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# **Assembly Language and Microcomputer Interface**

## **Chapter 3 – Addressing Modes**

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# Introduction

- Efficient software development for the microprocessor requires a complete familiarity with the addressing modes employed by each instruction.
- This chapter explains the operation of the stack memory so that the PUSH and POP instructions and other stack operations will be understood.

# Chapter Objectives

**Upon completion of this chapter, you will be able to:**

- Explain the operation of each data-addressing mode.
- Use the data-addressing modes to form assembly language statements.
- Explain the operation of each program memory-addressing mode.
- Use the program memory-addressing modes to form assembly and machine language statements.

# Chapter Objectives

(*cont.*)

**Upon completion of this chapter, you will be able to:**

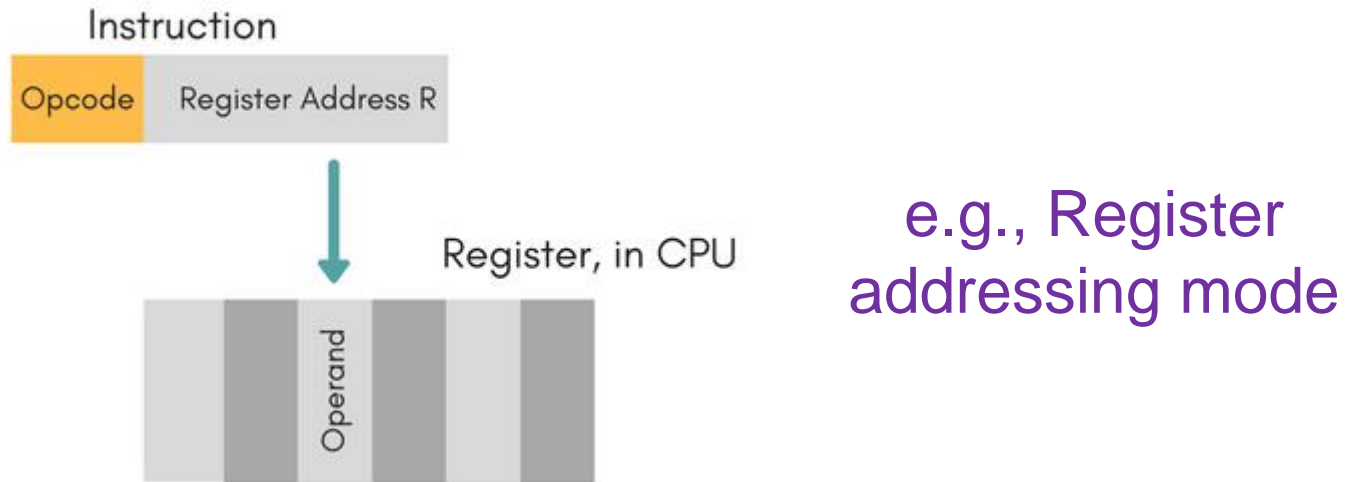
- Select the appropriate addressing mode to accomplish a given task.
- Detail the difference between addressing memory data using real mode and protected mode operation.
- Describe sequence of events that place data onto the stack or remove data from the stack.
- Explain how a data structure is placed in memory and used with software.

# Operation Mode

- There are three operation modes with following default address and operand size:
  - 16-bit modes (real, vm86, protected): default address and operand-size are 16-bit
  - 32-bit protected mode (protected): default address and operand-size are 32-bit
  - 64-bit mode: default address size is 64-bit, default operand-size is 32-bit

# Addressing Modes: Definition

- When a processor executes an instruction, it performs the specified function on data.



- Addressing modes** are the techniques for specifying the address of the operands.
- There are various techniques to specify the address of data.

# Classification of Addressing Modes

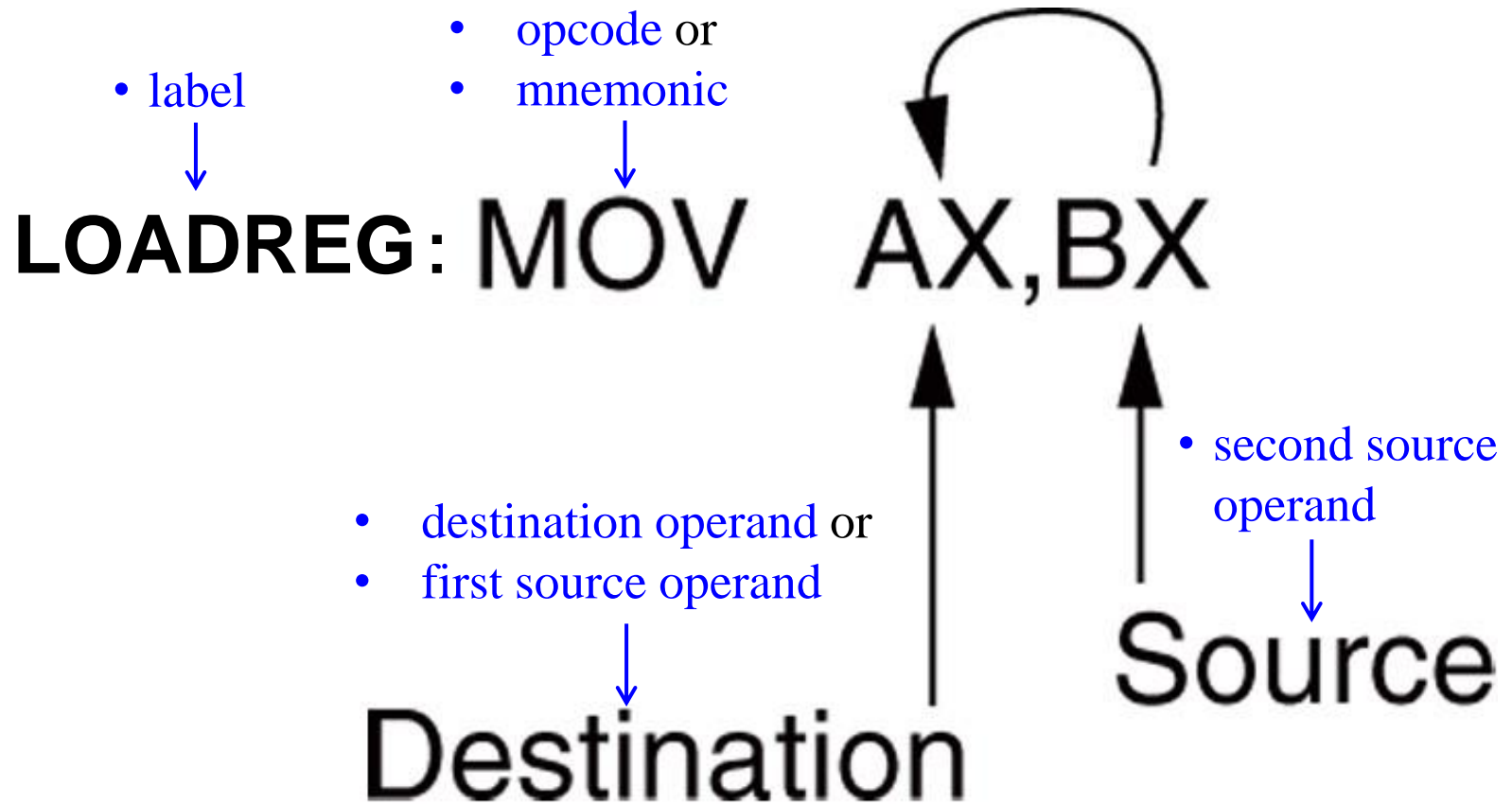
- Data-Addressing Modes
  - This mode is related to data transfer operation. Data is transferred either from the memory to registers or from one register to another register, e.g., **MOV AX, DX**.
- Stack Memory-Addressing Modes
  - This mode involves stack registry operations, e.g., **PUSH AX**.
- Program Memory-Addressing Modes
  - These types of addressing modes are used in branch instructions like **JMP** or **CALL**.

# 3–1 DATA ADDRESSING MODES

- MOV instruction is a common and flexible instruction.
  - provides a basis for explanation of data-addressing modes
- Figure 3–1 illustrates the MOV instruction and defines the direction of data flow.
- **Source** is to the right and **destination** the left, next to the opcode MOV.
  - an **opcode**, or operation code, tells the microprocessor which operation to perform



**Figure 3–1** The MOV instruction showing the source, destination, and direction of data flow.



Note: Some assembly languages (e.g., **AT&T syntax**) put the source and destination in reverse order.

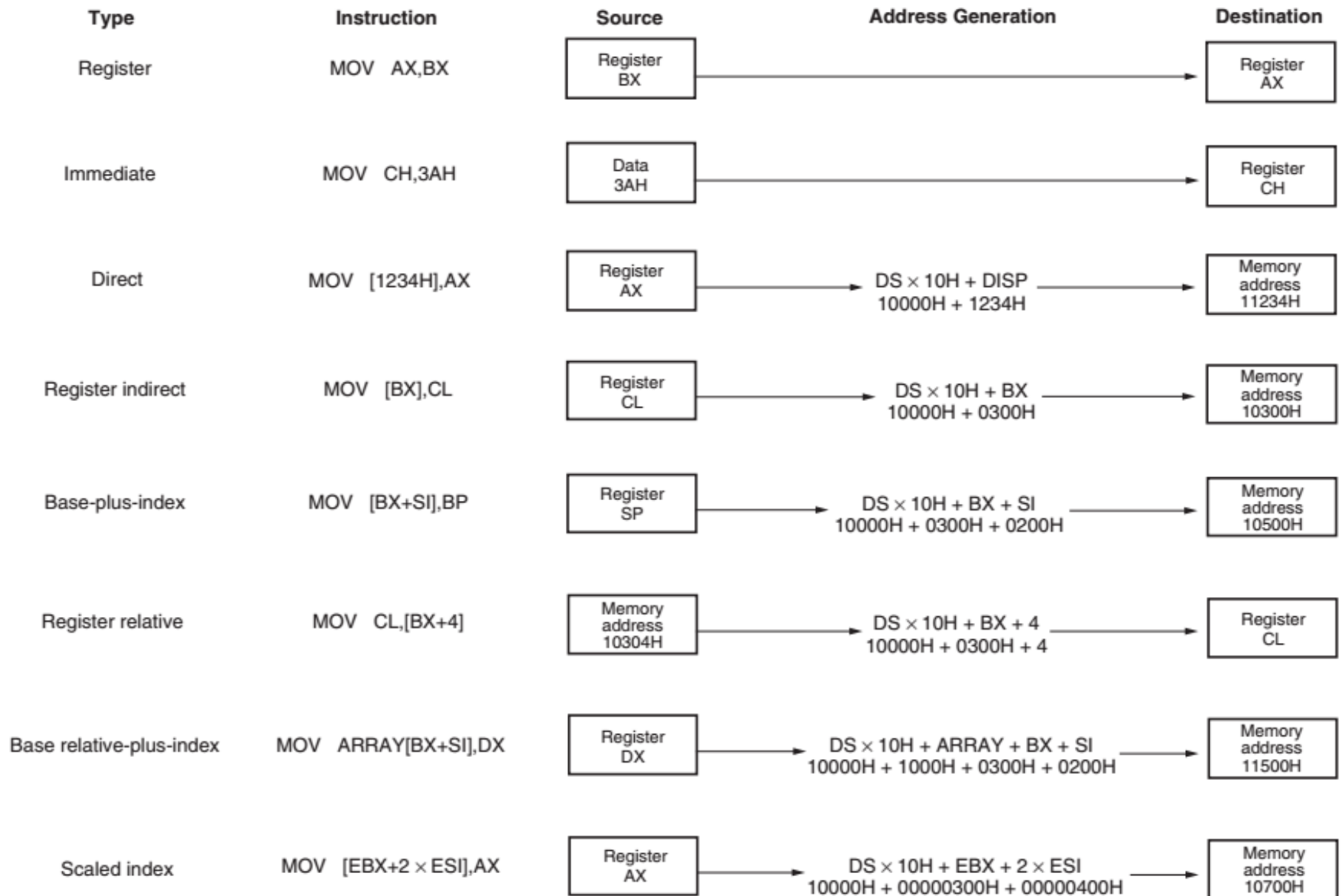
- Each statement in an assembly language program consists of four parts or fields.
- The leftmost field is called the *label*.
  - used to store a **symbolic name** for the memory location it represents
- All **labels** must begin with a **letter** or one of the following **special characters**: @, \$, -, or ?.
  - e.g., begin, data\$, here@, etc.
  - a label may any length from 1 to 35 characters
- The label appears in a program to identify the name of a memory location for storing data and for other purposes.

- The next field to the right is the *opcode field*.
  - designed to hold the instruction, or opcode
  - the MOV part of the move data instruction is an example of an opcode
- Right of the opcode field is the *operand field*.
  - contains information used by the opcode
  - the MOV AL,BL instruction has the opcode MOV and operands AL and BL
- The *comment field*, the final field, contains a comment about the instruction(s).
  - comments always begin with a semicolon (;)

- There are **three basic types of operands**: immediate, register, and memory.
- An **immediate operand** is a constant value that is encoded as part of the instruction. Only source operands can specify an immediate value.
- **Register operands** are contained in a general purpose or SIMD register.
- A **memory operand** specifies a location in memory.

- Figure 3–2 shows all possible variations of the data-addressing modes using MOV.
- These data-addressing modes are found with all versions of the Intel microprocessor.
  - except for the scaled-index-addressing mode, found only in 80386 through Core2
- RIP relative addressing mode is not illustrated.
  - only available on the Pentium 4 and Core2 in the 64-bit mode

**Figure 3–2** 8086–Core2 data-addressing modes.



Notes: EBX = 00000300H, ESI = 00000200H, ARRAY = 1000H, and DS = 1000H

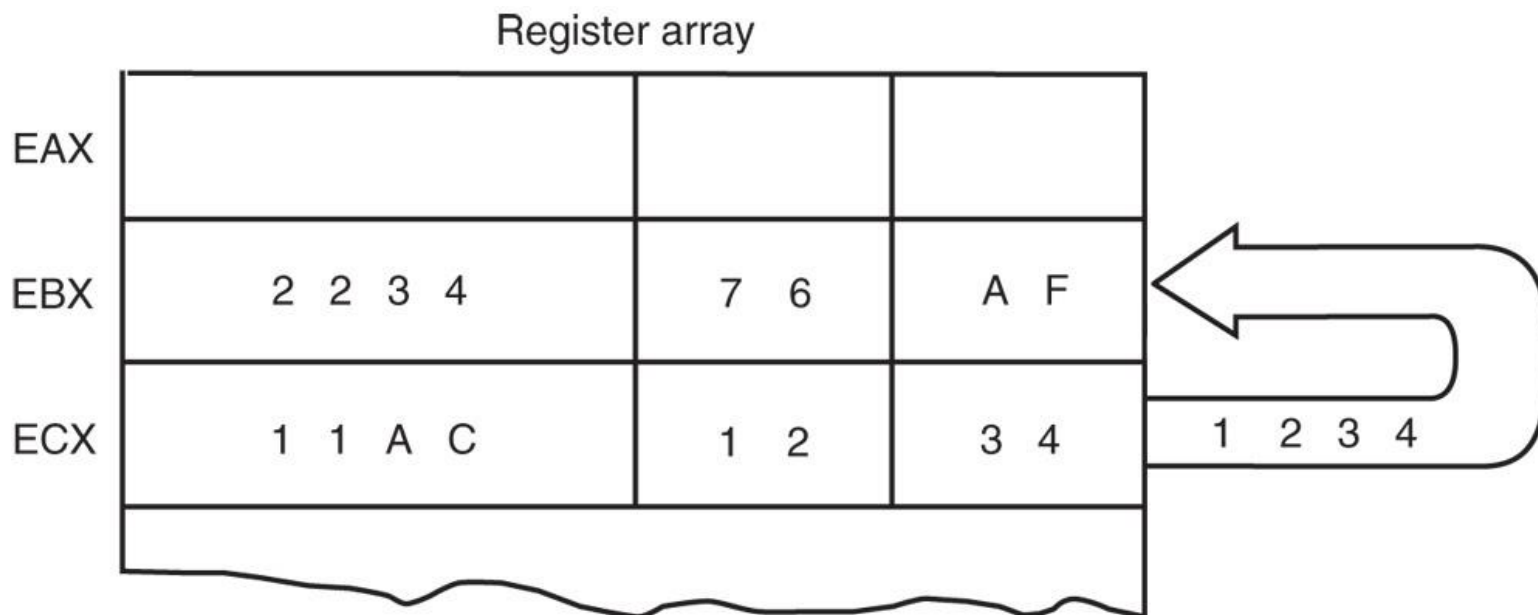
# Register Addressing

- The most common form of data addressing.
  - once register names learned, easiest to apply.
- The microprocessor contains these 8-bit register names used with register addressing: AH, AL, BH, BL, CH, CL, DH, and DL.
- 16-bit register names: AX, BX, CX, DX, SP, BP, SI, and DI.
- In 80386 & above, extended 32-bit register names are: EAX, EBX, ECX, EDX, ESP, EBP, EDI, and ESI.

