# Homework # 01

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# Chapter 01

# Problem 3.5

Let  $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}\$  be an orthonormal basis for  $\mathbb{R}^3$  with  $\mathbf{a} \times \mathbf{b} = \mathbf{c}$ . Prove  $\mathbf{b} \times \mathbf{c} = \mathbf{a}$  and  $\mathbf{c} \times \mathbf{a} = \mathbf{b}$ .

#### Solution

Recall that the components of a cross product can be decomposed into a sum involving the Levi-Civita symbol, i.e.,

$$(\mathbf{u} \times \mathbf{v})_k = \sum_i \sum_j \varepsilon_{ijk} u^i v^j$$

We can use this to deduce a useful vector identity. Consider the following:

$$(\mathbf{u} \times \mathbf{v} \times \mathbf{w})_k = \sum_i \sum_j \varepsilon_{ijk} u_i (\mathbf{v} \times \mathbf{w})_j$$
$$= \sum_i \sum_j \varepsilon_{ijk} u_i \sum_l \sum_m \varepsilon_{lmj} v_l w_m$$
$$= \sum_i \sum_j \sum_l \sum_m \varepsilon_{ijk} \varepsilon_{lmj} u_i v_l w_m.$$

By the cyclic nature of the Levi-Civita symbol, we can write  $\varepsilon_{ijk} = \varepsilon_{kij}$ . Recall the contracted epsilon identity:

$$\sum_{i} \varepsilon_{kij} \varepsilon_{lmj} = \delta_{kl} \delta_{im} - \delta_{km} \delta_{il}.$$

Hence, we get

$$(\mathbf{u} \times \mathbf{v} \times \mathbf{w})_{k} = \sum_{i} \sum_{j} \sum_{l} \sum_{m} \varepsilon_{ijk} \varepsilon_{lmj} u_{i} v_{l} w_{m}$$

$$= \sum_{i} \sum_{l} \sum_{m} (\delta_{kl} \delta_{im} - \delta_{km} \delta_{il}) u_{i} v_{l} w_{m}$$

$$= \sum_{i} \sum_{l} \sum_{m} \delta_{kl} \delta_{im} u_{i} v_{l} w_{m} - \sum_{i} \sum_{l} \sum_{m} \delta_{km} \delta_{il} u_{i} v_{l} w_{m}$$

$$= \sum_{m} \left( \sum_{l} \delta_{kl} v_{l} \right) \left( \sum_{i} \delta_{im} u_{i} \right) w_{m} - \sum_{l} \left( \sum_{m} \delta_{km} w_{m} \right) \left( \sum_{i} \delta_{il} u_{i} \right) v_{l}$$

$$= \sum_{m} v_{k} u_{m} w_{m} - \sum_{l} w_{k} u_{l} v_{l}$$

$$= \left( \sum_{m} u_{m} w_{m} \right) v_{k} - \left( \sum_{l} u_{l} v_{l} \right) w_{k}$$

$$= \left[ (\mathbf{u} \cdot \mathbf{w}) \mathbf{v} - (\mathbf{u} \cdot \mathbf{v}) \mathbf{w} \right]_{k}$$

Hence, we have

$$\mathbf{u} \times \mathbf{v} \times \mathbf{w} = (\mathbf{u} \cdot \mathbf{w})\mathbf{v} - (\mathbf{u} \cdot \mathbf{v})\mathbf{w}. \tag{1}$$

This will be useful in proving the claim in the problem statement.

Now suppose  $\{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$  is an orthonormal basis for  $\mathbf{R}^3$  with  $\mathbf{a} \times \mathbf{b} = \mathbf{c}$ . Taking the cross product on the right of both sides with  $\mathbf{a}$ , we get

$$\mathbf{c} \times \mathbf{a} = \mathbf{a} \times \mathbf{b} \times \mathbf{a} \stackrel{\text{(1)}}{=} (\mathbf{a} \cdot \mathbf{a}) \mathbf{b} - (\mathbf{a} \cdot \mathbf{b}) \mathbf{a} = \mathbf{b}.$$

