

# Trees

## ① Algorithm of Recursive Traversal for

### i) Preorder

PREORDER (ROOT, LEFT, RIGHT, INFO) %- Given a linked binary tree whose root node pointed to by a pointer ROOT. A local variable PTR is a pointer that points to current being processed.

- 1)  $PTR \leftarrow ROOT$
- 2) if ( $PTR \neq NULL$ ) then
  - a) Print INFO [PTR]
  - b) Call PREORDER (LEFT [PTR])
  - c) Call PREORDER (RIGHT [PTR])
- 3) EXIT

### ii) INORDER

INORDER (ROOT, LEFT, RIGHT, INFO)

- 1)  $PTR \leftarrow ROOT$
- 2) if ( $PTR \neq NULL$ ) then
  - a) call INORDER (LEFT [PTR])
  - b) Print INFO [PTR]
  - c) call INORDER (RIGHT [PTR])
- 3) EXIT

### iii) POSTORDER

POSTORDER (ROOT, LEFT, RIGHT, INFO)

- 1)  $PTR \leftarrow ROOT$
- 2) if ( $PTR \neq NULL$ ) then
  - a) Call POSTORDER (LEFT [PTR])
  - b) Call POSTORDER (RIGHT [PTR])

- c) Print INFO[PTR]
- 3) EXIT

## ② Algorithm of non-recursive Traversal for

### i) Preorder

PREORDER (INFO, LEFT, RIGHT, ROOT) :- A Binary Tree T is in memory. This algorithm does a preorder Traversal of T. An array stack is used to temporarily hold the addresses of nodes.

- 1) Set TOP = 1, STACK[1] = NULL and PTR = ROOT
- 2) Repeat step 3 to 5 while (PTR ≠ NULL)
- 3) Apply PROCESS to INFO[PTR]
- 4) if (RIGHT[PTR] ≠ NULL) then  
Set TOP = TOP + 1 and STACK[TOP] = RIGHT[PTR]  
[end if]
- 5) if (LEFT[PTR] ≠ NULL) then  
Set PTR = LEFT[PTR]  
else  
Set PTR = STACK[TOP] and TOP = TOP - 1  
[end if]
- 6) EXIT

### ii) Inorder

INORDER (INFO, LEFT, RIGHT, ROOT) :- This algorithm does an inorder traversal of binary tree T.

- 1) Set TOP = 1, STACK[1] = NULL and PTR = ROOT
- 2) Repeat while (PTR ≠ NULL)
  - a) Set TOP = TOP + 1 and STACK[TOP] = PTR
  - b) Set PTR = LEFT[PTR][end loop]

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3) Set  $PTR = STACK[TOP]$  and  $TOP = TOP - 1$

4) Repeat step 5 to 7 while ( $PTR \neq NULL$ )

5) Apply PROCESS to  $INFO[PTR]$

6) if ( $RIGHT[PTR] \neq NULL$ ) then

a) Set  $PTR = RIGHT[PTR]$

b) Go to step 2

[end if]

7) Set  $PTR = STACK[TOP]$  and  $TOP = TOP - 1$

[end loop step 4]

8) EXIT

iii) Postorder

POSTORDER (LEFT, RIGHT, INFO, ROOT) :- This algorithm does a postorder traversal of binary tree T.

1) Set  $TOP = 1$ ,  $STACK[1] = NULL$  and  $PTR = ROOT$

2) Repeat step 3 to 5 while ( $PTR \neq NULL$ )

3) Set  $TOP = TOP + 1$  and  $STACK[TOP] = PTR$

4) if ( $RIGHT[PTR] \neq NULL$ ) then

Set  $TOP = TOP + 1$  and  $STACK[TOP] = -RIGHT[PTR]$

[end if]

5) Set  $PTR = LEFT[PTR]$

[end loop step 2]