- 64-bit mode register names are: RAX, RBX, RCX, RDX, RSP, RBP, RDI, RSI, and R8 through R15.
- Important for instructions to use registers that are the same size.
  - *never* mix an 8-bit with a 16-bit register, an 8- or a 16-bit register with a 32-bit register, e.g.,
  - `MOV EAX, BX`      **Error: operand type mismatch**
  - this is not allowed by the microprocessor and results in an error when assembled



**Figure 3–3** The effect of executing the `MOV BX, CX` instruction at the point just before the BX register changes. Note that only the rightmost 16 bits of register EBX change.

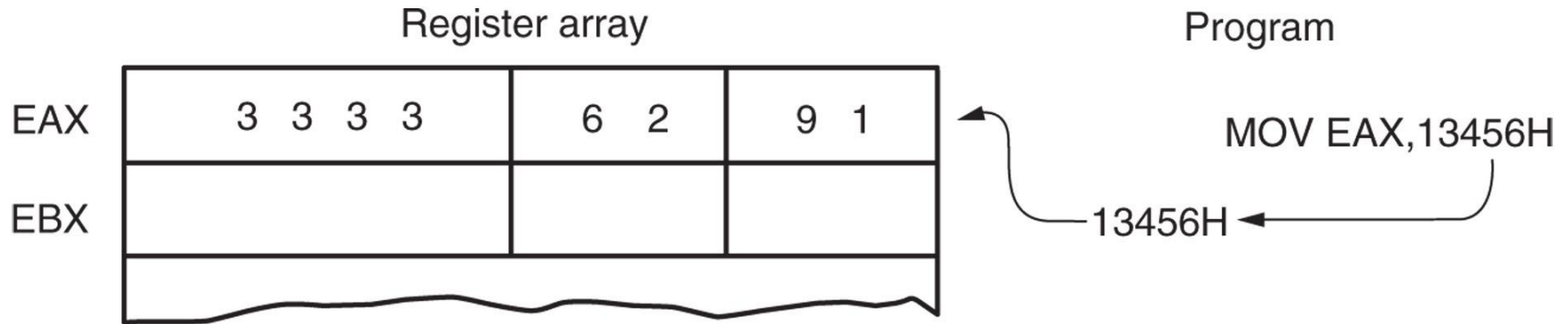


- Figure 3–3 shows the operation of the MOV BX, CX instruction.
- The source register's contents do not change.
  - the destination register's contents do change
- The contents of the destination register or destination memory location change for all instructions **except the CMP and TEST instructions.**
- The MOV BX, CX instruction does not affect the leftmost 16 bits of register EBX.

# Immediate Addressing

- Term *immediate* implies that data immediately follow the hexadecimal opcode in the memory.
  - immediate data are constant data
  - data transferred from a register or memory location are variable data
- Immediate addressing operates upon a byte or word of data.
- Figure 3–4 shows the operation of a MOV EAX,13456H instruction.

**Figure 3–4** The operation of the `MOV EAX,13456H` instruction. This instruction copies the immediate data (13456H) into EAX.



- As with the MOV instruction illustrated in Figure 3–3, the source data overwrites the destination data.

- In symbolic assembly language, the symbol # precedes immediate data in some assemblers.
  - MOV AX, #3456H ; an example
- Most assemblers do not use the # symbol, but represent immediate data as
  - MOV AX,3456H
  - an older assembler used with some Hewlett-Packard logic development does, as may others
  - in this text, the # is not used for immediate data

- The symbolic assembler portrays immediate data in many ways.
- The letter **H** appends hexadecimal data.
- In **MASM**, hexadecimal numbers must always start with a decimal digit (0–9). Otherwise they would be mistaken for label names.
- If necessary, add a leading zero to distinguish between symbols and hexadecimal numbers that start with a letter. E.g.,
  - **MOV** AX, **F2H** ; load a **label** named F2H
  - **MOV** AX, **0F2H** ; load a **hexadecimal** F2H

- **Decimal data** are represented as is and require no special codes or adjustments.
  - an example is the 100 decimal in the `MOV AL,100` instruction
- **Binary data** are represented if the binary number is followed by the **letter B**.
  - in some assemblers, the letter Y
- An **ASCII-coded character or characters** may be depicted in the immediate form if the ASCII data are enclosed in apostrophes.
  - be careful to use the apostrophe (') for ASCII data and not the single quotation mark (`)

# TABLE 3–2 Examples of immediate addressing

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV BL,44	8 bits	Copies 44 decimal (2CH) into BL
MOV AX,44H	16 bits	Copies 0044H into AX
MOV SI,0	16 bits	Copies 0000H into SI
MOV CH,100	8 bits	Copies 100 decimal (64H) into CH
MOV AL,'A'	8 bits	Copies ASCII A into AL
MOV AH,1	8 bits	Not allowed in 64-bit mode, but allowed in 32- or 16-bit modes
MOV AX,'AB'	16 bits	Copies ASCII BA* into AX
MOV CL,11001110B	8 bits	Copies 11001110 binary into CL
MOV EBX,12340000H	32 bits	Copies 12340000H into EBX
MOV ESI,12	32 bits	Copies 12 decimal into ESI
MOV EAX,100B	32 bits	Copies 100 binary into EAX
MOV RCX,100H	64 bits	Copies 100H into RCX

\*Note: This is not an error. [The ASCII characters are stored in reverse order](#) as BA, so be care when using word-sized pairs of ASCII characters.



# Addressing Operand in the Memory

- Instead of using an operand within the register or instruction, the operand can also be addressed in any memory location.
- When an operand is in the memory, the addressing mode specifies how to calculate the **effective memory address** of the operand by **combination of four parameters** held in registers and/or constants within the instruction.
- In brief, the effective address is an offset from segment base address.

# Effective Address Calculation

- An effective address can be calculated using:

$$\text{Effective Address} = \text{Base} + (\text{Scale} \times \text{Index}) + \text{Disp}$$

- The flexibility in calculating the effective address results in various addressing modes:
  - Direct Data Addressing (Disp)
  - Register Indirect Addressing (Base)
  - Base-Plus-Index Addressing (Base + Index)
  - Register Relative Addressing (Base/Index + Disp)
  - Base Relative-Plus-Index Addressing (Base + Index + Disp)
  - Scaled-Index Addressing (Base+Scale+Index+Disp)

# Direct Data Addressing

Effective Address = Base + (Scale × Index) + Disp



memory location

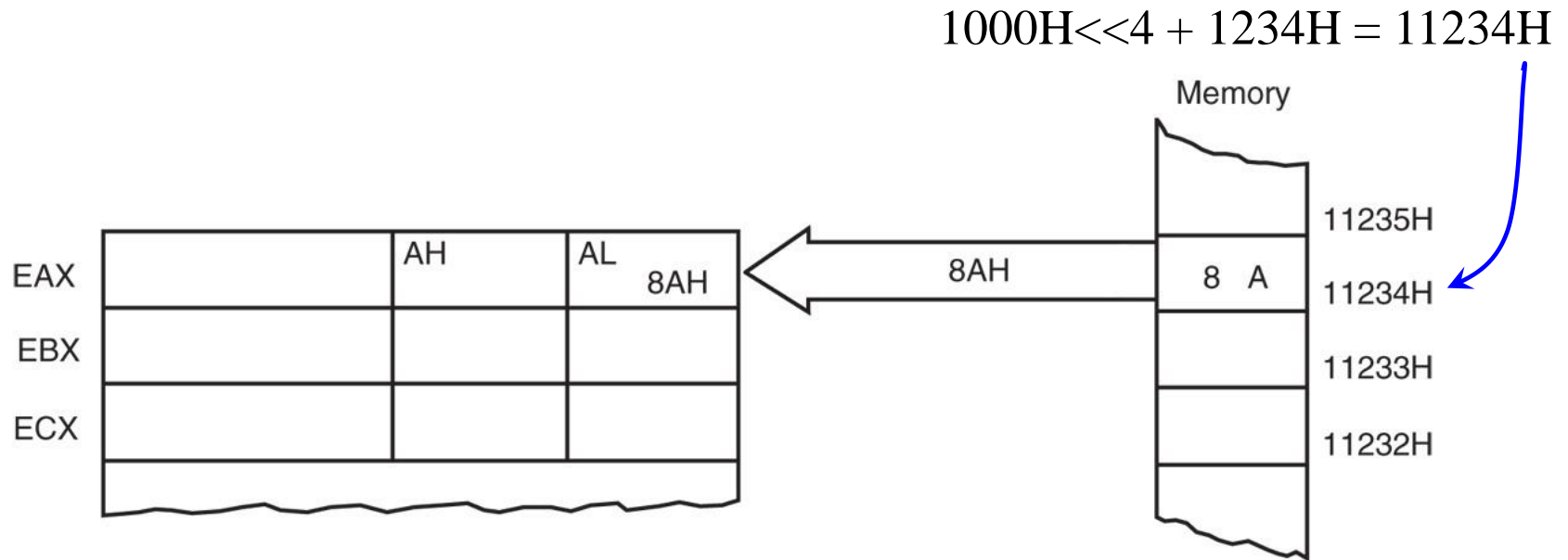
- Address is formed by adding the displacement to the default data segment address or an alternate segment address.
- Two basic forms of direct data addressing:
  - direct addressing, which applies to a MOV between a memory location and AL, AX, or EAX
  - displacement addressing, which applies to almost any instruction in the instruction set

# Direct Addressing

- Direct addressing with a MOV instruction transfers data between a memory location, located within the data segment, and the AL (8-bit), AX (16-bit), or EAX (32-bit) register.
  - usually a 3-byte long instruction
- e.g., load AL from the data segment memory location DATA (1234H)
  - MOV AL, [1234H] or
  - MOV AL, DATA

note: DATA is a symbolic memory location (i.e., label), while 1234H is the actual hexadecimal location

**Figure 3–5** The operation of the `MOV AL,[1234H]` instruction when DS=1000H.



- This instruction transfers a copy contents of memory location 11234H into AL.
  - the linear address is formed by adding 1234H (the offset address) and 10000H (the data segment address of 1000H times 10H) in a system operating in the real mode

# TABLE 3–3 Direct addressed instructions using EAX, AX, and AL and RAX in 64-bit mode

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV AL,NUMBER	8 bits	Copies the byte contents of data segment memory location NUMBER into AL
MOV AX,COW	16 bits	Copies the word contents of data segment memory location COW into AX
MOV EAX,WATER*	32 bits	Copies the doubleword contents of data segment location WATER into EAX
MOV NEWS,AL	8 bits	Copies AL into byte memory location NEWS
MOV THERE,AX	16 bits	Copies AX into word memory location THERE
MOV HOME,EAX*	32 bits	Copies EAX into doubleword memory location HOME
MOV ES:[2000H],AL	8 bits	Copies AL into extra segment memory at offset address 2000H
MOV AL,MOUSE	8 bits	Copies the contents of location MOUSE into AL; in 64-bit mode MOUSE can be any address
MOV RAX,WHISKEY	64 bits	Copies 8 bytes from memory location WHISKEY into RAX

# Displacement Addressing

- Almost identical to direct addressing, except the instruction is 4 bytes wide instead of 3.
  - MOV AL, [1234H] ; A0 34 12
  - MOV CL, [1234H] ; 8A 0E 34 12
- In 80386 through Pentium 4, this instruction can be up to 7 bytes wide if a 32-bit register and a 32-bit displacement are specified.
- This type of direct data addressing is much more flexible because most instructions use it.

# TABLE 3–4 Examples of direct data addressing using a displacement

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV CH,DOG	8 bits	Copies the byte contents of data segment memory location DOG into CH
MOV CH,DS:[1000H]*	8 bits	Copies the byte contents of data segment memory offset address 1000H into CH
MOV ES,DATA6	16 bits	Copies the word contents of data segment memory location DATA6 into ES
MOV DATA7,BP	16 bits	Copies BP into data segment memory location DATA7
MOV NUMBER,SP	16 bits	Copies SP into data segment memory location NUMBER
MOV DATA1,EAX	32 bits	Copies EAX into data segment memory location DATA1
MOV EDI,SUM1	32 bits	Copies the doubleword contents of data segment memory location SUM1 into EDI



# How would compiler use this mode?

- The compiler uses direct data addressing mode to access static addresses (e.g., global variables) that are determined at compile-time. For example:

```
int var;
```

```
void f(int x) {  
    var = x;  
}
```

```
f:
```

```
    mov    eax, [esp+4] ; eax is x  
    mov    var, eax      ; store x to var  
    ret
```

x86-64 gcc 12.2, option: -O2 -m32

# Register Indirect Addressing

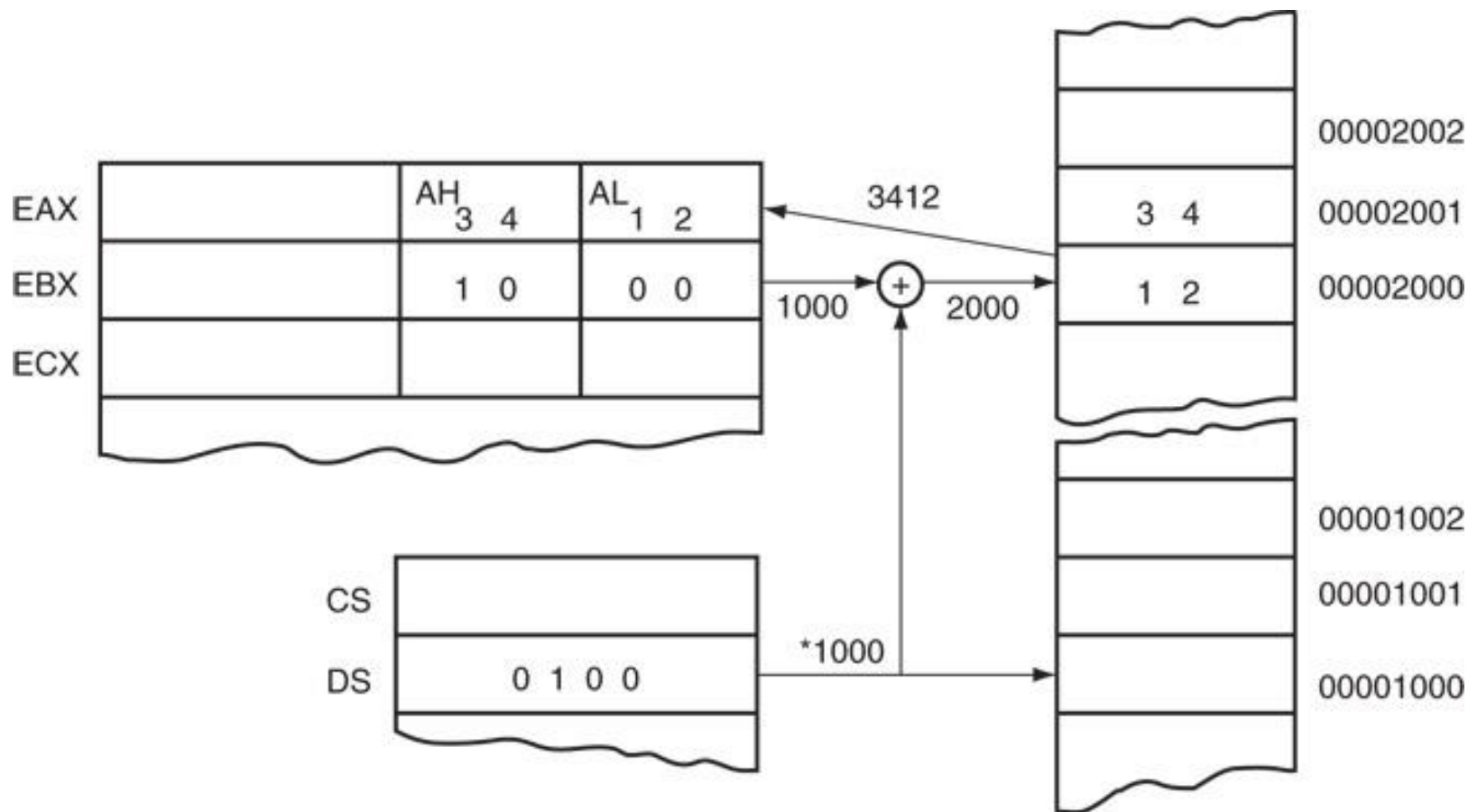
Effective Address = Base + (Scale × Index) + Disp



memory location (GPR)

- For indirect addressing
  - In the 8086 through the 80286, indirect addressing can only use the BX, BP, SI and DI registers, e.g., `MOV AX,[BX]`.
  - 80386 and above allow any extended register, e.g., `MOV AX,[EDX]`
  - In the 64-bit mode, segment registers are not used in address calculation.

