Chessboard Image to Position Notation Using Logistic Regression and Cross Validation

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Abstract

When introducing their reinforcement learning algorithm AlphaZero in 2018, Silver et al remarked that "The game of chess is the longest-studied domain in the history of artificial intelligence...the study of computer chess is as old as computer science itself". Indeed, chess is a familiar field of exploration with many subdomains in which to explore computational concepts. Our team created a model which can receive an input of an image of a computer chessboard of variable color, size, and piece style, and generating, as output, a file in Forsyth-Edwards Notation (FEN). This notation assigns integers based on the number of empty board squares, and characters based on chess pieces. Characters appear in upper or lower case depending on which side of the board they begin, or in traditional chess, what color piece they are.

Chess is played on a square board with 64 spaces on it of alternating light and dark squares. In a full chess set, there are 32 pieces, 16 white and 16 black, with 6 distinct piece types: pawn, knight, bishop, rook, queen, and king. Piece design differs from set to set, but in nearly every set, these elements are consistent.

The model learns by training on individual board squares extracted from a dataset of digital chess boards. Figure 1 shows a row by row example of FEN notation on a digital chess board. The first row is a rook (r) and a king (k), separated by 6 empty spaces.

Data

The dataset used in the present work was created by Pavel Koryakin and was posted to Kaggle under a CC0 Public Domain license. The data set consists of 100,000 randomly generated chess boards of 5-15 pieces, with a training set of 80,000 images of chess boards and a test set of 20,000 images of chess boards. However, these boards are not all in the same exact format. Many vary in color and texture, with wide stylistic differences between piece types. See Figures 2 and 3.

The images were compressed to size 80 x 80 pixels in order to speed up load and processing times. As a reference, Figure 4 shows the compressed version of the original image in Figure 5. Note that these are not real game positions, as the purpose of this analysis is not related to gameplay or strategy, but is exclusively aimed at identifying the position of pieces upon a board.

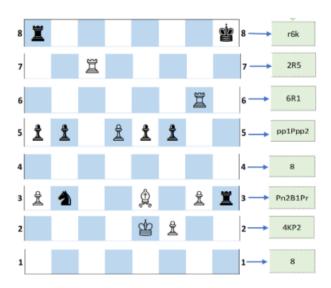


Figure 1: FEN notation on a digital chess board



Figure 2: Example of board 1.



Figure 3: Example of board 2.

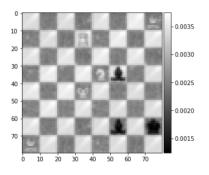


Figure 4: Compressed image.



Figure 5: Original image.

Parameters

```
IMAGE_LOAD_SIZE = 1000 #The amount of board files to load
DROP_BLANKS_PCT = .8 #When learning squares, drop this percent of blank squares from fitting
SAVE_CLASSIFIER = True #Saves squares classifier after fit
PIECE_LIST = 'prnbqkPRNBQK' #FEN piece codes. Case represents color.
PIECE_DICT = {} #dictionary from piece code to piece list
for ii in range(1, len(PIECE_LIST)+1):
    PIECE_DICT[PIECE_LIST[ii-1]] = ii
```

As seen above, the model contains a set of parameters that may used to tune the output on the given data set. Image_Load_Size simply lets the model know how many of the 80,000 images to load. Of course, the model performs higher with all 80,000 images (over 99.5% accuracy). However, past a certain threshold there are diminishing returns given the long load times, memory constraints and the processing power. Our team was able to produce classifiers performing above 97% accuracy trained on just 2,000 samples.

The Drop_Blanks_PCT (or drop blanks percentage) parameter, lets the user control the percentage of blank chess spaces or spaces without pieces occupying. When set to .8, the pipeline will randomly drop 20% of blank squares in the training set. By decreasing the number of blank squares the model has to learn on, more effort can be spent learning to identify pieces rather than blank squares, which are by far the most common square label. This parameter shifts the accuracy by smaller amounts than the total image parameters (multiples of 0.1% or 0.01%).

Save Classifier, if true, simply saves the generated classifier to the user's filesystem once the model has been fit. The piece list is simply a character list of all FEN abbreviations.

We achieved 99.94% accuracy in the test set and the confusion matrix:

$\Gamma 172414$	0	0	0	0	0	0	0	0	0	0	0	Γ0	
3	2888	3	2	0	0	0	0	0	0	0	0	0	
6	0	2843	1	2	2	0	0	0	0	0	0	0	
7	2	4	2812	0	6	1	0	0	0	0	0	0	
3	0	3	2	2902	3	4	0	0	0	0	0	0	
3	1	1	2	1	1460	8	0	0	0	0	0	0	
7	0	2	1	4	5	3181	0	0	0	0	0	0	
1	3	0	0	0	0	0	2863	0	0	0	0	0	
0	0	0	0	0	0	0	1	2908	0	0	1	0	
2	0	0	0	0	0	0	0	2	2893	0	1	0	
0	0	0	0	0	0	0	1	0	0	2827	1	0	
0	0	0	0	0	0	0	1	0	0	0	1505	1	
0	0	0	0	0	0	0	0	0	0	0	0	3200	

Solution

Our solution pipeline begins by preprocessing the images. A set of functions are imported from the Scikit-Learn machine learning/data analytics library, along with numpy, and matplotlib (to visualize the data).

