarrow \infty$   $V_A = 0$

The potential at any point ( $r_B \rightarrow r$ ) due to a point charge  $Q$  located at origin is

$$\boxed{V = \frac{Q}{4\pi\epsilon_0 r}}$$

def:- The potential at any point is the potential difference between that point and a chosen point at which the potential is zero.

$$V = - \int_{\infty}^r E \cdot d\mathbf{l}$$

If the point charge ' $Q$ ' is not located at origin but at a point whose position vector is  $\mathbf{r}'$ , the potential  $V(x, y, z)$  or simply  $V(\mathbf{r})$  at

$$\mathbf{r} \text{ becomes } V(\mathbf{r}) = \frac{Q}{4\pi\epsilon_0 |\mathbf{r} - \mathbf{r}'|}$$

$Q_1, Q_2, \dots, Q_n$  at  $\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n$  the potential at  $\mathbf{r}$  is

$$V(\mathbf{r}) = \frac{Q_1}{4\pi\epsilon_0 |\mathbf{r} - \mathbf{r}_1|} + \frac{Q_2}{4\pi\epsilon_0 |\mathbf{r} - \mathbf{r}_2|} + \dots + \frac{Q_n}{4\pi\epsilon_0 |\mathbf{r} - \mathbf{r}_n|}$$

$$V(\mathbf{r}) = \frac{1}{4\pi\epsilon_0} \sum_{k=1}^n \frac{Q_k}{|\mathbf{r} - \mathbf{r}_k|} \quad (\text{point charges}).$$

for continuous charges  $V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_L \frac{\rho_L(\vec{r}') d\ell'}{|\vec{r} - \vec{r}'|}$  (line charge)

$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_S \frac{\rho_S(\vec{r}') ds'}{|\vec{r} - \vec{r}'|}$  (surface charge)

$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \int_V \frac{\rho_V(\vec{r}') dv'}{|\vec{r} - \vec{r}'|}$  (volume charge)

$V_{AB} = V_B - V_A = - \int_A^B \vec{E} \cdot d\vec{\ell} = \frac{W}{Q}$   $V = \frac{Q}{4\pi\epsilon_0 r} + C$

→ Two point charges  $-4\mu C$  &  $5\mu C$  are located at  $(2, -1, 3)$  and  $(0, 4, -2)$ . Find the potential at  $(1, 0, 1)$  assuming zero potential at infinity.

Sol:  $Q_1 = -4\mu C$ ,  $Q_2 = 5\mu C$

$V(\vec{r}) = \frac{Q_1}{4\pi\epsilon_0 |\vec{r} - \vec{r}_1|} + \frac{Q_2}{4\pi\epsilon_0 |\vec{r} - \vec{r}_2|} + C_0$   $C_0 = 0$   
 $V(\infty) = 0$

$|\vec{r} - \vec{r}_1| = |(1, 0, 1) - (2, -1, 3)| = |(-1, 1, -2)| = \sqrt{6}$

$|\vec{r} - \vec{r}_2| = \sqrt{26}$

$V(1, 0, 1) = \frac{10^{-6}}{4\pi \times \frac{15}{36\pi}} \left[ -\frac{4}{\sqrt{6}} + \frac{5}{\sqrt{26}} \right] = -5.872 \text{ kV}$

Relation b/w  $\vec{E}$  &  $V$ :

$V_{AB} = V_B - V_A$

$V_{BA} = V_A - V_B = -(V_B - V_A) = -V_{AB}$

$V_{BA} + V_{AB} = \oint \vec{E} \cdot d\vec{\ell} = 0$

or  $\oint \vec{E} \cdot d\vec{\ell} = 0$

→ ①

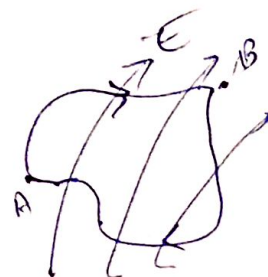


Fig: Conservative nature of electrostatic field.

Physically, this implies that no net work is done in moving a charge along a closed path in an electrostatic field. Apply Stokes th

$\oint \vec{E} \cdot d\vec{\ell} = \int (\nabla \times \vec{E}) \cdot d\vec{S} = 0$

①  $\nabla \times \vec{E} = 0$  → ②

any vector that satisfies ① & ② are called conservative or irrotational.