**Figure 3–6** The operation of the **MOV AX,[BX]** instruction when BX = 1000H and DS = 0100H. Note that this instruction is shown after the contents of memory are transferred to AX.



\*After DS is appended with a 0.

**TABLE 3–5** Examples of register indirect addressing

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV CX,[BX]	16 bits	Copies the word contents of the data segment memory location addressed by BX into CX
MOV [BP],DL*	8 bits	Copies DL into the stack segment memory location addressed by BP
MOV [DI],BH	8 bits	Copies BH into the data segment memory location addressed by DI
MOV [DI],[BX]	—	Memory-to-memory transfers are not allowed except with string instructions
MOV AL,[EDX]	8 bits	Copies the byte contents of the data segment memory location addressed by EDX into AL
MOV ECX,[EBX]	32 bits	Copies the doubleword contents of the data segment memory location addressed by EBX into ECX
MOV RAX,[RDX]	64 bits	Copies the quadword contents of the memory location address by the linear address located in RDX into RAX (64-bit mode)

- The **data segment** is used by default with register indirect addressing or any other mode that uses **BX, DI, or SI** to address memory.
- If the **BP** register addresses memory, the **stack segment** is used by default.
  - these settings are considered the default for these four index and base registers
- For the 80386 and above:
  - EBP addresses memory in the stack segment by default.
  - EAX, EBX, ECX, EDX, EDI, and ESI address memory in the data segment by default.

- When using a 32-bit register to address memory in the real mode, contents of the register must never exceed 0000FFFFH.
- In the protected mode, any value can be used in a 32-bit register that is used to indirectly address memory.
  - as long as it does not access a location outside the segment, dictated by the access rights byte
- In the 64-bit mode, segment registers are not used in address calculation; the register contains the actual linear memory address.

# Size Directives

- In general, the intended size of the data at a given memory address can be inferred from the instruction. For example
  - `MOV AL, [DI]` is a byte-sized move instruction, but
  - `MOV [DI], 10H` is ambiguous.
- In some cases, indirect addressing requires specifying the size of the data by the **size directive** or **pointer directive**: **BYTE PTR**, **WORD PTR**, **DWORD PTR** or **QWORD PTR**.
  - these directives **indicate the size of the memory data** addressed by the memory **pointer (PTR)**

- The instruction **MOV BYTE PTR [DI],10H** designates the location addressed by DI as a byte-sized memory location.
- Likewise, the **MOV DWORD PTR [DI],10H** identifies the memory location as doubleword-sized.
- The size directives (e.g., **BYTE PTR**, **WORD PTR**) are used only with instructions that address a memory location through a pointer or index register with immediate data.
- With SIMD instructions, the octal **QWORD PTR**, represents a 128-bit-wide number.

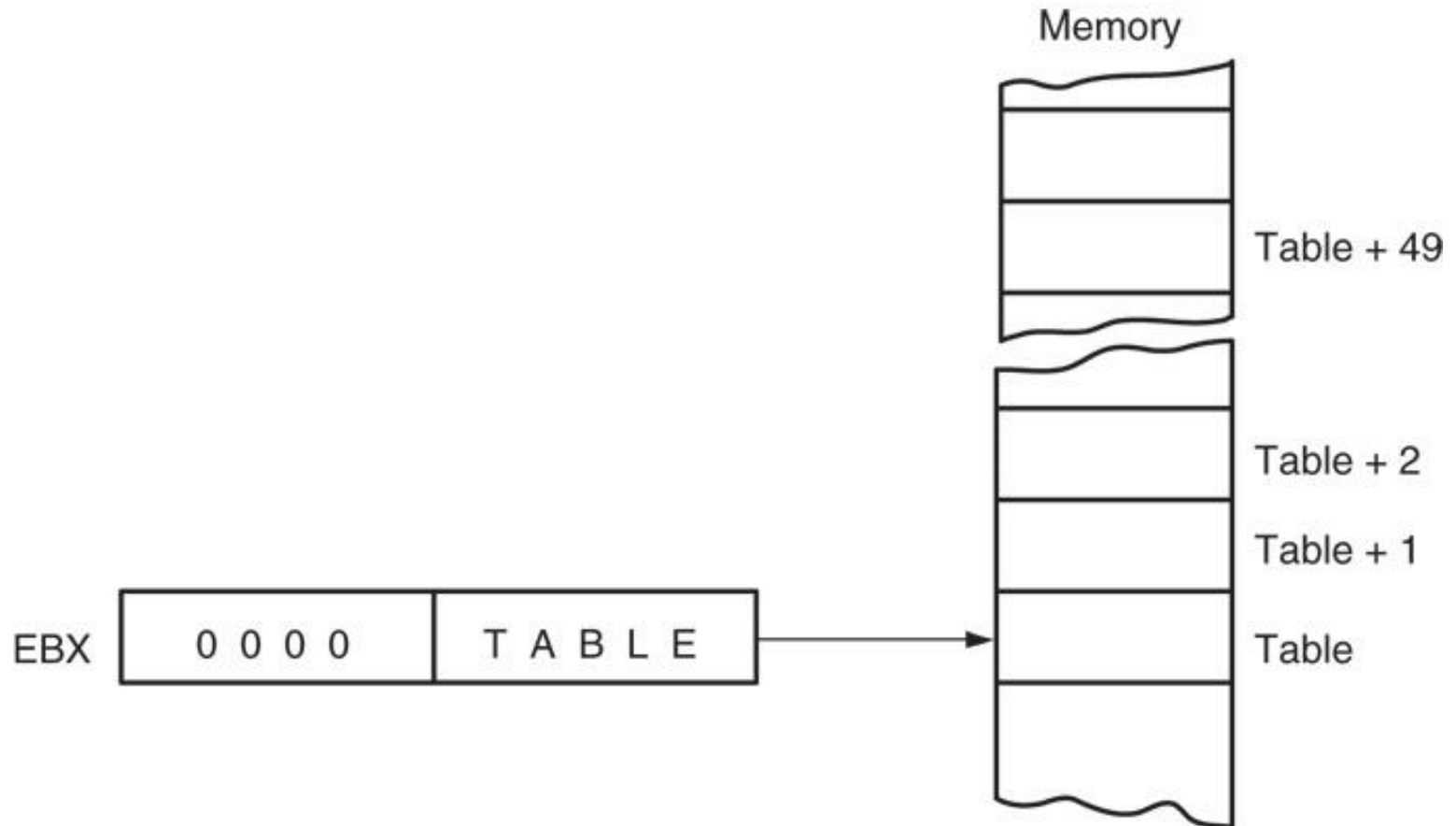


# How do size directives influence the instruction encoding?

- In 64 bit mode:
  - `MOV [RAX], 5`    Error: ambiguous operand size for `MOV'
  - `MOV BYTE PTR [RAX], 5`    ; C6 00 05  
                                         opcode   operand
  - `MOV WORD PTR [RAX], 5`    ; 66 C7 00 05 00  
                                 operand prefix opcode operand
  - `MOV DWORD PTR [RAX], 5` ; C7 00 05 00 00 00  
                                 opcode   operand
  - `MOV QWORD PTR [RAX], 5` ; 48 C7 00 05 00 00 00  
                         prefix for x86-64 opcode   operand

- Indirect addressing often allows a program to refer to tabular data located in memory.
- Figure 3–7 shows the table and the BX register used to sequentially address each location in the table.
- To accomplish this task, load the starting location of the table into the BX register with a MOV immediate instruction.
- After initializing the starting address of the table, use register indirect addressing to store the 50 samples sequentially.

**Figure 3–7** An array (TABLE) containing 50 bytes that are indirectly addressed through register BX.



# Base-Plus-Index Addressing

Effective Address = Base + (Scale × Index) + Disp



memory location (GPRs)

- The **base register** often holds the beginning location of a memory array.
- The **index register** holds the relative position of an element in the array
  - whenever BP addresses memory data, both the stack segment register and BP generate the effective address

# Base-Plus-Index Addressing

Effective Address = Base + (Scale × Index) + Disp



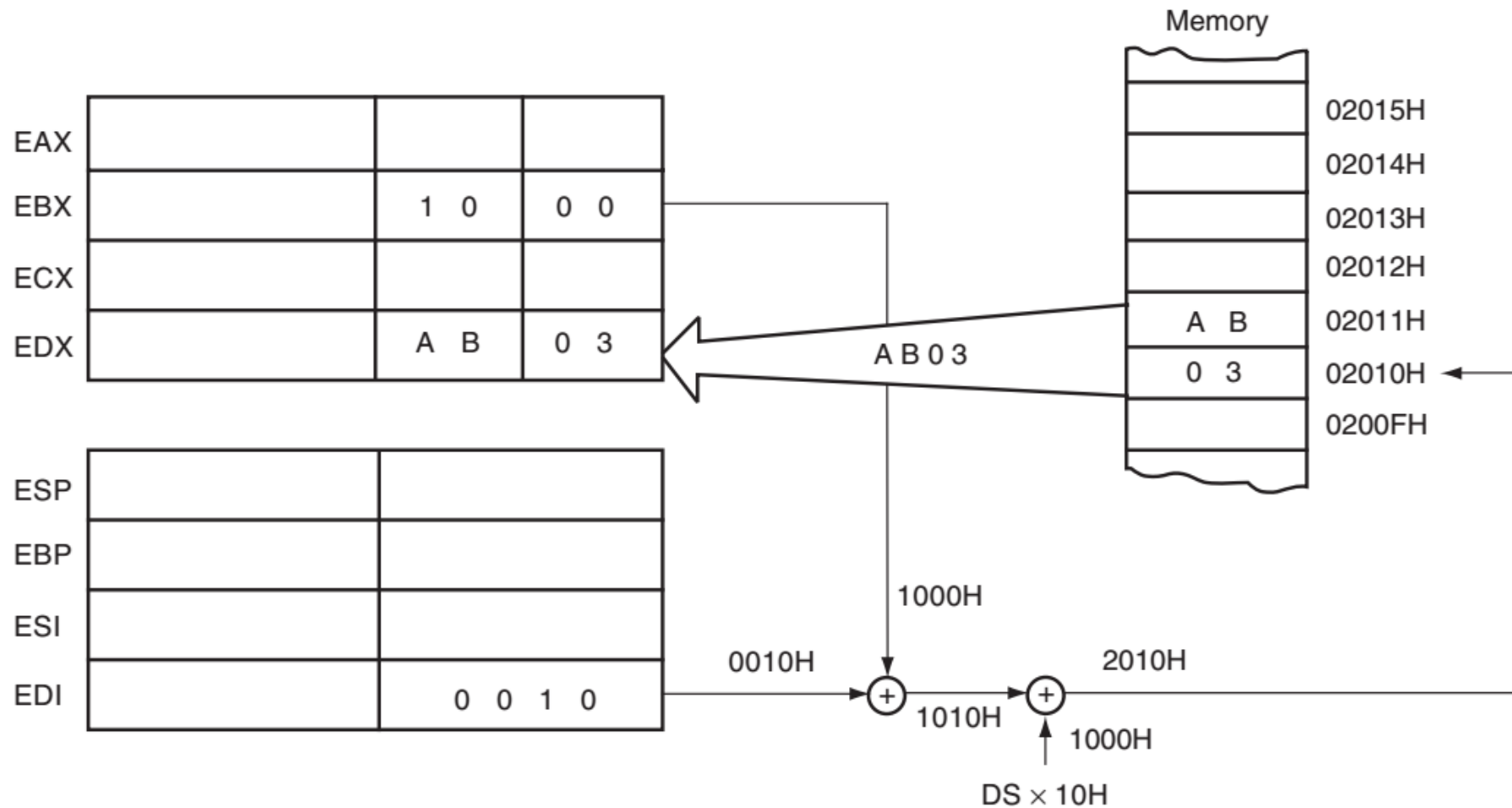
memory location (GPRs)

- For base-plus-index addressing
  - In the 8086 through the 80286, this type of addressing uses one **base register (BP or BX)** and one **index register (DI or SI)** to indirectly address memory, e.g., MOV DX,[BX + DI].
  - 80386 and above allow the combination of any two 32-bit registers (**except that ESP cannot be used as an index register**), e.g., MOV DL,[EAX+EBX].

# ***Locating Data with Base-Plus-Index Addressing***

- Figure 3–8 shows how data are addressed by the `MOV DX,[BX + DI]` instruction when the microprocessor operates in the real mode.
- The Intel assembler requires this addressing mode appear as `[BX][DI]` instead of `[BX + DI]`.
- The `MOV DX,[BX + DI]` instruction is `MOV DX,[BX][DI]` for a program written for the Intel ASM assembler.

**Figure 3–8** An example showing how the base-plus-index addressing mode functions for the `MOV DX, [BX + DI]` instruction. Notice that memory address 02010H is accessed because DS=0100H, BX=1000H and DI=0010H.



