

Linear Algebra

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Preliminary Assessment

1. (a) Is the set of polynomials of degree $n \in \mathbb{Z}_{\geq 0}$ over a field \mathbb{F} a vector space? If it is, prove it. If it is not, state which axioms are not satisfied and provide counterexamples.

Solution. No, the set of polynomials of degree $n \in \mathbb{Z}$ over a field \mathbb{F} is not a vector space. The set is not closed. For example, x^2 and $-x^2$ are in $P_2(\mathbb{R})$ but $x^2 + (-x^2) = 0$ is not.

- (b) Prove that the set of polynomials of degree at most n is a vector space. You may assume that the set of continuous functions $\mathcal{C}(\mathbb{F})$ in \mathbb{F} is a vector space. Why is this helpful?

Solution. Since $P_n(\mathbb{R}) \subseteq \mathcal{C}(\mathbb{F})$, it is sufficient to prove that $P_n(\mathbb{R})$ is nonempty and closed under addition and scalar multiplication. Since the identity function $\text{id}_{\mathcal{C}(\mathbb{F})}$ can be regarded as a polynomial of degree 0, $\text{id}_{\mathcal{C}(\mathbb{F})} \in P_n(\mathbb{F})$ for any n and so $\text{id}_{\mathcal{C}(\mathbb{F})}$ is nonempty. Let p and q be in $P_n(\mathbb{F})$ and c be in \mathbb{F} . Then we can write

$$p(t) := \sum_{i=0}^n a_i t^i \quad ; \quad q(t) := \sum_{i=0}^n b_i t^i$$

where the a_i and b_i are elements of \mathbb{F} . then

$$[p + q](t) = \sum_{i=0}^n (a_i + b_i) t^i \quad ; \quad [cp](t) = \sum_{i=0}^n (ca_i) t^i$$

Hence $p + q$ and cp are also elements of $P_n(\mathbb{F})$. Hence $P_n(\mathbb{F})$ is closed under addition and scalar multiplication and so $P_n(\mathbb{F})$ is indeed a vector space.

In what follows, let $P_2(\mathbb{R})$ be the vector space of polynomials of degree at most 2 and \mathbb{V} denote the subset of $P_2(\mathbb{R})$ such that:

$$\int_0^1 p(t) dt = 0.$$

- (c) Prove that \mathbb{V} is a subspace of $P_2(\mathbb{R})$.

Solution. Since $0 \in P_2(\mathbb{R})$ and $\int_0^1 0 dt = 0$, we have $0 \in \mathbb{V}$ and so \mathbb{V} is nonempty. Suppose p and q are elements of bV and c is real. Then $\int_0^1 p(t) dt = 0$ $\int_0^1 q(t) dt = 0$, and so

$$\int_0^1 (p(t) + q(t)) dt = \int_0^1 p(t) dt + \int_0^1 q(t) dt = 0 + 0 = 0$$

and

$$\int_0^1 cp(t) dt = c \int_0^1 p(t) dt = c \cdot 0 = 0.$$

Hence $p + q$ and cp are also elements of \mathbb{V} . This proves that \mathbb{V} is closed under addition and multiplication, and so \mathbb{V} is indeed a vector space.

- (d) Construct a basis for \mathbb{V} and prove it is indeed a basis. What is the dimension of \mathbb{V} ?

Solution. Any element p of $P_2(\mathbb{R})$ can be written as $p(t) = a_0 + a_1t + a_2t^2$. If p is in \mathbb{V} , then

$$0 = \int_0^1 p(t) dt = \int_0^1 (a_0 + a_1t + a_2t^2) dt = a_0 + \frac{1}{2}a_1 + \frac{1}{3}a_2.$$

Hence if p is in \mathbb{V} , we may write $a_0 = -\frac{1}{2}a_1 - \frac{1}{3}a_2$, and so

$$p(t) = a_0 + a_1t + a_2t^2 + \left(-\frac{1}{2}a_1 - \frac{1}{3}a_2\right) + a_1t + a_2t^2 = \frac{a_1}{2}(2t - 1) + \frac{a_2}{3}(3t^2 - 1).$$

Recall that a basis for a vector space is any set which is linearly independent and which spans the vector space. By construction, $\beta := \{2t - 1, 3t^2 - 1\}$ spans \mathbb{V} , so we need only verify that β is linearly independent. But since $(2t - 1) \neq c(3t^2 - 1)$ for any real c , the vectors are indeed linearly independent. Hence β is a basis for \mathbb{V} , and so $\dim \mathbb{V} = |\beta| = 2$.