6) Set  $PTR = STACK[TOP]$  and  $TOP = TOP - 1$

7) Repeat while ( $PTR > 0$ )

a) Apply PROCESS to  $INFO[PTR]$

b) Set  $PTR = STACK[TOP]$  and  $TOP = TOP - 1$

[end loop]

8) if ( $PTR < 0$ ) then

a) Set  $PTR = -PTR$

b) Go to step 2

9) EXIT

### ③ Algorithm to search a node in the Binary Tree

FIND (INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR) :- A binary search tree is in memory and an ITEM of information is given. This procedure finds the location LOC of ITEM in T and also the location PAR of the parent of ITEM. There are 3 cases:

- (i) LOC = NULL and PAR = NULL will indicate empty tree
- (ii) LOC  $\neq$  NULL and PAR = NULL will indicate ITEM is the root of T
- (iii) LOC = NULL and PAR  $\neq$  NULL will indicate ITEM is not in T and can be added to T as a child of node N with location PAR

1) if (ROOT = NULL) then

Set LOC = NULL and PAR = NULL and Return  
[end if]

2) if (ITEM = INFO[ROOT]) then

Set LOC = ROOT and PAR = NULL and Return  
[end if]

3) if (ITEM < INFO[ROOT]) then

Set PTR = LEFT[ROOT] and SAVE = ROOT  
else

Set PTR = RIGHT[ROOT] and SAVE = ROOT  
[end if]

4) Repeat step 5 and 6 while (PTR  $\neq$  NULL)

5) if (ITEM = INFO[PTR]) then

Set LOC = PTR and PAR = SAVE and Return

6) if (ITEM < INFO[PTR]) then

Set SAVE = PTR and PTR = LEFT[PTR]

else

Set SAVE = PTR and PTR = RIGHT[PTR]  
[end if]

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[end loop step4]

7) Set  $LOC = NULL$  and  $PAR = SAVE$

8) EXIT

#### ④ Algorithm to insert a node in Binary Tree

$INSBST(INFO, LEFT, RIGHT, ROOT, AVAIL, ITEM, LOC)$  :- A binary search tree  $T$  is in memory and an  $ITEM$  of information is given. This algorithm finds the location  $LOC$  of  $ITEM$  in  $T$  and/or adds  $ITEM$  as a new node in  $T$  at location  $LOC$ .

1. Call  $FIND(INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR)$

2. if ( $LOC \neq NULL$ ) then

Exit

[end if]

3. a) if ( $AVAIL = NULL$ ) then

Print "Overflow"

Return

[end if]

b) set  $NEW = AVAIL$ ,  $AVAIL = LEFT[AVAIL]$ ;  $INFO[NEW] = ITEM$

c) set  $LOC = NEW$ ,  $LEFT[NEW] = NULL$  and  $RIGHT[NEW] = NULL$

4. if ( $PAR = NULL$ ) then

Set  $ROOT = NEW$

else if ( $ITEM < INFO[PAR]$ ) then

Set  $LEFT[PAR] = NEW$

else

Set  $RIGHT[PAR] = NEW$

[end if]

5. EXIT

#### ⑤ Algorithm to delete a node in Binary Tree



(i) **CASEA**(INFO, LEFT, RIGHT, ROOT, LOC, PAR) :- This procedure deletes the node  $N$  at location  $LOC$ , where  $N$  does not have two children. The pointer  $PAR$  gives the location of parent of  $N$  or else  $PAR = NULL$  indicates that  $N$  is the root node. The pointer  $CHILD$  gives the location of the only child of  $N$ , or else  $CHILD = NULL$  indicates  $N$  has no children.