**TABLE 3–6** Examples of base-plus-index addressing

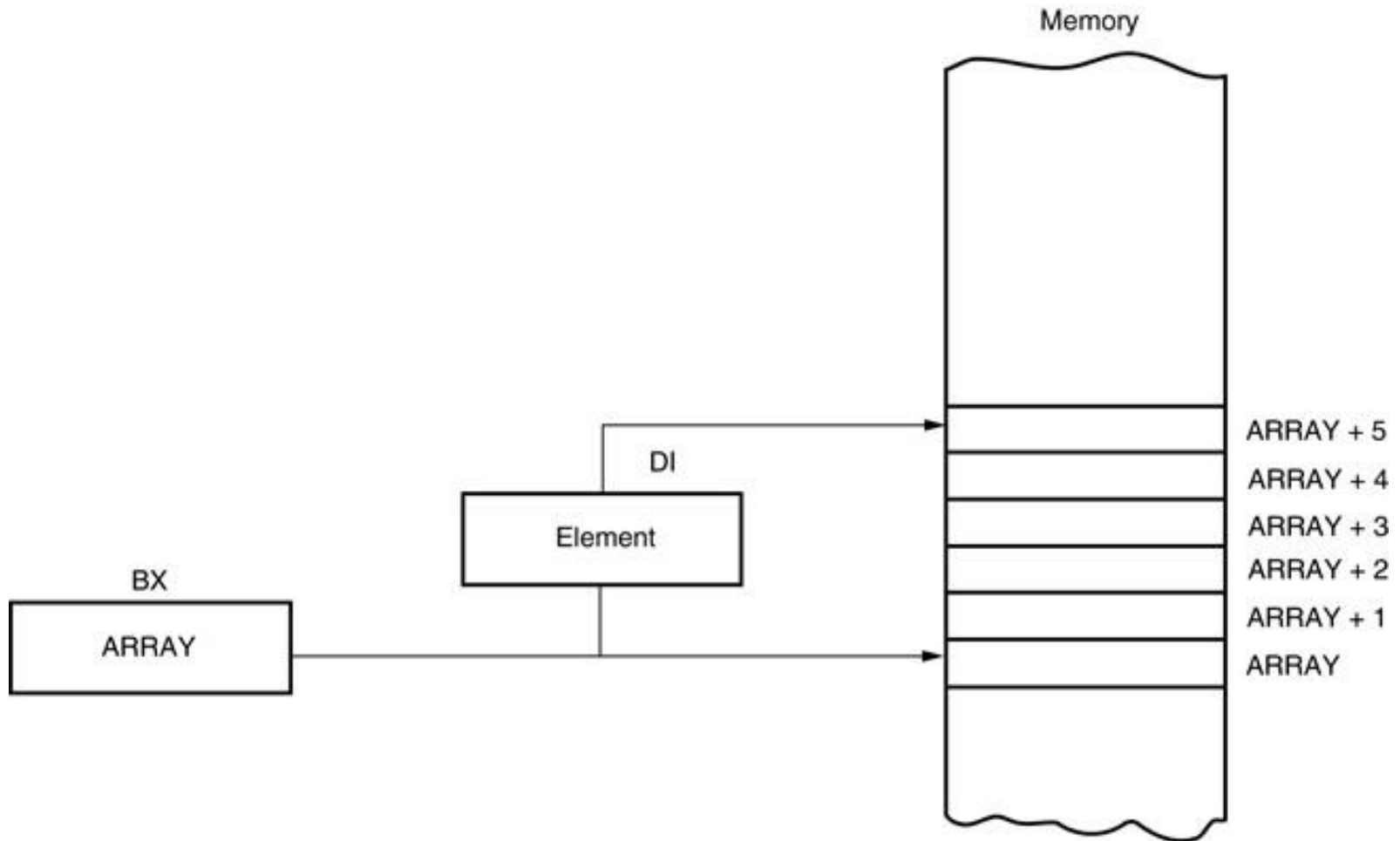
<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV CX,[BX+DI]	16 bits	Copies the word contents of the data segment memory location addressed by BX plus DI into CX
MOV CH,[BP+SI]	8 bits	Copies the byte contents of the stack segment memory location addressed by BP plus SI into CH
MOV [BX+SI],SP	16 bits	Copies SP into the data segment memory location addressed by BX plus SI
MOV [BP+DI],AH	8 bits	Copies AH into the stack segment memory location addressed by BP plus DI
MOV CL,[EDX+EDI]	8 bits	Copies the byte contents of the data segment memory location addressed by EDX plus EDI into CL
MOV [EAX+EBX],ECX	32 bits	Copies ECX into the data segment memory location addressed by EAX plus EBX
MOV [RSI+RBX],RAX	64 bit	Copies RAX into the linear memory location addressed by RSI plus RBX (64-bit mode)



# ***Locating Array Data Using Base-Plus-Index Addressing***

- A major use is to address elements in a memory array.
- To accomplish this, load the BX register (base) with the beginning address of the array and the DI register (index) with the element number to be accessed.
- Figure 3–9 shows the use of BX and DI to access an element in an array of data.

**Figure 3–9** An example of the base-plus-index addressing mode. Here an element (DI) of an ARRAY (BX) is addressed.



# How would compiler use this mode?

- The compiler uses base-plus-index addressing mode to access an one-dimensional array.
- For example:

```
int foo(char *buf, int index)
{
    return buf[index];
}
```

foo:

```
    mov    eax, [esp+4] ; eax ← buf
    mov    edx, [esp+8] ; edx ← index
    movsx  eax, BYTE PTR [edx+eax]
                                ; eax ← buf[index]
    ret
```

x86-64 gcc 12.2, option: -O2 -m32

# Register Relative Addressing

Effective Address = Base + (Scale × Index) + Disp

OR

memory location (GPRs)

- For register relative addressing
  - In the 8086 through the 80286, the memory data are addressed by adding the displacement to the contents of a base register (BP or BX) or an index register (DI or SI), e.g., MOV AX,[DI+100H].
  - In the 80386 and above, the displacement can be a 32-bit number and the register can be any 32-bit register (except that ESP cannot be used as an index register), e.g., MOV DL,[EAX+10H].

# Register Relative Addressing

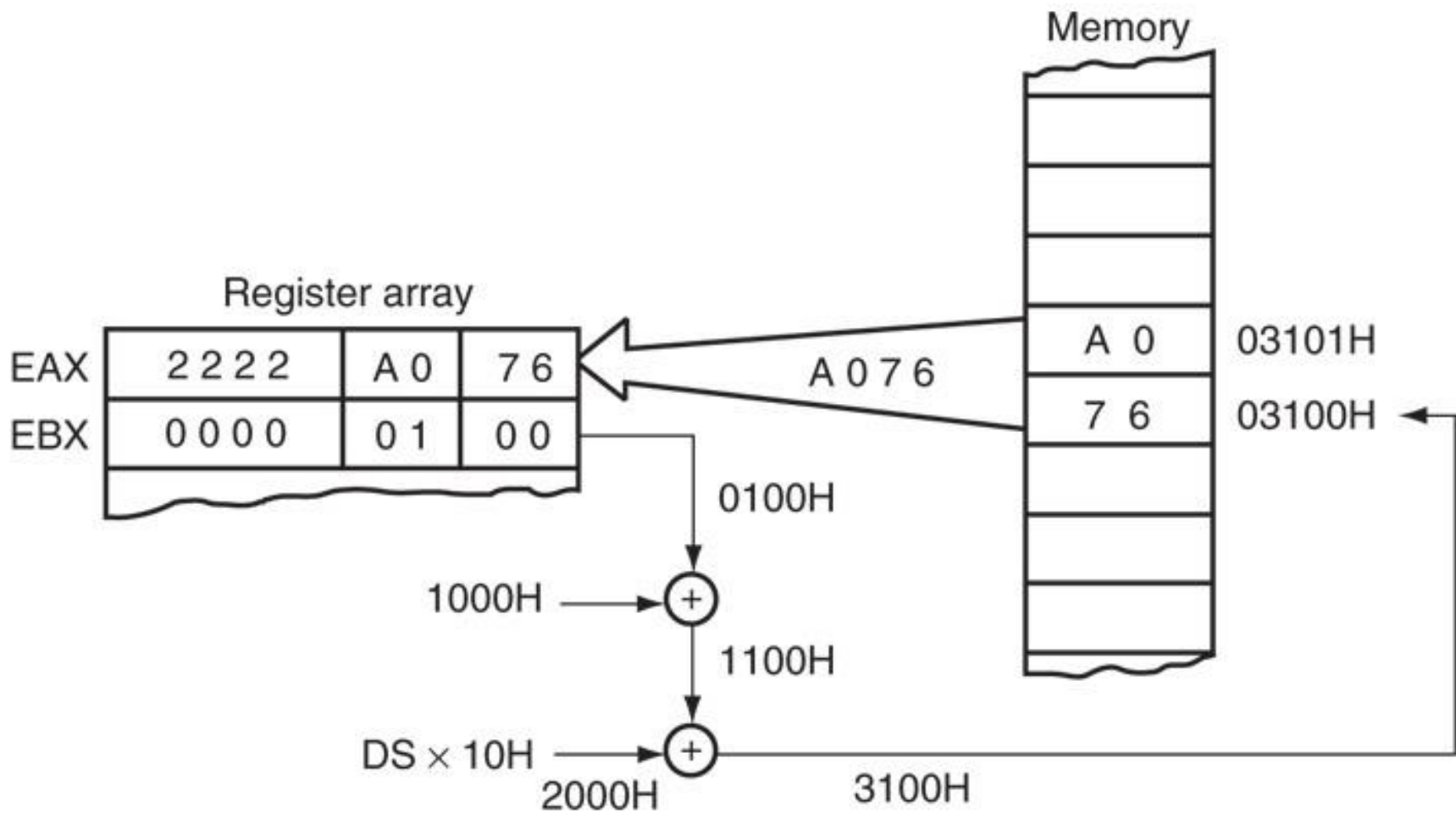
Effective Address = Base + (Scale × Index) + Disp

OR

memory location (GPRs)

- Similar to base-plus-index addressing and displacement addressing.
  - data in a segment of memory are addressed by adding the displacement to the contents of a base or an index register.
- Figure 3–10 shows the operation of the MOV AX,[BX+1000H] instruction.
- A real mode segment is 64K bytes long.

**Figure 3–10** The operation of the `MOV AX, [BX+1000H]` instruction, when BX=100H and DS=0200H .



# TABLE 3–7 Examples of register relative addressing

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV AX,[DI+100H]	16 bits	Copies the word contents of the data segment memory location addressed by DI plus 100H into AX
MOV ARRAY[SI],BL	8 bits	Copies BL into the data segment memory location addressed by ARRAY plus SI
MOV LIST[SI+2],CL	8 bits	Copies CL into the data segment memory location addressed by the sum of LIST, SI, and 2
MOV DI,SET_IT[BX]	16 bits	Copies the word contents of the data segment memory location addressed by SET_IT plus BX into DI
MOV DI,[EAX+10H]	16 bits	Copies the word contents of the data segment location addressed by EAX plus 10H into DI
MOV ARRAY[EBX],EAX	32 bits	Copies EAX into the data segment memory location addressed by ARRAY plus EBX
MOV ARRAY[RBX],AL	8 bits	Copies AL into the memory location ARRAY plus RBX (64-bit mode)
MOV ARRAY[RCX],EAX	32 bits	Copies EAX into memory location ARRAY plus RCX (64-bit mode)

# How would compiler use this mode?

- The compiler uses register relative addressing mode for **structure** access:
  - the **base register** holds the **beginning address of the structure**, and
  - the **displacement** contains the **offset of the structure**.
- For example:

```
struct foo {  
    int a;  
    int b;  
};
```

```
int bar(struct foo *foobar) {  
    return foobar->b;  
}
```

```
bar:
```

```
    mov    eax, [esp+4]; eax ← foobar  
    mov    eax, [eax+4]; eax + 4 =  
                                ; foobar→b
```

```
    ret
```

**x86-64 gcc 12.2, option: -O2 -m32**



# Base Relative-Plus-Index Addressing

$$\text{Effective Address} = \text{Base} + (\text{Scale} \times \text{Index}) + \text{Disp}$$

AND  
memory location (GPRs)

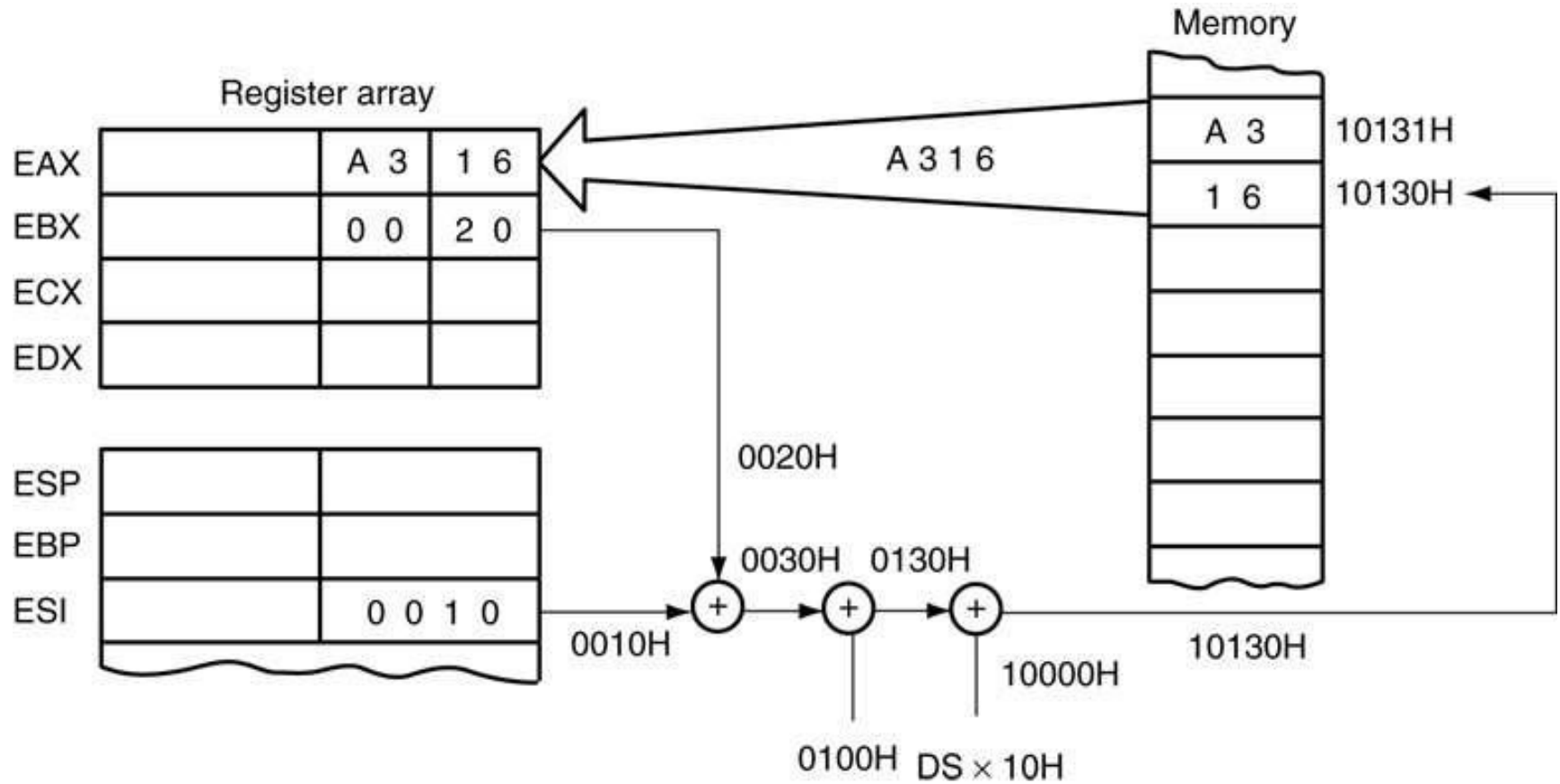


- Similar to base-plus-index addressing.
  - adds a displacement
  - uses a base register and an index register to form the memory address
- This type of addressing mode often addresses a two-dimensional array of memory data.

# ***Addressing Data with Base Relative-Plus-Index***

- Least-used addressing mode.
- Figure 3–12 shows how data are referenced if the instruction executed by the microprocessor is `MOV AX, [BX + SI + 100H]`.
  - displacement of 100H adds to BX and SI to form the offset address within the data segment
- This addressing mode is too complex for frequent use in programming.

