

1 Deformations of Toric Algebras

Let k be a field and let $q_{ij} \in k$ for $1 \leq i < j \leq n$ and for convenience, we set $q_{ii} = 0$ and when $q_{ij} \neq 0$, we set $q_{ji} = q_{ij}^{-1}$. We also write $Q = (q_{ij})$ be the multiplicatively skew-symmetric matrix. Let $S = k\langle x_1, \dots, x_n \rangle$. Let I be the two sided ideal of S generated by

$$x_j x_i - q_{ij} x_i x_j \quad 1 \leq i < j \leq n.$$

We let $A = A_Q$ be S/I . This is a family of algebras of dimension $\binom{n}{2}$. Note that A has a k -basis of ordered monomials and so we have

$$A \simeq \bigoplus_{i_1 \geq 0, \dots, i_n \geq 0} kx_1^{i_1} \cdots x_n^{i_n}$$

as vector spaces. Note that the Hilbert Series of A is $H_A(t) = 1/(1-t)^n$ and if $q_{ij} \neq 0$ for all $i < j$ then A_Q is an AS-regular algebra. We will compute the Hochschild cohomology $HH^2(A)_0$ using the degree zero part of the complex

$$A(1)_0^n \xrightarrow{d_1} A(2)_0^{\binom{n}{2}} \xrightarrow{d_2} A(3)_0^{\binom{n}{3}}$$

We interpret $HH^2(A)_0$ as graded first order deformations, and we first compute the kernel of d_2 .

To compute first order deformations of $A = S/I$, we perturb the relations. We consider $a_{ij} \in A$ with $1 \leq i < j \leq n$. Let $k_1 = k[\varepsilon]/(\varepsilon^2)$ and write $\alpha_{ij} = \varepsilon a_{ij}$.

$$x_j x_i - q_{ij} x_i x_j - \alpha_{ij} \quad 1 \leq i < j \leq n.$$

We obtain the following family of algebras

$$A_1 = k_1\langle x_1, \dots, x_n \rangle / I_1.$$

Proposition 1 *The algebra A_1 is a first order deformation of A if and only one of the three equivalent conditions hold.*

1. A_1 is a flat k_1 algebra with a fixed isomorphism $A_1/(\varepsilon) \simeq A$.
2. $\varepsilon A_1 \simeq A$ as k -vector spaces.
3. (a_{ij}) are a Hochschild cocycle giving a class in $HH^2(A)$.
4. If $k > j > i$ when we reduce $(x_k x_j) x_i = x_k (x_j x_i)$ both ways to ordered monomials, we get the same answer.

We begin by computing the fourth condition above.

$$\begin{aligned} x_k(x_j x_i) &= x_k(q_{ij} x_i x_j + \alpha_{ij}) = q_{ij} x_k x_i x_j + x_k \alpha_{ij} \\ &= q_{ij} (q_{ik} x_i x_k + \alpha_{ik}) x_j + x_k \alpha_{ij} \\ &= q_{ij} q_{ik} x_i x_k x_j + q_{ij} \alpha_{ik} x_j + x_k \alpha_{ij} \\ &= q_{ij} q_{ik} q_{jk} x_i x_j x_k + q_{ik} q_{ik} x_i \alpha_{jk} + q_{ij} \alpha_{ik} x_j + x_k \alpha_{ij} \end{aligned}$$

$$\begin{aligned}
(x_k x_j) x_i &= (q_{jk} x_j x_k + \alpha_{jk}) x_i = q_{jk} x_j x_k x_i + \alpha_{jk} x_i \\
&= q_{jk} x_j (q_{ik} x_i x_k + \alpha_{ik}) + \alpha_{jk} x_i \\
&= q_{jk} q_{ik} x_j x_i x_k + q_{jk} x_j \alpha_{ik} + \alpha_{jk} x_i \\
&= q_{jk} q_{ik} q_{ij} x_i x_j x_k + q_{jk} q_{ik} \alpha_{ij} x_k + q_{jk} x_j \alpha_{ik} \alpha_{jk} x_i
\end{aligned}$$

Hence we have a first order deformation if and only if

$$q_{ij} q_{ik} x_i \alpha_{jk} + q_{ij} \alpha_{ik} x_j + x_k \alpha_{ij} = q_{jk} q_{ik} \alpha_{ij} x_k + q_{jk} x_j \alpha_{ik} + \alpha_{jk} x_i$$

We will solve these equations for graded deformations, i.e. when $\alpha_{ij} \in \varepsilon A_2$ are quadratic. This could be done for choices of degree other than two.

