



3D Data Processing

Image processing-2

Hyoseok Hwang

contents



- Introduction of image processing
- Pixel point processing
- Geometric transform
- Domain transform
- Spatial filtering

Image transform

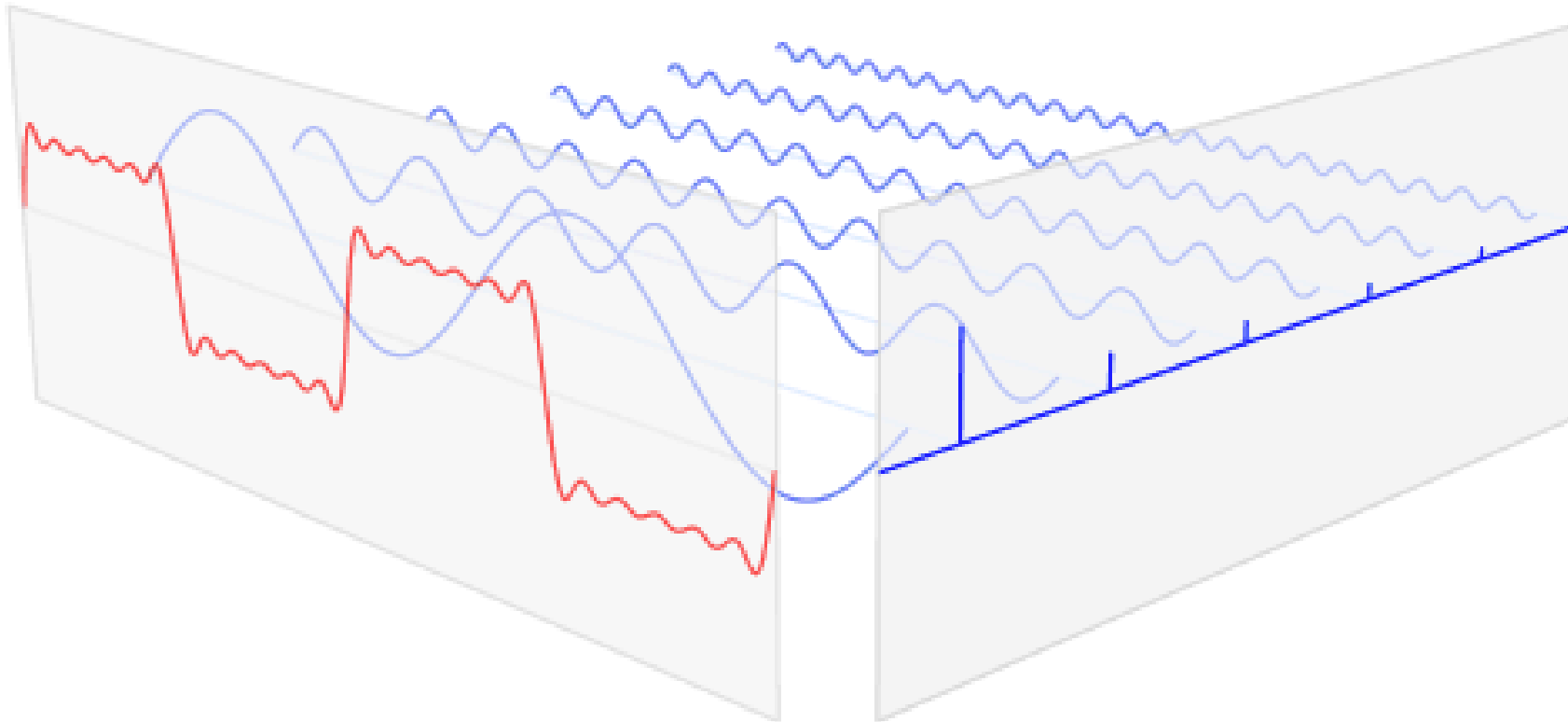


- Hough Transform
- Fourier Transform

Fourier Transform



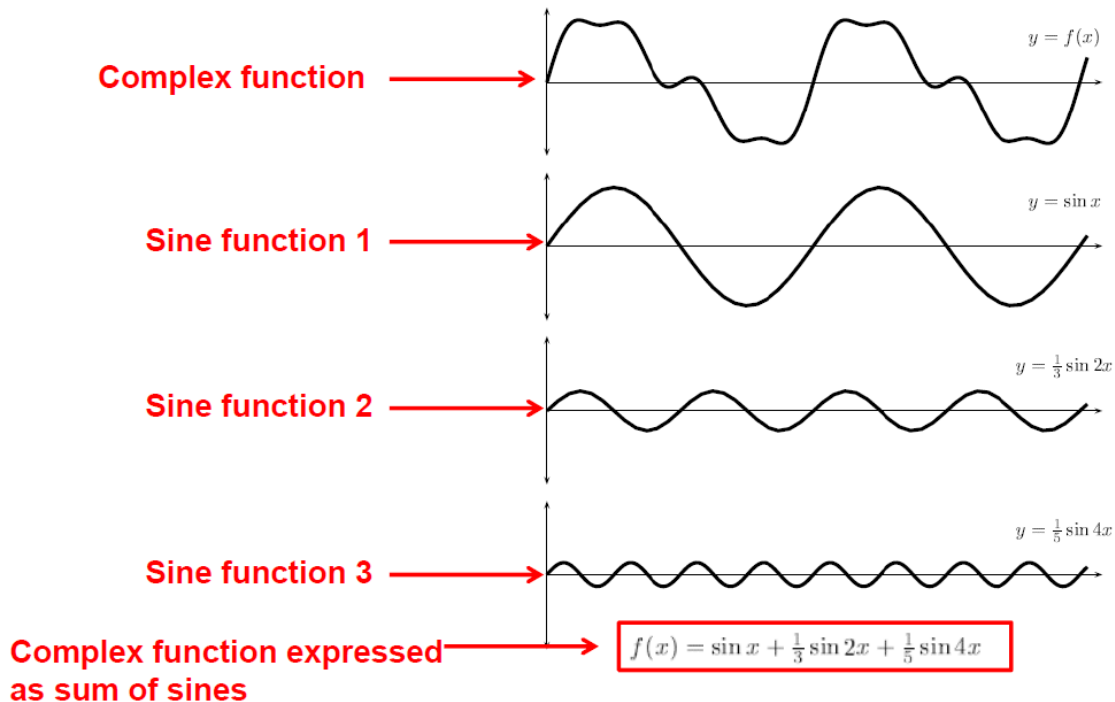
- Main idea: Any periodic function can be decomposed into a summation of sines and cosines



Fourier Transform



- Main idea: Any periodic function can be decomposed into a summation of sines and cosines
- Mathematically easier to analyze effects of transmission medium, noise, etc. on simple sine functions, then add to get effect on complex signal



Fourier transform

$$G(\omega) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot [\cos(\omega x) - i \cdot \sin(\omega x)] dx$$
$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g(x) \cdot e^{-i\omega x} dx.$$

