

Hashing allows user to insert/delete/find records in constant average time.

Linear Search in arrays and linked lists

Search: 70

20	40	50	70	80	90	10
0	1	2	3	4	5	6

Linear Search

 We need to search in a linear fashion, which is costly in practice.





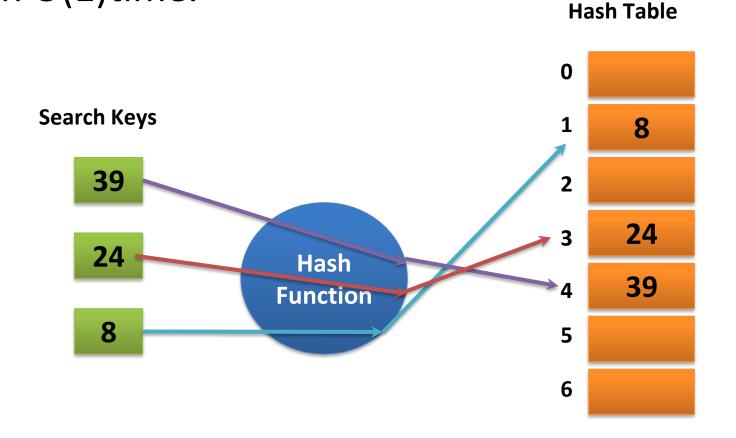
Time complexity of linear search is O(N)

Binary Search

If we keep the data sorted, then it can be searched in **O(Logn)** time using Binary Search, but insert and delete operations become costly as we have to maintain sorted order.



Efficient data structure that can be searched in O(1)time.





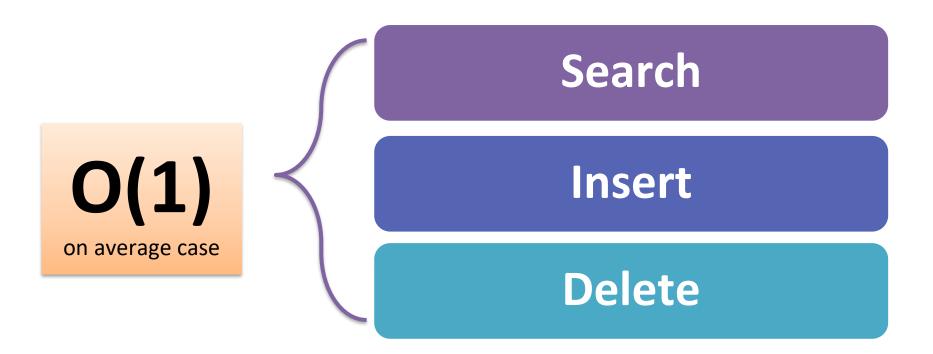




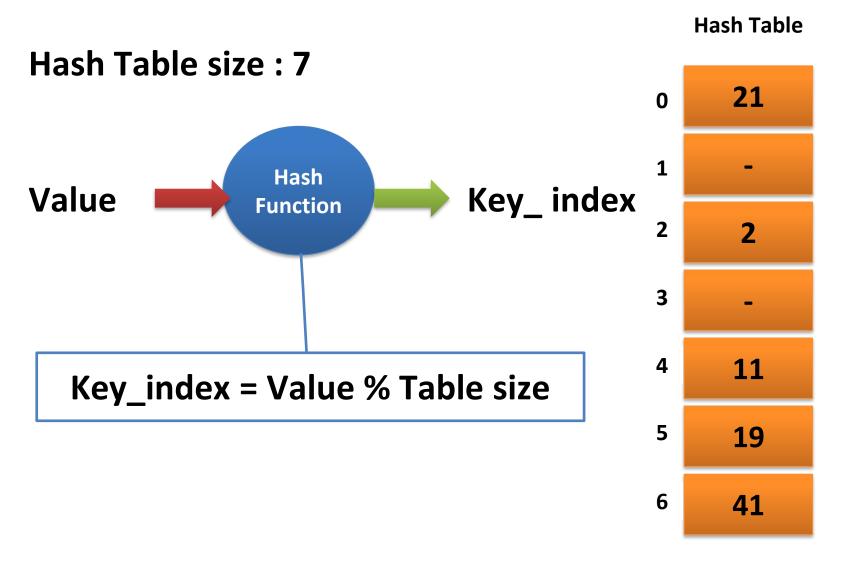


- Hashing is the process of mapping the data item to a hash table with the help of a hashing function.
- A hash table is a collection of items which are stored in such a way as to make it easy to find them later.
- hash function to compute an index so that a data can be stored at a specific location in a table such that it can easily be found.
- With hashing we get O(1) search time on average (under reasonable assumptions) and O(n) in worst case.

