

RoboControl



NewRoboControl

- m_stopCruisingNow
- m_isCruising
- m_cruiseThread

- + NewRoboControl()
- + ~NewRoboControl()
- + IsOnTarget()
- + cruisetoBias()
- + RandomMove()
- + drivePath()
- + setSpeed()
- + getDirection()
- + getDiffAngle()
- + getSpeedP()
- + getSpeedPt()
- + getSpeedT()
- + degToRad()
- + IsOnTarget()



OpponentRobot

- + OpponentRobot()