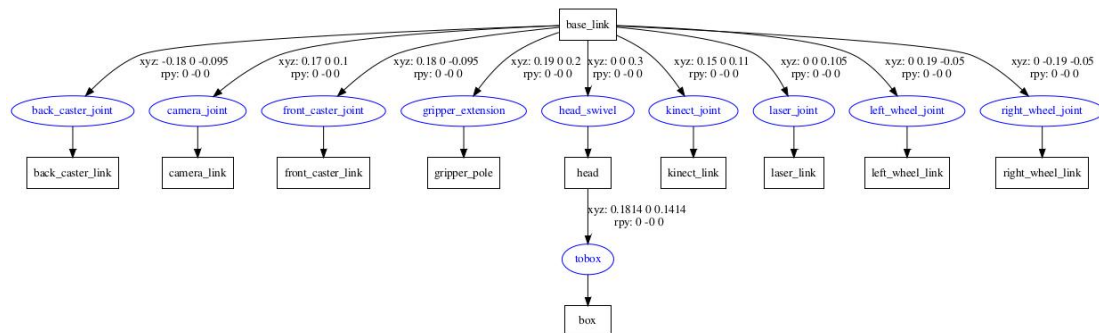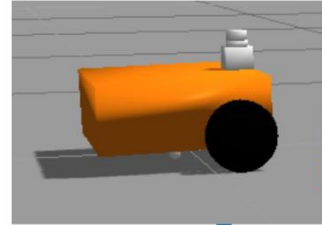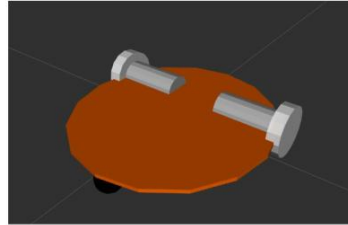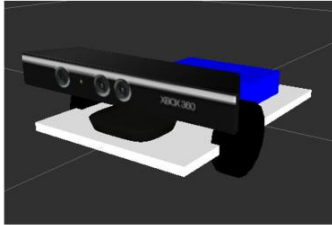# 参考本讲机器人URDF模型

创建一个自己的机器人模型

（差速轮式移动机器人）

Assignment: To build a robot.urdf model

1. build a tow wheels mobile robot with camera, laser, kinect, box, front&back caster, left&right_wheel link
2. writing a launch file
3. Ctrl + Alt + T open a terminal
4. roslaunch mbot_description robot.launch
5. urdf_to_graphiz robot.urdf