Inverse Fourier transform

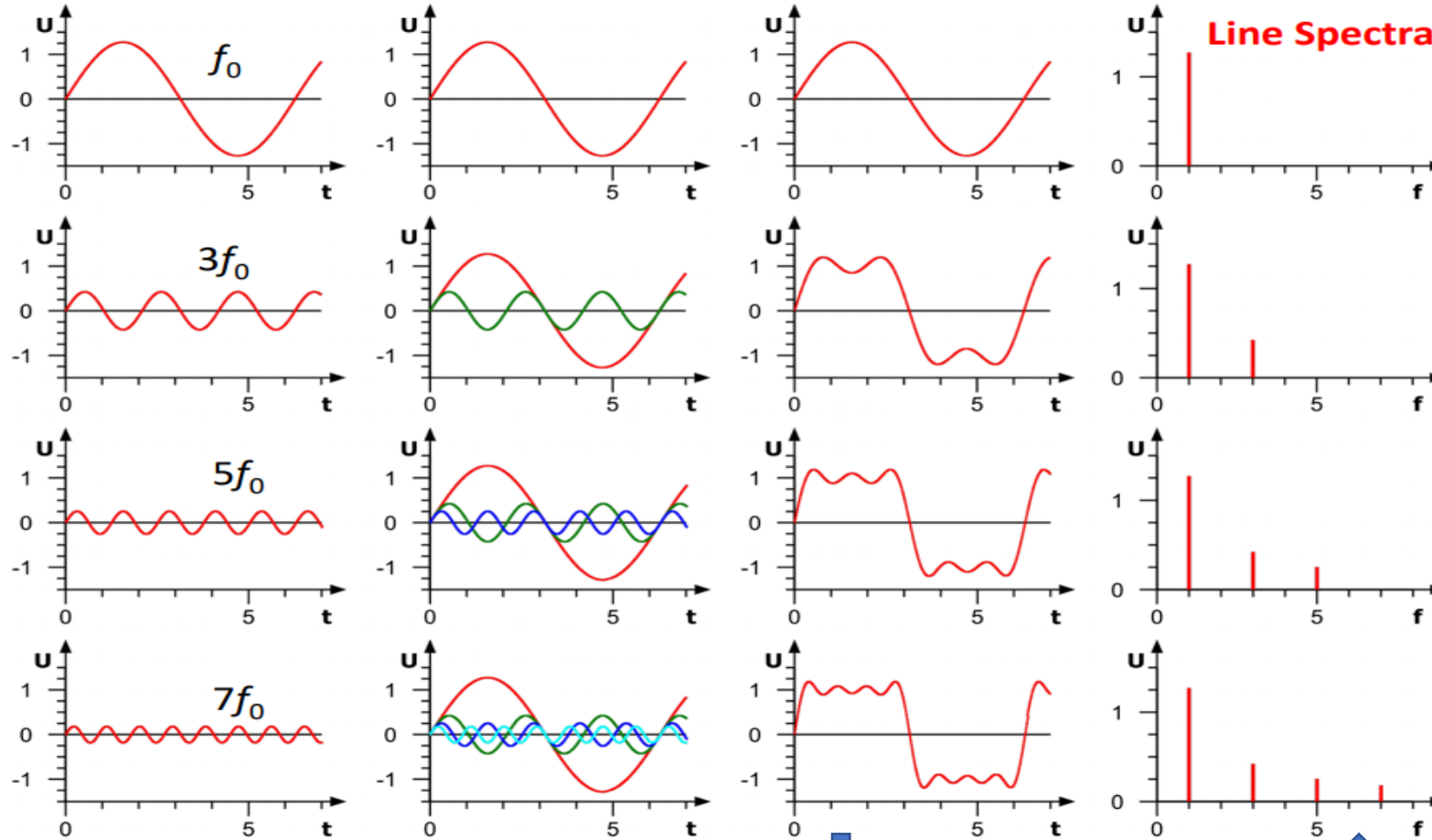
$$g(x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot [\cos(\omega x) + i \cdot \sin(\omega x)] d\omega$$
$$= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} G(\omega) \cdot e^{i\omega x} d\omega.$$

Fourier Transform



- Example

Example: Periodic Square Wave as Sum of Sinusoids

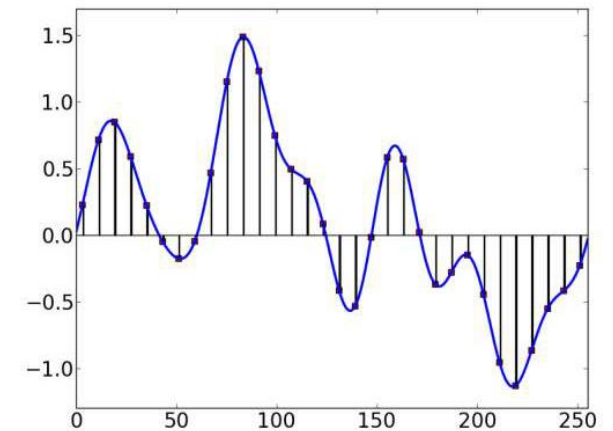


Fourier Transform

Fourier Transform



- Fourier transform
 - Convert **continuous** signals of time domain into frequency domain
- Inverse Fourier transform
 - Convert **continuous** signals of frequency domain into time domain
- Discrete Fourier transform (DFT)
 - The equivalent of the continuous Fourier Transform for **discrete(sampling)** signals.
 - Discrete signals = Quantization(Sampling(continuous signals))
- Fast Fourier transform (FFT)
 - A fast algorithm for computing the Discrete Fourier Transform
 - In image processing, FFT (iFFT) is mainly used.

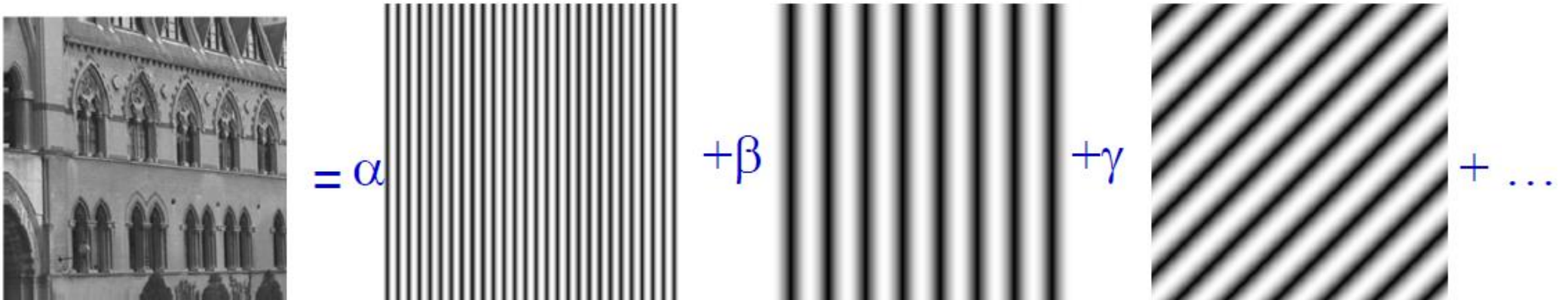


Fourier Transform



- 2D Fourier Transform
 - Fourier transform can be generalized to higher dimensions
- Images as functions
 - Gray scale images: 2D functions – Domain of the functions: set of (x,y) values for which $f(x,y)$ is defined : 2D lattice $[i,j]$ defining the pixel locations – Set of values taken by the function : gray levels

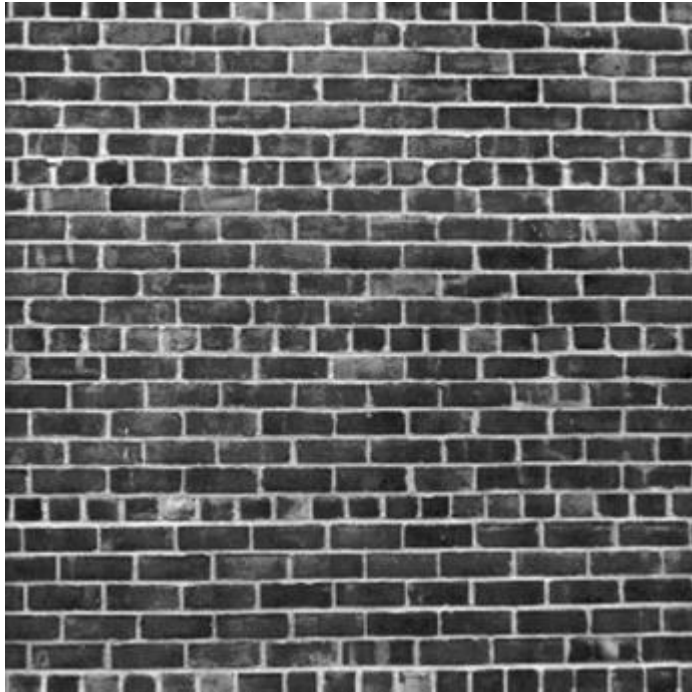
$f(x,y)$



Fourier Transform

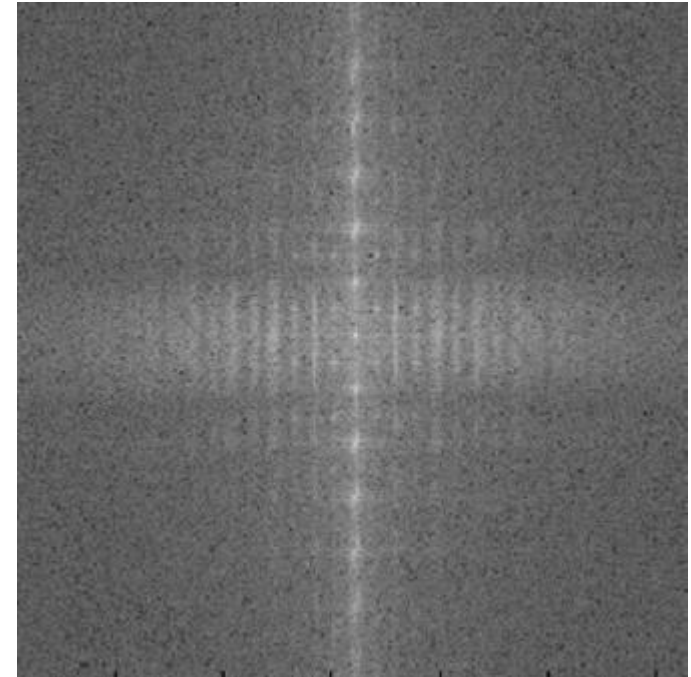


- 2D Fourier Transform
 - Fourier transform is invertible.



