

## Jacobian and its Properties

**Definition.** If  $u$  and  $v$  are continuous functions of two independent variables  $x$  and  $y$  having first order partial derivatives, then the Jacobian determinant or the Jacobian of  $u$  and  $v$  is defined by

$$\frac{\partial(u, v)}{\partial(x, y)} \text{ or } J\left(\frac{u, v}{x, y}\right) \text{ or } J = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix}.$$

If  $u, v, w$  are continuous functions of three independent variables  $x, y, z$  having first order partial derivatives, then the Jacobian of  $u, v, w$  w.r.t.  $x, y, z$  is defined as

$$\frac{\partial(u, v, w)}{\partial(x, y, z)} = \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix}.$$

**Example** If  $x = r \cos \theta, y = r \sin \theta$ , find the Jacobian of  $x$  and  $y$  w.r.t  $r$  and  $\theta$ .

**Solution.**

$$x = r \cos \theta \implies \frac{\partial x}{\partial r} = \cos \theta, \frac{\partial x}{\partial \theta} = -r \sin \theta.$$

$$y = r \sin \theta \implies \frac{\partial y}{\partial r} = \sin \theta, \frac{\partial y}{\partial \theta} = r \cos \theta.$$

$$\text{Now, } \frac{\partial(x, y)}{\partial(r, \theta)} = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r.$$

**Example** In cylindrical polar coordinates,  $x = \rho \cos \phi, y = \rho \sin \phi, z = z$ . Show that  $\frac{\partial(x, y, z)}{\partial(\rho, \phi, z)} = \rho$ .

**Solution.**

$$\begin{aligned} \frac{\partial(x, y, z)}{\partial(\rho, \phi, z)} &= \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \phi} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \phi} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \phi} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \phi & -\rho \sin \phi & 0 \\ \sin \phi & \rho \cos \phi & 0 \\ 0 & 0 & 1 \end{vmatrix} \\ &= 1(\rho \cos^2 \phi + \rho \sin^2 \phi) = \rho. \end{aligned}$$

## Properties of Jacobians

**Property I.** If  $u$  and  $v$  are functions of  $r$  and  $s$  where  $r$  and  $s$  are functions of  $x, y$

then  $\frac{\partial(u, v)}{\partial(x, y)} = \frac{\partial(u, v)}{\partial(r, s)} \frac{\partial(r, s)}{\partial(x, y)}$

**Example** If  $u = 2xy, v = x^2 - y^2, x = r \cos \theta, y = r \sin \theta$ , evaluate  $\frac{\partial(u, v)}{\partial(r, \theta)}$  without actual substitution.

**Solution.** Given that  $u$  and  $v$  are functions of  $x$  and  $y$ .  $x$  and  $y$  are functions of  $r$  and  $\theta$ .

$\therefore$  By property (1) of the Jacobians we have

$$\begin{aligned}\frac{\partial(u, v)}{\partial(r, \theta)} &= \frac{\partial(u, v)}{\partial(x, y)} \frac{\partial(x, y)}{\partial(r, \theta)} \\ \frac{\partial(u, v)}{\partial(x, y)} &= \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} \end{vmatrix} = \begin{vmatrix} 2y & 2x \\ 2x & -2y \end{vmatrix} \\ &= -4y^2 - 4x^2 = -4(x^2 + y^2) = -4r^2. \\ \frac{\partial(x, y)}{\partial(r, \theta)} &= \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} \\ &= r \cos^2 \theta + r \sin^2 \theta = r \\ \frac{\partial(u, v)}{\partial(r, \theta)} &= -4(r^2)r = -4r^3.\end{aligned}$$

**Property II.** If  $J_1$  is the Jacobian of  $u, v$  with respect to  $x, y$  and  $J_2$  is the Jacobian of  $x, y$  w.r.t.  $u, v$  then  $J_1 J_2 = 1$ . i.e.,  $\frac{\partial(u, v)}{\partial(x, y)} \bullet \frac{\partial(x, y)}{\partial(u, v)} = 1$ .

**Example** If  $x = u(1 - v), y = uv$  then compute  $J_1$  and  $J_2$  and prove that  $J_1 J_2 = 1$ .

**Solution.** We have

$$J_1 = \frac{\partial(x, y)}{\partial(u, v)}, J_2 = \frac{\partial(u, v)}{\partial(x, y)}$$
$$x = u - uv, y = uv.$$

$$J_1 = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} 1 - v & -u \\ v & u \end{vmatrix} = u - uv + uv = u.$$

We shall express  $u$  and  $v$  in terms of  $x$  and  $y$ .

$$x = u - uv = u - y \Rightarrow x + y = u$$

$$y = uv \Rightarrow v = \frac{y}{u} = \frac{y}{x+y}.$$

$$\text{we get } J_2 = \frac{1}{u}.$$

$$\text{Now } J_1 J_2 = u \frac{1}{u} = 1.$$

**Property III.** If the functions  $u, v, w$  of three independent variables  $x, y, z$  are not independent, then the Jacobian of  $u, v, w$  with respect to  $x, y, z$  vanishes.

**Example** If  $u = x + 2y + z$ ,  $v = x - 2y + 3z$  and  $w = 2xy - xz + 4yz - 2z^2$ , show that they are not independent. Find the relation between  $u, v$  and  $w$ .

**Solution.** Given:  $u = x + 2y + z$ .

$$\frac{\partial u}{\partial x} = 1, \frac{\partial u}{\partial y} = 2, \frac{\partial u}{\partial z} = 1.$$

$$v = x - 2y + 3z.$$

$$\frac{\partial v}{\partial x} = 1, \frac{\partial v}{\partial y} = -2, \frac{\partial v}{\partial z} = 3.$$

$$w = 2xy - xz + 4yz - 2z^2.$$

$$\frac{\partial w}{\partial x} = 2y - z, \frac{\partial w}{\partial y} = 2x + 4z, \frac{\partial w}{\partial z} = -x + 4y - 4z.$$

$$\begin{aligned} \frac{\partial(u, v, w)}{\partial(x, y, z)} &= \begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \\ \frac{\partial w}{\partial x} & \frac{\partial w}{\partial y} & \frac{\partial w}{\partial z} \end{vmatrix} = \begin{vmatrix} 1 & 2 & 1 \\ 1 & -2 & 3 \\ 2y - z & 2x + 4z & -x + 4y - 4z \end{vmatrix} \\ &= 1(-2(-x + 4y - 4z) - 3(2x + 4z)) - 2(-x + 4y - 4z - 3(2y - z)) \\ &\quad + 1(2x + 4z + 2(2y - z)) \\ &= 2x - 8y + 8z - 6x - 12z + 2x - 8y + 8z + 12y - 6z + 2x + 4z + 4y - 2z = 0. \end{aligned}$$

Hence,  $u, v, w$  are not independent.

Now  $u + v = 2x + 4z$ ,  $u - v = 4y - 2z$ .

$$(u + v)(u - v) = 2(x + 2z) \cdot 2(2y - z)$$

$$u^2 - v^2 = 4(2xy - xz + 4yz - 2z^2)$$

$$u^2 - v^2 = 4w.$$