```
* Lavet af:
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* Mesterprogrammør.
 * 3. semsterprojekt, Ingeniørhøjskolen i Århus.
 * PWM Sinus til fuld bro inverter i solfanger.
 * /
#include project.h>
const uint8 sinetable[ 64 ] = { 1, 2, 5, 10, 15, 21, 29, 37, 46, 56,
                               67, 78, 90, 102, 115, 127, 139, 152,
                               164, 176, 187, 198, 208,
                                 217, 225, 233, 239, 244, 249, 252, 253,
                                 254, 253, 252, 249, 244, 239, 233, 225,
                                 217, 208, 198, 187, 176, 164, 152, 139,
                                 127, 115, 102, 90, 78, 67, 56, 46, 37,
                                 29, 21, 15, 10, 5, 2, 1, 0, };
uint8 sineCursor = 0;
int main()
   /* Place your initialization/startup code here (e.g. MyInst Start()) */
          PWMsinus Start();
   /* CyGlobalIntEnable; */ /* Uncomment this line to enable global interrupts. */
   for(;;) {
       Pin 2 Write(0);
       Pin 1 Write(1);
       for(sineCursor = 0; sineCursor < 64; sineCursor++)</pre>
                    CyDelayUs (152);
                    PWMsinus WriteCompare( sinetable[ sineCursor ] );
       sineCursor = 0;
```

```
Pin 1 Write(0);
        Pin 2 Write(1);
        for(sineCursor = 0; sineCursor < 64; sineCursor++)</pre>
                        CyDelayUs (152);
                        PWMsinus_WriteCompare( sinetable[ sineCursor ] );
         sineCursor = 0;
           }
}
/* [] END OF FILE */
   const uint8 sinetable[ 64 ] = { 1, 2, 5, 10, 15, 21, 29, 37, 46, 56,
                                      67, 78, 90, 102, 115, 127, 139, 152,
                                      164, 176, 187, 198, 208,
                                        217, 225, 233, 239, 244, 249, 252, 253,
                                        254, 253, 252, 249, 244, 239, 233, 225, 217, 208, 198, 187, 176, 164, 152, 139,
                                        127, 115, 102, 90, 78, 67, 56, 46, 37,
                                        29, 21, 15, 10, 5, 2, 1, 0, };
  */
```