It is referred to the second Maxwell's eqn for static electric field.



Potential,  $V = - \int \mathbf{E} \cdot d\mathbf{l}$

$$dV = - \mathbf{E} \cdot d\mathbf{l} = - (E_x a_x + E_y a_y + E_z a_z) \cdot (dx a_x + dy a_y + dz a_z)$$

$$= - E_x dx - E_y dy - E_z dz \rightarrow (3)$$

but

$$dV = \frac{\partial V}{\partial x} dx + \frac{\partial V}{\partial y} dy + \frac{\partial V}{\partial z} dz \rightarrow (4)$$

$$E_x = - \frac{\partial V}{\partial x}, E_y = - \frac{\partial V}{\partial y}, E_z = - \frac{\partial V}{\partial z}$$

$$\mathbf{E} = - \nabla V$$

↓

$\mathbf{E}$  is opposite to the direction in which  $V$  increases.

$$\nabla \times \mathbf{E} = 0 \Rightarrow \nabla \times \nabla V = 0.$$

## \* AN ELECTRIC DIPOLE AND FLUX LINES:-

An electric dipole is formed when two point charges of equal magnitude but opposite sign are separated by a small distance.

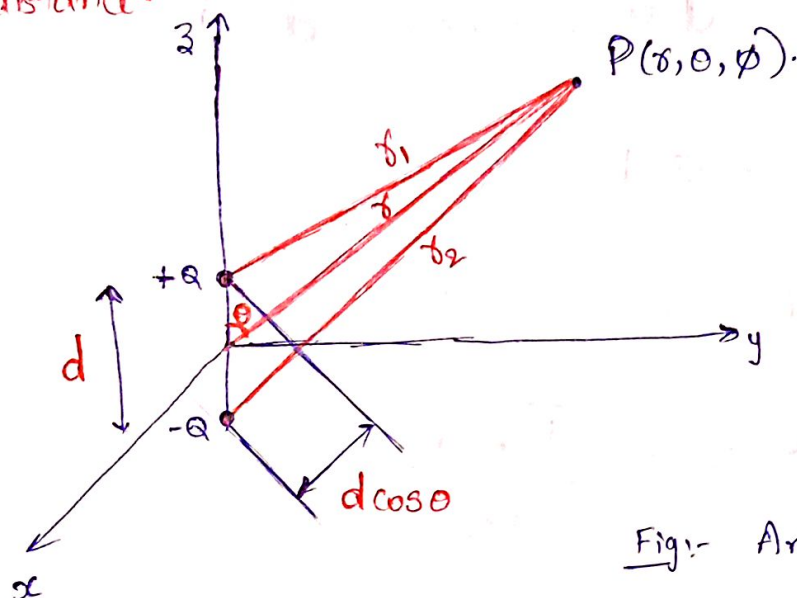


Fig:- An electric dipole.

Consider the dipole shown in Fig. The potential at point P(x, y, z) is given by

$$V = \frac{Q}{4\pi\epsilon_0} \left[ \frac{1}{r_1} - \frac{1}{r_2} \right]$$

$$\Rightarrow V = \frac{Q}{4\pi\epsilon_0} \left[ \frac{r_2 - r_1}{r_1 r_2} \right] \quad \longrightarrow \textcircled{1}$$

where  $r_1$  and  $r_2$  are the distances between P and +Q & P and -Q, respectively.

$$\text{If } r \gg d, \quad r_2 = r_1 + d \cos \theta$$

$$\therefore r_2 - r_1 = d \cos \theta.$$

$$\text{and } r_1 r_2 \simeq r^2,$$

then eq. ① becomes

$$\Rightarrow V = \frac{Q}{4\pi\epsilon_0} \frac{d \cos \theta}{r^2} \longrightarrow \textcircled{2}$$

since  $d \cos \theta = \vec{d} \cdot \vec{a}_r$ , where  $\vec{d} = d\vec{a}_z$ , if we define

$$\vec{P} = Q\vec{d} \quad \text{as the dipole moment,}$$

eq. ② can be written as

$$\Rightarrow V = \frac{\vec{P} \cdot \vec{a}_r}{4\pi\epsilon_0 r^2} \longrightarrow \textcircled{3}$$

Note:- The dipole moment  $\vec{P}$  is directed from  $-Q$  to  $+Q$ .

