

Assignment1:

1. Ctrl + Alt + T
2. roslaunch robot\_vision usb\_cam.launch
3. roslaunch robot\_vision face\_detector.launch
4. rqt\_image\_view
5. roslaunch mbot\_gazebo robot\_control.launch

Assignment2:

1. souce ~tensorflow/bin/activate
2. roslaunch tensorflow\_object\_dectector usb\_cam\_detector.launch
3. roslaunch mbot\_gazebo robot\_control.launch
4. rosrun vision2 vision2