So we let

$$\alpha_{ij} = \sum_{1 \leq \ell \leq m \leq n} \alpha_{ij}^{\ell m} x_\ell x_m$$

be arbitrary quadratic elements of A . We look at the above condition for these α . So we have

$$\begin{aligned}
&\sum (q_{ij} q_{ik} x_i \alpha_{jk}^{\ell m} x_\ell x_m + q_{ij} \alpha_{ik}^{\ell m} x_\ell x_m x_j + x_k \alpha_{ij}^{\ell m} x_\ell x_m) = \\
&\sum (q_{jk} q_{ik} \alpha_{ij}^{\ell m} x_\ell x_m x_k + q_{jk} x_j \alpha_{ik}^{\ell m} x_\ell x_m + \alpha_{jk}^{\ell m} x_\ell x_m x_i)
\end{aligned}$$

This gives cubic expressions in A , which we can separate in to different equations, for example:

$$(q_{ij} q_{ik} \alpha_{jk}^{ii} - \alpha_{jk}^{ii}) x_i^3 = 0.$$

On examining the coefficients of different monomials, we obtain the following equations:

$$\begin{aligned}
(q_{ij} q_{ik} - q_{il}) \alpha_{jk}^{i\ell} &= 0 \quad \{j, k\} \cap \{i, \ell\} = \emptyset, \quad j < k, \quad i \leq \ell \\
q_{ij} (q_{ik} - q_{il}) \alpha_{jk}^{j\ell} + q_{ij} (q_{j\ell} - q_{jk}) \alpha_{ik}^{i\ell} &= 0 \quad |\{i, j, k\}| = 3.
\end{aligned}$$

We note that these conditions are mostly independent. The first set of equations is completely independent from each other and the second set of equations. The second set of equations decomposes into sets of three equations for each ordered pair k, ℓ with $k \neq \ell$. Hence we can combine them into a matrix equation for $i < j < k$ we have

$$\begin{pmatrix} q_{jk} & & \\ & q_{ik} & \\ & & q_{ij} \end{pmatrix} \begin{pmatrix} 0 & q_{k\ell} - q_{kk} & q_{jk} - q_{j\ell} \\ q_{kk} - q_{k\ell} & 0 & q_{i\ell} - q_{ik} \\ q_{j\ell} - q_{jk} & q_{ik} - q_{i\ell} & 0 \end{pmatrix} \begin{pmatrix} \alpha_{i\ell}^{ik} \\ \alpha_{j\ell}^{jk} \\ \alpha_{k\ell}^{kk} \end{pmatrix} = 0$$

Recall that a skew symmetric matrix always has even rank, so we always have a solution

$$\begin{pmatrix} \alpha_{i\ell}^{ik} \\ \alpha_{j\ell}^{jk} \\ \alpha_{k\ell}^{kk} \end{pmatrix} \in k \begin{pmatrix} q_{i\ell} - q_{ik} \\ q_{j\ell} - q_{jk} \\ q_{k\ell} - q_{kk} \end{pmatrix}.$$

These are all solutions when the matrix has rank two, otherwise the matrix must have rank zero, so

$$q_{i\ell} = q_{ik}, q_{j\ell} = q_{jk}, q_{k\ell} = q_{kk}$$

and there are no conditions on the corresponding $\alpha_{i\ell}^{ik}, \alpha_{j\ell}^{jk}, \alpha_{k\ell}^{kk}$. Hence we can conclude the following result.

Definition 1 Q is generic if

$$q_{ij} \neq 0 \quad i < j$$

$$q_{ij}q_{ik} \neq q_{i\ell} \quad j < k, i \leq \ell.$$

$$Q \notin V(q_{i\ell} = q_{ik}, q_{j\ell} = q_{jk}, q_{k\ell} = q_{kk}).$$

Proposition 2 Let A_1 be determined by the (α_{ij}) then if Q is generic A_1 is a flat deformation if and only if the (α_{ij}) satisfy

$$\alpha_{jk}^{i\ell} = 0 \quad j < k, i \leq \ell,$$

$$\begin{pmatrix} \alpha_{i\ell}^{ik} \\ \alpha_{j\ell}^{jk} \\ \alpha_{k\ell}^{kk} \end{pmatrix} \in k \begin{pmatrix} q_{i\ell} - q_{ik} \\ q_{j\ell} - q_{jk} \\ q_{k\ell} - q_{kk} \end{pmatrix}.$$

Proposition 3 If Q above is not generic, then we have further deformations as follows:

- If $q_{ij}q_{ik} = q_{i\ell}$ then we allow $\alpha_{ik}^{i\ell}$ to be free.
- If $q_{ij} = 0$ then we allow $\alpha_{jk}^{j\ell}, \alpha_{ik}^{i\ell}$ to be free.
- If $q_{i\ell} = q_{ik}, q_{j\ell} = q_{jk}, q_{k\ell} = q_{kk}$ then we allow $\alpha_{i\ell}^{ik}, \alpha_{j\ell}^{jk}, \alpha_{k\ell}^{kk}$ to be free.

Question 1 Does the family A_Q meet other families of AS-regular algebras along the loci described above?