The final equality follows from the orthonormality of the basis  $\beta := \{\mathbf{a}, \mathbf{b}, \mathbf{c}\}$ , i.e., that  $\mathbf{e}_i \cdot \mathbf{e}_j = \delta_{ij}$  for  $\mathbf{e}_i \in \beta$ . Thus

$$(\mathbf{a} \times \mathbf{b} = \mathbf{c}) \implies (\mathbf{c} \times \mathbf{a} = \mathbf{b}).$$

To prove  $\mathbf{b} \times \mathbf{c} = \mathbf{a}$ , we repeat a similar argument and cross the above equation on the right with  $\mathbf{c}$ :

$$\mathbf{b} \times \mathbf{c} = \mathbf{c} \times \mathbf{a} \times \mathbf{c} \stackrel{\text{(1)}}{=} (\mathbf{c} \cdot \mathbf{c}) \mathbf{a} - (\mathbf{c} \cdot \mathbf{a}) \mathbf{c} = \mathbf{a}.$$

Hence

$$\boxed{(\mathbf{c} \times \mathbf{a} = \mathbf{b}) \implies (\mathbf{b} \times \mathbf{c} = \mathbf{a})}$$

which completes the proof.

### Problem 4.1

Let  $\mathbf{a} = (2, 1, -3)$ ,  $\mathbf{b} = (1, 0, 1)$ ,  $\mathbf{c} = (0, -1, 3)$ . What is the equation of

- (a) the line through a parallel to b;
- (b) the line through b and c;
- (c) the plane through **b** perpendicular to **a**;
- (d) the plane through **c** parallel to **a** and **b**;
- (e) the sphere with center a and radius 2?

#### Solution

Throughout this problem, I will assume that we are adopting the Euclidean inner product on  $\mathbb{R}^3$ .

(a) A parameterization of the line through **a** parallel to **b** is manifestly  $\ell_a(t) = \mathbf{a} + t\mathbf{b}$ . We see that the line passes through **a** at t = 0 and travels parallel to **b** as t increases. In this case,

$$\ell_a(t) = (2+t, 1, -3+t).$$

(b) A parameterization of the line through both **b** and **c** is  $\ell_b(t) = \mathbf{b} + t(\mathbf{c} - \mathbf{b})$ . Here, the line passes through the tip of **b** at t = 0 and passes through the tip of **c** at t = 1. In the present case,

$$\ell_b(t) = (1 - t, -t, 1 + 2t).$$

(c) The plane which passes through **b** and is perpendicular to **a** is the set of all vectors **v** such that  $\langle \mathbf{v} - \mathbf{b}, \mathbf{a} \rangle = 0$ . Let  $\mathbf{v} = (x, y, z)$ . Then

$$0 = \langle \mathbf{v} - \mathbf{b}, \mathbf{a} \rangle$$
  
=  $\langle (x - 1, y, z - 1), (2, 1, -3) \rangle$   
=  $2(x - 1) + y - 3(z - 1).$ 

Alternatively, in standard form, the equation is

$$2x + y - 3z = -1.$$

(d) Note that a plane parallel to both  $\mathbf{a}$  and  $\mathbf{b}$  must necessarily be perpendicular to  $\mathbf{a} \times \mathbf{b}$ . Hence, the plane which passes through  $\mathbf{c}$  and is parallel to both  $\mathbf{a}$  and  $\mathbf{b}$  is the same as the plane which passes through  $\mathbf{c}$  and is perpendicular to  $\mathbf{a} \times \mathbf{b}$ . Here,

$$\mathbf{a} \times \mathbf{b} = (1, -[2+3], -1) = (1, -5, -1).$$

Then, repeating the same procedure as in (c) with  $\mathbf{v} = (x, y, z)$ , we find that the equation of the plane is

$$0 = \langle \mathbf{v} - \mathbf{c}, \mathbf{a} \times \mathbf{b} \rangle$$
  
=  $\langle (x, y + 1, z - 3), (1, -5, -1) \rangle$   
=  $x - 5(y + 1) - (z - 3)$ .

