

# SawyerDroneSimulation

This project is being developed for a multidisciplinary research project at Oklahoma State University. This code simulates a quadcopter drone on a Sawyer Robotic Arm and demonstrates the use of various motion interfaces of the arm.

## Contents

<b>1 Files of Interest</b>	<b>1</b>
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## 1 Files of Interest

- `../sawyer_ws/src/position_control/scripts/position_control.py`
- `../sawyer_ws/src/position_control/scripts/motion_control.py`
- `../sawyer_ws/src/position_control/scripts/drone_control.py`
- `../sawyer_ws/src/position_control/scripts/drone_sim.py`
- `../sawyer_ws/src/position_control/scripts/drone_sim_joints.py`