**Figure 3–12** An example of base relative-plus-index addressing using a **MOV AX,[BX+SI+100H]** instruction. Note: DS=1000H



# How would compiler use this mode?

- The compiler uses base relative-plus-index addressing mode to access **structure within an array**, for example:

```
struct foo {  
    int a;  
    int b;  
    int c;  
    int d  
};
```

```
int query(struct foo foos[], int i)  
{  
    struct foo x = foos[i];  
    return x.d;  
}
```

query:

```
mov    eax, [esp + 4] ;  $\text{eax} \leftarrow \text{foos}$ 
```

```
mov    ecx, [esp + 8] ;  $\text{ecx} \leftarrow i$ 
```

```
shl    ecx, 4          ;  $i * 16$ 
```

```
mov    eax, [eax + ecx + 12]
```

$\text{; } \text{eax} + \text{ecx} + 12 = \text{foos}[i].\text{d}$

```
ret
```

x86-64 clang trunk, option: -O2 -m32

# Scaled-Index Addressing

$$\text{Effective Address} = \text{Base} + (\text{Scale} \times \text{Index}) + \text{Disp}$$

AND

memory location (GPRs)

- Unique to 80386 - Core2 microprocessors.
  - uses two 32-bit registers (a base register and an index register) to access the memory
- The second register (index) is multiplied by a **scaling factor**.
  - the scaling factor can be 1x, 2x, 4x, 8x
- A scaling factor of 1x is implied and need not be included, e.g., MOV AL, [EBX + ECX].
- Displacement is optional.

**TABLE 3–9** Examples of scaled-index addressing

<i>Assembly Language</i>	<i>Size</i>	<i>Operation</i>
MOV EAX,[EBX+4*ECX]	32 bits	Copies the doubleword contents of the data segment memory location addressed by the sum of 4 times ECX plus EBX into EAX
MOV [EAX+2*EDI+100H],CX	16 bits	Copies CX into the data segment memory location addressed by the sum of EAX, 100H, and 2 times EDI
MOV AL,[EBP+2*EDI+2]	8 bits	Copies the byte contents of the stack segment memory location addressed by the sum of EBP, 2, and 2 times EDI into AL
MOV EAX,ARRAY[4*ECX]	32 bits	Copies the doubleword contents of the data segment memory location addressed by the sum of ARRAY and 4 times ECX into EAX

# How would compiler use this mode?

- The compiler uses scaled-index addressing mode to access **structure within an array**, for example:

```
struct foo {  
    int a;  
    int b  
};
```

```
int query(struct foo foos[], int i)  
{  
    struct foo x = foos[i];  
    return x.b;  
}
```

query:

```
mov    eax, [esp + 4] ;  $eax \leftarrow \text{foos}$   
mov    edx, [esp + 8] ;  $edx \leftarrow i$   
mov    eax, [eax + edx*8 + 4]  
                ;  $eax+edx*8+4 = \text{foos}[i].b$ 
```

ret

x86-64 clang trunk, option: -O2 -m32

# RIP Relative Addressing

- The legacy x86 supports IP-relative addressing only in control transfer instructions.
- 64-bit mode supports data addressing relative to the 64-bit instruction pointer (RIP) to address a linear location in the flat memory model.
- The **RIP-relative addressing** is represented with the register relative addressing [Base + Displacement] syntax, except that the base register is RIP instead of a general purpose register.



- RIP-relative addressing uses a signed 32-bit displacement to calculate the effective address of the next instruction by sign-extend the 32-bit value and add to the 64-bit value in RIP, e.g.,

```
int var;
```

```
void f(int x) {  
    var = x;  
}
```

f:

```
    mov    var[rip], edi    ; edi = x  
    ret
```

- Using RIP-relative addressing makes **position-independent code** smaller and simpler, where all code and data need to be addressable within a 32-bit offset.

# Canonical Addressing and Canonical Form (1/2)

- In 64-bit mode, an address is considered to be in **canonical form** if bits 63 through to the most-significant are set to either all ones or all zeros.
- For a 48-bit linear address, a canonical address must have bits 63 through 48 set to zeros or ones (depending on whether bit 47 is a zero or one),
  - **canonical address**: **FFFF**8010BC001000,  
**0000**7C80B8102040
  - **non-canonical address**: **1122**334455667788,  
**3375**DA44B5667788

# Canonical Addressing and Canonical Form (2/2)

- If the memory address is a non-canonical form, a general-protection exception (#GP) is generated, e.g., `MOV RAX, [1122334455667788H]`.
- By checking canonical-address form, the architecture prevents software from exploiting unused high bits of pointers for other purposes.
- Software complying with canonical-address form on a specific processor implementation can run unchanged on long-mode implementations supporting larger virtual-address spaces.

# AT&T vs Intel Syntax (1/6)

- **AT&T** and **Intel** are two syntax branches of x86 assembly language. They will become the same machine codes and can be converted to each other.
- Their notable differences are:

## ⊕ Direction of Operands

### AT&T syntax

1. Data flows from left to right

`movl $1, %eax`    # 1 -> eax

### Intel syntax

1. Data flows from right to left

`mov eax, 1`    ; eax <- 1

# AT&T vs Intel Syntax (2/6)

## ⊕ Prefixes

### AT&T syntax

1. '%' before registers
2. '\$' before immediate operands

`movl $1, %eax`

### Intel syntax

1. No prefixes before registers or immediate operands.

`mov eax, 1`

## ⊕ Memory Addressing

### AT&T syntax

1. `disp(base, index, scale)`

`subl 20(%ebx, %ecx, 4), %eax`

### Intel syntax

1. `[base + index * scale + disp]`

`sub eax, [ebx + ecx * 4 + 20]`

# AT&T vs Intel Syntax (3/6)

## ⊕ Size of Memory Operands

### AT&T syntax

1. suffixes of b, w, l and q specify byte, word, doubleword and quadword memory references

`movl $0x7FFF, (%eax)`

### Intel syntax

1. prefixing memory operands with byte ptr, word ptr, dword ptr and qword ptr

`mov dword ptr [eax], 7FFFh`

## ⊕ Number Formats

### AT&T syntax

1. BIN: 0b100
2. OCT: 04
3. DEC: 4
4. HEX: 0x4

### Intel syntax

1. BIN: 100b
2. OCT: 4o
3. DEC: 4
4. HEX: 4h

# AT&T vs Intel Syntax (4/6)

- An example

```
int sum (int * buf, int index) {  
    return (buf[index]+10);  
}
```

AT&T syntax

sum:

```
movl    4(%esp), %eax  
movl    8(%esp), %edx  
movl    (%eax,%edx,4), %eax  
addl    $10, %eax  
ret
```

Intel syntax

sum:

```
mov     eax, [esp+4]  
mov     edx, [esp+8]  
mov     eax, [eax+edx*4]  
add     eax, 10  
ret
```

- GCC and Clang++ use option **masm=intel** to generate assembly code with Intel syntax.

# AT&T vs Intel Syntax (5/6)

- AT&T Syntax

- Syntax Redundancy and Complex

- The category of operands is explicit (**\$1**, **%eax**)
- The size of operands is explicit (**movl**, **addl**)
- Reduces the possibility of making mistakes
- Need to type more characters while coding

- Somehow Counter-intuitive

- Direction of operands (**movl** **%ebx**, **%eax** **# ebx -> eax**)
- Memory addressing (disp(base, index, scale))



# AT&T vs Intel Syntax (6/6)

- Intel Syntax

- Looks Clean

- But the size and category of operands is implicit
    - When operating imm and mem, it needs to point the size of operands out (e.g., byte ptr, word ptr, etc.)

- More Intuitive

- Direction of operands (`mov eax, ebx ; eax <- ebx`)
    - Memory addressing (`[base + index * scale + disp]`)

- Supported by many assemblers and disassemblers

- MASM, NASM, FASM, TASM, YASM
    - GAS with `.intel_syntax`
    - IDA Pro

# Summary—Instruction Operands

Type	Example	Equivalent C/C++ Statement
Immediate	<code>mov eax,42</code>	<code>eax = 42</code>
	<code>imul ebx,11h</code>	<code>ebx *= 0x11</code>
	<code>xor dl,55h</code>	<code>dl ^= 0x55</code>
	<code>add esi,8</code>	<code>esi += 8</code>
Register	<code>mov eax,ebx</code>	<code>eax = ebx</code>
	<code>inc ecx</code>	<code>ecx += 1</code>
	<code>add ebx,esi</code>	<code>ebx += esi</code>
	<code>mul ebx</code>	<code>edx:eax = eax * ebx</code>
Memory	<code>mov eax,[ebx]</code>	<code>eax = *ebx</code>
	<code>add eax,[val1]</code>	<code>eax += *val1</code>
	<code>or ecx,[ebx+esi]</code>	<code>ecx  = *(ebx + esi)</code>
	<code>sub word ptr [edi],12</code>	<code>*(short*)edi -= 12</code>

**Table** three types of operands: immediate, register, and memory

# Summary——Memory Addressing Modes

$$\text{Offset} = \text{Base} + (\text{Index} * \text{Scale}) + \text{Displacement}$$

Addressing Form	Example
BaseReg	<code>mov rax,[rbx]</code>
BaseReg + Disp	<code>mov rax,[rbx+16]</code>
IndexReg * SF + Disp	<code>mov rax,[r15*8+48]</code>
BaseReg + IndexReg	<code>mov rax,[rbx+r15]</code>
BaseReg + IndexReg + Disp	<code>mov rax,[rbx+r15+32]</code>
BaseReg + IndexReg * SF	<code>mov rax,[rbx+r15*8]</code>
BaseReg + IndexReg * SF + Disp	<code>mov rax,[rbx+r15*8+64]</code>
RIP + Disp	<code>mov rax,[Val]</code>

**Table** Memory Operand Addressing Forms

# Summary——Effective Address Computation

$$\text{Offset} = \text{Base} + (\text{Index} * \text{Scale}) + \text{Displacement}$$

- **8086-80286 :**
  - **Base:** BX/BP
  - **Index:** SI/DI
  - **Disp:** 8-bit/16-bit
- **80386 and above :**
  - **Base:** any 32-bit register
  - **Index:** any 32-bit register except ESP
  - **Disp:** 8-bit/16-bit/32-bit
- A scale factor can be 1, 2, 4, and 8, which may be used only when an index also is used.
- When the BP/EBP or ESP is used, the SS segment is the default segment. In all other cases, the DS segment is the default segment.

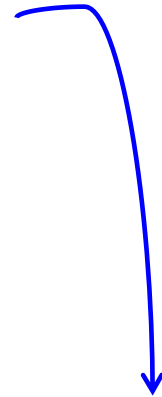
- **Problem:** Which of the addressing mode in the following instruction is invalid ?

A. `MOV EAX, [ESP + 2]`

B. `MOV EAX, [ESP + EBX + 2]`

C. `MOV EAX, [ESP + 2*EBX + 2]`

D. `MOV EAX, [2*ESP + EBX + 2]`



The assembler is smart enough to make ESP the base and EBX the index.

## 3–2 PROGRAM MEMORY- ADDRESSING MODES

- Used with the JMP (jump) and CALL instructions.
- The destination (target) operand specifies the address of the instruction being jumped to.
- Two different types of jump offset:
  - relative offset
  - absolute offset
- Four different types of jumps:
  - short jump
  - near jump
  - far jump
  - task switch

# PROGRAM MEMORY-ADDRESSING MODES

- Two different types of jump offset:
  - A **relative offset** is generally specified as a **label** in assembly code (e.g., JMP start), but at the machine code level, it is encoded as a signed displacement relative to the current value of the instruction pointer in the **EIP register**.
  - An **absolute offset** is specified indirectly in a **general-purpose register** or a **memory location** (e.g., JMP AX). An absolute offset is an offset from the base of the **code segment**.

- an example of two different types of jump offset :

071A0	B8	MOV AX, @data
071A1	17	
071A2	07	
071A3	8E	MOV DS, AX
071A4	DB	
071A5	B8	MOV AX, start
071A6	0C	
071A7	00	
071A8	EB	relative offset JMP start
071A9	02	
071AA	FF	JMP AX
071AB	E0	

start: 071AC

absolute offset



# PROGRAM MEMORY-ADDRESSING MODES

- Four different types of jumps:
  - **Short jump**—A near jump where the jump range is limited to  $-128$  to  $+127$  from the current EIP value.
  - **Near jump**—A jump to an instruction within the current code segment (the segment pointed to by the CS register), referred to as an intrasegment jump.
  - **Far jump**—A jump to an instruction located in a different segment than the current code segment but at the same privilege level, referred to as an intersegment jump.
  - **Task switch**—A jump to an instruction located in a different task (in protected mode only).

# Direct Program Memory Addressing

- The instructions for direct program memory addressing store an absolute far address with the opcode, e.g., JMP 1234:5678.
- Often called a *far jump* because it can jump to any memory location for the next instruction.
  - in real mode, any location within the first 1M byte
  - In protected mode operation, the far jump can jump to any location in the 4G-byte address range in the 80386 - Core2 microprocessors

- The microprocessor uses this form to perform operating modes control transfers.
- E.g., far jump after switching from real mode to protected mode

[ bits 16 ]

real mode

```
switch_to_pm:
    cli
    lgdt [ gdt_descriptor ]
    mov eax, cr0
    or eax, 0x1
    mov cr0, eax
    jmp CODE_SEG:init_pm
```

[ bits 32 ]

protected mode

```
init_pm:
    mov ax, DATA_SEG
    mov ds, ax
    mov ss, ax
```

CODE\_SEG equ gdt\_code - gdt\_start

gdt\_start:

descriptor table

gdt\_null:

```
    dd 0x0
    dd 0x0
```

null descriptor

gdt\_code:

```
    dw 0xffff
    dw 0x0
    db 0x0
    db 10011010b
    db 11001111b
    db 0x0
```

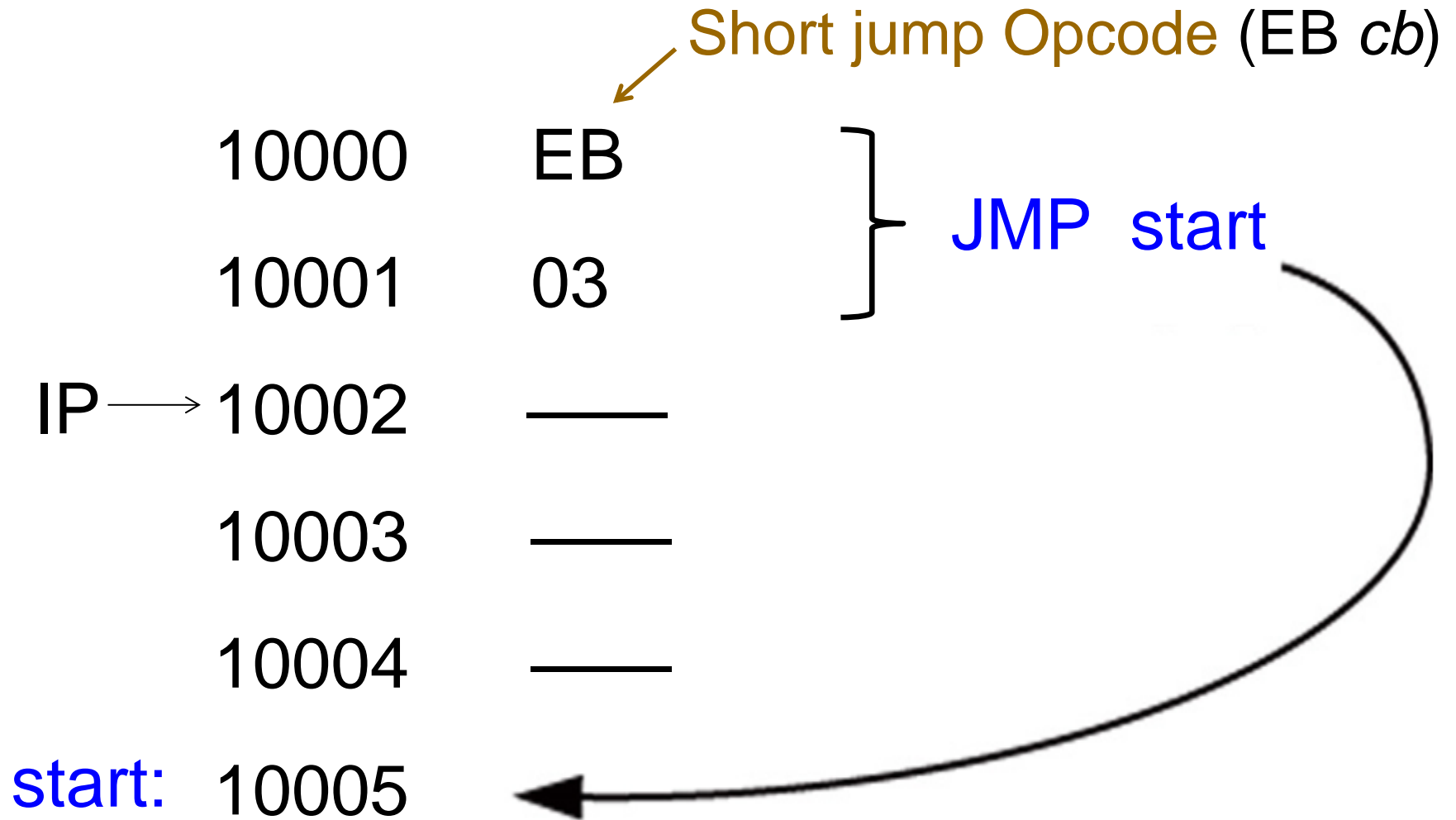
code descriptor

- The instruction using direct program addressing is the **intersegment** or **far CALL** instruction.
- Usually, the name of a memory address, called a **label**, refers to the location that is called or jumped to instead of the actual numeric address.
- We can use a **FAR PTR** directive to obtain a far jump, e.g., **JMP FAR PTR START**.