2D FFT

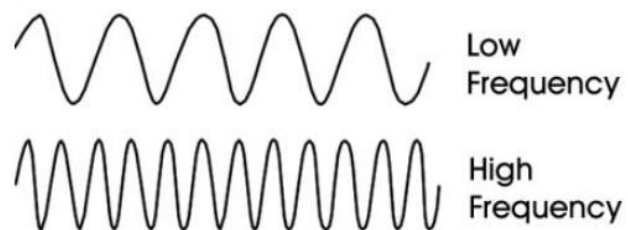
2D iFFT



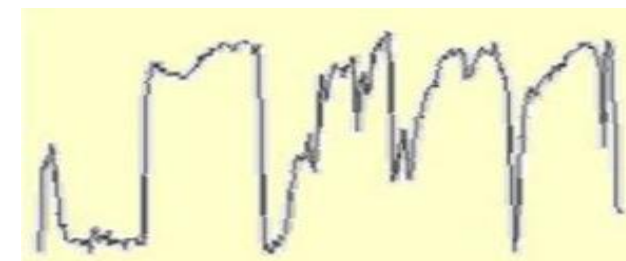
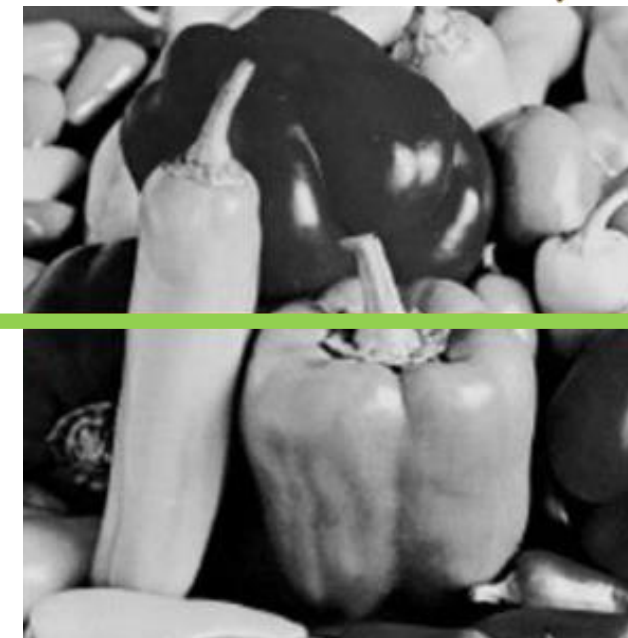
Fourier Transform



- Frequency on images
 - High frequency: edges, points
 - Low frequency: All the rest



Check the region of Low/High frequency



Intensity of N-th row

Image restoration



- Removing artifacts by frequency analysis
- Types of artifacts
 - Noise
 - Noise is a large difference from the nearby values → high frequency
 - Unwanted pattern
 - The periodic pattern is distributed throughout the image(spatial domain), but is displayed as a single dot in the frequency domain.
- Methodology
 - Convert image to frequency domain using FFT
 - Remove artifacts
 - Convert frequency values to image using iFFT

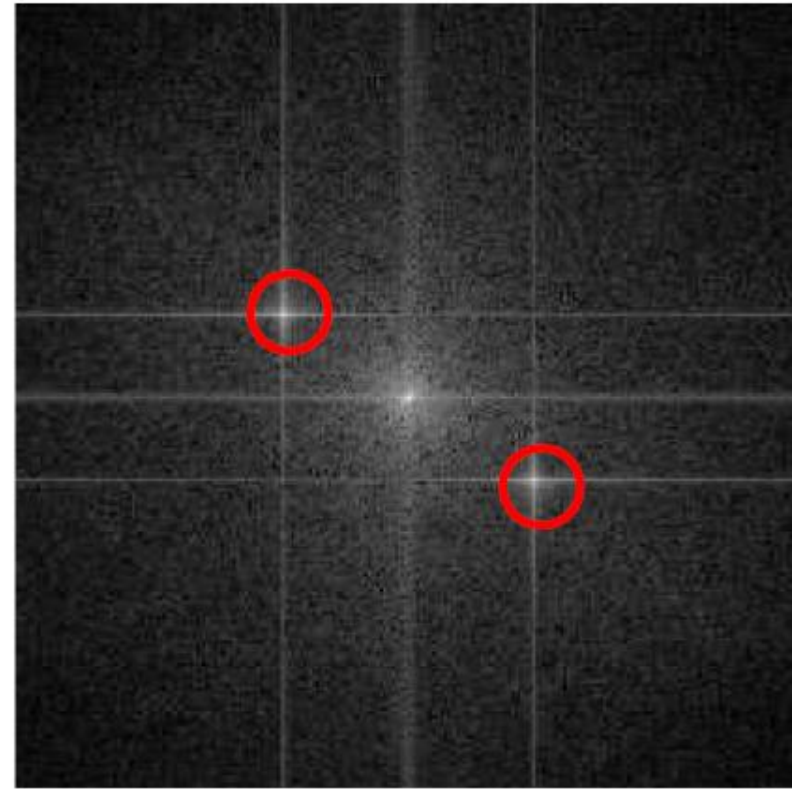
Image restoration



- Removing unwanted pattern (periodic noise)



Image with periodic Noise

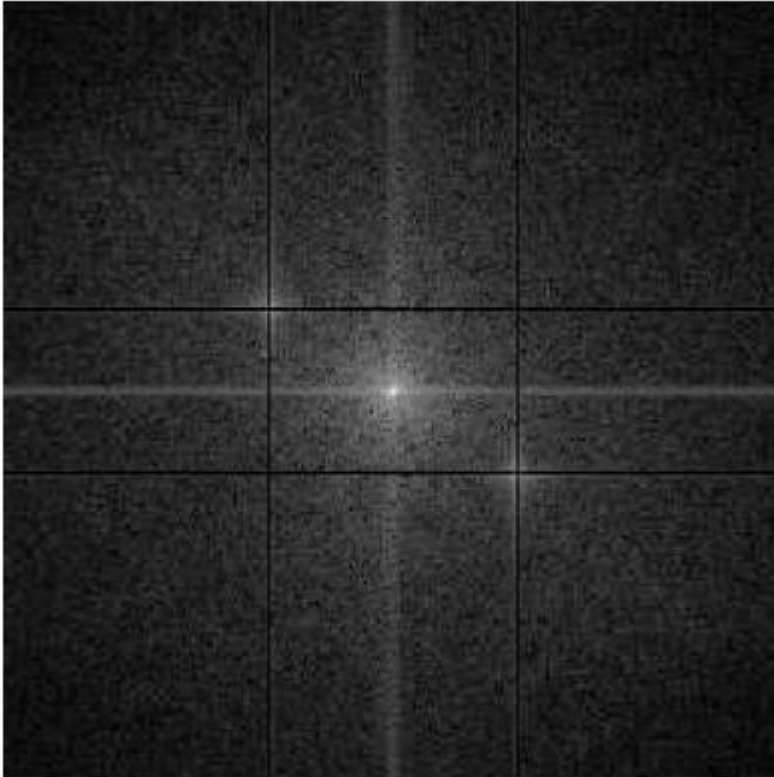


DFT of Image

Image restoration



- Removing unwanted pattern (periodic noise)



Notch Filter



**Result after notch filter
applied then inverted**

Image restoration



- Removing random noise



2D FFT



Remove high frequency (low-pass filter)



