



MATH 3333 PRACTICE PROBLEM SET 2

Problem 1. Compute the cofactor matrix and the determinant of the matrix given below. If it is invertible, write down its inverse.

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 3 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix}$$

Solution:

$$C_{11}(A) = (-1)^2 \begin{vmatrix} 1 & 0 \\ -1 & 1 \end{vmatrix} = 1$$

$$C_{12}(A) = (-1)^3 \begin{vmatrix} 3 & 0 \\ 0 & 1 \end{vmatrix} = -3$$

$$C_{13}(A) = (-1)^4 \begin{vmatrix} 3 & 1 \\ 0 & -1 \end{vmatrix} = -3$$

$$C_{21}(A) = (-1)^3 \begin{vmatrix} -1 & 2 \\ -1 & 1 \end{vmatrix} = -1$$

$$C_{22}(A) = (-1)^4 \begin{vmatrix} 1 & 2 \\ 0 & 1 \end{vmatrix} = 1$$

$$C_{23}(A) = (-1)^5 \begin{vmatrix} 1 & -1 \\ 0 & -1 \end{vmatrix} = 1$$

$$C_{31}(A) = (-1)^4 \begin{vmatrix} -1 & 2 \\ 1 & 0 \end{vmatrix} = -2$$

$$C_{32}(A) = (-1)^5 \begin{vmatrix} 1 & 2 \\ 3 & 0 \end{vmatrix} = 6$$

$$C_{33}(A) = (-1)^6 \begin{vmatrix} 1 & -1 \\ 3 & 1 \end{vmatrix} = 4$$

By taking the cofactor expansion along row 1, we have $|A| = 1 \times 1 + (-1) \times (-3) + 2 \times (-3) = -2$

$$\text{cof}(A) = \begin{bmatrix} 1 & -3 & -3 \\ -1 & 1 & 1 \\ -2 & 6 & 4 \end{bmatrix}$$

$$A^{-1} = \frac{1}{|A|}(\text{cof}(A))^T = \frac{1}{-2} \begin{bmatrix} 1 & -1 & -2 \\ -3 & 1 & 6 \\ -3 & 1 & 4 \end{bmatrix}$$

Problem 2. Determine whether following statements are true or false. If true, write down a short proof. If false, provide a counterexample.

- (a) $\det(A + B) = \det(A) + \det(B)$

Solution: False. Take $A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$ and $B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$. Then $|A| = 0 = |B|$ but $A + B = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ has the determinant -1 .

- (b) If $\det(A) = 0$ then A has two identical rows.

Solution: False. A counterexample would be $\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$

- (c) If R is the RRE form of A , then $\det(a) = \det(R)$

Solution: False. Some of the row operations can change the determinant. $A = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix}$ has the determinant 2. But its RRE form $\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$ has the determinant 1.

- (d) If A is 2×2 then $\det(7A) = 49\det(A)$

Solution: True. As we saw in the class, for an $n \times n$ matrix A and a scalar k , $|kA| = k^n|A|$.

- (e) If A has a row of all zeroes then so does $\text{cof}(A)$.

Solution: True. Let's say R_i of A has only zeroes. Then any sub matrix obtained by deleting any column and a row different from R_i will have a row of all zeroes, making the determinant of that sub matrix 0. Hence the cofactors along that whole row will be zero.

- (f) Recall that the transpose of $\text{cof}(A)$ is called as the adjoint of A and denoted by $\text{adj}(A)$. If $\text{adj}(A) = A^{-1}$ then $\det(A) = 1$ **Solution:** True. We showed in the class, $A.\text{adj}(A) = |A|I$. If $A^{-1} = \text{adj}(A)$ then $A.\text{adj}(A) = I$.

$$\text{Hence we have } |A|I = I \Rightarrow \begin{bmatrix} |A| & 0 & \dots & 0 \\ 0 & |A| & 0 \dots & 0 \\ \dots & \dots & \dots & 0 \\ 0 & 0 & \dots & |A| \end{bmatrix} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & 0 \dots & 0 \\ \dots & \dots & \dots & 0 \\ 0 & 0 & \dots & 1 \end{bmatrix} \Rightarrow |A| = 1$$

Problem 3. Suppose that the first row of a matrix A is $\begin{bmatrix} 1 & -1 & 2 \end{bmatrix}$ and the first row of the cofactor matrix of A is $\begin{bmatrix} 3 & 1 & 2 \end{bmatrix}$

- (a) Determine whether A is invertible.