# Relative Program Memory Addressing

- The term *relative* means “relative to the instruction pointer (IP)”.
- The JMP instruction is a 1-byte instruction, with a 1-byte or a 2-byte displacement that adds to the instruction pointer.
- A 1-byte displacement is used in short jumps, and a 2-byte displacement is used with near jumps and calls. Both types are considered to be intrasegment jumps.

**Figure 3–15** A **JMP start** instruction. This instruction skips over the 3 bytes of memory that follow the JMP instruction.



# Indirect Program Memory Addressing

- The microprocessor allows several forms of program indirect memory addressing.
  - In the 8086 through the 80286, this type of addressing can use 16-bit register (AX, BX, CX, DX, SP, BP, DI, or SI), or any **relative register** ([BP], [BX], [DI], or [SI]) with a displacement, e.g., **JMP NEAR PTR[DI+2]**.
  - In 80386 and above, an extended register can be used to hold the address or indirect address of a relative JMP or CALL, e.g., JMP EAX.

- If a relative register holds the address, the jump is considered to be an indirect jump.
- For example, **JMP NEAR PTR [BX]** refers to the memory location within the data segment at the offset address contained in BX.
  - at this offset address is a 16-bit number used as the offset address in the intrasegment jump
  - this type of jump is sometimes called an *indirect-indirect* or *double-indirect jump*



**TABLE 3–10** Examples of indirect program memory addressing

<i>Assembly Language</i>	<i>Operation</i>
JMP AX	Jumps to the current code segment location addressed by the contents of AX
JMP CX	Jumps to the current code segment location addressed by the contents of CX
JMP NEAR PTR[BX]	Jumps to the current code segment location addressed by the contents of the data segment location addressed by BX
JMP NEAR PTR[DI+2]	Jumps to the current code segment location addressed by the contents of the data segment memory location addressed by DI plus 2
JMP TABLE[BX]	Jumps to the current code segment location addressed by the contents of the data segment memory location address by TABLE plus BX
JMP ECX	Jumps to the current code segment location addressed by the contents of ECX
JMP RDI	Jumps to the linear address contained in the RDI register (64-bit mode)

- Figure 3–16 shows a **jump table** that is stored, beginning at memory location TABLE. The exact address chosen from the TABLE is determined by an index stored with the jump instruction.

This is a jump table that stores addresses of various programs.

```
TABLE DW LOC0
      DW LOC1
      DW LOC2
      DW LOC3
```

```
;Using indirect addressing for a jump
;
MOV  BX, 4           ;address LOC2
JMP  TABLE[BX]      ;jump to LOC2
```

The jump table is referenced by the program

# 3–3 STACK MEMORY-ADDRESSING MODES

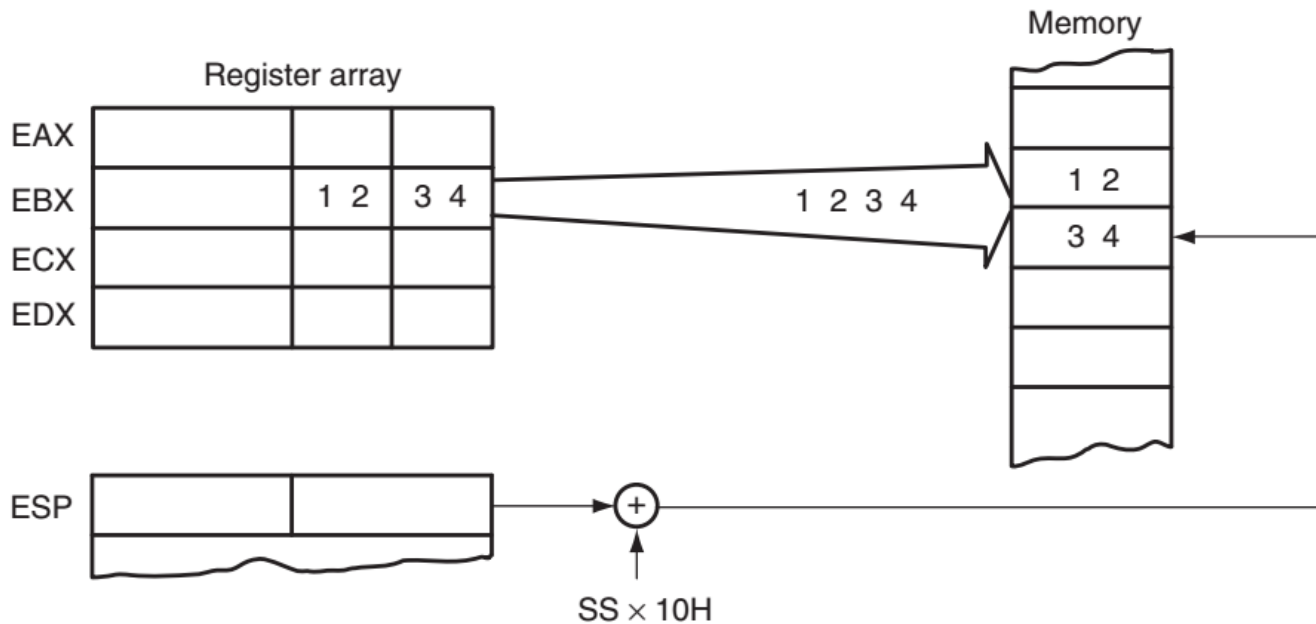
- PUSH/POP are important instructions that *store* and *retrieve* data from the LIFO (last-in, first-out) stack memory.
- Six forms of the PUSH and POP instructions:
  - register, memory, immediate
  - segment register, flags, all registers
- The PUSH and POP immediate & PUSHA and POPA (all registers) available 80286 - Core2.

- **Register addressing** allows contents of any 16-bit register to transfer to & from the stack.
- **Memory-addressing** PUSH and POP instructions store contents of a 16- or 32 bit memory location on the stack or stack data into a memory location.
- **Immediate addressing** allows immediate data to be pushed onto the stack, but not popped off the stack.

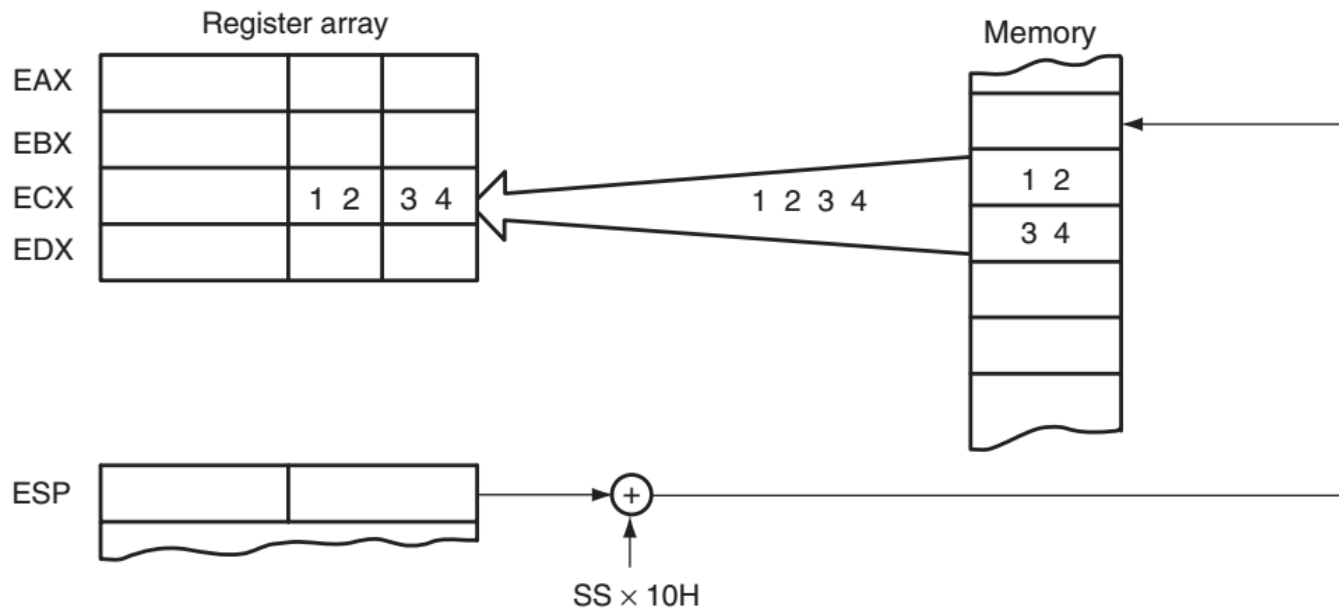
- **Segment register addressing** allows contents of any segment register to be pushed onto the stack or removed from the stack.
  - CS may be pushed, but data from the stack may never be popped into CS
- The **flags** may be pushed or popped from that stack.
  - contents of all registers may be pushed or popped

- Data are placed on the stack with a **PUSH instruction**; removed with a **POP instruction**.
- Stack memory is maintained by two registers:
  - the stack segment register (SS)
  - the stack pointer (SP or ESP)
- Whenever a word of data is pushed onto the stack:
  - the high-order 8 bits are placed in the location addressed by  $SP - 1$
  - low-order 8 bits are placed in the location addressed by  $SP - 2$

- The SP is decremented by 2 so the next word is stored in the next available stack location.
  - the SP/ESP register always points to an area of memory located within the stack segment.
- In protected mode operation, the SS register holds a selector that accesses a descriptor for the base address of the stack segment.
- When data are popped from the stack:
  - the low-order 8 bits are removed from the location addressed by SP
  - high-order 8 bits are removed; the SP register is incremented by 2



**PUSH BX** places the contents of BX onto the stack



**POP CX** removes data from the stack and places them into CX



# Initializing the Stack

- Assembly language stack segment setup, e.g.,:

```
STACK_SEG SEGMENT STACK
```

```
    DW  100H DUP(?)
```

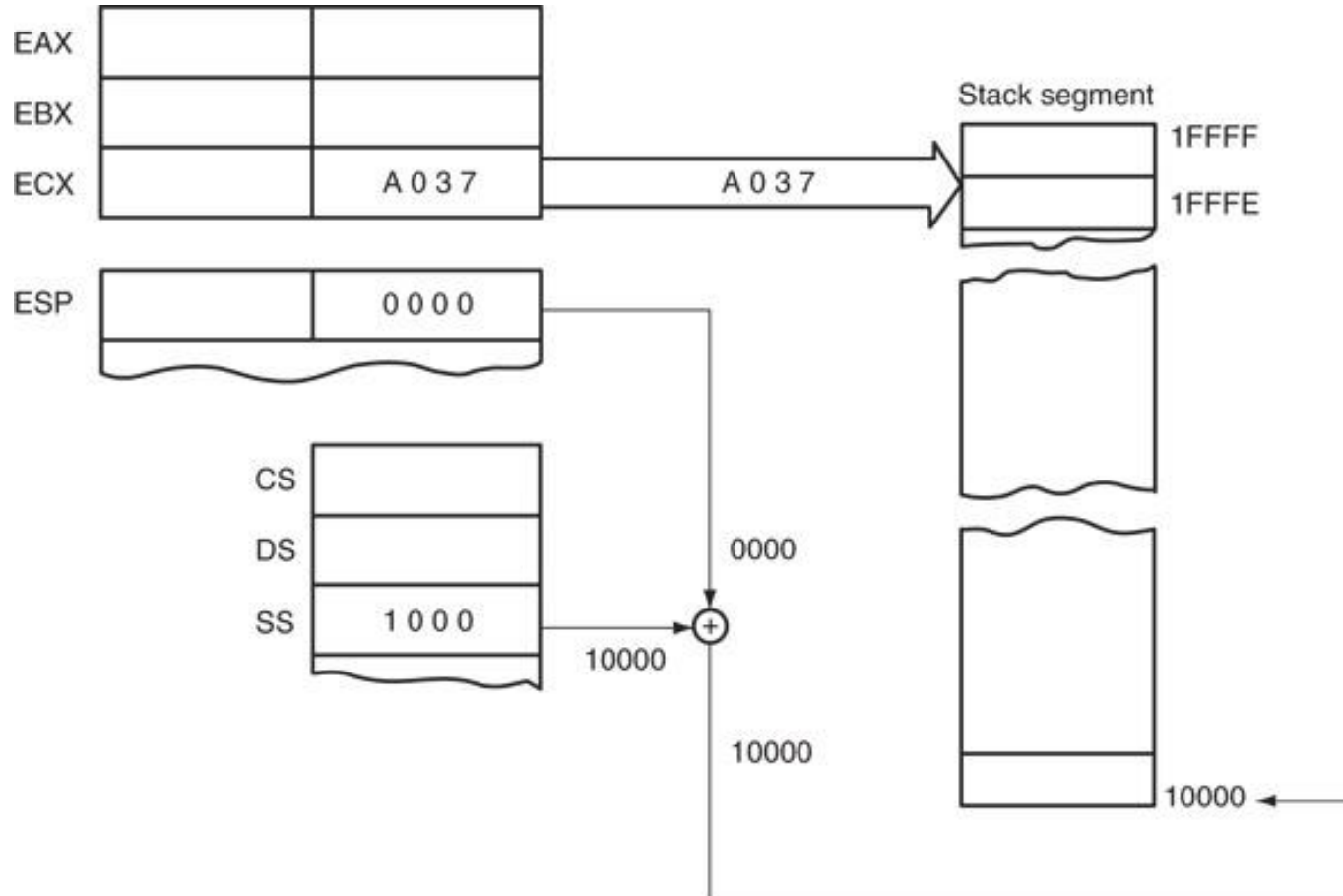
```
STACK_SEG ENDS
```

- first statement identifies start of the segment
  - last statement identifies end of the stack segment
- Assembler and linker programs place correct stack segment address in SS and the length of the segment (top of the stack) into SP.

- If the stack is not specified, a warning will appear when the program is linked.
- Memory section is located in the **program segment prefix (PSP)**, appended to the beginning of each program file.
- If you use more memory for the stack, you will erase information in the PSP.
  - information critical to the operation of your program and the computer
- Error often causes the program to crash.

