

```
* /random_complex/init_state_y: 0.0
* /random_complex/map/circle_num: 40
* /random_complex/map/obs_num: 300
* /random_complex/map/resolution: 0.1
* /random_complex/map/x_size: 20.0
* /random_complex/map/y_size: 20.0
* /random_complex/map/z_size: 10.0
* /random_complex/sensing/rate: 0.5
* /roscdistro: melodic
* /rosversion: 1.14.3
* /waypoint_generator/waypoint_type: manual-lonely-way...
```

NODES

```
/
  demo_node (grid_path_searcher/demo_node)
  random_complex (grid_path_searcher/random_complex)
  waypoint_generator (waypoint_generator/waypoint_generator)
```

ROS_MASTER_URI=http://127.0.0.1:11311

```
process[demo_node-1]: started with pid [19811]
process[random_complex-2]: started with pid [19812]
process[waypoint_generator-3]: started with pid [19813]
```

