Exercise 1

(a) Using Theorem 3.6: With $|\mathcal{H}| = 3^3 = 27$

$$\Pr_{T \mathcal{D}^{m}} (\forall h \in \mathcal{H} : |err_{T}(h) - err_{D}(h)| \leq \epsilon) > 1 - \delta$$

$$\Pr_{T \mathcal{D}^{m}} (\forall h \in \mathcal{H} : |err_{T}(h) - err_{D}(h)| \leq \epsilon) > 0.9$$

$$\Rightarrow \delta = 0.1$$

$$\begin{split} m &\geq \frac{1}{2\epsilon^{2}} \log \left(\frac{2|\mathcal{H}|}{\delta} \right) \\ 143 &\geq \frac{1}{2\epsilon^{2}} \log \left(\frac{2 \cdot 3^{3}}{0.1} \right) \\ 143 &\geq \frac{1}{2\epsilon^{2}} (\log(54) - \log(0.1)) \\ 143 &\geq \frac{1}{2\epsilon^{2}} (\log(54) - \log(0.1)) \\ \epsilon^{2} &\geq \frac{(\log(54) - \log(0.1))}{1432} \\ |\epsilon| &\geq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \\ \Rightarrow &\epsilon &\geq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \\ \Pr_{T \mathcal{D}^{m}} \left(\forall h \in \mathcal{H} : |err_{T}(h) - err_{D}(h)| \leq \epsilon \right) > 0.9 \\ \Pr_{T \mathcal{D}^{m}} \left(\forall h \in \mathcal{H} : |0.03 - err_{D}(h)| \leq \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \right) > 0.9 \\ \Rightarrow &err_{D}(h) \leq 0.03 + \sqrt{\frac{(\log(54) - \log(0.1))}{286}} \simeq 0.208149 \simeq 0.21 \end{split}$$

(b) Using Theorem 3.4:

$$\Pr_{T \mathcal{D}^m} (\forall h \in \mathcal{H} : \text{if } h \text{ is consistent with } T, \text{ then } err_D(h) \leq \epsilon) 1 - \delta$$

$$\Pr_{T \mathcal{D}^m} (\forall h \in \mathcal{H} : \text{if } h \text{ is consistent with } T, \text{ then } err_D(h) \leq 0.01) 0.9$$

$$\Rightarrow \epsilon = 0.01, \delta = 0.1$$

$$m \ge \frac{1}{\epsilon} \ln \left(\frac{|\mathcal{H}|}{\delta} \right)$$

$$m \ge \frac{1}{0.01} \ln \left(\frac{3^3}{0.1} \right)$$

$$m \ge 100(\ln(27) - \ln(0.1)) \simeq 559.84$$

$$\Rightarrow m \ge 560$$

Exercise 2

- (a) The dimension of the instance space is $l = a \cdot v$. Such a decision scheme can be described using $|h|_{\Delta} \in O(n(\log n + \log l)) = O(n(\log n + \log(a \cdot v))) = O(n(\log n + \log a + \log v))$ bits

Exercise 3

(a) The VC-Dimension is 3. To prove this, let us prove some properties which every Y, that shatters \mathcal{H} , must hold.

Notation:

- $a_i, b_i \in \mathbb{R}, i \in \mathbb{N}$
- $y_{i,j} \in Y, i, j \in \mathbb{N} \to y_{i,j} = (a_i, b_j)$ (analog for $y'_{i,j} \in Y'$)

Property 1:

$$\neg \exists y_{i,j} \exists y_{i',j'} \exists y_{i'',j''} (a_i \neq a_{i'} \land a_i \neq a_{i''} \land a_{i'} \neq a_{i''} \land b_i \neq b_{i'} \land b_i \neq b_{i''} \land b_{i'} \neq b_{i''})$$

In words: There cannot be 3 vectors in Y that have neither their a nor b values in common. Let's prove this be counterexample.

Let $Y' = \{(a_1, b_1), (a_2, b_2), (a_3, b_3)\} \subseteq Y$. There exists no $h_{a,b} \in \mathcal{H}$, such that $Y' \subseteq S_{h_{a,b}}$. Therefore, $Y' = S_{h_{a,b}} \cap Y$ does not hold.