Solution: $|A| = a_{11}C_{11}(A) + a_{12}C_{12}(A) + a_{13}C_{13}(A) = 1 \times 3 + (-1) \times 1 + 2 \times 2 = 6$. So A is invertible as $|A| \neq 0$

- (b) Why cannot the second row the cofactor matrix be $\begin{bmatrix} 0 & -1 & 2 \end{bmatrix}$? **Solution:** We saw in the class that $a_{i1}C_{j1}(A) + a_{i2}C_{j2}(A) + \dots + a_{in}C_{jn}(A)$ is equal to $|A|$ if $i = j$ and to 0 if $i \neq j$.

But if the second row is as given above, then

$$a_{21}C_{11}(A) + a_{22}C_{12}(A) + a_{23}C_{13}(A) = 0 - 1 + 4 = 3 \neq 0 \text{ which is not possible.}$$

Problem 4. Let S and T be two linear transformations as described below.

$T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is the projection onto yz -plane. That is for any vector U in \mathbb{R}^3 , $T(U)$ is the projection of U onto yz -plane.

$S : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ is the function that scales vectors by 5. That is for any vector U in \mathbb{R}^3 , $S(U) = 5U$.

- (1) Write down a matrix A such that T is the transformation induced by A .

Solution: Let $U = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$. Then $T(U) = \begin{bmatrix} 0 \\ x_2 \\ x_3 \end{bmatrix}$

$$\text{Hence } A = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- (2) Find eigenvalues and associated eigenvectors of A . Can you geometrically interpret your answer?

$$\text{Solution: } A - \lambda I = \begin{bmatrix} -\lambda & 0 & 0 \\ 0 & 1 - \lambda & 0 \\ 0 & 0 & 1 - \lambda \end{bmatrix}$$

Then $\det(A - \lambda I) = -\lambda(1 - \lambda)^2 = 0$. Then $\lambda = 0, 1$ are the eigenvalues of A

If $\lambda = 0$

$$(A - \lambda I)X = 0 \Rightarrow AX = 0$$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right]$$

By $R_2 \leftrightarrow R_1$ and then $R_3 \leftrightarrow R_2$ we obtain the RRE form

$$\left[\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Take $x_1 = s$. Then $x_2 = x_3 = 0$. So eigenvectors associated with $\lambda = 0$ are the vectors of the form $X = \begin{bmatrix} s \\ 0 \\ 0 \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

If $\lambda = 1$

$$(A - \lambda I)X = 0 \Rightarrow (A - I)X = 0$$

The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

By $R_1 \rightarrow -R_1$ we obtain the RRE form

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Take $x_2 = s$ and $x_3 = t$. Then $x_1 = 0$. So eigenvectors associated with $\lambda = 1$ are the vectors of the form $X = \begin{bmatrix} 0 \\ s \\ t \end{bmatrix} = s \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

Most vectors change the direction when projected onto yz -plane. What are the vectors that don't change the direction or change the direction by 180 degrees ?

- If a vector U is on yz -plane, then its projection onto yz -plane is itself ; $AU = U$. So the vectors on yz -plane are eigenvectors of A associated to $\lambda = 1$. The answer we

got for $\lambda = 1$ was $\begin{bmatrix} 0 \\ s \\ t \end{bmatrix}$ and these are precisely all the vectors on yz -plane.

- If a vector U lies on the x -axis, its projection onto yz -plane is $\begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$; $AU = 0 = 0U$.

So the vectors on x -axis are eigenvectors of A associated to $\lambda = 0$. The answer we

got for $\lambda = 0$ was $s \begin{bmatrix} s \\ 0 \\ 0 \end{bmatrix}$ and these are precisely all the vectors that lie on x -axis.

- (3) Write down a matrix B such that S is the transformation induced by B .

Solution: Let $U = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$. Then $S(U) = \begin{bmatrix} 5x_1 \\ 5x_2 \\ 5x_3 \end{bmatrix}$

Hence $B = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

- (4) Find eigenvalues and associated eigenvectors of B . Can you geometrically interpret your answer ?