If the dipole center is not at the origin, but at  $\vec{r}'$ ,

eq. ③ becomes

~~$$V(\vec{r}) = \frac{\vec{P} \cdot (\vec{r} - \vec{r}')}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}$$~~

$$V(\vec{r}) = \frac{\vec{P} \cdot (\vec{r} - \vec{r}')}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}$$

 $\longrightarrow \textcircled{4}$

The electric field due to the dipole with center at the origin, can be obtained readily from

$$\vec{E} = -\nabla V$$

$$\Rightarrow \vec{E} = - \left[ \frac{\partial V}{\partial r} \vec{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \vec{a}_\theta \right]$$

$$\Rightarrow \vec{E} = - \left[ \frac{\partial}{\partial r} \left( \frac{Q}{4\pi\epsilon_0} \frac{d \cos \theta}{r^2} \right) \vec{a}_r + \frac{1}{r} \frac{\partial}{\partial \theta} \left( \frac{Q}{4\pi\epsilon_0} \frac{d \cos \theta}{r^2} \right) \vec{a}_\theta \right]$$

$$\Rightarrow \vec{E} = \frac{Qd \cos \theta}{2\pi\epsilon_0 r^3} \vec{a}_r + \frac{Qd \sin \theta}{4\pi\epsilon_0 r^3} \vec{a}_\theta$$

or

$$\vec{E} = \frac{Qd}{4\pi\epsilon_0 r^3} (2 \cos \theta \vec{a}_r + \sin \theta \vec{a}_\theta)$$

$$\therefore \vec{E} = \frac{P}{4\pi\epsilon_0 r^3} (2 \cos \theta \vec{a}_r + \sin \theta \vec{a}_\theta)$$

where  $p = |\vec{p}| = Qd$ .

Note:-

- A point charge is **monopole** and its electric field

$$E \propto \frac{1}{r^2} \quad \text{and} \quad V \propto \frac{1}{r}$$

- For dipole.,  $E \propto \frac{1}{r^3}$  and  $V \propto \frac{1}{r^2}$



An electric flux line is an imaginary path or line drawn in such a way that its direction at any point is the direction of the electric field at that point.

In other words, they are the lines to which the electric flux density  $\vec{D}$  is tangential at every point.

Any surface on which the potential is the same throughout is known as an equipotential surface. The intersection of an equipotential surface and a plane results in a path or line known as an equipotential line. No work is done in moving a charge from one point to another along an equipotential line or surface.  $(V_A - V_B) = 0$  and hence  $\int_L \vec{E} \cdot d\vec{l} = 0$ .

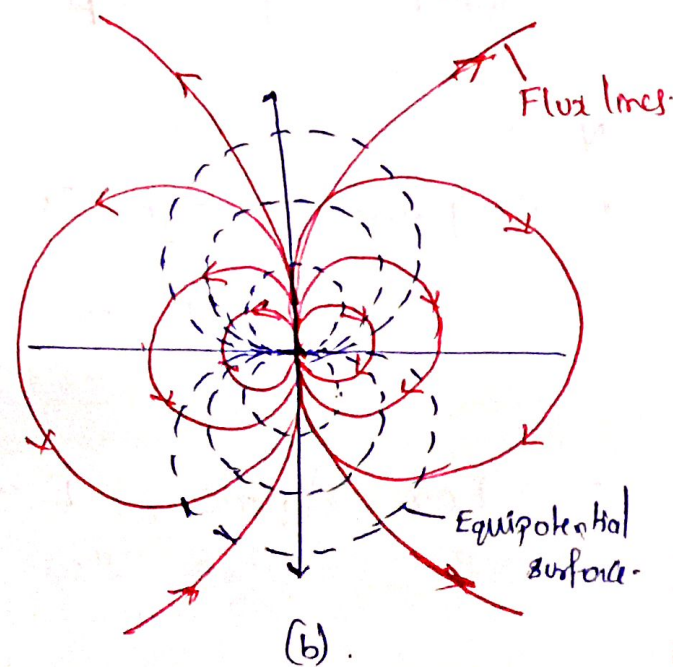
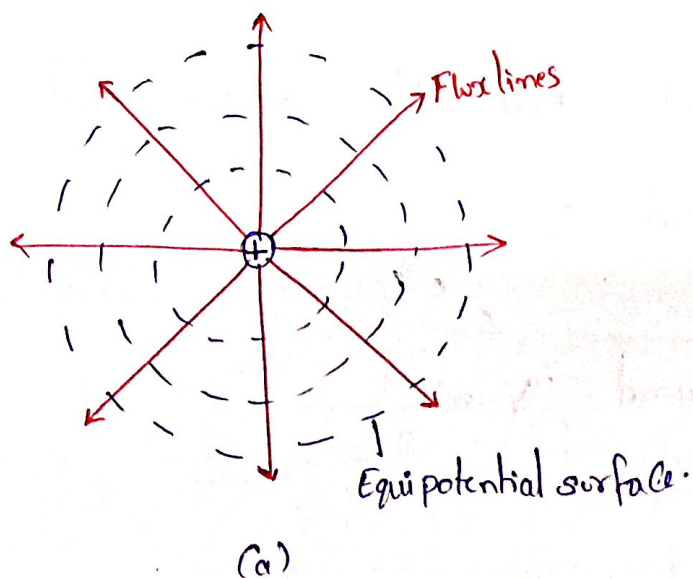


