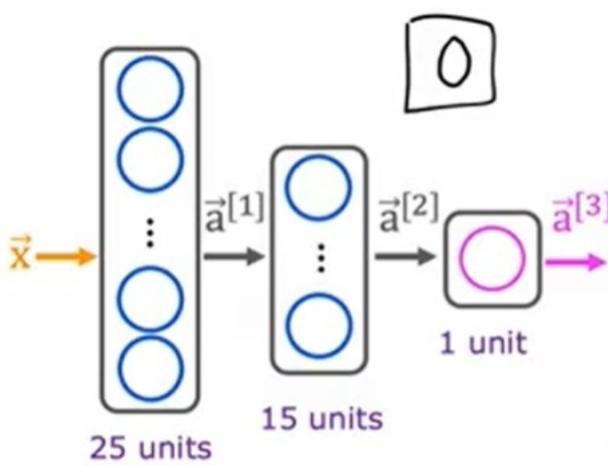


Training a Neural Network in TensorFlow

Train a Neural Network in TensorFlow



Given set of (x, y) examples

How to build and train this in code?

```
import tensorflow as tf
from tensorflow.keras import Sequential
from tensorflow.keras.layers import Dense
model = Sequential([
    Dense(units=25, activation='sigmoid'),
    Dense(units=15, activation='sigmoid'),
    Dense(units=1, activation='sigmoid')
])
from tensorflow.keras.losses import
BinaryCrossentropy
model.compile(loss=BinaryCrossentropy())
model.fit(X, Y, epochs=100) ③ ← fit model
epochs: number of steps  
in gradient descent
```

specify model

compile with loss function

fit model

earlier

logistic reg:-

Given w, b compute output

$$z = np.dot(w, x) + b$$
$$f - x = g(z) = \frac{1}{1 + e^{-z}}$$

2) Specify loss & cost

$$-y \times \log(f - x) - (1 - y) \log(1 - f - x)$$

cost func_m

$$\frac{1}{m} \sum_{i=1}^m L(f_{\vec{w}, b}(x^{(i)}, y^{(i)}))$$

3) Train on data to minimize $J(w, b)$

$$w = w - \alpha * dj - dw \quad b = b - \alpha * dj - db$$

specify how to compute output given input x and parameters w, b (define model)

$$f_{\vec{w}, b}(\vec{x}) = ?$$

② specify loss and cost

$$L(f_{\vec{w}, b}(\vec{x}), y) \quad 1 \text{ example}$$

$$J(\vec{w}, b) = \frac{1}{m} \sum_{i=1}^m L(f_{\vec{w}, b}(\vec{x}^{(i)}), y^{(i)})$$

③ Train on data to minimize $J(\vec{w}, b)$

(gradient descent)

logistic regression

$$z = \text{np.dot}(w, x) + b$$

$$f_x = 1 / (1 + \text{np.exp}(-z))$$

logistic loss

$$\text{loss} = -y * \text{np.log}(f_x) - (1-y) * \text{np.log}(1-f_x)$$

$$w = w - \alpha * \frac{\partial}{\partial w} \text{loss}$$

$$b = b - \alpha * \frac{\partial}{\partial b} \text{loss}$$

neural network

```
model = Sequential([
    Dense(...),
    Dense(...),
    Dense(...),
])
```

binary cross entropy

```
model.compile(
    loss=BinaryCrossentropy())
```

```
model.fit(X, y, epochs=100)
```

(model-compile
(loss = Mean Squared Error)

$$J(w, B) = \frac{1}{m} \sum_{i=1}^m L(f(x^{(i)}, y^{(i)}))$$

$$w^{(1)}, w^{(2)}, w^{(3)}, \dots \quad b^{(1)}, b^{(2)}, b^{(3)}$$

repeat;

$$w_j = w_j - \alpha \frac{\partial}{\partial w_j} J(\vec{w}, b)$$

$$b_j = b_j - \alpha \frac{\partial}{\partial b_j} J(\vec{w}, b)$$

model.fit(x, y, epochs=100)

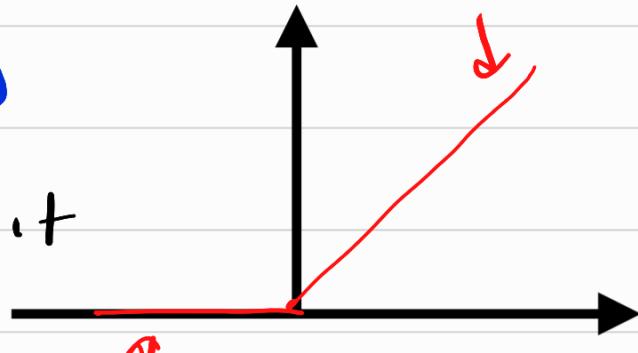
→ Compute derivatives for gradient descent using "back propagation"

Alternatives to sigmoid;

faster learning
not flat

$$g(z) = \max(0, z)$$

Rectified Linear Unit

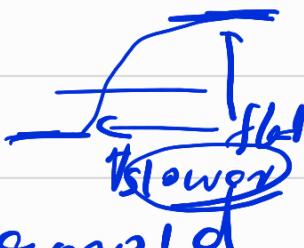


choosing:-

Output layer

binary classification \rightarrow sigmoid

P_{flat}



regression problems

(e.g. stock price \rightarrow +, -)
(+) or (-)

\rightarrow linear activation

Regression (+)



ReLU



most common choice

Hidden Layer \rightarrow ReLU

if all activations were linear

\rightarrow equivalent to linear regression

if all act. were linear except
output logistic

→ logistic regression