2. Let $P_n(\mathbb{F})$ be the vector space of polynomials of degree at most n with coefficients in a field \mathbb{F} . Define the transformation $T : P_3(\mathbb{R}) \rightarrow P_2(\mathbb{R})$ by

$$T(p(t)) = 2p'(t) - 3p''(t).$$

- (a) Prove that T is a linear transformation.

Solution. It is sufficient to show that for any p and q in $P_3(\mathbb{R})$ and a in \mathbb{R} that

$$T(ap + q) = aT(p) + T(q).$$

We have

$$\begin{aligned} T(ap + q) &= 2(ap(t) + q(t))' - 3(ap(t) + q(t))'' = 2ap'(t) + 2q'(t) - 3ap''(t) - 3q''(t) \\ &= a[2p'(t) - 3p''(t)] + [2q'(t) - 3q''(t)] = aT(p) + T(q), \end{aligned}$$

hence T is indeed linear.

- (b) Find a basis for the nullspace of T .

Solution. If $p(t) := a + bt + ct^2 + dt^3$ is an element of the nullspace of T , then we have

$$0 = T(p) = 2[b + 2ct + 3dt^2] + 3[2c + 6dt] = (2b + 6c) + (4c + 18d)t + (6d)t^2$$

Hence $d = c = b = 0$. The constant term a need not be specified, so every term in the nullspace of T has the form $p(t) = a$ for some real a . Hence $N(T) = \text{span}\{1\}$ and so a basis for the nullspace of T is $\{1\}$.

- (c) Given the bases $\beta := \{1, t, t^2, t^3\}$ and $\gamma := \{1, t - 1, t^2 - 1\}$ for $P_3(\mathbb{R})$ and $P_2(\mathbb{R})$ respectively, determine the matrix $[T]_\beta^\gamma$ which represents T . That is, if v is a vector in $P_3(\mathbb{R})$, $w = T(v)$, and $[v]_\beta$ represents the coordinates of v in the β -basis, find the matrix $[T]_\beta^\gamma$ for which $[w]_\gamma = [T]_\beta^\gamma[v]_\beta$.

Solution. Recall that the i 'th column of $[T]_\beta^\gamma$ is just $[T(\beta_i)]_\gamma$. We have

$$\begin{aligned} T(\beta_1) &= T(1) = 0 & \implies [T(\beta_1)]_\gamma &= (0, 0, 0)^\top \\ T(\beta_2) &= T(t) = 2 & \implies [T(\beta_2)]_\gamma &= (2, 0, 0)^\top \\ T(\beta_3) &= T(t^2) = 4t - 6 & \implies [T(\beta_3)]_\gamma &= (-1, 4, 0)^\top \end{aligned}$$

$$T(\beta_4) = T(t^3) = 6t^2 - 18t \implies [T(\beta_4)]_\gamma = (-12, -18, 6)^\top.$$

So,

$$[T]_\beta^\gamma = \begin{pmatrix} 0 & 2 & -2 & -12 \\ 0 & 0 & 4 & -18 \\ 0 & 0 & 0 & 6 \end{pmatrix}$$

is the matrix which represents the transformation.

3. Let $\beta := \{(1, 1), (1, -1)\}$ and $\beta' := \{(2, 4), (3, 1)\}$.

- (a) Verify that β and β' are bases for \mathbb{R}^2 .

Solution. Since $\dim \mathbb{R}^2 = 2$, we need only show the sets are linearly independent. Since each set only has two elements, they are (each) linearly independent if and only if neither vector is a multiple of the other. Since $(1, 1) \neq c(1, -1)$ for any real c , β is linearly independent and hence a basis for \mathbb{R}^2 . Similarly, $(2, 4) \neq c(3, 1)$ for any real c , so β' is linearly independent and hence is a basis for \mathbb{R}^2 .

- (b) Construct the matrix Q which changes β' -coordinates to β -coordinates. That is, if $v \in \mathbb{R}^2$ and $[v]_\beta$ represents the coordinates of v in the β -basis, determine the matrix Q such that $[v]_\beta = Q[v]_{\beta'}$.

Solution. Recall that to form the change-of-basis matrix from β' to β , we need to write the elements of the β' basis in terms of the β basis. The reader can verify that

$$\begin{aligned} (2, 4) &= 3(1, 1) - 1(1, -1) \\ (3, 1) &= 2(1, 1) + 1(1, -1). \end{aligned}$$

Hence:

$$Q = \begin{pmatrix} 3 & -1 \\ 2 & 1 \end{pmatrix}$$

is the matrix which maps β' -coordinates to β -coordinates.