Solution: $A - \lambda I = \begin{bmatrix} 5 - \lambda & 0 & 0 \\ 0 & 5 - \lambda & 0 \\ 0 & 0 & 5 - \lambda \end{bmatrix}$

Then $\det(A - \lambda I) = \lambda(5 - \lambda)^3 = 0$. Then $\lambda = 5$ is the only eigenvalue of B

If $\lambda = 5$

$(A - 5I)X = 0 \Rightarrow AX = 0$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

So all three variables are free variables. Take $x_1 = r$, $x_2 = s$ and $x_3 = t$. So eigenvectors associated with $\lambda = 5$ are the vectors of the form $X = \begin{bmatrix} r \\ s \\ t \end{bmatrix} = r \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

When multiplying by 5 (or by any scalar), no vector changes its direction. So any non-zero vector in \mathbb{R}^3 is an eigenvector of A and since $AU = 5U$, all the vectors in \mathbb{R}^3 are associated with the eigenvalue 5. Note that the answer we got for $\lambda = 5$ was $\begin{bmatrix} r \\ s \\ t \end{bmatrix}$ describes all the vectors in \mathbb{R}^3 .

- (5) Find a matrix C such that $T \circ S$ is the transformation induced by C .

Solution: $C = AB = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$

- (6) Find the eigenvalues and associated eigenvectors of C . Can you geometrically interpret your answer ?

Solution: $C - \lambda I = \begin{bmatrix} -\lambda & 0 & 0 \\ 0 & 5 - \lambda & 0 \\ 0 & 0 & 5 - \lambda \end{bmatrix}$

Then $\det(A - \lambda I) = -\lambda(5 - \lambda)^2 = 0$. Then $\lambda = 0, 5$ are the eigenvalues of A

If $\lambda = 0$

$$(C - \lambda I)X = 0 \Rightarrow CX = 0$$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 0 & 0 & 0 \\ 0 & 5 & 0 & 0 \\ 0 & 0 & 5 & 0 \end{array} \right]$$

First apply the row operation $R_2 \leftrightarrow R_1$ and then $R_3 \leftrightarrow R_2$ and finally divide both first and second rows by 5 to obtain the RRE form

$$\left[\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Take $x_1 = s$. Then $x_2 = x_3 = 0$. So eigenvectors associated with $\lambda = 0$ are the vectors of

$$\text{the form } X = \begin{bmatrix} s \\ 0 \\ 0 \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

If $\lambda = 5$

$$(A - \lambda I)X = 0 \Rightarrow (A - 5I)X = 0$$

The augmented matrix is

$$\left[\begin{array}{ccc|c} -5 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

By $R_1 \rightarrow -1/5R_1$ we obtain the RRE form

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Take $x_2 = s$ and $x_3 = t$. Then $x_1 = 0$. So eigenvectors associated with $\lambda = 5$ are the

$$\text{vectors of the form } X = \begin{bmatrix} 0 \\ s \\ t \end{bmatrix} = s \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

We know no non zero vector changes direction when multiplied by B . Then the vectors that don't change the direction when multiplied by AB are same as the vectors that don't change the direction when multiplied by A . We can confirm this by observing that the eigenvectors of AB we computed in this part are same as the eigenvectors of A we computed in part (2).

Problem 5. Let A, B and C be 4×4 matrices such that $\det(A) = -2, \det(B) = 7$ and $\det(C) = 5$. Compute the determinants of following matrices.

• $BC^2(A^{-1})^2(C^2)^T$

Solution: $\det(BC^2(A^{-1})^2(C^2)^T) = \det(B)(\det(C))^2 \left(\frac{1}{\det(A)}\right)^2 (\det(C))^2$
 $= 7 \times 5^2 \times \left(\frac{1}{-2}\right)^2 \times 5^2 = 1093.75$

• $E_1 B^2 (A^T)^3 E_2$ where E_1 and E_2 are the elementary matrices obtained by performing the row operations $R_2 \rightarrow R_2 + 2R_1$ and $R_3 \rightarrow -3R_3$ on I respectively.

Solution: The row operation $R_2 \rightarrow R_2 + 2R_1$ does not change the determinant. Hence $\det(E_1) = \det(I) = 1$. The row operation $R_3 \rightarrow -3R_3$ multiplies the determinant by a factor of -3 . Hence, $\det(E_2) = -3\det(I) = -3$.

$$\det(E_1 B^2 (A^T)^3 E_2) = \det(E_1)(\det(B))^2(\det(A))^3 \det(E_2) = 1 \times 7^2 \times (-2)^3 \times (-3) = 1176$$

Problem 6. Let $A = \begin{bmatrix} x & -2 & x^2 \\ y & -2 & y^2 \\ 1 & 2 & 3 \end{bmatrix}$ and $B = \begin{bmatrix} -x & 2 & -x^2 \\ 4y & -8 & 4y^2 \\ x - y + 1 & 2 & x^2 - y^2 + 3 \end{bmatrix}$.

