



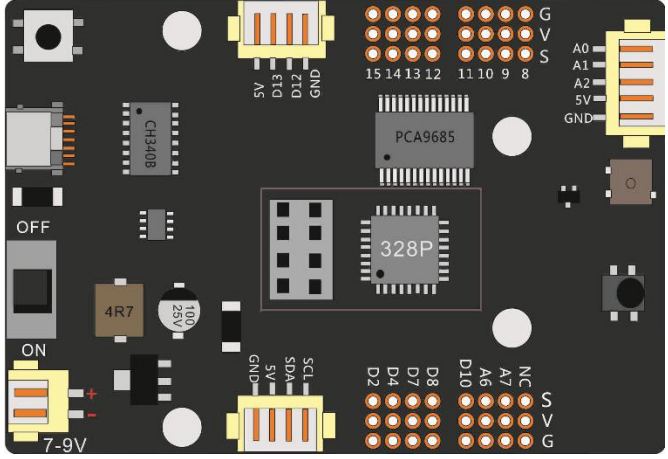
Lesson 11 Test the IR remote controller

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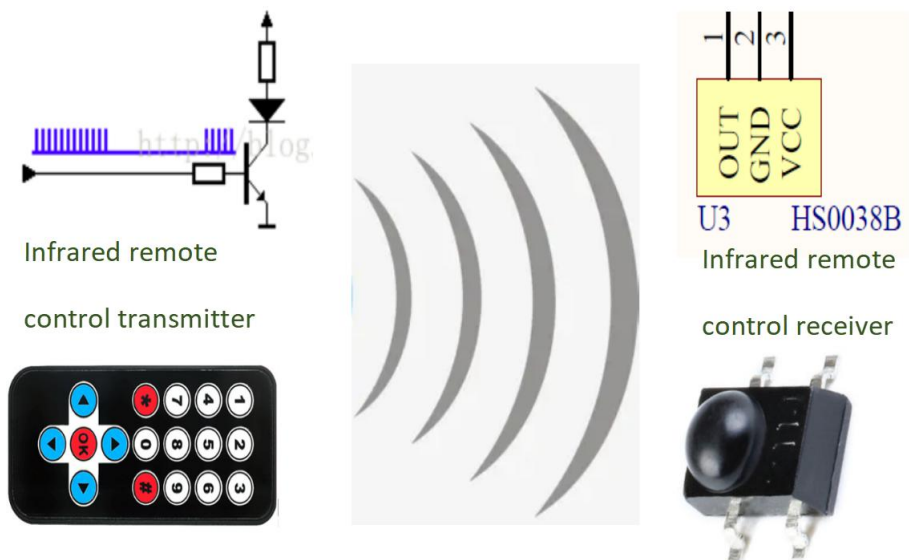
1. What do you need to prepare

Components	Quantity	Picture
USB cable	1	
Infrared remote controller	1	

Control board	1	
---------------	---	--

2. Principle

Infrared remote control by transmitting and receiving two components. The transmitter uses microcontroller to encode and modulate the binary signal to be sent into a series of pulse train signals, which are transmitted through the infrared transmitter tube. Infrared reception completes the reception, amplification, detection, shaping of infrared signals, and demodulation of remote coding pulse. In order to reduce interference, an integrated infrared receiver (HS0038, which receives infrared signals with a frequency of 38kHz and a period of about $26\mu s$, and adopts NEC infrared coding) is used to receive infrared signals. At the same time, HS0038 amplifies, detects and shapes the signals to obtain the coded signals of TTL level, which is then sent to the microcontroller. The MCU decoded and executed to control the related objects.

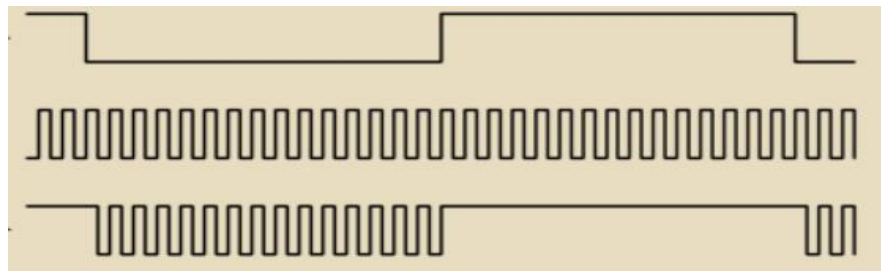


HS0038 infrared receiver, which internal integration of monitoring, amplification, filtering, demodulation and a series of circuits to process the output baseband signal. The original signal is a data "0" bit or a data "1" bit that we want to send, while the so-called 38K carrier is a square wave signal with a frequency of 38K, and the modulated signal is the final waveform that we transmit. We use the original signal to control the 38K carrier. When the signal is data "0", all the 38K carrier is sent without reservation. When the signal is data "1", no carrier signal is sent.