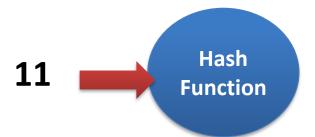
Hashing - Operations

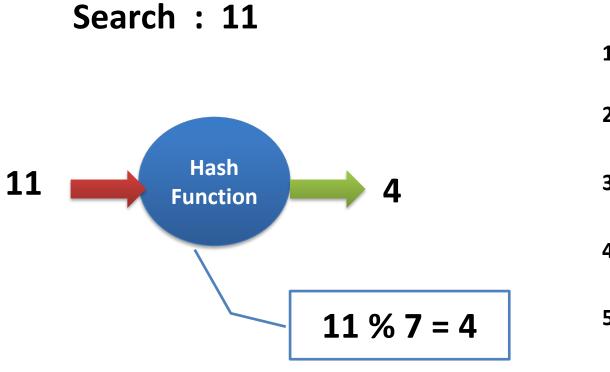


Hash Function

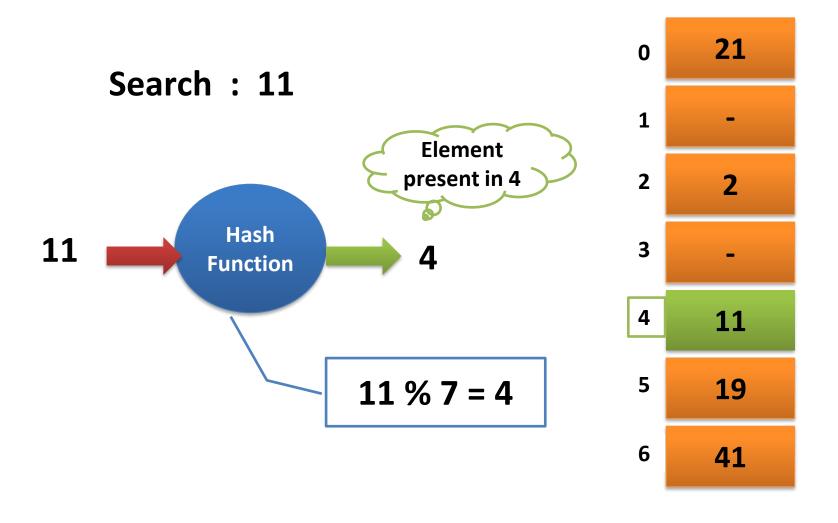


Search: 11

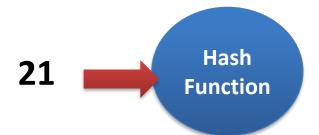


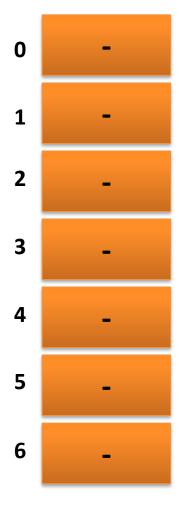


0	21
1	-
2	2
3	-
4	11
5	19
6	41

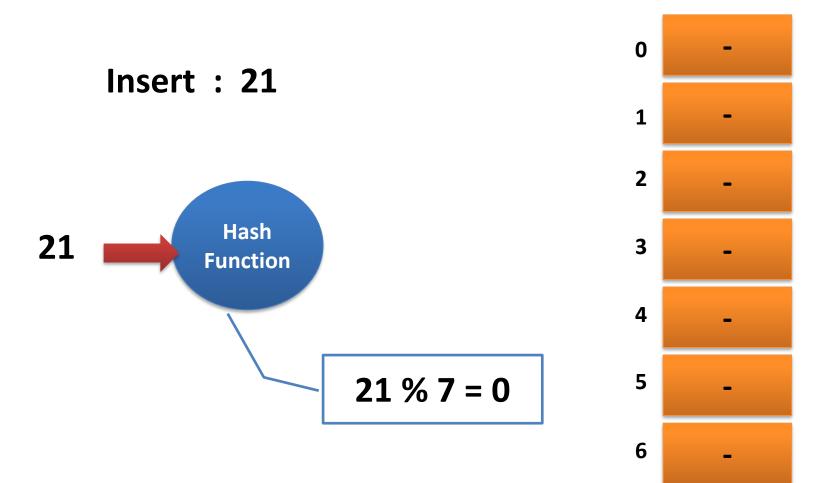


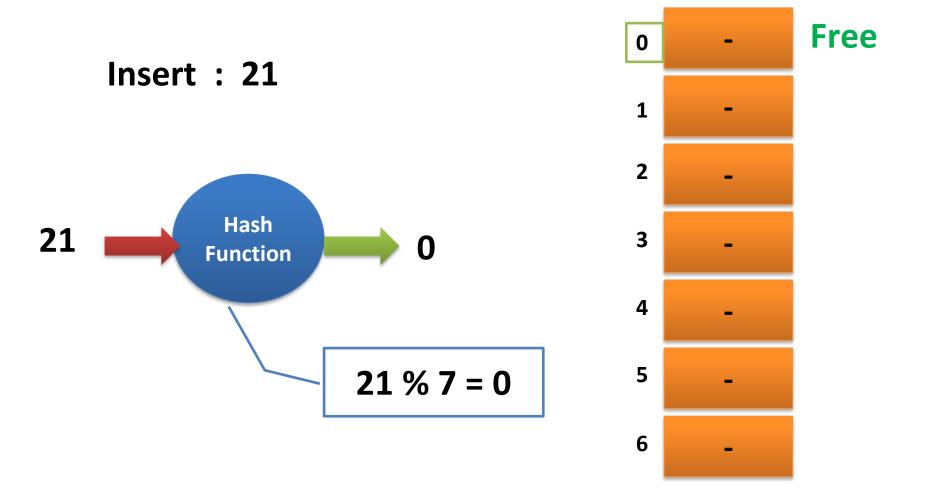
Insert: 21

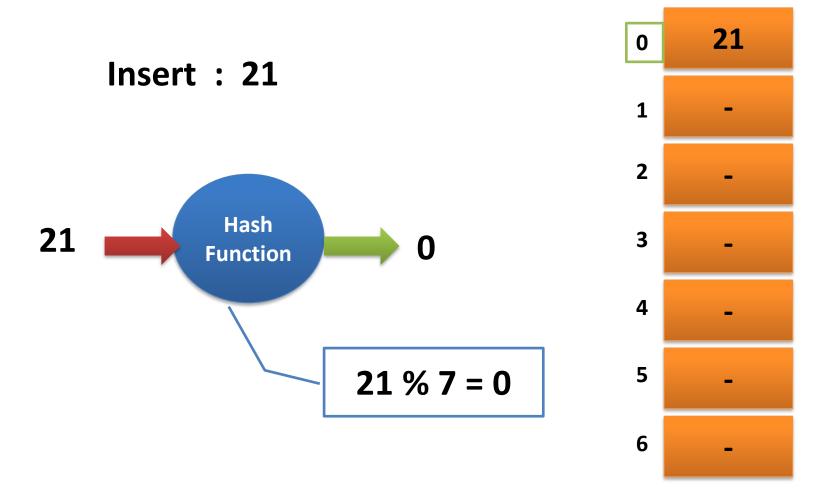






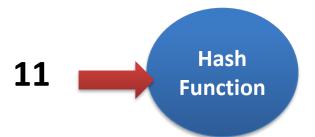