2D iFFT

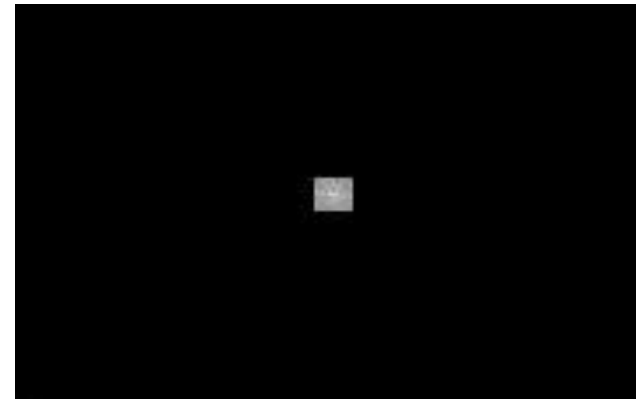


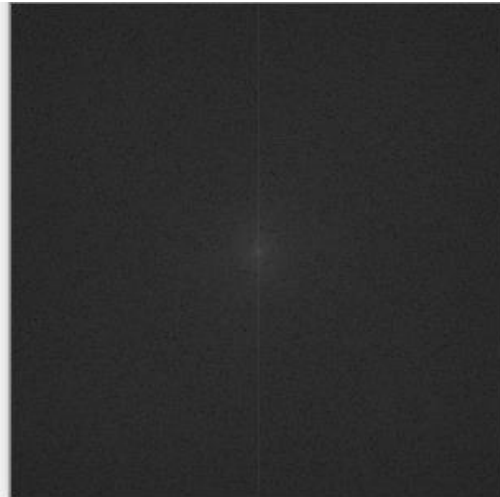
Image restoration



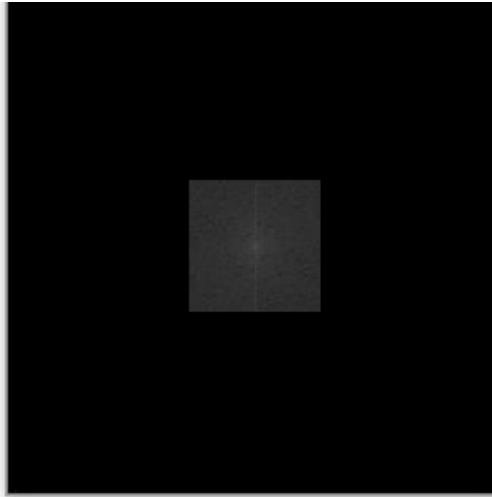
- Exercise
 - File name: [3_2D_FFT_denoising.py](#)



2D FFT



low-pass filter



2D iFFT



Hough transform

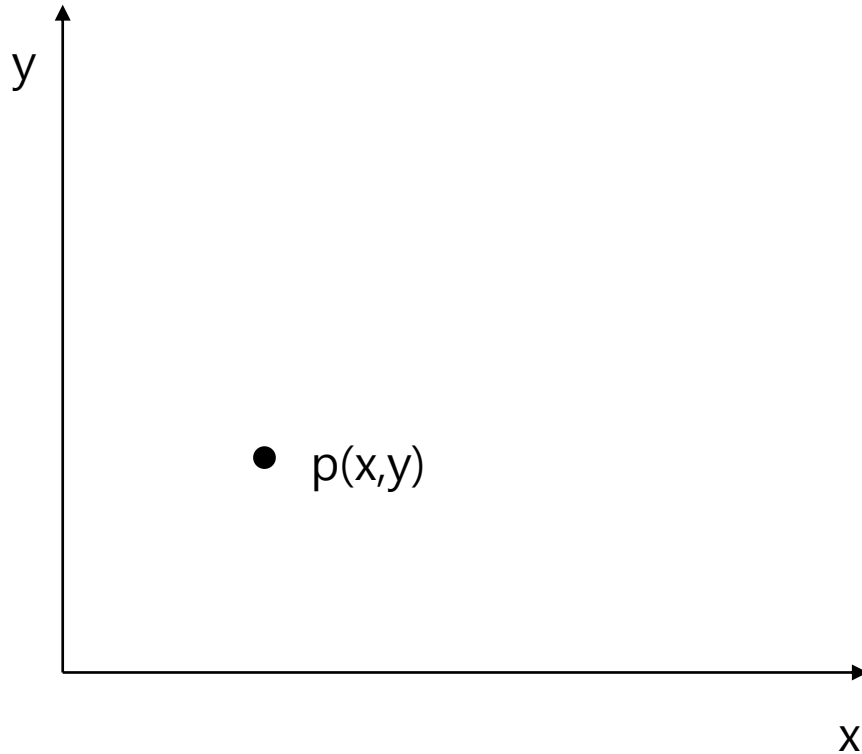


- Convert (x,y) domain to (ρ, θ)
 - Represent a line on (x,y) coordinate to a point on the (ρ, θ) coordinate.
- Hough transform is used for detection certain shapes (especially lines)
 - Suppose that there is a point $p(x,y)$
 - Infinitely many straight lines pass through that point.
 - Each line can be represented to a point in (ρ, θ) coordinate
 - Lines passing through $p(x,y)$ are represented in the form of a curve.
 - The straight line we are looking for appears as a superposition(such as a point) of the curves in A.

Hough transform



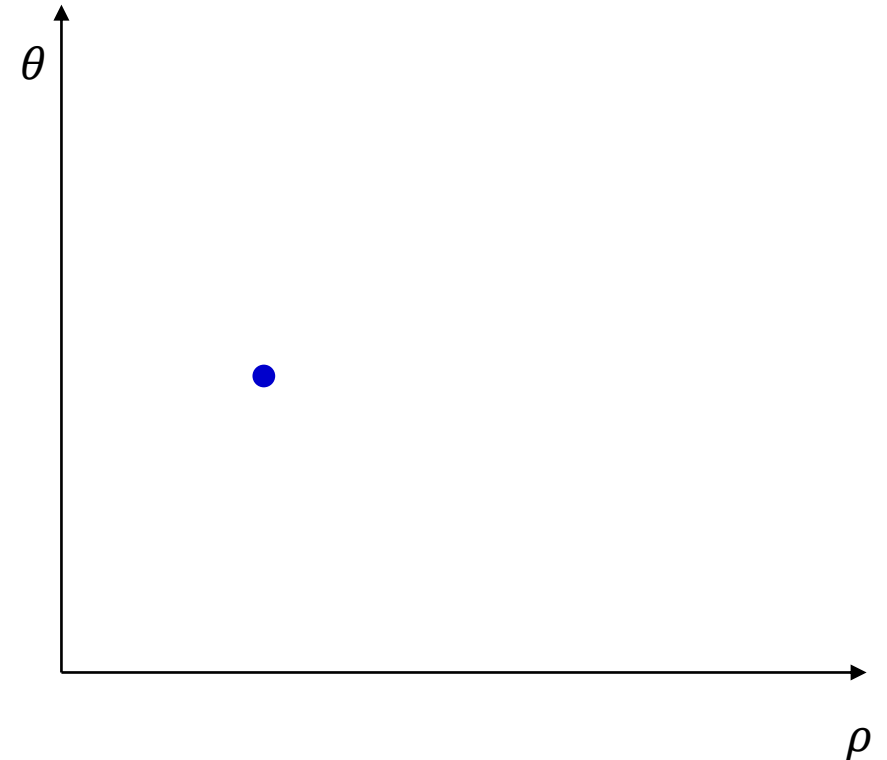
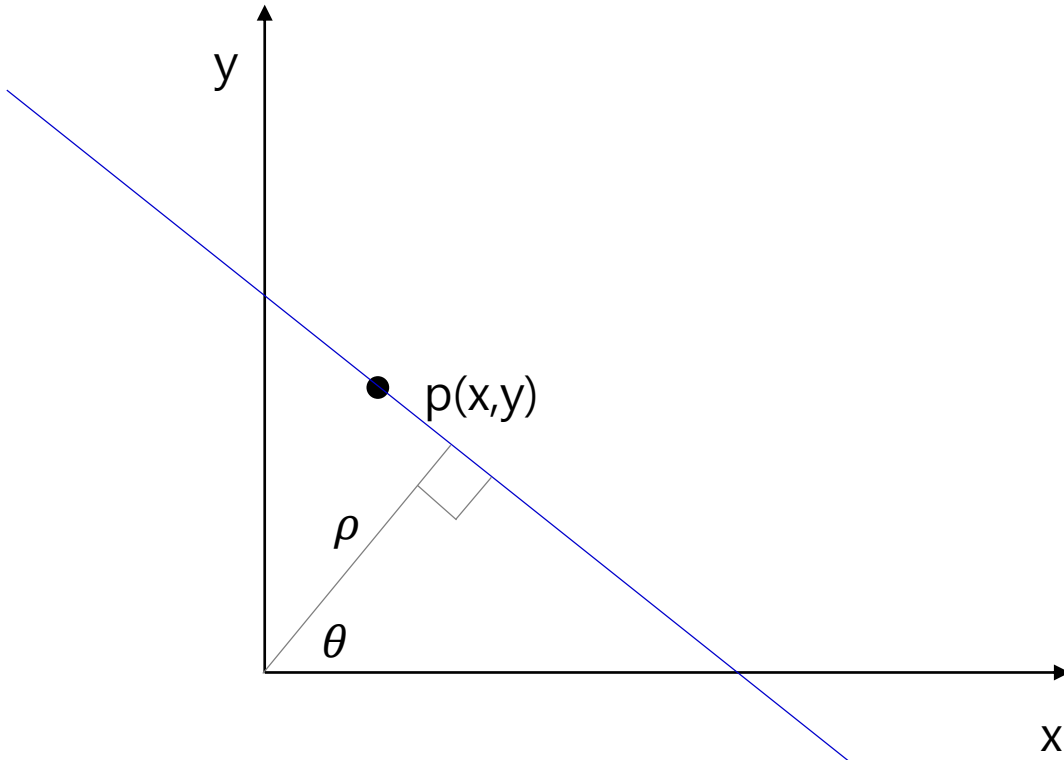
- Transform of a line on the point $p(x,y)$