Or, in standard form,

$$x - 5y - z = 2.$$

(e) Let  $\mathbf{v} = (x, y, z)$  lie on the surface of the sphere in question. Then  $\mathbf{v} - \mathbf{a}$  points from the center of the sphere to the surface. The length of this vector is  $|\mathbf{v} - \mathbf{a}|$  and is also the radius 2. Hence, the equation of the sphere is  $|\mathbf{v} - \mathbf{a}| = 2$ , or equivalently  $\langle \mathbf{v} - \mathbf{a}, \mathbf{v} - \mathbf{a} \rangle = 4$ . Hence,

$$4 = \langle \mathbf{v} - \mathbf{a}, \mathbf{v} - \mathbf{a} \rangle$$
  
=  $\langle (x - 2, y - 1, z + 3), (x - 2, y - 1, z + 3) \rangle$   
=  $(x - 2)^2 + (y - 1)^2 + (z + 3)^2$ .

So the equation of the sphere of radius 2 and center a is

$$(x-2)^2 + (y-1)^2 + (z+3)^2 = 2.$$

# Problem 5.1

Prove Lemma 5.1.

**Lemma** (5.1). Let  $\mathbf{f}, \mathbf{g} : \mathbb{R} \to V$  and suppose that V has an inner product  $\langle , \rangle$ . Then

$$\frac{\mathrm{d}}{\mathrm{d}t}\langle\mathbf{f},\mathbf{g}\rangle = \left\langle\frac{\mathrm{d}\mathbf{f}}{\mathrm{d}t},\mathbf{g}\right\rangle + \left\langle\mathbf{f},\frac{\mathrm{d}\mathbf{g}}{\mathrm{d}t}\right\rangle.$$

In particular, if  $|\mathbf{f}|$  is constant then  $d\mathbf{f}/dt$  is perpendicular to  $\mathbf{f}$ .

#### Solution

Fix a basis  $\{\mathbf{v}_i\}$  for V. Then, there exists sets of real functions  $\{f^i(t)\}$  and  $\{g^j(t)\}$  for which

$$\mathbf{f}(t) = \sum_{i} f^{i}(t)\mathbf{v}_{i},$$
$$\mathbf{g}(t) = \sum_{i} g^{j}(t)\mathbf{v}_{j}.$$

Then, using the linearity of the inner product, we find

$$\langle \mathbf{f}(t), \mathbf{g}(t) \rangle = \sum_{i} \sum_{j} f^{i}(t) g^{j}(t) \langle \mathbf{v}_{i}, \mathbf{v}_{j} \rangle. \tag{2}$$

Since the t-dependence lies entirely with the functions  $\{f^i(t)\}\$  and  $\{g^j(t)\}\$ , differentiation follows trivially from the product rule. Indeed,

$$\frac{\mathrm{d}}{\mathrm{d}t}\langle\mathbf{f}(t),\mathbf{g}(t)\rangle = \sum_{i} \sum_{j} \langle\mathbf{v}_{i},\mathbf{v}_{j}\rangle \frac{\mathrm{d}}{\mathrm{d}t} \left\{ f^{i}(t)g^{j}(t) \right\}$$
$$= \sum_{i} \sum_{j} \langle\mathbf{v}_{i},\mathbf{v}_{j}\rangle \left( \frac{\mathrm{d}f^{i}}{\mathrm{d}t}g^{j} + f^{i}\frac{\mathrm{d}g^{j}}{\mathrm{d}t} \right)$$

$$= \sum_{i} \sum_{j} \frac{\mathrm{d}f^{i}}{\mathrm{d}t} g^{j} \langle \mathbf{v}_{i}, \mathbf{v}_{j} \rangle + \sum_{i} \sum_{j} f^{i} \frac{\mathrm{d}g^{j}}{\mathrm{d}t} \langle \mathbf{v}_{i}, \mathbf{v}_{j} \rangle.$$

Comparing the above to Eq. (2), we get

$$\frac{\mathrm{d}}{\mathrm{d}t}\langle\mathbf{f},\mathbf{g}\rangle = \left\langle\frac{\mathrm{d}\mathbf{f}}{\mathrm{d}t},\mathbf{g}\right\rangle + \left\langle\mathbf{f},\frac{\mathrm{d}\mathbf{g}}{\mathrm{d}t}\right\rangle$$

which is precisely the result of Lemma 5.1.