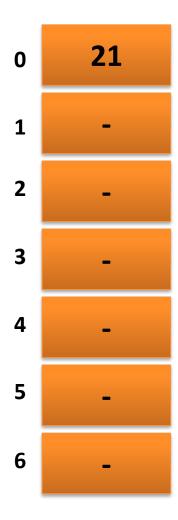


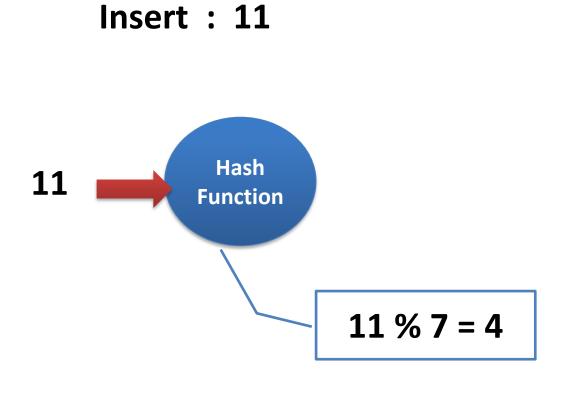


Hash Table

Insert: 11





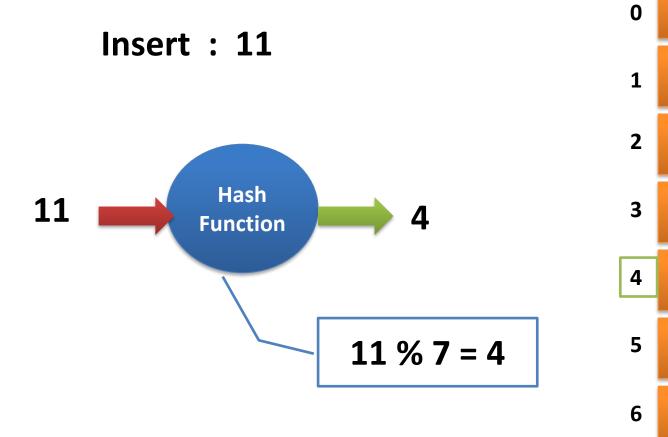


0	21
1	-
2	-
3	-
4	-
5	-
6	-

Hash Table

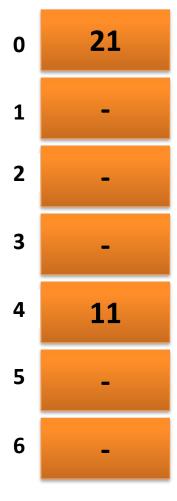
21

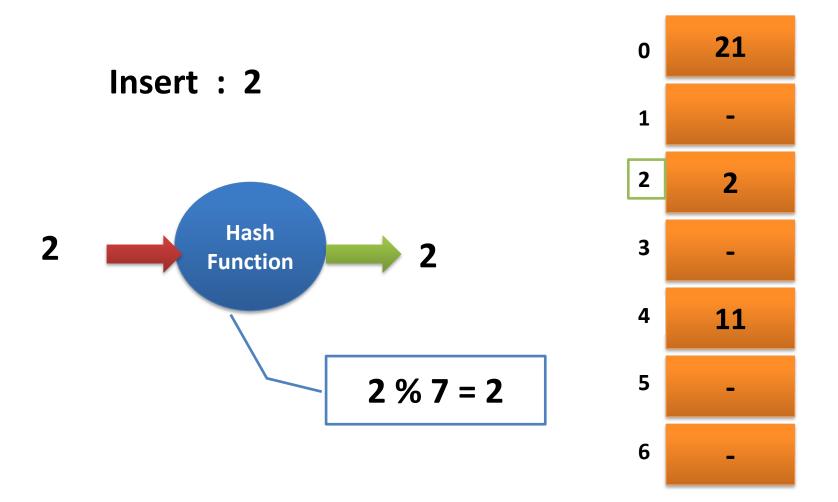
11



Hash Table

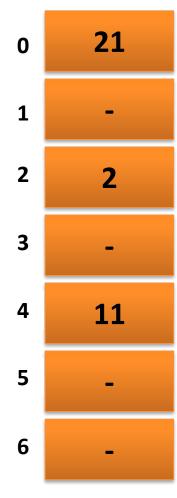
Insert: 2

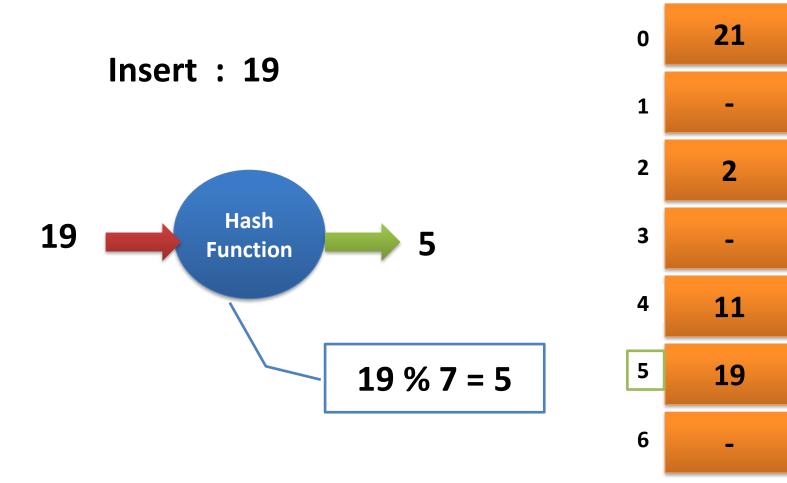




Hash Table

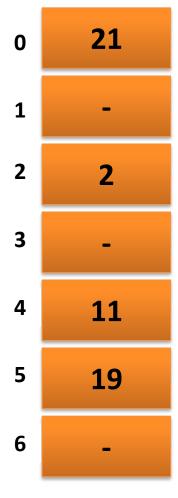
Insert: 19