Hough transform



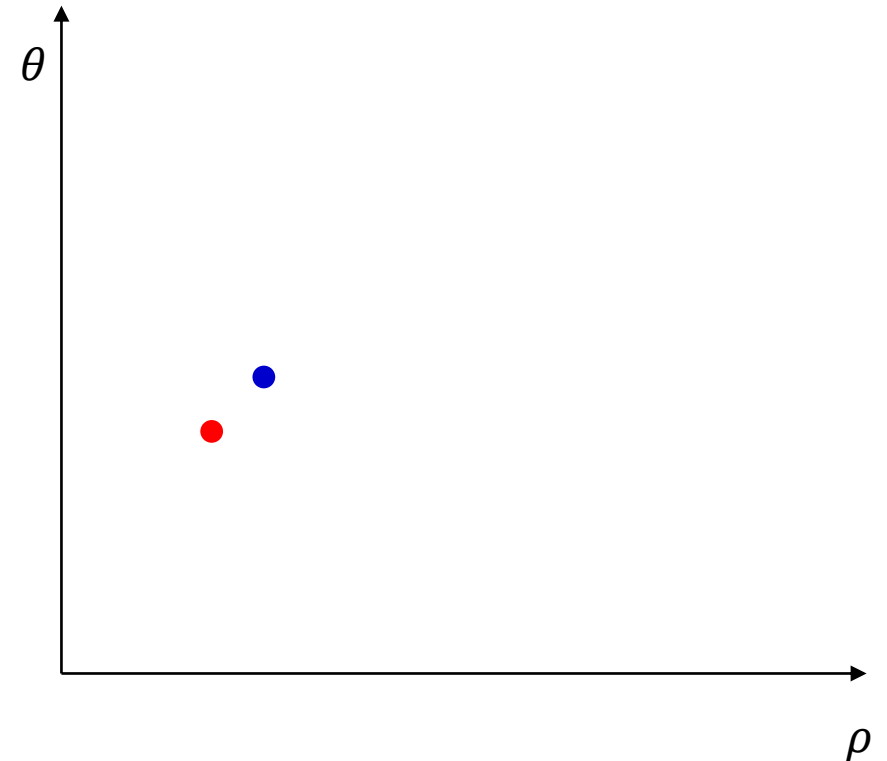
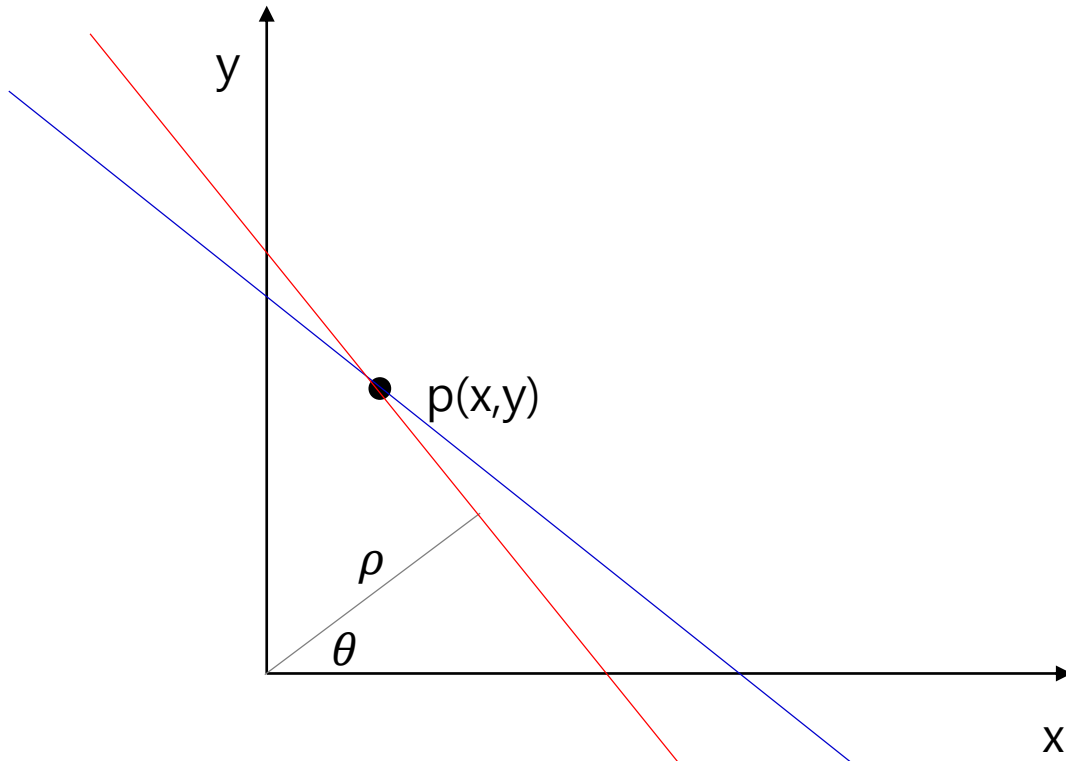
- Transform of a line on the point $p(x,y)$
 - ρ : The orthogonal distance between the origin and a straight line.
 - θ : angle of orthogonal line



Hough transform



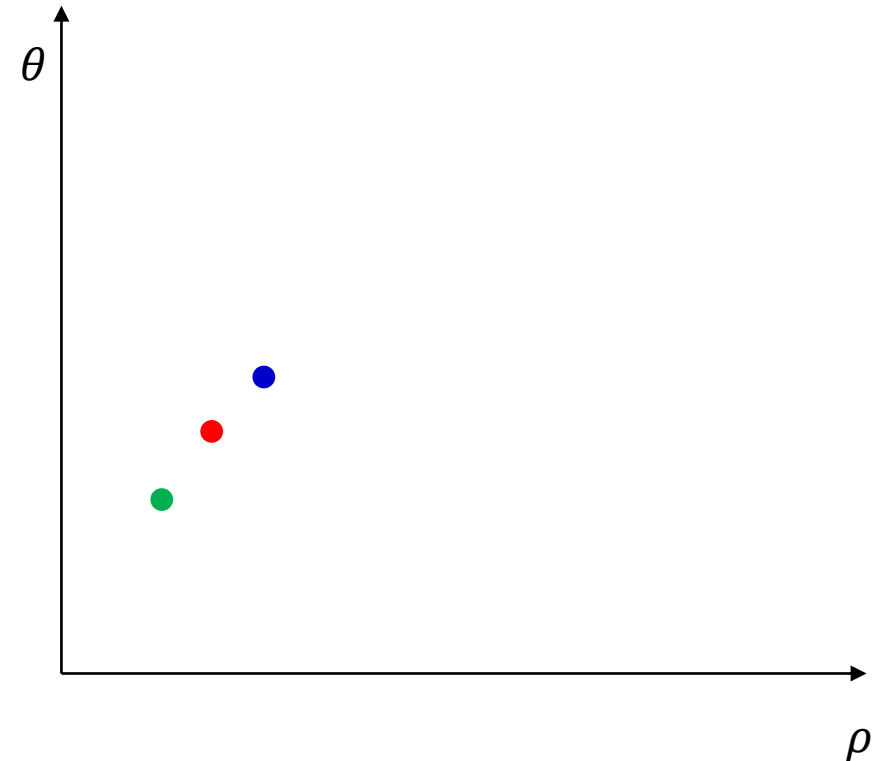
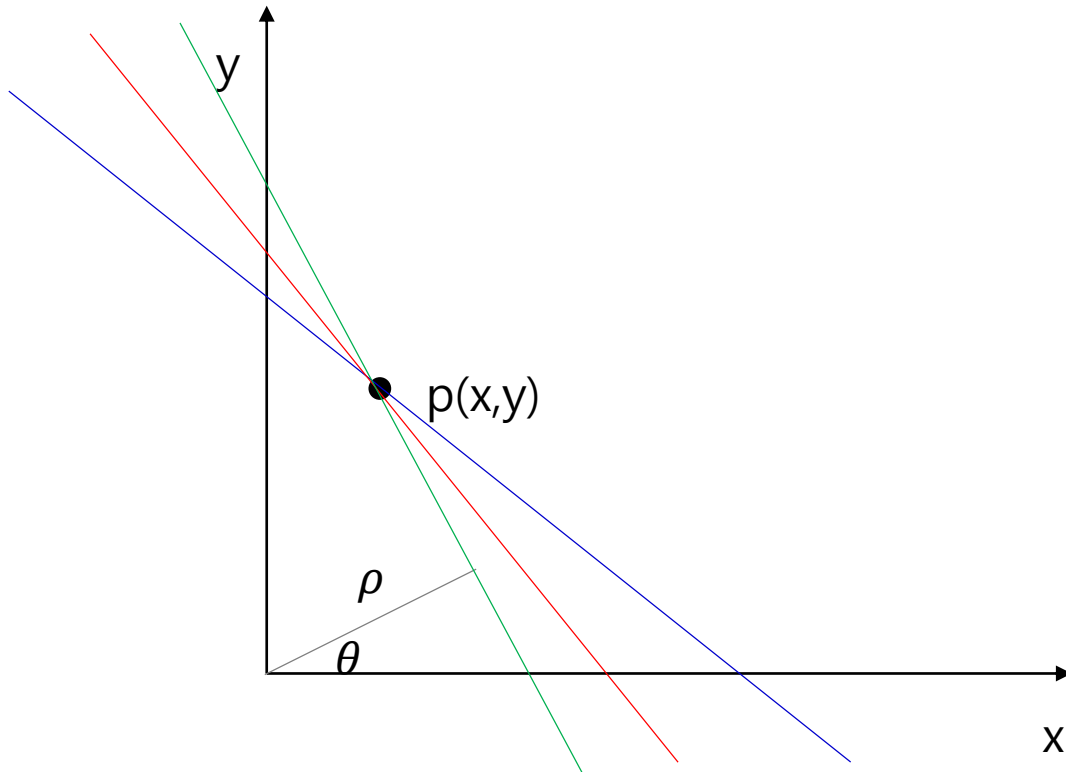
- Transform of a line on the point $p(x,y)$
 - Repeat getting parameters of other lines passing through $p(x,y)$