Now suppose that  $|\mathbf{f}|$  is constant. Then,  $|\mathbf{f}|^2$  is also constant. From Lemma 5.1:

$$0 = \frac{\mathrm{d}}{\mathrm{d}t} |\mathbf{f}|^2 = \frac{\mathrm{d}}{\mathrm{d}t} \langle \mathbf{f}, \mathbf{f} \rangle = \left\langle \frac{\mathrm{d}\mathbf{f}}{\mathrm{d}t}, \mathbf{f} \right\rangle + \left\langle \mathbf{f}, \frac{\mathrm{d}\mathbf{f}}{\mathrm{d}t} \right\rangle.$$

By the symmetry of the inner product, we have  $\langle d\mathbf{f}/dt, \mathbf{f} \rangle = \langle \mathbf{f}, d\mathbf{f}/dt \rangle$ , so we find  $2\langle d\mathbf{f}/dt, \mathbf{f} \rangle = 0$ , or that  $\langle d\mathbf{f}/dt, \mathbf{f} \rangle = 0$ , i.e., that  $d\mathbf{f}/dt$  is perpendicular to  $\mathbf{f}$ .

Note that all of the steps in the proof above are logically consistent in either direction. Hence, this is sufficient to claim that  $|\mathbf{f}|$  is constant  $\iff$   $d\mathbf{f}/dt$  is perpendicular to  $\mathbf{f}$ . This will be useful in Problem 1.7 of Chapter 02.

#### Problem 5.3

Prove that for any  $t \in \mathbb{R}$ ,  $\cosh^2(t) - \sinh^2(t) = 1$ . (Since  $x^2 - y^2 = 1$  is a hyperbola, this gives the origin of the term "hyperbolic function." Also, you should think about the analogy between this equation and  $\cos^2 \theta + \sin^2 \theta = 1$ .)

#### Solution

This can be proved via direct calculation. Let  $t \in \mathbb{R}$ . Then,

$$\cosh^{2}(t) - \sinh^{2}(t) = \left(\frac{e^{t} + e^{-t}}{2}\right)^{2} - \left(\frac{e^{t} - e^{-t}}{2}\right)^{2} \\
= \frac{e^{2t} + 2 + e^{-2t}}{4} - \frac{e^{2t} - 2 + e^{-2t}}{4} \\
= \frac{1}{4} \left(e^{2t} + 2 + e^{-2t} - e^{2t} + 2 - e^{-2t}\right) \\
= 1$$

Hence  $\cosh^2(t) - \sinh^2(t) = 1$  for all  $t \in \mathbb{R}$ .

#### Problem 5.4

Prove that  $\cosh'(t) = \sinh(t)$ , and  $\sinh'(t) = \cosh(t)$  for all  $t \in \mathbb{R}$ .

#### Solution

This can also be proved via direct calculation. We have

$$\frac{\mathrm{d}}{\mathrm{d}t}\cosh(t) = \frac{\mathrm{d}}{\mathrm{d}t} \left( \frac{e^t + e^{-t}}{2} \right)$$

$$= \frac{\frac{d}{dt}e^t + \frac{d}{dt}e^{-t}}{2}$$
$$= \frac{e^t - e^{-t}}{2}$$
$$= \sinh(t).$$

Similarly, we find

$$\frac{d}{dt}\sinh(t) = \frac{d}{dt} \left(\frac{e^t - e^{-t}}{2}\right)$$

$$= \frac{\frac{d}{dt}e^t - \frac{d}{dt}e^{-t}}{2}$$

$$= \frac{e^t + e^{-t}}{2}$$

$$= \cosh(t).$$

# Chapter 02

## Problem 1.1

- (a) Show that  $\alpha(t) = (\sin 3t \cos t, \sin 3t \sin t, 0)$  is a regular curve.
- (b) Find the equation of the tangent line to  $\alpha$  at  $t = \pi/3$ .