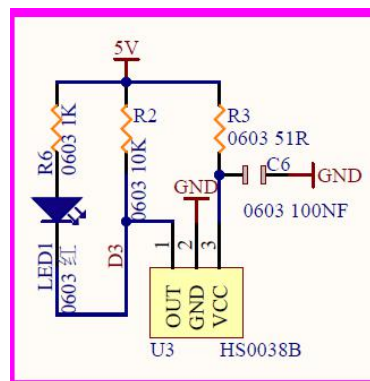
The original

32K Carrier

The modulated



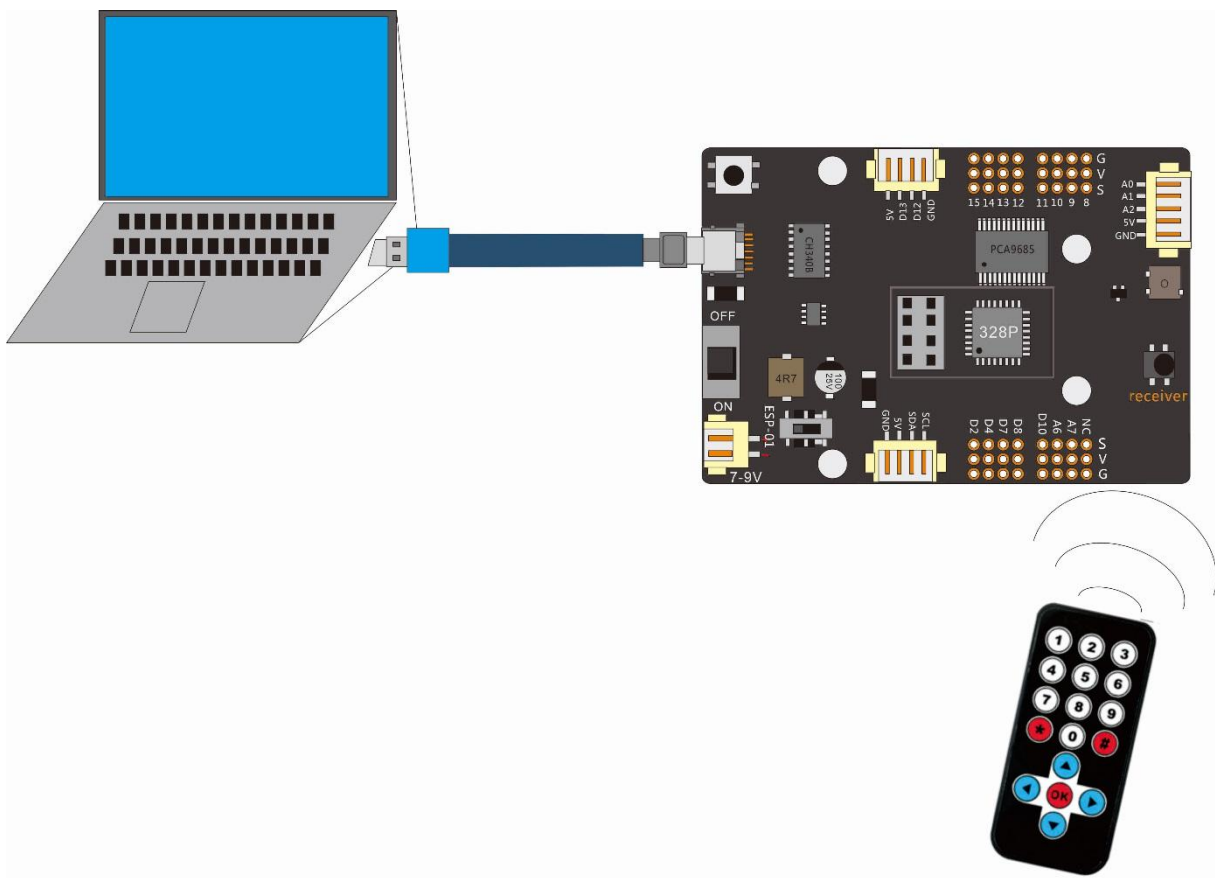
The schematic diagram:



The infrared remote control receiver HS0038B mounted on the Arduino 4WD Shield, and it occupies the D3 pin of the Atmega328p. HS0038B receives the signal from the controller, then modulates it and transmits to Atmega328p MCU by D3.

3. Wiring

Connect the control board to the computer via a USB cable, Get an infrared remote control and place it next to the control board.



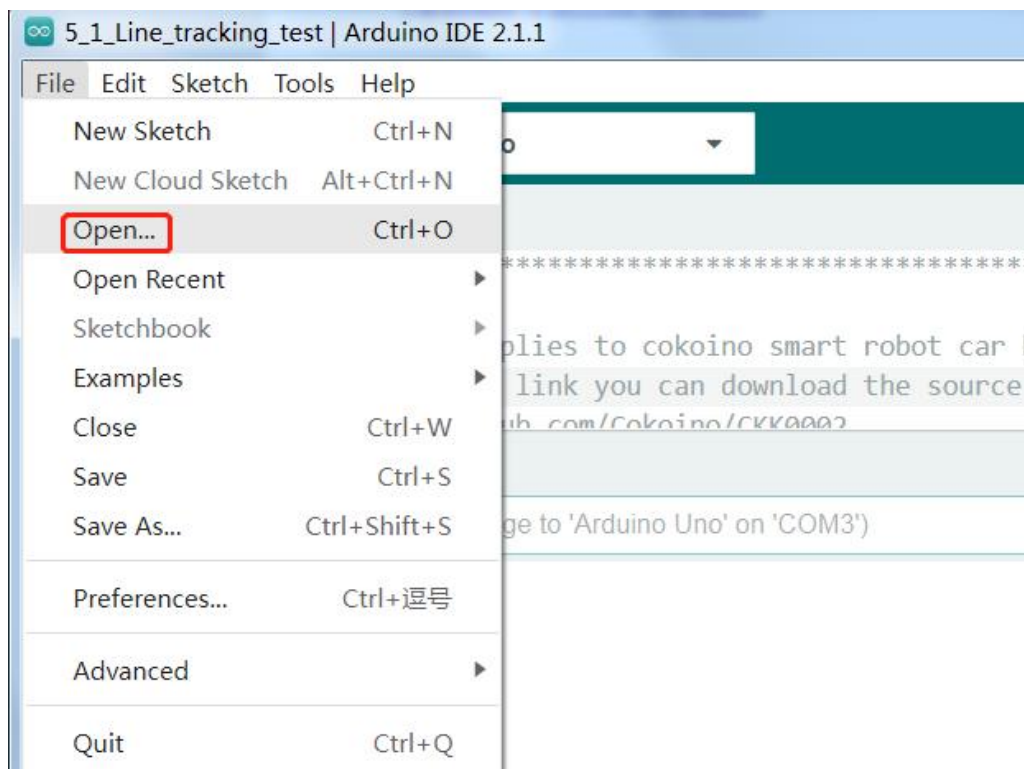
4. Upload the code and test

The code used in this lesson is placed in this folder: “<E:\CKK0014-main\Tutorial\sketches>”

