Weight Uncertainty in Neural Networks

Google DeepMind (2015)

Uncertainty on Weights

Problem: Plain feedforward neural networks are prone to overfitting.

Solution: Use variational Bayesian learning to introduce uncertainty on the weights in the network. (*Bayes by Backprop*)

Motivation:

- Regularization via a complexity cost on the weights
- Richer representations and predictions from cheap model averaging
- Exploration in simple RL problems

Probabilistic View of Neural Networks

Probabilistic Model: P(y|x,w) where $x \in \mathbb{R}^p$, $y \in Y$

Training the weights:

$$w^{MLE} = \arg\max_{w} \underbrace{\sum_{i} \log P(y_i|x_i, w)}_{\log P(D|w)}$$

$$w^{MAP} = \operatorname*{arg\,max} \log P(D|w) + \log P(w)$$

Black Box Variational Inference for Neural Networks

Variational Model:
$$\theta = \{\mu, \rho\}$$

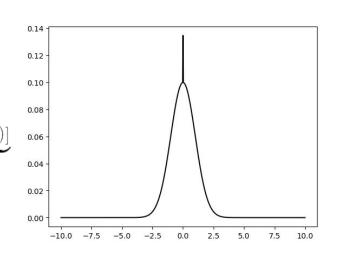
$$\sigma = \underbrace{\log(1 + \exp(\rho))}_{\text{softplus}}$$

$$q(w; \theta) = \mathcal{N}\left(w; \mu, \sigma^2\right)$$

Objective:
$$\theta^* = \arg\min_{\theta} \operatorname{KL}(q(w; \theta) \mid\mid P(w \mid \mathcal{D}))$$

$$= \arg\min_{\theta} \underbrace{\operatorname{KL}(q(w; \theta) \mid\mid P(w))}_{\text{prior/regularization}} + \underbrace{\mathbb{E}_{q(w; \theta)} \left[-\log P(\mathcal{D} \mid w)\right]}_{\text{data-driven/likelihood}}$$

$$\mathcal{F}(\theta) = \mathbb{E}_{q(w; \theta)} \left[\underbrace{\log q(w; \theta) - \log P(w) - \log P(\mathcal{D} \mid w)}_{f(w; \theta)} \right]$$



Black Box Variational Inference for Neural Networks

Reparameterization trick:

$$\mathcal{F}(\theta) = \mathbb{E}_{q(\omega;\theta)} [f(w;\theta)]$$
$$= \mathbb{E}_{p(\epsilon)} [f(w;\theta)]$$
$$\nabla_{\theta} \mathcal{F}(\theta) = \mathbb{E}_{p(\epsilon)} [\nabla_{\theta} f(w;\theta)]$$

Backpropagation:

$$\nabla_{\mu} \mathcal{F}(\theta) = \mathbb{E}_{p(\epsilon)} \left[\frac{\partial f(w; \theta)}{\partial w} + \frac{\partial f(w; \theta)}{\partial \mu} \right]$$

$$\nabla_{\rho} \mathcal{F}(\theta) = \mathbb{E}_{p(\epsilon)} \left[\frac{\partial f(w; \theta)}{\partial w} \frac{\epsilon}{1 + \exp(-\rho)} + \frac{\partial f(w; \theta)}{\partial \rho} \right]$$

$$\frac{\partial f(w; \theta)}{\partial w} \equiv \text{Backpropagation}$$

Bayes by Backprop

- 1. Sample $\epsilon \sim \mathcal{N}(0, I)$
- 2. Let $w = \mu + \log(1 + \exp(\rho)) \circ \epsilon$
- 3. Let $\theta = (\mu, \rho)$
- 4. Let $f(w, \theta) = \log q(w|\theta) \log P(w) \log P(D|w)$
- 5. Calculate gradients:

$$\Delta_{\mu} = \frac{\partial f(w, \theta)}{\partial w} + \frac{\partial f(w, \theta)}{\partial \mu}$$

$$\Delta_{\rho} = \frac{\partial f(w, \theta)}{\partial w} \frac{\epsilon}{1 + \exp(\rho)} + \frac{\partial f(w, \theta)}{\partial \rho}$$

7. Update the variational parameters:

$$\mu \leftarrow \mu - \alpha \Delta_{\mu}$$
$$\rho \leftarrow \rho - \alpha \Delta_{\rho}$$

