Balle.java

```
1 package Serveur.triangulation;
3 import java.awt.Graphics;
 4 import java.awt.Rectangle;
 5 import java.io.Closeable;
6 import java.util.ArrayList;
8 import Serveur.maths.Utils;
9 import Serveur.maths.vectors.Vector2d;
10 import Serveur.maths.vectors.Vector3d;
12 public class Balle implements Closeable {
13
      private ArrayList<Vector2d> gradients = new ArrayList<Vector2d>();
14
      private Vector2d pos;
15
      public double learningRate = 0.1;
16
17
      public double momentum = 0.5;
18
19
      private int nbGradientsMax;
20
      private volatile boolean training = false;
21
22
      public Balle(double x, double y) {
23
          pos = new Vector2d(x, y);
24
25
          setMomentum(momentum);
26
      }
27
28
      public Vector2d getPosition() {
29
          return pos.clone();
30
31
      public void setPosition(Vector2d pos) {
32
33
          this.pos = pos.clone();
34
35
          gradients.clear();
36
      }
37
38
      private void setMomentum(double momentum) {
39
          this.momentum = momentum;
40
          nbGradientsMax = (int) (Math.log(0.02) / Math.log(momentum));
41
42
          while (gradients.size() > nbGradientsMax)
43
               gradients.remove(0);
44
      }
45
46
      private void gradientDescent(final ArrayList<Vector3d> cercles) {
47
          training = true;
48
          Vector3d[] tangentes = calculateTangentes(cercles);
49
50
          Vector2d gradient = new Vector2d();
51
          int nbCercles = cercles.size();
52
53
          for (Vector3d t : tangentes) {
               double cte = 2 * (t.x * pos.x + t.y * pos.y + t.z)
54
55
                       / (nbCercles * (t.x * t.x + t.y * t.y));
56
57
               gradient.x += cte * t.x;
58
               gradient.y += cte * t.y;
59
          }
60
          for (Vector2d g : gradients) {
61
62
               g.x *= momentum;
```

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```
g.y *= momentum;
 63
 64
           }
 65
66
           gradients.add(gradient);
67
 68
           while (gradients.size() > nbGradientsMax)
 69
                gradients.remove(0);
 70
 71
           Vector2d totalGradient = new Vector2d();
72
 73
           for (Vector2d g : gradients)
 74
                totalGradient = totalGradient.add(g);
 75
 76
           training = false;
 77
 78
           pos = pos.sub(totalGradient.mult(learningRate));
 79
       }
80
81
       private Vector3d[] calculateTangentes(final ArrayList<Vector3d> cercles) {
 82
           ArrayList<Vector3d> tangentes = new ArrayList<Vector3d>(); // (a, b, c)
 83
                                                                          // tel que a
                                                                          // * x + b *
 84
85
                                                                          // y + c = 0
86
87
           for (Vector3d cercle : cercles) {
88
                if (cercle.z == 0)
 89
                    continue;
 90
 91
                Vector3d inter = cercle.clone();
92
                Vector2d centre = new Vector2d(cercle.x, cercle.y);
93
                double distance = centre.distance(pos);
 94
95
                if (distance == 0)
96
                    continue;
97
98
                double coeff = cercle.z / distance; // rayon / distance
99
                inter.x += coeff * (pos.x - cercle.x);
100
101
                inter.y += coeff * (pos.y - cercle.y);
102
103
                double a = pos.x - inter.x;
104
                double b = pos.y - inter.y;
105
                double c = -a * inter.x - b * inter.y;
106
107
                if (Math.abs(a) > Math.abs(b) && Math.abs(a) > Math.abs(c)) {
108
                    b /= a;
109
                    c /= a;
110
                    a = 1;
111
                } else if (Math.abs(b) > Math.abs(c)) {
112
                    a /= b;
113
                    c /= b;
                    b = 1;
114
115
                } else {
116
                    a /= c;
117
                    b /= c;
                    c = 1;
118
119
120
121
               Vector3d tangente = new Vector3d(a, b, c);
122
123
                if (tangente.normSquared() > 0)
124
                    tangentes.add(tangente);
```

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```
125
           }
126
127
           Vector3d[] list = tangentes.toArray(new Vector3d[tangentes.size()]);
128
           tangentes.clear();
129
130
           return list;
131
       }
132
       public Vector2d train(final ArrayList<Vector3d> cercles, int iterations) {
133
134
135
           for (int i = 0; i < iterations; i++)</pre>
136
               gradientDescent(cercles);
137
138
           return pos.clone();
139
       }
140
141
       public void paintComponent(Graphics g, double xmin, double xmax,
142
               double ymin, double ymax) {
143
           Rectangle rect = g.getClipBounds();
144
145
           int x = (int) Utils.map(pos.x, xmin, xmax, rect.x, rect.x + rect.width);
           int y = (int) Utils.map(pos.y, ymin, ymax, rect.y + rect.height,
146
147
                   rect.y);
148
           int radius = 5;
149
           g.fillOval(x - radius, y - radius, 2 * radius, 2 * radius);
150
       }
151
152
153
       public void close() {
154
           while (training);
155
           gradients.clear();
156
       }
157 }
```