4.1 Double-click the Arduino IDE shortcut on the desktop to open it



4.2 Click "File" --- "open"

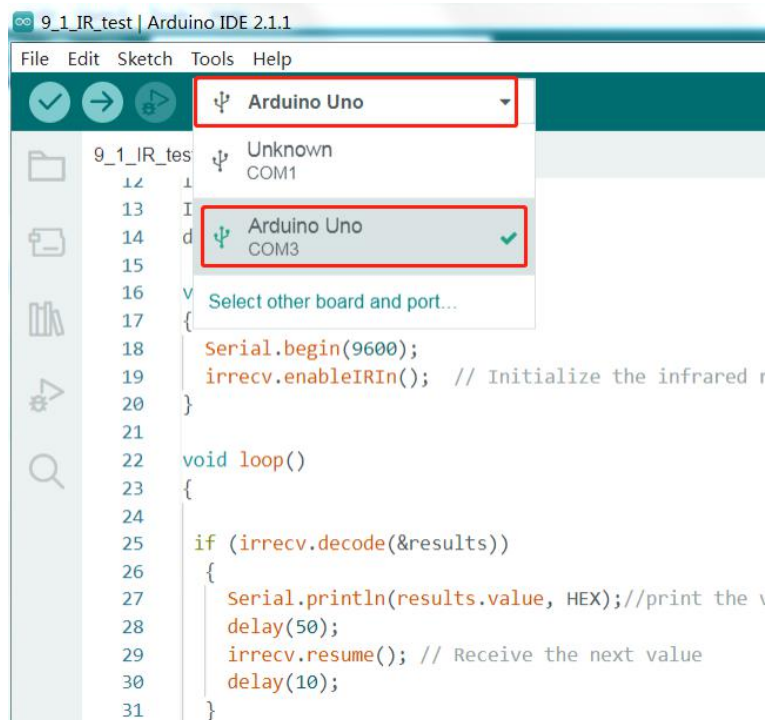


4.3 Select the code in the folder named [9_1_IR_test](#):

E:\CKK0014-main\Tutorial\sketches\9_1_IR_test

Then click "open"

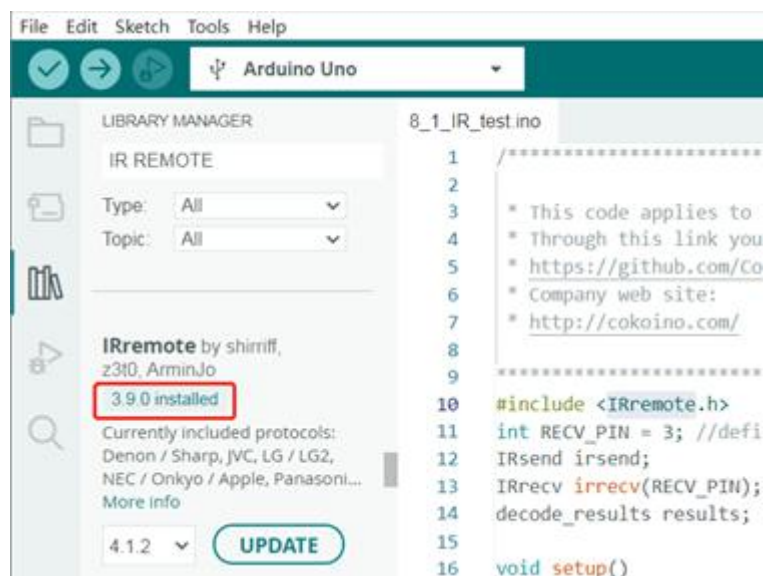
4.4 Select the board "Arduino UNO" and Port "COM3" (COM port is commonly known as an input output port for a device normally PC which enables communication between Arduino and PC. You can check your arduino com number in device manager, the com port of our arduino board is recognized as COM3 in this tutorial)




4.5 Install IRremote library


For the installation method, please refer to the method of installing the library Servo.h in Lesson 4

Note that to run the sample code of this lesson, you need to install the Irremote library version below 4.0.0, and the library version 4.0.0 and above does not support this sample code. In this lesson, we installed the “3.9.0 Irremote”