- When the stack area is initialized, load both the stack segment (SS) register and the stack pointer (SP) register.
- Figure 4–16 shows how this value causes data to be pushed onto the top of the stack segment with a PUSH CX instruction.
- All **segments are cyclic** in nature
  - the top location of a segment is contiguous with the bottom location of the segment

**Figure 4–16** The PUSH CX instruction, showing the cyclical nature of the stack segment. This instruction is shown just before execution, to illustrate that the stack bottom is contiguous to the top.



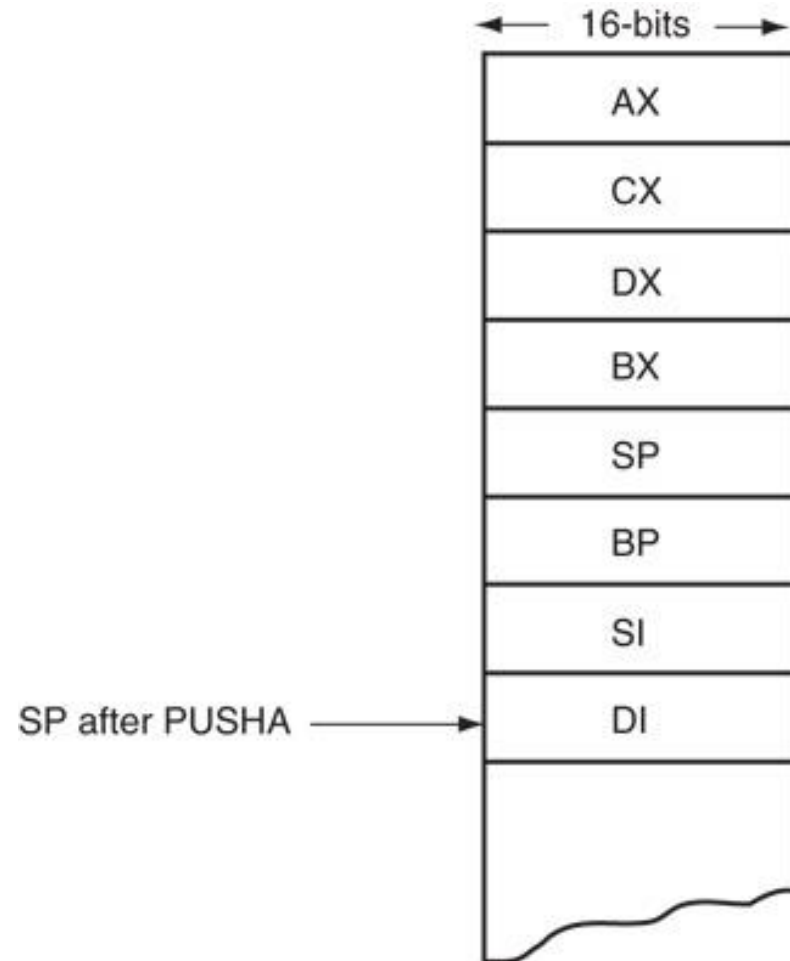
# PUSH

- **PUSH** transfers data to the stack:
  - 8086 - 80286 transfer **2 bytes**, but **never 1 byte**
  - 80386 and above transfer **2, 4 or 8 bytes**
- **PUSHA** (push all) instruction copies contents of the internal register set, except the segment registers, to the stack.
- PUSHA instruction copies the registers to the stack in the following order: AX, CX, DX, BX, SP (**original value**), BP, SI, and DI.
- The value pushed for the SP register is its value before prior to pushing the first register.

- **PUSHAD** (push all double) instruction pushes 32-bit registers in 80386 - Pentium 4.
- The PUSHHA and PUSHAD reference the same opcode (0x60):
  - PUSHHA is used when the operand-size is 16
  - PUSHAD is used when the operand size is 32
  - not available on early 8086/8088 processors
  - do not function in the 64-bit mode of operation for the Pentium 4
- **PUSHF** (**push flags**) instruction copies the contents of the flag register to the stack.

- PUSH instruction pushes all the internal 16-bit registers onto the stack, illustrated in 4–14.
  - requires 16 bytes of stack memory space to store all eight 16-bit registers
- After all registers are pushed, the contents of the SP register are decremented by 16.
- PUSH is very useful when the entire register set of 80286 and above must be saved.
- PUSHAD instruction places 32-bit register set on the stack in 80386 - Core2.
  - PUSHAD requires 32 bytes of stack storage

**Figure 4–14** The operation of the PUSHA instruction, showing the location and order of stack data.





# POP

- Performs the inverse operation of PUSH.
- **POP** removes data from the stack and places it in a target 16-bit register, segment register, or a 16-bit memory location.
  - not available as an immediate POP
- **POPA** (pop all) removes 16 bytes of data from the stack and places them into the following registers, in the order shown: DI, SI, BP, SP, BX, DX, CX, and AX.

- **POPAD** (pop all double) instruction pops 32-bit registers in 80386 - Pentium 4.
- The POPA and POPAD reference the same opcode (0x61):
  - POPA is used when the operand-size is 16
  - POPAD is used when the operand size is 32
  - not available on early 8086/8088 processors
  - do not function in the 64-bit mode of operation for the Pentium 4
- **POPF** (pop flags) removes a 16-bit number from the stack and places it in the flag register.

# SUMMARY

- The MOV instruction copies the contents of the source operand into the destination operand.
- The second source never changes for any instruction.
- Register addressing specifies any 8-bit register (AH, AL, BH, BL, CH, CL, DH, or DL) or any 16-bit register (AX, BX, CX, DX, SP, BP, SI, or DI).

# SUMMARY

(*cont.*)

- The segment registers (CS, DS, ES, or SS) are also addressable for moving data between a segment register and a 16-bit register/memory location or for PUSH and POP.
- In the 80386 through the Core2 microprocessors, the extended registers also are used for register addressing; they consist of EAX, EBX, ECX, EDX, ESP, EBP, EDI, and ESI.

# SUMMARY

(*cont.*)

- In the 64-bit mode, the registers are RAX, RBX, RCX, RDX, RSP, RBP, RDI, RSI, and R8 through R15.
- The MOV immediate instruction transfers the byte or word that immediately follows the opcode into a register or a memory location.
- Immediate addressing manipulates constant data in a program.

# SUMMARY

(*cont.*)

- In the 80386 and above, doubleword immediate data may also be loaded into a 32-bit register or memory location.
- The `.MODEL` statement is used with assembly language to identify the start of a file and the type of memory model used with the file.
- If the size is `TINY`, the program exists in the code segment, and assembled as a command (`.COM`) program.

# SUMMARY

(*cont.*)

- If the SMALL model is used, the program uses a code and data segment and assembles as an executable (.EXE) program.
- Direct addressing occurs in two forms in the microprocessor: direct addressing and displacement addressing.

# SUMMARY

(*cont.*)

- Both forms of addressing are identical except that direct addressing is used to transfer data between EAX, AX, or AL and memory; displacement addressing is used with any register-memory transfer.
- Direct addressing requires 3 bytes of memory, whereas displacement addressing requires 4 bytes.



# SUMMARY

*(cont.)*

- Register indirect addressing allows data to be addressed at the memory location pointed to by either a base (BP and BX) or index register (DI and SI).
- In the 80386 and above, extended registers EAX, EBX, ECX, EDX, EBP, EDI, and ESI are used to address memory data.

# SUMMARY

(*cont.*)

- Base-plus-index addressing often addresses data in an array.
- The memory address for this mode is formed by adding a base register, index register, and the contents of a segment register times 10H.
- In the 80386 and above, the base and index registers may be any 32-bit register except EIP and ESP.

# SUMMARY

(*cont.*)

- Register relative addressing uses a base or index register, plus a displacement to access memory data.
- Base relative-plus-index addressing is useful for addressing a two-dimensional memory array.
- The address is formed by adding a base register, an index register, displacement, and the contents of a segment register times 10H.

# SUMMARY

(*cont.*)

- Scaled-index addressing is unique to the 80386 through the Core2.
- The second of two registers (index) is scaled by a factor of 2 to access words, doublewords, or quadwords in memory arrays.
- The `MOV AX,[ EBX + 2*ECX]` and the `MOV [4 * ECX ],EDX` are examples of scaled-index instructions.

# SUMMARY

(*cont.*)

- Data structures are templates for storing arrays of data and are addressed by array name and field.
- Direct program memory addressing is allowed with the JMP and CALL instructions to any location in the memory system.
- With this addressing mode, the off-set address and segment address are stored with the instruction.

# SUMMARY

(*cont.*)

- Relative program addressing allows a JMP or CALL instruction to branch for-ward or backward in the current code segment by bytes.
- In the 80386 and above, the 32-bit displacement allows a branch to any location in the current code segment by using a displacement value of bytes.
- The 32-bit displacement can be used only in protected mode.

# SUMMARY

(*cont.*)

- Indirect program addressing allows the JMP or CALL instructions to address another portion of the program or subroutine indirectly through a register or memory location.
- The PUSH and POP instructions transfer a word between the stack and a register or memory location.
- A PUSH immediate instruction is available to place immediate data on the stack.

# SUMMARY

- The PUSHA and POPA instructions transfer AX, CX, DX, BX, BP, SP, SI, and DI between the stack and these registers.
- In 80386 and above, the extended register and extended flags can also be transferred between registers and the stack.
- A PUSHFD stores the EFLAGS, whereas a PUSHF stores the FLAGS. POPA and PUSHA are not available in 64-bit mode.



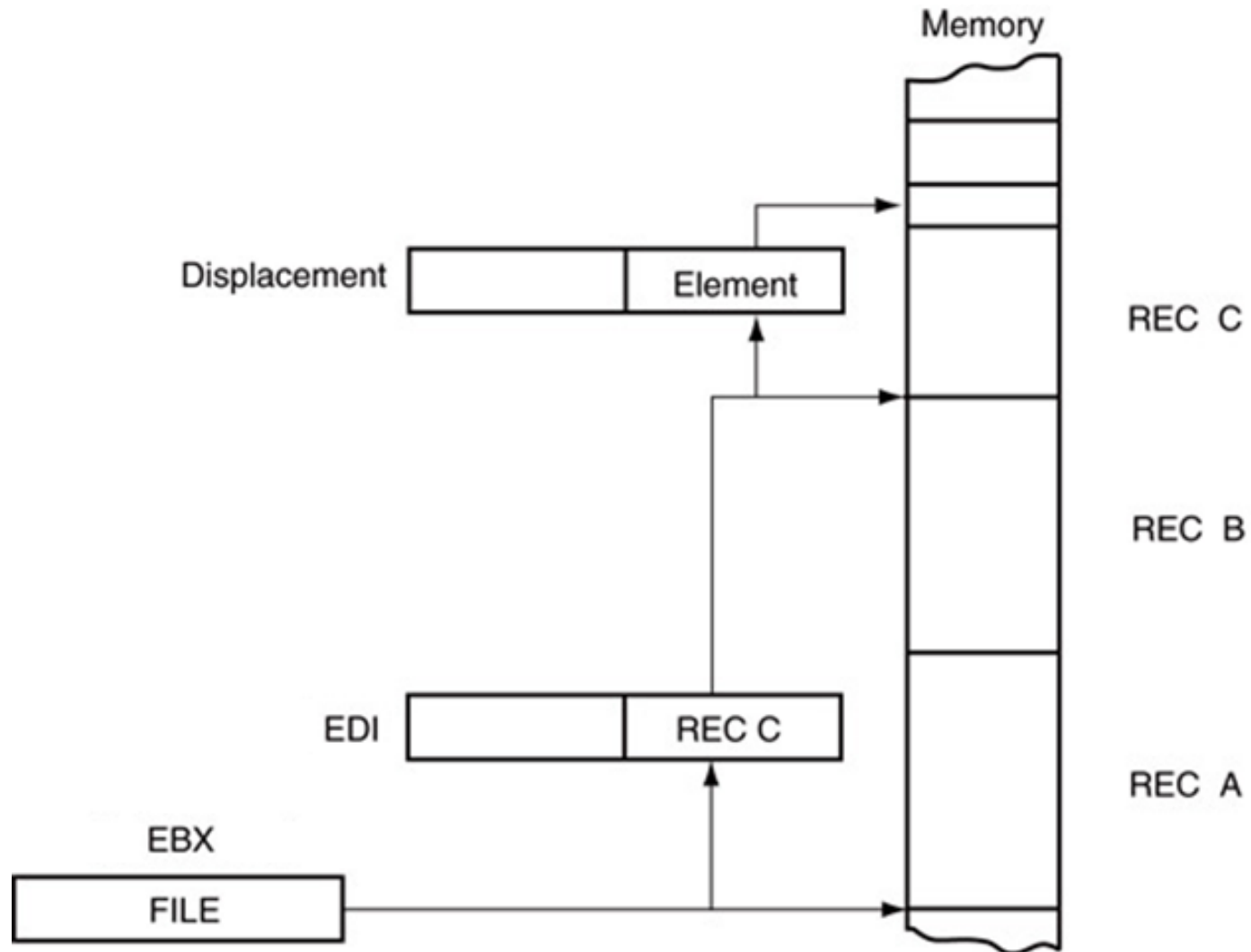
# Assignment

3-10, 23, 28-32, 35, 36, 45, 48, 49, 53

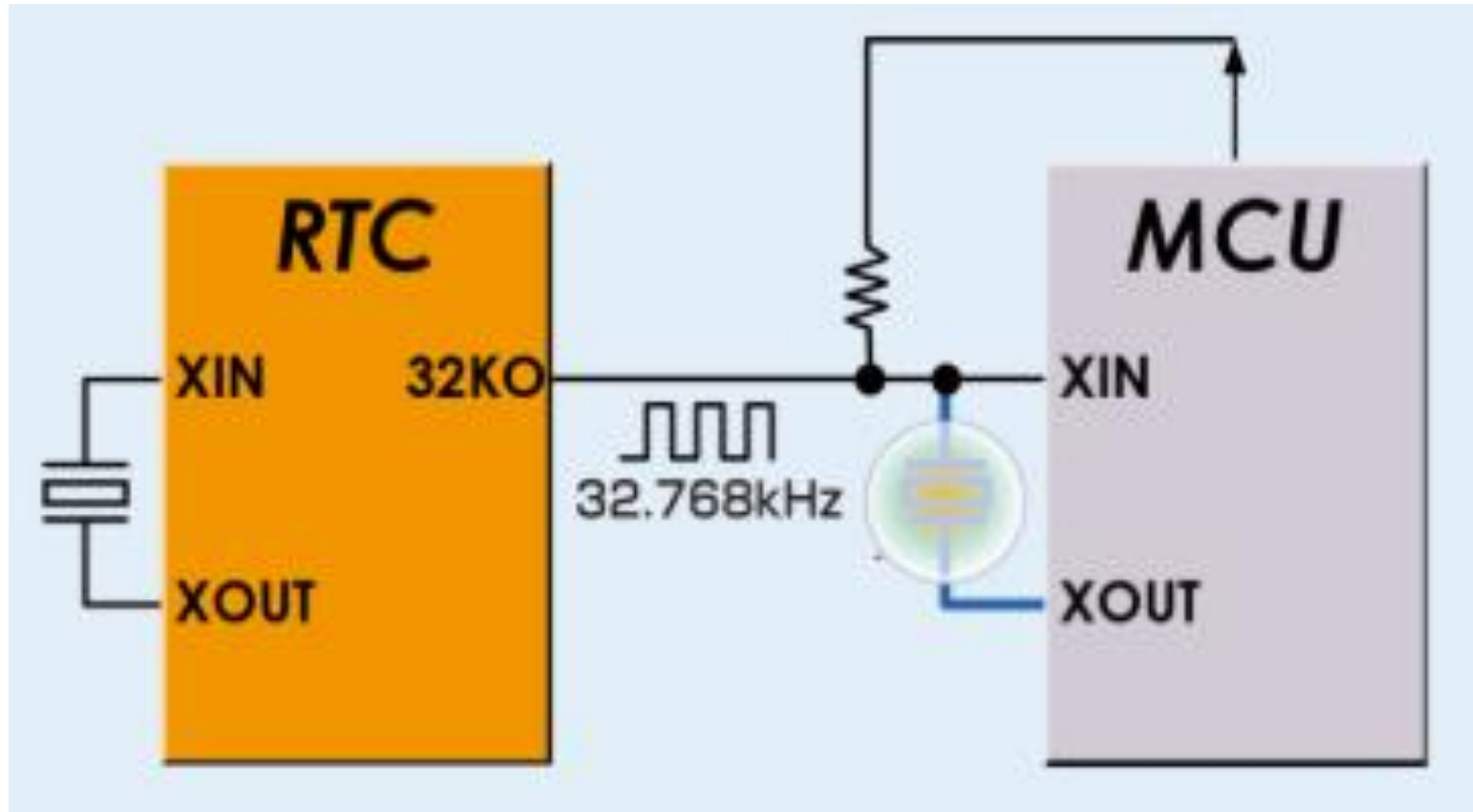
# ***Addressing Arrays with Base Relative-Plus-Index***

- Suppose a file of many records exists in memory, each record with many elements.
  - displacement addresses the file, base register addresses a record, the index register addresses an element of a record
- Figure 3–13 illustrates this very complex form of addressing.