Next, we will discuss infinitesimal automorphisms of first order deformations. Hochschild cohomology captures infinitesimal deformation up to infinitesimal isomorphism. Let $d_i \in A$ for $1 \leq i \leq n$ and write $\delta_i = \varepsilon d_i$. We can carry out an infinitesimal change of coordinates that will change our presentation of A_1 . Consider

$$x_i \mapsto x_i + \delta_i.$$

We can associate a derivation δ of S to this information by

$$x_i \mapsto d_i$$

and extending linearly and by the Leibniz rule. The effect of an infinitesimal change of coordinates on relations is determined by

$$r_{ij} \mapsto \delta(r_{ij}).$$

In particular for our case, we have

$$x_j x_i - q_{ij} x_i x_j \mapsto \delta_j x_i + x_j \delta_i - q_{ij} (\delta_i x_j + x_i \delta_j).$$

This changes the relations in the following way:

Proposition 4 *Two first order deformations A_1 and A'_1 determined by (a_{ij}) and (a'_{ij}) are infinitesimally isomorphic if and only if*

1. *There is a commutative diagram*

$$\begin{array}{ccc} A_1 & \rightarrow & A'_1 \\ & \searrow & \downarrow \\ & & A \end{array}$$

2. *There are $d_i \in A$ so that have*

$$a_{ij} = a'_{ij} + d_j x_i + x_j d_i - q_{ij} (d_i x_j + x_i d_j).$$

We consider $\delta_i = \sum_j x_j$ and consider the infinitesimal deformations we obtain by infinitesimal change of coordinates, i.e. trivial deformations. We see the relations become

$$\begin{aligned} (x_j + \delta_j)(x_i + \delta_i) &= q_{ij}(x_i + \delta_i)(x_j + \delta_j) \\ x_j x_i + \delta_j x_i + x_j \delta_i &= q_{ij}(x_i x_j + \delta_i x_j + x_i \delta_j) \\ x_j x_i &= q_{ij} x_i x_j + q_{ij} \delta_i x_j + x_i \delta_j - \delta_j x_i + x_j \delta_i \end{aligned}$$

and so

$$\begin{aligned} \alpha_{ij} &= q_{ij} \delta_i x_j + x_i \delta_j - \delta_j x_i + x_j \delta_i \\ \alpha_{ij} &= q_{ij} \delta_i^k x_k x_j + x_i \delta_j^\ell x_\ell - \delta_j^\ell x_\ell x_i + x_j \delta_i^k x_k \\ &= \delta_j^k (q_{ik} - q_{ij}) x_i x_k + \delta_i^\ell (q_{\ell j} - q_{ij}) x_\ell x_j. \end{aligned}$$

Theorem 1 *Let A_Q be generic, then any deformation of A_Q lies in the same family and so A_Q forms a component of the moduli space of AS-regular algebras of dimension four. This component possibly meets other components of the moduli space when we have some*

$$i < j \quad q_{ij} = 0$$

or

$$i < j, k, \ell \quad q_{ij} q_{ik} = q_{i\ell}$$

or

$$q_{i\ell} = q_{ik}, q_{j\ell} = q_{jk}, q_{k\ell} = q_{kk}$$

Question 2 *Can we find other components of the moduli space that meet A_Q in the loci described above?*

Question 3 *Does this theorem work for any n , not just $n = 4$.*

Question 4 *The families of algebras described in Pym's thesis are all components. How do they meet other components and each other?*

2 The moduli space of AS-regular Algebras

In this section we discuss the moduli space of AS-regular algebras and some rigidifications. We will obtain a closed variety and so we will allow algebras that are possibly not regular. Let A be generated by a vector space of dimension four V . Then A has six quadratic relations.

This gives a point in

$$A \in \text{Gr}(6, V \otimes V).$$

Alternatively, we can consider the Koszul dual in

$$A^\dagger \in \text{Gr}(10, V^* \otimes V^*).$$

Imposing

$$\dim A_d = \binom{3+d}{d}$$

is a closed condition for each d . Since the intersection of closed spaces is closed, we see that

$$A_4 := \{A \in \text{Gr}(6, V \otimes V) \mid H_A(t) = 1/(1-t)^4\} \subset \text{Gr}(6, V \otimes V).$$

is a closed subvariety. The algebra defined by $x_j x_i = 0$ for $i < j$ is in M_4 and is not AS-regular, so we know that M_4 is larger than the set of AS-regular algebras.

Question 5 *Is the generic point of each component of M_4 regular?*

Changing coordinates gives an action of $\text{PGL}_4 V$ on this variety and the moduli (stack) space of algebras with this Hilbert series is

$$M_4 = A_4 / \text{PGL}_4 V \subset \text{Gr}(6, V \otimes V) / \text{PGL} V.$$

Note that the stabilizer of a point $A_0 \in M_4$ is $\text{Aut } A/k^*$. Recall we always have that $k^* \subseteq \text{Aut } A \subseteq V$.

Since deformation are flat, they preserve the Hilbert Series. So Hochschild cohomology measures the tangent spaces of M_4 . More precisely, let $A_0 \in M_4$, then

$$HH^2(A)_0 = T_{A_0} M_4$$

as $\text{Aut } A/k^*$ equivariant vector spaces.

We can rigidify these spaces. First recall there are standard open subsets of the Grassmanian, with the simplest being the span of

$$(I|P)$$

where P is an arbitrary matrix.

We define $A^\dagger = A^\perp$ and if A is Koszul then we know further that $A^\dagger \simeq \text{Ext}_A^*(k, k)$. and $\dim A_d^\dagger = \binom{4}{d}$. We could impose these closed conditions on M_4 to obtain a possibly smaller variety, whose algebras are more likely to be AS-regular.