Fig:- Equipotential surfaces for (a) a point charge & (b) an electric dipole.



## \*. ENERGY DENSITY IN ELECTROSTATIC FIELDS:-

To determine the energy present in an assembly of charges, we must ~~and~~ first determine the amount of work necessary to assemble them. Suppose we wish to position three point charges  $Q_1$ ,  $Q_2$ , and  $Q_3$  in an initially empty space shown in Fig.

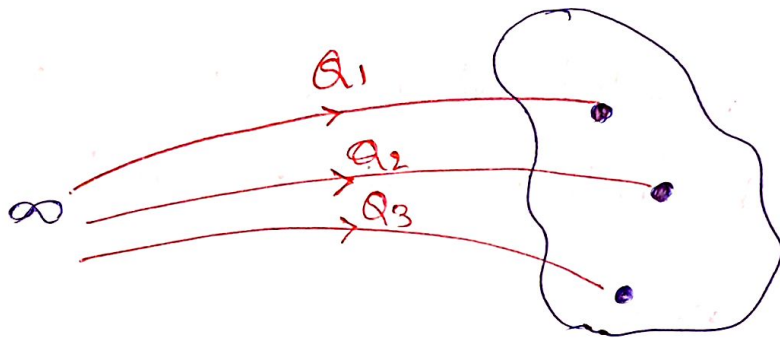


Fig:- Assembling of charges.

No work is required to transfer  $Q_1$  from infinity to  $P_1$  because the space is initially charge free ~~and~~ and there is no electric field. The work done in transferring  $Q_2$  from infinity to  $P_2$  is equal to the product of  $Q_2$  and the potential  $V_{21}$  at  $P_2$  due to  $Q_1$ . Similarly, the work done in positioning  $Q_3$  at  $P_3$  is equal to  $Q_3(V_{32} + V_{31})$ , where  $V_{32}$  &  $V_{31}$  are the potentials at  $P_3$  due to  $Q_2$  and  $Q_1$  respectively.

Hence the total work done in positioning the three charges is  $W_E = W_1 + W_2 + W_3$ .

$$\Rightarrow W_E = 0 + Q_2 V_{21} + Q_3 (V_{31} + V_{32}). \rightarrow (1)$$

If the charges were positioned in reverse order,

$$\Rightarrow W_E = W_3 + W_2 + W_1$$

$$\Rightarrow W_E = 0 + Q_2 V_{23} + Q_1 (V_{12} + V_{13}). \rightarrow (2)$$

where  $V_{23}$  is the potential at  $P_2$  due to  $Q_3$ ,  $V_{12}$  and  $V_{13}$  are, respectively, the potentials at  $P_1$  due to  $Q_2$  &  $Q_3$ .

adding (1) & (2) gives..

$$\Rightarrow 2W_E = Q_1 (V_{12} + V_{13}) + Q_2 (V_{21} + V_{23}) + Q_3 (V_{31} + V_{32}).$$

$$\Rightarrow 2W_E = Q_1 V_1 + Q_2 V_2 + Q_3 V_3.$$

$$\therefore W_E = \frac{1}{2} (Q_1 V_1 + Q_2 V_2 + Q_3 V_3) \rightarrow (3)$$

where  $V_1, V_2$ , and  $V_3$  are total potentials at  $P_1, P_2$  and  $P_3$  respectively.