If $|A| = 6$ compute $|B|$.

Solution: We need to send A through a sequence of row operations till we obtain B and keep track on the changes in the determinant under each row operation.

We start with $R_3 \rightarrow R_3 + R_1$ on A .

$$\begin{bmatrix} x & -2 & x^2 \\ y & -2 & y^2 \\ x+1 & -2+2 & x^2+3 \end{bmatrix}$$

This row operation does not change the determinant. So the determinant of the above matrix is same as the determinant of A which is 6.

Then $R_3 \rightarrow R_3 - R_2$ yields

$$\begin{bmatrix} x & -2 & x^2 \\ y & -2 & y^2 \\ x-y+1 & (-2+2)+2 & x^2-y^2+3 \end{bmatrix}$$

This row operation also does not change the determinant. So the determinant of the above matrix is still 6.

Then $R_2 \rightarrow 4R_2$ yields

$$\begin{bmatrix} x & -2 & x^2 \\ 4y & -8 & 4y^2 \\ x-y+1 & 2 & x^2-y^2+3 \end{bmatrix}$$

This row operation multiply the determinant by 4. So the determinant of the above matrix is still 24.

Then $R_1 \rightarrow -R_1$ yields

$$B = \begin{bmatrix} -x & 2 & -x^2 \\ 4y & -8 & 4y^2 \\ x - y + 1 & 2 & x^2 - y^2 + 3 \end{bmatrix}$$

This row operation multiply the determinant by -1 . So the determinant of the above matrix is still -24 and since this matrix is B we have $\det(B) = -24$.

Problem 7. Explain what can be said about the determinant of A in each of the following cases. A is an $n \times n$ matrix.

(1) $A^2 = A$

Solution: $\det(A^2) = \det(A) \Rightarrow \det(A).\det(A) = \det(A) \Rightarrow \det(A)(\det(A) - 1) = 0$. Hence $\det(A) = 0$ or 1

(2) A is symmetric

Solution: $\det(A^T) = \det(A) \Rightarrow \det(A) = \det(A)$. This does not tell us anything about $\det(A)$.

(3) $A = PA$ where P is an invertible matrix.

Solution: $\det(P)\det(A) = \det(P) \Rightarrow \det(A)(1 - \det(P)) = 0$.

If $\det(P) \neq 1$ then $\det(A) = 0$. If $\det(P) = 1$ we cannot say anything about $\det(A)$.

(4) $A^2 = PA$ where P is an invertible matrix and $|P| = 4$

Solution: $(\det(A))^2 = \det(P)\det(A) = 4\det(A) \Rightarrow \det(A)(\det(A) - 4) = 0 \Rightarrow \det(A) = 0$ or 4 .

(5) $A^2 + I = 0$ and n is even

Solution: $A^2 = -I \Rightarrow (\det(A))^2 = (-1)^n \det(I) = (-1)^n$. If n is even then $(-1)^n$ is 1 . So. $(\det(A))^2 = 1 \Rightarrow \det(A) = 1$ or -1 .

(6) $A^2 + I = 0$ and n is odd

Solution: If n is odd then $(-1)^n$ is -1 . So. $(\det(A))^2 = -1$ which is not possible. So if n is odd, there cannot be an $n \times n$ matrix A such that $A^2 + I = 0$.

Problem 8. Compute the determinant of the following matrices in terms of x .

$$(1) \begin{bmatrix} 1 & x & x^2 & x^3 \\ x & x^2 & x^3 & 1 \\ x^2 & x^3 & 1 & x \\ x^3 & 1 & x & x^2 \end{bmatrix}$$

Solution:

Let's call the matrix given in this problem as A . We perform the following operations on A
 $R_2 \rightarrow R_2 - xR_1$, $R_3 \rightarrow R_3 - x^2R_1$ and $R_4 \rightarrow R_4 - x^3R_1$
 and obtain the following matrix which we will call as B .

$$B = \begin{bmatrix} 1 & x & x^2 & x^3 \\ 0 & 0 & 0 & 1 - x^4 \\ 0 & 0 & 1 - x^4 & x - x^5 \\ 0 & 1 - x^4 & x - x^5 & x^2 - x^6 \end{bmatrix}$$

The three row operations we applied do not change the determinant.