#### Solution

(a) Clearly  $\alpha$  is a parameterized curve, since  $\alpha : \mathbb{R} \to \mathbb{R}^3$  is smooth (since each component of  $\alpha$  is a smooth function in  $\mathbb{R}$ ). For  $\alpha$  to be a regular curve, we need to show that  $d\alpha/dt \neq 0$ . We have

$$\frac{\mathrm{d}\alpha}{\mathrm{d}t} = 3(\cos 3t \cos t - \sin 3t \sin t, \cos 3t \sin t + \sin 3t \cos t, 0).$$

We recognize the first and second components of  $d\alpha/dt$  as the expansion of  $\cos(3t+t)$  and  $\sin(3t+t)$ , respectively, which gives

$$\frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}t} = 3(\cos(4t), \sin(4t), 0).$$

If  $\alpha$  was not a regular curve, then there would exist at least one t for which  $\sin(4t) = \cos(4t) = 0$ . But,  $\sin(4t) = 0 \iff t = n\pi/4$  for  $n \in \mathbb{Z}$  and  $\cos(4t) = 0 \iff t = (2m+1)\pi/8$  for  $m \in \mathbb{Z}$ . Such a t would then require

$$\frac{n\pi}{4} = \frac{(2m+1)\pi}{8} \iff n = m + \frac{1}{2}.$$

Hence, n and m cannot both be integers, so there cannot be such a t. Thus,  $d\alpha/dt$  is never zero and  $\alpha$  is a regular curve.

(b) A parameterization of the tangent line to  $\alpha$  at  $t = t_0$  is

$$\ell(t_0; \mu) = \alpha(t_0) + \mu \left. \frac{\mathrm{d}\alpha}{\mathrm{d}t} \right|_{t=t_0}$$

where  $\mu \in \mathbb{R}$ . So in general, we get

$$\ell(t; \mu) = (\sin 3t \cos t + 3\mu \cos 4t, \sin 3t \sin t + 3\mu \sin 4t, 0).$$

Plugging in  $t = \pi/3$  gives

$$\ell(\frac{\pi}{3};\mu) = -\frac{\mu}{2}(3,\sqrt{3},0).$$

# Problem 1.6

Let  $\alpha(\theta) = (e^{\theta} \cos \theta, e^{\theta} \sin \theta, 0)$ . Prove that the angle between  $\alpha$  and **T** is constant. (A curve with this property is called a logarithmic spiral.)

#### Solution

Modulo  $\pi$ , the angle between  $\alpha(\theta)$  and **T** is

$$\varphi = \arccos\left(\frac{\langle \boldsymbol{\alpha}, \mathbf{T} \rangle}{|\boldsymbol{\alpha}||\mathbf{T}|}\right)$$

assuming the Euclidean metric. First, we find  $\mathbf{T} = \left| \frac{\mathrm{d}\alpha}{\mathrm{d}\theta} \right|^{-1} \frac{\mathrm{d}\alpha}{\mathrm{d}\theta}$ . We have

$$\frac{\mathrm{d}\alpha}{\mathrm{d}\theta} = (e^{\theta}[\cos\theta - \sin\theta], e^{\theta}[\cos\theta + \sin\theta], 0).$$

The magnitude is therefore

$$\left| \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\theta}} \right| = \sqrt{\left\langle \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\theta}}, \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\theta}} \right\rangle} = \sqrt{2}e^{\boldsymbol{\theta}}.$$

Thus, the tangent vector is

$$\mathbf{T} = \left| \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\theta}} \right|^{-1} \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}\boldsymbol{\theta}} = \left( \frac{\cos \boldsymbol{\theta} - \sin \boldsymbol{\theta}}{\sqrt{2}}, \frac{\cos \boldsymbol{\theta} + \sin \boldsymbol{\theta}}{\sqrt{2}}, 0 \right).$$