In general, if there are 'n' point charges, eq(3) becomes

$$W_E = \frac{1}{2} \sum_{k=1}^n Q_k V_k \quad (\text{in joules}). \rightarrow (4)$$

If, instead of point charges, the region has a continuous charge distribution, the summation in eq. (4) becomes integration; that is,

$$W_E = \frac{1}{2} \int_L \rho_L V dl \quad (\text{line charge}) \rightarrow (5)$$

$$W_E = \frac{1}{2} \int_S \rho_S V ds \quad (\text{surface charge}) \rightarrow (6)$$

$$W_E = \frac{1}{2} \int_V \rho_V V dv \quad (\text{volume charge}) \rightarrow (7)$$

Since  $\rho_V = \nabla \cdot \vec{D}$ , eq. (7) can be further developed to yield

$$W_E = \frac{1}{2} \int_V (\nabla \cdot \vec{D}) V dv \rightarrow (8)$$

But for any vector  $\vec{A}$  and scalar  $V$ , the identity

$$\nabla \cdot V \vec{A} = \vec{A} \cdot \nabla V + V (\nabla \cdot \vec{A})$$

$$\text{or } ( \nabla \cdot \vec{A} ) V = \nabla \cdot V \vec{A} - \vec{A} \cdot \nabla V \rightarrow (9)$$

\* Applying the identity in eq. (9) to (8), we get

$$\Rightarrow W_E = \frac{1}{2} \int_V (\nabla \cdot V \vec{D}) dv - \frac{1}{2} \int_V (\vec{D} \cdot \nabla V) dv$$

By applying divergence theorem to the first term on the RHS of this equation, we have

$$\Rightarrow W_E = \frac{1}{2} \oint_S (V \vec{D}) \cdot d\vec{s} - \frac{1}{2} \int_V (\vec{D} \cdot \nabla V) dv \rightarrow (10)$$



We know that  $V$  varies as  $\frac{1}{r}$  and  $\vec{D}$  as  $\frac{1}{r^2}$  for point charges;  $V$  varies as  $\frac{1}{r^2}$  and  $\vec{D}$  as  $\frac{1}{r^3}$  for dipoles; and so on. Hence,  $V\vec{D}$  in the first term on the R.H.S must vary at least as  $\frac{1}{r^3}$  while  $dS$  varies as  $r^2$ . Consequently, the first integral in eq. (10) must tend to ~~zero~~ ~~as~~ zero as the surface  $S$  becomes large.

$$\Rightarrow W_E = 0 - \frac{1}{2} \int_V (\vec{D} \cdot \nabla V) dV$$

$$\Rightarrow W_E = -\frac{1}{2} \int_V (\vec{D} \cdot -\vec{E}) dV$$

$$\left( \because \vec{E} = -\nabla V \right. \\ \left. \text{and } \vec{D} = \epsilon_0 \vec{E} \right)$$

$$\Rightarrow W_E = \frac{1}{2} \int_V (\vec{D} \cdot \vec{E}) dV$$

$$\Rightarrow W_E = \frac{1}{2} \int_V \epsilon_0 \vec{E} \cdot \vec{E} dV$$

$$\Rightarrow W_E = \frac{1}{2} \int_V \epsilon_0 |\vec{E}|^2 dV$$

$$\therefore W_E = \frac{1}{2} \int_V \vec{D} \cdot \vec{E} dV = \frac{1}{2} \int_V \epsilon_0 E^2 dV$$

From this, we can define electrostatic energy density  $W_E$  (in J/m<sup>3</sup>) as

$$w_E = \frac{dW_E}{dv} = \frac{1}{2} \vec{D} \cdot \vec{E} = \frac{1}{2} \epsilon_0 E^2 = \frac{D^2}{2\epsilon_0}$$

$$\therefore W_E = \int_V w_E dv$$