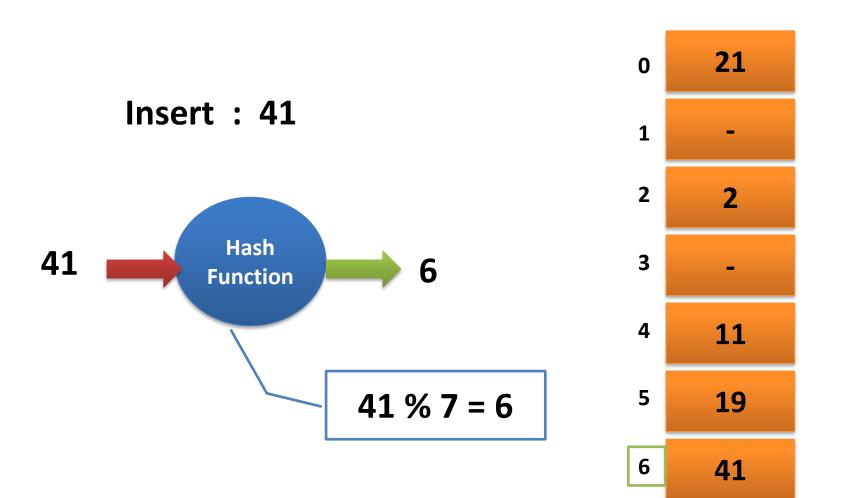




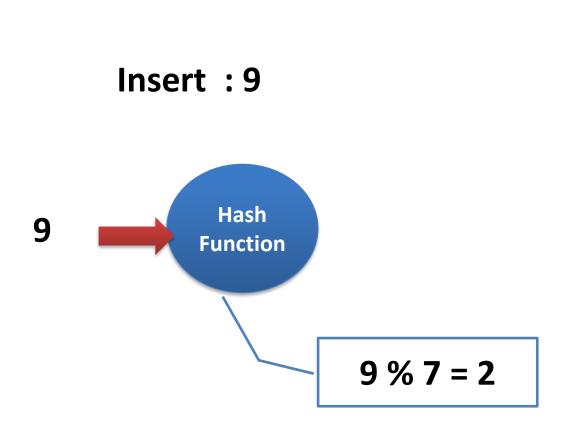
Hash Table

Insert: 41

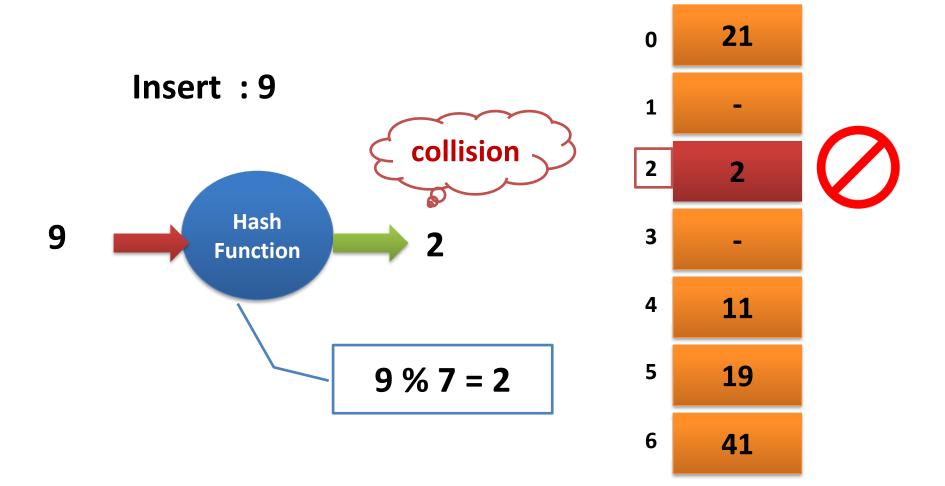




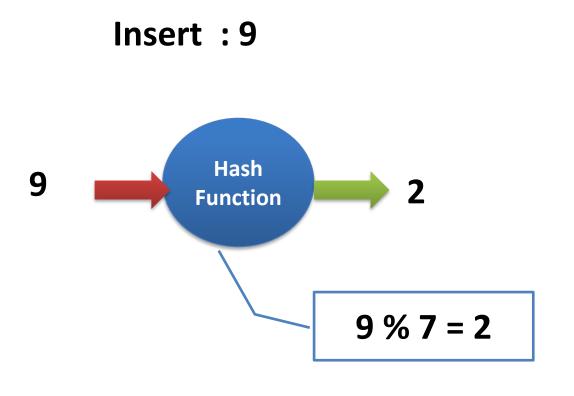
	0	21
Load factor = Number of slots are now occupied	1	-
Table size	2	2
	3	-
	4	11
	5	19
	6	41



0	21
1	-
2	2
3	-
4	11
5	19
6	41



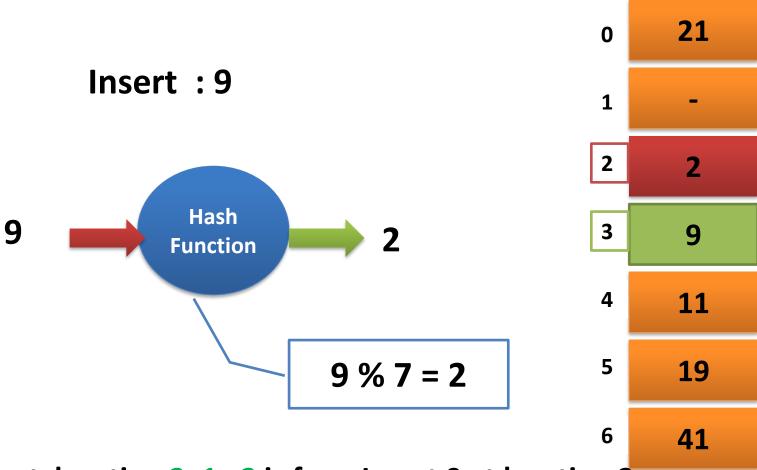
Hash Table





looking for the next available location i + 1 =

Hash Table



next location 2+1=3 is free. Insert 9 at location 3.

