

**Tutorial save:**

You will get a zip pack called "CKK0017-main" after downloading, unzip it to get the "CKK0017-main" folder. For the convenience of using and querying tutorials in the future, it is recommended to put the downloaded files in a local folder on the computer. For example, we put the folder in E:\CKK0017-main

**If you don't want to use Arduino IDE, just want to assemble the robotic arm and control it. Please refer to the folder 'Run the robotic arm without Arduino IDE' for detailed manuals.**

**If you want to learn more about Arduino, write code based on Arduino IDE, and understand the principles of servos and joysticks, please refer to the folder "Run the robotic arm with Arduino IDE" for detailed courses.**

**Arduino Libraries:**

We have packaged all the Arduino Libraries needed for the code and placed them in the path :[CKK0017-main \ Tutorial \ Libraries](#).

You can unzip these Arduino Libraries, copy and paste them into the Libraries folder in the Arduino ide installation path on your computer. For example, when using the code for this product on my computer, I copy and paste them in [C: \ Users \ Administrator \ Documents \ Arduino \ libraries](#)

Or you can refer to Lesson 3 to download and install the required libraries from the Arduino IDE interface before compiling the code.