Results

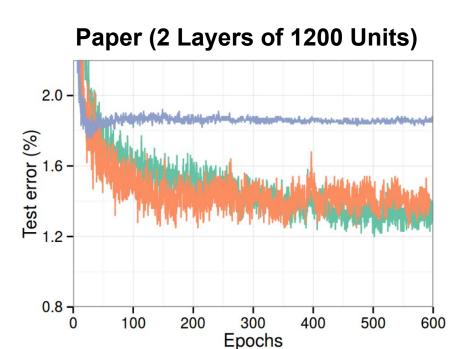
Our Implementations:

- Homebrewed numpy w/autograd
- PyTorch

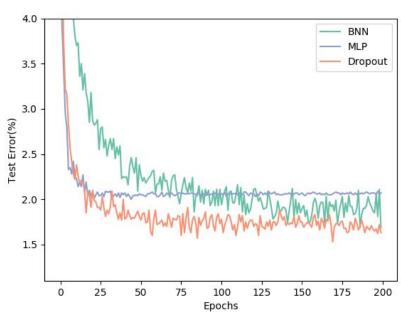
Trained Model with 'Backprop by Bayes' on three domains:

- Classification: MNIST digit recognition
- Regression: 1D synthetic non-linear function
- Contextual Bandits: "mushroom" domain

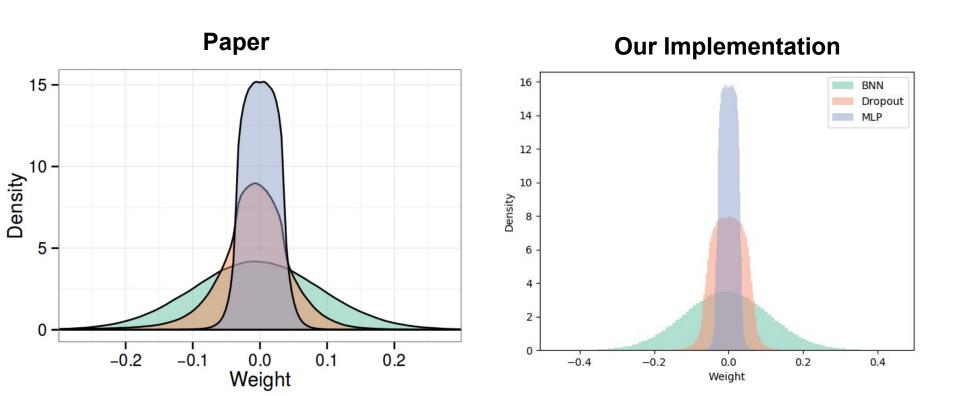
MNIST - Test Error



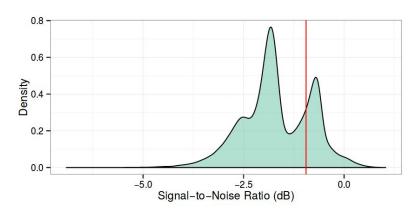
Our Implementation (2 Layers of 400 Units)



MNIST - Weight Histogram



MNIST - Weight Pruning



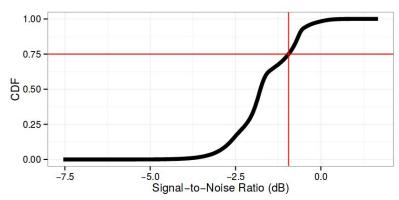
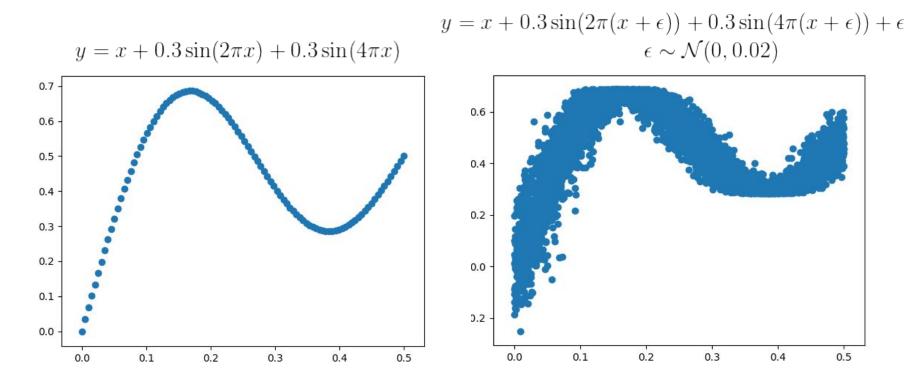