Collision Resolution Techniques

- Collision: hash(x) = hash(y) for two different keys x and y.
- Collision Resolution techniques:
 - Closed Hashing or Open Addressing
 - Linear Probing
 - Quadratic Probing
 - Double Hashing
 - Open Hashing:
 - Separate Chaining

Open Addressing

- Linear Probing:
 - (hash(key) + 1) % hashTableSize, (hash(key) + 2)% hashTableSize, etc
- Quadratic Probing:
 - (hash(key) + 1²) % hashTableSize, (hash(key) + 2²)
 % hashTableSize, etc
- Double Hashing:
 - (hash1(key) + i * hash2(key)) % hashTableSize

Search - Procedure

1. Find the hash value of the element to be found.

position = Element % table_size

2. If the hash_table[position] == Element then, element is found in the position.

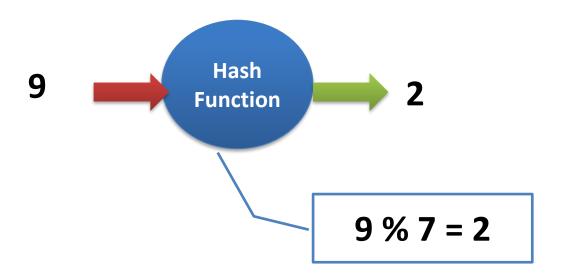
Else

Step through an array one item at a time looking for a desired item.

The search stops when the item is found or when it find any null value or when the search has examined each item without success.

search:9

1. Find the hash value of the element to be found.



Hash Table

0	21
1	-
2	2
3	9
4	11

19

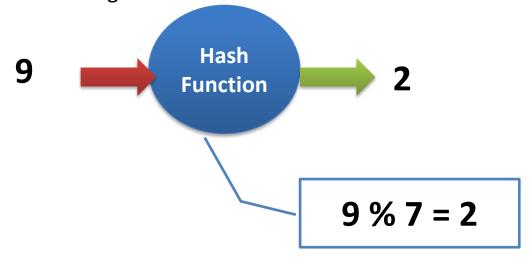
41

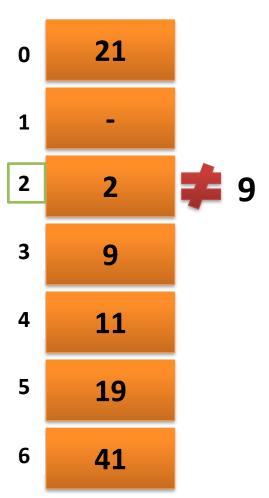
6

search: 9

If (hash_table[position] != Element)then

Step through an array one item at a time looking for a desired item.





Hash Table

search:9

9

If (hash_table[position] != Element) then

Step through an array one item at a time

Hash

Function

looking for a desired item.

Element present in 3

9 % 7 = 2

21

0

1

3

4

5

-

2

9

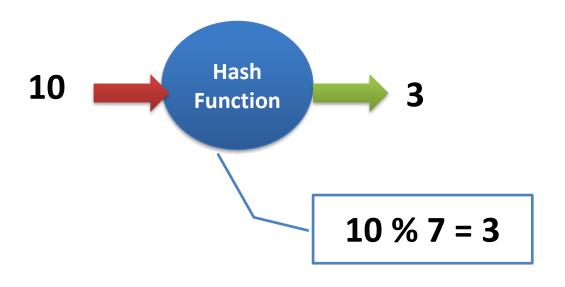
11

19

6 **41**

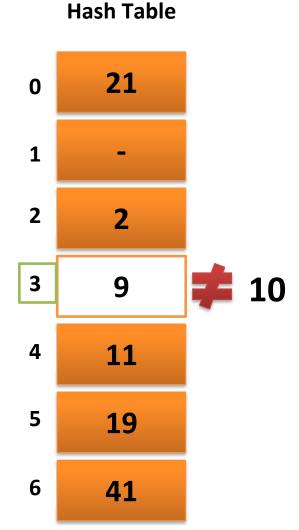
search: 10

1. Find the hash value of the element to be found.

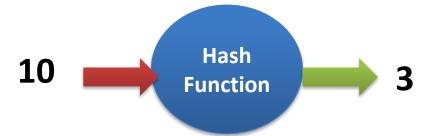


2. If (hash_table[position]!= Element)then

Step through an array one item at a time looking for a desired item.



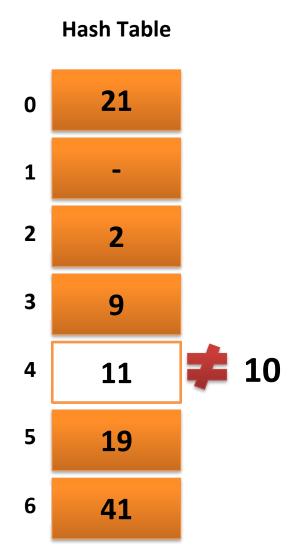
search: 10



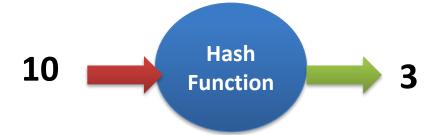
Step through an array one item at a time looking for a desired item.

looking for the next slot 3 + 1 = 4

The search **stops** when the item **is found or** when it **find any null value or** when the search has **examined each item without success.**



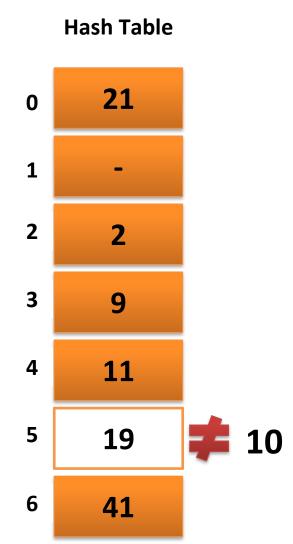
search: 10



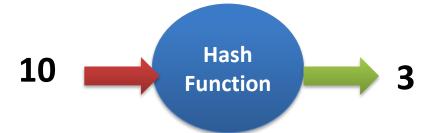
Step through an array one item at a time looking for a desired item.

looking for the next slot 4 + 1 = 5

The search **stops** when the item **is found or** when it **find any null value or** when the search has **examined each item without success.**



search: 10

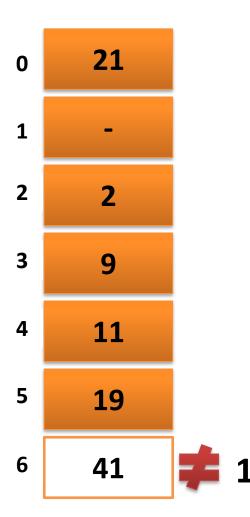


Step through an array one item at a time looking for a desired item.