Hough transform



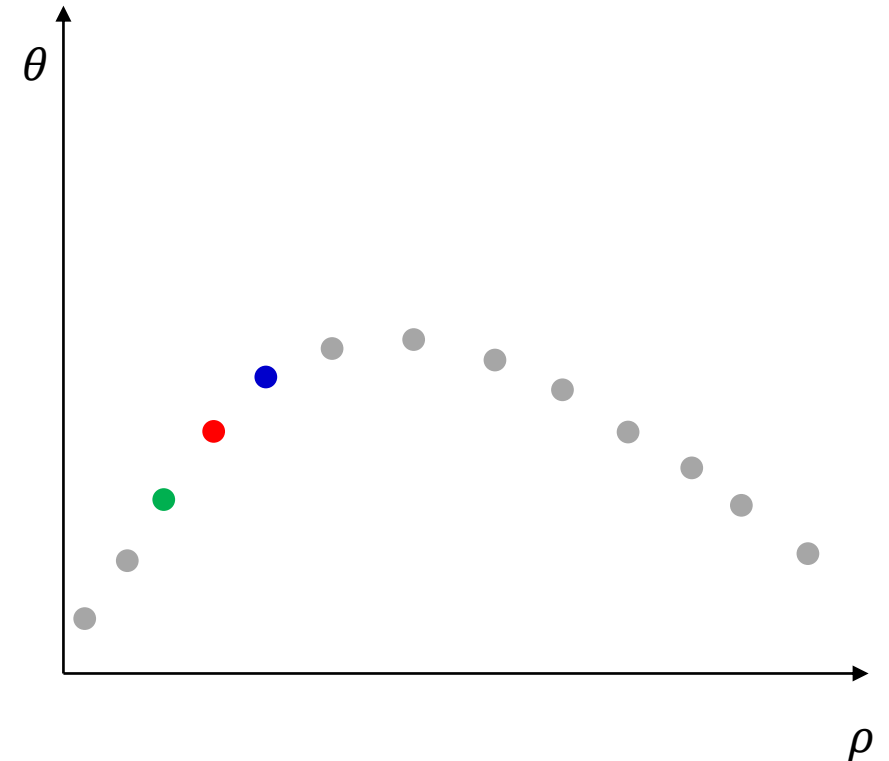
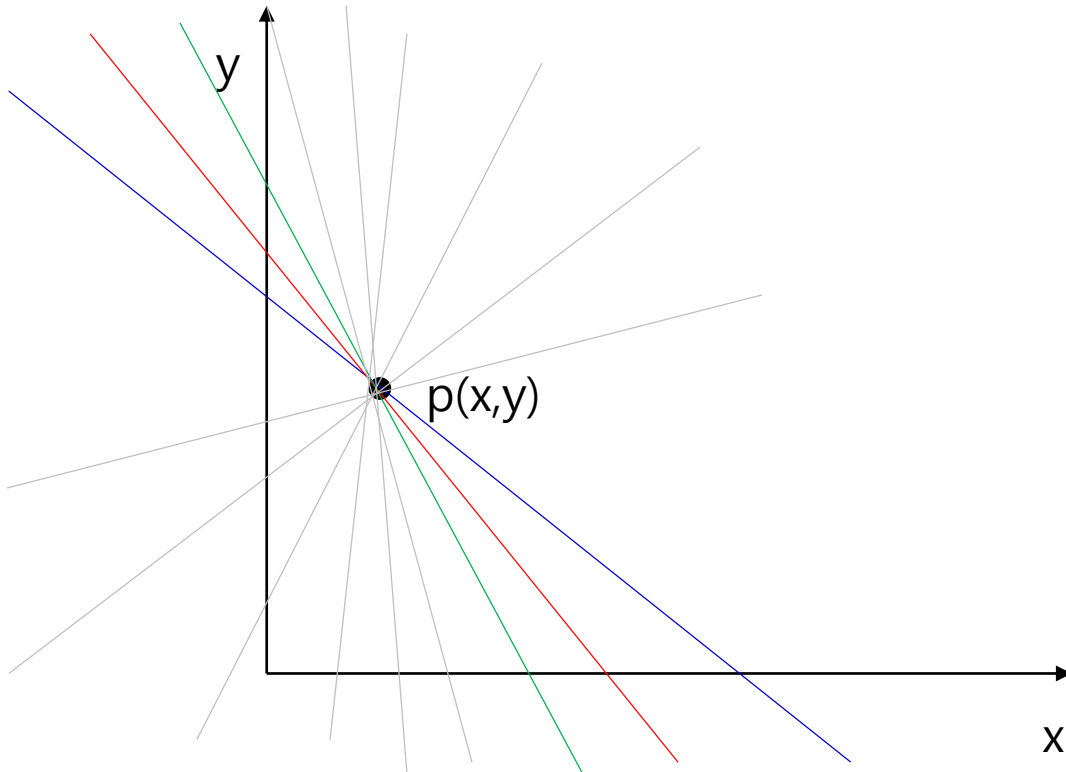
- Transform of a line on the point $p(x,y)$
 - Repeat getting parameters of other lines passing through $p(x,y)$