Property 2:

$$\neg \exists y_{i,j} \exists y_{i'',j''} \exists y_{i'',j''} (y_{i,j} \neq y_{i'',j'} \land y_{i,j} \neq y_{i'',j''} \land y_{i',j'} \neq y_{i'',j''}) \land ((a_i = a_{i'} \land a_i = a_{i''}) \lor (b_i = b_{i'} \land b_i = b_{i''}))$$

In words: There cannot be 3 vectors in Y that have their a or b values in common. Let's prove this be counterexample.

Let $Y' = \{(a_1, b_1), (a_1, b_2)\} \subseteq \{(a_1, b_1), (a_1, b_2), (a_1, b_3)\} \subseteq Y$ (analog when the *b*-components are equal). Then there exists no $h_{a,b} \in \mathcal{H}$ so that $Y' \subseteq S_{h_{a,b}}$ but $(a_1, b_3) \notin S_{h_{a,b}}$. This is true, since the only functions $h_{a,b}$ with $Y' \subseteq S_{h_{a,b}}$ are where $a = a_1$, thus also $(a_1, b_3) \notin S_{h_{a,b}}$, which is a contradiction.

Property 3:

$$\neg \exists y_{i,j} \exists y_{i',j'} \exists y_{i'',j''} (y_{i,j} \neq y_{i',j'} \land y_{i,j} \neq y_{i'',j''} \land y_{i',j'} \neq y_{i'',j''}) \land (a_i = a_{i'} \land b_{i'} = b_{i''})$$

In words: There cannot be a vector containing of an a-component that also exists in another vector and a b-component that also exists in another vector.

Let's prove this be counterexample.

Let $Y' = \{(a_1, b_2)\} \subseteq \{(a_1, b_1), (a_1, b_2), (a_2, b_2)\} \subseteq Y$. For all $h_{a,b} \in \mathcal{H}$ with $Y' \subseteq S_{h_{a,b}}$ $a = a_1 \lor b = b_2$ must hold. However, for such $h_{a,b}$ $(a_1, b_1) \in S_{h_{a,b}}$ or $(a_2, b_2) \in S_{h_{a,b}}$ would also hold. This is a contradiction.

Thus, the only valid form of Y must be (or analog when two b-components are equal):

$$Y := \{(a_1, b_1), (a_1, b_2), (a_2, b_2)\}, a_1 \neq a_2 \land b_1 \neq b_2 \land b_1 \neq b_3 \land b_2 \neq b_3$$

We can prove that Y shatters \mathcal{H} :

• $Y' = \emptyset$: We can use h_{a_0,b_0} with $a_0 \notin \{a_1,a_2\}, b_0 \notin \{b_1,b_2,b_3\}$. Thus, $Y \notin S_{h_{a_0,b_0}}$. So $Y' = \emptyset = S_{h_{a_0,b_0}} \cap Y$.

- $Y' = \{(a_1, b_i)\}, i \in \{1, 2\}$: We can use h_{a_0, b_i} with $a_0 \notin \{a_1, a_2\}$. Thus, $Y' = \emptyset = S_{h_{a_0, b_i}} \cap Y$.
- $Y' = \{(a_2, b_3)\}:$ We can use h_{a_2,b_3} . Thus, $Y' = \emptyset = S_{h_{a_0,b_i}} \cap Y$.
- $Y' = \{(a_1, b_1), (a_1, b_2)\}:$ We can use h_{a_1,b_1} . Thus, $Y' = \emptyset = S_{h_{a_0,b_i}} \cap Y$.
- $Y' = \{(a_1, b_i), (a_2, b_3)\}, i \in \{1, 2\}$: We can use h_{a_2, b_i} . Thus, $Y' = \emptyset = S_{h_{a_0, b_i}} \cap Y$.
- Y' = Y: We can use h_{a_1,b_3} . Thus, $Y' = \emptyset = S_{h_{a_0,b_i}} \cap Y$.

So, the VC-Dimension is at least 3. Let's now prove, that no Y with |Y| > 3 shatters \mathcal{H} .