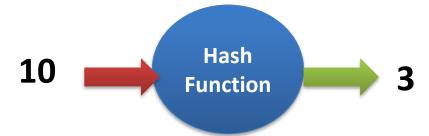
looking for the next slot 5 + 1 = 6

The search **stops** when the item **is found or** when it **find any null value or** when the search has **examined each item without success.**





search: 10

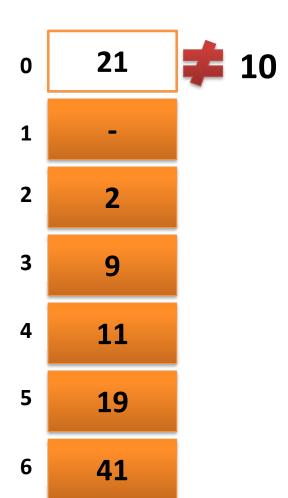


Step through an array one item at a time looking for a desired item.

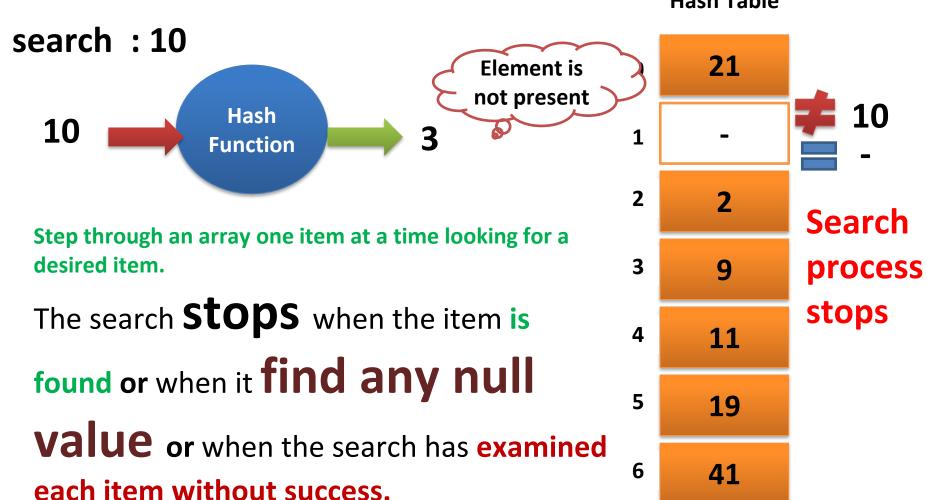
looking for the next slot 6 + 1 = 7 (6+1) mod 7 = 0

The search **stops** when the item **is found or** when it **find any null value or** when the search has **examined each item without success.**

Hash Table



Hashing – unsuccessful search



Quadratic Probing

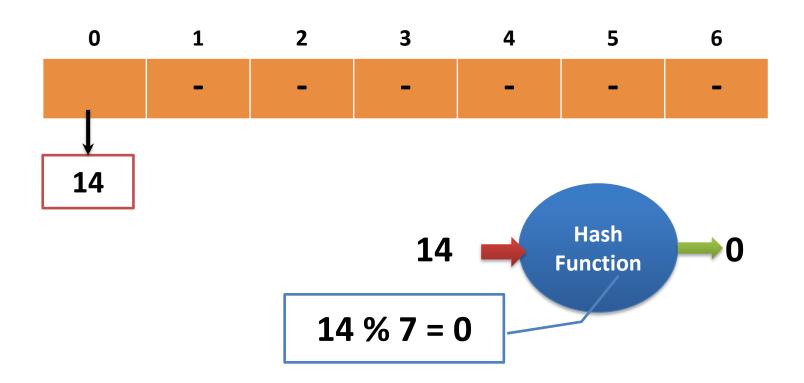
Let hash(x) be the slot index computed using the hash function.

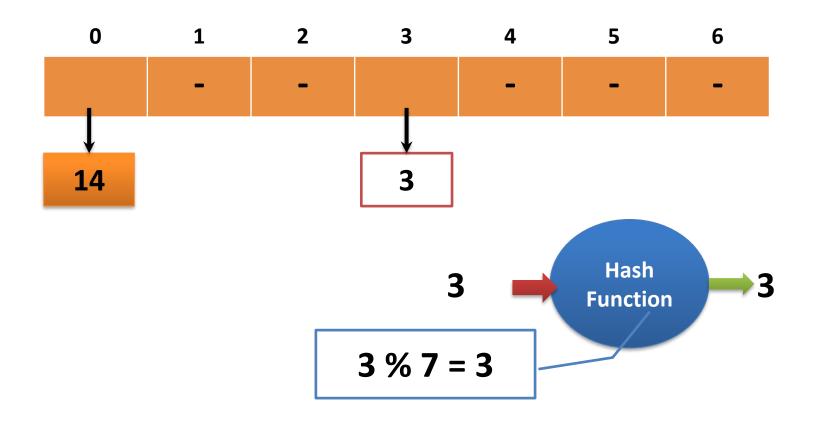
- If the slot hash(x) % S is full, then we try (hash(x) + 1*1) % S.
- If (hash(x) + 1*1) % S is also full, then we try (hash(x) + 2*2) % S.
- If (hash(x) + 2*2) % S is also full, then we try (hash(x) + 3*3) % S.
- This process is repeated for all the values of i until an empty slot is found.

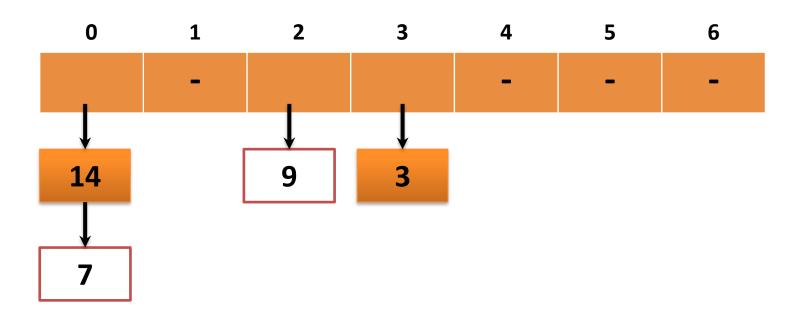
The process of creating a **linked list of values** if they hashed into the same location.