Hough transform



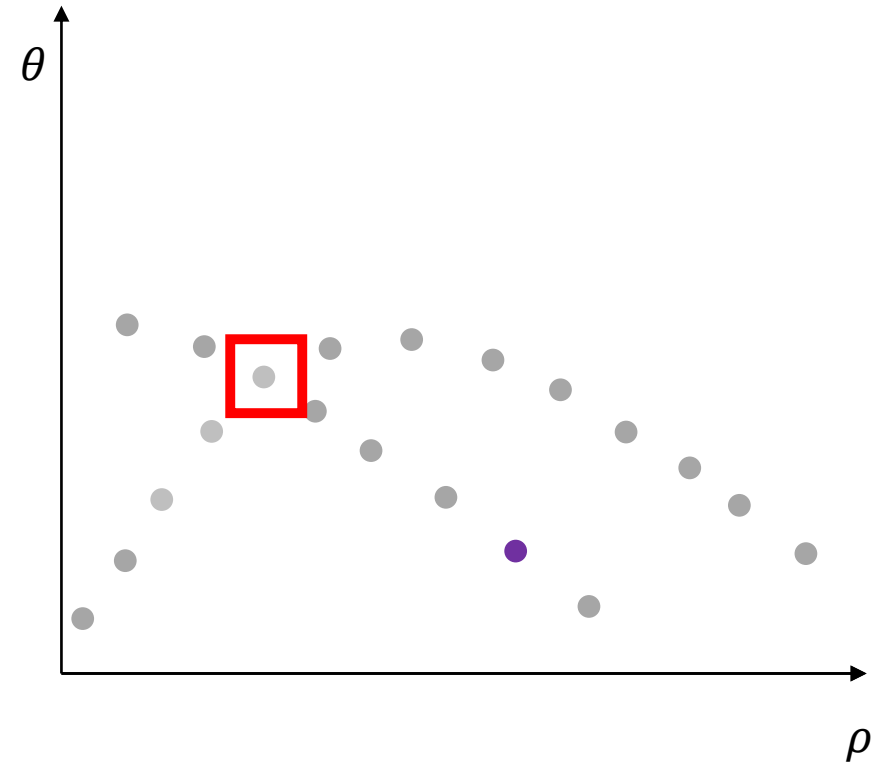
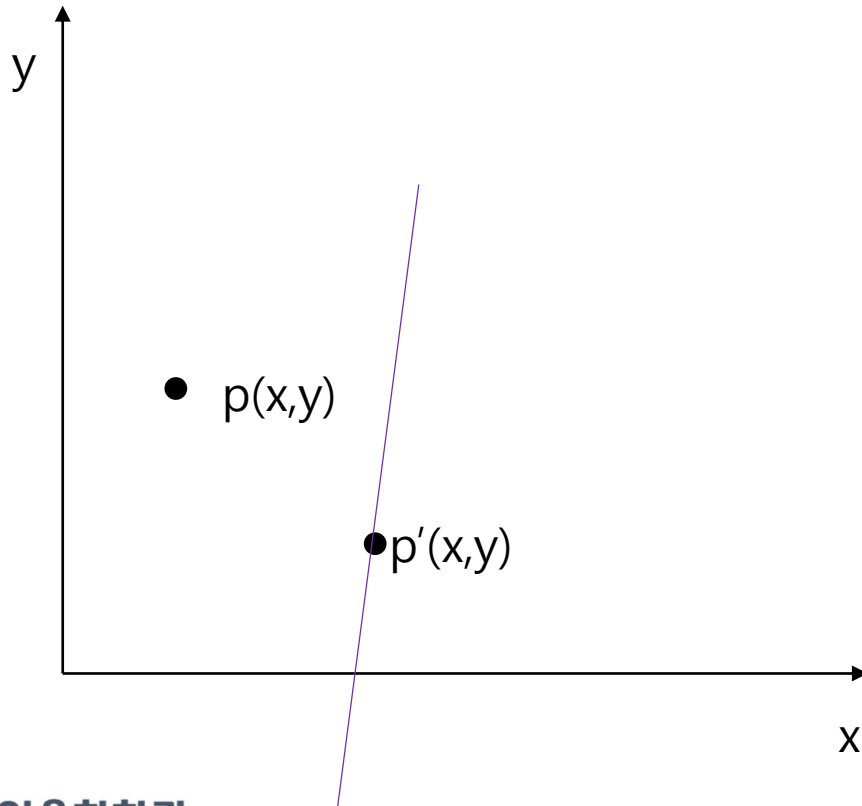
- Transform of a line on the point $p(x,y)$
 - Repeat getting parameters of other lines passing through $p(x,y)$



Hough transform



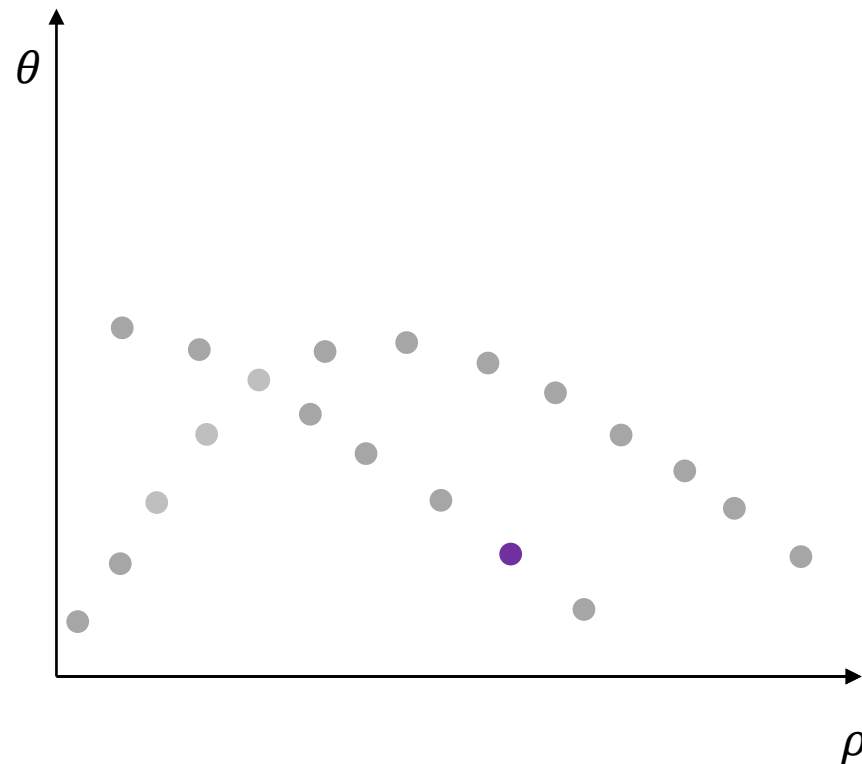
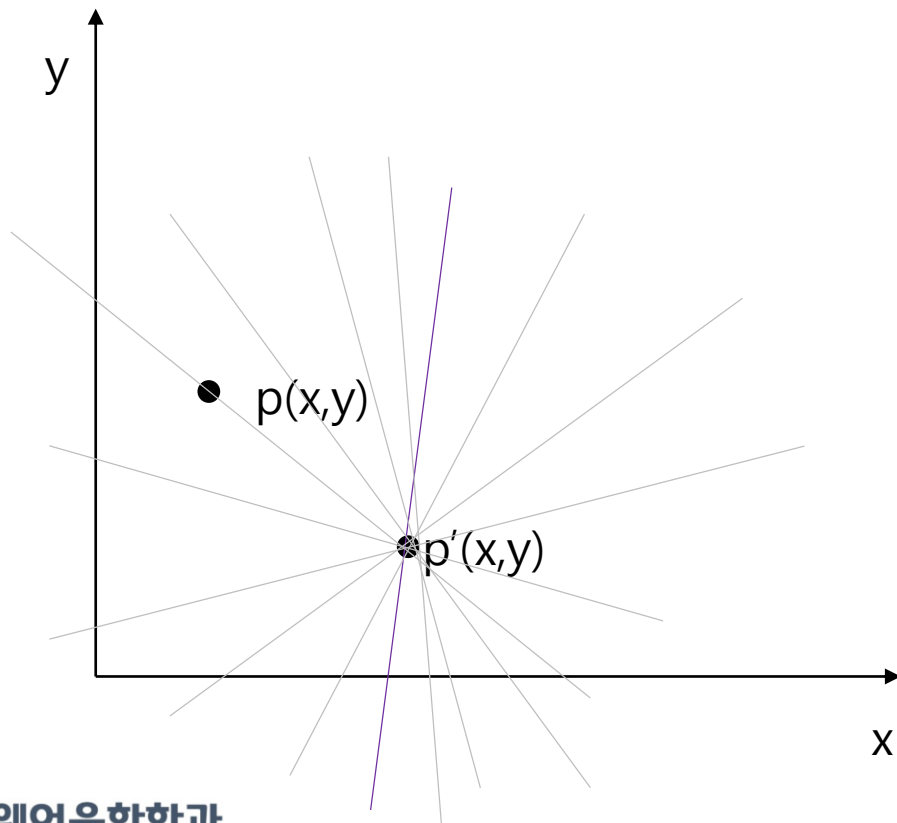
- Transform of a line on the point $p(x,y)$
 - Get parameters of other lines passing through $p'(x,y)$