For now, let Y be $Y := \{(a_1, b_1), (a_1, b_2), (a_2, b_2)\}, a_1 \neq a_2 \land b_1 \neq b_2 \land b_1 \neq b_3 \land b_2 \neq b_3$ (which we proved was the only valid form of Y with |Y| = 3). We can now try to add any $y_{i,j}$ to Y:

- Let's try to add $y_{1,j} = (a_1, b_j), j \in \mathbb{N}$. This would violate **Property 1**. Thus, we cannot add any such $y_{1,j}$.
- Let's try to add $y_{2,j} = (a_2, b_j), j \in \mathbb{N}$. Since $(a_2, b_3) \in Y$, $b_j \in \mathbb{R} \setminus \{b_3\}$. Then the condition in the remark would not hold for Y' = Y. Thus, we cannot add any such $y_{2,j}$.
- Let's try to add $y_{3,4} = (a_3, b_4), a_3 \in \mathbb{R} \setminus \{a_1, a_2\}, b_4 \notin \{b_1, b_2, b_3\}$. This would violate **Property 1**. Thus, we cannot add any such $y_{3,4}$.
- Let's try to add $y_{3,j} = (a_3, b_j)$, $j \in \{1, 2\}$, $a_3 \in \mathbb{R} \setminus \{a_1, a_2\}$. Then, we cannot find any $h_{a,b} \in \mathcal{H}$ for Y' = Y, so that the condition in the remark holds. Thus, we cannot add any such $y_{3,j}$
- Let's try to add $y_{3,j} = (a_3, b_3)$, $a_3 \in \mathbb{R} \setminus \{a_1, a_2\}$. Then, for $Y' = \{(a_1, b_2), (a_2, b_3), (a_3, b_3)\}$ we cannot find any $h_{a,b} \in \mathcal{H}$, for which $Y' \subseteq S_{h_{a,b}}$ but $(a_1, b_1) \notin S_{h_{a,b}}$. Thus, we cannot add any such $y_{3,j}$.

So, we cannot add any element to Y. Thus, all Y that shatter \mathcal{H} must be at most $|Y| \leq 3$. Therefore, the VC Dimension is 3.

(b) The VC-Dimension is ∞ . Let be $Y \subseteq \mathfrak{X} = \Sigma^*$. For any $Y' \subseteq Y$ we can choose L := Y'. Thus, $Y' = S_{h_L}$, so also $S_{h_L} \subseteq Y$. So $Y \cap S_{h_L} = S_{h_L} = Y'$. So Y can also be infinite in size.

Exercise 4

(a) See Referencesappendix for code.

```
Final probabilities: [0.4 0.4 0.2]

Tracked weight vectors:

Round: 1 Weights: [1. 1. 1.]
Round: 2 Weights: [0.5 0.5 1.]
Round: 3 Weights: [0.5 0.25 0.5]
Round: 4 Weights: [0.25 0.25]
```

```
9 Round: 5 Weights: [0.25 0.125 0.125]
10 Round: 6 Weights: [0.125 0.125 0.0625]
11 Round: 7 Weights: [0.125 0.0625 0.04419417]
```

(b) No, the weights are always the same. This is because the loss matrix does not change throughout the algorithm, so the loss is always the same. If all the events still happen in the sequence, only in a different order, this won't have an effect as the loss will still be included in the updated weight.

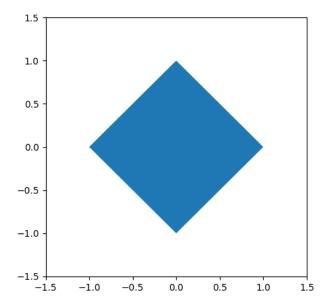
Exercise 5

(a) See Referencesappendix for code.

```
Probabilities:
 Round:
                    Probabilities:
                                      [0.33 0.33 0.33]
                    Probabilities:
4 Round:
          2
                                      [0.46 0.27 0.27]
                    Probabilities:
                                      [0.28 0.51 0.21]
5 Round:
          3
6 Round:
                    Probabilities:
                                      [0.25 0.42 0.33]
  Weight vectors:
10 Round:
                    Weights:
                                      [1. 1. 1.]
11 Round:
          2
                    Weights:
                                      [2.83 1.
                                                  1.
12 Round:
          3
                    Weights:
                                      [2.83 8.48 1.
                                                      ]
13 Round:
                    Weights:
                                      [2.83 8.48 5.32]
```

(b) $w_1^{(4)}$ and $w_3^{(4)}$ are different because with $\gamma=0.5$ we put a certain weight on exploration. Therefore, even with the same reward, different actions can have different weights as γ is part of the weight updating calculation.

Exercise 6



(ii) The shape of $B_1^3 \subset \mathbb{R}^3$ would look like a octahedron with the same edge length $(\sqrt{2})$.