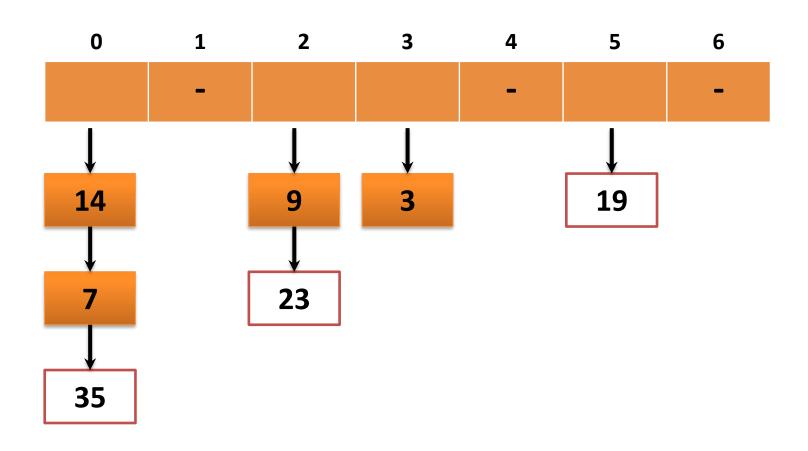
In **open addressing**, each array element can **hold just one entry**. When the array is full, no more records can be added to the table.

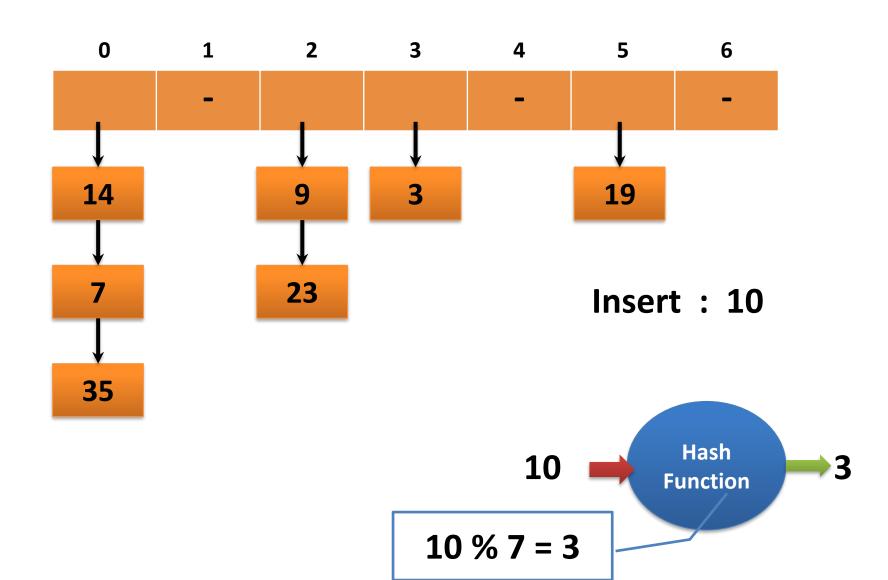
But in **Chaining** each component of the hash table's array **can hold more than one entry**.