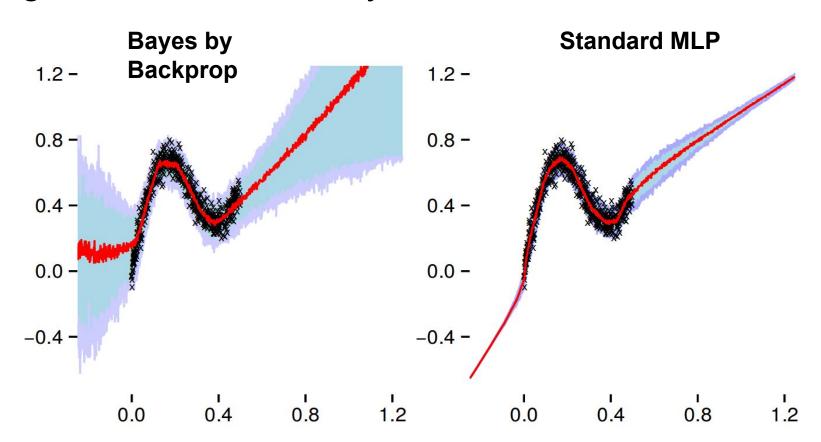
Table 2. Classification Errors after Weight pruning

Proportion removed	# Weights	Test Error
0%	2.4m	1.24%
50%	1.2m	1.24%
75%	600k	1.24%
95%	120k	1.29%
98%	48k	1.39%

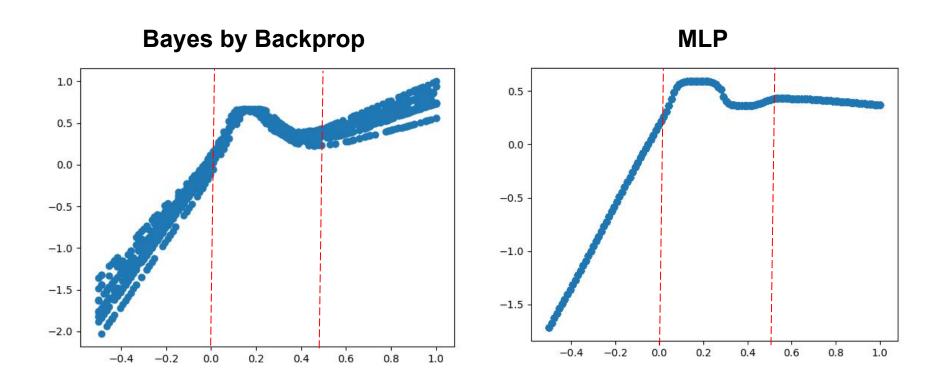
Regression - Non-Linear Functions



Regression - Uncertainty in New Data



Regression - Uncertainty in New Data



Multi-Armed Bandits (Recap)

Objectives:

- Exploitation Choose "best" bandit;
- Exploration Discover better bandits;

Approaches:

- Non-Bayesian Point-estimate of expected rewards, explore w/ ϵ -greedy
- Bayesian (optimal) Full belief over rewards, optimize long term return.
- Bayesian (heuristic) e.g. Thompson sampling.

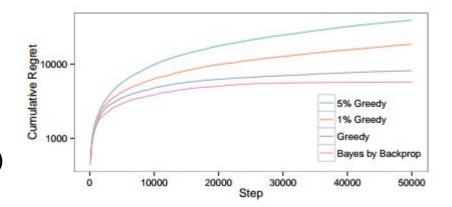
Contextual Bandits - Mushroom Domain

Context: Mushroom features $x \in \{0,1\}^{117}$ (color, size, shape, population, ...)

Actions: Eat or Ignore

Rewards:

- Ignore ⇒ 0
- Eat + Edible \Rightarrow 5
- Eat + Toxic ⇒ Discrete({5, -35})



Conclusions

Contribution: Extension of Backprop training for approx. Bayesian inference.

Pros:

- Performs similarly to non-Bayesian state-of-the-art (SGD + dropout).
- Learns sensible notion of uncertainty.
- Straightforward parallelization.
- Results partially replicated.

Cons:

- Finicky, sensitive to hyperparameters (typical of NNs, BBVI innocent?).
- Substantially slower (more parameters, more samples required).