(b)
$$|diag(B_1^2)| = 2 \xrightarrow{\text{Pythagoras}} \text{ edge length of } B_1^2 = \sqrt{2} \Rightarrow vol(B_1^2) = \sqrt{2}^2 = 2$$

 $vol(B_1^3) = \frac{1}{3}\sqrt{2}a^3$ with a being the edge length of the octahedron $\Rightarrow vol(B_1^3) = \frac{1}{3}\sqrt{2}^4 = \frac{1}{3}4 = \frac{4}{3} \approx 1.33$
A more general formula for the volume $vol(B_1^l)$ is $vol(B_1^l) = \frac{2^l}{l!}$ (cmp. this paper). Using $l = 1, 2$ yields the same results.

(c)

$$\lim_{l \to \inf} \operatorname{vol}(B_1^l) = \frac{2^l}{l!}$$

$$\Rightarrow \lim_{l \to \inf} \operatorname{vol}(B_1^l) = \frac{2}{1} \cdot \frac{2}{2} \cdot \frac{2}{3} \cdot \dots \cdot \frac{2}{l-1} \cdot \frac{2}{l}$$

$$\leq 2 \cdot \frac{2}{l} = \frac{4}{l}$$

$$\Rightarrow \lim_{n \to \inf} \frac{4}{l} = 0$$

Appendix

Code for Exercise 4

```
import numpy as np
  def mwu_algorithm(loss_matrix, events, rounds, alpha):
      # initial weight vector of 1s
      weights = np.ones((loss_matrix.shape[0]))
      weights_tracking = {}
      weights_tracking[0] = weights
      # more convenient to loop through rounds and events
      rounds_arr = [i for i in range(rounds)]
10
      for round, event in zip(rounds_arr, events):
11
          # getting the current probabilities, not really needed here
          p = probabilities(weights)
13
          # need to use event-1 as events start at 1 but indexing at 0
14
          weights = np.power((1 - alpha), loss_matrix[:, event-1]) * weights
          # loss isn't really needed
          loss = calculate_loss(loss_matrix, p, event-1)
17
          weights_tracking[round+1] = weights
18
19
      return p, weights_tracking
21
  def probabilities(weights):
      return weights / np.sum(weights)
23
24
  def calculate_loss(loss_matrix, probabilities, event):
25
      return np.sum(probabilities * loss_matrix[:, event])
26
27
  loss_matrix = np.array([[0,1,1,0],
                           [1,0,1,1],
30
                           [1,1,0,0.5]])
31
  observed_events = [3,1,2,1,2,4]
```

Code for Exercise 5

```
import numpy as np
2 from copy import deepcopy
 def exp3(gamma, rounds, actions, rewards):
      weights = np.ones((len(actions)))
      rounds_arr = [i for i in range(rounds)]
      n = len(actions)
      # for tracking weights and probabilities
8
      weights_tracking = {}
9
      probabilities_tracking = {}
10
      weights_tracking[0] = np.ones(len(actions))
11
      probabilities_tracking[0] = probability_dist(weights, gamma)
      for round, action in zip(rounds_arr, actions):
13
          probabilities = probability_dist(weights, gamma)
14
          probabilities_tracking[round] = probabilities
          reward = rewards[action]
16
          weights = update_weights(weights, reward, probabilities, action,
17
     gamma)
          weights_tracking[round + 1] = deepcopy(weights)
18
19
      probabilities_tracking[rounds] = probability_dist(weights, gamma)
20
      return weights_tracking, probabilities_tracking
 def probability_dist(weights, gamma):
23
      return (1 - gamma) * (weights / np.sum(weights)) + gamma / len(weights)
24
25
  def update_weights(weights, reward, probabilities, action, gamma):
26
      n = len(weights)
      # only update chosen action
      weights[action] = weights[action] * np.exp((gamma * reward) / (n *
     probabilities[action]))
      return weights
30
31
action_seq = np.array([ 1, 2, 3 ])
_{34} rewards = np.array([ 3, 5, 3 ]) * np.log(2)
 weights, probs = exp3(gamma=0.5, rounds=3, actions=action_seq - 1, rewards=
     rewards)
37
38 print(f'Probabilities: \n')
39 for key, val in probs.items():
      print(f'Round:\t{key + 1}\tProbabilities:\t{val.round(2)}')
40
42 print(f'\nWeight vectors: \n')
43 for key, val in weights.items():
print(f'Round:\t{key + 1}\tWeights:\t{val.round(2)}')
```