4. Let $M_n(\mathbb{F})$ denote the vector space of $n \times n$ matrices over a field \mathbb{F} and define $T : P_2(\mathbb{R}) \rightarrow M_2(\mathbb{R})$ by

$$T(f(x)) = \begin{pmatrix} f(1) - f(2) & 0 \\ 0 & f(0) \end{pmatrix}.$$

Find a basis for the range $R(T)$ of T and a basis for the nullspace $N(T)$ of T . Verify that $\dim R(T) + \dim N(T) = 3 = \dim P_2(\mathbb{R})$.

Solution. To find the range, it is sufficient to compute $T(\beta_i)$ for each β_i in a given basis $\beta \subset P_2(\mathbb{R})$ and determine its span. Let $\beta = \{1, t, t^2\}$ be the standard basis for $P_2(\mathbb{R})$. Then

$$T(1) = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \quad ; \quad T(t) = \begin{pmatrix} -1 & 0 \\ 0 & 0 \end{pmatrix} \quad ; \quad T(t^2) = \begin{pmatrix} -3 & 0 \\ 0 & 0 \end{pmatrix}.$$

Hence the span is

$$\text{span}\{T(1), T(t), T(t^2)\} = \text{span}\left\{\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}\right\},$$

the generators of which can be taken as a basis for $R(T)$. To determine a basis for $N(T)$, we suppose $p(t) = a + bt + ct^2$ is an element of $N(T)$ and determine conditions on a , b , and c . Indeed,

$$0 = T(p(t)) = \begin{pmatrix} -b - 3c & 0 \\ 0 & a \end{pmatrix}.$$

For equality to hold, we require $a = 0$ and $b = -3c$. Hence, if $p(t) = a + bt + ct^2$ is an element of $N(T)$, then

$$p(t) = (-3c)t + ct^2 = c(t^2 - 3t).$$

Thus $N(T) = \text{span}\{t^2 - 3t\}$ and so a basis for $N(T)$ is $\{t^2 - 3t\}$. Note that $\dim R(T) + \dim N(T) = 2 + 1 = 3 = \dim P_2(\mathbb{R})$, as expected.

5. Define the following matrix.

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 0 \\ 0 & 1 & 2 \end{pmatrix}.$$

Determine the eigenvalues of A . Use these eigenvalues to write $A = PDP^{-1}$ where D is a diagonal matrix and P is nonsingular.

Solution. The eigenvalues of A are just the roots λ of the characteristic polynomial $f_A(t) := \det(A - t\mathbb{I})$, where in this case \mathbb{I} is the 3×3 identity. We have

$$f_A(t) = \begin{vmatrix} 1-t & 1 & 1 \\ 0 & 1-t & 0 \\ 0 & 1 & 2-t \end{vmatrix} = (1-t)^2(2-t),$$

and so the eigenvalues are $\lambda_1 = 1$ (with *algebraic multiplicity* 2) and $\lambda_2 = 2$ (with *algebraic multiplicity* 1). We next construct a set of eigenvectors of A . For simplicity, we start with $\lambda_2 = 2$. An associated eigenvector is a nonzero vector $v_2 = (x_2, y_2, z_2)^\top$ such that $(A - \lambda_2\mathbb{I})v_2 = 0$; that is,

$$\begin{pmatrix} -1 & 1 & 1 \\ 0 & -1 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

The second and third rows require $y_2 = 0$, and so the first requires $x_2 = z_2$. Setting $x_2 = 1$, we get an eigenvector of the form $v_2 = (1, 0, 1)^\top$. Moving to $\lambda_1 = 1$, the associated eigenvectors are of the form $v_1 = (x_1, y_1, z_1)^\top \neq 0$ such that $(A - \lambda_1\mathbb{I})v_1 = 0$; that is,

$$\begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$

There are two degrees of freedom here, since the first and third rows require $x_2 = -x_3$ and the second requires nothing of x_1 . Setting $x_1 = \alpha$ and $x_2 = \beta$ for arbitrary real α and β , we find that the λ_1 -eigenspace of A is the set of all vectors of the form $\alpha(1, 0, 0)^\top + \beta(0, 1, -1)^\top$, i.e., that the eigenspace has a basis $\{(1, 0, 0)^\top, (0, 1, -1)^\top\}$. Hence λ_1 has *geometric multiplicity* 2. Since the algebraic multiplicity of λ_1 equals the geometric multiplicity of λ_1 , A is indeed diagonalizable, and we have

$$A = \underbrace{\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}}_P \underbrace{\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}}_D \underbrace{\begin{pmatrix} 1 & 0 & 1 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix}}_P^{-1}$$

which is the decomposition we wanted.