In our image processing function, a gaussian filter is added to each image. Gaussian filters typically transform the image by reducing grain and smoothing edges. This removes unwanted detail and noise, and is especially useful when one compresses an image and wants to get rid of pixelation. This step is especially important given the textured nature of the chessboards. By blurring the images, the pipeline was effectively able to remove noise from wood-grain or marbled rock textures. The gaussian distribution is used to calculate the changes in each pixel of a given image. In one dimension, a gaussian filter simply uses figure g1 below

for the transformation. When done in multiple dimensions, as for the present case that is bi-dimensional, it transforms each picture using a product of gaussian functions as in the expression for G_2 in Equation (1).

$$G_1(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{x^2}{2\sigma^2}}; \qquad G_2(x,y) = \frac{1}{2\pi\sigma^2} e^{-\frac{x^2+y^2}{2\sigma^2}};$$
 (1)

The rescale function then ensures that all images are of the same size without becoming distorted. Subsequently each transformed image is returned.

The load images function next takes all of the preprocessed images and puts them into an array where they can be accessed and operated on by the functions that will classify them. Instead of working with the original 80,000 samples that we had available, we selected at random to work with 20,000 of them, assuming this would be sufficient for the current work. From that, we split the data into train (80%) and test (20%) sets. We used 5-fold cross validation to validate our problem.

Each of the images of the training were split into 64 squares with 10 by 10 pixels. Those 1,024,000 squares were split again into train (80%) and test sets (20%) in order to train and test classification of individual squares. The strategy of splitting each board into small squares, predicting the pieces and putting pieces together to make a prediction for the entire board is somewhat similar to pooling layers. Our goal was to use a multiclass classifier to learn the features of the chess pieces, allowing us to identify whether a square was occupied and by what piece. Since the blank squares vastly outnumbered squares with pieces, for the sake of distributing classes more evenly we used the variable Drop_Blanks_PCT at 0.8. In the following we used softmax to classify the squares. The implementation was done using the sklearn.linear_model.LogisticRegression from the SciKit package with the configuration multi_class='multinomial', solver='newton-cg', fit_intercept = True, verbose = 10.

Initial Attempts and Iterations

Our image processing algorithm originally tried to learn by viewing the chessboard as a whole. However, it proved to be became easier, more efficient, and more accurate to train the model to look at each board square to recognize the specific pieces. Once the squares are split one can more clearly decipher the distinctions between pieces, build the connections between pieces, and later assign the correct FEN values.

Another useful feature we added was the parameters menu described above. This lets us see how each parameter affects the accuracy of the model, and which parameters have the highest impact. It also lets us find the threshold for each parameter that yields the most accurate result without using too much processing power.

Related Work and Applications

There are many papers which explore the chessboard as a field for studying vision and classification. In 2005, Martin's presentation, Finding a Chessboard, introduced fundamental concepts of early computer vision with this motivating question in mind. A few of the publications we found tackled the problem of identifying physical pieces. In Kory and Sumer's 2016 paper, they tracked full sequences of moves in a chess game by comparing image frames before, during, and after moves with an RGB webcam and a series of processing steps implemented in MATLAB.

Image filtering is a vital tool for processing large datasets like the one we used. We were able to cut down on file sizes, while still maintaining the necessary feature components for our classification. Without this, each trial could take hours to run, or not run at all. Additionally, in 2018, Marzi et al. (2018) showed that preprocessing medical images for higher information sparsity can help defend against adversarial attacks. This would be particularly relevant if we applied these techniques towards real chessboard images or images that may have distortions or irregularities.

Though our project focused on chess boards, one could hypothetically split any image up into pieces to identify desired components. Not only is this easily applicable to identify pieces/characteristics of other game boards but also for forms that follow consistent patterns. For example, this same pipeline could be modified to identify components of tax forms and QR codes. Also, the chess specific application can be applied as the first step of a puzzle solving algorithm. After we've identified the pieces and converted the board to FEN notation we can then use a strategic algorithm, such as Stockfish or Leela Chess Zero, to determine the next move.

Conclusions

Overall, our method of synthesizing various methods (logistic regression, cross validation and splitting our board squares to be processed) successfully labeled and classified the chess pieces. We consistently displayed levels of accuracy over 99% when parameters were optimized. Even when the image load size and drop blanks percentage were less than the optimal solution, our classifier consistently yielded results of over 95% accuracy. From there, we were able to smoothly label each piece position with the desired FEN character.

References

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