Then, the inner product reads

$$\langle \boldsymbol{\alpha}, \mathbf{T} \rangle = \left\langle (e^{\theta} \cos \theta, e^{\theta} \sin \theta, 0), \left( \frac{\cos \theta - \sin \theta}{\sqrt{2}}, \frac{\cos \theta + \sin \theta}{\sqrt{2}}, 0 \right) \right\rangle$$
$$= \frac{e^{\theta}}{\sqrt{2}} [\cos \theta (\cos \theta - \sin \theta) + \sin \theta (\cos \theta + \sin \theta)]$$
$$= \frac{e^{\theta}}{\sqrt{2}}.$$

Furthermore, the magnitudes of the two vectors also read

$$|\boldsymbol{\alpha}| = \sqrt{\langle (e^{\theta} \cos \theta, e^{\theta} \sin \theta, 0), (e^{\theta} \cos \theta, e^{\theta} \sin \theta, 0) \rangle} = e^{\theta}$$
  
 $|\mathbf{T}| = 1$  (by construction)

Hence, we find

$$\varphi = \arccos\left(\frac{\langle \boldsymbol{\alpha}, \mathbf{T} \rangle}{|\boldsymbol{\alpha}||\mathbf{T}|}\right) = \arccos\left(\frac{e^{\theta}/\sqrt{2}}{e^{\theta}}\right) = \arccos\left(\frac{1}{\sqrt{2}}\right) = \frac{\pi}{4},$$

which is indeed constant. Hence,  $\alpha$  is a logarithmic spiral.

#### Problem 1.7

Let  $\alpha(t)$  be a regular curve. Suppose there is a point  $\mathbf{a} \in \mathbb{R}^3$  such that  $\alpha(t) - \mathbf{a}$  is orthogonal to  $\mathbf{T}(t)$  for all t. Prove that  $\alpha(t)$  lies on a sphere. (*Hint:* What should be the center of the sphere?)

## Solution

If there is a point  $\mathbf{a} \in \mathbb{R}^3$  such that  $\alpha(t) - \mathbf{a}$  is orthogonal to  $\mathbf{T}(t)$  for all t, then necessarily  $\langle \alpha(t) - \mathbf{a}, \mathbf{T}(t) \rangle = 0$ .

Then, since  $\mathbf{T} := \left| \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}t} \right|^{-1} \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}t}$ , by the linearity of the inner product, we can multiply through by  $\left| \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}t} \right|$  and get:

$$\left\langle \boldsymbol{\alpha}(t) - \mathbf{a}, \frac{\mathrm{d}\boldsymbol{\alpha}}{\mathrm{d}t} \right\rangle = 0.$$

Additionally, since **a** is constant in t,  $\frac{d\mathbf{a}}{dt} = 0$  and we can equivalently write

$$\left\langle \boldsymbol{\alpha}(t) - \mathbf{a}, \frac{\mathrm{d}}{\mathrm{d}t} \{ \boldsymbol{\alpha}(t) - \mathbf{a} \} \right\rangle = 0.$$

In the proof of Lemma 5.1<sup>1</sup>, I proved that, for a function  $\mathbf{f} : \mathbb{R} \to \mathbb{R}^3$ ,  $|\mathbf{f}|$  is constant  $\iff$   $d\mathbf{f}/dt$  is perpendicular to  $\mathbf{f}$ . Letting  $\mathbf{f}(t) := \boldsymbol{\alpha}(t) - \mathbf{a}$  (which is indeed a map  $\mathbb{R} \to \mathbb{R}^3$ ), we find

$$\left\langle \boldsymbol{\alpha}(t) - \mathbf{a}, \frac{\mathrm{d}}{\mathrm{d}t} \{ \boldsymbol{\alpha}(t) - \mathbf{a} \} \right\rangle = 0 \implies |\boldsymbol{\alpha}(t) - \mathbf{a}| = r$$

<sup>&</sup>lt;sup>1</sup>See Problem 5.1 of Chapter 01

where  $r \in \mathbb{R}^+ \cup \{0\}$  (since magnitudes are axiomatically non-negative). Indeed, this proves that  $\alpha(t)$  lies on a sphere of radius r with center **a** for all  $t \in \text{dom}\{\alpha\}$ .

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