Hough transform



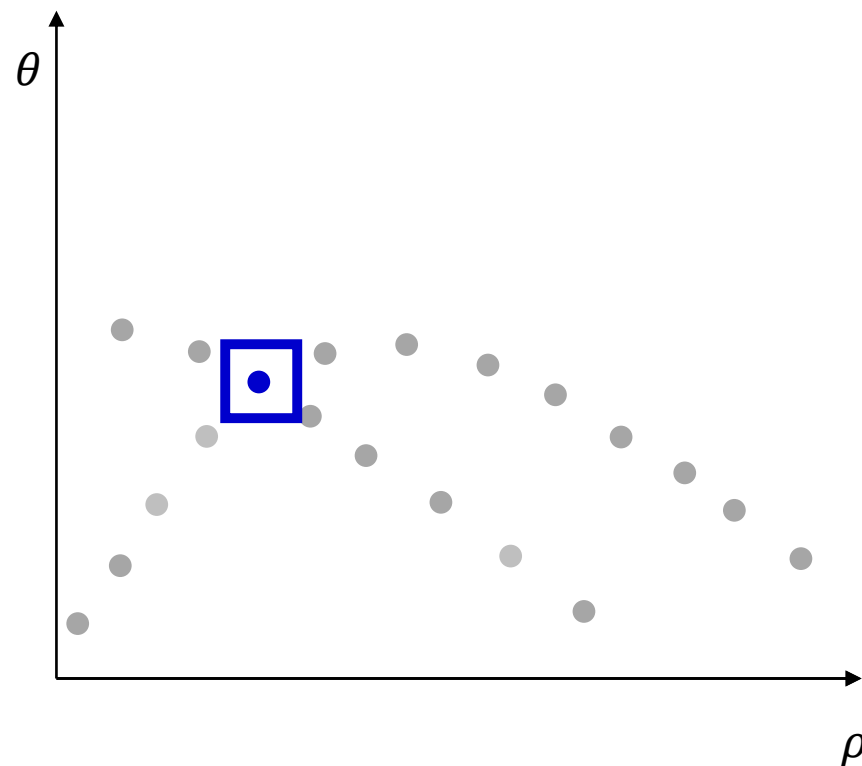
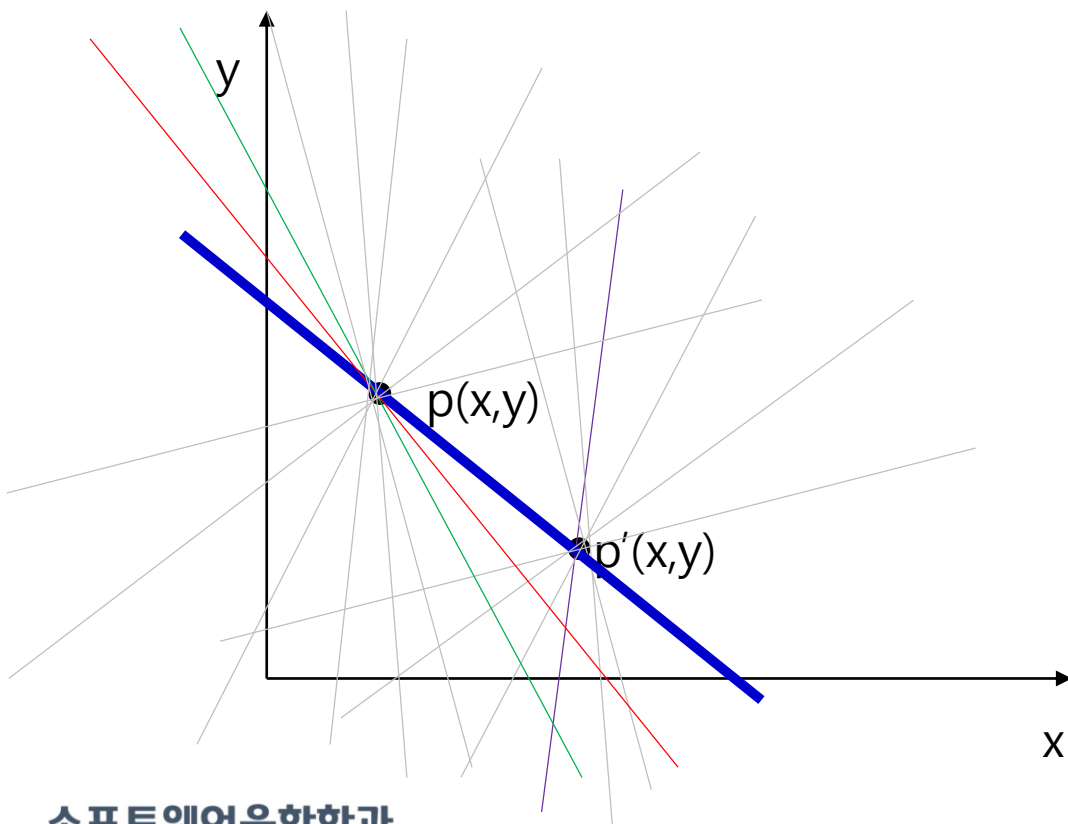
- Transform of a line on the point $p(x,y)$
 - Repeat getting parameters of other lines passing through $p'(x,y)$



Hough transform



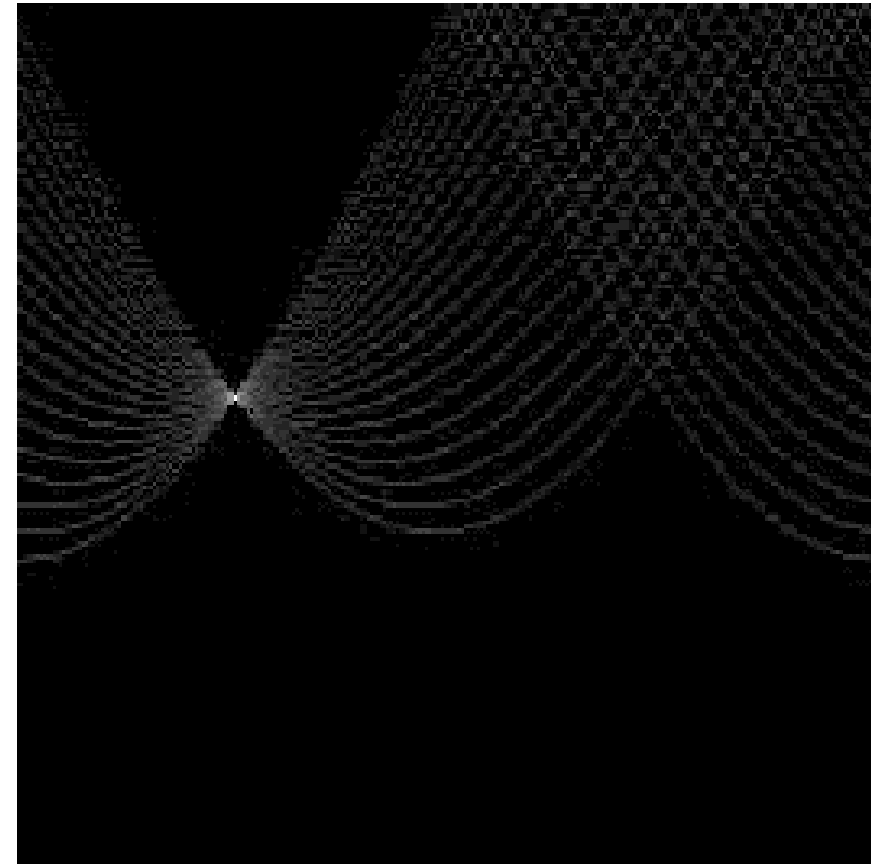
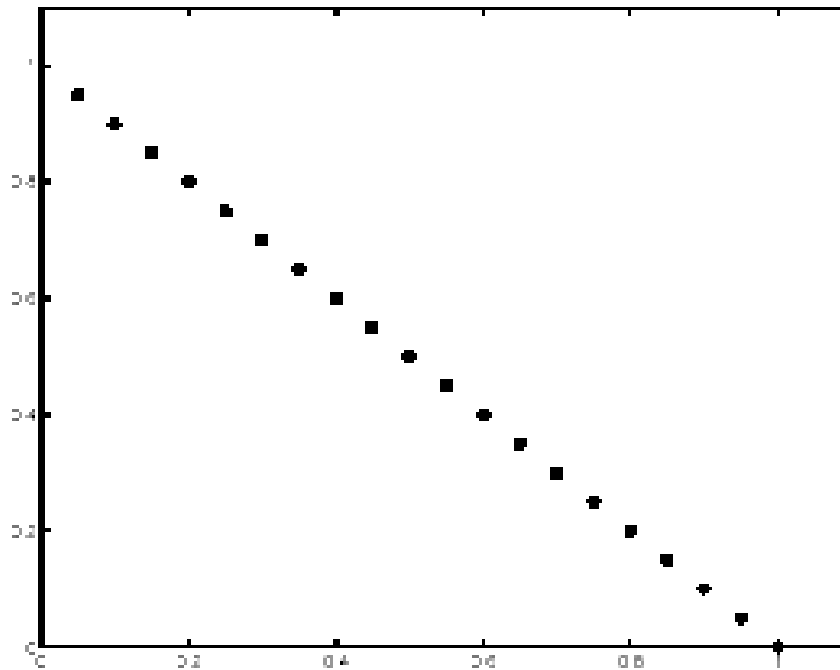
- Transform of a line on the point $p(x,y)$
 - They have a same point on (ρ, θ) coordinate if they are on the same line.



Hough transform



- An example of Hough transform





Thank you