6. Suppose $\{v_1, \dots, v_n\}$ is an orthogonal set of vectors. Let $\|\cdot\|$ denote the norm generated by the inner product $\langle \cdot, \cdot \rangle$. Prove

$$\left\| \sum_{i=1}^n a_i v_i \right\|^2 = \sum_{i=1}^n |a_i|^2 \|v_i\|^2,$$

where a_1, \dots, a_n are scalars.

Solution. For any vector v in an inner product space, recall $\|v\|^2 = \langle v, v \rangle$. Using the linearity in the right argument and conjugate linearity in the left, we have

$$\left\| \sum_{i=1}^n a_i v_i \right\|^2 = \left\langle \sum_{i=1}^n a_i v_i, \sum_{j=1}^n a_j v_j \right\rangle = \sum_{i=1}^n \sum_{j=1}^n a_i^* a_j \langle v_i, v_j \rangle.$$

If $\{v_1, \dots, v_n\}$ is an orthogonal set, then $\langle v_i, v_j \rangle = 0$ whenever $i \neq j$. Hence, we have

$$\left\| \sum_{i=1}^n a_i v_i \right\|^2 = \sum_{i=1}^n \sum_{j=1}^n a_i^* a_j \langle v_i, v_j \rangle = \sum_{i=1}^n a_i^* a_i \langle v_i, v_i \rangle = \sum_{i=1}^n |a_i|^2 \|v_i\|^2,$$

which completes the proof.

7. Let \mathbb{V} be a finite-dimensional inner product space over \mathbb{C} and suppose $T : \mathbb{V} \rightarrow \mathbb{V}$ is linear. Then there exists a unique linear transformation $T^* : \mathbb{V} \rightarrow \mathbb{V}$ (called the *adjoint* of T) such that $\langle T(v), w \rangle = \langle v, T^*(w) \rangle$ for all v, w in \mathbb{V} . Using only the definition above and the axioms of an inner product, show that if $T = T^*$, then the eigenvalues of T are real.

Solution. Suppose v is an eigenvector of T , i.e., suppose that there exists a $\lambda \in \mathbb{C}$ such that $T(v) = \lambda v$. Note that since v is an eigenvector, $v \neq 0$. Then

$$\lambda \langle v, v \rangle = \langle v, \lambda v \rangle = \langle v, T(v) \rangle = \langle T(v), v \rangle = \langle \lambda v, v \rangle = \lambda^* \langle v, v \rangle.$$

Hence $(\lambda - \lambda^*) \langle v, v \rangle = 0$. Since $v \neq 0$, $\langle v, v \rangle \neq 0$; hence $\lambda = \lambda^*$, i.e., λ is real.

8. Consider the vector space $\mathbb{V} := \{p(t) = a + bt^2 \mid a, b \in \mathbb{R}\}$. Let ω_1 and ω_2 be linear functionals on \mathbb{V} such that $\omega_1\{p(t)\} = p(1)$ and $\omega_2\{p(t)\} = p(2)$. Find the basis for \mathbb{V} for which $\{\omega_1, \omega_2\}$ is the dual basis.

Solution. Suppose the basis for which $\{\omega_1, \omega_2\}$ is dual is $\{v_1, v_2\}$. Then by definition, we have $\omega_i\{v_j\} = \delta_{ij}$, the Kronecker delta. Given the structure of \mathbb{V} , we know $v_j = a_j + b_j t^2$ for as-yet unknown constants a_j and b_j , $j = 1, 2$. This gives us four equations:

$$\begin{aligned} \omega_1\{v_1\} &= v_1(1) = a_1 + b_1 = \delta_{11} = 1 & \omega_1\{v_2\} &= v_2(1) = a_2 + b_2 = \delta_{21} = 0 \\ \omega_2\{v_1\} &= v_1(2) = a_1 + 4b_1 = \delta_{12} = 0 & \omega_2\{v_2\} &= v_2(2) = a_2 + 4b_2 = \delta_{22} = 1 \end{aligned}$$

Going through the algebra, one finds that

$$\{v_1, v_2\} = \left\{ \frac{4}{3} - \frac{1}{3}t^2, -\frac{1}{3} + \frac{1}{3}t^2 \right\}$$

is the basis for \mathbb{V} to which $\{\omega_1, \omega_2\}$ is dual.