Hence $\det(A) = \det(B) = b_{11}c_{11}(B)$

$$c_{11}(B) = (-1)^{1+1} \begin{vmatrix} 0 & 0 & 1 - x^4 \\ 0 & 1 - x^4 & x - x^5 \\ 1 - x^4 & x - x^5 & x^2 - x^6 \end{vmatrix}$$

Note that each row of the 3×3 matrix above has a common factor $(1 - x^4)$. By factoring it out from each row we have the following.

$$c_{11}(B) = (1 - x^4)^3 \begin{vmatrix} 0 & 0 & 1 \\ 0 & 1 & x \\ 1 & x & x^2 \end{vmatrix} = (1 - x^4)^3 \left(1 \cdot (0 \times x - 1 \times 1) \right) = (1 - x^4)^3 (-1) = -(1 - x^4)^3$$

So, $\det(A) = \det(B) = b_{11}(-1)(1 - x^4)^3 = -(1 - x^4)^3$.

$$(2) \begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & x & x \\ 1 & x & 0 & x \\ 1 & x & x & 0 \end{bmatrix}$$

Solution:

Let's call the matrix given in this problem as A . We perform following operations on the matrix

$R_3 \rightarrow R_3 - R_2$, $R_4 \rightarrow R_4 - R_2$ and obtain the following matrix which we will call as B .

$$\begin{bmatrix} 0 & 1 & 1 & 1 \\ 1 & 0 & x & x \\ 0 & x & -x & 0 \\ 0 & x & 0 & -x \end{bmatrix}$$

The two row operations we applied do not change the determinant. Hence $\det(A) = \det(B) = b_{21}c_{21}(B)$

$$c_{21}(B) = (-1)^{2+1} \begin{vmatrix} 1 & 1 & 1 \\ x & -x & 0 \\ x & 0 & -x \end{vmatrix}$$

To find the determinant of the matrix $P = \begin{bmatrix} 1 & 1 & 1 \\ x & -x & 0 \\ x & 0 & -x \end{bmatrix}$ we perform $R_2 \rightarrow R_2 - xR_1$ and $R_3 \rightarrow R_3 - xR_1$ and obtain

$$Q = \begin{bmatrix} 1 & 1 & 1 \\ 0 & -2x & -x \\ 0 & -x & -2x \end{bmatrix}$$

The two row operations we applied do not change the determinant.

Hence $\det(P) = \det(Q) = 1((-2x)(-2x) - (-x)(-x)) = 3x^2$

So, $\det(A) = \det(B) = b_{21}c_{21}(B) = 1 \times (-1)^3 \times 3x^2 = 3x^2 = -3x^2$

Problem 9. For each of the following matrix, find its eigenvalues and eigenvectors associated with those values.

(1) $\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ **Solution:** The characteristic equation $|A - \lambda I| = 0$ can be simplified into

$$-(\lambda + 1)^2(\lambda - 2) = 0. \text{ So, the eigenvalues are } -1 \text{ and } 2.$$

When $\lambda = -1$, corresponding eigenvectors are given by $s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$

When $\lambda = 2$, corresponding eigenvectors are given by $s \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

(2) $\begin{bmatrix} 6 & 3 & -8 \\ 0 & -2 & 0 \\ 1 & 0 & -3 \end{bmatrix}$

Solution: The characteristic equation $|A - \lambda I| = 0$ can be simplified into $-(\lambda + 2)^2(\lambda - 5) = 0$. So, the eigenvalues are -1 and 2 .

When $\lambda = -2$, corresponding eigenvectors are given by $s \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$

When $\lambda = 5$, corresponding eigenvectors are given by $s \begin{bmatrix} 8 \\ 0 \\ 1 \end{bmatrix}$

Problem 10. The matrix A is given by

$$\begin{bmatrix} 0 & 3 & 6 \\ 0 & 2 & 4 \\ 0 & 1 & 2 \end{bmatrix}$$

(a) Find all eigenvalues of A .

Solution: $|A - \lambda I| = -\lambda \left((2 - \lambda)(2 - \lambda) - 4 \right) = -\lambda(4 - 4\lambda + \lambda^2 - 4)$
 $= -\lambda(-4\lambda + \lambda^2) = -\lambda^2(\lambda - 4) = 0 \Rightarrow \lambda = 0, 4$

(b) For each eigenvalue λ of A , find a basis for $Null(A - \lambda I)$. **Solution:** Take $\lambda = 0$. We need to find the solutions to the homogeneous system, $(A - 0I)X = 0 \Rightarrow AX = 0$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 3 & 6 & 0 \\ 0 & 2 & 4 & 0 \\ 0 & 1 & 2 & 0 \end{array} \right]$$

and its RRE form is

$$\left[\begin{array}{ccc|c} 0 & 1 & 2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The general solution is given by $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} s \\ -2t \\ t \end{bmatrix} = s \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix}$