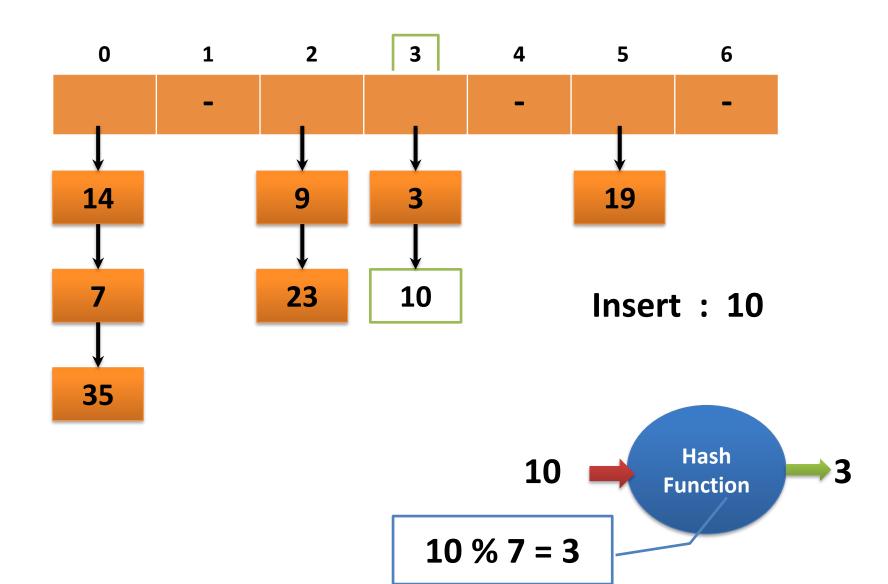


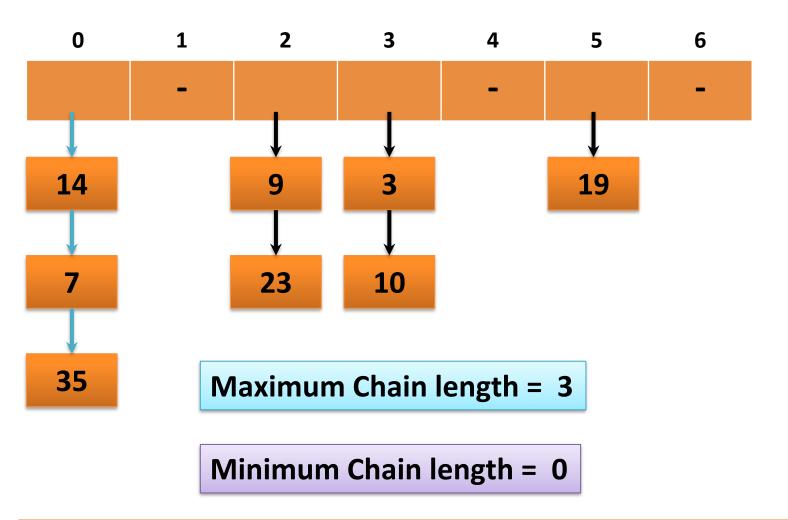








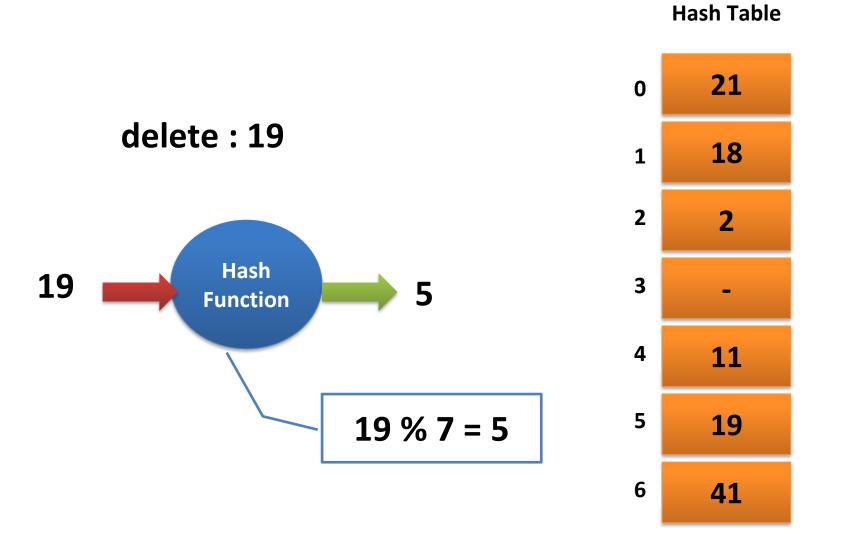


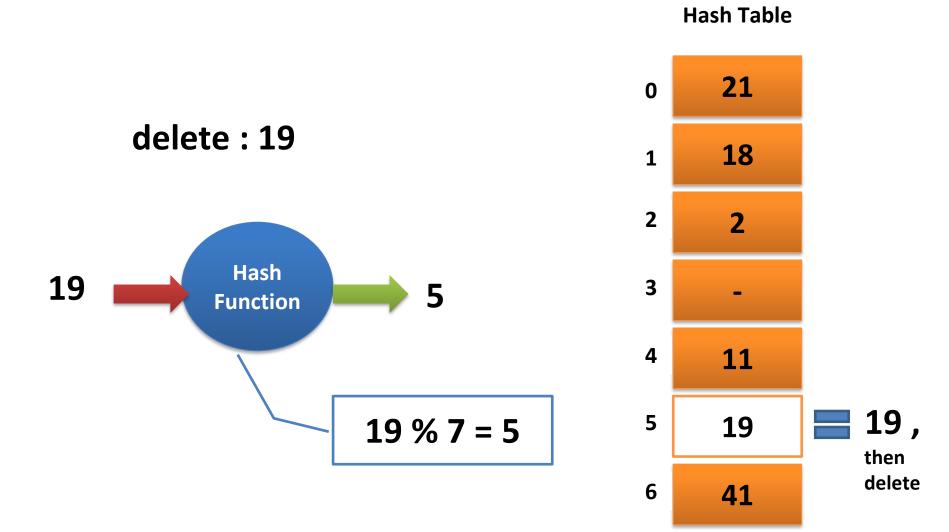


Average Chain length = (3 + 0 + 2 + 2 + 0 + 1 + 0) / 7 = 8 / 7

 separate chaining: if the number of records is not known in advance

 open addressing: if the number of the records can be predicted and there is enough memory available

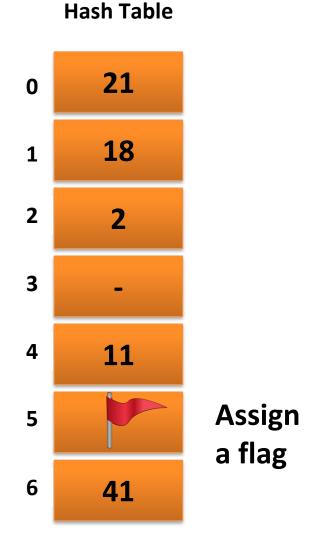




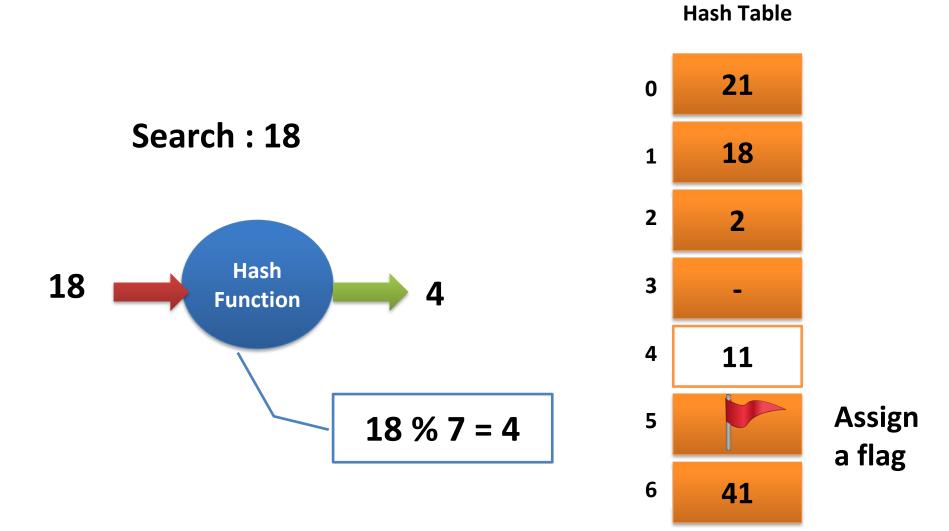
Data 19 is removed and we put a flag to indicate the element is deleted.

The flag indicates that a record once occupied the slot but does so no longer.

deletions are done by marking an element as deleted, rather than erasing it entirely.



 Deleted locations are treated as empty when inserting and as occupied during a search.



Search: 18 Hash 18 **Function** 18 % 7 = 4

Deleted locations are treated as **occupied** during a search.