4.6 Click compile button , successfully compiled the code will display “Done compiling”

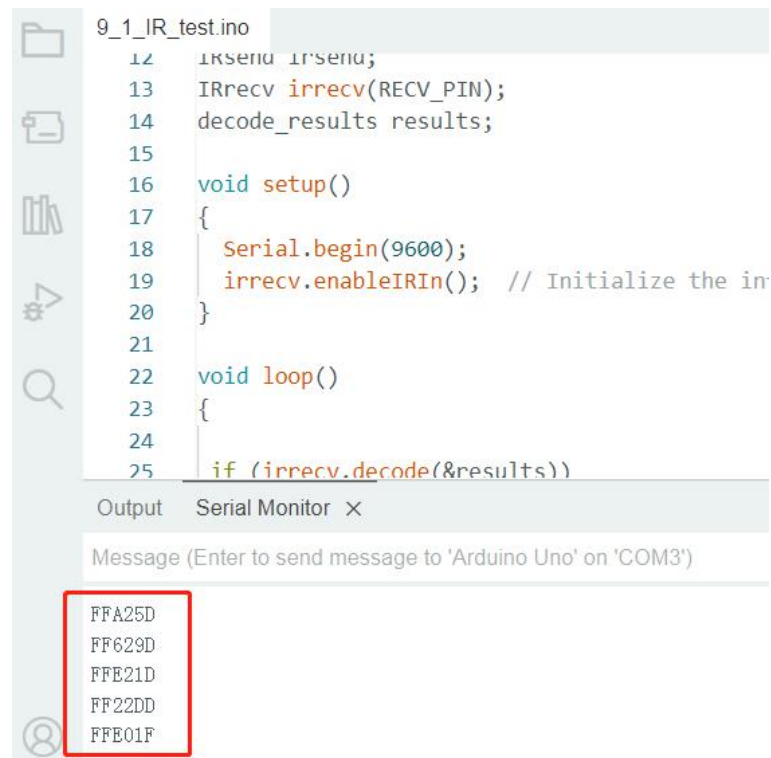
4.7 Before uploading the code, turn the ESP-01 switch on the control board to the side away from the "ESP-01" silk screen.

4.8 Click upload button , successfully uploading the code will display “Done uploading”. When code is uploaded successfully, the program starts to run.

4.9 After the code is successfully uploaded, open the Serial Monitor, select the baud rate as 9600, then pick up the infrared remote control and press the remote control button against the control board. You can see the value of the button on the remote control in the Serial Monitor window, which is the button signal received by the infrared receiver and printed out in HEX format. Pressing different buttons will print out different values in the Serial Monitor window.

Number Labels of Infrared Remote	The value received by the infrared receiver	Number Labels of Infrared Remote	The value received by the infrared receiver
0	FF9867	9	FF906F
1	FFA25D	*	FF6897
2	FF629D	#	FFB04F
3	FFE21D	↑	FF18E7
4	FF22DD	←	FF10EF
5	FF02FD	→	FF5AA5
6	FFC23D	↓	FF4AB5
7	FFE01F	Ok	FF38C7
8	FFA857		





The screenshot shows the Arduino IDE interface. The top pane displays the code for `9_1_IR_test.ino`. The code includes headers for `IRremote`, defines `RECV_PIN` as 3, and declares `IRsend irsend`, `IRrecv irrecv`, and `decode_results results`. The `setup()` function initializes the serial port at 9600 baud and enables the IR receiver. The `loop()` function contains a conditional statement to decode the received IR signal. The bottom pane shows the Serial Monitor with a list of received IR codes: FFA25D, FF629D, FFE21D, FF22DD, and FFE01F. The list is enclosed in a red box.

```
9_1_IR_test.ino
12  IRsend irsend;
13  IRrecv irrecv(RECV_PIN);
14  decode_results results;
15
16  void setup()
17  {
18      Serial.begin(9600);
19      irrecv.enableIRIn(); // Initialize the infrared receiver
20  }
21
22  void loop()
23  {
24
25      if (irrecv.decode(&results))
```

Output Serial Monitor X

Message (Enter to send message to 'Arduino Uno' on 'COM3')

FFA25D
FF629D
FFE21D
FF22DD
FFE01F

5. Code

9_1_IR_test.ino:

```
#include <IRremote.h>
int RECV_PIN = 3; //define input pin
IRsend irsend;
IRrecv irrecv(RECV_PIN);
decode_results results;

void setup()
{
    Serial.begin(9600);
    irrecv.enableIRIn(); // Initialize the infrared receiver
}

void loop()
{
```



```
if (irrecv.decode(&results))
{
  Serial.println(results.value, HEX); //print the value in HEX format
  delay(50);
  irrecv.resume(); // Receive the next value
  delay(10);
}
}
```

6. Any questions and suggestions are welcome

Thank you for reading this document!

If you find any errors and omissions in the tutorial, or if you have any suggestions and questions, please feel free to contact us at:

cokoino@outlook.com

We will do our best to make changes and publish revisions as soon as possible.

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