**Figure 3–13** Base relative-plus-index addressing used to access a FILE that contains multiple records (REC).



**EXAMPLE 3–7** create a table that contains 50 samples taken from memory location 0000:046C (real-time clock)



## EXAMPLE 3-7 create a table that contains 50 samples taken from memory location 0000:046C (real-time clock)

```
.MODEL SMALL          ;select small model
.DATA                ;start data segment

[ DATAS DW 50 DUP(?) ;setup array of 50 words 0000 ]

.CODE                ;start code segment
.STARTUP             ;start program
MOV AX,0
MOV ES,AX             ;address segment 0000 with ES
MOV BX,OFFSET DATAS ;address DATAS array with BX
MOV CX,50             ;load counter with 50
AGAIN:
MOV AX,ES:[046CH]   ;get clock value
MOV [BX],AX         ;save clock value in DATAS
INC BX               ;increment BX to next element
INC BX
LOOP AGAIN           ;repeat 50 times

.EXIT                ;exit to DOS
END                  ;end program listing
```

## EXAMPLE 3–8 moves array element 10H into element 20H

```
0000                                .MODEL SMALL                ;select small model
                                .DATA                          ;start data segment
0000 0010 [                        ARRAY DB 16 DUP(?)         ;setup array of 16 bytes
                                00
                                ]
0010 29                            DB 29H                    ;element 10H
0011 001E [                        DB 20 dup(?)
                                00
                                ]
0000                                .CODE                      ;start code segment
                                .STARTUP

0017 B8 0000 R                     MOV BX,OFFSET ARRAY      ;address ARRAY
001A BF 0010                       MOV DI,10H                ;address element 10H
001D 8A 01                         MOV AL,[BX+DI]             ;get element 10H
001F BF 0020                       MOV DI,20H                ;address element 20H
0022 88 01                         MOV [BX+DI],AL            ;save in element 20H

                                .EXIT                          ;exit to DOS
                                END                            ;end program
```

# How would compiler use this mode?

- The compiler uses scaled-index addressing mode to access **structure within a two-dimensional array**, for example:

```
struct foo {  
    int a;  
    int b  
}tbl[10][10];  
  
int query(int i, int j)  
{  
    return tbl[i][j].b;  
}
```

query:

```
mov    eax, [esp+4]    ; eax is i  
mov    edx, [esp+8]    ; edx is j  
lea    eax, [eax+eax*4] ; eax * 5  
lea    eax, [edx+eax*2] ; j + 10i  
mov    eax, tbl[4+eax*8]  
                        ; tbl[4+eax*8] is tbl[i][j].b  
ret
```

## EXAMPLE 3–9 transfer the contents of array element 10H into array element 20H

```

        .MODEL  SMALL                ;select small model
        .DATA                        ;start data segment
ARRAY   DB    16  dup(?)             ;setup ARRAY

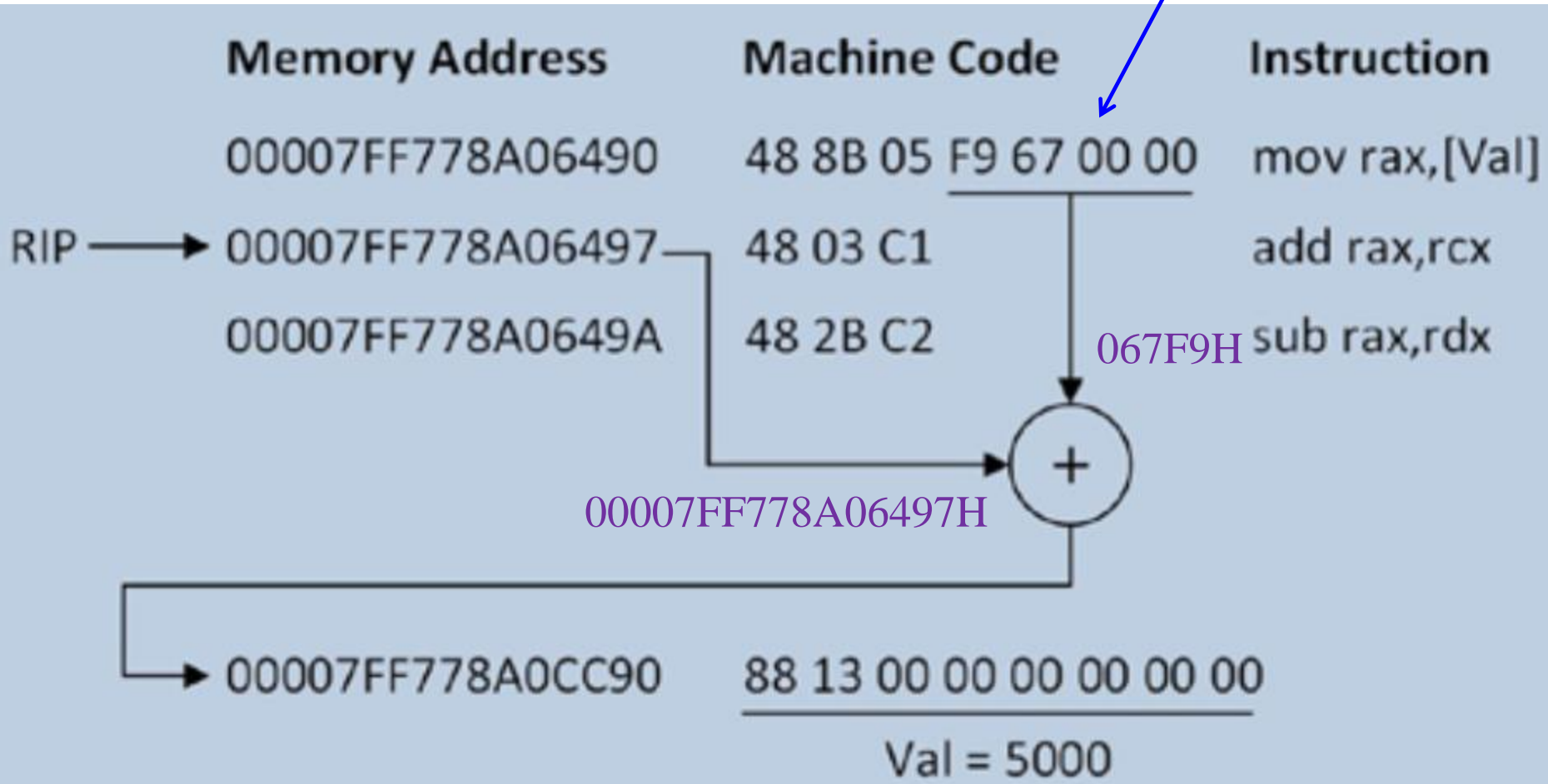
        DB    29                      ;element 10H
        DB    30  dup(?)

        .CODE                        ;start code segment
        .STARTUP                     ;start program
MOV     DI,10H                       ;address element 10H
MOV     AL,ARRAY[DI]                ;get ARRAY element 10H
MOV     DI,20H                       ;address element 20H
MOV     ARRAY[DI],AL                ;save it in element 20H
        .EXIT                        ;exit to DOS
        END                          ;end of program
```

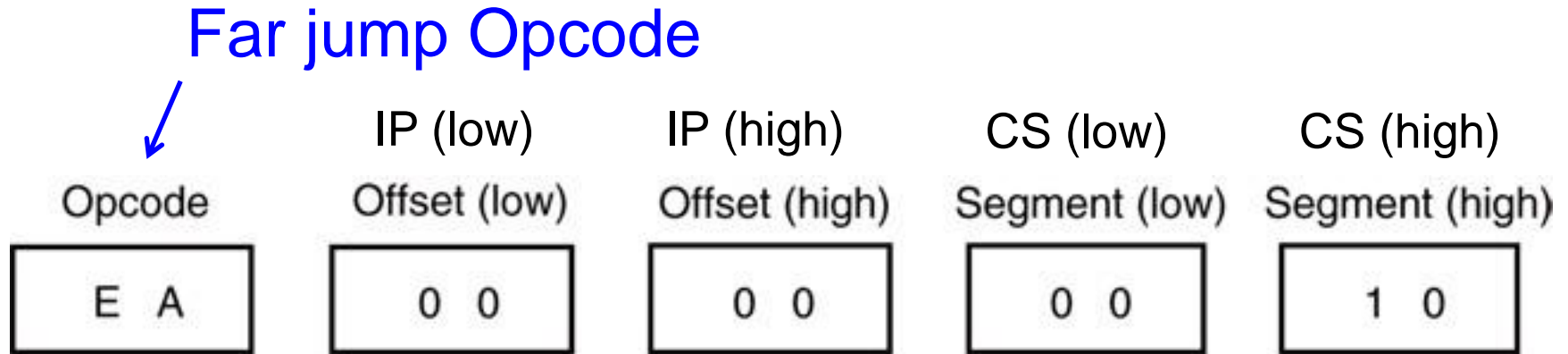


## Example RIP-relative effective address calculation

32-bit displacement



**Figure 3–14** JMP [10000H] instruction loads CS with 1000H and IP with 0000H to jump to memory location 10000H for the next instruction.

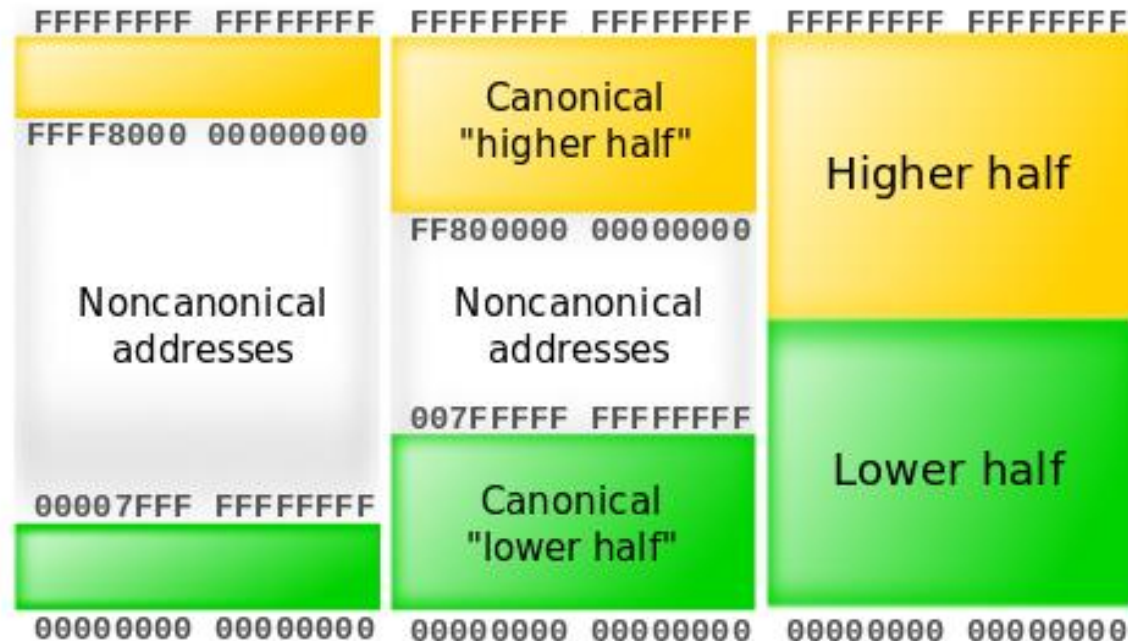


The 5-byte machine language version of a **JMP [10000H]** instruction.

- This JMP instruction loads CS with 1000H and IP with 0000H to jump to memory location 10000H for the next instruction.
  - an **intersegment jump** is a jump to any memory location within the entire memory system

# Canonical Address Form (1/2)

- In 64-bit mode, an address is considered to be in **canonical form** if bits 63 through to the most-significant are set to either all ones or all zeros.
- If the memory address is a non-canonical form, a general-protection exception (#GP) is generated, e.g., **MOV RAX, [1122334455667788H]**.



# Data Structures

- Used to specify how information is stored in a memory array.
  - a template for data
- The start of a structure is identified with the **STRUC** (or **STRUCT**) directive and the end with the **ENDS** statement.
- Syntax

```
name STRUC [alignment] [, NONUNIQUE]
field-declarations
name ENDS
```

## EXAMPLE 3–12 define five fields of information

structure name

```
INFO      STRUC

NAMES     DB    32 dup(?)    ;reserve 32 bytes for a name
STREET    DB    32 dup(?)    ;reserve 32 bytes for the street address
CITY      DB    16 dup(?)    ;reserve 16 bytes for the city
STATE     DB     2 dup(?)    ;reserve 2 bytes for the state
ZIP       DB     5 dup(?)    ;reserve 5 bytes for the zipcode

INFO      ENDS

NAME1     INFO <'Bob Smith', '123 Main Street', 'Wanda', 'OH', '44444'>
NAME2     INFO <'Steve Doe', '222 Moose Lane', 'Miller', 'PA', '18100'>
NAME3     INFO <'Jim Dover', '303 Main Street', 'Orender', 'CA', '90000'>
```

field-declarations

Use structure 3 times

## EXAMPLE 3–13 field initialization for a structure

```
;clear NAMES in array NAME1  
;
```

The STOS instruction copies the data from AL/AX/EAX to the destination string, pointed to by ES:DI.

```
MOV    CX, 32  
MOV    AL, 0  
MOV    DI, OFFSET NAME1.NAMES  
REP    STOSB  → MOV ES:[DI], AL
```

refer to the NAMES field  
in structure NAME1

```
;clear STREET in array NAME2  
;
```

```
MOV    CX, 32  
MOV    AL, 0  
MOV    DI, OFFSET NAME2.STREET  
REP    STOSB
```

refer to the STREET field  
in structure NAME2

```
;clear ZIP in NAME3  
;
```

```
MOV    CX, 5  
MOV    AL, 0  
MOV    DI, OFFSET NAME3.ZIP  
REP    STOSB
```

refer to the ZIP field in  
structure NAME3

## 3–2 PROGRAM MEMORY- ADDRESSING MODES

- Used with the JMP (jump) and CALL instructions.
- The destination (target) operand specifies the address of the instruction being jumped to.
- Consist of three distinct forms: **direct**, **relative**, and **indirect**
- The offset address can be
  - **an immediate value** in direct or relative program memory addressing
  - **a general-purpose register or a memory location** in indirect program memory addressing

# PROGRAM MEMORY-ADDRESSING MODES

- Two different types of jump offset:
  - **relative offset**: a signed displacement **relative to the current value of the instruction pointer (EIP)**.
  - **absolute offset**: that is an **offset from the base of the code segment**.
- For memory usage, relative jumps take less memory in the instruction code than the absolute jumps.
- For code generation, relative offset can be computed at compile time, while the absolute address needs to be computed at link time.