# Exercise 1

(a) Using Theorem 3.6: With  $|\mathcal{H}| = 3^3 = 27$ 

$$\Pr_{T \ \mathcal{D}^m} (\forall h \in \mathcal{H} : |err_T(h) - err_D(h)| \le \epsilon) > 1 - \delta$$

$$\Pr_{T \ \mathcal{D}^m} (\forall h \in \mathcal{H} : |err_T(h) - err_D(h)| \le \epsilon) > 0.9$$

$$\Rightarrow \delta = 0.1$$

$$\begin{split} m &\geq \frac{1}{2\epsilon^{2}} \log \left( \frac{2|\mathcal{H}|}{\delta} \right) \\ 143 &\geq \frac{1}{2\epsilon^{2}} \log \left( \frac{2 \cdot 3^{3}}{0.1} \right) \\ 143 &\geq \frac{1}{2\epsilon^{2}} (\log(54) - \log(0.1)) \\ 143 &\geq \frac{1}{2\epsilon^{2}} (\log(54) - \log(0.1)) \\ \epsilon^{2} &\geq \frac{(\log(54) - \log(0.1))}{1432} \\ |\epsilon| &\geq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \\ \Rightarrow &\epsilon &\geq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \\ \Pr_{T \mathcal{D}^{m}} \left( \forall h \in \mathcal{H} : |err_{T}(h) - err_{D}(h)| \leq \epsilon \right) > 0.9 \\ \Pr_{T \mathcal{D}^{m}} \left( \forall h \in \mathcal{H} : |0.03 - err_{D}(h)| \leq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \right) > 0.9 \\ \Rightarrow &err_{D}(h) \leq 0.03 + \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \simeq 0.208149 \simeq 0.21 \end{split}$$

(b) Using Theorem 3.4:

 $\Pr_{T \mathcal{D}^m} (\forall h \in \mathcal{H} : \text{if } h \text{ is consistent with } T, \text{ then } err_D(h) \leq \epsilon) 1 - \delta$   $\Pr_{T \mathcal{D}^m} (\forall h \in \mathcal{H} : \text{if } h \text{ is consistent with } T, \text{ then } err_D(h) \leq 0.01) 0.9$   $\Rightarrow \epsilon = 0.01, \delta = 0.1$ 

$$m \ge \frac{1}{\epsilon} \ln \left( \frac{|\mathcal{H}|}{\delta} \right)$$

$$m \ge \frac{1}{0.01} \ln \left( \frac{3^3}{0.1} \right)$$

$$m \ge 100(\ln(27) - \ln(0.1)) \simeq 559.84$$

$$\Rightarrow m \ge 560$$

## Exercise 2

# Exercise 3

## Exercise 4

See Referencesappendix for code.

```
Final probabilities: [0.4 0.4 0.2]

Tracked weight vectors:

Round: 1 Weights: [1. 1. 1.]
Round: 2 Weights: [0.5 0.5 1.]
Round: 3 Weights: [0.5 0.25 0.5]
Round: 4 Weights: [0.25 0.25 0.25]
Round: 5 Weights: [0.25 0.125 0.125]
Round: 6 Weights: [0.125 0.125 0.0625]
Round: 7 Weights: [0.125 0.0625 0.04419417]
```

## Exercise 5

See Referencesappendix for code.

```
Probabilities:

Round: 1 Probabilities: [0.33 0.33 0.33]
Round: 2 Probabilities: [0.46 0.27 0.27]
Round: 3 Probabilities: [0.28 0.51 0.21]
Round: 4 Probabilities: [0.25 0.42 0.33]

Weight vectors:

Round: 1 Weights: [1. 1. 1.]
Round: 2 Weights: [2.83 1. 1.]
Round: 3 Weights: [2.83 8.48 1.]
Round: 4 Weights: [2.83 8.48 5.32]
```

# Exercise 6

# **Appendix**

#### Code for Exercise 4

```
import numpy as np

def mwu_algorithm(loss_matrix, events, rounds, alpha):
    # initial weight vector of 1s
    weights = np.ones((loss_matrix.shape[0]))
    weights_tracking = {}
    weights_tracking[0] = weights
    # more convenient to loop through rounds and events
    rounds_arr = [i for i in range(rounds)]
    for round, event in zip(rounds_arr, events):
```

```
# getting the current probabilities, not really needed here
12
          p = probabilities(weights)
13
          # need to use event-1 as events start at 1 but indexing at 0
14
          weights = np.power((1 - alpha), loss_matrix[:, event-1]) * weights
          # loss isn't really needed
          loss = calculate_loss(loss_matrix, p, event-1)
17
          weights_tracking[round+1] = weights
19
      return p, weights_tracking
20
21
  def probabilities(weights):
      return weights / np.sum(weights)
24
  def calculate_loss(loss_matrix, probabilities, event):
      return np.sum(probabilities * loss_matrix[:, event])
27
 loss_matrix = np.array([[0,1,1,0],
                           [1,0,1,1],
                           [1,1,0,0.5]
31
32
observed_events = [3,1,2,1,2,4]
35 p_6, weights_tracking = mwu_algorithm(loss_matrix, observed_events, 6, alpha
     =0.5)
37 print(f'Final probabilities: {p_6}\n')
38 print(f'Tracked weight vectors: \n')
39 for key, val in weights_tracking.items():
print(f'Round:\t{key + 1}\tWeights:\t{val}')
```

#### Code for Exercise 5

```
1 import numpy as np
 from copy import deepcopy
  def exp3(gamma, rounds, actions, rewards):
      weights = np.ones((len(actions)))
      rounds_arr = [i for i in range(rounds)]
      n = len(actions)
      # for tracking weights and probabilities
      weights_tracking = {}
      probabilities_tracking = {}
      weights_tracking[0] = np.ones(len(actions))
11
      probabilities_tracking[0] = probability_dist(weights, gamma)
      for round, action in zip(rounds_arr, actions):
13
          probabilities = probability_dist(weights, gamma)
          probabilities_tracking[round] = probabilities
          reward = rewards[action]
16
          weights = update_weights(weights, reward, probabilities, action,
     gamma)
          weights_tracking[round + 1] = deepcopy(weights)
18
19
      probabilities_tracking[rounds] = probability_dist(weights, gamma)
20
      return weights_tracking, probabilities_tracking
 def probability_dist(weights, gamma):
      return (1 - gamma) * (weights / np.sum(weights)) + gamma / len(weights)
24
26 def update_weights(weights, reward, probabilities, action, gamma):
n = len(weights)
```

```
# only update chosen action
      weights[action] = weights[action] * np.exp((gamma * reward) / (n *
29
     probabilities[action]))
     return weights
31
32
33 action_seq = np.array([ 1, 2, 3 ])
_{34} rewards = np.array([ 3, 5, 3 ]) * np.log(2)
weights, probs = exp3(gamma=0.5, rounds=3, actions=action_seq - 1, rewards=
     rewards)
38 print(f'Probabilities: \n')
39 for key, val in probs.items():
      print(f'Round:\t{key + 1}\tProbabilities:\t{val.round(2)}')
42 print(f'\nWeight vectors: \n')
for key, val in weights.items():
print(f'Round:\t{key + 1}\tWeights:\t{val.round(2)}')
```