1. if (LEFT[LOC] = NULL and RIGHT[LOC] = NULL) then

Set CHILD = NULL

else if (LEFT[LOC]  $\neq$  NULL) then

Set CHILD = LEFT[LOC]

else

Set CHILD = RIGHT[LOC]

[end if]

2. if (PAR  $\neq$  NULL) then

if (LOC = LEFT[PAR]) then

Set LEFT[PAR] = CHILD

else

Set RIGHT[PAR] = CHILD

[end if]

else

Set ROOT = CHILD

[end if step 2]

3. Return

(ii) **CASEB**(INFO, LEFT, RIGHT, ROOT, LOC, PAR) :- This procedure will delete the node  $N$  at location  $LOC$ , where  $N$  has two children. The pointer  $PAR$  gives location of parent of  $N$  or else  $PAR = NULL$  indicates  $N$  is root node. The pointer  $SUC$  gives the location of inorder successor of  $N$  and  $PARSUC$  gives

the location of the parent of the inorder successor.

1) a) Set  $PTR = RIGHT[LOC]$  and  $SAVE = LOC$

b) Repeat while ( $LEFT[PTR] \neq NULL$ )

Set  $SAVE = PTR$  and  $PTR = LEFT[PTR]$

[end loop]

c) Set  $SUC = PTR$  and  $PARSUC = SAVE$

2) Call  $CASEA(INFO, LEFT, RIGHT, ROOT, SUC, PARSUC)$

3) a) if ( $PAR \neq NULL$ ) then

if ( $LOC = LEFT[PAR]$ ) then

set  $LEFT[PAR] = SUC$

else

set  $RIGHT[PAR] = SUC$

[end if]

else

set  $ROOT = SUC$

b) Set  $LEFT[SUC] = LEFT[LOC]$

Set  $RIGHT[SUC] = RIGHT[LOC]$

4) Return

(iii)  $DEL(INFO, LEFT, RIGHT, ROOT, AVAIL, ITEM)$  :- A binary search tree is in memory and an ITEM of Information is given. This algorithm deletes ITEM from the Tree.

1) Call  $FIND(INFO, LEFT, RIGHT, ROOT, ITEM, LOC, PAR)$

2) if ( $LOC = NULL$ ) then

Print "Item not in tree"

EXIT

[end if]

3) if ( $RIGHT[LOC] \neq NULL$  and  $LEFT[LOC] \neq NULL$ ) then

Call  $CASEB(INFO, LEFT, RIGHT, ROOT, LOC, PAR)$

else

Call CASE A (INFO, LEFT, RIGHT, ROOT, LOC, PAR)

[end if]

4) Set LEFT[LOC] = AVAIL and AVAIL = LOC

5) EXIT

Output :-

1. Insert

2. Delete

3. Inorder Traversal

4. Preorder Traversal

5. Postorder Traversal

6. Find

7. Quit

Enter choice 1

Enter number to insert 10

Enter choice 1

Enter number to insert 8

Enter choice 1

Enter number to insert 20

Enter choice 3

8 10 20

Enter choice 2

Enter number to delete 8

Enter choice 3

10 20



## b) Graphs

### ① Algorithm of BFS (Breadth-First Search)

- 1) Initialize all nodes to the ready state ( $STATUS = 1$ ).
  - 2) Put the starting node A in Queue and change its status to the waiting state ( $STATUS = 2$ ).
  - 3) Repeat step 4 and 5 until Queue is empty:
  - 4) Remove the front node N of Queue. Process N and change the status of N to the processed state ( $STATUS = 3$ ).
  - 5) Add to the rear of Queue all the neighbours of N that are in the ready state ( $STATUS = 1$ ), and change their status to the waiting state ( $STATUS = 2$ ).
- [end loop step 3]
- 6) Exit

### ② Algorithm of DFS (Depth-First Search)

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- 1) Initialize all nodes to the ready state ( $STATUS = 1$ ).
- 2) Push the starting node A onto stack and change its status to the waiting state. ( $STATUS = 2$ )
- 3) Repeat step 4 and 5 until stack is empty.
- 4) Pop the top Node N of stack. Process N and changes its status to the processed state ( $STATUS = 3$ ).
- 5) Push onto stack all the neighbours of N that are still in ready state ( $STATUS = 1$ ), and change their status to the waiting state.
- 6) Exit

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