Therefore, a basis for $\text{Null}(A - \lambda I)$ when $\lambda = 0$ is $\left\{ \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ -2 \\ 1 \end{bmatrix} \right\}$

Take $\lambda = 4$. We need to find the solutions to the homogeneous system, $(A - 4I)X = 0$

The augmented matrix is

$$\left[\begin{array}{ccc|c} -4 & 3 & 6 & 0 \\ 0 & -2 & 4 & 0 \\ 0 & 1 & -2 & 0 \end{array} \right]$$

and its RRE form is

$$\left[\begin{array}{ccc|c} 1 & 0 & -3 & 0 \\ 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The general solution is given by $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3s \\ 2s \\ s \end{bmatrix} = s \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix}$

Therefore, a basis for $\text{Null}(A - \lambda I)$ when $\lambda = 4$ is $\left\{ \begin{bmatrix} 3 \\ 2 \\ 1 \end{bmatrix} \right\}$

- (c) Determine if A is diagonalizable. If it is, find an invertible matrix P and a diagonal matrix D such that $A = PDP^{-1}$. **Solution:** A is diagonalizable because for each eigenvalue λ of A , we have the following : If λ is repeated k times in the characteristic equation then the linear system $(A - \lambda I)X = 0$ has k basic solutions.

We can take $D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 4 \end{bmatrix}$ and $P = \begin{bmatrix} 1 & 0 & 3 \\ 0 & -2 & 2 \\ 0 & 1 & 1 \end{bmatrix}$

Problem 11. The matrix A is given by

$$\begin{bmatrix} 4 & 2 & 2 \\ 2 & 1 & 1 \\ -8 & -4 & -4 \end{bmatrix}$$

Show that A is diagonalizable and compute A^{2024} .

Solution: The characteristic polynomial can be simplified in to $-\lambda^2(\lambda - 1) = 0 \Rightarrow \lambda = 0, 1$

Take $\lambda = 0$. We need to find the solutions to the homogeneous system , $(A - 0I)X = 0 \Rightarrow AX = 0$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 4 & 2 & 2 & 0 \\ 2 & 1 & 1 & 0 \\ -8 & -4 & -4 & 0 \end{array} \right]$$

and its RRE form is

$$\left[\begin{array}{ccc|c} 1 & 1/2 & 1/2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The general solution is given by $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1/2s - 1/2t \\ s \\ t \end{bmatrix} = s \begin{bmatrix} -1/2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} -1/2 \\ 0 \\ 1 \end{bmatrix}$

$$= s \begin{bmatrix} 1 \\ -2 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}$$

Take $\lambda = 1$. We need to find the solutions to the homogeneous system , $(A - I)X = 0$

The augmented matrix is

$$\left[\begin{array}{ccc|c} 3 & 2 & 2 & 0 \\ 2 & 0 & 1 & 0 \\ -8 & -4 & -5 & 0 \end{array} \right]$$

and its RRE form is

$$\left[\begin{array}{ccc|c} 1 & 0 & 1/2 & 0 \\ 0 & 1 & 1/4 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The general solution is given by $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -1/2s \\ -1/4s \\ s \end{bmatrix} = s \begin{bmatrix} -1/2 \\ -1/4 \\ 1 \end{bmatrix} = s \begin{bmatrix} 2 \\ 1 \\ -4 \end{bmatrix}$

So, A is diagonalizable (because it satisfies the same condition mentioned in the problem 10(c).)

We can take $D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ and $P = \begin{bmatrix} 1 & 1 & 2 \\ -2 & 0 & 1 \\ 0 & -2 & -4 \end{bmatrix}$

For P and D as above, we have $A = PDP^{-1}$.

Multiplying this equation with itself, we have $A.A = PDP^{-1}PDP^{-1} \Rightarrow A^2 = PD^2P^{-1}$.

By doing this again, we can obtain $A^3 = PD^3P^{-1}$

By continuing this process we can obtain $A^{2024} = PD^{2024}P^{-1}$

D is a diagonal matrix. So, $D^{2024} = \begin{bmatrix} 0^{2024} & 0 & 0 \\ 0 & 0^{2024} & 0 \\ 0 & 0 & 1^{2024} \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} = D$

Hence $A^{2024} = PD^{2024}P^{-1} = PDP^{-1} = A = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 1 & 1 \\ -8 & -4 & -4 \end{bmatrix}$